

## ON THE BOUNDEDNESS AND THE STABILITY RESULTS FOR THE SOLUTIONS OF CERTAIN FIFTH ORDER DIFFERENTIAL EQUATIONS

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**Summary :** The paper investigates the equation (1.1) in the two cases : (i)  $p \equiv 0$ , (ii)  $p (\neq 0)$  satisfies  $|p(t, x, y, z, w, u)| \leq (1 + |y| + |z| + |w| + |u|) q(t)$ , where  $q(t)$  is a nonnegative function of  $t$ . For the case (i) the asymptotic stability in the large of the trivial solution  $x = 0$  is investigated and for the case (ii) a boundedness result is obtained for solutions of (1.1). The results obtained here extend several well-known results.

### 5. MERTEBEDEN BELİRLİ DİFERANSİYEL DENKLEMLERİN ÇÖZÜMLERİ İÇİN SINIRLILIK VE STABİLİTE SONUÇLARI HAKKINDA

**Özet :** Bu çalışmada (1.1) denklemini şu iki halde incelenmektedir: (i)  $p \equiv 0$  dir, (ii)  $p (\neq 0)$ ,  $|p(t, x, y, z, w, u)| \leq (1 + |y| + |z| + |w| + |u|) q(t)$  bağıntısını gerçekler ki, burada  $q(t)$ ,  $t$  nin negatif olmayan bir fonksiyonudur. (i) hali için  $x=0$  trivial çözümünün asimtotik stabilitesi incelenmektedir, (ii) halinde de (1.1) in çözümleri için bir sınırlılık sonucu elde edilmektedir ve burada elde edilen sonuçlar, bilinen bazı sonuçlara genişletilmektedir.

#### 1. Introduction and statement of the results

We shall consider the non-linear fifth order differential equation

$$x^{(5)} + \varphi(x, \dot{x}, \ddot{x}, \ddot{\ddot{x}}, x^{(4)}) x^{(4)} + \psi(\ddot{x}, \ddot{\ddot{x}}) + h(\ddot{x}) + g(\dot{x}) + f(x) = p(t, \dot{x}, \ddot{x}, \ddot{\ddot{x}}, x^{(4)}) \quad (1.1)$$

in which the functions  $\varphi$ ,  $\psi$ ,  $h$ ,  $g$ ,  $f$  and  $p$ , which depend only on the arguments shown explicitly, are such that  $\varphi(x, y, z, w, u)$ ,  $\psi(z, w)$ ,  $\frac{\partial}{\partial z} \psi(z, w)$ ,  $g'(y)$ ,  $f'(x)$  and  $p(x, y, z, w, u)$  are continuous for all values of  $t, x, y, z, w$  and  $u$ .

The boundedness and stability properties of solutions of non-linear fourth order differential equations have been the subject of intensive investigation. Many of these results are summarized in [4]. Similar investigations have been carried out on various special cases of (1.1) by a number of authors.

**Key words :** Nonlinear differential equations of the fifth order, stability, boundedness,  $V$ -function.

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Chukwu [2] dealt with the equation of the form

$$x^{(5)} + ax^{(4)} + f_2(x) + cx + f_4(x) + f_5(x) = 0 \quad (1.2)$$

and presented sufficient conditions for asymptotic stability in the large of the zero solution for that equation.

A similar result was also obtained for the equation

$$x^{(5)} + f_1(x) x^{(4)} + f_2(x) + f_3(x) + f_4(x) + f_5(x) = 0 \quad (1.3)$$

by Abou-El-Ela and Sadek [1].

Furthermore, recently, in [5], Yuanhong studied fifth order non-linear differential equations of the form

$$x^{(5)} + \varphi(x, \dot{x}, \ddot{x}, \dddot{x}, x^{(4)}) x^{(4)} + b\ddot{x} + h(\dot{x}) + g(x) + f(x) = p(t). \quad (1.4)$$

He obtained some results concerning asymptotic stability in the large of the zero solution of (1.4) with  $p(t) \equiv 0$  and the boundedness of solutions of (1.4) with  $p(t) \neq 0$ .

