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# Comparison of Two Different Circular Diaphragm Models with Central Mass for MEMS Based FPI Pressure Sensor Performance Based on Sensitivity and Frequency Response

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#### Abstract

The sensitivity and the fundamental frequency of circular membrane with a central mass (embossment) were analytically evaluated for Fabry- Pérot interferometers (FPI) based pressure sensor. Two different previously developed model (named as M1 and M2, respectively in this study), which includes a diaphragm with center embossment, were considered to obtain results and performance of models were compared. Thickness of diaphragms were 5 µm and 10 µm with the radius of 300 µm, 500 µm, 600 µm and 700 µm, respectively. According to the results, it was noted that diaphragm considering M1 model shows higher sensitivity and displacement compared to diaphragm considering M2 model. 155.15-102.87 nm/kPa and 149.5-39.7 nm/kPa sensitivity range were calculated for the diaphragm based on the M1 and M2 model, respectively when 300 µm in radius and 5 µm thick diaphragm was used. Moreover, frequency response of diaphragm considering two different model is slightly different for thinner embossment; however, same frequency response was calculated for thicker embossment. For example, frequency range of 700 µm in radius and 10 µm was changes between 42-22.7 kHz and 42.2-22.7 kHz when M1 and M2 model was considered. It was understand that compared with the conventional circular diaphragm (CD) model, non-uniform diaphragm with a central mass provides more geometrical parameters to tune the device performance (sensitivity) and it provides design flexibility on the sensor structure.

Keywords: central embossment, FPI pressure sensor, MEMS, sensitivity analyze

#### **1. INTRODUCTION**

Pressure is a fundamental parameter and significance for different applications [1-4]. It has studied intensively for years [5]. Pressure sensors based on piezo resistive/piezoelectric effects have

dominantly used in this field. However, electromagnetic interference still is an issue such type of devices [6,7]. Fiber optic pressure sensors are the alternative to the conventional piezo resistive/piezoelectric based sensors [8]. Some of them are Mach-Zehnder interferometers and Fabry-Pérot interferometers (FPI) [9-14]. FPI-

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based sensors have various superiorities among the other fiber optic sensors [14-17]. Reflecting parallel mirrors separated by a gap (cavity) are the main component of the FPI-based pressure sensor [3]. Extrinsic cavity with a diaphragm is commonly used for variety applications [5], [18,19]. An extrinsic Fabry-Pérot interferometer is placed between a fiber end face and a reflective membrane [20]. Thus, the choice of diaphragm material and geometry is a key factor for pressure sensor design [21]. Some of the studies related to MEMS based FPI pressure sensors are summarized below.

Rectangular, square or circular shape flat diaphragm have extensively used in the MEMS based pressure sensor technology. In one study, the design guidelines of pressure sensors with a square shape diaphragm have presented by considering the relationships between diaphragm thickness, side length, sensitivity and resonant frequency [22]. Another study of different research group used a piezoresistive pressure sensor with polysilicon piezoresistors and a square shape diaphragm for high temperature applications in the desired operation range (0-30)Bar). Fabricated sensor results show good sensitivity and linearity [23]. In the different work, a micro piezoresistive pressure sensor was designed, fabricated using wet etching technology and tested for Tire Pressure Measurement System (TPMS) [24]. Another previous study designed, fabricated, and tested the micro pressure sensor with a square diagram made of silicon and bossed diaphragm. 11.098 µV/V/Pa sensitivity was measured in the operating range of 500 Pa and it was confirmed that the sensor enables to measure the absolute micro pressure lower than 500 Pa [25]. More studies are available and can be found in literature [26].

Square diaphragm as a pressure sensor commonly used due to better sensitivity than rectangular diaphragm or circular diaphragm under same conditions [23]. However, advantages of compatibility with standard fiber components make circular geometries more use in literature for numerical and analytical modeling [27-30]. Moreover, the sensitivity and the frequency response of the circular diaphragm are tuned by less geometric parameters compared to square or rectangular shape geometry [22-28]. However, one of the disadvantage of flat diaphragms is pressure induced large deflections and thus, undesired volatility effects to the output of the sensor [21]. Hence, many innovative sensor designs have been widely explored in the past decades with the aim of fabrication of high performance pressure sensors. Placing a center mass on diaphragm is an effective method to improve sensor characteristics by increase the stiffness of the diaphragm and reduce the nonlinear effects [21].

