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ON TRANS-SASAKIAN MANIFOLD EQUIPPED WITH *m*-PROJECTIVE CURVATURE TENSOR

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ABSTRACT. The work towards of the attending paper is to interpret the trans-Sasakian manifold equipped with *m*-projective curvature tensor and its various geometric properties. First, we observe that *m*-projectively flat trans-Sasakian manifold is Einstein. In order, we discussed *m*-projectively conservative and ϕ -*m*-projectively flat trans-Sasakian manifold. Following, we found the sufficient condition for quasi *m*-projectively flat trans-Sasakian manifold to be *m*-projectively flat. In the end, the *m*-projectively and ϕ -*m*-projectively symmetric trans-Sasakian manifolds are analyzed.

Keywords: Trans-Sasakian manifold, m-projectively flat, Einstein manifold, m-projective conservative.

AMS Subject Classification: 53C15, 53B05.

1. INTRODUCTION

Oubina [8] initiated a new class of almost contract manifold, called trans-Sasakian manifold, which is of type (0, 0), $(\alpha, 0)$ and $(0, \beta)$ are respectively, familiar as the cosymplectic, α -Sasakian and β -Kenmotsu manifold, α, β are the scalar smooth functions. In fact if $\alpha = 0$, $\beta = 1$ and $\alpha = 1$, $\beta = 0$, then a trans-Sasakian manifold will enhance a Kenmotsu and Sasakian manifold, respectively.

In 1971, Pokhariyal and Mishra[9] established a new curvature known as *m*-projectively curvature tensor on Riemannian manifold. Followed that many researcher such as Ojha [6, 7], Singh [12], Choubey and Ojha [3] studied properties of *m*-projective curvature in different manifolds. We say that a Riemannian manifold is flat if its curvature vanishes at each point. Following this sense Ojha [7] and Zengin [15] consider the *m*-projective flat in the Sasakian and LP-Sasakian manifold, respectively. The idea of local symmetry of a Riemannian manifold studied by Cartan [2] and mild version of local symmetry, Takahashi [13] introduced the notion of ϕ -symmetry on a Sasakian manifold. In this series, we investigate some results about flatness, symmetry and space time with *m*-projective curvature in trans-Sasakian structure.

The paper classified as follows: In part 2, we put some basic formulae and definition of trans-Sasakian manifold. In the next part, we confer about m-projectively flat trans-Sasakian manifold and mentioned a sufficient condition for such a manifold to be Einstein.

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Then, we found the condition such that the *m*-projective conservative trans-Sasakian manifold is of constant curvature. Successive that, we find the condition for ϕ -*m*-projectively flat trans-Sasakian manifold to be η -Einstein and quasi *m*-projectively flat is of constant curvature. In the last, we examine the *m*-projective and ϕ -*m*-projective symmetric trans-Sasakian manifolds.

2. Preliminaries

In this section, we mention some basic formulae and definitions, which will be used later.

Let M^m be an m = (2n+1) dimensional almost contact metric manifold [1], consisting of a (1,1) tensor field ϕ , a characteristic vector field ξ , a 1-form η and a Riemannian metric g. Then

$$\phi^2 X = -X + \eta(X)\xi, \ \eta(\xi) = 1, \ \eta(\phi X) = 0, \ \phi\xi = 0, \tag{1}$$

$$g(\phi X, \phi Y) = g(X, Y) - \eta(X)\eta(Y), \tag{2}$$

$$g(\xi,\xi) = 1, \ \phi \circ \xi = 0, \ \eta \circ \phi = 0, \tag{3}$$

for any X, Y in TM. From (1) and (2), it can be easily seen that

$$g(X,\phi Y) = -g(\phi X,Y), g(X,\xi) = \eta(X).$$

$$\tag{4}$$

For an almost contact metric structure (ϕ, ξ, η, g) on M, we put

$$\Phi(X,Y) = g(X,\phi Y). \tag{5}$$

Let M^{2n+1} be almost contact manifold and consider the structure $(M \times \mathcal{R}, \mathcal{J}, \mathcal{G})$ belongs to the class W_4 of the Hermitian manifolds, we denote a vector field on $M \times \mathcal{R}$ by $(X, f\frac{d}{dt})$, where X is tangent to M, t is the co-ordinates of \mathcal{R} and f as C^{∞} function on $M \times \mathcal{R}$. Define an almost complex structure [4]