The assumptions which will be established here are generalizations of the Routh-Hurwitz conditions

$$\begin{aligned} a > 0, \quad ab - c > 0, \quad (ab - c)c - (ad - e)a > 0, \\ \Lambda = (cd - be)(ab - c) - (ad - e)^2 > 0, \quad e > 0, \end{aligned} \quad (1.5)$$

which are necessary and sufficient for the asymptotic stability in the large of the trivial solution of the linear differential equation

$$x^{(5)} + ax^{(4)} + b\ddot{x} + cx + dx + ex = 0 \quad (1.6)$$

with constant coefficients.

Equation (1.1) has an equivalent system

$$\begin{aligned} \dot{x} &= y, \quad \dot{y} = z, \quad \dot{z} = w, \quad \dot{w} = u, \\ \dot{u} &= -\varphi(x, y, z, w, u)u - \psi(z, w) - h(z) - g(y) - f(x) + p(t, x, y, z, w, u). \end{aligned} \quad (1.7)$$

We start with the case  $p \equiv 0$  in (1.1) and prove here that:

**Theorem 1.** In addition to the fundamental assumptions of  $\varphi$ ,  $\psi$ ,  $h$ ,  $g$  and  $f$ , we suppose that:

D) The constants  $a$ ,  $b$ ,  $c$ ,  $d$  and  $e$  satisfy (1.5) and following two inequalities:

$$\Delta_1 = \frac{(cd - be)(ab - c)}{ad - e} - (ag'(y) - e) > 2\epsilon b \text{ for all } y, \quad (1.8)$$

$$\Delta_2 = \frac{cd - be}{ad - e} - \frac{d'(ad - e)}{d(ab - e)} - \frac{\epsilon}{a} > 0 \text{ for all } y, \tag{1.9}$$

where

$$d' = \begin{cases} \frac{g(y)}{y}, & y \neq 0, \\ g'(0), & y = 0. \end{cases} \tag{1.10}$$

II)  $f(0) = g(0) = h(0) = \psi(z, 0) = 0,$

$$\frac{f(x)}{x} \geq \alpha > 0 \text{ for all } x \neq 0, \text{ where } \alpha \text{ is a positive constant,}$$

$$\frac{g(y)}{y} \geq d \text{ for all } y \neq 0,$$

$$\frac{h(z)}{z} \geq c \text{ for all } z \neq 0,$$

$$\frac{\psi(z, w)}{w} \geq b \text{ for all } z \text{ and } w \neq 0,$$

$$\varphi(x, y, z, w, u) \geq a \text{ for all } x, y, z, w \text{ and } u.$$

III)  $f'(x) \leq e$  for all  $x,$

$$(f'(x) - e)^2 < \min \left[ \frac{\epsilon^2 d}{16}, \frac{\epsilon \Delta_1 d}{32a^2} \right] \text{ for all } x. \tag{1.11}$$

IV)  $g'(y) - \frac{g(y)}{y} \leq \beta$  for all  $y \neq 0,$  (1.12)

where  $\beta$  is a positive constant such that

$$\beta < \frac{e\Delta}{d^2(ab - c)}, \tag{1.13}$$

$$[g'(y) - d]^2 < \frac{\epsilon \Delta_1}{64} \text{ for all } y. \tag{1.14}$$

V)  $\left[ \frac{h(z)}{z} - c \right]^2 < \frac{\epsilon d \Delta_1}{16 \delta^2}$  for all  $z \neq 0,$  (1.15)

where  $\delta$  is a positive constant satisfying

$$\delta = \frac{e(ab - c)}{ad - e} + \epsilon, \tag{1.16}$$

$$\left[ \frac{h(z)}{z} - c \right]^2 \leq \frac{\Delta_1}{16} (\varphi - a) \text{ for all } x, y, w, u \text{ and } z \neq 0, \tag{1.17}$$

and

$$\varphi - a < \varepsilon_0 \equiv \min \left[ \frac{\varepsilon}{4a^2}, \frac{\varepsilon d}{4\delta^2}, \frac{\Delta_1(ad-e)^2}{16d^2(ab-c)^2} \right] \text{ for all } x, y, z, w \text{ and } u. \quad (1.18)$$

$$\text{VI) } \left[ \frac{\psi(z, w)}{w} - b \right]^2 < \min \left[ \frac{\varepsilon \Delta_1(ad-e)^2}{64d^2(ab-c)^2}, \frac{\varepsilon^2 d}{16\delta^2} \right] \text{ for all } z \text{ and } w \neq 0, \quad (1.19)$$

and

$$\psi_z(z, w) \leq 0 \text{ for all } z, w. \quad (1.20)$$

Then every solution  $(x(t), y(t), z(t), w(t), u(t))$  of system (1.7) satisfies

$$x^2(t) + y^2(t) + z^2(t) + w^2(t) + u^2(t) \rightarrow 0 \text{ as } t \rightarrow \infty, \quad (1.21)$$

provided that the positive constants  $\varepsilon$  and  $\varepsilon_0$  are sufficiently small.