In this paper, two different model of centerembossed circular diaphragm, which were previously developed and available in literature [26,33], were used to determine performance and behaviors of the circular diaphragm with a center embossment (mass). These two models explained in the following section of study. The sensitivity and frequency response as a function of embossment thickness and radius at a given pressure were obtained. Then performance of pressure sensors based on embossed diaphragm results were compared and discussed considering the two different circular diaphragm models with a central mass.

#### 2. SENSOR DESIGN

In general, a fiber optic EFPI (Extrinsic Fabry-Pérot Interferometer) system composed of a sensor probe, a fiber optic coupler, a light source, and a detector [31,32] as illustrated in Figure 1. Membrane is the main part of the sensing probe, which sense the acoustic signal. In this system, the light emitted by the source passing through the fiber optic coupler is reflected from two different surface: fiber optic coupler and diaphragm. Detection of incoming pressure waves is measured by comparison of light intensity of reflected light from first and second surface (membrane). The membrane structure is deformed under pressure and, thus, change the cavity length, which results in the phase differences between collected light from the consecutive surfaces [28,31]. Therefore, the membrane deflection due to the acoustic pressure determines the performance of FPI system in

terms of the sensitivity and linear range. Frequency response also an important parameter to evaluate sensor characteristic. Two of FPI sensor designs, (a) conventional circular diaphragm and (b) center embossment diaphragm, are illustrated in Figure 2.



Figure 1 Schematic of a FPI pressure sensor components



Figure 2 Schematic of FPI pressure sensor. (a) Crosssectional and (b) top view of conventional circular diaphragm sensor. (c) Cross-sectional and (d) top view of embossed diaphragm

Analysis of FPI pressure sensor, thus, can be initiated by considering its diaphragm geometry. Different kind of diaphragms have been designed in literature [22,23], [27-29]. One approaches is the use of non-uniform membrane by adding a mass on the geometrical center of vibrating membrane [26,33,34]. Under the small deflection approximation, the equation governing deflection, w(r), of a thin flexible circular plate with radius, R, under a uniform loading, P, is given as [35-37]

$$\nabla^2 w \nabla^2 D = \mathbf{P} \tag{1}$$

$$D = \frac{Eh^3}{12(1-v^2)}$$
(2)

Here, P is the applied pressure, D is the flexural rigidity of the plate, E is the Young's modulus, h is the diaphragm thickness, and v is the Poisson's ratio. The differential operator ( $\nabla$ ) in cylindrical coordinates is given by Eq.3. When substitution Eq.3 into Eq.1 and considering D is constant through the plate, Eq.4 is obtained.

$$\nabla^{2} = \frac{\partial}{\partial r^{2}} + \frac{1}{r^{2}} \frac{\partial^{2}}{\partial \phi^{2}} + \frac{1}{r} \frac{\partial}{\partial r}$$
(3)

$$\nabla^2 w = P/D$$

The vertical deflection w(r) is obtained as

$$w(r) = \frac{Pr^{4}}{64D} \left\{ 1 - \left(\frac{r}{R}\right)^{2} \right\}^{2}$$
(4)  
$$w(r = 0) = w_{max} = \frac{Pr^{4}}{64D}$$

Eq.4 describes the deflection of clamped circular diaphragm (CD) (Figure 2 (a-b)). Deflection profile of non-uniform membrane as illustrated in Figure 2 (c-d), can be re-established using above equation of clamped thin circular membrane [33]. In this study, two different model of central embossment membrane were considered for calculation of frequency response and sensitivity.

