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Commun.Fac.Sci.Univ.Ank.Ser. A1 Math. Stat. Volume 70, Number 2, Pages 600–611 (2021) DOI: 10.31801/cfsuasmas.792265 ISSN 1303–5991 E-ISSN 2618–6470



Received by the editors: September 8, 2020; Accepted: January 30, 2021

# $S-\delta$ -CONNECTEDNESS IN S-PROXIMITY SPACES

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ABSTRACT. New types of connectedness in S-proximity spaces, named as an S- $\delta$ -connectedness, local S- $\delta$ -connectedness are introduced. Also, their interrelationships are studied. In an S-proximity space  $(X, \delta_X)$ , the S- $\delta$ -connectedness of a subset U of X with respect to  $\delta_X$  may not be same as the S- $\delta$ -connectedness of U with respect to its subspace proximity  $\delta_U$ . Further, S- $\delta$ -component and S- $\delta$ -treelike spaces are also defined and a number of results are given.

#### 1. INTRODUCTION

In 1908, Reisz [13] discussed the idea of proximity (now it is called an E-proximity) and although this idea was revived by Wallace [17, 18]. But the real beginning of E-proximity was due to Efremovič [5, 6] who gave axioms of it as a natural generalization of metric space and topological group. Smirnov [14, 15] demonstrated that a completely regular space always has a compatible E-proximity relation and vice versa. Also, he found the relationship between E-proximity space and uniform space. Several generalizations of E-proximity were defined and studied. The notion of Čech proximity spaces was given by E. Čech [2], later elaborated in [10], [11] and [12]. An S-proximity was introduced independently by Krishna Murti [7], Szymanski [16], Wallace [17, 18].

Mrówka *et al.* [9] defined the notion of  $\delta$ -connectedness in *E*-proximity spaces and after that in 1987, the concepts of local  $\delta$ -connectedness,  $\delta$ -component and  $\delta$ quasi components were introduced by Dimitrijević *et al.* [3]. Dimitrijević *et al.* [4] also studied  $\delta$ -treelike proximity spaces. Recently, Modak *et al.* [8] introduced the weaker form of connectedness (*Cl-Cl*-connectedness) in topological spaces.

In this paper, we introduce a new type of  $\delta$ -connectedness (named as S- $\delta$ -connectedness) in S-proximity spaces and show that S- $\delta$ -connectedness is different

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<sup>2020</sup> Mathematics Subject Classification. Primary 54D40, 03E15; Secondary 54E05.

Keywords and phrases. S-proximity space,  $\delta$ -connected,  $\delta$ -component, locally  $\delta$ -connected,  $\delta$ -treelike.

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from  $\delta$ -connectedness [9] in the category of S-proximity spaces. And it become identical in the categories of L-proximity spaces and E-proximity spaces. We give a characterization for an S-proximity space X to be S- $\delta$ -connected and several other properties analogous to  $\delta$ -connectedness are justified. Relation among different types of connectedness are shown. In the last section, S- $\delta$ -component, local S- $\delta$ -connectedness and S- $\delta$ -treelike spaces are defined and their properties are studied.

Throughout this paper,  $(A, B) \in \delta$   $((A, B) \notin \delta)$  denotes A, B are near ( $\delta$ -separated). We write an S-proximity space as X instead of  $(X, \delta)$  whenever there is no confusion of the S-proximity  $\delta$ .  $Cl_X(.)$  and  $int_X(.)$  are used to denote closure and interior, respectively, with respect to topology  $\mathcal{T}_{\delta}$  generated by  $\delta$  in X.

## 2. Preliminaries

In this section, we recall some important definitions and results that will be used in subsequent sections.

**Definition 1.** [10] For a nonempty set X, a Čech proximity (or basic proximity) on X is a binary relation  $\delta$  on the power set of X,  $\mathcal{P}(X)$ , that satisfies the following axioms for all A, B,  $C \in \mathcal{P}(X)$ :

(i) If  $(A, B) \in \delta$ , then  $(B, A) \in \delta$ .

- (ii) If  $(A, B) \in \delta$ , then  $A \neq \phi$  and  $B \neq \phi$ .
- (iii) If  $A \cap B \neq \phi$ , then  $(A, B) \in \delta$ .
- (iv)  $(A, B \cup C) \in \delta$  if and only if  $(A, B) \in \delta$  or  $(A, C) \in \delta$ .

The set X together with a Čech proximity  $\delta$  is called a Čech proximity space  $(X, \delta)$ .

**Definition 2.** [10] A Čech proximity space X is called separated if we have  $(\{x\}, \{y\}) \in \delta$ , then x = y for all  $x, y \in X$ .

**Definition 3.** [10, 12] For  $A, B, C \in \mathcal{P}(X)$ , a Čech proximity  $\delta$  on a set X is:

- (i) E-proximity if  $(A, B) \notin \delta$ , then there is some  $E \subset X$  with  $(A, E) \notin \delta$  and  $(X \setminus E, B) \notin \delta$ .
- (ii) L-proximity if  $(A, B) \in \delta$  and  $(\{b\}, C) \in \delta$  for each  $b \in B$ , then  $(A, C) \in \delta$ .
- (iii) S-proximity if  $(\{x\}, B) \in \delta$  and  $(\{b\}, C) \in \delta$  for each  $b \in B$ , then  $(x, C) \in \delta$ .

