

## Optimal Homotopy Asymptotic and Homotopy Perturbation Methods for Linear Mixed Volterra-Fredholm Integral Equations

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### Abstract

In this paper, we study the mixed Volterra-Fredholm integral equations of the second kind by means of optimal homotopy asymptotic method (OHAM) and Homotopy Perturbation method (HPM). Our approach is independent of time and contains simple computations with quite acceptable approximate solutions in which approximate solutions obtained by these methods are close to exact solutions. Comparison of these methods have been discussed. The accuracy and efficiency of OHAM approach with respect to Homotopy Perturbation method (HPM) is illustrated by presenting four test examples. The results indicate that the OHAM is very effective and flexible to use with respect to HPM.

**Keywords:** Mixed Volterra-Fredholm integral equations, Optimal homotopy asymptotic method, Least square method, Homotopy Perturbation method.

## Lineer Karma Volterra-Fredholm İntegral Denklemleri için Optimal Homotopi Asimptotik ve Homotopi Perturbasyon Metotları

### Öz

Bu çalışmada, karma Volterra-Fredholm integral denklemleri optimal homotopi asimptotik metod (OHAM) ve Homotopi Perturbasyon metodu (HPM) vasıtasıyla irdelenmiştir. Yaklaşımımız zamandan bağımsız ve basit hesaplamalar yolu ile tam çözüme oldukça yaklaşık çözümler veren bir yöntemdir. Bu iki yöntemin karşılaştırılması tartışılmıştır. OHAM yaklaşımının doğruluğu ve etkinliği HPM çözümleri ile dört örnek kullanılarak karşılaştırılmıştır. Sonuçlar OHAM ın HPM ye göre daha verimli ve esnek bir yöntem olduğunu göstermektedir.

**Anahtar Kelimeler:** Karma Volterra-Fredholm integral denklemleri, Optimal homotopi asimptotik metodu, En küçük kareler yöntemi, Homotopi Perturbasyon Metodu.

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## 1. Introduction

Many models in different areas of applied mathematics lead to mixed Volterra-Fredholm integral equations. They have been studied in some cases such as boundary value problems of parabolic type, Spatio-Temporal problem in Epidemic development and some issues in different physical and biological structures. Spatial-temporal problems are studied a lot in statistical mathematics. They can be defined for example in a monitoring network of an atmospheric pollutant or a network in meteorological problems so that their data are analyzed at regular intervals. Epidemic data have Spatio-temporal processes with autoregressive nature. Spread of a communicable disease in a population is described by epidemic structures. Spatio Temporal analysis has been studied by many researchers [5-7, 11, 18, 37, 43].

Therefore, numerical, analytical and semi-analytic methods play an important role to analyze such these phenomena. Spatio-temporal analysis in some mathematical models leads to mixed Volterra-Fredholm integral equations. A comprehensive description for formulation of these models has proposed by Wazwaz [45] and other researchers in this field [3-4, 44, 47-49]. The Volterra-Fredholm integral equations of mixed form [45] is in the following format :

$$v(x) = f(x) + \int_c^x \int_c^d K(y, z)v(z)dzdy \quad (1)$$

Such that  $f(x)$  and  $K(y, z)$  can be defined as known functions. It is noticed that Eq.1 includes mixed Volterra and Fredholm integral equations. Fredholm integral is defined in the interior part and Volterra integral is appeared in exterior one. Furthermore, the unknown function  $v(x)$  exists in inside and outside of integral part that is called characteristic feature for these types of equations. The exact and analytic solutions of mentioned equations cannot be found easily. Hence some numerical methods have been suggested to solve them [2, 8, 13, 15, 24, 28, 31, 36, 47, 48]. In some cases, partial differential equations in physics can be converted to mixed Volterra-Fredholm integral equation [32]. Double integral equations have been solved through methods like Collocation and Galerkin method, Spline functions and Taylor series expansion method [1, 3, 32, 44].

Now, we explain optimal homotopy asymptotic method (OHAM) to solve these types of equations in comparison with HPM. Marinca and Herisanu [20, 40] invented this approach for the first time. In addition, they published some papers presented in [19, 25, 26, 27, 39] to show the ability of OHAM to expand their ideas in order to implement it to solve a vast domain of nonlinear problems. The advantage of OHAM is its convergence criteria so that is similar to homotopy analysis method (HAM) in more flexible area of convergence. Moreover, power of this method has been studied by some researchers [25, 26, 19]. Some different examples are presented to indicate the power of the method compared to HPM in the section of numerical examples. Graphs are used to illustrate solutions obtained by OHAM. Therefore, we have presented a powerful approach OHAM which is generalized form HAM and HPM and has simple procedure to perform. This method has been used by various researchers in different fields as a useful technique [29, 34, 38, 39, 42]. In this paper, we introduce the main structure of OHAM compared to HPM; Three numerical examples are tested and illustrated. At last, we discuss about the obtained computational results.