In the first model named as M1 in this study, deflection of center embossment membrane  $(Y_0)$  is analytically expressed as in Eq.5 as described previously in [26]:

$$Y_0 = \frac{A_p a^4 P}{EH^3} \tag{5}$$

$$A_p = \frac{3(1-v^2)}{16} \left(1 - \frac{b^4}{a^4} - 4\frac{b^2}{a^2}\log\frac{a}{b}\right)$$
(6)

where H is the thickness of membrane, b is the radius of embossment and a is the radius of membrane.

To obtain simplified analytical model of the center-embossed diaphragm, it is divided into two parts [33], which is named as as M2 in this study. First part is referring to a thin round plates expect that there is a circular hole in the center. Second part defines the circular plates with a sum of thickness of a central mass and diaphragms. More details can be found about analytical model of center-embossed membrane in [33]. Center deflection and structural sensitivity of embossed membrane under constant pressure is expressed as Eq.7-8 [33];

$$W_{0}$$
(7)  
=  $\left(\frac{[D_{0}r_{1}^{4} + D_{1}(r_{0}^{4} - r_{1}^{4})]}{64D_{0}D_{1}} + \frac{(D_{1} - D_{0})(r_{0}^{2} - r_{1}^{2})r_{0}^{2}r_{1}^{2}\ln\frac{r_{1}}{r_{0}}}{16D_{0}\left[D_{1}(r_{0}^{2} - r_{1}^{2}) + D_{0}(\frac{1 - \nu}{1 + \nu}r_{0}^{2} + r_{1}^{2})\right]}\right)P$ 

$$S = \frac{w_0}{P}$$
  
=  $\frac{[D_0 r_1^4 + D_1 (r_0^4 - r_1^4)]}{64D_0 D_1}$   
+  $\frac{(D_1 - D_0)(r_0^2 - r_1^2)r_0^2 r_1^2 \ln \frac{r_1}{r_0}}{16D_0 \left[D_1 (r_0^2 - r_1^2) + D_0 (\frac{1 - v}{1 + v}r_0^2 + r_1^2)\right]}$ 

(8)

where D0 and D1 denote the flexural rigidities of first and second part, respectively, which can be expressed as below and H is the thickness of central mass, r0 is the radius of the membrane and r1 is the radius of embossment.

$$D_{0} = \frac{Eh^{3}}{12(1-v^{2})} and D_{1}$$

$$= \frac{E(h+H)^{3}}{12(1-v^{2})}$$
(9)

When the central embossment ignored, in other word H = 0 or  $r_0 = r_1$ , sensitivity equals to  $r_0/64D_0$ same as the clamped round shape plate [33]. The resonance frequency of a circular and fixed diaphragm is expressed as Eq.10 [38];

$$f = \frac{1}{2\pi} \sqrt{\frac{k_m}{m_m + m_a}} \tag{10}$$

here,  $k_m$  is elastic coefficient of the membrane,  $m_m$  is mass of the membrane,  $m_a$  any additional mass on the surface of the membrane. The elastic coefficient,  $k_m$ , of the membrane depends on its shape and can be calculated using Hooke's law, having a circular shaped membrane with a radius of  $a_m$ 

$$k_m = \frac{188D}{a_m^2} \tag{11}$$

where D is the flexural rigidity of membrane. In this study, FPI diaphragm with a central mass was analytically evaluated using the previously developed two different models and these models are available in literature [26,33]. Sensitivity and frequency response were calculated and results of diaphragm with a central mass considering two different models were compared.

#### **3. RESULTS AND DISCUSSION**

Two different model of center-embossed membranes were used to obtain analytical results in terms of sensitivity and frequency response. Displacement profile of first model (M1) is not include effect of embossment thickness [26]. On the other hand, thickness of embossment is considered for analytical results for second model(M2) [33]. Performance of these two model was evaluated in terms of sensitivity and frequency response of center embossed diaphragm. Moreover, results were also compared with the conventional circular design (CD).