$$\mathcal{J}\left(X, f\frac{d}{dt}\right) = \left(\phi X - f\xi, \eta(X)\frac{d}{dt}\right),$$

for any vector field X on $M \times \mathcal{R}$ and \mathcal{G} is Hermitian metric on the product $M \times \mathcal{R}$. This may be expressed by the condition

$$(\nabla_X \phi)Y = \alpha(g(X,Y)\xi - \eta(Y)X) + \beta(g(\phi X,Y)\xi - \eta(Y)\phi X), \tag{6}$$

where ∇ is a Levi-civita connection and α , β are some smooth functions on M^{2n+1} and we say that trans-Sasakian structure is type (α, β) . From the above, it is follows that

$$(\nabla_X \eta)Y = -\alpha g(\phi X, Y) + \beta g(\phi X, \phi Y), \tag{7}$$

$$(\nabla_X \xi) = -\alpha \phi X + \beta (X - \eta(X)\xi).$$
(8)

On a trans-Sasakian manifold M^{2n+1} with structure (ϕ, ξ, η, g) , the following relations hold [11]

$$R(X,Y,\xi) = (\alpha^2 - \beta^2)[\eta(Y)X - \eta(X)Y] + 2\alpha\beta[\eta(Y)\phi X - \eta(X)\phi Y] + (Y\alpha)\phi X - (X\alpha)\phi Y + (Y\beta)\phi^2 X - (X\beta)\phi^2 Y,$$
(9)

$$R(\xi, X, \xi) = (\alpha^2 - \beta^2 - \xi\beta)[\eta(X)\xi - X],$$
(10)

$$2\alpha\beta + \xi\alpha = 0,\tag{11}$$

$$\eta(R(X, Y, \xi)) = \eta(R(\xi, Y, \xi)) = 0,$$
(12)

$$R(\xi, Y, Z) = (\alpha^2 - \beta^2)[g(Z, Y)\xi - \eta(Z)Y] + 2\alpha\beta[g(\phi Z, Y)\xi + \eta(Z)\phi Y] + (Z\alpha)\phi Y + g(\phi Z, Y)grad\alpha + (Z\beta)[Y - \eta(Y)\xi] - g(\phi Z, \phi Y)grad\beta,$$
(13)

$$S(X,\xi) = [2n(\alpha^2 - \beta^2) - \xi\beta]\eta(X) - (2n-1)X\beta - (\phi X)\alpha,$$
(14)

$$S(\xi,\xi) = 2n(\alpha^2 - \beta^2 - \xi\beta), \tag{15}$$

$$S(\phi X, \phi Y) = S(X, Y) - 2n(\alpha^2 - \beta^2 - \xi\beta)\eta(X)\eta(Y), \tag{16}$$

$$Q\xi = (2n(\alpha^2 - \beta^2) - \xi\beta)\xi - (2n - 1)grad\beta + \phi(grad\alpha),$$
(17)

$$S(X,Y) = g(QX,Y),$$
(18)

where R is the curvature tensor, S is the Ricci tensor, r is scalar curvature and Q being the symmetric endomorphism of the tangent space at each point corresponding to Ricci-tensor S. Now, we assume that

$$\phi(grad\alpha) = (2n-1)grad\beta,\tag{19}$$

then [11]

$$S(X,\xi) = 2n(\alpha^2 - \beta^2)\eta(X), \qquad (20)$$

$$S(\phi X, \phi Y) = S(X, Y) - 2n(\alpha^2 - \beta^2)\eta(X)\eta(Y),$$
(21)

$$Q\xi = 2n(\alpha^2 - \beta^2)\xi, \qquad (22)$$

$$(\nabla_W S)(Y,\xi) = 2n(\alpha^2 - \beta^2)[-\alpha g(Y,\phi W) + \beta g(Y,W)] +\alpha S(Y,\phi W) - \beta S(Y,W).$$
(23)

