Results in Nonlinear Analysis  ${\bf 1}$  (2018) No. 3, 128–132 Available online at www.resultsinnonlinear analysis.com



# An Extention of Angelov's Fixed Point Theorem in Uniform Spaces

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# Abstract

In this paper we establish an existence result for fixed points of mapping in a uniform space, which extends some previous theorems of V. G. Angelov [1].

*Keywords:* fixed point theorems, uniform space. 2010 MSC: 47H10, 47H09

## 1. Introduction and Preliminaries

We begin the present note recalling some basic notions from [1], [2].

Further on we denote by  $(X, \mathbf{A})$  a Hausdorff sequentially complete uniform space, whose uniformity is generated by a saturated family  $\mathbf{A} = \{\rho_{\alpha} : \alpha \in A\}$  of pseudo-metrics  $\rho_{\alpha} : X \times X \to [0, \infty)$ , A being an index set.

Recall that a Hausdorff uniform space is called *sequentially complete* if any Cauchy sequence in it is convergent. The sequence  $\{x_n \in X\}_{n=1}^{\infty}$  is said to be *Cauchy* one if for every  $\varepsilon > 0$  and  $\alpha \in A$  there is a natural number  $n_0 \in \mathbb{N} := \{1, 2, 3, ...\}$  such that  $\rho_{\alpha}(x_m, x_n) < \varepsilon$  for all  $m, n \ge n_0$ . The sequence  $\{x_n \in X\}_{n=1}^{\infty}$ is called *convergent* if there exists an element  $x \in X$  such that for every  $\varepsilon > 0$  and  $\alpha \in A$ , there exists  $n_0 \in \mathbb{N}$ with  $\rho_{\alpha}(x, x_n) < \varepsilon$  for all  $n \ge n_0$ . Let us point out that the uniform spaces and gauge spaces are equivalent notions [3].

Let  $(\Phi) = {\Phi_{\alpha} : \alpha \in A}$  be a family of functions  $\Phi_{\alpha}(\cdot) : [0, \infty) \to [0, \infty)$  with the properties (for every fixed  $\alpha \in A$ ):

(**Φ1**)  $\Phi_{\alpha}(\cdot)$  is non-decreasing and continuous from the right;

(**42**)  $0 < \Phi_{\alpha}(t) < t$ ,  $\forall t > 0$ . (It follows  $\Phi_{\alpha}(0) = 0$ .)

Let  $j : A \to A$  be an arbitrary mapping of the index set into itself. The iterations can be defined inductively as follows:  $j^n(\alpha) = j(j^{n-1}(\alpha)), j^0(\alpha) = \alpha \ (n = 1, 2, 3, ...).$ 

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Received September 02, 2018, Accepted December 18, 2018, Online December 19, 2018.

**Definition 1.1.** [1] Let M be a subset of X and  $T: M \to M$  be a mapping. T is said to be  $(\Phi, j)$  – contractive on M, if  $\rho_{\alpha}(T(x), T(y)) \leq \Phi_{\alpha}(\rho_{i(\alpha)}(x, y))$  for every fixed  $\alpha \in A$  and for every  $x, y \in M$ .

**Remark 1.2.** Recall that if  $\Phi_{\alpha} \in (\Phi)$  and the function  $\varphi_{\alpha} : (0, \infty) \to (0, \infty)$ , defined by  $\varphi_{\alpha}(t) = \frac{\Phi_{\alpha}(t)}{t} \ \forall t \in (0,\infty), \text{ is non-decreasing, then } \sum_{l=0}^{\infty} \Phi_{\alpha}^{l}(t) < \infty \text{ for any fixed } t \in (0,\infty)$ (where  $\Phi^0_{\alpha}(t) = t$ ,  $\Phi^l_{\alpha}(t) = \Phi_{\alpha}\left(\Phi^{l-1}_{\alpha}(t)\right), l \in \mathbb{N}$ ).

