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# Weingarten Map of the Henneberg-Type Minimal Surfaces in 4-Space

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#### Abstract

We consider a two parameter family of Henneberg-type minimal surfaces  $\mathfrak{H}_{m,n}$  using the Weierstrass representation in the four dimensional Euclidean space  $\mathbb{E}^4$ . An invariant linear map of Weingarten type in the tangent space of the Henneberg-type minimal surface  $\mathfrak{H}_{4,2}$  which generates two invariants  $\kappa$  and  $\varkappa$ , is characterized by  $\varkappa^2 = \kappa$  in  $\mathbb{E}^4$ .

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#### 1. Introduction

A minimal surface in three dimensional Euclidean space  $\mathbb{E}^3$ , also in the higher dimensions is a regular surface for which the mean curvature vanishes identically [4, 5, 8, 21, 23].

On the other hand, the classical Henneberg surface [14, 15, 16] also obtained by Weierstrass representation [24, 25] is well-known classical minimal surface in  $\mathbb{E}^3$ . Henneberg's minimal surface was the unique nonorientable example known until 1981, when Meeks indicated the first example of a nonorientable, regular, complete, minimal surface of finite total curvature  $-6\pi$ . See [22] for details.

A general definition of rotational surfaces in  $\mathbb{E}^4$  was obtained by Moore in [20]. Güler, Hacısalihoğlu, and Kim [9] worked the Gauss map and the third Laplace-Beltrami operator of the rotational hypersurfaces in  $\mathbb{E}^4$ . See also [1, 2, 3, 12, 13, 18, 19] for some new works of the topic.

Güler and Kişi [10] studied Weierstrass representation, degree and classes of the surfaces in the Euclidean 4-space. Güler, Kişi, and Konaxis [11] introduced Henneberg implicit algebraic minimal surfaces in  $\mathbb{E}^4$ .

We study a two-parameter family of Henneberg type minimal surfaces using the Weierstrass representation in  $\mathbb{E}^4$ . We give the Weierstrass equation for a minimal surface in  $\mathbb{E}^4$ , also obtain two normals of the surface in the Section 2.

In Section 3, we introduce to the Henneberg type minimal surfaces of values (m,n) for positive integers m,n called  $H_{m,n}$ . Finally, we study Henneberg type minimal surfaces  $H_{4,2}$  using Weierstrass representation in  $\mathbb{E}^4$ . Then we give an invariant linear map of Weingarten type in the tangent space of the Henneberg-type minimal surface  $H_{4,2}$  which generates two invariants  $\kappa$  and  $\varkappa$ , is characterized by  $\varkappa^2 = \kappa$  in Section 4.

## 2. Weierstrass equation and normals for a minimal surface in $\mathbb{E}^4$

We identify  $\overrightarrow{x}$  and  $\overrightarrow{x^{t}}$  without further comment. Let  $\mathbb{E}^{4} = (\{\overrightarrow{x} = (x_{1}, x_{2}, x_{3}, x_{4})^{t} | x_{i} \in \mathbb{R}\}, \langle \cdot, \cdot \rangle)$  be the 4-dimensional Euclidean space with metric  $\langle x, y \rangle = x_{1}y_{1} + x_{2}y_{2} + x_{3}y_{3} + x_{4}y_{4}$ .

Hoffman and Osserman [17] gave the Weierstrass equation for a minimal surface in  $\mathbb{E}^4$  as follows

$$\Phi(z) = \frac{\Psi}{2} \left[ 1 + fg, i(1 - fg), f - g, -i(f + g) \right].$$
(2.1)

Here  $\psi$  is analytic and the order of the zeros of  $\psi$  must be greater than the order of the poles of f, g at each point. **Theorem 1.** Normal vectors of a minimal surface with respect to Weierstrass equation  $X_x - iX_y = \Phi(z)$  in  $\mathbb{E}^4$ , are as follows:

$$n_1 = \sqrt{\frac{a}{a^2 - b^2}} \left( w_1 + \frac{b}{a} X_y \right) \tag{2.2}$$

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and

$$n_2 = \sqrt{\frac{a}{a^2 - b^2}} \left( w_2 - \frac{b}{a} X_x \right), \tag{2.3}$$

where  $a = \langle X_x, X_x \rangle$ ,  $b = \langle X_x, w_2 \rangle$ , and  $w_1, w_2$  are perpendicular to  $X_x, X_y$ , respectively. Proof. See [11] for the proof.