**2. Uniqueness and existence theorems in mixed Volterra- Fredholm integral equations**

Now we take into account linear mixed Volterra-Fredholm type integral equation (1) so that  $u$  is called an unknown function,  $v, f \in C[c, d]$  and  $K \in L^2[c, d]$ . The purpose is to study existence and uniqueness for the solution of equation (1). We apply Banach fixed-point theorem to discuss the existence and uniqueness of physical, biological and applied problems given by the equation (1).

**3. Main Results**

Suppose that  $S$  be a space of functions  $\phi: [c, d] \rightarrow R^n$ , continuous in  $[c, d]$  and satisfy the condition

$$|\lambda(x)| = O\left(\exp\left(\theta(|x|)\right)\right), x \in [c, d] \tag{2}$$

where  $\mu > 0$  is a constant. In the space  $S$ , we define the following norm

$$|\lambda| = \sup_{[c,d]} \left[ |\lambda(x)| \exp\left(\theta(|x|)\right) \right] \tag{3}$$

It is noticed that  $S$  is a Banach space. We notice that there is a nonnegative constant  $M$  such that

$$|\lambda(x)| \leq M \exp\left(\theta(|x|)\right), x \in [c, d] \tag{4}$$

Then, we can conclude that

$$|\lambda| \leq M$$

Now we give sufficient conditions for the existence and uniqueness of the solutions in equation (1).

**Theorem 1:**

We assume that

1) Continuous kernel  $K(y, z)v(z)$  defined on  $[c, d] \times [c, d]$

such that

$$\left| K(y, z)v_1(z) - K(y, z)v_2(z) \right| \leq K(y, z) |v_1 - v_2| \tag{5}$$

for  $(y, z, v_1, v_2) \in [c, d] \times [c, d], i = 1, 2$  and

$$\int_c^x \int_c^d K(y, z)v(z) \exp(\theta|y|) dydz \leq Q \exp(\theta|x|) \tag{6}$$

So that  $Q$  is a nonnegative constant.

2) There exists a constant  $N > 0$  such that

$$\left| f(x) + \int_a^x \int_a^b K(y, z)v(z) \exp(\theta|y|) dydz \right| \leq N \exp(\theta|x|) \tag{7}$$

If  $Q < 1$ , then we can find  $u \in S$  as a solution of Eq.1 that is considered as a limit for sequence of solutions.

**Proof:**

For  $v \in S$ ,  $A(v)$  is defined as an operator in right side of equation (1). It can be shown that

$A(v): S \rightarrow S$ .  $A(u)$  is continuous in  $[c, d]$  and  $A(v(x)) \in L^2[c, d]$  for  $x \in [c, d]$ . To verify Eq.2, we have :

$$\begin{aligned} |A(v(x))| &\leq \int_0^x \int_c^d |K(y, z, v_1, 0) - K(y, z, v_2, 0)| dydz \\ &+ |f(x)| + \int_0^x \int_c^d |K(y, z, v_2, 0)| dydz \leq |v| \int_0^x \int_c^d h(y, z, v) \exp(\theta|y|) dydz \\ &+ N \exp(\theta(y)) dydz \leq [MQ + N] \exp(\theta|x|). \end{aligned} \tag{8}$$

Therefore, we conclude that  $A(u) \in S$ . Now we show that the operator  $A(u)$  is a contraction mapping.

We assume that  $u, z \in S$ , and then from the assumption (1), we have

$$\begin{aligned} &\|A(v(t, x)) - A(z(t, x))\| \\ &\leq \int_0^t \int_{\Omega} \|F(t, x, s, y, v(s, y)) - F(t, x, s, y, z(s, y))\| dyds \\ &\leq |v - z| \int_0^t \int_{\Omega} h(t, x, s, y) \exp(\theta(s + \|y\|)) dyds \\ &\leq Q|v - z| \exp(\theta(t + \|x\|)) \\ &|A(v(x)) - A(z(x))| \leq \int_0^x \int_c^d |K(y, z, u) - K(y, z, v)| dydz \\ &\leq |u - v| \int_0^x \int_c^d h(y, z, v) \exp(\theta|x|) dydz \\ &\leq Q|u - v| \exp(\theta|x|) \end{aligned}$$

Then, we obtain :

$$|A(u(x)) - A(z(x))| \leq Q|u - v| \exp(\theta|x|)$$

Therefore, there is a unique solution  $u \in S$  of equation (1) and it completes the proof. ■

