UJMA

Universal Journal of Mathematics and Applications

Journal Homepage: www.dergipark.gov.tr/ujma ISSN: 2619-9653



On polar relative normalizations of ruled surfaces

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Article Info

Abstract

Keywords: Pick invariant, Polar normalizations, Ruled surfaces, Tchebychev vector field 2010 AMS: 53A25, 53A05, 53A15, 53A40. Received: 14 February 2018 Accepted: 18 March 2018 Available online: 26 June 2018 This paper deals with skew ruled surfaces in the Euclidean space \mathbb{E}^3 which are equipped with polar normalizations, that is, relative normalizations such that the relative normal at each point of the ruled surface lies on the corresponding polar plane. We determine the invariants of a such normalized ruled surface and we study some properties of the Tchebychev vector field and the support vector field of a polar normalization. Furthermore, we study a special polar normalization, the relative image of which degenerates into a curve.

1. Introduction

In 1989 F. Manhart introduced the one-parameter family of relative normalizations ${}^{(a)}\overline{y}$ of a hypersurface with non-vanishing Gaussian curvature \widetilde{K} in the Euclidean space \mathbb{E}^{n+1} which are characterized by the support functions ${}^{(a)}q = |\widetilde{K}|^a$, $a \in \mathbb{R}$ and called Manhart's normalizations (see [2]).

G. Stamou and A. Magkos in [9] and G. Stamou, St. Stamatakis and I. Delivos in [10] studied ruled surfaces in the Euclidean space \mathbb{E}^3 which are equipped with Manhart's normalizations. Later, S. Stamatakis and I. Kaffas studied in [5] the asymptotic relative normalizations of a ruled surface Φ , that is, relative normalizations such that the relative normals at each point *P* of Φ lie on the corresponding asymptotic plane of Φ .

Following this idea the authors introduced in [7] three special relative normalizations:

- 1. the *central* normalizations, i.e, relative normalizations such that the relative normals at each point P of Φ lie on the corresponding central plane,
- 2. the *polar* normalizations, i.e, relative normalizations such that the relative normals at each point *P* of Φ lie on the corresponding polar plane and finally
- 3. the *right* normalizations, that is relative normalizations of Φ whose relative images $\overline{\Phi}$ are also ruled surfaces with the additional property that their generators are parallel to those of Φ . Some of these relative normalizations degenerate into a curve.

The central and the right normalizations were studied thoroughly in [7] and [8], respectively. In this paper we will study the polar normalizations.

2. Preliminaries

A brief discussion of some definitions, results and formulae of relative Differential Geometry of surfaces and Differential Geometry of ruled surfaces in the Euclidean space \mathbb{E}^3 appears in this section. We refer the reader to [3] and [4].

In the three-dimensional Euclidean space \mathbb{E}^3 let $\Phi = (U, \bar{x})$ be a ruled C^r -surface of nonvanishing Gaussian curvature, $r \ge 3$, defined by an injective C^r -immersion $\bar{x} = \bar{x}(u, v)$ on a region $U := I \times \mathbb{R}$ ($I \subset \mathbb{R}$ open interval) of \mathbb{R}^2 . We introduce the so-called standard parameters $u \in I, v \in \mathbb{R}$ of Φ , such that

$$\overline{x}(u,v) = \overline{s}(u) + v \overline{e}(u),$$

(2.1)

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and

$$|\overline{e}| = |\overline{e}'| = 1, \quad \langle \overline{s}', \overline{e}' \rangle = 0,$$

where the differentiation with respect to *u* is denoted by a prime and \langle , \rangle denotes the standard scalar product in \mathbb{E}^3 . Here $\Gamma : \bar{s} = \bar{s}(u)$ is the striction curve of Φ and the parameter *u* is the arc length along the spherical curve $\bar{e} = \bar{e}(u)$.

