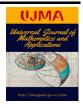
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Compact Totally Real Minimal Submanifolds in a Bochner-Kaehler Manifold

Mehmet Bektaş^a, Zühal Küçükarslan Yüzbaşı^{a*} and Münevver Yıldırım Yılmaz^a

^aDepartment of Mathematics, Faculty of Science, Fırat University, 23119 Elazığ, Turkey ^{*}Corresponding author

Article Info

Abstract

Keywords: Bochner-Kaehler manifold, Ricci curvature 2010 AMS: 53B25, 53C55 Received: 9 May 2018 Accepted: 16 July 2018 Available online: 20 December 2018 In this paper, we establish the following results: Let M be an m-dimensional compact totally real minimal submanifold immersed in a locally symmetric Bochner-Kaehler manifold \tilde{M} with Ricci curvature bounded from below. Then either M is a totally geodesic or

$$\inf r \leq \frac{1}{2} \left(\frac{1}{2} m (m-1) \tilde{k} - \frac{1}{3} (m+1) \tilde{c} \right),$$

where r is the scalar curvature of M.

1. Introduction

The Bochner tensor was originally introduced in 1948 by S. Bochner as a Kaehler analogue of the Weyl conformal curvature tensor. Kaehler manifolds with vanishing Bochner tensor are known as Bochner-Kaehler manifolds, [1]. The Bochner tensor has interesting connections to several areas of mathematics and Bochner-Kaehler manifolds have been studied quite intensively in the last two decades, see for instance, [1, 2, 3].

In this work, we make us of Yau's [4] maximum principle to compact study totally real minimal submanifold with Ricci curvature bounded from below and obtain the following results:

Main Theorem. Let M be an m-dimensional compact totally real minimal submanifold immersed in a locally symmetric Bochner-Kaehler manifold \tilde{M} with Ricci curvature bounded from below. Then either M is totally geodesic or $\inf r \leq \frac{1}{2} \left(\frac{1}{2}m(m-1)\tilde{k} - \frac{1}{3}(m+1)\tilde{c} \right)$ where r is the scalar curvature of M.

We use the same notation and terminologies as in [5] unless otherwise stated.

Let \tilde{M} be an *n*-dimensional Kaehler manifold and denote by g_{AB} , F_{AB} , \tilde{K}_{ABCD} and \tilde{K} , the metric tensor, the complex structure tensor, the curvature tensor, the Ricci tensor and the scalar curvature of \tilde{M} , respectively. Suppose that the Boechner curvature tensor of \tilde{M} vanishes, then we have

$$\tilde{K}_{ABCD} = -g_{AD}L_{BC} + g_{BD}L_{AC} - L_{AD}g_{BC} + L_{BD}g_{AC} - F_{AD}M_{BC}$$

$$+ F_{BD}M_{AC} - M_{AD}F_{BC} + M_{BD}F_{AC} + 2(M_{AB}F_{CD} + F_{AB}M_{CD}),$$

$$(1.1)$$

where

$$\begin{split} & L_{BC} = \tilde{K}_{BC} / \left(2n + 4 \right) - \tilde{K} g_{BC} / 2 \left(2n + 2 \right) \left(2n + 4 \right), \ \tilde{K}_{BC} = g^{AD} \tilde{K}_{ABDC}, \\ & \tilde{K} = g^{BC} \tilde{K}_{BC}, \ M_{BC} = -L_{BD} F_C^D, \ F_C^D = g^{BD} F_{CB} \ . \end{split}$$

 L_{BC} are components of a hybrid tensor of type (0,2). That is

$$L_{BC}F_A^BF_D^C = L_{AD}$$

In order to avoid repetitions it will be agreed that our indices have the following ranges throughout this paper:

$$\begin{split} A, B, C, D, &\ldots = 1, 2, \dots, m, 1^*, 2^*, \dots, m^*, \\ i, j, k, l, &\ldots = 1, 2, \dots, m; \alpha, \beta, \gamma, \dots = 1^*, 2^*, \dots, m^* \end{split}$$

Email addresses and ORCID numbers: mbektas@firat.edu.tr, 0000-0002-5797-4944 (M. Bektaş), zuhal2387@yahoo.com.tr, 0000-0001-7630-5490 (Z. Küçükarslan Yüzbaşı), myildirim@firat.edu.tr, 0000-0003-1278-3981 (M. Yıldırım Yılmaz)

In the following sections, \tilde{M} is always supposed to be a Bochner-Kaehler manifold, that is, \tilde{M} is a Kaehler manifold with curvature tensor \tilde{K}_{ABCD} given by (1.1).