**4. Description of Optimal Homotopy Asymptotic Method (OHAM)**

Now, we introduce the general structure of OHAM based on the below scheme. We perform the OHAM to a general nonlinear equation like  $A(v(y)) = f(y)$  that can be decomposed as

$$L(v(y)) + f(y) + N(v(y)) = 0 \tag{9}$$

So that  $L$  is considered as a linear operator,  $N$  an unknown function,  $f(y)$  a known function and  $N(v(y))$  a non-linear operator. Then, a new homotopy function is made for OHAM as follows [16, 17, 40]:

$$(1 - p)[L(v(y, p)) + f(y)] = H(p)[L(v(y, p)) + f(y) + N(v(y, p))] \tag{10}$$

So that  $p \in [0,1]$  is a small embedding parameter ( $p \neq 0$ ),  $H(p)$  is an auxiliary function, and  $v(y, p)$  is defined as unknown function that needs to be obtained. For values  $p = 0$  and  $p = 1$ , we have :

$$v(y, 0) = v_0(y), v(y, 1) = v(y) \tag{11}$$

respectively. When  $p$  changes from 0 to 1, the solution  $v(y, p)$  moves from  $v_0(y)$  to the solution  $v(y)$  and  $v_0(y)$  is attainable from Eq.9 for  $p = 0$ .

$$L[v_0(y)] + f(y) = 0 \tag{12}$$

We can define  $H(p)$ , the auxiliary function as follows :

$$H(p) = pc_1 + p^2c_2 + p^3c_3 + \dots \tag{13}$$

in which the constants  $c_1, c_2, \dots$  need to be determined.

Therefore, the solution of Eq.9 can be obtained as

$$v(y; p, c_i) = v_0(y) + \sum_{k \geq 1} v_k(y, c_i) p^k, i = 1, 2, \dots \tag{14}$$

Inserting Eq.14 to Eq.10 and finding the coefficients from similar powers of  $p$ ,  $u_0(y)$  is obtained by Eq.12. So, we have :

$$L(v_1(y)) = c_1 N(v_0(y)) \tag{15}$$

Therefore, we can obtain general iterative relation as follows:

$$L(v_k(y) - v_{k-1}(y)) = c_k N_0(v_0(y)) + \sum_{i=1}^{k-1} c_i [L(v_{k-i}(y)) + N_{k-i}(v_0(y), v_1(y), \dots, v_{k-1}(y))] \tag{16}$$

For the values  $k = 2, 3, \dots$  such that  $N_m(v_0(y), v_1(y), \dots, v_m(y))$  can be obtained through using Taylor expansion of  $N(v, p, c_i)$  in series with respect to  $p$  as follows :

$$N(v(y; p, c_i)) = N_0(v_0(y)) + \sum_{m \geq 1} N_m(v_0, v_1, \dots, v_m) p^m \tag{17}$$

The unknown expression  $v(y; p, c_i)$  is obtained by Eq.14. The elements  $u_k$  for  $k > 0$  are calculated through the system of Eqns.14, 15 and 16 that we can easily solve it. The series Eq.14 converges by obtaining optimal values of auxiliary constants  $c_1, c_2, \dots, c_m$ .

In  $p = 1$ , it yields

$$v(y, c_i) = v_0(y) + \sum_{k \geq 1} v_k(y, c_i). \tag{18}$$

Then, the solution of Eq.2 is obtained in this form :

$$v^m(y, c_i) = v_0(y) + \sum_{k=1}^m v_k(y, c_i), i = 1, 2, \dots, m \tag{19}$$

Residual is obtained by substituting Eq.19 into Eq.9 as follows :

$$R(y; c_i) = L(v^m(y, c_i)) + g(y) + N(v^m(y, c_i)), \quad i = 1, 2, \dots, m \quad (20)$$

If  $R(y; c_i) = 0$ , then  $u^m(y, c_i)$  is the exact solution. Auxiliary constants  $c_i, i = 1, 2, \dots$  can be obtained by finite element methods like Galerkin, Ritz, Collocation and Least Squares methods. Now, we use least square method to minimize the residual function. Then, we have :

$$J(c_i) = \int_c^d R^2(y, c_i) dy, \quad (21)$$

The values  $c$  and  $d$  are optional and can be chosen based on the type of problem and its given interval .

By forming system of normal equations, we find optimal parameters  $c_i, i = 1, 2, \dots, m$  as follows :

$$\frac{\partial J}{\partial c_1} = \frac{\partial J}{\partial c_2} = \dots = \frac{\partial J}{\partial c_m} = 0. \quad (22)$$

Therefore, the favorite approximate solution is easily obtained . Then, if  $k \in [c, d]$ , putting  $k_i$  into

Eq.20 gives the following equation :

$$R(k_1, c_i) = R(k_2, c_i) = \dots = R(k_m, c_i), \quad i = 1, 2, \dots, m \quad (23)$$

Therefore, we can propose advantages and disadvantages of the method as follows:

- (1) OHAM sometimes takes a lot of time to evaluate the residual by increasing the convergence parameters. Therefore, computing of convergence constants is not feasible over three or four times. Time-consuming problems have presented by [33] and [41, 46].
- (2) Although OHAM obtains best approximations for many cases but the closed form solution cannot be achieved all the time. This case occurs due to the existence of the convergence constants  $c_i$  in the auxiliary function  $H(p)$ .