A Čech proximity space  $(X, \delta)$  is called an *E*-proximity space (or a *L*-proximity space, an *S*-proximity space respectively) if the Čech proximity  $\delta$  satisfies the *E*-proximity axiom (or *L*-proximity axiom, *S*-proximity axiom respectively.).

**Definition 4.** [10, 12] Let  $(X, \delta)$  be an S-proximity space and  $\mathcal{T}$  be a topology on X. Then  $\delta$  is compatible with  $\mathcal{T}$  if and only if the generated topology  $\mathcal{T}_{\delta}$  and  $\mathcal{T}$  are equal.

**Definition 5.** [10] Let  $(X, \delta)$  be a Čech proximity space. Then a subset V of X is said to be a  $\delta$ -neighbourhood of  $U \subset X$  if  $(U, X \setminus V) \notin \delta$ .

**Definition 6.** [10, 12] Let  $(X, \delta)$  and  $(Y, \delta')$  be two *E*-proximity spaces, a function  $f: (X, \delta) \longrightarrow (Y, \delta')$  is  $\delta$ -continuous (or p-continuous) if for all  $A, B \subset X$  such that  $(A, B) \in \delta$ , implies  $(f(A), f(B)) \in \delta'$ .

**Definition 7.** [9] Let  $(X, \delta)$  be an *E*-proximity space. Then *X* is said to be  $\delta$ -connected if every  $\delta$ -continuous map from *X* to discrete proximity space is constant.

**Theorem 8.** [9] Let  $(X, \delta)$  be an *E*-proximity space. Then the following statements are equivalent:

- (i) X is  $\delta$ -connected.
- (ii)  $(A, X \setminus A) \in \delta$  for each nonempty subset A with  $A \neq X$ .
- (iii) For every  $\delta$ -continuous real-valued function f, the image f(X) is dense in some interval of  $\mathbb{R}$ .
- (iv) If  $X = A \cup B$  and  $(A, B) \notin \delta$ , then either  $A = \phi$  or  $B = \phi$ .

However, if X is not  $\delta$ -connected, then by Theorem 8 (*iv*) we have  $X = A \cup B$  with  $(A, B) \notin \delta$  where  $A, B \subset X$  are nonempty. Here, the pair (A, B) forms a  $\delta$ -separation for X.

**Definition 9.** [3] Let  $(X, \delta)$  be an *E*-proximity space and  $Y \subset X$ . Then *Y* is  $\delta$ -connected, if it is  $\delta$ -connected with respect to the subspace proximity of *Y*.

**Definition 10.** [3] An E-proximity space X is locally  $\delta$ -connected if for every point x of X and for every  $\delta$ -neighborhood U of x, there exists some  $\delta$ -connected  $\delta$ -neighborhood V of x such that  $x \in V \subset U$ .

**Definition 11.** [7, 10] Let  $(X, \delta_X)$  and  $(Y, \delta_Y)$  be S-proximity spaces. Then a map  $f: X \longrightarrow Y$  is said to be S- $\delta$ -continuous if  $(A, B) \notin \delta_X$  implies  $(f(A), f(B)) \notin \delta_Y$ , for all  $A, B \subset X$ .

**Definition 12.** [8] Let (X, T) be a topological space. A pair of non-empty subsets A, B of X is called Cl - Cl-separated (weak separated) if  $Cl(A) \cap Cl(B) = \phi$ . A subset U of a space X is said to be Cl - Cl-connected (weak connected) if U is not the union of two Cl - Cl-separated (weak separated) sets in X.

**Definition 13.** [4] If an E-proximity space X can be written as  $X = P \cup Q$  with  $(P,Q) \notin \delta$ , then the pair (P,Q) is said to be a separation for X and write it as X = P + Q. If P contains some set A and Q contains B, then it can be written as X = P(A) + Q(B).

**Definition 14.** [4] Let X be an E-proximity space. Then it is called  $\delta$ -treelike if it is  $\delta$ -connected, and for each pair (x, y) of distinct points in X there is a  $\delta$ -connected set V such that  $X \setminus V = P(x) + Q(y)$ .

### 3. S- $\delta$ -connectedness

In this section, we define S- $\delta$ -connectedness in S-proximity spaces and give characterizations of it.

Recall that every discrete proximity is an S-proximity and induces the discrete topology.

**Definition 15.** An S-proximity space X is said to be S- $\delta$ -connected if every S- $\delta$ -continuous map from X to discrete space is constant.

Next, we give a characterization for an S-proximity space to be S- $\delta$ -connected.

**Theorem 16.** For an S-proximity space X, the following statements are equivalent:

- (i) X is S- $\delta$ -connected.
- (ii)  $(Cl_X(A), X \setminus A) \in \delta$  for all nonempty proper subset A of X.
- (iii) If  $X = P \cup Q$  with  $(Cl_X(P), Q) \notin \delta$  or  $(P, Cl_X(Q)) \notin \delta$ , then either  $P = \phi$ or  $Q = \phi$ .

*Proof.*  $(i) \Rightarrow (ii)$ . If  $(Cl_X(A), X \setminus A) \notin \delta$  for some nonempty proper subset A of X, then the map  $f : X \longrightarrow \{0, 1\}$  defined as  $f(A) = \{0\}$  and  $f(X \setminus A) = \{1\}$  is non-constant, S- $\delta$ -continuous map. Therefore, X is not S- $\delta$ -connected.