Indeed, for any fixed  $l \in \mathbb{N}$  and t > 0 it follows by  $(\Phi 2) \Phi_{\alpha}^{l}(t) = \Phi_{\alpha} \left( \Phi_{\alpha}^{l-1}(t) \right) < \Phi_{\alpha}^{l-1}(t)$ . Therefore  $\Phi_{\alpha}^{l}(t) < \Phi_{\alpha}^{l-1}(t) < \Phi_{\alpha}^{l-2}(t) \dots < \Phi_{\alpha}(t) < t$  and the inequalities

$$\frac{\Phi_{\alpha}^{l+1}(t)}{\Phi_{\alpha}^{l}(t)} = \frac{\Phi_{\alpha}\left(\Phi_{\alpha}^{l}(t)\right)}{\Phi_{\alpha}^{l}(t)} = \varphi_{\alpha}\left(\Phi_{\alpha}^{l}(t)\right) \le \varphi_{\alpha}\left(\Phi_{\alpha}^{l-1}(t)\right) \le \dots \le \varphi_{\alpha}\left(\Phi_{\alpha}(t)\right) \le \varphi_{\alpha}(t) = \frac{\Phi_{\alpha}(t)}{t} < 1 \quad (l \in \mathbb{N})$$

are a sufficient condition for the convergence of  $\sum_{l=1}^{\infty} \Phi_{\alpha}^{l}(t)$ .

Fixed point theorems from [1], [2] guarantee an existence of fixed points of  $(\Phi, j)$  – contractive (or just  $(\Phi)$  – *contractive*) and j - non-expansive mappings under various conditions.

In this paper we extend the following result from [1]:

**Theorem 1.3.** (Angelov). Let the following conditions hold:

1) the operator  $T: X \to X$  is  $(\Phi) - contractive;$ 

2) for every  $\alpha \in A$  there exists a function  $\overline{\Phi}_{\alpha} \in (\Phi)$  such that

 $\sup \left\{ \Phi_{j^n(\alpha)}(t) : n = 0, 1, 2, 3, \ldots \right\} \leq \overline{\Phi}_{\alpha}(t) \text{ and } \frac{\overline{\Phi}_{\alpha}(t)}{t} \text{ is non-decreasing } (t > 0);$ 3) there exists an element  $x_0 \in X$  such that for every  $\alpha \in A$  there is  $q(\alpha) > 0$ :

$$\rho_{j^n(\alpha)}(x_0, T(x_0)) \le q(\alpha) < \infty \ (n = 0, 1, 2, 3, \ldots).$$

Then T has at least one fixed point in X.

If, in addition, we suppose that

4) for every  $\alpha \in A$  and  $x, y \in X$  there exists  $p = p(x, y, \alpha)$  such that

$$\rho_{j^k(\alpha)}(x,y) \le p(x,y,\alpha) < \infty \ (k=0,1,2,3,...),$$

then the fixed point of T is unique.

### 2. Main results

Let  $j_1: A \to A$ ,  $j_2: A \to A$  be two mappings of the index set into itself.

In this paper we introduce the notion of  $(\Phi, j_1, j_2)$  – contractive mappings and we establish some fixed point results for such mappings in uniform spaces.

Introduce the subfamily  $(\Psi) \subset (\Phi)$  of functions  $\Phi_{\alpha} \in (\Phi)$  which are sub-additive, i.e. (**43**) for every  $\alpha \in A$  ( $\forall \Phi_{\alpha} \in \Psi$ ) :  $\Phi_{\alpha}(t_1 + t_2) \leq \Phi_{\alpha}(t_1) + \Phi_{\alpha}(t_2)$  for all  $t_1, t_2 \in [0, \infty)$ .

**Definition 2.1.** The mapping  $T: X \to X$  is said to be  $(\Phi, j_1, j_2)$  –contractive on X, if for any fixed  $\alpha \in A$ there is a function  $\Phi_{\alpha} \in (\Psi)$  such that  $\rho_{\alpha}(T(x), T(y)) \leq \frac{1}{2} \Phi_{\alpha} \left( \rho_{j_1(\alpha)}(x, y) + \rho_{j_2(\alpha)}(x, y) \right)$  for every  $x, y \in X$ .