The distribution parameter $\delta(u) := (\bar{s}', \bar{e}, \bar{e}')$, the conical curvature $\kappa(u) := (\bar{e}, \bar{e}', \bar{e}'')$ and the function $\lambda(u) := \cot \sigma$, where $\sigma(u) := \triangleleft(\bar{e}, \bar{s}')$ is the striction of Φ ($-\frac{\pi}{2} < \sigma \leq \frac{\pi}{2}$, sign $\sigma = \operatorname{sign} \delta$), are the fundamental invariants of Φ and determine uniquely the ruled surface Φ up to Euclidean rigid motions. We also consider the central normal vector $\bar{n}(u) := \bar{e}'$ and the central tangent vector $\bar{z}(u) := \bar{e} \times \bar{n}$. It is known that the vectors of the moving frame $\mathscr{D} := \{\bar{e}, \bar{n}, \bar{z}\}$ of Φ fulfil the following equations [3, p. 280]

$$\overline{e}' = \overline{n}, \quad \overline{n}' = -\overline{e} + \kappa \overline{z}, \quad \overline{z}' = -\kappa \overline{n}. \tag{2.2}$$

Then we have

$$\overline{s}' = \delta \lambda \,\overline{e} + \delta \,\overline{z}. \tag{2.3}$$

We denote partial derivatives of a function (or a vector-valued function) f in the coordinates $u^1 := u$, $u^2 := v$ by $f_{/i}$, $f_{/ij}$ etc. Then from (2.1) and (2.3) we take

$$\bar{x}_{/1} = \delta \lambda \, \bar{e} + \nu \bar{n} + \delta \bar{z}, \quad \bar{x}_{/2} = \bar{e}, \tag{2.4}$$

and thus the unit normal vector $\overline{\xi}(u, v)$ to Φ is given by

$$\overline{\xi} = \frac{\delta \overline{n} - v\overline{z}}{w}$$
, where $w := \sqrt{\delta^2 + v^2}$.

Let $I = g_{ij} du^i du^j$ and $II = h_{ij} du^i du^j$, i, j = 1, 2 be the first and the second fundamental form of Φ , respectively, where

$$g_{11} = w^2 + \delta^2 \lambda^2, \qquad g_{12} = \delta \lambda, \qquad g_{22} = 1,$$
 (2.5)

$$h_{11} = -\frac{\kappa w^2 + \delta' v - \delta^2 \lambda}{w}, \qquad h_{12} = \frac{\delta}{w}, \qquad h_{22} = 0.$$
 (2.6)

The Gaussian curvature $\widetilde{K}(u, v)$ and the mean curvature $\widetilde{H}(u, v)$ of Φ are given by (see [3])

$$\widetilde{K} = -\frac{\delta^2}{w^4}, \quad \widetilde{H} = -\frac{\kappa w^2 + \delta' v + \delta^2 \lambda}{2w^3}.$$
(2.7)

A *C*^{*s*}-relative normalization of Φ is a *C*^{*s*}-mapping $\overline{y} = \overline{y}(u, v), 1 \le s < r$, defined on *U*, such that

$$\operatorname{rank}(\{\bar{x}_{/1}, \bar{x}_{/2}, \bar{y}\}) = 3, \operatorname{rank}(\{\bar{x}_{/1}, \bar{x}_{/2}, \bar{y}_{/i}\}) = 2, i = 1, 2, \forall (u, v) \in U.$$

$$(2.8)$$

The pair (Φ, \overline{y}) is called a relatively normalized ruled surface in \mathbb{R}^3 and the straight line issuing from a point $P \in \Phi$ in the direction of \overline{y} is called the relative normal of (Φ, \overline{y}) at *P*. The pair $\overline{\Phi} = (U, \overline{y})$ is called the relative image of (Φ, \overline{y}) .

The support function of the relative normalization \overline{y} is defined by $q(u,v) := \langle \overline{\xi}, \overline{y} \rangle$ (see [1]). For q = 1, we have $\overline{y} = \overline{\xi}$, that is, the normalization is the Euclidean one.

