

## PROJECTIVE AFFINE MOTION IN A $PRF_n$ -SPACE, III

A. KUMAR

In this paper the existence of an infinitesimal affine motion of concircular form

$$\bar{x}^i = x^i + v^i(x) dt, \quad v^i(j) = \beta \delta^i_j + \phi_j(x) v^i$$

is studied, where  $\beta(x)$  is any function and  $\phi_j(x)$  denotes a gradient vector defined by

$$\phi_j(x) = \phi_{(j)} = \partial_j \phi.$$

**1. Introduction.** Let us consider an  $n$ -dimensional affinely connected Finsler space  $F_n$  [1]<sup>1)</sup> having a fundamental positively homogeneous metric function  $F(x, \dot{x})$  which satisfies all the requisite conditions imposed upon it. The fundamental metric tensor of the space is given by

$$g_{ij}(x, \dot{x}) \stackrel{\text{def.}}{=} \frac{1}{2} \dot{\partial}_i \dot{\partial}_j F^2(x, \dot{x}) \quad (1.1)$$

where  $\dot{\partial}_i \equiv \partial / \partial \dot{x}^i$ .

Let us further consider a tensor field  $T_j^i(x, \dot{x})$  which depends both upon positional and directional arguments. The covariant derivative of  $T_j^i(x, \dot{x})$  in the sense of Berwald with respect to  $x^k$  is given by

$$T_{j(k)}^i = \partial_k T_j^i - \dot{\partial}_m T_j^i G_k^m + T_j^s G_{sk}^i - T_s^i G_{jk}^s, \quad (1.2)$$

where  $G_{jk}^i(x, \dot{x})$  are called Berwald's connection coefficients. The commutation formula involving the above covariant derivative is given by

$$2T_{j[(h)(k)]}^i = -\dot{\partial}_\gamma T_j^i H_{hk}^\gamma + T_j^s H_{shk}^i - T_s^i H_{jhk}^s, \quad (1.3)$$

where

$$H_{hjk}^i(x, \dot{x}) \stackrel{\text{def.}}{=} 2 \{ \partial_{[k} G_{j]h}^i - G_{\gamma h}^i \cup G_{kl}^\gamma + G_h^\gamma \cup G_{k] \gamma}^i \} \quad (1.4)$$

is called Berwald's curvature tensor and satisfies the following relations [1]:

<sup>1)</sup> Numbers in brackets refer to the references at the end of the paper.

<sup>2)</sup>  $2A_{[hk]} = A_{hk} - A_{kh}$

$$H^i_{hjk} + H^i_{jkh} + H^i_{khl} = 0, \quad (1.5)$$

$$H^i_{hjk(s)} + H^i_{hks(j)} + H^i_{hsj(k)} = G^i_{\gamma hj} H^\gamma_{sk} + G^i_{\gamma hk} H^\gamma_{js} + G^i_{\gamma hs} H^\gamma_{kj}, \quad (1.6)$$

$$H^i_{hjk} = -H^i_{hkj}. \quad (1.7)$$

Now, let us consider an infinitesimal point transformation

$$\bar{x}^i = x^i + v^i(x) dt,$$

where  $v^i(x)$  is any vector field and  $dt$  is an infinitesimal point constant. In view of the above point transformation and Berwald's covariant derivative, Lie-derivatives of  $T^i_j(x, \dot{x})$  and  $G^i_{jk}(x, \dot{x})$  are given by

$$\mathcal{L}_v T^i_j = T^i_{j(h)} v^h + T^i_h v^h_{(j)} - T^i_j v^i_{(h)} + \dot{\partial}_h T^i_j v^h_{(r)} \dot{x}^r \quad (1.9)$$

and

$$\mathcal{L}_v G^i_{jk} = v^l_{(j)(k)} + H^i_{jkh} v^h + G^i_{hjk} v^h_{(r)} \dot{x}^r \quad (1.10)$$

respectively.

If the Berwald's curvature tensor  $H^i_{hjk}(x, \dot{x})$  satisfies the relation

$$H^i_{hjk(s)} = \lambda_s H^i_{hjk}, \quad (1.11)$$

where  $\lambda_s(x)$  means a non-zero covariant vector then the space  $F_n$  is called a projective recurrent Finsler space or PRF $_n$ -space and  $\lambda_s(x)$  is called a projective recurrent vector.