 $(ii) \Rightarrow (iii)$ . If  $X = P \cup Q$ , where P, Q are nonempty subsets such that  $(Cl_X(P), Q) \notin \delta$  or  $(P, Cl_X(Q)) \notin \delta$ , then  $Q = X \setminus P$ . Thus,  $(Cl_X(P), X \setminus P) \notin \delta$ , a contradiction.

 $(iii) \Rightarrow (i)$ . If X is not S- $\delta$ -connected, then the map  $f : (X, \delta) \longrightarrow \{0, 1\}$  defined as  $f(P) = \{0\}$  and  $f(Q) = \{1\}$  is non-constant, surjective, S- $\delta$ -continuous map. Therefore,  $X = P \cup Q$ , where P, Q are nonempty subsets such that  $(Cl_X(P), Q) \notin \delta$ or  $(P, Cl_X(Q)) \notin \delta$ , a contradiction.

**Definition 17.** Let X be an S-proximity space. A pair (P,Q) of two nonempty subsets of X is said to be S- $\delta$ -separated in X if  $(Cl_X(P),Q) \notin \delta$  or  $(P,Cl_X(Q)) \notin \delta$ .

Every S- $\delta$ -separated sets are always  $\delta$ -separated. However, converse need not be true.

**Example 18.** Let  $X = \mathbb{R}$  be the real line. For  $P, Q \subset X$ , define a binary relation  $\delta$  on  $\mathcal{P}(X)$  as:

 $(P,Q) \in \delta$  if and only if  $(\bar{P} \cap Q) \cup (P \cap \bar{Q}) \neq \phi$ 

Here  $\overline{P}$  and  $\overline{Q}$  denote the closure of P and Q in X, respectively. Then  $\delta$  is a compatible S-proximity on X which is not an L-proximity. The pair P = (1, 2) and Q = (2, 3) is  $\delta$ -separated, but not S- $\delta$ -separated in X.

**Definition 19.** Let  $(X, \delta_X)$  be an S-proximity space and  $U \subset X$ . Then U is said to be S- $\delta$ -connected in X (that is, with respect to  $\delta_X$ ) if it cannot be written as the union of a pair of two S- $\delta$ -separated sets in X. If U is not S- $\delta$ -connected, then it is called S- $\delta$ -disconnected and the pair of two S- $\delta$ -separated sets is called S- $\delta$ -separation for U in X.

By an S- $\delta$ -connected subset U of an S-proximity space  $(X, \delta_X)$ , we mean it is an S- $\delta$ -connected with respect to  $\delta_X$  (that is, with respect to the proximity of X not subspace proximity of U). Since every S- $\delta$ -separation for a set always forms  $\delta$ -separation, therefore every  $\delta$ -connected set is S- $\delta$ -connected. But converse need not be true.

**Example 20.** Let  $X = \mathbb{R}$  be the real line and  $\delta$  be a S-proximity on X defined as in Example 18. Let  $U = (1, 2) \cup (2, 3)$ . Then U is S- $\delta$ -connected, but not  $\delta$ -connected subset of X.

Thus, S- $\delta$ -connectedness is different from  $\delta$ -connectedness in general. Next, we know that  $\delta$ -connectedness [9] of a subset U in E-proximity space  $(X, \delta_X)$  is same as the  $\delta$ -connectedness of U with respect to subspace proximity  $\delta_U$ . But, it is not true for the case of an S- $\delta$ -connectedness. In Example 20, note that U is S- $\delta$ -connected with respect to  $\delta_X$ , and with respect to  $\delta_U$ , it is not S- $\delta$ -connected as  $Cl_U((0,1)) = (0,1)$  and  $Cl_U((1,2)) = (1,2)$  with respect to  $\delta_U$ . But, if U is S- $\delta$ -connected with respect to  $\delta_U$ , then it is also S- $\delta$ -connected with respect to  $\delta_X$ .

**Remark 21.** The notions of  $\delta$ -connectedness and S- $\delta$ -connectedness are equivalent in the category of L-proximity spaces, as for every L-proximity space X, we have  $(P,Q) \in \delta$  if and only if  $(Cl_X(P), Cl_X(Q) \in \delta$  for all non-empty P, Q in X.

Since every E-proximity is an L-proximity, so above remark holds for E-proximity spaces.

Recall that if for all  $A, B \subset X$ ,  $(A, B) \in \delta_1$  implies  $(A, B) \in \delta_2$ , then  $\delta_1 > \delta_2$ .

**Corollary 22.** Let  $\delta_1, \delta_2$  be two S-proximities on X such that  $\delta_1 > \delta_2$ . If X is S- $\delta_1$ -connected, then so is S- $\delta_2$ -connected.

**Theorem 23.** Let X be an S-proximity space. Suppose M is an S- $\delta$ -connected subset of X and (P,Q) be a pair of S- $\delta$ -separated sets in X such that  $M \subset P \cup Q$ . Then either  $M \subset P$  or  $M \subset Q$ .

*Proof.* If possible,  $M \notin P$  and  $M \notin Q$ . M is S- $\delta$ -connected set such that  $M \subset P \cup Q$ . Therefore,  $M = (M \cap P) \cup (M \cap Q)$ . Also by hypothesis  $(Cl_X(P), Q) \notin \delta$  or  $(P, Cl_X(Q)) \notin \delta$ . If  $(Cl_X(P), Q) \notin \delta$ , then  $(Cl_X(M \cap P), M \cap Q) \notin \delta$ . On the other hand, if  $(P, Cl_X(Q)) \notin \delta$ , then  $(Cl_X(M \cap Q), M \cap P) \notin \delta$ . Thus, the pair  $M \cap P$  and  $M \cap Q$  forms an S- $\delta$ -separation for X.