Define the mapping  $S_1: A \to j_1(A) \cup j_2(A)$  as follows:  $S_1(\gamma) = \{j_1(\gamma), j_2(\gamma)\}$  for  $\gamma \in A$ . Introduce for any fixed index  $\alpha \in A$  the following notations:  $S^0(\alpha) \equiv \alpha_0 \equiv \alpha; S^1(\alpha) \equiv S_1(\alpha);$ 

 $S^{n}(\alpha) = \{\sigma^{n} = (\alpha_{1}, ..., \alpha_{n}) : \alpha_{k} \in S_{1}(\alpha_{k-1}), \forall k = 1, ..., n\}$  for every  $n \in \mathbb{N}, n > 1$ .

**Theorem 2.2.** Let  $(X, \mathbf{A})$  be a Hausdorff sequentially complete uniform space, whose uniformity is generated by a saturated family of pseudo-metrics  $\mathbf{A} = \{\rho_{\alpha}(x, y) : \alpha \in A\}$ , where A is an index set. Let the mappings  $j_1: A \to A \text{ and } j_2: A \to A \text{ be defined and } (\Psi) = \{\Phi_\alpha : \alpha \in A\}$  be the family of functions with properties  $(\Phi 1) - (\Phi 3)$ . Let the following conditions hold:

1. The mapping  $T: X \to X$  is  $(\Phi, j_1, j_2)$ -contractive on X.

2. For every  $\alpha \in A$  there is a function  $\overline{\Phi}_{\alpha} \in (\Phi)$  such that  $\frac{\overline{\Phi}_{\alpha}(t)}{t}$  is non-decreasing,  $\Phi_{\alpha}(t) \leq \overline{\Phi}_{\alpha}(t), \forall t > 0$ and for any fixed  $k \in \mathbb{N}$  for all  $\sigma^{k} = (\alpha_{1}, ..., \alpha_{k}) \in S^{k}(\alpha)$  the inequalities  $\Phi_{\alpha_{i}}(t) \leq \overline{\Phi}_{\alpha}(t), \forall t > 0$  are satisfied for all coordinates  $\alpha_{i}$  of  $\sigma^{k}$  (i = 1, ..., k).

3. There exists an element  $x_0 \in X$  such that for every  $\alpha \in A$  there exists a constant  $q_\alpha = q(\alpha) > 0$ such that  $\rho_\alpha(x_0, T(x_0)) \leq q_\alpha$  and for any fixed  $k \in \mathbb{N}$  for all  $\sigma^k = (\alpha_1, ..., \alpha_k) \in S^k(\alpha)$  the inequalities  $\rho_{\alpha_m}(x_0, T(x_0)) \leq q_\alpha$  are satisfied for all coordinates  $\alpha_m$  of  $\sigma^k$  (m = 1, ..., k).

Then T has at least one fixed point in X.

**Theorem 2.3.** If to the conditions of Theorem 2.2 we add the following assumption for the set X:

4. for any fixed  $\alpha \in A$  there exists  $p_{\alpha} : X \times X \to (0, \infty)$  such that  $\rho_{\alpha}(x, y) \leq p_{\alpha}(x, y)$  for all  $(x, y) \in X \times X$ and for any fixed  $k \in \mathbb{N}$  for all  $\sigma^{k} = (\alpha_{1}, ..., \alpha_{k}) \in S^{k}(\alpha)$  the inequalities  $\rho_{\alpha_{n}}(x, y) \leq p_{\alpha}(x, y)$  are satisfied for all  $(x, y) \in X \times X$  and for all coordinates  $\alpha_{l}$  of  $\sigma^{k}$  (l = 1, ..., k), then the fixed point of T is unique.