The present author has studied infinitesimal affine motions of many kinds in such an PRF $_n$ -space and obtained the following results [6]:

An PRF $_n$ -space is able to admit an infinitesimal affine motion (1.8) characterized by

$$\text{a) } v^i_{(j)} = 0 \quad \text{b) } v^i_{(j)} = \phi_j(x) v^i \quad (1.12)$$

that is, a contraform and a recurrent form respectively, but PRF $_n$ -space is unable to have a motion of concurrent form and special concircular form respectively [5], [6]:

$$\begin{aligned} \text{a) } v^i_{(j)} &= p \delta_j^i \quad (p = \text{non-zero const.}), \\ \text{b) } v^i_{(j)} &= \phi(x) \delta_j^i \quad (\phi = \text{non-zero function}). \end{aligned} \quad (1.13)$$

In this manuscript we shall study the existence of an infinitesimal affine motion of concircular form:

$$\bar{x}^i = x^i + v^i(x) dt, \quad v^i_{(j)} = \beta \delta^i_j + \phi_j(x) v^i, \quad (1.14)$$

where  $\beta(x)$  is any function and  $\phi_j(x)$  denotes a gradient vector defined by

$$\phi_j(x) = \phi_{(j)} = \partial_j \phi. \quad (1.15)$$

**2. Fundamental Results (1).** For an infinitesimal projective affine motion, we have

$$\mathcal{L}_v G^i_{jk} = v^i_{(j)} G_{(k)} + H^i_{jkh} v^h + G^i_{hjk} v^h_{(r)} \dot{x}^r = 0. \quad (2.1)$$

In an PRF<sub>n</sub>-space, the integrability condition for the above equation is given by

$$\begin{aligned} \mathcal{L}_v H^i_{hjk} = & \lambda_s v^s H^i_{hjk} - H^s_{hjk} v^i_{(s)} + H^i_{sjk} v^s_{(h)} + H^i_{hsk} v^s_{(j)} + \\ & + H^i_{hjs} v^s_{(k)} + \dot{\partial}_s H^i_{hjk} v^s_{(r)} \dot{x}^r. \end{aligned} \quad (2.2)$$

During the process of study we shall assume here the existence of projective affine motion of concircular form as follows :

$$\bar{x}^i = x^i + v^i(x) dt, \quad v^i_{(j)} = \beta(x) \delta^i_j + \phi_j(x) v^i, \quad (2.3)$$

where  $\beta = \beta(x)$  is a scalar function and  $\phi_j(x)$  means a covariant vector depending only upon the positional arguments. From the above definition, we can obtain

$$v^i_{(j)(k)} = \phi_{j(k)} v^i + \phi_j \phi_k v^i + \beta \phi_j \delta^i_k + \beta_k \delta^i_j, \quad (2.4)$$

where

$$\beta_k \stackrel{\text{def}}{=} \beta_{(k)} = \partial_k \beta \quad (2.5)$$

and we have also used the equation (2.3).

In view of the equation (2.4), the formula (2.1) reduces to

$$H^i_{jkh} v^h = \phi_{j(k)} v^i + \phi_j \phi_k v^i + \beta \phi_j \delta^i_k + \beta_k \delta^i_j. \quad (2.6)$$

By virtue of the fact  $H^i_{hjk} v^j v^k = 0$ , transvecting the above equation by  $v^k$ , we have

$$\phi_{j(k)} v^i v^k + \phi_j \phi_k v^i v^k + \beta \phi_j v^i + \beta_k \delta^i_j v^k = 0. \quad (2.7)$$

Contracting the above equation with respect to the indices  $i$  and  $j$ , we get

$$\phi_{j(k)} v^j v^k + \phi_j \phi_k v^j v^k + \beta \phi_j v^j + n \beta_k v^k = 0. \quad (2.8)$$

Now, transvecting the result (2.7) by  $v^j$ , we obtain

$$\phi_{j(k)} v^i v^k v^j + \phi_j \phi_k v^i v^k v^j + \beta \phi_j v^i v^j + \beta_k v^k v^i = 0. \quad (2.9)$$

And for a non-vanishing  $v^i(x)$ , the above equation yields

$$\phi_{j(k)} v^k v^j + \phi_j \phi_k v^k v^j + \beta \phi_j v^j + \beta_k v^k = 0. \quad (2.10)$$

Now comparing the equations (2.8) and (2.10), we get

$$(n-1)\beta_k v^k = 0 \quad (2.11)$$

or

$$\beta_k v^k = 0 \quad (n \neq 1). \quad (2.12)$$

Thus, we have :

**Lemma (2.1).** If an  $n$ -dimensional  $\text{PRF}_n$ -space admits a projective affine motion of a torse-forming form

$$\bar{x}^i = x^i + v^i(x) dt, \quad v^i_{(j)} = \beta(x) \delta^i_j + \phi_j(x) v^i$$

then the scalar function  $\beta(x)$  must be a Lie-invariant-one or  $\mathfrak{L}\beta = 0$ .