Due to (2.8), q never vanishes on U. Conversely, when a support function q is given, the relative normalization \overline{y} of the ruled surface Φ is uniquely determined and can be expressed in terms of the moving frame \mathscr{D} as follows [5, p. 179]:

$$\overline{y} = y_1 \,\overline{e} + y_2 \,\overline{n} + y_3 \,\overline{z},\tag{2.9}$$

where

$$y_1 = -w \frac{\delta q_{/1} + q_{/2}(\kappa w^2 + \delta' v)}{\delta^2}, \quad y_2 = \frac{\delta^2 q - w^2 v q_{/2}}{\delta w}, \quad y_3 = -\frac{v q + w^2 q_{/2}}{w}.$$
(2.10)

For the coefficients $G_{ij}(u,v)$ of the relative metric G(u,v) of (Φ, \overline{y}) , which is indefinite, we have

$$G_{ij} = q^{-1} h_{ij}. (2.11)$$

Then, because of (2.6), the coefficients of the inverse relative metric tensor are

$$G^{(11)} = 0, \quad G^{(12)} = \frac{wq}{\delta}, \quad G^{(22)} = wq \, \frac{\kappa w^2 + \delta' v - \delta^2 \,\lambda}{\delta^2}. \tag{2.12}$$

For a function (or a vector-valued function) f we denote by $\nabla_i^G f$ the covariant derivatives in the direction of u^i , both with respect to the relative metric. The coefficients $A_{ijk}(u,v)$ of the Darboux tensor are given by

$$A_{ijk} := q^{-1} \langle \overline{\xi}, \nabla_k^G \nabla_j^G \overline{x}_{/i} \rangle.$$

Then, by using the relative metric tensor G_{ij} for "raising and lowering the indices", the Pick invariant J(u, v) of (Φ, \overline{y}) is defined by

$$J := \frac{1}{2} A_{ijk} A^{ijk}.$$

As we proved in [7] (see equation (2.2)) the Pick invariant is calculated by

$$J = \frac{3\left(w^2 q_{/2} + vq\right)}{2\delta^2 w^3 q} \left\{ w^2 \left[\kappa q v + 2\delta q_{/1} + q_{/2} \left(\kappa w^2 + \delta' v - \delta^2 \lambda \right) \right] - \delta^2 q \left(\lambda v - \delta' \right) \right\}.$$
(2.13)

The relative shape operator has the coefficients $B_i^J(u, v)$ given by

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$$\overline{y}_{i} = :-B_i^J \overline{x}_{ij}. \tag{2.14}$$

Then, for the relative curvature K(u, v) and the relative mean curvature H(u, v) of (Φ, \overline{v}) we have

$$K := \det\left(B_i^j\right), \quad H := \frac{B_1^1 + B_2^2}{2}.$$
(2.15)

We conclude this section by mentioning that, among the surfaces of \mathbb{E}^3 with negative Gaussian curvature the ruled surfaces are characterized by the relation

$$3H - J - 3S = 0 (2.16)$$

(see [6]), where S(u, v) is the scalar curvature of the relative metric G of such a surface Φ , which is defined formally as the curvature of the pseudo-Riemannian manifold (Φ , G).

3. Polar normalizations

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We concentrate now on the main topic of this paper, namely the polar normalizations of a skew ruled surface Φ , i.e., relative normalizations such that the relative normal at each point P of Φ lies on the corresponding polar plane $\{P; \overline{n}, \overline{z}\}$. In [7] it was shown that the support function of \overline{y} is of the form

$$q = f(V), \tag{3.1}$$

where f(V) is an arbitrary C^2 -function of

2

$$V = \arctan \frac{v}{\delta} - \int \kappa \mathrm{d}u. \tag{3.2}$$

By means of (2.9), (2.10), (3.1) and (3.2) we deduce that the arising relative normalization, i.e., the polar normalization of the given ruled surface Φ is

$$\overline{y} = \frac{\delta q - \dot{q}v}{w}\overline{n} - \frac{qv + \delta \dot{q}}{w}\overline{z},\tag{3.3}$$

where the dot denotes the differentiation with respect to V. Then, from (2.2), (2.4), (2.14) and (3.3), we take the coefficients B_i^j of the relative shape operator of a polar normalization:

$$\begin{split} B_1^1 &= -\frac{(\kappa w^2 + \delta' v)(q + \ddot{q})}{w^3}, \\ B_1^2 &= \frac{1}{w^3} \Big\{ -\dot{q}v^3 - \delta^2 \dot{q}v + \delta^3 \left[q \left(\kappa \lambda + 1 \right) + \kappa \lambda \ddot{q} \right] + \delta v \left[q \left(\kappa \lambda v + v + \delta' \lambda \right) + \lambda \ddot{q} \left(\kappa v + \delta' \right) \right] \Big\}, \\ B_2^1 &= \frac{\delta(q + \ddot{q})}{w^3}, \\ B_2^2 &= -\frac{\delta^2 \lambda (q + \ddot{q})}{w^3}. \end{split}$$

Hence, by using (2.15) and (2.7b), we obtain the relative curvature K and the relative mean curvature H:

$$K = -\delta \frac{(\delta q - \dot{q}v)(q + \ddot{q})}{w^4}, \quad H = \widetilde{H}(q + \ddot{q}).$$
(3.4)

From (3.4a) we deduce that the relative curvature K of a polar normalization vanishes identically iff

$$\delta q - \dot{q}v = 0$$
 or $q + \ddot{q} = 0$,

or, equivalently, iff

e.,

$$q = ce^{\frac{\partial V}{v}}, c \in \mathbb{R}^*$$
 or $q = c_1 \cos V + c_2 \sin V, c_1, c_2 \in \mathbb{R}, c_1^2 + c_2^2 \neq 0$

We reject the first support function since it leads to a non polar normalization. Thus we have the following

Theorem 3.1. Let $\Phi \subset E^3$ be a polar normalized ruled surface. The relative curvature K of (Φ, \overline{y}) vanishes identically iff the support function is of the form

 $q = c_1 \cos V + c_2 \sin V, \quad c_1, c_2 \in \mathbb{R}, \quad c_1^2 + c_2^2 \neq 0.$

By taking (2.7b) and (3.4b) into consideration we arrive at

Theorem 3.2. Let $\Phi \subset E^3$ be a polar normalized ruled surface. (Φ, \overline{y}) is relatively minimal (H = 0) iff one of the following holds true (a) the support function is of the form

$$q = c_1 \cos V + c_2 \sin V, \quad c_1, c_2 \in \mathbb{R}, \quad c_1^2 + c_2^2 \neq 0,$$

(b) (Φ, \overline{y}) is a polar normalized right helicoid $(\delta = c \in \mathbb{R}^* \text{ and } \kappa = \lambda = 0)$.

We notice that both the relative curvature K and the relative mean curvature H vanish identically iff the support function is of the form

$$q = c_1 \cos V + c_2 \sin V, \quad c_1, c_2 \in \mathbb{R}, \quad c_1^2 + c_2^2 \neq 0.$$
(3.5)

By using (2.7b) and (2.13) we find the Pick invariant

$$J = (qv + \delta \dot{q}) \left(\frac{J_{EUK}}{v} + \frac{3\tilde{H}\dot{q}}{\delta q} \right),$$
(3.6)

where

$$J_{EUK} = 3v \,\frac{\kappa v^3 + \delta^2 \left(\kappa - \lambda\right) v + \delta^2 \delta'}{2\delta^2 w^3} \tag{3.7}$$

is the Pick invariant of the Euclidean normalization. The Pick invariant vanishes identically iff

$$qv + \delta \dot{q} = 0$$
 or $\frac{J_{EUK}}{v} + \frac{3H \dot{q}}{\delta q} = 0$,

or, equivalently, iff

• the support function is of the form

$$q = c_1 e^{\frac{-VV}{\delta}}, c_1 \in \mathbb{R}^*, \text{ or }$$

• Φ is not a right helicoid and the support function is of the form

$$q = c_2 e^{\frac{V\left[\kappa v^3 + \delta^2(\kappa - \lambda)v + \delta^2 \delta'\right]}{\delta\left[\kappa v^2 + \delta' v + \delta^2(\kappa + \lambda)\right]}}, c_2 \in \mathbb{R}^*, \text{ or }$$

• Φ is a right helicoid.