2. Totally real submanifolds in \tilde{M}

We call *M* as a totally real submanifold of \tilde{M} if *M* admits an isometric immersion into \tilde{M} such that for all $x \in M$, $F(T_x(M)) \subset v_x$, where $T_x(M)$ denotes the tangent space of *M* at *x* and *F* the complex structure of \tilde{M} . If the real dimension of *M* is *m*, then $m \leq n$, *n* is the complex dimension of \tilde{M} . We choose a local field of orthonormal frames

$$e_1, \dots, e_m, e_{m+1}, \dots, e_n$$
; $e_{1^*} = Fe_{1,\dots,e_{m^*}} = Fe_{m,\dots,e_{n^*}} = Fe_n$,

in \tilde{M} in a such a way that, restricted to $M, e_1, ..., e_m$ are tangents to M. With respect to this frame field, F and g have the components

$$(F_{AB}) = \begin{pmatrix} 0 & -I_n \\ I_n & 0 \end{pmatrix}, \quad (g_{AB}) = (I_{2n}),$$

where I_k denotes the identity matrix of degree k. We consider the case n = m only in this paper. The equation of Gauss of M in \tilde{M} is written as

$$K_{ijkl} = \tilde{K}_{ijkl} + \sum_{\alpha} \left(h^{\alpha}_{ik} h^{\alpha}_{jl} - h^{\alpha}_{il} h^{\alpha}_{jk} \right).$$
(2.1)

 K_{ijkl} is the curvature tensor and h_{ij}^{α} is the second fundamental tensor of M. Since M is a totally real submanifold in \tilde{M} , with respect to the above frame we have the relation $h_{jk}^{i^*} = h_{ik}^{j^*}$. Let \tilde{K} be the curvature tensor field of \tilde{M} so that $\tilde{K}_{ABCD} = g\left(\tilde{K}(e_C, e_D)e_B, e_A\right)$. Then (1.1) is equivalent to

$$\tilde{K}(X,Y)Z = L(Y,Z)X - L(X,Z)Y + \langle Y,Z \rangle NX - \langle X,Z \rangle NY
+ M(Y,Z)FX - M(X,Z)FY + \langle FY,Z \rangle PX
- \langle FX,Z \rangle PY - 2(M(X,Y)FZ + \langle FX,Y \rangle PZ),$$
(2.2)

where *NX*, *PX* are defined by g(NX,Y) = L(X,Y), g(PX,Y) = M(X,Y) and \langle , \rangle denotes the inner product with respect to g. Let $\tilde{K}(X)$ be the holomorphic sectional curvature spanned by a unit vector X and FX. By (1.1) or (2.2) we have

$$\tilde{K}(X) = \tilde{K}(X, FX, FX, X) = \langle \tilde{K}(X, FX) FX, X \rangle = 8L(X, X),$$

Let $\tilde{\rho}(X,Y)$ denote the sectional curvature of \tilde{M} determined by section $\{X,Y\}$ spanned by two orthonormal vector $\{X,Y\}$. If X,Y are both tangent to the totally real submanifold M then we have

$$\tilde{\rho}(X,Y) = L(X,X) + L(Y,Y) = \frac{1}{8} \left(\tilde{K}(X) + \tilde{K}(Y) \right).$$
(2.3)

The equation of (2.3) has been obtained by Iwasaki and Ogitsu, [6].