### 5. Structure of Homotopy Perturbation Method(HPM)

To express this method, we make homotopy function by a small embedding parameter  $p \in [0, 1]$ . The structure of method includes a deformation from initial solution to the final step that is obtained our favorite solution. This method has been used by many researchers to solve different types of non linear problems [9, 10, 14, 21, 22, 23, 34, 35, 12]. HPM is considered as a combination of the classical perturbation technique and the homotopy from topology in pure mathematics. It is not restricted to small parameters like traditional perturbation methods. We can find highly accurate solutions in just few iterations. He in [23] extended methods of nonlinear analysis for a vast range of problems. In order to explain the structure of HPM, we assume the following nonlinear functional equation

$$A(v) - f(y) = 0, \quad y \in \Omega \quad (24)$$

with the following boundary conditions:

$$B\left(v, \frac{\partial v}{\partial y}\right) = 0, \quad y \in \Gamma \quad (25)$$

So that  $A$  is considered as general differential operator,  $B$  a boundary operator,  $f(y)$  a known analytic function, and  $\Gamma$  the domain boundary for  $A$  can be divided into two operators  $L$  and  $N$ , such that  $L$  is linear and  $N$  is nonlinear so that Eq.24 can be considered as

$$L(v) + N(v) - f(y) = 0. \tag{26}$$

Now, we construct the homotopy function as :

$$\begin{aligned} H(V, p) &= (1 - p)[L(V) - L(v_0)] + \\ p[L(v) + N(v) - f(y)] &= 0, p \in [0, 1], y \in \Omega \end{aligned} \tag{27}$$

or

$$\begin{aligned} H(V, p) &= L(V) - L(v_0) + \\ p[L(v) + N(v) - f(y)] &= 0, p \in [0, 1], y \in \Omega \end{aligned} \tag{28}$$

Such that  $p$  is in the range of zero and one as homotopy parameter and  $v_0$  is the first approximation for the solution of Eq.24 that satisfies in the boundary conditions. Eq.24 or Eq.26 is written as a power series of  $p$

$$V = v_0 + pv_1 + p^2v_2 + \dots \tag{29}$$

Substituting Eq.29 into Eq.27 or Eq.28 and equating similar powers of  $p$ , we can obtain the sequence  $v_0, v_1, v_2, \dots$ . When  $p \rightarrow 1$ , the approximate solution is given for Eq.24 in the form

$$V = v_0 + v_1 + v_2 + v_3 + \dots \tag{30}$$

### 6. Convergence theorem for optimal homotopy asymptotic method:

If the series

$$v(y, c_i) = v_0(y) + \sum_{k \geq 1} v_k(y, c_i) \tag{31}$$

converges to  $v(y)$  where  $v_k(y) \in L^2[c, d]$  in which it can be produced by relations:

$$L(v_1(y)) = c_1 N(v_0(y)) \tag{32}$$

$$L(v_k(y) - v_{k-1}(y)) = c_k N_0(v_0(y)) + \sum_{i=1}^{k-1} c_i [L(v_{k-i}(y)) + N_{k-i}(v_0(y), v_1(y), \dots, v_{k-1}(y))] \tag{33}$$

Such that  $k = 2, 3, \dots$ . Then,  $v(y)$  is the exact solution of the problem as follows:

$$L(v(y)) + f(y) + N(v(y)) = 0 \tag{34}$$

**Proof:** If the series

$$\sum_{k \geq 1} v_k(y, c_i) \tag{35}$$

converges, it can be written as

$$S(x) = \sum_{k=1}^{\infty} v_k(y, c_i) \tag{36}$$

In addition, it holds that

$$\lim_{k \rightarrow \infty} v_k(y, c_i) = 0 \tag{37}$$

Left hand side of relation (16) satisfies

$$v_1(y, c_1) + \sum_{k=2}^n v_k(y, c_k) - \sum_{k=2}^n v_{k-1}(y, c_{k-1}) = v_2(y, c_2) - v_1(y, c_1) + v_n(y, c_n) - v_{n-1}(y, c_{n-1}) = v_n(y, c_n) \tag{38}$$

According to summation relation in (36), we have:

$$v_1(y, c_1) + \sum_{k=2}^n v_k(y, c_k) - \sum_{k=2}^n v_{k-1}(y, c_{k-1}) = \lim_{n \rightarrow \infty} v_n(y, c_n) = 0 \tag{39}$$