# 3.1. Frequency Response

Different geometrical values were selected for frequency response analysis; membrane radius ( $r_0$ ), embossment radius ( $r_{em}$ ) and thickness of embossment ( $t_{em}$ ). Calculations were performed for the 5 µm and 10 µm thick membranes, respectively. SiO<sub>2</sub> was selected as diaphragm and embossment material (E=73 GPa, v=0.17 and p=2200 kg/m<sup>3</sup> [39]). The fundamental frequency

of diaphragm considering the M1 model and M2 model was calculated using Eq.10 and the results were presented in Table 1. Figure 3 shows the fundamental frequency of diaphragm considering M1 and M2 model as a function of thickness of central embossment (tem) and radius (rem) when the thickness of diaphragm is 5 µm. Maximum thickness of embossment was selected up to 10 thickness. times of membrane Similarly, embossment radius (ri in Fig.3) was selected as 10%, 30% and 50% of membrane radius. It has been observed that as the embossment thickness increases fundamental frequency of structures as expected based on the Eq.10. Comparatively, the embossment radius has an obviously impact on the fundamental frequency.

Table 1

Frequency (kHz) response of diaphragm considering CD, M1 and M2 model for different membrane thicknesses

r₀(μm)	$t_m(\mu m)=5$			$t_{\rm m}  (\mu m) = 10$		
	CD	M1	M2	CD	M1	M2
		t <sub>em</sub> =5-50 (μm)	t <sub>em</sub> =5-50 (μm)		tem=10-100 (μm)	t <sub>em</sub> =10-100 (μm)
		$r_{em=} r_0 / 2 (max.)$	$r_{em=} r_0 / 2 (max.)$		$r_{em=} r_0 / 2 (max.)$	$r_{em=} r_0 / 2$ (max.)
300	152.34	114.3-61.7	114.8-61.7	304.67	228.6-123.4	229.5-123.4
500	54.84	41.1-22.2	41.3-22.2	109.68	82.3-44.4	82.6-44.4
600	38.08	28.6-15.4	28.7-15.4	76.17	57.1-30.8	57.4-30.8
700	27.98	21-11.3	21.1-11.3	55.96	42-22.7	42.2-22.7



Figure 3 Comparison of frequency response for the diaphragm using M1 and M2 model, respectively. (a)  $t_m=5 \ \mu m$  and  $r_0=300 \ \mu m$ , (b)  $t_m=5 \ \mu m$  and  $r_0=500 \ \mu m$ , (c)  $t_m=5 \ \mu m$  and  $r_0=600 \ \mu m$  and (d)  $t_m=5 \ \mu m$  and  $r_0=700 \ \mu m$ 

Fundamental frequency results of diaphragm with a central mass was very close when both the M1

and M2 model were considered. It was seen form the Figure 3 that the diaphragm with same

embossment thickness and radius have almost same frequency response when M1 and M2 models were considered separately. For example, fundamental frequency of diaphragm based on M1 and M2 models are 105.9 kHz and 109.9 kHz, respectively with a 5 µm thick embossment and radius of 90  $\mu$ m (30% xr<sub>0</sub>). However, when thicker embossment selected, this differences is vanished as shown in Fig.3. From the Table 1 and Fig.3, the fundamental frequency of CD is constant and higher than M1 model and M2 model. This is the results of increased membrane mass due to embossment as in Eq.10. It can be concluded that pressure sensor diaphragm with a central embossment is suitable for low frequency and wide frequency bandwidth applications compared to CD structure.

#### 3.2. Sensitivity

As mentioned in the design section, the sensitivity, S, of pressure sensor is defined as ratio of center displacement to pressure. To obtain the sensitivity values of diaphragm, first membrane deformation was calculated under acoustic pressure ranging from 1 Pa to 10 kPa [20]. Then, the sensitivities for different cases depending on the embossment thickness and radius were obtained for the CD, M1 and M2 model. The results are listed in Table 2. Figure 4 shows the sensitivity of diaphragm with a thickness of 10  $\mu$ m. From these results, diaphragm considering M1 model has higher sensitivity than its M2 model based diaphragm counterparts.

