

A Study On The Parallel Normal Deformation In A Subspace W_n Of A Weyl Space W_m

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The parallel tangent and parallel Frenet deformation in Weyl space have already been investigated [7]. In this study some problems of deformations of subspace W_n of a Weyl space W_m were investigated. The necessary conditions that the normal N_ν^a ($\nu = n+1, \dots, m$) denoting the contravariant components of a system of unit normals to W_n be deformed parallelly and parallel tangent deformation for subspace W_n of W_m were obtained.

1. Introduction

An n - dimensional manifold W_n is said to be a Weyl space if it has a conformal metric tensor g_{ij} and a symmetric connection ∇_k satisfying the compatibility condition given by the equation

$$\nabla_k g_{ij} - 2T_k g_{ij} = 0 \quad (1.1)$$

where T_k denotes a covariant vector field [1], [3],[4].

Under a renormalization of the fundamental tensor of the form

$$\tilde{g}_{ij} = \lambda^2 g_{ij} \quad (1.2)$$

the complementary vector field T_k is transformed by the law

$$\tilde{T}_k = T_k + \partial_k \ln \lambda \quad (1.3)$$

where λ is a scalar function defined on W_n .

A quantity A is called a satellite of weight $\{p\}$ of the tensor g_{ij} , if it admits a transformation of the form

$$\tilde{A} = \lambda^p A \quad (1.4)$$

under the renormalization (1.2) of the metric tensor g_{ij} [1], [3],[4].

The prolonged covariant derivative of a satellite A of the tensor g_{ij} of weight $\{p\}$ is defined by [1], [2],[3]

$$\dot{\nabla}_k A = \nabla_k A - p T_k A. \quad (1.5)$$

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We note that the prolonged covariant derivative preserves the weight.

The generalized derivative of a satellite A of the tensor g_{ij} with weight $\{p\}$ is defined by [1], [3],[4]

$$\partial_k A = \partial_k A - p T_k A . \quad (1.6)$$

Let $W_n(g_{ij}, T_k)$ be a subspace which is immersed in a Weyl space $W_m(g_{ab}, T_c)$. We shall denote the coordinates in W_n and W_m by $u^i (i=1, \dots, n)$ and $x^a (a=1, \dots, m)$; the fundamental tensors by g_{ij} and g_{ab} ; the complementary vector T_k and T_c , respectively.

The coefficients of the metrics are connected by the relation

$$g_{ab} \frac{\partial x^a}{\partial u^i} \frac{\partial x^b}{\partial u^j} = g_{ij} . \quad (1.7)$$

On the other hand, the complementary vectors T_c and T_k , relative to W_m and W_n are connected by the relation

$$T_k = x_k^a T_a . \quad (1.8)$$

So, the prolonged covariant derivative of A , related to W_n and W_m , are defined by

$$\dot{\nabla}_k A = x_k^a \dot{\nabla}_a A \quad (k=1, 2, \dots, n ; a=1, 2, \dots, m) \quad (1.9)$$

where x_k^a denotes the covariant derivatives of x^a with respect to u^i (in the sequel, the indices i, j, k, \dots will run from 1 to n , while the indices a, b, c, \dots will run from 1 to m).

Let $N_\nu^a (v = n+1, \dots, m)$ be the contravariant components in W_m of a system $(m-n)$ normals to W_n .

It is obvious that they satisfy the relations

$$g_{ab} N_\nu^a N_\mu^b = \delta_\mu^\nu \quad (1.10)$$

and

$$g_{ab} N_\mu^a x_i^b = 0 . \quad (1.11)$$

These $N_\nu^a (v, \mu, \tau, \rho = n+1, \dots, m)$ vectors as seen from (1.5) are normalized by the condition

$$g_{ab} N_\nu^a N_\nu^b = 1 .$$

It follows immediately from $g_{ab} N_\nu^a N_\nu^b = 1$ that N_ν^a are satellites of g_{ab} with weight $\{-1\}$, [4].

