Semi-Symmetry Properties of *S***-Manifolds Admitting a Quarter-Symmetric Metric Connection**

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Abstract

In this study *S*-manifolds admitting a quarter-symmetric metric connection naturally related with the *S*-structure are considered and some general results concerning the curvature of such a connection is given. In addition, we prove that an *S*-manifold has constant *f*-sectional curvature with respect to this quarter-symmetric metric connection if and only if has the same constant *f*-sectional curvature with respect to the Riemannian connection. In particular, the conditions of semi-symmetry, Ricci semi-symmetry, and projective semi-symmetry of this quarter-symmetric metric connection are investigated.

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1. Introduction

The idea of metric connection with torsion tensor in a Riemannian manifold was introduced by Hayden [8]. Later, Yano [17] studied some properties of semi symmetric metric connection on a Riemannian manifold. The semi-symmetric metric connection has important physical application such as the displacement on the earth surface following a fixed point is metric and semi-symmetric. Golab [5] defined semi-symmetric non-metric connections on a Riemannian manifold (M,g) and studied some of its properties. More precisely, if ∇ is a linear connection in a differentiable manifold M, the torsion tensor T of ∇ is given by $T(Z,W) = \nabla_Z W - \nabla_W Z - [Z,W]$, for any vector fields Z and W on M. The connection ∇ is said to be symmetric if the torsion tensor T vanishes, otherwise it is said to be non-symmetric. In this case, ∇ is said to be a semi-symmetric connection if its torsion tensor T is of the form $T(Z,W) = \eta(W)Z - \eta(Z)W$, for any Z,W, where η is a 1-form on M. Moreover, ∇ is called a metric connection if $\nabla g = 0$, otherwise it is called non-metric. It is well known that the Riemannian connection is the unique metric and symmetric linear connection on a Riemannian manifold (M,g) of dimension $n \ge 3$ endowed with a linear connection ∇ whose curvature tensor field is denoted by R, for any (0,k)-tensor field \tilde{W} on M, $k \ge 1$, the (0, k+2)-tensor field $R.\tilde{W}$ is defined by

$$(R.\tilde{W})(Z_1...,Z_k,Z,Y) = -\sum_{i=1}^k \tilde{W}(Z_1,...,Z_{i-1},R(Z,Y)Z_i,Z_{i+1},...,Z_k),$$
(1)

for any $Z, Y, Z_1, ..., Z_k \in \mathscr{X}(M)$. In this context, M is called semi-symmetric respect to ∇ if R.R = 0 and Ricci semi-symmetric if R.S = 0, where S is denoting the Ricci tensor field of ∇ . Moreover, M is said to be projectively semi-symmetric if R.P = 0, being P the Weyl projective curvature tensor field of ∇ , defined by

$$P(V,U)Z = R(V,U)Z - \frac{1}{n-1} \{S(U,Z)V - S(V,Z)U\}$$
(2)



(alternatively, P(V, U, Z, W) = g(P(V, U)Z, W)), for any $U, V, Z, W \in \mathscr{X}(M)$. For the Riemannian connection it is known that the semi-symmetry implies the Ricci semi-symmetry (for more details, [4, 14] and references therein can be consulted; specifically, for the contact geometry case we recommend the papers [9, 11, 15]).

In 1963, Yano [16] introduced the notion of *f*-structure on a C^{∞} *m*-dimensional manifold *M*, as a non-vanishing tensor field φ of type (1, 1) on *M* which satisfies $\varphi^3 + \varphi = 0$ and has constant rank *r*. It is known that *r* is even, say r = 2n. Moreover, *TM* splits into two complementary subbundles Im φ and ker φ and the restriction of φ to Im φ determines a complex structure on such subbundle. It is also known that the existence of an *f*-structure on *M* is equivalent to a reduction of the structure group to $U(n) \times O(s)$ [1], where s = m - 2n. In 1970, Goldberg and Yano [6] introduced globally frame *f*-manifolds (also called metric *f*-manifolds and *f*.pk-manifolds). A wide class of globally frame *f*-manifolds was introduced in [1] by Blair according to the following definition: a metric *f*-structure is said to be a *K*-structure if the fundamental 2-form Φ , defined usually as $\Phi(X,Y) = g(X,\varphi Y)$, for any vector fields *X* and *Y* on *M*, is closed and the normality condition holds, that is, $[\varphi, \varphi] + 2\sum_{i=1}^{s} d\eta^i \otimes \xi_i = 0$, where $[\varphi, \varphi]$ denotes the Nijenhuis torsion of φ . A *K*-manifold is called an *S*-manifold if $d\eta^k = \Phi$, for all $k = 1, \ldots, s$. The *S*-manifolds have been studied by several authors (see, for instance, [2, 3, 7, 10]).