Proof. (of Theorem 2.2) Begin with  $x_0 \in X$ , we define the sequence  $\{x_n : n = 0, 1, 2, ...\}$ ,  $x_n = T^n(x_0)$ , where  $T^0 \equiv Id$  and  $T^n(\cdot) = T(T^{n-1}(\cdot))$  for  $n \in \mathbb{N}$ . If  $x_{n'} = x_{n'-1}$  for some  $n' \in \mathbb{N}$  then  $x_{n'-1}$  is a fixed point of T. Consequently we may assume  $x_n \neq x_{n-1}, \forall n \in \mathbb{N}$ .

Let  $\alpha \in A$  be any fixed index. Define the sequence  $\{c_n^{\alpha}\}_{n=0}^{\infty}$ :  $c_n^{\alpha} = \rho_{\alpha}(x_n, x_{n+1})$  (n = 0, 1, 2, ...). For any fixed  $n \in \mathbb{N}$  let  $\sigma^n = (\alpha_1, ..., \alpha_n)$  be an arbitrary element of  $S^n(\alpha)$ .

Define  $c_k^{\alpha_{n-k}} = \rho_{\alpha_{n-k}}(x_k, x_{k+1})$  for every k = 1, ..., n (with  $\alpha_0 \equiv \alpha$  and  $c_n^{\alpha_0} \equiv c_n^{\alpha}$ ). It follows:

$$c_{1}^{\alpha_{n-1}} = \rho_{\alpha_{n-1}}(x_{1}, x_{2}) \leq \frac{1}{2} \Phi_{\alpha_{n-1}}(\rho_{j_{1}(\alpha_{n-1})}(x_{0}, x_{1}) + \rho_{j_{2}(\alpha_{n-1})}(x_{0}, x_{1}))$$

$$\leq \frac{1}{2} \Phi_{\alpha_{n-1}}(\rho_{j_{1}(\alpha_{n-1})}(x_{0}, x_{1})) + \frac{1}{2} \Phi_{\alpha_{n-1}}(\rho_{j_{2}(\alpha_{n-1})}(x_{0}, x_{1}))$$

$$\leq \frac{1}{2} \overline{\Phi}_{\alpha}(\rho_{j_{1}(\alpha_{n-1})}(x_{0}, x_{1})) + \frac{1}{2} \overline{\Phi}_{\alpha}(\rho_{j_{2}(\alpha_{n-1})}(x_{0}, x_{1})) \leq \frac{1}{2} \cdot 2\overline{\Phi}_{\alpha}(q_{\alpha}) = \overline{\Phi}_{\alpha}(q_{\alpha}).$$

Therefore  $c_1^{\alpha_{n-1}} \leq \overline{\Phi}_{\alpha}(q_{\alpha})$  for any  $\alpha_{n-1} \in S_1(\alpha_{n-2})$ . By induction, for every choice of  $\sigma^n \in S^n(\alpha)$  and its coordinates  $\alpha_{n-k}$ , we prove:

$$c_k^{\alpha_{n-k}} \le \overline{\Phi}_{\alpha}^k(q_{\alpha}) \,\forall k = 1, ..., n-1.$$

In fact, such estimates are valid when k = 1, as we have already proven. Suppose that the above inequalities are valid for all  $k \le m < n - 1$ . Then for k = m + 1 we obtain:

$$\begin{aligned} c_{m+1}^{\alpha_{n-m-1}} &= \rho_{\alpha_{n-m-1}}(x_{m+1}, x_{m+2}) \leq \frac{1}{2} \Phi_{\alpha_{n-m-1}}(\rho_{j_1(\alpha_{n-m-1})}(x_m, x_{m+1}) + \rho_{j_2(\alpha_{n-m-1})}(x_m, x_{m+1})) \\ &\leq \frac{1}{2} \Phi_{\alpha_{n-m-1}}(\rho_{j_1(\alpha_{n-m-1})}(x_m, x_{m+1})) + \frac{1}{2} \Phi_{\alpha_{n-m-1}}(\rho_{j_2(\alpha_{n-m-1})}(x_m, x_{m+1})) \\ &\leq \frac{1}{2} \overline{\Phi}_{\alpha}(\rho_{j_1(\alpha_{n-m-1})}(x_m, x_{m+1})) + \frac{1}{2} \overline{\Phi}_{\alpha}(\rho_{j_2(\alpha_{n-m-1})}(x_m, x_{m+1})) \leq \overline{\Phi}_{\alpha}\left(c_m^{\alpha^*_{n-m}}\right), \end{aligned}$$