Table 2

Sensitivity (nm/kPa) performance of CD, M1 and M2 models for different membrane thicknesses

$r_0(\mu m)$	$t_m(\mu m)=5$			$t_{m}(\mu m)=10$		
	CD	M1	M2	CD	M1	M2
		t <sub>em</sub> =5-50 (μm)	t <sub>em</sub> =5-50 (μm)		t <sub>em</sub> =10-100 (μm)	t <sub>em</sub> =10-100 (μm)
		$r_{em=} r_0 / 2$ (max.)	$r_{em=} r_0 / 2$ (max.)		$r_{em=} r_0 / 2$ (max.)	$r_{em=} r_0 / 2$ (max.)
300	161.63	155.15-102.87	149.5-39.7	20.20	19.39-12.86	18.7-5
500	1247.13	1197.12-793.76	1153.4-306.2	155.89	149.64-99.22	144.2-38.3
600	2586.05	2482.35-1645.94	2391.7-634.9	323.26	310.29-205.74	299-79.4
700	4790.98	4598.86-3049.32	4431-1176.1.	598.87	574.86-381.16	553.9-147



Figure 4 Comparison of diaphragm sensitivity (nm/kPa) considering the M1 model and M2 model. (a)  $t_m=10 \ \mu m$  and  $r_0=300 \ \mu m$ , (b)  $t_m=10 \ \mu m$  and  $r_0=500 \ \mu m$ , (c)  $t_m=10 \ \mu m$  and  $r_0=600 \ \mu m$  and (d)  $t_m=10 \ \mu m$  and  $r_0=700 \ \mu m$ 

Moreover, sensitivity of diaphragm considering model changes only with radius of M1 embossment. This results can be explained when considering Eq.5-6. The narrower the width of embossment is, the larger the sensitivity. On the other hand, diaphragm sensitivity based on M2 model changes with both embossment thickness and radius. Analytical results of central displacement and sensitivity of diaphragm based on M2 model showed lower values compared to CD and M1 model based diaphragm. Sensitivity of M2 model based diaphragm is decreases, when the embossment thickness increases. Therefore, it was founded that sensitivity values of FPI diaphragm based on M1 and M2 models are not agrees well and there is discrepancy between these two models in terms of sensitivity. It is suggested that more experimental and numerical studies are required to find best model of embossment membrane and eliminate the differences between two models in terms of sensitivity.

# 4. CONCLUSION

The frequency response and sensitivity of MEMS based fiber optic pressure sensor diaphragm with central embossment were analytically а investigated and compared using two different models. These models were developed previously and available in literature [26,33]. As a result of these analyses, the following conclusions are reached. M1 model based diaphragm structure show better sensitivity than M2 model based diaphragm structure and however, this model ignores the effect of embossment thickness on performance. From sensor these results. differences between diaphragm sensitivities were calculated. For example, 149.64-99.22 nm/kPa and 144.2-38.3 nm/kPa sensitivity range were calculated for the diaphragm based on the M1 and M2 model, respectively when 500 µm in radius and 10 µm thick diaphragm was used for calculations. On the other hand, these two diaphragm model show very close frequency values. For example, frequency range of 600 µm in radius and 5 µm thick diaphragm was changes between 28.6-15.4 kHz and 28.7-15.4 kHz when M1 and M2 model was considered, respectively.

M2 model based diaphragm not only includes more geometrical parameters for determination of sensitivity and but also provides stiffer membrane compared to M1 model based diaphragm due to lower membrane deformation under same pressure conditions. This provides more flexibility to tune sensitivity response of sensor. From the point of view of frequency response, both of M1 and M2 model based diaphragm show slight differences between the fundamental frequencies for thinner and wider embossment.

As a conclusion, we hoped that the results obtained from this study will be used as a comparative study and help the obtain more accurate theoretical and practical models of embossed diaphragm for the future studies.

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# The Declaration of Ethics Committee Approval

This study does not require ethics committee permission or any special permission.

# The Declaration of Research and Publication Ethics

The authors of the paper declare that they comply with the scientific, ethical and quotation rules of SAUJS in all processes of the paper and that they do not make any falsification on the data collected. In addition, they declare that Sakarya University Journal of Science and its editorial board have no responsibility for any ethical violations that may be encountered, and that this study has not been evaluated in any academic publication environment other than Sakarya University Journal of Science.

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