The purpose of this paper is to link the three notions commented above by investigating semi-symmetry properties of *S*-manifolds endowed with certain quarter-symmetric metric connection naturally related with the *S*-structure. To this end, in Section 2 we give a brief introduction about *S*-manifolds. Section 3 is devoted to obtaining results on the curvature properties of S-manifold with Riemannian connection. In Section 4 we define a quarter-symmetric metric connection on an *S*-manifold, obtaining some general results and, in Section 5, we investigate the curvature and the Ricci tensor fields of such connection. Specially, we prove that an *S*-manifold has constant *f*-sectional curvature with respect to this quarter-symmetric metric connection. Consequently, the curvature of the quarter-symmetric metric connection is completely determined by its *f*-sectional curvature. Finally, in Section 6 we present the results concerning the semi-symmetry properties of the quarter-symmetric metric connection.

2. Preliminaries

A (2n+s)- dimensional differentiable manifold *M* is called a *metric f-manifold* if there exist an (1,1) type tensor field φ , *s* vector fields ξ_1, \ldots, ξ_s , *s* 1-forms η^1, \ldots, η^s and a Riemannian metric *g* on *M* such that

$$\varphi^2 = -I + \sum_{i=1}^s \eta^i \otimes \xi_i, \ \eta^i(\xi_j) = \delta_{ij}, \tag{3}$$

$$g(\varphi U, \varphi V) = g(U, V) - \sum_{i=1}^{s} \eta^{i}(U) \eta^{i}(V)$$

$$\tag{4}$$

for any $U, V \in \mathscr{X}(M)$, $i, j \in \{1, \dots, s\}$. In addition we have:

$$\varphi\xi_i = 0, \ \eta^i \circ \varphi = 0, \ \eta^i(U) = g(U,\xi_i). \tag{5}$$

Then, a 2-form Φ is defined by $\Phi(U,V) = g(U, \varphi V)$ for any $U, V \in \mathscr{X}(M)$ called the *fundamental 2-form*. In what follows, we denote by \mathscr{M} the distribution spanned by the structure vector fields ξ_1, \ldots, ξ_s and by \mathscr{L} its orthogonal complementary distribution. Then, $\mathscr{X}(M) = \mathscr{L} \oplus \mathscr{M}$. If $U \in \mathscr{M}$ we have $\varphi U = 0$ and if $U \in \mathscr{L}$ we have $\eta^i(U) = 0$, for any $i \in \{1, \ldots, s\}$, that is, $\varphi^2 U = -U$.

Moreover, a metric *f*-manifold is *normal* if

$$[\boldsymbol{\varphi},\boldsymbol{\varphi}]+2\sum_{i=1}^{s}d\boldsymbol{\eta}^{i}\otimes\boldsymbol{\xi}_{i}=0$$

where $[\varphi, \varphi]$ is denoting the Nijenhuis tensor field associated to φ . A metric *f*-manifold is said to be an *S*-manifold if it is normal and

$$\eta^1 \wedge \cdots \wedge \eta^s \wedge (d\eta^i)^n \neq 0$$
 and $\Phi = d\eta^i, \ 1 \leq i \leq s$.

Examples of S-manifolds can be found in [1, 2, 7].

Theorem 1. An *S*-manifold $(M, \varphi, \xi_i, \eta^i, g)$ satisfies the condition

$$(\nabla_U^* \varphi) V = \sum_{i=1}^s \{g(\varphi U, \varphi V) \xi_i + \eta^i(V) \varphi^2 U\}$$
(6)

for all $U, V \in \mathscr{X}(M)$, where ∇^* denotes the Riemannian connection with respect to g [2].