Since the functions x^a are invariants for transformations of u 's in W_n , their first prolonged covariant derivative with respect to u 's is the same as their covariant derivative or partial derivative, that is

$$\nabla_i x = x^a_{,i} = x_i^a = \frac{\partial x^a}{\partial u^i}. \quad (1.12)$$

On the other hand, the weight of x_i^a is $\{0\}$, [2], [3], [5]. So

$$\square \nabla_j x_i^a = \nabla_j x_i^a. \quad (1.13)$$

According to (1.13) the covariant derivative of x_i^a with respect to u^j is

$$\square \nabla_j x_i^a = \sum_{\nu} w_{ij}^{\nu} N_{\nu}^a \quad (1.14)$$

where the coefficients w_{ij}^{ν} are the components of a symmetric covariant tensor of the second order. Using (1.10) and (1.13), it is easily seen that the prolonged covariant derivatives of N_{ν}^a with respect to u^i is [5]

$$\square \nabla_i N_{\nu}^a = -w_{ij}^{\nu} g^{kj} x_j^a + \sum_{\mu} \theta_i^{\mu} N_{\mu}^a. \quad (1.15)$$

2. Paralel Normal Deformation

Let the point of $W_n(g_{ij}, T_{\kappa})$ be infinitesimally displaced in $W_m(g_{ab}, T_c)$ such that the coordinates \bar{x}^a of the point \bar{P} (of the deformed subspace \bar{W}_n) corresponding to the point P of the subspace W_n are given by

$$\bar{x}^a = x^a + \varepsilon \lambda^a \quad (2.1)$$

where ε is an infinitesimal constant with weight $\{1\}$ and λ^a are components of the contravariant vector with weight $\{-1\}$ [6],[7],[10]. On the other hand, let T be tensor field in W_m and let the points of the manifold undergo an infinitesimal transformation of the form (2.1). The value of the tensor field at the new points \bar{x}^a will be given by

$$T(\bar{x}) = T(x) + \varepsilon \lambda^b \partial_b T. \quad (2.2)$$

In addition, it will be supposed that without loss of the generality that \bar{x}^a are also functions of u 's

$$\bar{x}^a = \bar{x}^a(u^1, u^2, \dots, u^n). \quad (2.3)$$

Let us give and prove the different statements of the two theorems for the parallel normal deformation.

Theorem 1: The condition that the normal N_{ν}^a of the space $W_n(g_{ij}, T_{\kappa})$ immersed in a Weyl space $W_m(g_{ab}, T_c)$ be deformed paralelly during an infinitesimal deformation defined by (2.1)

$$\text{is } g_{ab} N_{\mu}^a \square \nabla_i \lambda^b = 0.$$

Proof: N^a_ν ($\nu = n+1, \dots, m$) at the point P of the subspace W_n denote the components of $(m-n)$ mutually orthonormals with weight $\{-1\}$ normalized by the condition

$$g_{ab} N^a_\nu N^b_\nu = 1 \quad (2.4)$$

The values of covariant components of the fundamental tensor of W_m at \bar{P} which is in the deformed subspace \bar{W}_n are given by

$$\bar{g}_{ab} = g_{ab} + \varepsilon \lambda^c (g_{ad} W_{bc}^d + g_{bd} W_{ac}^d) \quad (2.5)$$

[7],[9].

On the other hand let us use the symbol $\dot{\bar{\nabla}}$ for the prolonged covariant derivative in the deformed subspace \bar{W}_n .

\bar{N}^a_μ ($\mu = n+1, \dots, m$) at the point \bar{P} of the deformed subspace \bar{W}_n denote the components of $(m-n)$ mutually orthogonal normals with weight $\{-1\}$ normalized by the condition

$$\bar{g}_{ab} \bar{N}^a_\mu \bar{N}^b_\mu = 1 \quad (2.6)$$

and

$$\bar{g}_{ab} \bar{N}^a_\mu \dot{\bar{\nabla}}_i \bar{x}^b = 0 \quad (2.7)$$

\bar{N}^a_ν ($\nu = n+1, \dots, m$) at the point \bar{P} of the deformed subspace \bar{W}_n denote the components of $(m-n)$ mutually orthonormals with weight $\{-1\}$ normalized by the condition $\bar{g}_{ab} \bar{N}^a_\mu \bar{N}^b_\mu = 1$ and \bar{N}^a_μ is a vector with weight $\{-1\}$ normalized by the condition $\bar{g}_{ab} \bar{N}^a_\nu \bar{N}^b_\nu = 1$ and parallel to unit normal N^a_μ at P .