By using linear operator  $L$ , we have:

$$\begin{aligned} &L(v_1(y, c_1)) + \sum_{k=2}^{\infty} L(v_k(y, c_k)) - \sum_{k=2}^{\infty} L(v_{k-1}(y, c_{k-1})) \\ &= L(v_1(y, c_1)) + L\left(\sum_{k=2}^{\infty} L(v_k(y, c_k))\right) - L\left(\sum_{k=2}^{\infty} L(v_{k-1}(y, c_{k-1}))\right) = 0 \end{aligned} \tag{40}$$

that satisfies in the relation:

$$\begin{aligned} &L(v_1(y, c_1)) + L\left(\sum_{k=2}^{\infty} v_k(y, c_k)\right) - \left(\sum_{k=2}^{\infty} v_{k-1}(y, c_{k-1})\right) \\ &= \sum_{k=2}^{\infty} \left[ c_k N_0(v_0(y)) + \sum_{i=1}^{k-1} c_i L(v_{k-i}(y, c_{k-i})) + N_{k-i}(v_{k-i}(y, c_{k-i})) + f(y) \right] = 0 \end{aligned} \tag{41}$$

Right hand side of Eq.41 can be written as follows:

$$\sum_{k=1}^{\infty} \left[ \sum_{i=1}^k c_{i-k} \left[ L(v_{i-1}(y, c_{i-k})) + N_{i-1}(v_{i-1}, c_{k-1}) \right] \right] + f(y) = 0 \tag{42}$$

If  $c_i, i = 1, 2, \dots, m$  are chosen appropriately, then relation (42) leads to

$$L(v(y)) + f(y) + N(v(y)) = 0 \tag{43}$$

That is the exact solution of the problem.

## 7. Illustrative examples

**7.1. Example1.** We consider the mixed Volterra-Fredholm integral equation as follows:

$$v(x) = 11x + \frac{17}{2}x^2 + \int_0^x \int_0^1 (y-z)v(z)dzdy. \tag{44}$$

in which whose exact solution is given by  $v(x) = 6x + 12x^2$ .

**Item1:** Homotopy Perturbation method (HPM)

The Homotopy function can be constructed from Eq.44 as follows:

$$H(v, p) = v(x) - f(x) - p \int_0^x \int_0^1 (y-z)v(z)dzdy \tag{45}$$

where  $f(x) = 11x + \frac{17}{2}x^2$ . By using Eq.29 into Eq.45 and finding the coefficients from similar powers of  $p$ , we have :

$$v_0(x) = f(x) = 11x + \frac{17}{2}x^2 \tag{46}$$

$$v_i(x) = \int_0^x \int_0^1 (y-z)v_i(z)dzdy$$

In this case, our experience shows that in 16-th iteration we can obtain the approximate solution as follows:

$$\tilde{u}(x) = \sum_{i=0}^{16} u_i(x) = \frac{(x(2218611106740437146 + 4437222213480873833x))}{369768517790072832}$$

The comparative graph of approximate and exact solution of Example1 by HPM and graph of error function are illustrated in Fig.1 and Fig.2. In addition, numerical results have been tabulated in Table 1.

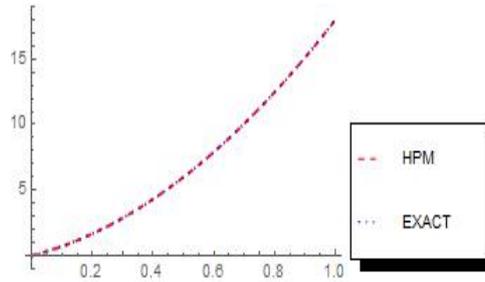


Fig1. Graph of approximate and exact solutions of Example 1 by HPM.

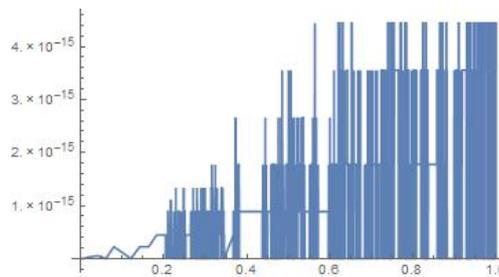


Fig2. The error function of Example 1 by HPM.

