# COMMUNICATIONS 

# DE LA FACULTÉ DES SCIENCES DE L'UNIVERSITÉ D'ANKARA 

Série $A_{1}$ : Mathématiques

ALA MEMOIRE D'ATATÜRK AU CENTENAIRE DE SA NAISSANCE


The Effects Of Multicollinearity -A Geometric View-

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Faculté des Sciences de l'Université d'Ankara<br>Ankara, Turquie

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## DEDICATION TO ATATURK'S CENTENNIAL

Holding the torch that was lit by Atatürk in the hope of advancing our Country to a modern level of civilization, we celebrate the one hundredth anniversary of his birth. We know that we can only achieve this level in the fields of science and technology that are the wealth of humanity by being productive and creative. As we thus proceed, we are conscious that, in the words of Atatürk, "the truest guide'' is knowledge and science.

As members of the Faculty of Science at the University of Ankara we are making every effort to carry out scientific research, as well as to educate and train technicians, scientists, and graduates at every level. As long as we keep in our minds what Atatürk created for his Country, we can never be satisfied with what we have been able to achieve. Yet, the longing for truth, beauty, and a sense of responsibility toward our fellow human beings that he kindled within us gives us strength to strive for even more basic and meaningful service in the future.

From this year forward, we wish and aspire toward surpassing our past efforts, and with each coming year, to serve in greater measure the field of universal science and our own nation.

# The Effects Of Multicollinearity -A Geometric View- 

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(Received April 24, 1981; accepted July 15, 1981)

## SUMMARY

This paper considers the effects of multicollinearity on the multiple coefficient of determination and on the estimated regression coefficients

## 1. INTRODUCTION

Consider the equation

$$
\begin{equation*}
\underline{Y}=\underline{1} \beta_{o}+\mathbf{Z} \underline{\delta}+\underline{\underline{u}} \tag{1}
\end{equation*}
$$

where $\underline{Y}$ is a nxl vector of observations on the dependent variable, $\underline{1}$ is a nxl vector of unit elements, $Z=\left(\underline{Z}_{1}, \underline{Z}_{1}, \ldots, \underline{Z}_{p-1}\right)$ is $n x(p-1)$ matrix of observations on ( $\mathrm{p}-1$ ) nonstochastic regressors, $\delta$ is a ( $\mathrm{p}-1$ ) xl vector of unknown slope coefficients, $\beta_{o}$ is an unknown constant, and $\underline{u}$ is a nxl vector of disturbances. It is assumed that $\mathrm{E}(\underline{\underline{u}})=\underline{0}, E\left(\underline{\underline{u}} \underline{\underline{\prime}}^{\prime}\right)=\sigma^{2} \mathrm{I}$, $0<\sigma^{2}<\infty, X=(\underline{1}, Z)$ is a matrix of fixed elements, the rank of $\mathbf{X}$ is $\mathbf{p}$. Let $\underline{\beta}=\left(\beta_{o}, \underline{\delta}\right)$ ' The objective is to estimate $\beta$. The best linear unbiased estimate of $\beta$ is

$$
\begin{equation*}
\hat{\beta}=\left(\mathbf{X}^{\prime} \mathbf{X}\right)^{-1} \mathbf{X}^{\prime} \mathbf{Y} \tag{2}
\end{equation*}
$$

with

$$
\begin{equation*}
\operatorname{Var}(\hat{\beta})=\sigma^{2}\left(\mathbf{X}^{\prime} \mathbf{X}\right)^{-1} \tag{3}
\end{equation*}
$$

If the $\mathbb{Z}$ 's are higly multicollinear, the variance of $\hat{\beta}$ tends to become large, and little confidence can be placed in $\hat{\beta}$ as an estimate of $\underline{\beta}$.

In this paper, we use the definition of collinearity given by Silvey [9], in which collinearity is said to exist if there are one or more linear relationship between the predictor variables for each observation. Of
course, in practice collinearity is said to exists when the linear relationships hold only approximately. (see Mason, Gunst and Webster [7]. This problem has been discussed throughly in the excellent paper by Farrar and Glauber [1], who gave precise statistical procedures for detecting and localizing sources of collinearity within a given data set.

This paper considers the effects of multicollinearity on the multiple coefficient of determination from geometic viewpoint. Furthermore, the limiting cases are investigated of the estimated regression coefficients.