where  $\alpha_{n-m}^* \in S_1(\alpha_{n-m-1})$  is such that

$$c_m^{\alpha_{n-m}^*} = \rho_{\alpha_{n-m}^*}(x_m, x_{m+1}) = \max\{\rho_{j_1(\alpha_{n-m-1})}(x_m, x_{m+1}), \rho_{j_2(\alpha_{n-m-1})}(x_m, x_{m+1})\}.$$

It follows by assumption that  $c_m^{\alpha_{n-m}^*} \leq \overline{\Phi}_{\alpha}^m(q_{\alpha})$ . Therefore  $c_{m+1}^{\alpha_{n-m-1}} \leq \overline{\Phi}_{\alpha}\left(\overline{\Phi}_{\alpha}^m(q_{\alpha})\right) = \overline{\Phi}_{\alpha}^{m+1}(q_{\alpha})$ . For  $c_n^{\alpha}$  we obtain as follows:

$$c_{n}^{\alpha} = \rho_{\alpha}(x_{n}, x_{n+1}) \leq \frac{1}{2} \Phi_{\alpha}(\rho_{j_{1}(\alpha)}(x_{n-1}, x_{n}) + \rho_{j_{2}(\alpha)}(x_{n-1}, x_{n}))$$
  
$$\leq \frac{1}{2} \overline{\Phi}_{\alpha}\left(\rho_{j_{1}(\alpha)}(x_{n-1}, x_{n})\right) + \frac{1}{2} \overline{\Phi}_{\alpha}\left(\rho_{j_{2}(\alpha)}(x_{n-1}, x_{n})\right) \leq \overline{\Phi}_{\alpha}\left(\rho_{\alpha_{1}^{*}}(x_{n-1}, x_{n})\right),$$

where  $\alpha_1^* \in S_1(\alpha)$  is such that

$$\rho_{\alpha_1^*}(x_{n-1}, x_n) = \max\{\rho_{\alpha_1}(x_{n-1}, x_n) : \alpha_1 \in S_1(\alpha)\} = \max\{\rho_{j_1(\alpha)}(x_{n-1}, x_n), \rho_{j_2(\alpha)}(x_{n-1}, x_n)\}.$$

Hence  $c_n^{\alpha} \leq \overline{\Phi}_{\alpha} \left( \rho_{\alpha_1^*}(x_{n-1}, x_n) \right) = \overline{\Phi}_{\alpha} \left( c_{n-1}^{\alpha_1^*} \right) \leq \overline{\Phi}_{\alpha} (\overline{\Phi}_{\alpha}^{n-1}(q_{\alpha}))$  (since  $\alpha_1^* \in S_1(\alpha)$ ).

Thus we obtain the inequality  $c_n^{\alpha} \leq \overline{\Phi}_{\alpha}^n(q_{\alpha})$ , which is valid for any fixed index  $\alpha \in A$  and for every  $n \in \mathbb{N}$ . Consequently for every fixed m = 0, 1, 2, ... and  $p \in \mathbb{N}$  we obtain:

$$\rho_{\alpha}(x_m, x_{m+p}) \le \sum_{k=0}^{p-1} c_{m+k}^{\alpha} \le \sum_{k=0}^{p-1} \overline{\Phi}_{\alpha}^{m+k}(q_{\alpha}) = \Psi_{m+p} - \Psi_m$$

where  $\Psi_k = \sum_{l=0}^{k-1} \overline{\Phi}_{\alpha}^l(q_{\alpha})$  is the k-th partial sum of the series  $\sum_{l=0}^{\infty} \overline{\Phi}_{\alpha}^l(q_{\alpha})$ , which is convergent, in view of

Remark 1.2.