**Item2:** Optimal Homotopy Asymptotic method (OHAM)

We construct homotopy function from Eq.44 as follows:

$$f(x) = 11x + \frac{17}{2}x^2$$

$$H(v, p) = (1-p)(v(x) - f(x)) = H(p) \left( v(x) - f(x) - \int_0^x \int_0^1 (y-z)v(z)dzdy \right) \tag{47}$$

By using Eq.29 into Eq.47 and doing the similar procedures, we have :

$$v_0(x) = 11x + \frac{17}{2}x^2$$

$$v_1(x) = -\frac{1}{24}x(-139 + 100x)c_1$$

$$v_2(x) = \frac{1}{288} \begin{pmatrix} 1668xc_1 - 1200x^2c_1 + 1924xc_1^2 \\ -1417x^2c_1^2 + 1668xc_2 - 1200x^2c_2 \end{pmatrix}$$

Then, by using least square method presented in section 3, we find real optimal parameters  $c_1$  and  $c_2$  among a set of complex and real roots as follows:

$$c_1 = 0.923077, c_2 = -3.69231$$

Then, the series solution is given as:

$$v(x) = 11x + \frac{17}{2}x^2 - 0.038461538461538464x(-139 + 100x) + \frac{1}{288} \begin{pmatrix} -2979.692307692308x \\ +2115.692307692308x^2 \end{pmatrix} \quad (48)$$

The comparative graph of approximate and exact solution of Example 1 by OHAM and graph of error function are illustrated in Figure 3 and Figure 4.

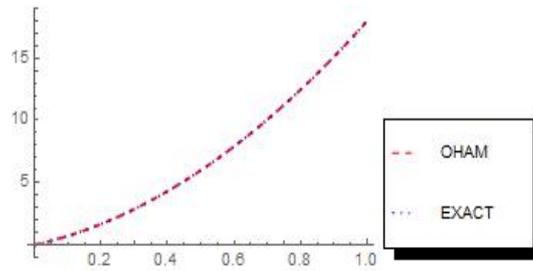


Fig3. Graph of approximate and exact solutions of Example 1 by OHAM.

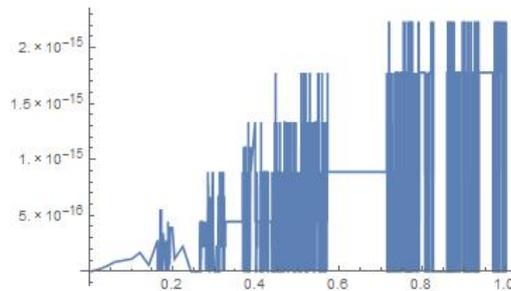


Fig4. The error function of Example 1 by OHAM.

Table1. Approximate and exact solutions with absolute error of Example 1 by OHAM.

x	OHAM	Exact solution	Absolute Error
0	0	0	0
0.1	0.720000	0.720000	0
0.2	1.680000	1.680000	0
0.3	2.880000	2.880000	0
0.4	4.320090	4.320000	0
0.5	6.000000	6.000000	0
0.6	7.920000	7.920000	0
0.7	10.080000	10.080000	0

0.8	12.480000	12.480000	0
0.9	15.120000	15.120000	0
1.0	18.000000	18.000000	0

**7.2. Example2.** We consider the mixed Volterra-Fredholm integral equation as follows:

$$v(x) = 2 + 4x - \frac{9}{8}x^2 - 5x^3 + \int_0^x \int_0^1 (y-z)v(z)dzdy. \tag{49}$$

In which the exact solution is given by  $v(x) = 2 + 3x - 5x^3$ .

**Item1:** Homotopy Perturbation method (HPM)

The Homotopy function can be constructed from Eq.28 as follows:

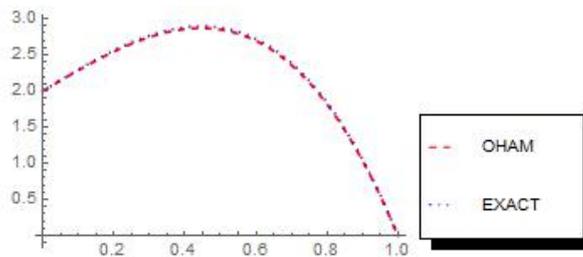
$$H(v, p) = (1-p)(v(x) - f(x)) = v(x) - f(x) - p \int_0^x \int_0^1 (y-z)v(z)dzdy \tag{50}$$

where  $f(x) = 2 + 4x - \frac{9}{8}x^2 - 5x^3$ .

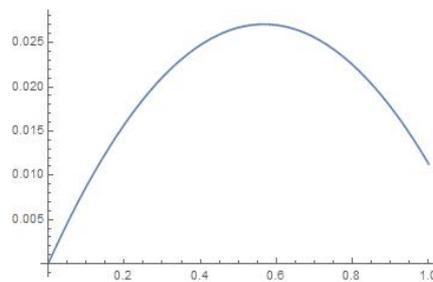
By using Eq.29 into Eq.50 and finding the coefficients from similar powers of  $p$ , we obtain solutions

similar to Eq.46 with  $v_0(x) = f(x) = 2 + 4x - \frac{9}{8}x^2 - 5x^3$ .

The comparative graph of approximate and exact solution of Example 2 by HPM and graph of error function are illustrated in Fig.5 and Fig.6. It can be shown that increasing the number of iterations cannot effect on the accuracy of approximation obtained by HPM. This shows that this method has been saturated. Therefore, HPM has disability to solve this integral equation. Partial fractions are provided in higher iterations and continuing the iterations is not effective.