**Theorem 24.** Let M, N are two S- $\delta$ -connected subsets of an S-proximity space X. If (M, N) is not S- $\delta$ -separated, then  $M \cup N$  is S- $\delta$ -connected in X.

*Proof.* Suppose (P, Q) be an S- $\delta$ -separation for  $M \cup N$ . Therefore,  $M \cup N = P \cup Q$  where  $(Cl_X(P), Q) \notin \delta$  or  $(P, Cl_X(Q)) \notin \delta$ . Since M and N are S- $\delta$ -connected. Thus, by Theorem 23, two case arises:

Case (i). If  $M \subset P$  and  $N \subset Q$ , then  $(Cl_X(M), N) \notin \delta$  or  $(M, Cl_X(N)) \notin \delta$ , because  $(Cl_X(P), Q) \notin \delta$  or  $(P, Cl_X(Q)) \notin \delta$ . Hence, (M, N) is S- $\delta$ -separated which is a contradiction.

Case (*ii*). If  $M \subset Q$  and  $N \subset P$ , then  $(Cl_X(N), M) \notin \delta$  or  $(N, Cl_X(M)) \notin \delta$ , because  $(Cl_X(P), Q) \notin \delta$  or  $(P, Cl_X(Q)) \notin \delta$ . Hence, (M, N) is S- $\delta$ -separated which is a contradiction.

**Theorem 25.** Let  $\{W_j : j \in J\}$  be a nonempty family of S- $\delta$ -connected subsets of an S-proximity space X. If there exists some  $j_0 \in J$  such that  $(W_{j_0}, W_j) \in \delta$  for all  $j \in J$ , then  $\bigcup_{i \in J} W_j$  is also S- $\delta$ -connected in X.

Proof. If possible, there exists an S- $\delta$ -separation (P,Q) such that  $\bigcup_{j\in J} W_j = P \cup Q$ with  $(Cl(P),Q) \notin \delta$  or  $(P,Cl(Q)) \notin \delta$ . Therefore,  $W_{j_0} \subset P \cup Q$  which implies either  $W_{j_0} \subset P$  or  $W_{j_0} \subset Q$ . If  $W_{j_0} \subset P$ , then  $W_j \subset P$  for all  $j \in J$  because  $(W_{j_0}, W_j) \in \delta$ for all  $j \in J$ . Thus  $\bigcup_{j\in J} W_j \subset P$  so  $Q = \phi$ . Similarly, if  $W_{j_0} \subset Q$ , then  $P = \phi$ . Thus,  $\bigcup_{i\in J} W_j$  is S- $\delta$ -connected.

**Corollary 26.** If  $\{W_j : j \in J\}$  is a nonempty family of S- $\delta$ -connected subsets of an S-proximity space X and  $\bigcap_{j \in J} W_j \neq \phi$ , then  $\bigcup_{j \in J} W_j$  is also S- $\delta$ -connected in X.

*Proof.* Since  $\bigcap_{j \in J} W_j \neq \phi$ , therefore  $(W_i, W_j) \in \delta$  for all  $i, j \in J$ . So for some fix  $j_0 \in J$ ,  $(W_{j_0}, W_j) \in \delta$  for all  $j \in J$ . Thus, by Theorem 25,  $\bigcup_{j \in J} W_j$  is S- $\delta$ -connected in X.

**Corollary 27.** If Y is an S- $\delta$ -connected subset of an S-proximity space X, then every subset Z such that  $Y \subset Z \subset Cl_X(Y)$  is also S- $\delta$ -connected in X.

*Proof.* Note that  $\{Y \cup \{z\} : z \in Z\}$  is a family of S- $\delta$ -connected sets such that Y is near to each of the set. Therefore, by Theorem 25, Z is S- $\delta$ -connected.

**Corollary 28.** If an S-proximity space X contains some S- $\delta$ -connected dense subset, then X is S- $\delta$ -connected.

*Proof.* Let Y be an S- $\delta$ -connected dense subset of X. Then,  $Cl_X(Y) = X$ . Therefore, by Corollary 27, X is S- $\delta$ -connected.

**Lemma 29.** Let X be an S-proximity space and  $\{M_i : i \in I\}$  be a nonempty family of S- $\delta$ -connected subsets of X. If M is S- $\delta$ -connected in X such that  $M \cap M_i \neq \phi$ for all  $i \in I$ , then  $M \cup (\bigcup_{i \in I} M_i)$  is also S- $\delta$ -connected in X.

*Proof.* By Theorem 25,  $(M, M_i) \in \delta$  for all  $i \in I$ . Hence the proof follows.

**Corollary 30.** In an S-proximity space X, if any two points can be joined by an S- $\delta$ -connected subset of X, then X is S- $\delta$ -connected.

*Proof.* Fix a point  $x_0$  in X and let  $M_x$  be an S- $\delta$ -connected subset of X which joins  $x_0$  and x. By Lemma 29,  $M = \{x_0\}$  and  $M \cap M_x \neq \phi$  for all  $x \in X$ . Thus,  $M \cup (\bigcup_{x \in X} M_x) = X$  is S- $\delta$ -connected.