## 2. EFFECTS OF MULTICOLLINEARITY ON R ${ }^{2}$

The interpretation of the value of the multiple coefficient of determination, $\mathbf{R}^{2}$, is effected by multicollinearity. First, consider the estimated regression parameters and the partial correlation coefficients using the perpendicular projection operators to find the value $\hat{\beta}$ that $\operatorname{minimize} Q$, we write $Q$ as

$$
\mathbf{Q}=\|\underline{\mathbf{Y}}-\mathbf{X} \underline{\beta}\|^{2}
$$

and notice that $Q$ is the squared distance of $Y$ from [ $X$ ] the subspace of Euclidian n-space $E^{n}$ spanned by the columns of $X$. Minimizing $Q$ corresponds then to finding the point in [X] closest to $Y$. When $X$ has full column rank, then $X\left(X^{\prime} X\right)^{-1} X^{\prime}$ and $I-X\left(X^{\prime} X\right)^{-1} X^{\prime}$ are perpendicular projection operators onto the $[X]$ and $[X]^{\perp}$ respectively, where $[X]^{\perp}$ is the orthogonal complement of $[X]$, such that $R^{n}=[X] \oplus[X]^{\perp}$.

Now, let us assume that $r_{i j(p-3)}$ the partial correlation coefficient of $Z_{i}$ and $Z_{j}$ adjuisted for the remaining ( $p-3$ ) regressor variables is defined as

$$
\begin{equation*}
\mathbf{r}_{\mathbf{i j}(\mathbf{p}-3)}=\mathbf{z}_{\mathrm{i}} \mathbf{z}_{\mathbf{j}} /\left\|\mathbf{z}_{\mathbf{i}}\right\| \cdot\left\|\underline{z}_{j}\right\| \tag{4}
\end{equation*}
$$

where $\underline{z}_{i}=\left(\mathbf{I}-B\left(B^{\prime} B\right)^{-1} B^{\prime}\right) \underline{Z}_{i}, \underline{z}_{j}=\left(I-B\left(B^{\prime} B\right)^{-1} B^{\prime}\right) \underline{Z}_{j}$ and $B=(\underline{1}$, $\left.Z_{1}, Z_{2}, \ldots, Z_{i-1}, Z_{i+1}, \ldots, Z_{j-1}, Z_{j+1}, \ldots, Z_{p \ldots 1}\right)$. Applying the appropriate complementary perpendicular projection operators to $Z_{i}$ and $Z_{j}$, which yields the partial correlation coefficient $r_{i j(p-3)}$ as a direction cosine between the vectors $Z_{1}$ and $\underline{Z}_{j}$.

If one lets $\mathbf{B}=1$, then the partial correlation coefficient between the vectors $Z_{i}$ and $Z_{j}$ becomes the simple correlation coefficient, that is

$$
\begin{equation*}
r_{i j}=\left(Z_{i}-\underline{1} Z_{i}\right)^{\prime}\left(Z_{j}-\underline{1} Z_{j}\right) /\left\|Z_{i}-\underline{1} \underline{Z}_{i}\right\| \cdot\left\|Z_{j}-\underline{1} Z_{j}\right\| . \tag{5}
\end{equation*}
$$

where $\bar{Z}_{i}=1 / n \sum_{k=1}^{n} Z_{k_{i}}$ and $Z_{j}=1 / n \sum_{k=1}^{n} Z_{k_{j}}$. Thus, the simple correlation is the direction cosine between the perpendicuiar projections in $[\underline{l}]^{+}$. Where the perpendicular projection operator is

$$
\begin{equation*}
A=I_{n}-1 / n \underline{1} \underline{1}^{\prime} \tag{6}
\end{equation*}
$$

Multiplying the model (1) by matrix A, we get

$$
\begin{equation*}
\mathbf{A Y}=\mathbf{A} \underline{1} \beta_{0}+\mathbf{A} \underline{Z} \underline{\delta}+\mathbf{A u} \tag{7}
\end{equation*}
$$

or

$$
\underline{Y}-\underline{1} \mathbf{Y}=\left(\underline{Z}_{1}-\underline{1} \bar{Z}_{1}, \ldots, \mathbf{Z}_{p-1}-\underline{1} \bar{Z}_{p-1}\right) \underline{\delta}+\mathbf{A} \underline{u}
$$

If we wish to use the following deviations

$$
\tilde{\underline{Y}}=\underline{Y}-\underline{1} \bar{Y}, \tilde{Z}_{i}=Z_{i}-1 \bar{Z}_{i}, i=1,2, \ldots, p-1 \text { and } \underline{\tilde{u}}=A \underline{\mathbf{u}}, \text { we can }
$$ write equation (8) as follows:

$$
\tilde{\mathbf{Y}}=\left(\tilde{\mathbf{Z}}_{1}, \ldots, \tilde{\mathbf{Z}}_{\mathrm{p}-1}\right) \underline{\delta}+\underline{\tilde{\mathbf{u}}}
$$

or

$$
\begin{equation*}
\underline{\tilde{Y}}=\tilde{\mathrm{Z}} \underline{\delta}+\underline{\hat{u}} . \tag{9}
\end{equation*}
$$