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From (6), we have

$$\nabla_U^* \xi_i = -\varphi U \tag{7}$$

for any $U \in \mathscr{X}(M)$, $i \in \{1, \ldots, s\}$.

Theorem 2. Let $(M, \varphi, \xi_i, \eta^i, g)$ be a (2n+s)-dimensional S-manifold. Then

$$R^{*}(U,V)\xi_{i} = \sum_{j=1}^{s} \{\eta^{j}(U)\varphi^{2}V - \eta^{j}(V)\varphi^{2}U\},$$
(8)

$$R^{*}(U,\xi_{i})V = -\sum_{j=1}^{s} \{g(\varphi U,\varphi V)\xi_{j} + \eta^{j}(V)\varphi^{2}U\}$$
(9)

for all $U, V \in \mathscr{X}(M)$, $i \in \{1, ..., s\}$, where R^* denotes the curvature of the Riemannian connection [3].

Corollary 3. Let $(M, \varphi, \xi_i, \eta^i, g)$ be a (2n+s)-dimensional S-manifold. Then

$$R^*(\xi_i, U, \xi_j, V) = -g(\varphi U, \varphi V), \tag{10}$$

$$K^*(\xi_i, U) = g(\varphi U, \varphi U), \tag{11}$$

$$S^{*}(U,\xi_{i}) = 2n \sum_{i=1}^{s} \eta^{i}(U)$$
(12)

for all $U, V \in \mathscr{X}(M)$, $i, j \in \{1, ..., s\}$, where K^* and S^* denote respectively the sectional curvature and the Ricci tensor field of the Riemannian connection [3].

Since, from (11), we have that $K^*(\xi_i, \xi_j) = 0$, for any $i, j \in \{1, ..., s\}$, an *S*-manifold can not have constant sectional curvature. For this reason, it is necessary to introduce a more restrictive curvature. In general, a plane section π on a metric *f*-manifold $(M, \varphi, \xi_i, \eta^i, g)$ is said to be an *f*-section if it is determined by a unit vector *U*, normal to the structure vector fields and φU . The sectional curvature of π is called an *f*-sectional curvature. An *S*-manifold is said to be an *S*-space-form if it has constant *f*-sectional curvature *c* and then, it is denoted by M(c). In such case, the curvature tensor field R^* of M(c) satisfies [10]:

$$R^{*}(U,V,K,L) = \sum_{i,j=1}^{s} \{g(\varphi U,\varphi L)\eta^{i}(V)\eta^{j}(K) - g(\varphi U,\varphi K)\eta^{i}(V)\eta^{j}(L) + g(\varphi V,\varphi K)\eta^{i}(U)\eta^{j}(L) - g(\varphi V,\varphi L)\eta^{i}(U)\eta^{j}(K)\} + \frac{c+3s}{4} \{g(\varphi U,\varphi L)g(\varphi V,\varphi K) - g(\varphi U,\varphi K)g(\varphi V,\varphi L)\} + \frac{c-s}{4} \{\Phi(U,L)\Phi(V,K) - \Phi(U,K)\Phi(V,L) - 2\Phi(U,V)\Phi(K,L)\}$$

$$U,U,K,L = \mathcal{O}(M)$$
(13)

for any $U, V, K, L \in \mathscr{X}(M)$.

3. Semi-Symmetry Properties of S-Manifolds Respect to the Riemannian Connection

With respect to the Riemannian connection ∇^* of an S-manifold $(M, \varphi, \xi_i, \eta^i, g)$, we can prove:

Theorem 4. Any semi-symmetric S-manifold $(M, \varphi, \xi_i, \eta^i, g)$ is an S-space-form of constant f-sectional curvature equal to s. *Proof.* Let $U \in \mathscr{L}$ be a unit vector field. Since $(M, \varphi, \xi_i, \eta^i, g)$ is semi-symmetric, then,

$$(R^*.R^*)(U,\xi_i,U,\varphi U,\varphi U,\xi_i)=0$$

for any $i, j \in \{1, ..., s\}$. Expanding this formula from (1) and taking into account (9), we get $R^*(U, \varphi U, \varphi U, U) = s$, which completes the proof.



Observe that, in the case s = 1, by using (10) we obtain that a semi-symmetric Sasakian manifold is of constant curvature equal to 1. This result was firstly proved by Takahashi (see [15]).