Let $\rho(X,Y)$ denote the sectional curvature of *M* determined by orthonormal tangent vectors $\{X,Y\}$ of *M*. Then the equation of Gauss (2.1) and (2.3) imply

$$\rho(X,Y) = \frac{1}{8} \left(\tilde{K}(X) + \tilde{K}(Y) \right) + \langle \sigma(X,X), \sigma(Y,Y) \rangle - \| \sigma(X,Y) \|^2,$$

where σ is the second fundamental form which is related to h_{ij}^{α} by $g(\sigma(X,Y),\xi) = h_{jk}^{i^*} X^j Y^k \xi^{i^*}$ for any normal $\xi = \xi^{i^*} e_{i^*}$. Let *S* be the Ricci tensor of *M* and *r* the scalar curvature of *M*. Then

$$S(X,Y) = (m-2)L(X,Y) + \frac{1}{8}m\tilde{k}\langle X,Y\rangle - \sum_{\alpha}g(h_{\alpha}X,h_{\alpha}Y),$$
$$r = \frac{1}{4}m(m-1)\tilde{k} - \|\sigma\|^{2}.$$

Let \tilde{M} is locally symmetric. Let Δ denote the Laplacian, \bigtriangledown' denote the covariant differentiation with respect to connection in (tangent bundle) \oplus (normal bundle) of M in \tilde{M} . If M is a minimal submanifold of \tilde{M} the following holds (see [5] for example). Since \tilde{M} is assumed to be locally symmetric:

$$\frac{1}{2}\Delta \|\sigma\|^{2} = \|\nabla'\sigma\|^{2} + \frac{1}{4}(m+1)\tilde{c}\|\sigma\|^{2} + \sum tr\left(h_{i^{*}}h_{j^{*}} - h_{j^{*}}h_{i^{*}}\right)^{2} - \sum tr\left(h_{i^{*}}h_{j^{*}}\right)^{2},$$
(2.4)

where \tilde{c} is a function on M defined by $h_{lk}^{j^*} \tilde{K}_{li} = \frac{1}{2} (m+1) \tilde{c} ||\sigma||^2$. In order to prove the main theorem, we need the following lemmas. **Lemma 2.1.** Let H_i , $i \ge 2$ be symmetric $n \times n$ matrices, $S_i = trH_i^2$, $S = \sum S_i$. Then

$$\sum_{i,j} tr \left(H_i H_j - H_j H_i \right)^2 - \sum_{i,j} tr \left(H_i H_j \right)^2 \ge -\frac{3}{2} \|\sigma\|^4,$$
(2.5)

and the equality holds if and only if either all $H_i = 0$ or there exists two of H_i different from zero. Moreover, if $H_1 \neq 0, H_2 \neq 0, H_i = 0, i \neq 1, 2$, then $S_1 = S_2$ and there exists an orthogonal $n \times n$ matrices T such that

$$TH_1^t T = \begin{pmatrix} \frac{\sqrt{S_1}}{2} & 0 & \dots & 0\\ 0 & -\frac{\sqrt{S_1}}{2} & \dots & 0\\ \vdots & \vdots & \ddots & \vdots\\ 0 & 0 & \dots & 0 \end{pmatrix}, \ TH_2^t T = \begin{pmatrix} 0 & \frac{\sqrt{S_1}}{2} & \dots & 0\\ \frac{\sqrt{S_1}}{2} & 0 & \dots & 0\\ \vdots & \vdots & \ddots & \vdots\\ 0 & 0 & \dots & 0 \end{pmatrix},$$

[**7**, **8**].

Lemma 2.2. Let N be a complete Riemannian manifold with Ricci curvature bounded from below and let f be a C^2 -function bounded from above on N, then for all $\varepsilon > 0$, there exists a point $x \in N$ at which, i) $\sup f - \varepsilon < f(x)$, ii) $\|\nabla f(x)\| < \varepsilon$,

iii) $\Delta f(x) < \varepsilon$, in [9].