Let us define the following simple functions of the normalized vectors:

$$
\begin{aligned}
& \underline{Y}^{*}=1 / \sqrt{\mathbf{n - 1}} . \underline{\tilde{Y}} / S_{Y}=\underline{\tilde{Y}} /\|\underline{\mathbf{Y}}\|, Z^{*}{ }_{i}=\tilde{Z}_{i} / \sqrt{n-1} . S_{x_{1}}=\tilde{\mathbf{Z}}_{i} /\left\|Z_{i}\right\| \\
& i=1, \ldots, p-1 \text { where } S^{2}=1 /\left(n_{-1}\right) \sum_{k=1}^{n}\left(y_{1}-Y\right)^{2} \text { and } S_{z_{i}}^{2}=1 /(n-1) \sum_{k=1}^{n} \\
& \left(Z_{k_{i}}-\bar{Z}_{i}\right)^{2}, i=1, \ldots, p-1 \text {. Hence, we have } \\
& \underline{Y}^{*}=\delta_{1} S_{\mathbf{z}_{1}} / \mathrm{S}_{\mathbf{Y}} \underline{Z}_{1}^{*}+\ldots+\delta_{\mathfrak{p}-1} \mathrm{~S}_{\mathbf{z}_{\mathfrak{p}-1}} / \mathrm{S}_{\mathbf{Y}} \cdot \mathbf{Z}_{\mathbf{p}-1}^{*}+\underline{\mathbf{u}}^{*} \\
& \text { or }
\end{aligned}
$$

$$
\begin{equation*}
\underline{\mathbf{Y}}^{*}=\mathbf{Z}^{*} \underline{\hat{\delta}}^{*} \tag{10}
\end{equation*}
$$

where

$$
\widehat{\delta}_{1} . S_{z_{i}} / S_{Y}=\widehat{\delta}_{i}^{*}, i=1,2, \ldots, p-1 \text { and } Z_{i}^{* \prime} Z_{j}^{*}=r_{i j}
$$

On the other hand, let us consider the following matrices

$$
\begin{equation*}
\mathbf{R}^{*}=\left(\underline{\mathbf{Y}}^{*}, \mathbf{Z}^{*}, \ldots, \underline{\mathbf{Z}}^{*}{ }_{p-1}\right)^{\prime}\left(\underline{\mathbf{Y}}^{*}, \mathbf{Z}_{1}^{*}, \ldots, \mathbf{Z}_{p-1}^{*}\right) \tag{11}
\end{equation*}
$$

and

$$
\begin{equation*}
\mathbf{R}_{11}=\mathrm{Z}^{* \prime} \cdot \mathrm{Z}^{*} \tag{12}
\end{equation*}
$$

where $R^{*}$ is the (symmetric) correlation matrix and $R_{11}$ is the submatrix of $\mathbf{R}^{*}$ formed by deleting the first row and first column of $\mathbf{R}^{*}$. Furthermore, we get

$$
\begin{equation*}
\widehat{\delta}_{i}^{*}=(-1)^{i-1}\left|\mathbf{R}_{1_{(i+1)}}\right| /\left|\mathbf{R}_{11}\right| \quad \mathbf{i}=1, \ldots, p-1 \tag{13}
\end{equation*}
$$

and

$$
\begin{equation*}
\mathbf{R}^{2}=1-|\mathbf{R}| /\left|\mathbf{R}_{11}\right| . \tag{14}
\end{equation*}
$$

(see for example Johnson [4]).
Now, consider the multiple coefficient of determination, $R^{2}$, that is,

$$
\mathbf{R}^{2}=\sum_{j=1}^{\mathrm{n}}\left(\hat{\mathbf{y}}_{j}-\overline{\mathbf{Y}}\right)^{2} / \sum_{j=1}^{\mathrm{n}}\left(\mathrm{y}_{\mathrm{j}}-\overline{\mathbf{Y}}\right)^{2}=\|\underline{\mathbf{Y}}-\underline{\mathbf{Y}}\|^{2} /\|\underline{\mathbf{Y}}-\underline{1} \overline{\mathbf{Y}}\|^{2} .
$$

Then, $\mathbf{R}^{2}$ can be expressed as:

$$
\begin{align*}
& \mathbf{R}^{2}=\|\underline{\hat{Y}}-\underline{\underline{\mathbf{Y}}}\|^{2} / \underline{\mathbf{Y}}-\underline{\mathbf{1}} \underline{\mathbf{Y}}\left\|^{2}=\right\| \mathbf{A} \underline{\hat{\mathbf{Y}}}\left\|^{2} /\right\| \mathbf{A} \underline{\mathbf{Y}}\left\|^{2}=\right\| \underline{\hat{\mathbf{Y}}}\left\|^{2}\right\| \underline{\tilde{\mathbf{Y}}} \|^{2} \\
& =(\cos \theta)^{2} . \tag{15}
\end{align*}
$$