Therefore for any  $\varepsilon > 0$  there exists  $N_0 \in \mathbb{N}$  such that  $\forall m \ge N_0$ :  $\rho_\alpha(x_m, x_{m+p}) \le \Psi_{m+p} - \Psi_m < \varepsilon$  for every  $p \in \mathbb{N}$ , i.e.  $\{x_n = T^n(x_0) : n = 0, 1, 2, ...\}$  is a Cauchy sequence in X. In view of the sequential completeness of  $(X, \mathbf{A})$  there exists  $x \in X$ :  $\rho_{\alpha}(x_n, x) \xrightarrow[n \to \infty]{} 0, \forall \alpha \in A$ .

The right-continuity of  $\Phi_{\alpha}$  and the inequalities

$$\rho_{\alpha}(x, T(x)) \leq \rho_{\alpha}(x, T^{n+1}(x_{0})) + \rho_{\alpha}(T^{n+1}(x_{0}), T(x)) \leq \\ \leq \rho_{\alpha}(x, x_{n+1}) + \frac{1}{2} \Phi_{\alpha} \left( \rho_{j_{1}(\alpha)}(x_{n}, x) + \rho_{j_{2}(\alpha)}(x_{n}, x) \right) (n \in \mathbb{N})$$

imply  $\rho_{\alpha}(x, T(x)) = 0 \ \forall \alpha \in A$ , that is x = T(x). Theorem 2.2 is thus proved.

*Proof.* (of Theorem 2.3) Let  $(x, y) \in X \times X$  be an arbitrary fixed pair. Let  $\alpha \in A$  be any fixed index. Denote by  $d_n^{\alpha} = d_n^{\alpha}(x, y) = \rho_{\alpha}\left(T^n(x), T^n(y)\right)$  (n = 0, 1, 2, ...). For any fixed  $n \in \mathbb{N}$  let  $\sigma^n = (\alpha_1, ..., \alpha_n)$  be an arbitrary element of  $S^{n}(\alpha)$ .

Define  $d_k^{\alpha_{n-k}} = d_k^{\alpha_{n-k}}(x,y) = \rho_{\alpha_{n-k}}(T^k(x),T^k(y))$  for every k = 1, ..., n (with  $\alpha_0 \equiv \alpha$  and  $d_n^{\alpha_0} \equiv d_n^{\alpha}$ ). It follows:

$$d_1^{\alpha_{n-1}} = \rho_{\alpha_{n-1}}(T(x), T(y)) \le \frac{1}{2} \Phi_{\alpha_{n-1}}(\rho_{j_1(\alpha_{n-1})}(x, y) + \rho_{j_2(\alpha_{n-1})}(x, y))$$
  
$$\le \frac{1}{2} \Phi_{\alpha_{n-1}}(\rho_{j_1(\alpha_{n-1})}(x, y)) + \frac{1}{2} \Phi_{\alpha_{n-1}}(\rho_{j_2(\alpha_{n-1})}(x, y)) \le \overline{\Phi}_{\alpha}(\rho_{\alpha_n^*}(x, y)),$$

where  $\alpha_n^* \in S_1(\alpha_{n-1})$  is such that  $\rho_{\alpha_n^*}(x, y) = \max\{\rho_{j_1(\alpha_{n-1})}(x, y), \rho_{j_2(\alpha_{n-1})}(x, y)\}$ .

Therefore  $d_1^{\alpha_{n-1}} \leq \overline{\Phi}_{\alpha}(p_{\alpha}(x,y))$  for  $\alpha_{n-1} \in S_1(\alpha_{n-2})$ .