**Fig5.** Graph of approximate and exact solutions of Example 2 by HPM.



**Fig6.** The error function of Example 2 by HPM.

**Item 2:** Optimal Homotopy Asymptotic method (OHAM)

The homotopy function for Eq.28 is made as follows:

$$f(x) = 2 + 4x - \frac{9}{8}x^2 - 5x^3$$

$$H(v, p) = (1 - p)(v(x) - f(x)) = H(p) \left( v(x) - f(x) - \int_0^x \int_0^1 (y - z)v(z) dz dy \right) \quad (51)$$

By using Eq.22 into Eq.51 and finding the coefficients from similar powers of  $p$ , we have :

$$v_0(x) = 2 + 4x - \frac{9}{8}x^2 - 5x^3$$

$$v_1(x) = -\frac{1}{96}x(-101 + 114x)c_1$$

$$v_2(x) = \frac{1212xc_1 - 1368x^2c_1 + 1274xc_1^2}{1152} + \frac{-1443x^2c_1^2 + 1212xc_2 - 1368x^2c_2}{1152}$$

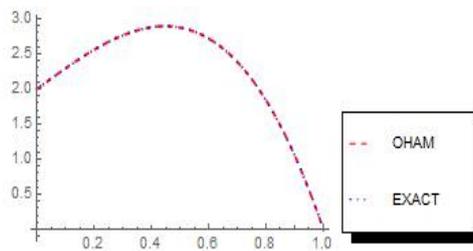
Moreover, by using least square method presented in section 2, we find real optimal parameters  $c_1$  and  $c_2$  among a set of complex and real roots as follows:

$$c_1 = 0.923077, c_2 = -3.69231$$

Then, we obtain the series solution as

$$v(x) = 2 + 4x - \frac{9}{8}x^2 - 5x^3 - 0.009615384615384616x(-101 + 114x) + \frac{-2270.769230769231x}{1152} + \frac{+2558.7692307692314x^2}{1152} \quad (52)$$

The comparative graph of approximate and exact solution of Example 2 and graph of error function are illustrated in Fig.7 and Fig.8. Also; numerical results have been tabulated in Table 2.



**Fig7.** Graph of approximate and exact solutions of Example 2 by OHAM.

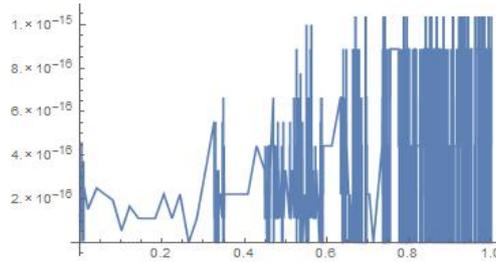


Fig8. The error function of Example 2 by OHAM.

**Table2.** Approximate and exact solutions with absolute error of Example 2 by OHAM.

$x$	OHAM	Exact solution	Absolute Error
0	2.000000	2.000000	0
0.1	2.295000	2.295000	0
0.2	2.560000	2.560000	0
0.3	2.765000	2.765000	0
0.4	2.880000	2.880000	0
0.5	2.875000	2.875000	0
0.6	2.720000	2.720000	0
0.7	2.385000	2.385000	0
0.8	1.840000	1.840000	0
0.9	1.055000	1.055000	0
1.0	0.000000	0.000000	0

**7.3. Example3.** The mixed Volterra-Fredholm integral equation is defined as follows:

$$v(x) = \cos x + \sin x - x^2 + \frac{\pi}{2}x + \int_0^x \int_0^1 (y-z)v(z)dzdy. \tag{53}$$

In which whose exact solution is given by  $v(x) = \cos x + \sin x$ .

**Item1:** Homotopy Perturbation method (HPM)

The Homotopy function can be constructed from Eq.53 as follows:

$$H(v, p) = v(x) - f(x) - p \int_0^x \int_0^1 (y-z)v(z)dzdy \tag{54}$$

where  $f(x) = \cos x + \sin x - x^2 + \frac{\pi}{2}x$ .

By using Eq.22 into Eq.54 and finding the coefficients from similar powers of  $p$ , we have a sequence of

solutions similar to Eq.46 with  $v_0(x) = f(x) = \cos x + \sin x - x^2 + \frac{\pi}{2}x$ .

Again, in this case, there is no convergent series solution in close agreement with exact solution and increasing the number of iterations is ineffective too.