Theorem 5. Let $(M, \varphi, \xi_i, \eta^i, g)$ be a Ricci semi-symmetric S-manifold. Then, its Ricci tensor field S^{*} respect the Riemannian connection satisfies

$$S^{*}(U,V) = 2n\{sg(\varphi U,\varphi V) + \sum_{i,j=1}^{s} \eta^{i}(U)\eta^{j}(V)\}$$
(14)

for any $U, V \in \mathscr{X}(M)$.

Proof. Since $(M, \varphi, \xi_i, \eta^i, g)$ is Ricci semi-symmetric, then, by using (1),

 $S^{*}(R^{*}(U,\xi_{i})\xi_{j},V) + S^{*}(\xi_{j},R^{*}(U,\xi_{i})V) = 0$

for any $U, V \in \mathscr{X}(M)$ and $i, j \in \{1, ..., s\}$. Now, from (9) and (12) we get the desired result.

Corollary 6. Any Ricci semi-symmetric Sasakian manifold is an Einstein manifold.

Proof. Considering s = 1 in (14), we deduce $S^*(U, V) = 2ng(\varphi U, \varphi V) + \eta(U)\eta(V) = 2ng(U, V)$ for any $U, V \in \mathcal{X}(M)$.

For the Weyl projective curvature tensor field, we have the following theorem:

Theorem 7. Any projectively semi-symmetric S-manifold $(M, \varphi, \xi_i, \eta^i, g)$ is an S-space-form of constant f-sectional curvature equal to s.

Proof. Let $U \in \mathscr{L}$ a unit vector field. Then, from (2) and taking into account (9) and (10), we have

for any i, j = 1, ..., s and this completes the proof.

4. A Quarter-Symmetric Metric Connection on S-Manifolds

From now on, let *M* denote a (2n+s)-dimensional manifold $(M, \varphi, \xi_i, \eta^i, g)$. We define a new connection on *M* given by

$$\nabla_U V = \nabla_U^* V - \sum_{j=1}^s \eta^j(U) \varphi V \tag{15}$$

for any $U, V \in \mathscr{X}(M)$. It is easy to show that ∇ is a linear connection on *M*. Moreover, we can prove:

Theorem 8. Let M be an S-manifold. The linear connection ∇ defined in (15) is a quarter-symmetric metric connection on M.

Using (15) and taking into account that the Riemannian connection is free-torsion, the torsion tensor T of the connection ∇ is given by

$$T(U,V) = \sum_{j=1}^{s} \{ \eta^{j}(V) \varphi U - \eta^{j}(U) \varphi V \}$$
(16)

for any $U, V \in \mathscr{X}(M)$. Moreover, by using (15) again, we have, for all $U, V, Z \in \mathscr{X}(M)$ and since ∇^* is a metric connection, that:

$$(\nabla_U g)(V, Z) = \sum_{j=1}^{s} \eta^j(U) \{ g(\varphi V, Z) + g(V, \varphi Z) \}.$$
(17)

Proof. From (16) and (17) we conclude that the linear connection ∇ is a quarter-symmetric metric connection on M.

Example 9. Let us consider \mathbb{R}^{2n+s} with its standard S-structure given by [7]

$$\begin{split} \eta^{\alpha} &= \frac{1}{2} \left(dz^{\alpha} - \sum_{i=1}^{n} y^{i} dx^{i} \right), \ \xi_{\alpha} = 2 \frac{\partial}{\partial z^{\alpha}}, \\ g &= \sum_{\alpha=1}^{s} \eta^{\alpha} \otimes \eta^{\alpha} + \frac{1}{4} \left(\sum_{i=1}^{n} (dx^{i} \otimes dx^{i} + dy^{i} \otimes dy^{i}) \right), \\ \varphi \left(\sum_{i=1}^{n} (X_{i} \frac{\partial}{\partial x^{i}} + Y_{i} \frac{\partial}{\partial y^{i}}) + \sum_{\alpha} Z_{\alpha} \frac{\partial}{\partial z^{\alpha}} \right) = \sum_{i=1}^{n} (Y_{i} \frac{\partial}{\partial x^{i}} - X_{i} \frac{\partial}{\partial y^{i}}) + \sum_{\alpha=1}^{s} \sum_{i=1}^{n} Y_{i} y^{i} \frac{\partial}{\partial z^{\alpha}} \end{split}$$