For the case  $p(t, x, y, z, w, u) \neq 0$ , we shall prove

**Theorem 2.** Suppose that

(I) conditions (I)-(VI) of Theorem 1 hold,

(II) the function  $p(t, x, y, z, w, u)$  satisfies  $|p(t, x, y, z, w, u)| \leq (1 + |y| + |z| + |w| + |u|)q(t)$ , where  $q(t)$  is a nonnegative and continuous function of  $t$ , and satisfies  $\int_0^t q(s) ds \leq A < \infty$ , for all  $t \geq 0$ ,  $A$  is a positive constant. Then for

any given finite  $x_0, y_0, z_0, w_0, u_0$  there exists a constant  $D = D(x_0, y_0, z_0, w_0, u_0)$ , such that any solution  $(x(t), y(t), z(t), w(t), u(t))$  of system (1.7) determined by

$$x(0) = x_0, y(0) = y_0, z(0) = z_0, w(0) = w_0, u(0) = u_0,$$

satisfies for all  $t \geq 0$ ,

$$|x(t)| \leq D, |y(t)| \leq D, |z(t)| \leq D, |w(t)| \leq D, |u(t)| \leq D. \quad (1.22)$$

**Remark 1.** When  $\varphi(x, \dot{x}, \ddot{x}, \ddot{\ddot{x}}, x^{(4)}) = a$ ,  $\psi(\ddot{x}, \ddot{\ddot{x}}) = b\ddot{x}$ ,  $h(\ddot{x}) = c\ddot{x}$ ,  $g(\dot{x}) = d\dot{x}$  and  $f(x) = ex$  and  $p(t, x, \dot{x}, \ddot{x}, \ddot{\ddot{x}}, x^{(4)}) = 0$ , equation (1.1) reduces to the linear differential equation (1.6) with constant coefficients and conditions (I)-(VI) of Theorem 1 reduce to the corresponding conditions of Routh-Hurwitz criterion.

**Remark 2.** When  $\psi(\ddot{x}, \ddot{\ddot{x}}) = b\ddot{x}$ ,  $p(t, x, \dot{x}, \ddot{x}, \ddot{\ddot{x}}, x^{(4)}) = p(t)$ , then the conditions of Theorem 1 and Theorem 2 reduce to those of Yuanhong [5].

## 2. The function $V(x, y, z, w, u)$

The proofs of the theorems depend on a scalar differentiable function  $V(x, y, z, w, u)$ . This function and its time derivative satisfy fundamental inequalities. The function  $V = V(x, y, z, w, u)$  is defined by:

$$\begin{aligned}
2V = & u^2 + 2awu + \frac{2d(ab-c)}{ad-e} zu + 2 \int_0^w \psi(z, s) ds + \left[ a^2 - \frac{d(ab-c)}{ad-e} \right] w^2 + \\
& + 2 \left[ c + \frac{ad(ab-c)}{ad-e} - \delta \right] zw + 2\delta yu + 2a\delta yw + 2wf(x) + 2wg(y) + \\
& + 2a \int_0^z h(s) ds + \left[ \frac{bd(ab-c)}{ad-e} - d - a\delta \right] z^2 + 2b\delta yz + 2azg(y) - 2eyz + \\
& + 2azf(x) + (\delta c - ae) y^2 + \frac{2d(ab-c)}{ad-e} \int_0^y g(s) ds + \frac{2d(ab-c)}{ad-e} yf(x) + \\
& + 2 \int_0^x f(s) ds,
\end{aligned} \tag{2.1}$$

where  $\epsilon > 0$  and  $\delta > 0$  are constants satisfying (1.8), (1.9) and (1.16).