In view of the above lemma and the non-vanishing property of the vector  $v^i(x)$ , the equation (2.7) can be written like

$$\phi_{j(k)} v^k + \phi_j \phi_k v^k + \beta \phi_j = 0. \quad (2.13)$$

The above formula can also be written in a compact form :

$$(\phi_j v^j)_{(k)} = 0, \quad (2.14)$$

where we have used (2.3) and the fact that  $\phi_{j(k)} = \phi_{k(j)}$ . Thus, we have :

**Lemma (2.2).** If an  $n$ -dimensional  $\text{PRF}_n$ -space admits an projective affine motion of concircular form,  $\phi_j v^j$  must be a constant.

Contracting the equation (2.4) with respect to the indices  $i$  and  $k$ , we have

$$v^h_{(j)(i)} = \phi_{j(i)} v^h + \phi_j (n\beta + \phi_h v^h) + \beta_j. \quad (2.15)$$

Substituting (2.13) into the right hand side of the equation (2.15), we get

$$v^h_{(j)(i)} = (n-1)\beta \phi_j + \beta_j. \quad (2.16)$$

Differentiating the equation (2.6) covariantly with respect to  $x^s$  and using the equations (1.11) and (2.3), we obtain

$$\begin{aligned} (\lambda_s + \phi_s) H^i_{jkh} v^h + \beta H^i_{jks} &= \phi_{j(k)(s)} v^i + \phi_{j(k)} v^i_{(s)} + \phi_{j(s)} \phi_k v^i + \\ &+ \phi_j \phi_{k(s)} v^i + \phi_j \phi_k v^i_{(s)} + \beta_s \phi_j \delta^i_k + \beta \phi_{j(s)} \delta^i_k + \beta_{k(s)} \delta^i_j. \end{aligned} \quad (2.17)$$

Contracting the above equation with respect to the indices  $i$  and  $j$ , we have

$$\begin{aligned} (\lambda_s + \phi_s) H^i_{ikh} v^h + \beta H^i_{iks} &= \phi_{i(k)(s)} v^i + \phi_{i(k)} v^i_{(s)} + \phi_i \phi_{k(s)} v^i + \\ &+ \phi_i \phi_k v^i_{(s)} + \beta_s \phi_k + \beta \phi_{k(s)} + n\beta_{k(s)}. \end{aligned} \quad (2.18)$$

Now, differentiating (2.13) covariantly with respect to  $x^s$  and arranging indices appearing in its result suitably, we get

$$\begin{aligned} \phi_{k(i)(s)} v^i + \phi_{k(i)} v^i_{(s)} + \phi_{k(s)} \phi_i v^i + \phi_k \phi_{i(s)} v^i + \phi_k \phi_i v^i_{(s)} + \\ + \beta_s \phi_k + \beta \phi_{k(s)} = 0, \end{aligned} \quad (2.19)$$

If we compare these two equations (2.18) and (2.19) with each other and use the property  $\phi_{j(k)} = \phi_{k(j)}$ , we obtain

$$(\lambda_s + \phi_s) H^i{}_{ikh} v^h + \beta H^i{}_{iks} = n \beta_{k(s)}. \quad (2.20)$$

Using commutativity of  $\beta_{k(s)}$  with respect to its indices, we can get an equality

$$(\lambda_s + \phi_s) H^i{}_{ikh} v^h + \beta H^i{}_{iks} = (\lambda_k + \phi_k) H^i{}_{ish} v^h + \beta H^i{}_{isk} \quad (2.21)$$

or

$$2\beta H^i{}_{iks} = (\lambda_k + \phi_k) H^i{}_{ish} v^h - (\lambda_s + \phi_s) H^i{}_{ikh} v^h, \quad (2.22)$$

where we have used (1.7).