By using (1.5), (1.6)

$$\dot{\bar{\nabla}}_i \bar{x}^a = \frac{\dot{\bar{\partial}} \bar{x}^a}{\partial u^i} = \bar{\nabla}_i \bar{x}^a = \frac{\partial \bar{x}^a}{\partial u^i} \quad (2.8)$$

can be written.

By using [7],[8] and [10] we can define the vectors δN^a_ν and ΔN^a_ν , respectively as

$$\delta N^a_\nu = \bar{N}^a_\nu - \bar{\bar{N}}^a_\nu \quad (2.9)$$

and

$$\Delta N^a_\nu = \lim_{\delta s \rightarrow 0} \frac{\delta N^a_\nu}{\delta s} \quad (2.10)$$

where δs define as

$$\delta s = \sqrt{g_{ab} \delta x^a \delta x^b} = \varepsilon \lambda \quad (2.11)$$

On the other hand, the condition that the unit normal N^a_ν be deformed parallelly is written by using [7] and [8] as

$$\Delta N^a_\nu = 0 \tag{2.12}$$

According to (2.10)

$$\delta N^a_\nu = 0 \tag{2.13}$$

and according to (2.9), it is seen that

$$\overline{N^a_\nu} = \overline{N^a_\nu} . \tag{2.14}$$

Then, from [7],

$$\overline{N^a_\nu} = N^a_\nu - W^a_{bc} N^b_\nu \cdot \varepsilon \lambda^c . \tag{2.15}$$

By using (2.14) in (2.15) it follows that,

$$\overline{N^a_\nu} = N^a_\nu - \varepsilon W^a_{bc} N^b_\nu \lambda^c . \tag{2.16}$$

From (2.1) and (2.8), it follows that

$$\frac{\dot{\partial} \overline{x^a}}{\partial u^i} = \frac{\dot{\partial} x^a}{\partial u^i} + \varepsilon \frac{\dot{\partial} \lambda^a}{\partial u^i} . \tag{2.17}$$

or

$$\dot{\nabla}_i x^a = \dot{\nabla}_i x^a + \varepsilon \frac{\dot{\partial} \lambda^a}{\partial u^i} \tag{2.18}$$

If we use (2.5), (2.16) and (2.18) in (2.7) and neglecting the terms of the second and higher order of ε , the following equations can be written;

$$\left[g_{ab} + \varepsilon \lambda^c (g_{ad} W^d_{bc} + g_{bd} W^d_{ac}) \right] \left[N^a_\mu + \varepsilon \lambda^f W^a_{ef} N^e_\mu \right] \left[\nabla_i x^b + \varepsilon \frac{\dot{\partial} \lambda^b}{\partial u^i} \right] = 0$$

$$g_{ab} N^a_\mu \frac{\partial \lambda^b}{\partial u^i} + g_{ab} W^b_{dc} \lambda^c N^a_\mu x^d_i = 0 \tag{2.20}$$

$$N^b_\mu \left(\frac{\dot{\partial} \lambda^b}{\partial u^i} + W^b_{dc} \lambda^c x^d_i \right) = 0 \tag{2.21}$$

and by using (1.6),

$$N^b_\mu \left(\frac{\partial \lambda^b}{\partial u^i} + T_i \lambda^b + W^b_{dc} \lambda^c x^d_i \right) = 0 \tag{2.22}$$

and by using [9],

$$N^b_\mu (\nabla_i \lambda^b + T_i \lambda^b) = 0 \tag{2.23}$$

and from (1.5)

$$N^b_\mu \dot{\nabla}_i \lambda^b = 0 \tag{2.24}$$

So, the theorem is proved.

Now, let us prove the following theorem which is the another form for the condition of parallel normal deformation.

Theorem 2: The condition of parallel deformation of the normal N_μ^a of the subspace $W_n(g_{ij}, T_k)$ immersed in a Weyl space $W_m(g_{ab}, T_c)$ is

$$p^k w_{kj} + (\nabla_j^\square c) + \sum_{\tau} c \theta_j = 0. \quad (2.25)$$

Proof: λ^a defined in [10] as a vector in W_m being expressed linearly in terms of any m vectors not lying in the same geodesic surface can be expressed by tangential and normal component with respect to W_n .