We reject the two support functions since they are not polar. Hence, we deduce

Theorem 3.3. Let $\Phi \subset E^3$ be a polar normalized ruled surface. The Pick invariant J of (Φ, \overline{y}) vanishes identically iff Φ is a right helicoid. From (2.16), (3.4b), (3.6) and (3.7) we evaluate the scalar curvature of the relative metric

$$S = \frac{1}{2\delta^2 w^3 q} \left\{ -q^2 \left\{ \kappa w^4 + \delta^2 \left[\left(-v^2 + \delta^2 \right) \lambda + 2\delta' v \right] \right\} + \delta^2 \left(\kappa w^2 + \delta^2 \lambda + \delta' v \right) \dot{q}^2 + \delta q \left\{ \left[2\delta^2 \lambda v + \left(v^2 - \delta^2 \right) \delta' \right] \dot{q} - \delta \left(\kappa w^2 + \delta' v + \delta^2 \lambda \right) \ddot{q} \right\} \right\}.$$

4. The Tchebychev vector field and the support vector field of a polar normalization

In [5] it was shown that the coordinate functions of the Tchebychev vector $\overline{T}(u,v)$ of (Φ,\overline{y}) , which is defined by

$$\overline{T} := T^m \overline{x}_{/m}$$
, where $T^m := \frac{1}{2} A_i^{im}$,

are given by

$$T^1 = \frac{w^2 q_{/2} + vq}{\delta w}, \ T^2 = \frac{2\delta w^2 q_{/1} + \delta' q \left(\delta^2 - v^2\right)}{2\delta^2 w} + \frac{T^1 (\kappa w^2 + \delta' v - \delta^2 \lambda)}{\delta}$$

Hence, by using (3.1) and (3.2), we deduce that the coordinate functions of the Tchebychev vector of a polar normalization are

$$T^{1} = \frac{qv + \delta\dot{q}}{\delta w}, \quad T^{2} = \frac{q\left(2\kappa v w^{2} - 2\delta^{2}\lambda v + \delta' w^{2}\right) - 2\delta^{3}\lambda\dot{q}}{2\delta^{2}w}.$$
(4.1)

The divergence $\operatorname{div}^{I}\overline{T}$ of \overline{T} with respect to the first fundamental form I of Φ , which initially reads (see [5])

becomes, on account of (4.1),

$$\operatorname{div}^{I} \overline{T} = \frac{1}{2\delta^{2}w^{3}} \left\{ 2w^{2}q \left[\left(3v^{2} + \delta^{2} \right) \kappa - \delta^{2} \lambda \right] \right. \\ \left. + \delta \left\{ \left[-\delta'v^{2} + \delta^{2} \left(-2\lambda v + \delta' \right) \right] \dot{q} - 2\delta \left(\kappa w^{2} + \delta^{2} \lambda + \delta' v \right) \ddot{q} \right\} \right\}.$$

The rotation $\operatorname{curl}^{I}\overline{T}$ of \overline{T} with respect to the first fundamental form I of Φ , which initially reads (see [5])

$$\operatorname{curl}^{I}\overline{T} = \frac{\left(g_{12}T^{1} + g_{22}T^{2}\right)_{/1} - \left(g_{11}T^{1} + g_{12}T^{2}\right)_{/2}}{w},\tag{4.3}$$

becomes, by taking (2.5) and (4.1) into consideration,

$$\begin{aligned} \operatorname{curl}^{I}\overline{T} &= -\frac{1}{2\delta^{3}w^{2}} \bigg\{ 2\delta' qv^{2} \left(2\kappa v + \delta' \right) + \delta^{2}q \Big[4\left(\kappa\lambda + 1\right)v^{2} + \delta'\left(2\kappa + \lambda\right)v + \delta'^{2} \Big] \\ &+ \delta^{3} \Big\{ \dot{q} \Big[4v + \left(\kappa + \lambda\right) \left(2\kappa v + \delta' \right) \Big] - q \left(2\kappa' v + \delta'' \right) \Big\} \\ &+ \delta v \Big[2\kappa^{2}\dot{q}v^{2} + 3\kappa\delta'\dot{q}v + \delta'^{2}\dot{q} - qv \left(2\kappa' v + \delta'' \right) \Big] + 2\delta^{4} \Big[q \left(\kappa\lambda + 1\right) + \ddot{q} \Big] \Big\}. \end{aligned}$$