With  $x = r\cos(\theta)$ ,  $y = r\sin(\theta)$ ,  $f_1 = 1 - r^{-m}\cos(m\theta)$ ,  $f_2 = -r^{-m}\sin(m\theta)$ ,  $g_1 = r^n\cos(n\theta)$ ,  $g_2 = r^n\sin(n\theta)$ , we have following normals

$$(n_{1})_{m,n}(r,\theta) = \mathscr{A} \begin{pmatrix} \mathscr{B}\sin(\theta) - r^{2m}r^{n}\sin((n+1)\theta) + r^{m}r^{n}\sin((m+n+1)\theta) \\ \mathscr{B}\cos(\theta) + r^{2m}r^{n}\cos((n+1)\theta) - r^{m}r^{n}\cos((m+n+1)\theta) \\ -r^{2m}\sin(\theta) + r^{m}\sin((m+1)\theta) - \mathscr{B}r^{n}\sin((n+1)\theta) \\ r^{2m}\cos(\theta) - r^{m}\cos((m+1)\theta) - \mathscr{B}r^{n}\cos((n+1)\theta) \end{pmatrix}$$
(2.4)

and

$$(n_2)_{m,n}(r,\theta) = \mathscr{A} \begin{pmatrix} \mathscr{B}\cos(\theta) - r^{2m}r^n\cos\left((n+1)\theta\right) + r^m r^n\cos\left((m+n+1)\theta\right) \\ -\mathscr{B}\sin(\theta) - r^{2m}r^n\sin\left((n+1)\theta\right) + r^m r^n\sin\left((m+n+1)\theta\right) \\ -r^{2m}\cos\left(\theta\right) + r^m\cos\left((m+1)\theta\right) - \mathscr{B}r^n\cos\left((n+1)\theta\right) \\ -r^{2m}\sin\left(\theta\right) + r^m\sin\left((m+1)\theta\right) + \mathscr{B}r^n\sin\left((n+1)\theta\right) \end{pmatrix},$$
(2.5)

where  $\mathscr{A} = \left[\mathscr{B}\left(r^{2n}+1\right)\left(2r^{2m}-2r^{m}\cos\left(m\theta\right)+1\right)\right]^{-1/2}, \mathscr{B} = r^{2m}-2r^{m}\cos\left(m\theta\right)+1$ . We check  $\langle n_{1},n_{1}\rangle = \langle n_{2},n_{2}\rangle = 1$ . See also [11] for details.

## **3.** Henneberg family of surfaces $\mathfrak{H}_{m,n}$

Choosing  $\psi = 2$ ,  $f = 1 - 1/z^m$  and  $g = z^n$  in analogy with the surface case, we see

$$\begin{split} \Phi(z) &= \frac{\Psi}{2} \left( 1 + fg, i(1 - fg), f - g, -i(f + g) \right) \\ &= \left( 1 + z^n - z^{n-m}, i(1 - z^n + z^{n-m}), 1 - z^{-m} - z^n, -i(1 - z^{-m} + z^n) \right). \end{split}$$

We integrate it to get following:

$$\int \Phi(z) dz = \begin{pmatrix} z + \frac{z^{n+1}}{n+1} - \frac{z^{-m+n+1}}{-m+n+1} \\ i \left( z - \frac{z^{n+1}}{n+1} + \frac{z^{-m+n+1}}{-m+n+1} \right) \\ z - \frac{z^{-m+1}}{-m+1} - \frac{z^{n+1}}{n+1} \\ -i \left( z - \frac{z^{-m+1}}{-m+1} + \frac{z^{n+1}}{n+1} \right) \end{pmatrix}$$

with  $m \neq 1, n \neq -1, -m + n \neq -1$ . We let  $z = re^{i\theta}$  and taking the real part of the integral, we have the Henneberg type minimal surface  $H_{m,n}(r,\theta)$  as follows:

$$\mathfrak{H}_{m,n}(r,\theta) = \begin{pmatrix} r\cos(\theta) + \frac{r^{n+1}\cos((n+1)\theta)}{n+1} - \frac{r^{-m+n+1}\cos((-m+n+1)\theta)}{-m+n+1} \\ -r\sin(\theta) + \frac{r^{n+1}\sin((n+1)\theta)}{n+1} - \frac{r^{-m+n+1}\sin((-m+n+1)\theta)}{-m+n+1} \\ r\cos(\theta) - \frac{r^{-m+1}\cos((-m+1)\theta)}{-m+1} - \frac{r^{n+1}\cos((n+1)\theta)}{n+1} \\ r\sin(\theta) - \frac{r^{-m+1}\sin((-m+1)\theta)}{-m+1} + \frac{r^{n+1}\sin((n+1)\theta)}{n+1} \end{pmatrix}$$