Transvecting the equation (2.22) by  $v^s$  and noting the fact that  $H^i{}_{hjk} v^j v^k = 0$ , we obtain

$$2\beta H^i{}_{iks} v^s = (\lambda_s + \phi_s) H^i{}_{ikh} v^s v^h \quad (2.23)$$

or

$$H^i{}_{iks} v^s (2\beta + \lambda_h v^h + \phi_h v^h) = 0. \quad (2.24)$$

If we assume  $H^i{}_{iks} v^s \neq 0$ , the above equation reduces to

$$2\beta + \lambda_h v^h + \phi_h v^h = 0. \quad (2.25)$$

In view of the commutation formula (1.3) and the latter part of (2.3), we can construct the relation

$$v^h H^i{}_{hjk} = \beta(\phi_j \delta^i{}_k - \phi_k \delta^i{}_j) + (\beta_k \delta^i{}_j - \beta_j \delta^i{}_k). \quad (2.26)$$

Contracting the above formula with respect to the indices  $i$  and  $k$ , we have

$$v^h H^i{}_{hji} = (n-1)(\beta\phi_j - \beta_j). \quad (2.27)$$

By virtue of the lemma (2.1) transvecting the above equation by  $v^j$ , and summing over the index  $j$ , we obtain

$$H^i{}_{hji} v^h v^j = (n-1)\beta\phi_j v^j. \quad (2.28)$$

Differentiating (2.28) covariantly with respect to  $x^m$ , we have

$$H^i_{hji(m)} v^h v^j + H^i_{hji} v^h_{(m)} v^j + H^i_{hji} v^h v^j_{(m)} = (n-1) \{ \beta_m \phi_j v^j + \beta \phi_{j(m)} v^j + \beta \phi_j v^j_{(m)} \}. \quad (2.29)$$

In view of the equations (1.11), (2.3), (2.13) and (2.28), the above relation can be written like

$$(n-1) (2\beta \phi_m + \beta \lambda_m - \beta_m) \phi_j v^j = \beta v^j (H^i_{mji} + H^i_{jmi}). \quad (2.30)$$

Transvecting the above equation by  $v^m$  and using the equation (2.27) and lemma (2.1), we obtain

$$(n-1) (2\beta \phi_m + \beta \lambda_m - \beta_m) \phi_j v^j v^m = 2(n-1) \beta^2 \phi_m v^m \quad (2.31)$$

or

$$(2\phi_m v^m + \lambda_m v^m + 2\beta) \beta \phi_j v^j = 0. \quad (n \neq 1). \quad (2.32)$$

Substituting the equation (2.25) into the left hand side of the above formula, we get

$$\beta (\phi_j v^j) (\phi_m v^m) = 0. \quad (2.33)$$

Hence, we get the two cases being  $\beta = 0$  or  $\phi_j v^j = 0$ .

**3. Fundamental Results (2).** In the previous section, we have obtained two cases  $\beta = 0$  or  $\phi_j v^j = 0$ , but, unfortunately, the latter condition becomes the former condition. In this section, we shall prove this fact.

In an affinely connected Finsler space, Bianchi identity for Berwald's curvature tensor  $H^i_{hjk}(x, \dot{x})$  is given by

$$H^i_{hjk(s)} + H^i_{hks(j)} + H^i_{hsj(k)} = 0. \quad (3.1)$$

By virtue of the equations (1.7) and (1.11), the above formula yields

$$\lambda_s H^i_{hjk} - \lambda_j H^i_{hsk} + \lambda_k H^i_{hsj} = 0. \quad (3.2)$$

Transvecting the above result by  $v^k$  and summing over the index  $k$ , we get

$$\lambda_s H^i_{hjk} v^k - \lambda_j H^i_{hsk} v^k + \lambda_k v^k H^i_{hsj} = 0. \quad (3.3)$$

By virtue of the equations (2.1) and (3.3) we can get

$$\lambda_s (v^i_{(h)(j)} + G^i_{nhj} v^n_{(\tau)} \dot{x}^\tau) - \lambda_j (v^i_{(h)(s)} + G^i_{nhs} v^n_{(\tau)} \dot{x}^\tau) + \lambda_k v^k H^i_{hsj} = 0. \quad (3.4)$$