Analogously we calculate the divergence and the rotation of \overline{T} with respect to the relative metric of Φ :

$$div^{G}\overline{T} = \frac{1}{\delta^{2}w^{3}q} \Big\{ q^{2} \big\{ \kappa w^{4} + \delta^{2} \left[\left(v^{2} - \delta^{2} \right) \lambda - 2\delta' v \right] \big\} + \delta^{2} \dot{q}^{2} \left(\kappa w^{2} + \delta' v + \delta^{2} \lambda \right) \\ + \delta q \big\{ \dot{q} \left[2\delta^{2}\lambda v + \delta' \left(v^{2} - \delta^{2} \right) \right] - \delta \ddot{q} \left(\kappa w^{2} + \delta' v + \delta^{2} \lambda \right) \big\} \Big\},$$

$$curl^{G}\overline{T} = 0.$$

Last relation agrees with

$$\overline{T} = \nabla^G \left(\ln \frac{q}{q_{AFF}}, \overline{x} \right)$$

(see [6]), where $q_{AFF} = |\tilde{K}|^{1/4}$ and ∇^G denotes the first Beltrami differential operator with respect to *G* for which holds $\nabla^G(f,g) = G^{(ij)}f_{/i}g_{/j}$. So, we have

Theorem 4.1. Let $\Phi \subset E^3$ be a polar normalized ruled surface. The rotation of the Tchebychev vector field with respect to the relative metric of Φ vanishes identically and its potential is given by

$$\tau(u,v) = \ln \frac{wq}{|\delta|^{1/2}} + c, \quad c \in \mathbb{R}.$$

Now let

$$\overline{Q} := \frac{1}{4} \nabla^G \left(\frac{1}{q}, \overline{x} \right) \tag{4.4}$$

be the support vector $\overline{Q}(u,v)$ of (Φ,\overline{y}) , which is introduced in [5]. By taking (2.12), (3.1) and (3.2) into consideration we find that the coordinate functions of the support vector field of a polar normalization are

$$Q^1 = -\frac{\dot{q}}{4wq}, \quad Q^2 = \frac{\delta\lambda\dot{q}}{4wq}.$$
(4.5)

By means of (2.7b), (4.2) and (4.5), we find the divergence div^I \overline{Q} of \overline{Q} with respect to the first fundamental form I of Φ

$$\operatorname{div}^{I} \overline{Q} = \widetilde{H} \frac{\dot{q}^{2} - q\ddot{q}}{2q^{2}}.$$

Hence, we derive

Theorem 4.2. Let $\Phi \subset E^3$ be a polar normalized ruled surface. The support vector field is incompressible with respect to the first fundamental form of Φ (div $I\overline{Q} = 0$) iff (a) the support function is of the form

$$q = c_2 e^{c_1 V}, \quad c_1 \in \mathbb{R}, \quad c_2 \in \mathbb{R}^*, \text{ or }$$

(b) Φ is a right helicoid.