The properties of the function  $V$ , which are required for the proof of (1.21) and (1.22), are summarized in Lemma 1 and Lemma 2.

**Lemma 1.** Under the conditions of Theorem 1, there exist positive constants  $D_i = D_i(a, b, c, d, e, \alpha, \beta, \epsilon)$  ( $i = 1, 2, 3, 4, 5$ ) such that

$$V \geq D_1 x^2 + D_2 y^2 + D_3 z^2 + D_4 w^2 + D_5 u^2$$

for all  $x, y, z, w, u$ .

**Proof.**  $V(0, 0, 0, 0, 0) = 0$ , since  $f(0) = g(0) = h(0) = \psi(z, 0) = 0$ .

Also, since  $\psi(z, 0) = 0$  and  $\frac{\psi(z, w)}{w} \geq b$  ( $w \neq 0$ ) it is clear that  $\int_0^w \psi(z, s) ds \geq bw^2$ .

Therefore (2.1) takes the form

$$\begin{aligned}
2V \geq & \left[ u + aw + \frac{d(ab-c)}{ad-e} z + \delta y \right]^2 + \frac{d\Delta}{(ad-e)^2} \left[ z + \frac{e}{d} y \right]^2 + \Delta_2 [w + az]^2 + \\
& + \frac{d(ad-e)}{d'(ab-c)} \left[ \left( \frac{ab-c}{ad-e} \right) f(x) + \left( \frac{ab-c}{ad-e} \right) d'y + \left( \frac{ad'}{d} \right) z + \left( \frac{d'}{d} \right) w \right]^2 + \\
& + 2\delta \int_0^x f(s) ds - \frac{d(ab-c)}{d'(ad-e)} f^2(x) + \frac{d(ab-c)}{ad-e} \left[ 2 \int_0^y g(s) ds - yg(y) \right] +
\end{aligned}$$

$$\begin{aligned}
 &+ \left[ \delta c - ae - \frac{e^2 \Delta}{d(ad-e)^2} - \delta^2 \right] y^2 + a \left[ 2 \int_0^z h(s) ds - cz^2 \right] + \\
 &+ \left( \frac{\varepsilon}{a} \right) w^2 + 2\varepsilon \left[ \frac{cd-be}{ad-e} \right] yz, \tag{2.2}
 \end{aligned}$$

where  $\Delta$  and  $\Delta_2$  are defined by (1.5) and (1.9), respectively.

The terms on the right-hand side of the inequality (2.2) are the same as the terms on the right-hand side of the inequality (2.4) in [5, pp. 269, 270]. In fact, the estimation there for the terms on the right-hand side of (2.2) yields

$$V \geq D_1 x^2 + D_2 y^2 + D_3 z^2 + D_4 w^2 + D_5 u^2. \tag{2.3}$$

This completes the proof of Lemma 1.

**Lemma 2.** Let all the conditions of Theorem 1 be satisfied. Then there exist positive constants  $D_i \equiv D_i(b, d, \varepsilon)$  ( $i = 6, 7, 8$ ) such that every solution  $(x, y, z, w, u)$  of system (1.7) satisfies

$$\dot{V} \equiv \frac{d}{dt} V(x, y, z, w, u) \leq - (D_6 y^2 + D_7 z^2 + D_8 w^2). \tag{2.4}$$

**Proof.**  $\Delta$  straightforward calculation using the identity

$$\dot{V} = \frac{\partial V}{\partial x} x + \frac{\partial V}{\partial y} y + \frac{\partial V}{\partial z} z + \frac{\partial V}{\partial w} w + \frac{\partial V}{\partial u} u$$

yields

$$\begin{aligned}
 \dot{V} = & -(\varphi - a)u^2 - \left[ a \frac{\psi(z, w)}{w} - c + \delta - \frac{ad(ab-c)}{ad-e} \right] w^2 - \\
 & - \left[ \frac{d(ab-c)}{ad-e} \frac{h(z)}{z} - \{\delta b + (ag'(y) - e)\} \right] z^2 - \\
 & - \left[ \delta yg(y) - \frac{d(ab-c)}{ad-e} f'(x)y^2 \right] - a(\varphi - a)wu - \\
 & - \left[ \frac{h(z)}{z} - c \right] zu - \frac{d(ab-c)}{ad-e} (\varphi - a)zu - \delta(\varphi - a)yu + \\
 & + [g'(y) - d]zw + [f'(x) - e] yw - \delta \left[ \frac{h(z)}{z} - c \right] yz - \\
 & - a[e - f'(x)]yz - \frac{d(ab-c)}{ad-c} \psi(z, w)z - \\
 & - \delta y\psi(z, w) + \frac{bd(ab-c)}{ad-e} zw + b\delta yw + w \int_0^w \psi_\varepsilon(z, s) ds. \tag{2.5}
 \end{aligned}$$