Contracting the above equation with respect to the indices  $i$  and  $h$ , we have after little simplification

$$\lambda_s v^h_{(h)(j)} - \lambda_j v^h_{(h)(s)} + \lambda_k v^k H^h_{hsj} = 0. \quad (3.5)$$

For  $\phi_h v^h = 0$ , the formula (2.25) takes the form :

$$\lambda_h v^h = -2\beta. \quad (3.6)$$

Therefore, in view of the above equation the formula (3.5) takes the form :

$$\lambda_s v^h_{(h)(j)} - \lambda_j v^h_{(h)(s)} - 2\beta H^h_{hsj} = 0. \quad (3.7)$$

Contracting the latter part of (2.3) with respect to the indices  $i$  and  $j$ , we obtain

$$v^h_{(h)} = n\beta + \phi_h v^h = n\beta. \quad (3.8)$$

Differentiating the above equation covariantly with respect to  $x^m$ , we have

$$v^h_{(h)(m)} = n\beta_m. \quad (3.9)$$

Substituting the above equation into the left hand side of (3.7), we get

$$2\beta H^h_{hsj} = n(\lambda_s \beta_j - \lambda_j \beta_s). \quad (3.10)$$

Equating the two equations, (2.22) and (3.10), we obtain

$$\begin{aligned} n(\lambda_s \beta_j - \lambda_j \beta_s) &= (\lambda_s + \phi_s) H^h_{hjm} v^m - (\lambda_j + \phi_j) H^h_{hsm} v^m \\ &= (\lambda_s + \phi_s) v^h_{(h)(j)} - (\lambda_j + \phi_j) v^h_{(h)(s)} \\ &= n(\lambda_s + \phi_s) \beta_j - n(\lambda_j + \phi_j) \beta_s \end{aligned} \quad (3.11)$$

or

$$\beta_j \phi_s - \beta_s \phi_j = 0, \quad (3.12)$$

where we have used the equations (2.1) and (3.9) in the process of calculation. Consequently, there exists a function  $\mu = \mu(x)$  such that

$$\phi_h = \mu \beta_h. \quad (3.13)$$

Making a cyclic interchange in the (3.4) with respect to the indices  $h, s$  and  $j$ , we get two more similar results. Adding the two equations thus obtained with (3.4), we have

$$\lambda_s (v^i_{(h)(j)} - v^i_{(j)(h)}) + \lambda_h (v^i_{(j)(s)} - v^i_{(s)(j)}) + \lambda_j (v^i_{(s)(h)} - v^i_{(h)(s)}) = 0, \quad (3.14)$$

where we have used the Bianchi identity (1.5) during the process of calculation.

In view of the equation (2.4), the above relation reduces to

$$\begin{aligned} \lambda_s (\beta \phi_h \delta^i_j + \beta_j \delta^i_h - \beta \phi_j \delta^i_h - \beta_h \delta^i_j) + \lambda_h (\beta \phi_j \delta^i_s + \beta_s \delta^i_j - \beta \phi_s \delta^i_j - \beta_j \delta^i_s) \\ + \lambda_j (\beta \phi_s \delta^i_h + \beta_h \delta^i_s - \beta \phi_h \delta^i_s - \beta_s \delta^i_h) = 0, \end{aligned} \quad (3.15)$$

where we have used  $\phi_{h(j)} = \phi_{j(h)}$ .

Contracting the above equation with respect to the indices  $i$  and  $h$ , we get

$$(n-2) \{ \lambda_j \beta_s - \lambda_s \beta_j + \beta (\lambda_j \phi_s - \lambda_s \phi_j) \} = 0. \quad (3.16)$$

Thus, for  $n \geq 3$ , the above formula reduces to

$$\beta (\lambda_j \phi_s - \lambda_s \phi_j) + \lambda_j \beta_s - \lambda_s \beta_j = 0. \quad (3.17)$$

Introducing (3.13) into the left hand side of the above equation, we have

$$(\beta\mu + 1) (\lambda_j \beta_s - \lambda_s \beta_j) = 0. \quad (3.18)$$

Therefore, we get here the following two cases :

$$\text{a) } \beta\mu = -1 \quad \text{and} \quad \text{b) } \lambda_j \beta_s - \lambda_s \beta_j = 0. \quad (3.19)$$

On substituting (3.19b) into the right hand side of the formula (3.10), we obtain

$$\beta H^h_{hsj} = 0. \quad (3.20)$$

So we have here  $\beta H^h_{hsj} v^j = 0$  for a non-zero vector  $v^j$ . But we have assumed  $H^h_{hsj} v^j \neq 0$ , therefore from this conclusion, we get  $\beta = 0$ , that is,  $\phi_h v^h = 0$  yields  $\beta = 0$ .