**Theorem 31.** The S- $\delta$ -continuous image of S- $\delta$ -connected space is S- $\delta$ -connected.

Proof. Let  $f : (X, \delta) \longrightarrow (Y, \delta')$  be S- $\delta$ -continuous, surjective map and X is S- $\delta$ connected space. It is to show that Y is also an S- $\delta$ -connected space. On contrary, suppose Y is not S- $\delta$ -connected space. So, there exists a pair (P,Q) in Y such that  $Y = P \cup Q$  with  $(Cl_Y(P), Q) \notin \delta'$  or  $(P, Cl_Y(Q)) \notin \delta'$ . If  $(Cl_Y(P), Q) \notin \delta'$ , then  $(f^{-1}(Cl_Y(P)), f^{-1}(Q)) \notin \delta$ . Since S- $\delta$ -continuity of f implies continuity with respect to  $\mathcal{T}_{\delta}$ , so  $Cl_X(f^{-1}(P)) \subset f^{-1}(Cl_Y(P))$ . Thus,  $(Cl_X(f^{-1}(P)), f^{-1}(Q)) \notin \delta$ . Hence,  $(f^{-1}(P), f^{-1}(Q))$  forms an S- $\delta$ -separation for X, a contradiction. A similar case for  $(P, Cl_Y(Q)) \notin \delta'$ .

As every S- $\delta$ -continuous map is continuous, so every weak connected [8] space is S- $\delta$ -connected.

**Example 32.** The set of rationals  $\mathbb{Q}$  is an S- $\delta$ -connected in  $\mathbb{R}$ , but is not weak connected.

However, compact Hausdorff S- $\delta$ -connected space is weak connected as every continuous map with compact Hausdorff domain is S- $\delta$ -continuous. Thus, we have the following diagram of implications.

$$\begin{array}{ccc} \delta - \text{connected} & \longleftarrow & \text{connected} \\ & \downarrow & & \downarrow \\ S - \delta - \text{connected} & \longleftarrow & \text{weak connected} \end{array}$$

Following example concludes that a locally  $\delta$ -connected space may not be an S- $\delta$ -connected.

**Example 33.** Let  $\mathbb{R}$  be the real line and  $\delta$  be a compatible S-proximity defined as in Example 18. Let  $X = (-1, 0) \cup (2, 3)$ . Then the pair (P, Q) where P = (-1, 0) and Q = (2, 3), is S- $\delta$ -separation for X. Therefore X is not S- $\delta$ -connected in  $\mathbb{R}$ , but it is locally  $\delta$ -connected.

An S- $\delta$ -connected space may not be locally  $\delta$ -connected.

**Example 34.** The closed Topologist's Sine curve  $T = \{(x, \sin(1/x)) : 0 < x \leq 1\} \cup \{(0, y) : -1 \leq y \leq 1\}$  with subspace *E*-proximity induced by  $\mathbb{R}^2$  is *S*- $\delta$ -connected in  $\mathbb{R}^2$ , but not locally  $\delta$ -connected.

**Theorem 35.** Suppose  $\{(X_i, \delta_i) : i \in I\}$  be a nonempty family of S-proximity spaces. Then the product  $(X, \delta) = \prod\{(X_i, \delta_i) : i \in I\}$  is S- $\delta$ -connected if and only if  $X_i$  is S- $\delta$ -connected for each  $i \in I$ .

*Proof.* Let  $\prod_{i \in I} X_i$  be S- $\delta$ -connected. Since S- $\delta$ -continuous image of S- $\delta$ -connected set is S- $\delta$ -connected, therefore  $X_i$  is S- $\delta$ -connected for each  $i \in I$  as projections are S- $\delta$ -continuous, surjective maps.

Conversely, assume that each  $X_i$  is S- $\delta$ -connected. Firstly, take  $I = \{1, 2\}$ . Then in  $X_1 \times X_2$ , any two distinct points  $(x_1, x_2)$  and  $(y_1, y_2)$  can be connected by the S- $\delta$ -connected set  $(X_1 \times \{x_2\}) \cup (\{y_1\} \times X_2)$ . Therefore,  $X_1 \times X_2$  is S- $\delta$ -connected. Using induction, it can be shown that any finite product of S- $\delta$ -connected set is S- $\delta$ -connected. Now, for an arbitrary product, choose  $x_i \in X_i$  for all  $i \in I$ . Consider a family  $\mathcal{F}$  consisting of all finite subsets of the set I and put  $K_F = \prod_{i \in I} L_i$  for all  $F \in \mathcal{F}$  with  $L_i = X_i$  if  $i \in F$  and  $L_i = \{x_i\}$  if  $i \notin F$ . Then,  $\{K_F : F \in \mathcal{F}\}$  is

a family of S- $\delta$ -connected sets by induction hypothesis. Therefore,  $K = \bigcup_{F \in \mathcal{F}} K_F$  is S- $\delta$ -connected as  $\bigcap_{F \in \mathcal{F}} K_F \neq \phi$ . Since K is dense in  $\prod_{i \in I} X_i$ , therefore by Corollary 28,  $\prod_{i \in I} X_i$  is S- $\delta$ -connected.

**Definition 36.** For given S-proximity spaces  $(X, \delta)$  and  $(Y, \delta')$ , S- $\delta$ -continuous map  $f : X \longrightarrow Y$  is said to be S- $\delta$ -monotone if for every  $y \in Y$ , the pullback  $f^{-1}(y)$  is S- $\delta$ -connected in X.