**Item 2:** Optimal Homotopy Asymptotic method (OHAM)

We construct homotopy function from Eq.2.2 as follows:

$$f(x) = \cos x + \sin x - x^2 + \frac{\pi}{2}x$$

$$H(v, p) = (1-p)(v(x) - f(x)) = H(p) \left( v(x) - f(x) - \int_0^x \int_0^1 (y-z)v(z)dzdy \right) \tag{55}$$

By using Eq.22 into Eq.55 and finding the coefficients from similar powers of  $p$ , we obtain :

$$v_0(x) = f(x) = \cos x + \sin x - x^2 + \frac{\pi}{2}x$$

$$v_1(x) = \frac{1}{192}(96 + \pi^3)(\pi - 2x)xc_1$$

In addition, by using least square method presented in section 2, we find real optimal parameter  $c_1$  as follows:

$$c_1 = -0.755868$$

Therefore, the approximate solution is given by:

$$v(x) = \frac{\pi x}{2} - 0.5(\pi - 2x)x - x^2 + \cos x + \sin x \tag{56}$$

Graph of approximate and exact solutions of Example 4 and its error function are illustrated in Fig.9 and Fig.10. In addition, numerical results have been tabulated in Table 3.

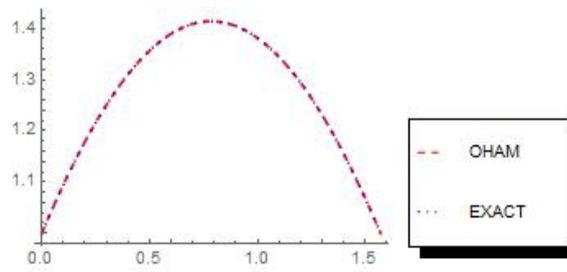


Fig9. Graph of approximate and exact solutions of Example 4 by OHAM.

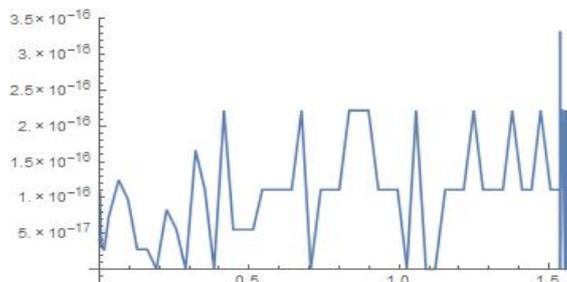


Fig10. The error function of Example 4 by OHAM.

Table3. Approximate and exact solutions with absolute error of Example 3 by OHAM.

$x$	OHAM	Exact solution	Absolute Error
0	1.000000	1.000000	0
$\pi/20$	1.144120	1.144120	0
$2\pi/20$	1.260070	1.260070	0
$3\pi/20$	1.345000	1.345000	0
$4\pi/20$	1.396800	1.396800	0
$5\pi/20$	1.414210	1.414210	0
$6\pi/20$	1.396800	1.396800	0
$7\pi/20$	1.345000	1.345000	0
$8\pi/20$	1.260070	1.260070	0

$9\pi/20$	1.144120	1.144120	0
$\pi/2$	1.000000	1.000000	0

## 8. Results and discussion

The purpose of the present paper is to demonstrate the power of OHAM with respect to HPM in order to find the solutions of mixed Volterra-Fredholm integral equations. We implemented all computations in a laptop by processor 2.53 GHz and we could handle them in OHAM until suitable number of iterations. Therefore, we confront with high cost of computations that occupy a vast space of our memory and it is natural that the process of computations takes a long time especially to compute integral components directly. If we have powerful processors, we can enhance accuracy of the OHAM approximations. Thus, we can conclude that the obtained results of OHAM method can solve mixed Volterra-Fredholm integral equations in just few iterations rather than HPM in high number of iteration and make favorite approximations close to exact solutions. It means that we can find a suitable series solution close to exact solution of expressed examples if we continue to computations in just enough number of iterations. In spite of the cost of computations, the OHAM method is very powerful, reliable, efficient and accurate compared to HPM and many competitive numerical methods that sometimes equations need to be changed before solving the problem by some approaches such as change of variables, Laplace transform, and mesh-based methods by a huge cost of programming and so on. Therefore, we can perform OHAM directly on any favorite problem without any concern. In addition, in cases that we have complicated integrals, quadrature methods such as Trapezoidal and Simpson rules can be used to approximate integral components numerically and it cannot make a problem in general to solve integral equations by implementation of OHAM and HPM.

## 9. Conclusions

In this paper, OHAM and HPM were employed to solve Mixed Volterra-Fredholm integral equations of the second kind. Our approach is time independent. In addition, our comparison shows that OHAM is a powerful method to solve these types of integral equations and we found out that HPM has powerlessness to solve these types of equations for high successive iterations to find an accurate approximation. The Advantage of OHAM with respect to HPM is optimal parameters  $c_i$ . In fact; these parameters play an important role to find approximations with high accuracy. In addition, other types of mixed integral equations can be solved easily by means of OHAM.

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