Now we are going to mention the following definition, which will be considered in the later results:

Definition 2.1. [4] A trans-Sasakian manifold M^{2n+1} is said to be η -Einstein, if the Ricci tensor S satisfies the relation

$$S(X,Y) = ag(X,Y) + b\eta(X)\eta(Y), \qquad (24)$$

for all X and $Z \in TM$, where a and b are smooth functions on M^{2n+1} .

In particular, if b = 0 then it reduce to the Einstein manifold.

3. *m*-projectively flat Trans-Sasakian Manifold

Definition 3.1. [10] A trans-Sasakian manifold M^{2n+1} is said to be m-projectively flat, if the m-projective curvature tensor M satisfies the relation

$$M(X, Y, Z) = 0, for all X, Yand Z,$$
(25)

where m-projective curvature tensor M is given by [9]

$$M(X, Y, Z) = R(X, Y, Z) - \frac{1}{4n} \left[S(Y, Z)X - S(X, Z)Y + g(Y, Z)QX - g(X, Z)QY \right].$$
(26)

Theorem 3.1. An *m*-projectively flat trans-Sasakian manifold M^{2n+1} is an Einstein manifold.

Proof. Let M^{2n+1} be *m*-projectively flat trans-Sasakian manifold, then the equation (26) becomes

$$R(X,Y,Z) = \frac{1}{4n} \bigg[S(Y,Z)X - S(X,Z)Y + g(Y,Z)QX - g(X,Z)QY \bigg].$$

$$(27)$$

284

Proceeds the inner product in above equation both side with respect to U, then we obtain

$$g(R(X, Y, Z), U) = \frac{1}{4n} \bigg[S(Y, Z)g(X, U) - S(X, Z)g(Y, U) + g(Y, Z)S(X, U) - g(X, Z)S(Y, U) \bigg].$$
(28)

Taking the contraction over X and U, we get

$$S(Y,Z) = \frac{r}{(2n+1)}g(Y,Z).$$
(29)

Theorem 3.2. An *m*-projectively flat trans-Sasakian manifold M^{2n+1} is of constant curvature.

Proof. Let M^{2n+1} be *m*-projectively flat trans-Sasakian manifold. Then by existence of the relation (27) and after using the equations (29), we can find

$$R(X, Y, Z) = \frac{r}{2n(2n+1)} [g(Y, Z)X - g(X, Z)Y].$$
(30)

By virtue of the Theorem (3.1) and Theorem (3.2), we state the following corollary:

Corollary 3.1. An *m*-projectively flat trans-Sasakian manifold M^{2n+1} , is of constant curvature iff it is Einstein.

4. *m*-projective conservative Trans- Sasakian Manifold

Definition 4.1. [5] A trans-Sasakian manifold M^{2n+1} is said to be m-projective conservative, if the m-projective curvature tensor M satisfies the relation

$$div(M(X,Y,Z)) = 0, for all X, Yand Z,$$
(31)

where div denotes the divergence.

Theorem 4.1. An Einstein trans-Sasakian manifold M^{2n+1} with constant scalar curvature is m-projective conservative iff it is conservative.

Proof. We assume that M^{2n+1} be Einstein *M*-projective trans-Sasakian manifold then by virtue of relation (26), we obtain

$$M(X, Y, Z) = R(X, Y, Z) - \frac{1}{4n} [g(Y, Z)X - g(X, Z)Y].$$
(32)

By taking covariant derivative both side with respect to W in above equation, we obtain

$$(\nabla_W)M(X,Y,Z) = (\nabla_W)R(X,Y,Z).$$
(33)

Contracting the above relation with W, we can find

$$div(M(X,Y,Z)) = div(R(X,Y,Z)).$$
(34)

If manifold is m-projective conservative, then

$$div(R(X, Y, Z)) = 0.$$
 (35)

Then the converse part is trivial.