**Definition 37.** A map  $f : (X, \delta) \longrightarrow (Y, \delta')$  is said to be  $\delta_b$ -map if for every pair of subsets A, B of Y, the following two axioms hold:

- (i) If  $(Cl_X f^{-1}(A), f^{-1}(B)) \notin \delta$ , then  $(Cl_Y(A), B) \notin \delta'_{-}$ .
- (ii) If  $(f^{-1}(A), Cl_X f^{-1}(B)) \notin \delta$ , then  $(A, Cl_Y(B)) \notin \delta'$ .

Following theorem shows that if a map is S- $\delta$ -monotone, surjective,  $\delta_b$ -map, then inverse image of S- $\delta$ -connected set is S- $\delta$ -connected.

**Theorem 38.** Let  $f : (X, \delta) \longrightarrow (Y, \delta')$  be a  $\delta_b$ -map, S- $\delta$ -monotone, surjective map. Then for each S- $\delta$ -connected subset U of Y,  $f^{-1}(U)$  is S- $\delta$ -connected in X.

Proof. Let  $f^{-1}(U)$  be not S- $\delta$ -connected. Then,  $f^{-1}(U) = P \cup Q$  with  $(Cl_X(P), Q) \notin \delta$  or  $(P, Cl_X(Q)) \notin \delta$ . As f is S- $\delta$ -monotone, so for each  $y \in U$ ,  $f^{-1}(y)$  is S- $\delta$ -connected. Thus,  $f^{-1}(y) \subset P$  or  $f^{-1}(y) \subset Q$  for all  $y \in U$ . Now, let us define  $A = \{y \in U : f^{-1}(y) \subset P\}$  and  $B = \{y \in U : f^{-1}(y) \subset Q\}$ . Note that  $P = f^{-1}(A)$ ,  $Q = f^{-1}(B)$  and  $U = A \cup B$ . Since f is  $\delta_b$ - map with  $(Cl_X(P), Q) \notin \delta$  or  $(P, Cl_X(Q)) \notin \delta$ , therefore (A, B) forms an S- $\delta$ -separation for U.

**Definition 39.** In an S-proximity space X, a finite sequence  $U_1, U_2, \dots, U_n$  of subsets of X is called an S- $\delta$ -chain if  $(Cl_X(U_i), U_{i+1}) \in \delta$  and  $(U_i, Cl_X(U_{i+1})) \in \delta$  for all  $i = 1, 2, \dots, n-1$ .

A family  $\mathcal{F}$  of subsets of X is said to be S- $\delta$ -chained in X if for every pair (U, V) of elements of  $\mathcal{F}$ , there is an S- $\delta$ -chain in  $\mathcal{F}$  joining U and V.

**Theorem 40.** Suppose  $\{U_i\}_{i=1}^n$  be a finite family of S- $\delta$ -connected subsets of an S-proximity space X and forms an S- $\delta$ -chain, then  $\bigcup_{i=1}^n U_i$  is S- $\delta$ -connected in X.

*Proof.* The Proof follows by induction on n as it holds for n = 2 by Theorem 24.  $\Box$ 

**Theorem 41.** For an S- $\delta$ -chained family  $\mathcal{F} = \{U_i : i \in I\}$  in X, if each member  $U_i$  is S- $\delta$ -connected in X, then  $U = \bigcup_{i \in I} U_i$  is also S- $\delta$ -connected in X.

Proof. Let  $x, y \in U$  be arbitrary. So, there is some  $i, j \in I$  such that  $x \in U_i$  and  $y \in U_j$ . Thus by hypothesis, there is an S- $\delta$ -chain joining  $U_i$  and  $U_j$ . Therefore, by Theorem 40, union of all the members of this S- $\delta$ -chain is S- $\delta$ -connected. Thus, x and y can be joined by an S- $\delta$ -connected set. Hence, by Corollary 30, U is S- $\delta$ -connected in X.

**Definition 42.** In an S-proximity space X, a cover  $\mathcal{F}$  is said to be an S- $\delta$ -cover if  $(Cl_X(M), N) \in \delta$  and  $(M, Cl_X(N)) \in \delta$  for  $M, N \subset X$ , then there is some  $U \in \mathcal{F}$  such that  $M \cap U \neq \phi$  and  $N \cap U \neq \phi$ .

**Theorem 43.** In an S- $\delta$ -connected space X, every S- $\delta$ -cover is an S- $\delta$ -chained family.

Proof. Assume that  $\mathcal{F} = \{U_i : i \in I\}$  be any S- $\delta$ -cover of X. Suppose there exist  $i, j \in I$  such that  $U_i$  and  $U_j$  can not be joined by any S- $\delta$ -chain in  $\mathcal{F}$ . Now, consider P as the union of all the members of  $\mathcal{F}$  which are joinable with  $U_i$  by some S- $\delta$ -chain  $\mathcal{F}' \subset \mathcal{F}$ , and Q as the union of rest of the elements of  $\mathcal{F}$ . Then note that  $X = P \cup Q$ . Now it is to show that X is not S- $\delta$ -connected, that is,  $(Cl_X(P), Q) \notin \delta$  or  $(P, Cl_X(Q)) \notin \delta$ . Again on the contrary, let  $(Cl_X(P), Q) \in \delta$  and  $(P, Cl_X(Q)) \in \delta$ . Then there exists  $U \in \mathcal{F}$  such that  $U \cap P \neq \phi$  and  $U \cap Q \neq \phi$ . Thus, there is some  $U_m \subset P$  and  $U_n \subset Q$  such that  $U \cap U_m \neq \phi$  and  $U \cap U_n \neq \phi$ . So,  $U_n$  can be joined with  $U_i$  using an S- $\delta$ -chain  $\mathcal{F}'' \subset \mathcal{F}$ , which is absurd.  $\Box$ 

**Theorem 44.** Let X be an S- $\delta$ -connected, separated S-proximity space. If for some  $x \in X, X \setminus \{x\} = P \cup Q$  where (P,Q) is S- $\delta$ -separated in X, then  $(\{x\}, Cl_X(P)) \in \delta$  and  $(\{y\}, Cl_X(Q)) \in \delta$ .