where (x^i, y^i, z^{α}) , i = 1, ..., n and $\alpha = 1, ..., s$, are the cartesian coordinates. It is known that, with this structure, \mathbf{R}^{2n+s} is an S-space-form of constant f-sectional curvature c = -3s. If, following [7], we denote

$$(x^1, \dots, x^n, y^1, \dots, y^n, z^1, \dots, z^s) = (x^1, \dots, x^{2n+s})$$

the Christoffel symbols of the quarter-symmetric metric connection defined in (15) are given by

$$\Gamma^{b}_{ai} = \Gamma^{*b}_{ai} - \frac{1}{2}sy_i\delta_{ab}; \ \Gamma^{b}_{a\alpha} = \Gamma^{*b}_{a\alpha} + \frac{1}{2}\delta_{ab}$$

for any $a, b \in \{1, ..., 2n+s\}$, $i \in \{1, ..., n\}$ and $\alpha \in \{1, ..., s\}$, where Γ_{ai}^{*b} and $\Gamma_{a\alpha}^{*b}$ are denoting the Christoffel symbols of the Riemannian connection of \mathbf{R}^{2n+s} and the not-written symbols are the same as the Riemannian connection ones (see [7] for the details concerning them).

Corollary 10. Let M be an S-manifold. Then we have

$$\nabla_U \xi_i = -\varphi U \tag{18}$$

$$(\nabla_U \eta^i) W = g(U, \varphi W) = \Phi(U, W) \tag{19}$$

for any $U, W \in \mathscr{X}(M)$, $i \in \{1, \ldots, s\}$.

Proof. First, taking $W = \xi_i$ in (15), from (7) we have

$$abla_U \xi_i =
abla^*_U \xi_i - \sum_{j=1}^s \eta^j(U) \varphi \xi_i = - \varphi U.$$

Now, by using (5), (7) and (15) again:

$$\begin{aligned} (\nabla_U \eta^i)(W) &= U \eta^i(W) - \eta^i(\nabla_U W) \\ &= g(\nabla_U^* W, \xi_i) + g(W, \nabla_U^* \xi_i) - \eta^i(\nabla_U W) \\ &= g(\varphi W, U). \end{aligned}$$

Theorem 11. Let *M* be an *S*-manifold. Then, we have

$$(\nabla_U \varphi) V = \sum_{i=1}^s \{g(\varphi U, \varphi V) \xi_i + \eta^i(V) \varphi^2 U\}$$
(20)

for all $U, V \in \mathscr{X}(M)$.

Proof. From (15), we get:

$$(\nabla_U \varphi) V = (\nabla_U^* \varphi) V - \sum_{i=1}^s \eta^i(V) \varphi U.$$

Therefore, we obtain the result from (6).

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By using (3) and (20), we easily prove:

Corollary 12. Let M be an S-manifold. Then we have

$$(\nabla_U \varphi) \xi_i = -\varphi \nabla_U \xi_i = \varphi^2 U, \tag{21}$$

$$\nabla_{\xi_i} \varphi U = \varphi \nabla_{\xi_i} U \tag{22}$$

for all $U \in \mathscr{X}(M)$, $i \in \{1, \ldots, s\}$.

5. The Curvature of ∇

Let *M* be an *S*-manifold endowed with the quarter-symmetric metric connection ∇ defined in (15). From the Formula (3.2) in [1], denoting by *R* and *R*^{*} the curvature tensor fields of ∇ and ∇^* , respectively, we have that

$$R(U,L)W = R^{*}(U,L)W + \sum_{i=1}^{s} \eta^{i}(U) \{ (\nabla_{L} \varphi)W \} - \sum_{i=1}^{s} \eta^{i}(L) \{ (\nabla_{U} \varphi)W \} + 2sg(U,\varphi L)\varphi W$$
(23)

for all $U, L, W \in \mathscr{X}(M)$. From (8), (9) and (23), we get:

Corollary 13. Let M be an S-manifold. Then we have

$$R(U,V)\xi_i = 2\sum_{j=1}^{3} \{\eta^j(U)\varphi^2 V - \eta^j(V)\varphi^2 U\} = 2R^*(U,V)\xi_i,$$
(24)

$$R(U,\xi_i)V = -2\sum_{j=1}^{s} \left\{ g(\varphi U,\varphi V)\xi_j + \eta^j(V)\varphi^2 U \right\} = -2R^*(U,\xi_i)V,$$
(25)

$$R(U,\xi_j)\xi_i = R^*(U,\xi_j)\xi_i - \varphi^2 U = -2\varphi^2 U,$$
(26)

$$R(\xi_i,\xi_j)U = R^*(\xi_i,\xi_j)U = 0$$
⁽²⁷⁾

 $R(\xi_k,\xi_j)\xi_i = 0, \tag{28}$

for all $U, V \in \mathscr{X}(M)$, $i, j, k \in \{1, ..., s\}$.

Corollary 14. Let M be an S-manifold. Then

for any $U, V, K.L \in \mathscr{X}(M)$.

Corollary 15. Let M be an S-manifold. Then

$$R(\varphi U, \varphi V, \varphi L, \varphi K) = R^*(U, V, L, K) + 2sg(\varphi U, V)g(L, \varphi K)$$
⁽²⁹⁾

for any $U, V, L, W \in \mathscr{L}$.

Proof. It is a direct computation from (23) taking into account that [2]

$$R^*(\varphi U, \varphi V, \varphi L, \varphi K) = R^*(U, V, L, K)$$

for any $U, V, L, K \in \mathscr{L}$.

To consider the sectional curvature of the quarter-symmetric metric connection ∇ has no sense because, from (24) we have that $R(\xi_i, U, U, \xi_i) = g(R(\xi_i, U)U, \xi_i) = 2$, while from (26), $R(U, \xi_i, \xi_i, U) = g(R(U, \xi_i)\xi_i, U) = 1$, for any unit vector field $U \in \mathscr{L}$ and any $i \in \{1, \ldots, s\}$. However, the *f*-sectional curvature of ∇ is well defined, since, by using (23), we obtain that, for any unit vector field $U \in \mathscr{L}$:

$$R(U,\varphi U,\varphi U,U) = R^*(U,\varphi U,\varphi U,U) + 2s[g(U,U)]^2.$$

Consequently, taking into account (13), from (23) we prove the following theorem.

Theorem 16. Let *M* be an *S*-manifold. Then, the *f*-sectional curvature associated with the quarter-symmetric metric connection ∇ is constant if and only if the *f*-sectional curvature associated with the Riemannian connection is constant too. In this case, both constants are the same and the curvature of ∇ is given by

$$R(U,V,Z,W) = \sum_{i,j=1}^{s} \{g(\varphi^{2}V,W)\eta^{i}(U)\eta^{j}(Z) - g(\varphi^{2}U,W)\eta^{i}(V)\eta^{j}(Z) + 2g(\varphi V,\varphi Z)\eta^{i}(U)\eta^{j}(W) - 2g(\varphi U,\varphi Z)\eta^{i}(V)\eta^{j}(W)\} + \sum_{i,k=1}^{s} \{g(\varphi V,W)\eta^{i}(U)\eta^{k}(Z) - g(\varphi U,W)\eta^{k}(Z)\eta^{i}(V)\} + 2sg(U,\varphi V)g(\varphi Z,W) + \frac{c+3s}{4} \{g(\varphi U,\varphi W)g(\varphi V,\varphi Z) - g(\varphi U,\varphi Z)g(\varphi V,\varphi W)\} + \frac{c-s}{4} \{\Phi(U,W)\Phi(V,Z) - \Phi(U,Z)\Phi(V,W) - 2\Phi(U,V)\Phi(Z,W)\}$$
(30)

for any $U, V, Z, W \in \mathscr{X}(M)$.

With respect to the Ricci tensor field *S* of the connection ∇ we know that it is a symmetric tensor field. In fact, since $d\eta^i = \Phi$, for any $i \in \{1, ..., s\}$, from Formulas (3.4) and (3.14) in [1] we deduce that

$$S(K,L) = S(L,K) \tag{31}$$

for any $K, L \in \mathscr{X}(M)$, where dim(M) = 2n + s. Moreover,

$$S(U,V) = S^{*}(U,V) + 2s \sum_{k=1}^{2n} \{g(\varphi U, E_{k})g(\varphi V, E_{k})\} + sg(\varphi V, \varphi U)$$
(32)

for any $U, V \in \mathscr{X}(M)$. Therefore, by using (12):

Proposition 17. Let M be an S-manifold. Then, we have

$$S(U,\xi_i) = s\eta^i(U) + 2n\sum_{i=1}^s \eta^i(U)$$
(33)

for any $U \in \mathscr{X}(M)$, $i \in \{1, \ldots, s\}$.