5. ϕ -m-projectively flat Trans- Sasakian Manifold

Definition 5.1. [11] A trans-Sasakian manifold M^{2n+1} is said to be ϕ -m-projectively flat, if the m-projective curvature tensor M satisfies the relation

$$\phi^2(M(\phi X, \phi Y, \phi Z)) = 0, for all X, Yand Z.$$
(36)

Theorem 5.1. A ϕ -m-projectively flat trans-Sasakian manifold M^{2n+1} is an η -Einstein manifold.

Proof. Let us we assume that M^{2n+1} be ϕ -*M*-projectively flat trans-Sasakian manifold. Then by virtue of the relations (36) and (1), we have

$$M(\phi X, \phi Y, \phi Z) = \eta(M(\phi X, \phi Y, \phi Z))\xi,$$
(37)

which implies

$$g(M(\phi X, \phi Y, \phi Z), \phi U) = \eta(M(\phi X, \phi Y, \phi Z))g(\xi, \phi U).$$
(38)

By the relation (1), the above equation becomes

$$g(M(\phi X, \phi Y, \phi Z), \phi U) = 0.$$
(39)

Now, by virtue of the relation (26), we obtain

$$g(R(\phi X, \phi Y, \phi Z), \phi U) = \frac{1}{4n} [S(\phi Y, \phi Z)g(\phi X, \phi U) - S(\phi X, \phi Z)g(\phi Y, \phi U) + g(\phi Y, \phi Z)S(\phi X, \phi U) - g(\phi X, \phi Z)S(\phi Y, \phi U)].$$
(40)

Let $\{e_1, e_2, \dots, e_{2n}, \xi\}$ be a local orthonormal basis of vector field in M^{2n+1} by using the fact that $\{\phi e_1, \phi e_2, \dots, \phi e_{2n}, \xi\}$ is also a orthonormal basis, if we put $X=U=e_i$ in above relation and taking summation with respect to i, then we have

$$\sum_{i=1}^{2n} g(R(\phi e_i, \phi Y, \phi Z), \phi e_i)$$

= $\frac{1}{4n} \bigg[\sum_{i=1}^{2n} S(\phi Y, \phi Z) g(\phi e_i, \phi e_i) - \sum_{i=1}^{2n} S(\phi e_i, \phi Z) g(\phi Y, \phi e_i) + \sum_{i=1}^{2n} g(\phi Y, \phi Z) S(\phi e_i, \phi e_i) - \sum_{i=1}^{2n} g(\phi e_i, \phi Z) S(\phi Y, \phi e_i) \bigg].$ (41)

Now, we find that

0.

$$\sum_{i=1}^{2n} g(R(\phi e_i, \phi Y, \phi Z), \phi e_i) = S(\phi Y, \phi Z) - (\alpha^2 - \beta^2 - \xi\beta)g(\phi Y, \phi Z),$$

$$\sum_{i=1}^{2n} g(\phi e_i, \phi e_i) = 2n, \tag{42}$$

$$\sum_{i=1}^{2n} S(\phi e_i, \phi Z) g(\phi Y, \phi e_i) = S(\phi Y, \phi Z),$$
(43)

$$\sum_{i=1}^{2n} S(\phi e_i, \phi e_i) = r - 2n(\alpha^2 - \beta^2 - \xi\beta),$$
(44)

286

$$(2n+2)S(\phi Y, \phi Z) = [r+2n(\alpha^2 - \beta^2 - \xi\beta)]g(\phi Y, \phi Z).$$
(45)

Using the relations (42)-(45), the equation (41) becomes

$$S(Y,Z) = \frac{1}{(2n+2)} \left[r + 2n(\alpha^2 - \beta^2 - \xi\beta) \right] g(Y,Z) + \frac{1}{(2n+2)} \left[2n(2n-1)(\alpha^2 - \beta^2 - \xi\beta) \right] \eta(Y)\eta(Z).$$
(46)
anifold is η -Einstein.