Using the binomial formula, we obtain the following parametric equation of  $\mathfrak{H}_{m,n}(u,v)$ :

$$x = \operatorname{Re}\left\{u + iv + \frac{1}{n+1}\left[\sum_{k=0}^{n+1} \binom{n+1}{k}u^{n+1-k}(iv)^{k}\right] - \frac{1}{-m+n+1}\left[\sum_{k=0}^{-m+n+1} \binom{-m+n+1}{k}u^{-m+n+1-k}(iv)^{k}\right]\right\},$$

$$y = \operatorname{Re}\left\{iu - v - \frac{i}{n+1}\left[\sum_{k=0}^{n+1} \binom{n+1}{k}u^{n+1-k}(iv)^{k}\right] + \frac{i}{-m+n+1}\left[\sum_{k=0}^{-m+n+1} \binom{-m+n+1}{k}u^{-m+n+1-k}(iv)^{k}\right]\right\},$$

$$z = \operatorname{Re}\left\{u + iv - \frac{1}{-m+1}\left[\sum_{k=0}^{-m+1} \binom{-m+1}{k}u^{-m+1-k}(iv)^{k}\right] - \frac{1}{n+1}\left[\sum_{k=0}^{n+1} \binom{n+1}{k}u^{n+1-k}(iv)^{k}\right]\right\},$$

$$w = \operatorname{Re}\left\{iu + v + \frac{i}{-m+1}\left[\sum_{k=0}^{-m+1} \binom{-m+1}{k}u^{-m+1-k}(iv)^{k}\right] - \frac{i}{n+1}\left[\sum_{k=0}^{n+1} \binom{n+1}{k}u^{n+1-k}(iv)^{k}\right]\right\},$$
(3.1)

where

$$\mathfrak{H}_{m,n}(u,v) = (x(u,v), y(u,v), z(u,v), w(u,v)).$$

 $\begin{array}{c} 6.\times10^{15} \\ 4.\times10^{15} \\ 2.\times10^{15} \\ -4.\times10^{15} \\ -4.\times10^{15} \\ -4.\times10^{15} \\ -2.\times10^{15} \\ -4.\times10^{15} \\ -2.\times10^{15} \\ -1.\times10^{15} \\ 2.\times10^{15} \\ -1.\times10^{15} \\ -1.\times10^{15} \\ -1.\times10^{15} \\ -2.\times10^{15} \\ -2.\times10^{16} \\ -2.\times10^{16} \\ -4.\times10^{16} \\$ 

**Figure 4.1:** Figure 1. Projections of  $H_{4,2}(r, \theta)$ : (Left) into  $x_1x_2x_4$ -space, (Right) into  $x_2x_3x_4$ -space

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## 4. Weingarten map of $\mathfrak{H}_{4,2}$

Using an arbitrary orthonormal frame field  $\{n_1, n_2\}$  for a surface S(u, v) in  $\mathbb{E}^4$ , we get the standard derivative formulas as follows

$$\nabla_{S_{u}}S_{u} = S_{uu} = \Gamma_{11}^{1}S_{u} + \Gamma_{11}^{2}S_{v} + c_{11}^{1}n_{1} + c_{11}^{2}n_{2},$$

$$\nabla_{S_{u}}S_{v} = S_{uv} = \Gamma_{12}^{1}S_{u} + \Gamma_{12}^{2}S_{v} + c_{12}^{1}n_{1} + c_{12}^{2}n_{2},$$

$$\nabla_{S_{u}}S_{v} = S_{vv} = \Gamma_{22}^{1}S_{u} + \Gamma_{22}^{2}S_{v} + c_{22}^{1}n_{1} + c_{22}^{2}n_{2},$$
(4.1)

where  $\Gamma_{ij}^k$  are the Christoffel symbols and  $c_{ij}^k$ ,  $i, j, k \in \{1, 2\}$  are functions on *S*. Taking standart notations of the first fundamental form coefficients

$$E = \langle S_u, S_u \rangle, \quad F = \langle S_u, S_v \rangle, \quad G = \langle S_v, S_v \rangle, \tag{4.2}$$

we get  $W_1 = EG - F^2$ . Also, using standart notations of the second fundamental form coefficients