$$\lambda^a = p^i x_i^a + \sum_{\nu} c N_\nu^a \quad (2.26)$$

where

$$c = g_{ab} \lambda^a N_\nu^b = \lambda \cos \theta. \quad (2.27)$$

Taking the prolonged covariant derivative of (2.26) with respect to u^j and using (1.14), (1.15), it follows that

$$\begin{aligned} \nabla_j \lambda^b = & [(\nabla_j^\square p^k) - \sum_{\nu} c W_{\nu j}^k g^{jk}] x_k^a + \\ & + \sum_{\nu} (p^k w_{kj} + \nabla_j^\square c + \sum_{\mu} c \theta_j) N_\nu^a \end{aligned} \quad (2.28)$$

by putting (2.28) in

$$N_\mu^b \nabla_j \lambda^b = 0$$

and also using (1.10) and (1.11) we get

$$p^k w_{kj} + \nabla_j^\square c + \sum_{\tau} c \theta_j = 0. \quad (2.29)$$

So, the theorem is proved.

Parallel tangent deformation in Weyl space has been already studied [7]. By using these results as well let us prove the following theorem.

Theorem 3: If all the tangents x_i^a of a subspace W_n immersed in W_m are displaced parallelly during an infinitesimal deformation, then so are all the normal of W_n in W_m

Proof: Let x_i^a be components of a vector at P tangential to the curve of parameter u^i in W_n . The components \bar{x}_i^a of the corresponding tangential vector at \bar{P} in the deformed subspace \bar{W}_n .

Let \bar{x}_i^a be a vector at \bar{P} parallel to x_i^a .

In this case, by using [7], [8] and [10], $\frac{\partial \bar{x}^a}{\partial u^i} = \frac{\partial x^a}{\partial u^i} + \varepsilon \frac{\partial \lambda^a}{\partial u^i}$, $\frac{\partial \bar{x}^a}{\partial u^i} = \frac{\partial x^a}{\partial u^i} - W_{bc}^a x_i^b \lambda^c \varepsilon$ and

$\delta x_i^a = \varepsilon \left(\frac{\partial \lambda^a}{\partial u^i} + W_{bc}^a x_i^b \lambda^c \right)$ are written.

Then, according to, (2.9), (2.10), (2.11) and (2.12) we write $\delta x_i^a = 0$,

$$\frac{\partial \lambda^a}{\partial u^i} + W_{bc}^a x_i^b \lambda^c = 0 \quad (2.30)$$

i.e.

$$\nabla_i \lambda^a = 0 \quad (2.31)$$

This condition and (2.24) are combined and the theorem is proved

3. Special cases:

I. Let $W_n(g_{ij}, T_k)$ be a hypersurface which is immersed in a Weyl space $W_{n+1}(g_{ab}, T_t)$.

The following equations are given in [11]

$$\lambda^b = p^k x_k^b + c N^b \quad (3.1)$$

$$\square \nabla_k x_i^a = w_{ik} N^a \quad (3.2)$$

$$\square \nabla_j \lambda^b = (\nabla_j p^m - c g^{km} w_{jk}) x_m^b + (w_{jm} p^m + \square \nabla_j c) N^b \quad (3.3)$$

By considering the above equations and the special case of (2.24), $N_b \square \nabla_j \lambda^b = 0$ then (2.29) becomes

$$\square \nabla_i c + p^j w_{ji} = 0. \quad (3.4)$$

II. If the deformation is in W_n , that is the vector λ^a lies in W_n , λ^a is written as

$$\lambda^a = p^i x_i^a \quad (3.5)$$

As can be seen from (2.26), all c are zero. In this case, the condition (2.29) becomes

$$p^k w_{kj} = 0. \quad (3.6)$$

If W_n is also totally geodesic according to enveloping space W_m , $w_{kj} = 0$.

In this case the condition (2.29) is identically satisfied.

III. $\lambda^a = \sum_{\nu} c_{\nu} N^{\nu}$, then the condition (2.27) becomes

$$\square \nabla_j c + \sum_{\tau} c_{\tau} N^{\tau} = 0 \quad (3.7)$$

If the deformation λ^a is only along N^a , the λ^a becomes

$$\lambda_{\mu}^{\alpha} = c N_{\mu}^{\alpha} \quad (3.8)$$

It is clear that $c_{\mu} = \lambda$ and $c_{\nu} = 0$ ($\mu \neq \nu$).

In this case, the condition (3.7) if $c_{\mu} = \text{const.}$, i.e. the deformation is of constant magnitude.

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