Hence the manifold is η -Einstein.

6. Quasi *m*-projectively flat Trans-Sasakian Manifold

Definition 6.1. [10] A trans-Sasakian manifold M^{2n+1} is said to be quasi m-projectively flat, if the m-projective curvature tensor M satisfies the relation

$$g(M(X,Y,Z),\phi U) = 0, for all X, Y Z and U.$$
(47)

Theorem 6.1. A quasi m-projectively flat trans-Sasakian manifold M^{2n+1} satisfying $\phi(grad\alpha) = (2n-1)grad\beta$ is m-projectively flat if it is of constant curvature.

Proof. Let M^{2n+1} be a quasi *m*-projectively flat trans-Sasakian manifold. Then by the relations (47) and (26), we obtain

$$g(R(X, Y, Z), \phi U) = \frac{1}{4n} [S(Y, Z)g(X, \phi U) - S(X, Z)g(Y, \phi U) + g(Y, Z)S(X, \phi U) - g(X, Z)S(Y, \phi U)].$$
(48)

Putting $X = \phi X$ in the above relation, we get

$$g(R(\phi X, Y, Z), \phi U) = \frac{1}{4n} [S(Y, Z)g(\phi X, \phi U) - S(\phi X, Z)g(Y, \phi U) + g(Y, Z)S(\phi X, \phi U) - g(\phi X, Z)S(Y, \phi U)].$$
(49)

After putting $X=U=e_i$ in above relation and taking summation with respect to *i*, we attain

$$\sum_{i=1}^{2n} g(R(\phi e_i, Y, Z), \phi e_i)$$

= $\frac{1}{4n} \bigg[\sum_{i=1}^{2n} S(Y, Z) g(\phi e_i, \phi e_i) - \sum_{i=1}^{2n} S(\phi e_i, Z) g(Y, \phi e_i) + \sum_{i=1}^{2n} g(Y, Z) S(\phi e_i, \phi e_i) - \sum_{i=1}^{2n} g(\phi e_i, Z) S(Y, \phi e_i) \bigg].$ (50)

If M^{2n+1} satisfies $\phi(grad\alpha) = (2n-1)grad\beta$, we have the following relation

$$\sum_{i=1}^{2n} g(R(\phi e_i, Y, Z), \phi e_i) = S(Y, Z) - (\alpha^2 - \beta^2) g(\phi Y, \phi Z),$$
(51)

$$\sum_{i=1}^{2n} S(\phi e_i, Z) g(Y, \phi e_i) = S(Y, Z) - 2n(\alpha^2 - \beta^2) \eta(Y) \eta(Z),$$
(52)

$$\sum_{i=1}^{2n} S(\phi e_i, \phi e_i) = r - 2n(\alpha^2 - \beta^2).$$
(53)

After using the relations (42), (51), (52) and (53) in the equation (50), we obtain

$$S(Y,Z) = \left[\frac{r+2n(\alpha^2 - \beta^2)}{(2n+2)}\right]g(Y,Z).$$
 (54)

By virtue of the equation (26) and using the above relation, we can get

$$M(X, Y, Z) = R(X, Y, Z) - \left[\frac{r + 2n(\alpha^2 - \beta^2)}{(n+1)}\right] [g(Y, Z)X - g(X, Z)Y].$$
(55)

Which shows the statement.

7. *m*-projectively symmetric Trans-Sasakian Manifold

Definition 7.1. [4] A trans-Sasakian manifold M^{2n+1} is said to be m-projectively symmetric, if the m-projective curvature tensor M satisfies the relation

$$(\nabla_W M)(X, Y, Z) = 0, for all X, Y Z and W.$$
(56)

Theorem 7.1. A *m*-projectively symmetric trans-Sasakian M^{2n+1} manifold is Riccirecurrent.