By induction, for every choice of  $\sigma^n \in S^n(\alpha)$  and its coordinates  $\alpha_{n-k}$ , we prove:

$$d_k^{\alpha_{n-k}} \leq \overline{\Phi}_{\alpha}^k(p_{\alpha}(x,y)) \forall k = 1, 2, ..., n-1.$$

Indeed, we have just obtained that the estimates are valid for k = 1. If we suppose that the above inequalities are satisfied for all  $k \leq m < n - 1$ , then for k = m + 1 we obtain:

$$\begin{aligned} d_{m+1}^{\alpha_{n-m-1}} &= \rho_{\alpha_{n-m-1}}(T^{m+1}(x), T^{m+1}(y)) \\ &\leq \frac{1}{2} \Phi_{\alpha_{n-m-1}}(\rho_{j_{1}(\alpha_{n-m-1})}(T^{m}(x), T^{m}(y))) + \frac{1}{2} \Phi_{\alpha_{n-m-1}}(\rho_{j_{2}(\alpha_{n-m-1})}(T^{m}(x), T^{m}(y))) \\ &\leq \overline{\Phi}_{\alpha}\left(d_{m}^{\alpha_{n-m}^{*}}\right), \end{aligned}$$

where  $\alpha_{n-m}^* \in S_1(\alpha_{n-m-1})$  is such that

$$d_m^{\alpha_{n-m}^*} = \rho_{\alpha_{n-m}^*}(T^m(x), T^m(y)) = \max\{\rho_{j_1(\alpha_{n-m-1})}(T^m(x), T^m(y)), \rho_{j_2(\alpha_{n-m-1})}(x_m, x_{m+1})\}$$

In particular,  $d_{m}^{\alpha_{n-m}^{*}} \leq \overline{\Phi}_{\alpha}^{m}(p_{\alpha}(x,y))$ . It follows  $d_{m+1}^{\alpha_{n-m-1}} \leq \overline{\Phi}_{\alpha}\left(\overline{\Phi}_{\alpha}^{m}(p_{\alpha}(x,y))\right) = \overline{\Phi}_{\alpha}^{m+1}(p_{\alpha}(x,y))$ . This completes the induction. Finally,

$$\begin{aligned} d_n^{\alpha} &= \rho_{\alpha} \left( T^n(x), T^n(y) \right) \leq \frac{1}{2} \Phi_{\alpha}(\rho_{j_1(\alpha)}(T^{n-1}(x), T^{n-1}(y)) + \rho_{j_2(\alpha)}(T^{n-1}(x), T^{n-1}(y))) \\ &\leq \frac{1}{2} \Phi_{\alpha}(\rho_{j_1(\alpha)}(T^{n-1}(x), T^{n-1}(y))) + \frac{1}{2} \Phi_{\alpha}(\rho_{j_2(\alpha)}(T^{n-1}(x), T^{n-1}(y))) \leq \overline{\Phi}_{\alpha}(\rho_{\alpha_1^*}(T^{n-1}(x), T^{n-1}(y))), \end{aligned}$$

where  $\alpha_1^* \in S_1(\alpha)$  is such that  $\rho_{\alpha_1^*}(x, y) = \max\{\rho_{j_1(\alpha)}(x, y), \rho_{j_2(\alpha)}(x, y)\}$ , and consequently

 $\rho_{\alpha_1^*}(T^{n-1}(x), T^{n-1}(y)) = d_{n-1}^{\alpha_1^*} \leq \overline{\Phi}_{\alpha}^{n-1}(p_{\alpha}(x, y)). \text{ Therefore } d_n^{\alpha} \leq \overline{\Phi}_{\alpha}^n(p_{\alpha}(x, y)).$ The properties of the function  $\overline{\Phi}_{\alpha} \in (\Phi)$  guarantee that  $\overline{\Phi}_{\alpha}^n(t) \xrightarrow[n \to \infty]{} 0$  for any fixed  $t \in [0, \infty).$  Thus, if we suppose that there exist two elements  $x \neq y$  of X, for which x = T(x) and y = T(y), then for every index  $\alpha \in A \ \rho_{\alpha}(x, y) = \rho_{\alpha}(T^n(x), T^n(y)) \leq \overline{\Phi}_{\alpha}^n(p_{\alpha}(x, y))$  for all  $n \in \mathbb{N}$ , which implies  $\rho_{\alpha}(x, y) = 0$  for every  $\alpha \in A$ . The obtained contradiction proves Theorem 2.3. 

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