By taking (2.5), (4.3) and (4.5) into account we deduce that the rotation $\operatorname{curl}^I \overline{Q}$ of \overline{Q} with respect to the first fundamental form I of Φ is

$$\operatorname{curl}^{I} \overline{Q} = \frac{-\delta \dot{q}^{2} + q\left(\dot{q}v + \delta \ddot{q}\right)}{4w^{2}q^{2}}$$

By taking (2.11), (4.2) and (4.5) into consideration we find the divergence div $^{G}\overline{Q}$ of \overline{Q} with respect to the relative metric of Φ

$$\begin{split} \operatorname{liv}^{G} \overline{Q} &= \frac{1}{4\delta w^{3}q^{2}} \Big\{ \dot{q} \Big\{ q \left[-\delta' v^{2} + \delta^{2} \left(-2\lambda v + \delta' \right) \right] - 2\delta \dot{q} \left(\kappa w^{2} + \delta' v + \delta^{2} \lambda \right) \Big\} \\ &+ \delta q \ddot{q} \left(\kappa w^{2} + \delta^{2} \lambda + \delta' v \right) \Big\}. \end{split}$$

By using (2.6), (2.11), (3.1), (3.2), (4.3) and (4.5) we have the rotation curl^G \overline{Q} of \overline{Q} with respect to the relative metric of Φ

$$\operatorname{curl}^{G}\overline{Q}=0,$$

which agrees with the relation (4.4). Thus, we have

Theorem 4.3. Let $\Phi \subset E^3$ be a polar normalized ruled surface. The rotation of the support vector field with respect to the relative metric of Φ vanishes identically and its potential is given by

$$\tau(u,v) = \frac{1}{4q} + c, \quad c \in \mathbb{R}$$

5. A special polar normalization

In this section we will study the support function of the form (3.5), which arises when the relative curvature K or the relative mean curvature H vanishes identically (see Sec. 3). By using (3.3) the corresponding relative normalization takes the form

$$\overline{y} = \left[c_1 \cos\left(\int \kappa du\right) - c_2 \sin\left(\int \kappa du\right)\right] \overline{n} - \left[c_2 \cos\left(\int \kappa du\right) + c_1 \sin\left(\int \kappa du\right)\right] \overline{z},$$

i.e., the relative normalization degenerates into a curve \varGamma^{\ast} with curvature

$$\kappa^* = \frac{1}{|c_1 \cos\left(\int \kappa du\right) - c_2 \sin\left(\int \kappa du\right)|}$$

and torsion

 $^{*} = \frac{-\kappa}{c_{1}\cos\left(\int\kappa du\right) - c_{2}\sin\left(\int\kappa du\right)}$

Since

$$\frac{\kappa^*}{\sigma^*} = \pm \frac{1}{\kappa},$$

we deduce that \overline{y} is a curve of constant slope iff Φ is a ruled surface of constant slope. By means of (3.6) and (3.7) we find the Pick invariant of this normalization:

$$J = \frac{3 \left[c_2 \cos\left(\int \kappa du\right) + c_1 \sin\left(\int \kappa du\right)\right]}{2\delta^2 w \left(c_1 \cos V + c_2 \sin V\right)} \left\{ \cos\left(\int \kappa du\right) \left[\kappa \left(c_2 v^2 + 2c_1 \delta v - c_2 \delta^2\right) + \delta \left(-c_2 \delta \lambda + c_1 \delta'\right)\right] + \sin \left(\int \kappa du\right) \left[\kappa \left(c_1 v^2 - 2c_2 \delta v - c_1 \delta^2\right) - \delta \left(c_1 \delta \lambda + c_2 \delta'\right)\right] \right\}$$

Then by using (2.4) and (4.1) we deduce the Tchebychev vector

$$\overline{T} = \frac{w}{2\delta^2} \left(c_1 \cos V + c_2 \sin V \right) \left(2\kappa v + \delta' \right) \overline{e} + \frac{v}{\delta} \left[c_2 \cos \left(\int \kappa du \right) + c_1 \sin \left(\int \kappa du \right) \right] \overline{n} + \left[c_2 \cos \left(\int \kappa du \right) + c_1 \sin \left(\int \kappa du \right) \right] \overline{z}.$$

Finally, by taking (2.4) and (4.5) into consideration we derive the support vector

$$\overline{Q} = \frac{c_1 \sin V - c_2 \cos V}{4w \left(c_1 \cos V + c_2 \sin V\right)} \left(v\overline{n} + \delta \overline{z}\right)$$

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