Proof. Let M^{2n+1} is a *m*-projectively symmetric trans-Sasakian manifold. Then by the equations (56) and (26), we find

$$g((\nabla_W R)(X, Y, Z), U) = \frac{1}{4n} [(\nabla_W S)(Y, Z)g(X, U) - (\nabla_W S(X, Z)g(Y, U) + (\nabla_W S)(X, U)g(Y, Z) - (\nabla_W S)(Y, U)g(X, Z)].$$
(57)

Taking contraction over X and U, we secure

$$(\nabla_W S)(Y,Z) = \frac{1}{4n} [(2n+1)(\nabla_W S)(Y,Z) - (\nabla_W S(Y,Z) + dr(W)g(Y,Z) - (\nabla_W S)(Y,Z)],$$
(58)

which implies

$$(\nabla_W S)(Y,Z) = \frac{dr(W)}{(2n+1)}g(Y,Z).$$
(59)

Hence the manifold is Ricci-recurrent.

Suppose the scalar curvature r is constant then we mention the corollary:

Corollary 7.1. An *m*-projective symmetric trans-Sasakian manifold M^{2n+1} with constant scalar curvature is Einstein.

8. ϕ -m-projectively symmetric Trans-Sasakian Manifold

Definition 8.1. [4] A trans-Sasakian manifold M^{2n+1} is said to be ϕ – m-projectively symmetric, if the m-projective curvature tensor M satisfies the relation

$$\phi^2(\nabla_W M)(X, Y, Z) = 0, for all X, Y Z and W.$$
(60)

Theorem 8.1. A ϕ – *m*-projectively symmetric trans-Sasakian M^{2n+1} manifold is an Einstein.

288

 \square

Proof. Let us consider M^{2n+1} is a ϕ – *m*-projectively symmetric trans-Sasakian manifold. Then by the equations (60) and (1), we get

$$g((\nabla_W M)(X, Y, Z), U) = \eta((\nabla_W M)(X, Y, Z))g(\xi, U).$$
(61)

The existence of the relation (26), the above equation becomes

$$g((\nabla_W R)(X, Y, Z), U) - \frac{1}{4n} \left[(\nabla_W S)(Y, Z)g(X, U) - (\nabla_W S)(X, Z)g(Y, U) + (\nabla_W S)(X, U)g(Y, Z) - (\nabla_W S)(Y, U)g(X, Z) \right]$$

$$= g((\nabla_W R)(X, Y, Z), \xi)g(\xi, U) - \frac{1}{4n} \left[(\nabla_W S)(Y, Z)g(X, \xi) - (\nabla_W S)(X, Z)g(Y, \xi) + (\nabla_W S)(X, \xi)g(Y, Z) - (\nabla_W S)(Y, \xi)g(X, Z) \right] g(\xi, U).$$
(62)

After contraction over X and Z, we secure

$$(\nabla_W S)(Y,U) - (\nabla_W S)(Y,\xi)\eta(U) = \frac{dr(W)}{(6n-1)} [-g(Y,U) + g(Y,\xi)\eta(U)].$$
(63)

Putting $Y = \xi$, we get

$$\nabla_W S)(\xi, U) = 0. \tag{64}$$

By virtue of the relation (23) and above equation, we have

(

$$2n(\alpha^{2} - \beta^{2})[-\alpha g(U, \phi W) + \beta g(U, W)] + \alpha S(U, \phi W) - \beta S(U, W) = 0.$$
(65)

We put $U=\phi U$ and $W=\phi W$, respectively in the above relation and then using equations (1), (4), (18), (19) and (22), we find that

$$S(U,W) = 2n(\alpha^2 - \beta^2)g(U,W)$$

$$S(\phi U,W) = 2n(\alpha^2 - \beta^2)g(\phi U,W).$$
(66)

and

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