3. Proof of the main theorem

In this section, the method proof used by Ximin in [9] is applied totally real minimal submanifold immersed in a Bochner-Kaehler manifold. From (2.4) and (2.5), we obtain

$$\frac{1}{2}\Delta \|\sigma\|^2 \ge \|\sigma\|^2 \left(\frac{1}{4} (m+1)\tilde{c} - \frac{3}{2} \|\sigma\|^2\right).$$
(3.1)

We know that $\|\sigma\|^2 = \frac{1}{4}m(m-1)\tilde{k} - r$. By the condition of the theorem, we conclude that $\|\sigma\|^2$ is bounded. We define $f = \|\sigma\|^2$ and $F = (f+a)^{\frac{1}{2}}$ (where a > 0 is any positive constant number). *F* is bounded. We have

$$dF = \frac{1}{2} (f+a)^{-\frac{1}{2}} df,$$

$$\Delta F = \frac{1}{2} \left(-\frac{1}{2} (f+a)^{-\frac{3}{2}} \|df\|^2 + (f+a)^{-\frac{1}{2}} \Delta f \right),$$

$$= \frac{1}{2} \left(-2 \|dF\|^2 + \Delta f \right) (f+a)^{-\frac{1}{2}},$$

i.e.,

$$\Delta F = \frac{1}{2} \left(-2 \left\| dF \right\|^2 + \Delta f \right)$$

Hence, $F\Delta F = -\|dF\|^2 + \frac{1}{2}\Delta f$ or $\frac{1}{2}\Delta f = F\Delta F + \|dF\|^2$. Applying Lemma 2.2 to *F*, we have for all $\varepsilon > 0$, there exists a point $x \in M$ such that at *x*

$$\|dF(\mathbf{x})\| \le \varepsilon,\tag{3.2}$$

$$\Delta F(x) < \varepsilon, \tag{3.3}$$

 $F(x) > \sup F - \varepsilon. \tag{3.4}$

From (3.2),(3.3) and (3.4), we have

$$\frac{1}{2}\Delta f < \varepsilon^2 + F\varepsilon = \varepsilon \left(\varepsilon + F\right). \tag{3.5}$$

We take a sequence $\{e_n\}$ such that $\varepsilon_n \to 0 \ (n \to \infty)$ and for all *n*, there exists a point $x_n \in M$ such that (3.2), (3.3) and (3.4) hold. Therefore, $\varepsilon_n \ (\varepsilon_n + F \ (x_n)) \to 0 \ (n \to \infty)$ (Because *F* is bounded). From (3.4), we have $F \ (x_n) > \sup F - \varepsilon_n$. Because $\{F \ (x_n)\}$ is a bounded sequence. So we get $F \ (x_n) \to F_0$ (If necessary, we can choose a subsequence). Hence, $F_0 \ge \sup F$. So we have

$$F_0 = \sup F.$$

From the definition of F, we get

 $f(x_n) \to f = \sup f.$

(3.1) and (3.5) imply that

$$f\left(\frac{1}{4}(m+1)\tilde{c}-\frac{3}{2}f\right)\leq \frac{1}{2}\Delta f\leq \varepsilon(\varepsilon+F),$$

and

$$f(x_n)\left(\frac{1}{4}(m+1)\tilde{c}-\frac{3}{2}f(x_n)\right)<\varepsilon_n^2+\varepsilon_nF(x_n)\leq\varepsilon_n^2+\varepsilon_nF_0,$$

let $n \to \infty$, then $\varepsilon_n \to 0$ and $f(x_n) \to f_0$. Hence,

$$f_0\left(\frac{1}{4}\left(m+1\right)\tilde{c}-\frac{3}{2}f_0\right)\leq 0.$$

i) If $f_0 = 0$, we have $f = ||\sigma||^2 = 0$. Hence *M* is a totally geodesic. *ii*) If $f_0 > 0$, we have $\frac{1}{4}(m+1)\tilde{c} - \frac{3}{2}f_0 \le 0$ and

$$f_0 \ge \frac{1}{6} \left(m + 1 \right) \tilde{c},$$

that is, $\sup \|\sigma\|^2 \ge \frac{1}{6} (m+1) \tilde{c}$. Therefore,

$$\inf r \leq \frac{1}{2} \left(\frac{1}{2} m \left(m - 1 \right) \tilde{k} - \frac{1}{3} \left(m + 1 \right) \tilde{c} \right)$$

This completes the proof.

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