Corollary 18. Let M be an S-manifold. Then we have

$$S(\xi_j,\xi_i) = s + 2n \tag{34}$$

for any $i, j = \{1, ..., s\}$.

Moreover, we can prove:



Proposition 19. Let M be an S-manifold. Then

$$S(\varphi U, \varphi V) = S(U, V) - 4s \sum_{i=1}^{s} g(U, \varphi E_i) g(V, \varphi E_i)$$

$$(35)$$

$$+2s\sum_{i=1}g(E_i,U)g(V,E_i)-2n\sum_{i,j=1}\eta^i(U)\eta^j(V)$$

for any $U, V \in \mathscr{X}(M)$.

Proof. Let $\{E_1, \ldots, E_n, \varphi E_1, \ldots, \varphi E_n, \xi_1, \ldots, \xi_s\}$ be an *f*-basis. Then, since from (25),

$$R(\xi_j, \varphi U, \varphi V, \xi_j) = R^*(\xi_j, \varphi U, \varphi V, \xi_j) + g(\varphi U, \varphi V)$$

for any $j \in \{1, ..., s\}$, then, by using (29), (14) and (32) taking into account that $U, V \in \mathcal{L}$, we deduce:

$$\begin{split} S(\varphi U, \varphi V) &= \sum_{i=1}^{n} \{ R(E_{i}, \varphi U, \varphi V, E_{i}) + R(\varphi E_{i}, \varphi U, \varphi V, \varphi E_{i}) \} + \sum_{j=1}^{s} R(\xi_{j}, \varphi U, \varphi V, \xi_{j}) \\ &= \sum_{i=1}^{s} \{ R^{*}(E_{i}, \varphi U, \varphi V, E_{i}) + R^{*}(\varphi E_{i}, \varphi U, \varphi V, \varphi E_{i}) \} + \sum_{j=1}^{s} R^{*}(\xi_{j}, \varphi U, \varphi V, \xi_{j}) \\ &+ 2s \sum_{i=1}^{s} \{ g(E_{i}, U)g(V, E_{i}) + g(\varphi E_{i}, U)g(V, \varphi E_{i}) \} + \sum_{j=1}^{s} g(\varphi U, \varphi V) \\ &= S^{*}(\varphi U, \varphi V) + 2s \sum_{i=1}^{s} \{ g(E_{i}, U)g(V, E_{i}) + g(\varphi E_{i}, U)g(V, \varphi E_{i}) \} + sg(\varphi U, \varphi V) \\ &= S(U, V) - 4s \sum_{i=1}^{s} g(U, \varphi E_{i})g(V, \varphi E_{i}) + 2s \sum_{i=1}^{s} g(E_{i}, U)g(V, E_{i}) - 2n \sum_{i,j=1}^{s} \eta^{i}(U)\eta^{j}(V). \end{split}$$

But, from (25) again,

$$R(\xi_j, U, V, \xi_j) = 2(\nabla_U \varphi) V$$

for any $j \in \{1, \dots, s\}$ and this completes the proof.

Corollary 20. Let M be an S-manifold. Then we have

$$S(X,Y) = S(\varphi X, \varphi Y) + 4n \sum_{i=1}^{s} \eta^{i}(X) \eta^{i}(Y)$$
(36)

for all $U, V \in \mathscr{X}(M)$.

Proof. We can put

$$U = U_0 + \sum_{i=1}^s \eta^i(U) \xi_i$$
 and $V = V_0 + \sum_{j=1}^s \eta^j(V) \xi_j$

where $U_0, V_0 \in \mathscr{L}$. Then, from (33) and (34):

$$S(U,V) = S(U_0,V_0) + 4n \sum_{i,j=1}^{s} \eta^i(U) \eta^j(V).$$
(37)

Now, by using (35), $S(U_0, V_0) = S(\varphi U_0, \varphi V_0) = S(\varphi U, \varphi V)$ and the proof is completed.