**4. Main Discourse.** For the case of  $\beta = 0$ , the equation of motion (2.3) takes the form :

$$\bar{x}^i = x^i + v^i(x) dt, \quad v^i_{(t)} = \phi_j(x) v^j, \quad (4.1)$$

but such a case was investigated by the author in [6].

Hence, we have to discuss, from now, remained case where (3.19a) holds good. In such a case, the motion to be studied becomes

$$\bar{x}^i = x^i + v^i(x) dt, \quad v^i_{(t)} = -\frac{1}{\beta} \beta_j v^j + \beta \delta^i_j. \quad (4.2)$$

Here, now let us introduce a contravariant vector  $\eta^i$  such that

$$\eta^i = \beta v^i. \quad (4.3)$$

Thus, we can now consider another infinitesimal point transformation

$$\bar{x}^i = x^i + \eta^i(x) dt. \quad (4.4)$$

Then,  $\eta^i$  becomes to define a special concircular field, for, we have

$$\eta^i_{(t)} = \beta_j v^j + \beta v^i_{(t)}. \quad (4.5)$$



Introducing the latter part of (4.2) into the above equation, we obtain

$$\eta^i_{(j)} = \beta_j v^i + \beta \left( -\frac{1}{\beta} \beta_j v^i + \beta \delta^i_j \right) = \beta^2 \delta^i_j. \quad (4.6)$$

Thus, the system (4.2) may be reduced to a special concircular form :

$$\bar{x}^i = x^i + \eta^i_j(x) dt, \quad \eta^i_{(j)} = \beta^2 \delta^i_j, \quad \beta \neq 0. \quad (4.7)$$

This case has been deeply studied by the author in [5].

In concluding this paper, we shall speak of an exceptional case, where

$$H^h_{hsm} v^m = 0. \quad (4.8)$$

If it will be the case, we can get from the equation (3.8), the following relation :

$$v^h_{(h)(s)} = (\phi_h v^h)_{(s)} + n\beta_s = 0. \quad (4.9)$$

In view of the lemma (2.2), the above equation reduces to

$$\beta_s = 0 \quad \text{or} \quad \beta = \text{Const.} \quad (4.10)$$

By virtue of the above formula, the equation (2.27) takes the form :

$$v^h H^i_{hji} = (n-1) \beta \phi_j. \quad (4.11)$$

Differentiating (4.11) covariantly with respect to  $x^m$  and noting the equations (1.11) and (2.3), we have

$$v^h H^i_{hji} (\lambda_m + \phi_m) + \beta H^h_{mjh} = (n-1) \beta \phi_{j(m)}. \quad (4.12)$$

Introducing the left hand side of (4.11) into (4.12), we get

$$(n-1) \beta \phi_j (\lambda_m + \phi_m) + \beta H^h_{mjh} = (n-1) \beta \phi_{j(m)}. \quad (4.13)$$

In view of the equation (1.7) transvecting the above relation by  $v^j$  and summing over the index  $j$ , we obtain

$$(n-1) \beta \phi_j v^j (\lambda_m + \phi_m) - \beta v^h_{(m)(h)} = (n-1) \beta \phi_{j(m)} v^j. \quad (4.14)$$

For a non-vanishing  $\beta$ , the above equation yields

$$(n-1) \phi_j v^j (\lambda_m + \phi_m) - v^h_{(m)(h)} = (n-1) \phi_{j(m)} v^j. \quad (4.15)$$

By virtue of the equations (2.13), (2.16) and (4.10), the above equation reduces to

$$\lambda_m \phi_j v^j = \phi_{j(m)} v^j - \beta \phi_m - \frac{1}{(n-1)} \beta_m - \beta_m \beta_j v^j = -2(\phi_j v^j + \beta) \phi_m. \quad (4.16)$$