$$L = \frac{2}{\sqrt{W_1}} \begin{vmatrix} c_{11}^1 & c_{12}^1 \\ c_{11}^2 & c_{12}^2 \end{vmatrix}, M = \frac{1}{\sqrt{W_1}} \begin{vmatrix} c_{11}^1 & c_{22}^1 \\ c_{11}^2 & c_{22}^2 \end{vmatrix}, N = \frac{2}{\sqrt{W_1}} \begin{vmatrix} c_{12}^1 & c_{22}^1 \\ c_{12}^2 & c_{22}^2 \end{vmatrix},$$
(4.3)

we have  $W_2 = LN - M^2$ . Here  $c_{ij}^k$  are defined by

$$\begin{array}{lll} c_{11}^1 &=& \langle S_{uu}, n_1 \rangle, \quad c_{12}^1 = \langle S_{uv}, n_1 \rangle, \quad c_{22}^1 = \langle S_{vv}, n_1 \rangle, \\ c_{11}^2 &=& \langle S_{uu}, n_2 \rangle, \quad c_{12}^2 = \langle S_{uv}, n_2 \rangle, \quad c_{22}^2 = \langle S_{vv}, n_2 \rangle. \end{array}$$

From the Lemma 2.1 and Lemma 2.2 in [6], we have the functions which are invariants of the surface S, as follows

$$\kappa = \frac{W_2}{W_1} \quad \text{and} \quad \varkappa = \frac{W_3}{2W_1},\tag{4.4}$$

where  $W_3 = EN + GL - 2FM$ .

Taking m = 4, n = 2, we have Henneberg type surface (See Figure 1. Left, and Figure 1. Right)

$$\mathfrak{H}_{4,2}(r,\theta) = \begin{pmatrix} \frac{r^3 \cos(3\theta)}{3} + r\cos(\theta) + \frac{\cos(\theta)}{r} \\ \frac{r^3 \sin(3\theta)}{3} - r\sin(\theta) - \frac{\sin(\theta)}{r} \\ -\frac{r^3 \cos(3\theta)}{3} + r\cos(\theta) + \frac{\cos(3\theta)}{3r^3} \\ \frac{r^3 \sin(3\theta)}{3} + r\sin(\theta) - \frac{\sin(3\theta)}{3r^3} \end{pmatrix}.$$
(4.5)

We obtain following Henneberg type surface taking  $u := r \cos \theta$ ,  $v := r \sin \theta$  in (4.5)

$$\mathfrak{H}_{4,2}(u,v) = \begin{pmatrix} \frac{1}{3}u^3 - uv^2 + u + \frac{u}{u^2 + v^2} \\ -\frac{1}{3}v^3 + u^2v - v - \frac{v}{v} \\ -\frac{1}{3}u^3 + uv^2 + u + \frac{1}{3}\frac{u^3}{(u^2 + v^2)^3} - \frac{uv^2}{(u^2 + v^2)^3} \\ -\frac{1}{3}v^3 + u^2v + v + \frac{1}{3}\frac{v^3}{(u^2 + v^2)^3} - \frac{u^2v}{(u^2 + v^2)^3} \end{pmatrix}.$$
(4.6)

Next, we want to find normals  $n_1(u, v)$  and  $n_2(u, v)$  of the Henneberg type minimal surface  $\mathfrak{H}_{4,2}(u, v)$ . From (2.4) and (2.5), we have following normals, respectively,

$$n_{1}(r,\theta) = \mathscr{A} \begin{pmatrix} \mathscr{B}\sin(\theta) - r^{10}\sin(3\theta) + r^{6}\sin(7\theta) \\ \mathscr{B}\cos(\theta) + r^{10}\cos(3\theta) - r^{6}\cos(7\theta) \\ -r^{8}\sin(\theta) - \mathscr{B}r^{2}\sin(3\theta) + r^{4}\sin(5\theta) \\ r^{8}\cos(\theta) - \mathscr{B}r^{2}\cos(3\theta) - r^{4}\cos(5\theta) \end{pmatrix}$$

$$(4.7)$$



and

$$n_{2}(r,\theta) = \mathscr{A} \begin{pmatrix} \mathscr{B}\cos(\theta) - r^{10}\cos(3\theta) + r^{6}\cos(7\theta) \\ -\mathscr{B}\sin(\theta) + r^{10}\sin(3\theta) - r^{6}\sin(7\theta) \\ -r^{8}\cos(\theta) - \mathscr{B}r^{2}\cos(3\theta) + r^{4}\cos(5\theta) \\ -r^{8}\sin(\theta) + \mathscr{B}r^{2}\sin(3\theta) + r^{4}\sin(5\theta) \end{pmatrix}.$$