It follows from  $\frac{\Psi(z,w)}{w} \geq b$  and (1.16) that

$$\left[ a \frac{\Psi(z,w)}{w} - c + \delta - \frac{ad(ab-c)}{ad-e} \right] w^2 \geq \left[ ab - c + \delta - \frac{ad(ab-c)}{ad-e} \right] w^2 = \varepsilon w^2. \quad (2.6)$$

By using  $\frac{h(z)}{z} \geq c$ , (1.8) and  $ab - c + \delta - \frac{ad(ab-c)}{ad-e} = \varepsilon$  we find

$$\begin{aligned} & \frac{d(ab-c)}{ad-e} \frac{h(z)}{z} - \{ \delta b + (ag'(y) - e) \} \geq \\ & \geq \frac{(cd-be)(ab-c)}{ad-e} - (ag'(y) - e) - \varepsilon b > \\ & > \frac{1}{2} \left[ \frac{(cd-be)(ab-c)}{ad-e} - (ag'(y) - e) \right]. \end{aligned} \quad (2.7)$$

From  $\frac{g(y)}{y} \geq d$  and  $f'(x) \leq e$ , we obtain

$$- \left[ \delta yg(y) - \frac{d(ab-c)}{ad-e} f'(x) y^2 \right] \leq -\varepsilon d y^2 - \frac{ab-c}{ad-e} [de - df'(x)] y^2 \leq -\varepsilon d y^2. \quad (2.8)$$

Because of (1.20), it follows that

$$w \int_0^w \psi_z(z, s) ds \leq 0. \quad (2.9)$$

Combining inequalities (2.6)-(2.9) in (2.5) we get

$$\dot{V} \leq -\frac{\varepsilon d}{8} y^2 - \frac{\Delta_1}{8} z^2 - \frac{\varepsilon}{4} w^2 - \sum_{i=7}^{14} V_i, \quad (2.10)$$

where

$$\begin{aligned} V_7 &= \left( \frac{1}{4} \right) (\varphi - a) u^2 + \left[ \frac{h(z)}{z} - c \right] zu + \left( \frac{\Delta_1}{16} \right) z^2, \\ V_8 &= \left( \frac{1}{4} \right) (\varphi - a) u^2 + \frac{d(ab-c)}{ad-e} (\varphi - a) zu + \left( \frac{\Delta_1}{16} \right) z^2, \\ V_9 &= \left( \frac{1}{4} \right) (\varphi - a) u^2 + a (\varphi - a) wu + \left( \frac{\varepsilon}{4} \right) w^2, \\ V_{10} &= \left( \frac{1}{4} \right) (\varphi - a) u^2 + \delta (\varphi - a) yu + \left( \frac{\varepsilon d}{4} \right) y^2, \end{aligned}$$

$$V_{11} = \left(\frac{\varepsilon}{4}\right)w^2 - [g'(y) - d]zw + \frac{d(ab-c)}{ad-e} \left[ \frac{\psi(z,w)}{w} - b \right] zw + \left(\frac{\Delta_1}{16}\right)z^2,$$

$$V_{12} = \left(\frac{\varepsilon}{4}\right)w^2 + [e - f'(x)]yw + \delta \left[ \frac{\psi(z,w)}{w} - b \right] yw + \left(\frac{\varepsilon d}{4}\right)y^2,$$

$$V_{13} = \left(\frac{\Delta_1}{16}\right)z^2 + \delta \left[ \frac{h(z)}{z} - c \right] yz + \left(\frac{\varepsilon d}{4}\right)y^2,$$

$$V_{14} = \left(\frac{\Delta_1}{16}\right)z^2 + a[e - f'(x)]yz + \left(\frac{\varepsilon d}{8}\right)y^2.$$