*Proof.* If  $(\{x\}, Cl_X(P)) \notin \delta$ , then  $(\{x\}, P) \notin \delta$ . Since pair (P, Q) is S- $\delta$ -separated in X and X is separated, therefore it is easy to conclude that X is not S- $\delta$ -connected, a contradiction. Similarly, conclude that  $(\{y\}, Cl_X(Q)) \in \delta$ .

#### 4. Local S- $\delta$ -connectedness

In this section, local S- $\delta$ -connectedness is defined and it's several properties are studied.

**Definition 45.** The S- $\delta$ -component of a subset U in an S-proximity space X is defined as the union of all S- $\delta$ -connected subsets of X containing U and it is denoted by  $C^*_{\delta}(U)$ .

Every  $\delta$ -component is contained in some S- $\delta$ -component. Any S- $\delta$ -component being union of S- $\delta$ -connected sets with nonempty intersection is S- $\delta$ -connected. An S- $\delta$ -component being a maximal S- $\delta$ -connected set is  $\mathcal{T}_{\delta}$ -closed.

Analogously, the S- $\delta$ -component of a point x can be defined as the union of all S- $\delta$ -connected subsets of X containing x. Note that S- $\delta$ -components of any two distinct points of X are either same or  $\delta$ -far sets in X.

In the next theorem, we show that the S- $\delta$ -component of product S-proximity is exactly the product of S- $\delta$ -components of each S-proximity.

**Theorem 46.** Suppose  $\{(X_i, \delta_i) : i \in I\}$  be a nonempty family of S-proximity spaces. Then the S- $\delta$ -component of the product  $(X, \delta) = \prod\{(X_i, \delta_i) : i \in I\}$  coincides with the product  $\prod\{C^*_{\delta_i}(x_i) : i \in I\}$  of each S- $\delta$ -component of the point  $x_i \in X_i$ .

Proof. Let  $C^*_{\delta}(x)$  be the S- $\delta$ -component of x in X and for each  $i \in I$ ,  $C^*_{\delta_i}(x_i)$ be the S- $\delta$ -component of  $x_i$  in  $X_i$ . Then,  $\prod\{C^*_{\delta_i}(x_i) : i \in I\}$  being the product of the S- $\delta$ -connected sets is S- $\delta$ -connected. Therefore it is contained in  $C^*_{\delta}(x)$ . Conversely, for each  $i \in I$ ,  $p_i C^*_{\delta}(x)$  being S- $\delta$ -continuous image of S- $\delta$ -connected set is S- $\delta$ -connected. Therefore,  $p_i C^*_{\delta}(x) \subset C^*_{\delta_i}(x_i)$  for each  $i \in I$ . Hence,  $C^*_{\delta}(x) \subset$  $\prod\{p_i C^*_{\delta}(x) : i \in I\} \subset \prod\{C^*_{\delta_i}(x_i) : i \in I\}$ .

Next, we show that S- $\delta$ -component is preserved under an S- $\delta$ -monotone, surjective,  $\delta_b$ -map

**Theorem 47.** Suppose  $f: (X, \delta) \longrightarrow (Y, \delta')$  be S- $\delta$ -monotone, surjective and  $\delta_b$ map. Then  $C^*$  is an S- $\delta$ -component of  $W \subset Y$  if and only if  $f^{-1}(C^*)$  is an S- $\delta$ component of  $f^{-1}(W)$ .

Proof. Assume that  $C^*$  is S- $\delta$ -component of subspace  $W \subset Y$ . Obviously,  $f^{-1}(C^*)$  is S- $\delta$ -connected by Theorem 38. Now, suppose there is some S- $\delta$ -connected set M in  $f^{-1}(W)$  such that  $f^{-1}(C^*) \subset M \subset f^{-1}(W)$ . Since the map f is surjective, therefore  $C^* \subset f(M) \subset W$ . As f is S- $\delta$ -continuous being S- $\delta$ -monotone, so f(M) is S- $\delta$ -connected. Thus,  $f(M) = C^*$  which implies  $f^{-1}(C^*) = M$ .

Conversely, let  $f^{-1}(C^*)$  be an S- $\delta$ -component of  $f^{-1}(W)$ . Therfore,  $f^{-1}(C^*)$ is S- $\delta$ -connected subset of  $f^{-1}(W)$  and f is S- $\delta$ -continuous being S- $\delta$ -monotone. Thus,  $C^*$  is S- $\delta$ -connected subset of W. Now, suppose that N be an S- $\delta$ -connected set such that  $C^* \subset N \subset W$ . Then,  $f^{-1}(C^*) \subset f^{-1}(N) \subset f^{-1}(W)$  and  $f^{-1}(N)$ is S- $\delta$ -connected by Theorem 38. Hence, by hypothesis,  $f^{-1}(C^*) = f^{-1}(N)$  which implies  $C^* = N$ .