6. Semi-Symmetry Properties of an S-Manifold with Respect to ∇

For the quarter-symmetric metric connection defined in (15) on an S-manifold M we can prove:

Theorem 21. Let *M* be a (2n+s)-dimensional *S*-manifold, $n \ge 1$. If *M* is semi-symmetric respect to the quarter-symmetric metric connection ∇ then

$$R(U, \varphi U, \varphi U, U) = -2s$$

for any U is unit vector field on M.

Proof. If R.R = 0, then, from (1) we deduce that

$$R(R(U,\xi_i)U,\varphi U,\varphi U,\xi_j) + R(U,R(U,\xi_i)\varphi U,\varphi U,\xi_j)$$

$$+R(U,\varphi U,R(U,\xi_i)\varphi U,\xi_j) + R(U,\varphi U,\varphi U,R(U,\xi_i)\xi_j) = 0$$
(38)

for any unit vector field $U \in \mathscr{X}(M)$ and any i, j = 1, ..., s. By using (25) and (26), a direct expansion of (38) gives $R(U, \varphi U, \varphi U, U) = -2s$.

Moreover, we have:

Theorem 22. Let *M* be a (2n+s)-dimensional *S*-manifold, $n \ge 1$. If *M* is Ricci semi-symmetric respect to the quarter-symmetric metric connection ∇ then

$$S(Y,V) = 2nsg(\varphi Y, \varphi V) + 4n\sum_{\alpha,\beta=1}^{s} \eta^{\alpha}(Y)\eta^{\beta}(V)$$

for all $Y, V \in \mathscr{X}(M)$.

Proof. We take $X = \xi_i$ and $U = \xi_j$. Then, from (1) we have that

$$R(\xi_i, Y).S = S(R(\xi_i, Y)\xi_j, V) + S(\xi_j, R(\xi_i, Y)V)$$
(39)

for any unit vector field $Y \in \mathscr{X}(M)$ and any $i, j \in \{1, ..., s\}$. Now, by using (26) and (33)

$$S(R(\xi_i, Y)\xi_j, V) = -2S(Y, V) + 4n\sum_{\alpha, \beta=1}^{s} \eta^{\alpha}(Y)\eta^{\beta}(V)$$

$$\tag{40}$$

for all $V \in \mathscr{X}(M)$. Next, from (25) and (33) we have

$$S(\xi_j, R(\xi_i, Y)V) = 4nsg(\varphi Y, \varphi V).$$
⁽⁴¹⁾

The proof is completed.

Due to the above results, it is natural to consider the Weyl projective curvature tensor field of ∇ (see (2)). For this tensor field we obtain the following theorem.

Theorem 23. Let *M* be a (2n+s)-dimensional *S*-manifold *M* with $n \ge 1$. If *M* is projectively semi-symmetric respect to the quarter-symmetric metric connection ∇ then

$$S(Y,V) = 2nsg(\varphi Y, \varphi V) + 4n\sum_{\alpha,\beta=1}^{s} \eta^{\alpha}(Y)\eta^{\beta}(V)$$

for all $Y, V \in \mathscr{X}(M)$.

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Proof. From (1) we have that

$$(P(X,Y).S)(U,V) = P(X,Y).S(U,V) - S(P(X,Y)U,V) - S(U,P(X,Y)V)$$
(42)

If P(X,Y).S = 0, then we have

S(P(X,Y)U,V) + S(U,P(X,Y)V) = 0.

Therefore, if we calculate the latter equation we can obtain;

S(R(X,Y)U,V) + S(U,R(X,Y)V) = 0.

The proof is completed from the Theorem 6.2.

7. Conclusions

A quarter-symmetric metric connection is defined on S-manifolds. Some properties of the curvature and the Ricci tensor fields of such connection are obtained. In addition, an S-manifold has constant f-sectional curvature with respect to this quarter-symmetric metric connection if and only if has the same constant f-sectional curvature with respect to the Riemannian connection. Consequently, the curvature of the quarter-symmetric metric connection is completely determined by its f-sectional curvature. This topic is open and there are many issues to work on.

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