According to the lemma (2.2) and the equation (4.10),  $\gamma = \phi_j v^j + \beta$  and  $\mu = \phi_j v^j$  means a constant respectively. And the equation (4.16) can be written like

$$\mu \lambda_m = -2\gamma \phi_m. \quad (4.17)$$

The case of  $\mu = 0$  gives  $\beta = 0$ , so the point transformation becomes one of the special recurrent form :

$$\bar{x}^i = x^i + v^i(x) dt, \quad v^i_{(t)} = \phi_j v^j (\phi_j : \text{gradient vector}). \quad (4.18)$$

Next, we consider that  $\mu \neq 0$ . For this case,  $\lambda_s$  becomes a gradient vector and  $\epsilon v H^i_{hjk} = 0$  gives

$$\epsilon^2 (\lambda_s v^s + 2\beta) H_{hj} - 2\beta (n-1) \lambda_h \lambda_j = 0, \quad (4.19)$$

where

$$\epsilon \stackrel{\text{def}}{=} -2\lambda/\mu. \quad (4.20)$$

But  $\lambda_s v^s + 2\beta = 0$  or  $\epsilon = 0$  implies  $\lambda_h = 0$ . In non-zero case, we can write

$$H_{hj} = d\lambda_h \lambda_j \quad (d = \text{non-zero const.}). \quad (4.21)$$

By virtue of the definition (1.11) differentiating covariantly with respect to  $x^m$ , we obtain

$$\lambda_m H_{hj} = d(\lambda_{h(m)} \lambda_j + \lambda_h \lambda_{j(m)}). \quad (4.22)$$

Again differentiating the above equation covariantly with respect to  $x^s$  and using the relation (1.11), we get

$$\begin{aligned} \lambda_m \lambda_s H_{hj} + \lambda_{m(s)} H_{hj} &= d(\lambda_{h(m)(s)} \lambda_j + \lambda_{h(m)} \lambda_{j(s)} + \\ &+ \lambda_{h(s)} \lambda_{j(m)} + \lambda_h \lambda_{j(m)(s)}). \end{aligned} \quad (4.23)$$

By virtue of the commutation formula (1.3) commutating the above equation with respect to the indices  $m$  and  $s$ , we have

$$\lambda_j \lambda_\gamma H^Y_{hms} + \lambda_h \lambda_\gamma H^Y_{jms} = 0. \quad (4.24)$$

By virtue of the equations (2.1), (4.24) and the fact that  $\epsilon \phi_j = \lambda_j$ , we can conclude

$$\lambda_h v^h \lambda_\gamma H^Y_{jms} = 0. \quad (4.25)$$

Hence, we get  $\lambda_h v^h = 0$  or  $\lambda_\gamma H^Y_{jms} = 0$ . If  $\lambda_h v^h = 0$ , holds, by virtue of (4.17),  $\lambda_h = 0$  and if  $\lambda_\gamma H^Y_{jms} = 0$  holds,  $\lambda_s$  means a parallel vector field. Therefore, in view of the equations (4.21) and (4.22), we can see

$$\lambda_s = 0. \quad (4.26)$$

Thus, we have:

**Theorem (4.1).** If a non-symmetric  $PRF_n$ -space (that is,  $\lambda_j \neq 0$ ) admits a projective affine motion of concircular form

$$\begin{aligned} \bar{x}^i &= x^i + v^i(x) dt, \quad v^i_{(j)} = \phi_j(x) v^i + \beta \delta^i_j \\ \phi &= \text{gradient vector, } \beta = \text{scalar function} \end{aligned}$$

then  $\beta(x)$  must be zero function. Consequently the motion should be a recurrent form.

**Theorem (4.2).** If an  $n$ -dimensional  $PRF_n$ -space admits a non-recurrent concircular projective affine motion (2.3) with  $\phi_j v^j$  non-zero constant, the space must be a projective symmetric space.

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DEPARTMENT OF APPLIED SCIENCES  
 M.M.M. ENGINEERING COLLEGE  
 GORAKHPUR - 273010, U.P.  
 INDIA

#### Ö Z E T

Bu çalışmada

$$\bar{x}^i = x^i + v^i(x) dt, \quad v^i_{(j)} = \beta \delta^i_j + \phi_j(x) v^i$$

formunda bir infinitesimal afin hareketin varlığı incelenmektedir. Burada  $\beta(x)$  herhangi bir fonksiyonu,  $\phi_j(x)$  te

$$\phi_j(x) = \phi_{(j)} = \partial_j \phi$$

ile tanımlanan bir gradiyent vektörü göstermektedir.