**Definition 48.** Let X be an S-proximity space. Then X is locally S- $\delta$ -connected at  $x \in X$ , if every  $\delta$ -neighbourhood of x contains some S- $\delta$ -connected  $\delta$ -neighbourhood of x. We call X is locally S- $\delta$ -connected if it is locally S- $\delta$ -connected for all  $x \in X$ . Further, a subset  $Y \subset X$  is locally S- $\delta$ -connected if Y is locally S- $\delta$ -connected in the subspace S-proximity of X.

Now, we show that locally S- $\delta$ -connectedness and S- $\delta$ -connectedness are two independent concepts.

**Example 49.** (a). Let X be any discrete proximity space with  $|X| \ge 2$ . Then X is locally S- $\delta$ -connected, but it is not S- $\delta$ -connected.

(b). Suppose X be an S-proximity space defined as in Example 33. Then X is locally S- $\delta$ -connected, but not S- $\delta$ -connected.

**Example 50.** The closed Topologist's sine curve  $T = \{(x, \sin(1/x)) : 0 < x \leq 1\} \cup \{(0, y) : -1 \leq y \leq 1\}$  with subspace E-proximity induced by  $\mathbb{R}^2$  is S- $\delta$ -connected, but not locally S- $\delta$ -connected.

**Example 51.** The subspace  $X = \{0\} \cup \{1/n : n \in \mathbb{N}\}$  of  $\mathbb{R}$  with S-proximity defined as in Example 18. Then X is not locally S- $\delta$ -connected.

**Theorem 52.** Suppose  $x \in P \cap Q$ , where P and Q are locally S- $\delta$ -connected sets at x. Then  $P \cup Q$  is also locally S- $\delta$ -connected at x.

*Proof.* Let W be a  $\delta$ -neighbourhood of the point x. Then,  $W_P = W \cap P$  and  $W_Q = W \cap Q$  are  $\delta$ -neighbourhoods of the point x in P and Q respectively. Using hypothesis, there exist some S- $\delta$ -connected  $\delta$ -neighbourhoods  $M_P$  and  $M_Q$  of x such that  $M_P \subset W_P$  and  $M_Q \subset W_Q$ . Then,  $x \in M_P \cup M_Q \subset W_P \cup W_Q$  such that  $M_P \cup M_Q$  is S- $\delta$ -connected set. Also,  $(\{x\}, (P \setminus M_P) \cup (Q \setminus M_Q)) \notin \delta$  which implies  $(\{x\}, (P \cup Q) \setminus (M_P \cup M_Q) \notin \delta$ . Therefore,  $M_P \cup M_Q$  is a  $\delta$ -neighbourhood of x.  $\Box$ 

**Theorem 53.** If an S-proximity space X is locally S- $\delta$ -connected, then S- $\delta$ -component of every  $\mathcal{T}_{\delta}$ -open subspace of X is  $\mathcal{T}_{\delta}$ -open.

Proof. Assme that X is locally S- $\delta$ -connected and W be  $\mathcal{T}_{\delta}$ -open subspace in X. Let  $C^*$  be an S- $\delta$ -component of W. If  $y \in C^*$ , then  $(\{y\}, X \setminus W) \notin \delta$ . Therefore W is a  $\delta$ -neighbourhood of y. Since X is locally S- $\delta$ -connected, then there exists an S- $\delta$ -connected  $\delta$ -neighbourhood M of y such that  $y \in M \subset W$ . But  $C^*$  is maximal S- $\delta$ -connected set containing y, so  $y \in M \subset C^*$ . Therefore,  $C^*$  is  $\mathcal{T}_{\delta}$ -open.

**Corollary 54.** If X is locally S- $\delta$ -connected space, then S- $\delta$ -components of X are clopen sets in the induced topology  $T_{\delta}$ .

**Corollary 55.** If an S-proximity space X is locally S- $\delta$ -connected and compact, then it has at most finite number of S- $\delta$ -components.

**Definition 56.** Let U be a subset of an S-proximity space X. Then it is called an S- $\delta$ -treelike in X if it is S- $\delta$ -connected and for each pair of points  $x, y \in U$  there exists an S- $\delta$ -connected set  $V \subset U$  in X such that  $U \setminus V = P \cup Q$  where  $x \in P$ ,  $y \in Q$  and the pair (P,Q) is S- $\delta$ -separated in X.

Example 20 shows that there exists an S- $\delta$ -treelike S-proximity space which is not  $\delta$ -treelike [4], and from Example 32 we conclude that there exists an S- $\delta$ -treelike S-proximity space which is not treelike [1] (Topologically).

**Theorem 57.** If an S-proximity space X is S- $\delta$ -treelike, then it is separated.

*Proof.* Suppose X is not separated. So, there exist two distinct points x, y in X such that  $(\{x\}, \{y\}) \in \delta$ . Thus,  $\{x, y\}$  is S- $\delta$ -connected in X. Since X is an S- $\delta$ -treelike space, therefore there exists an S- $\delta$ -connected set U in X such that  $X \setminus U = P \cup Q$  where  $x \in P$ ,  $y \in Q$  and the pair (P, Q) is S- $\delta$ -separated in X. Then the pair  $P \cap \{x, y\}$  and  $Q \cap \{x, y\}$  forms an S- $\delta$ -separation for  $\{x, y\}$ , a contradiction.  $\Box$ 

Authors Contribution Statement All the authors have contributed equally in the making of this paper.

**Declaration of Competing Interests** The authors of this paper declare that there are no conflicts of interest about publication of the paper.

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