$$(4.8)$$

Here,  $\mathscr{A} = \left[\mathscr{B}\left(r^4+1\right)\left(2r^8-2r^4\cos\left(4\theta\right)+1\right)\right]^{-1/2}, \mathscr{B} = r^8-2r^4\cos\left(4\theta\right)+1.$ In (u, v) coordinates, we find normals  $n_1$  and  $n_2$  as follows

$$n_{1} = \mathscr{C} \begin{pmatrix} \left[ p^{5} + \left(1 - 4u^{2}\right)p^{4} - p^{3} - 2\left(1 - 12u^{2}\right)p^{2} + 16u^{2}\left(1 - 5u^{2}\right)p + 64u^{6} - 16u^{4} + 1\right]v \\ \left[ -3p^{5} + \left(1 + 4u^{2}\right)p^{4} + 7p^{3} - 2\left(1 + 28u^{2}\right)p^{2} + 16u^{2}\left(1 + 7u^{2}\right)p - 64u^{6} - 16u^{4} + 1\right]u \\ \left[ -p^{4} + 16u^{4} - 12u^{2}p + p^{2} - \left(p^{4} - 16u^{4} + 16u^{2}p - 2p^{2} + 1\right)\left(4u^{2} - p\right)\right]v \\ \left[ p^{4} - 16u^{4} + 20u^{2}p - 5p^{2} - \left(p^{4} - 16u^{4} + 16u^{2}p - 2p^{2} + 1\right)\left(4u^{2} - 3p\right)\right]u \end{pmatrix}$$

$$(4.9)$$

and

$$n_{2} = \mathscr{C} \begin{pmatrix} [3p^{5} + (1 - 4u^{2})p^{4} - 7p^{3} - 2(1 - 28u^{2})p^{2} - 16u^{2}(1 + 7u^{2})p + 64u^{6} - 16u^{4} + 1]u \\ [p^{5} - (1 + 4u^{2})p^{4} - p^{3} + 2(1 + 12u^{2})p^{2} - 16u^{2}(1 + 5u^{2})p + 64u^{6} + 16u^{4} - 1]v \\ [-p^{4} + 16u^{4} - 20u^{2}p + 5p^{2} - (p^{4} - 16u^{4} + 16u^{2}p - 2p^{2} + 1)(4u^{2} - 3p)]u \\ [-p^{4} + 16u^{4} - 12u^{2}p + p^{2} + (p^{4} - 16u^{4} + 16u^{2}p - 2p^{2} + 1)(4u^{2} - p)]v \end{pmatrix},$$
(4.10)

where

$$\mathscr{C} = \left[ p \left( p^2 + 1 \right) \left( p^4 - 2p^2 + 16u^2p - 16u^4 + 1 \right) \left( 2p^4 - 2p^2 + 16u^2p - 16u^4 + 1 \right) \right]^{-1/2}$$

and  $p = u^2 + v^2$ .

**Remark 1.** Two invariants  $\kappa$  and  $\varkappa$  divide the points of surface S(u, v) into the four types. A point  $\mathbf{p}$  in  $E^4$  is called:

Using (4.1), (4.2), (4.3), (4.9) and (4.10) for the Henneberg type surface (4.6), we have

$$E = \frac{(p^2+1)\varphi}{p^4} = G,$$
  

$$F = 0,$$
  

$$L = -\frac{8p\beta}{(p^2+1)^2\varphi^2} = N,$$
  

$$M = 0,$$

where

$$\begin{split} \varphi &= \varphi(u,v) = 2\left(p^2 - 1\right)^2 + 2p^2 + 16u^2v^2 - 1 \neq 0, \\ \beta &= \beta(u,v) = \varphi^2 - 4\left(p^2 + 1\right)\left(p^4 + \left(1 - 16u^2v^2\right)p^2 + 64u^4v^4\right). \end{split}$$

**Corollary 1.** An invariant linear map of Weingarten type in the tangent space of the Henneberg-type minimal surface  $\mathfrak{H}_{4,2}$  which generates two invariants

$$\kappa = \frac{64p^{10}\beta^2}{\left(p^2 + 1\right)^6\varphi^6}$$

and

$$\varkappa = -\frac{8p^5\beta}{\left(p^2+1\right)^3\varphi^3}$$

is characterized by  $\varkappa^2 = \kappa$  in  $\mathbb{E}^4$ . Here,  $\beta, \phi \neq 0, p = u^2 + v^2$ . Hence, every point **p** on  $\mathfrak{H}_{4,2}(u,v)$  is elliptic. **Corollary 2.** If  $\beta = 0$  in Corollary 1., then the points on the surface is flat.

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