The functions  $V_7, V_8, V_9, V_{10}, V_{13}$  and  $V_{14}$  are the components of  $\dot{V}$  in the proof of [5, Lemma 2]. For precisely the same reasons as in [5]

$$V_7 \geq 0, V_8 \geq 0, V_9 \geq 0, V_{10} \geq 0, V_{13} \geq 0 \text{ and } V_{14} \geq 0.$$

Now consider the expressions

$$V_{11} = \left(\frac{\varepsilon}{4}\right)w^2 - [g'(y) - d]zw + \frac{d(ab-c)}{ad-e} \left[ \frac{\psi(z,w)}{w} - b \right] zw + \left(\frac{\Delta_1}{16}\right)z^2$$

and

$$V_{12} = \left(\frac{\varepsilon}{4}\right)w^2 + [e - f'(x)]yw + \delta \left[ \frac{\psi(z,w)}{w} - b \right] yw + \left(\frac{\varepsilon d}{4}\right)y^2.$$

By similar estimation using (1.11), (1.14) and (1.19) we obtain  $V_{11} \geq 0$  and  $V_{12} \geq 0$ . Summing up the above discussion we obtain

$$\dot{V} \leq - \left( \frac{\varepsilon d}{8} y^2 + \frac{\Delta_1}{8} z^2 + \frac{\varepsilon}{4} w^2 \right). \quad (2.11)$$

By (1.8), inequality (2.11) implies that

$$\dot{V} \leq - \left( \frac{\varepsilon d}{8} y^2 + \frac{\varepsilon b}{4} z^2 + \frac{\varepsilon}{4} w^2 \right), \quad (2.12)$$

which verifies (2.4).

**Proof of Theorem 1.** See [5].

**Proof of Theorem 2.** Consider the function  $V$  defined by (2.1). Then, since  $p \neq 0$ , under the conditions of Theorem 2, the conclusion of Lemma 2 can be revised as follows:

$$\begin{aligned} \dot{V}(x, y, z, w, u) &\leq -D_6 y^2 - D_7 z^2 - D_8 w^2 + \\ &+ \left[ u + aw + \frac{d(ab-c)}{ad-e} z + \delta y \right] p(t, x, y, z, w, u). \end{aligned} \quad (2.13)$$



Let

$$D_9 = \max \left( 1, a, \frac{d(ab - c)}{ad - e}, \delta \right).$$

We have

$$\dot{V} \leq D_9 [|y| + |z| + |w| + |u|] [1 + |y| + |z| + |w| + |u|] q(t).$$

Using the inequalities

$$|y| \leq 1 + y^2, |z| \leq 1 + z^2, |w| \leq 1 + w^2, |u| \leq 1 + u^2, 2|yz| \leq y^2 + z^2, 2|yw| \leq y^2 + w^2, \\ 2|yu| \leq y^2 + u^2, 2|zw| \leq z^2 + w^2, 2|zu| \leq z^2 + u^2, 2|wu| \leq w^2 + u^2$$

we get

$$\dot{V} \leq D_9 [4 + 5(y^2 + z^2 + w^2 + u^2)] q(t). \quad (2.14)$$

From the estimation given by (2.3) it is clear that

$$V \geq D_0 (y^2 + z^2 + w^2 + u^2), \quad (2.15)$$

where  $D_0 = \min (D_2, D_3, D_4, D_5)$ .

Thus it follows from (2.14) and (2.15) that

$$\dot{V} \leq D_{10} q(t) + D_{11} V q(t), \quad (2.16)$$

where  $D_{10} = 4D_9, D_{11} = \frac{5D_9}{D_0}$ .

Now, integrating (2.16) from 0 to  $t$ , we find

$$V(t) - V(0) \leq D_{10} \int_0^t q(s) ds + D_{11} \int_0^t V(s) q(s) ds.$$

Using condition (ii) of Theorem 2, we have

$$V(t) \leq D_{12} + D_{11} \int_0^t V(s) q(s) ds,$$

where  $D_{12} = V(0) + D_{10} A$ . Hence Gronwall-Bellman inequality yields

$$V(t) \leq D_{12} \exp \left( D_{11} \int_0^t q(s) ds \right).$$

This completes the proof of Theorem 2.

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