(see Figure 1)


Fig 1

It there exist a multicollinearity among the vectors $Z_{1}, Z_{2}, \ldots, Z_{K}$, $K \leq p-1$, then $Z_{1}, Z_{2}, \ldots, Z_{K}$ are approximately near the hyperplane. From this explanation, we observe that $R^{2} z_{i}$ is close to 1 , where $R^{2} z_{i}$ ( $i \leq K$ ) is the squared multiple correlation of $Z_{i}$ and other independent variables $Z_{1}, Z_{2}, \ldots, Z_{i+1}, Z_{i}, \ldots, Z_{p-1}$. Thes, this implies that Marquardt's [6] variance inflation factor $\left(1-R^{2} Z_{i}\right)^{-1}$ is very large. Where $\left(1-R^{2} Z_{i}\right)^{-1}$ is the $i^{\text {th }}$ diagonal element of $\mathbf{R}_{11}^{-1}$.

## 3. TWO REGRESSOR VARIABLES

When $p-1=2$, then the expression for the coefficient of determination with two independent variables is

$$
\begin{equation*}
\mathbf{R}^{2}=\left(\mathbf{r}_{y^{1}}^{2}+\mathbf{r}_{\mathrm{y}_{2}}^{2}-2 \mathbf{r}_{\mathrm{y} 1} \mathbf{r}_{\mathrm{y}_{2}} \mathbf{r}_{12}\right) /\left(1-\mathbf{r}_{12}^{2}\right) \tag{16}
\end{equation*}
$$

Fox and Cooney [2] and Fox [3] are concerned numerically the effects of multicollinearity for the case of two independent variables on the coefficient of determination for any particular values of $r_{y_{1}}$ and $r_{y 2}$. For the case of two independent variables, the multiple correlation coefficient of determination is shown graphically as a function of the pairwise correlation coefficient and the intercorrelation of the independent variables by Weber and Monarchi [10], see Figure 2.


Fig 2

$$
\begin{aligned}
& \text { A: } r_{y_{1}}=0.5 r_{y 2}=-0.5 \\
& \text { B: } r_{y_{1}}=0.1 r_{y_{2}}=0.3 \\
& \text { C: } \mathbf{r}_{y_{1}}=0.8 \mathbf{r}_{y_{2}}=0.6
\end{aligned}
$$

In this section, we would like to investigate from a geometric viewpoint, the variation of $R^{2}$, over the range $[0,1]$. Note that $R^{2}$ is bounded over the range $[0,1]$. For the special case of two explanatory variables, geometric represantations are shown in Figures 3A and 3B.


Fig 3 A


Fig 3 B

CASE A: $\mathbf{r}_{\mathrm{y} 1}=0.5$ and $\mathbf{r}_{\mathrm{y}_{2}}=-0.5$
Let $\theta_{2}$ be the angle between the two vectors $\underline{\tilde{Y}}$ and $\tilde{\mathbb{Z}}_{1}$. Then $\cos \theta_{1}=1 / 2$ and $\theta_{1}=60^{\circ}$. Let $\theta_{2}$ be the angle between the two vectors $\underline{\tilde{Y}}$ and $\tilde{\mathbb{Z}}_{2}$. Then $\cos \theta_{2}=-1 / 2$ and $\theta_{2}=120^{\circ}$. Let $\theta$ be the angle between the two vectors $\tilde{Z}_{1}$ and $\tilde{Z}_{2}$, and hence $\theta_{2}-\theta_{1} \leq \theta \leq \theta_{2}+\theta_{1}$. When $\theta$ is varied over its possible range $60^{\circ} \leq \theta \leq 180^{\circ}$; then the value of $r_{12}$ is restricted to the range $-1 \leq r_{12} \leq 0.5$. If $r_{12}$ attains its minimum at the lower limit of its permissible range then the estimation space. $\left[\tilde{Z}_{1}, \tilde{\mathbb{Z}}_{2}\right]$ is a line spanned by the vectors $\tilde{Z}_{1}$ or $\tilde{Z}_{2}$. Thus, we get $\mathbf{R}^{2}=\left(\cos \theta_{1}\right)^{2}=0.25$. Furthermore, $\mathbf{r}_{12}$ has its greatest numerical value for $\theta=60^{\circ}$. For this case, since $\tilde{\mathbf{Y}}$ will be in the estimation space, then the value of $R^{2}$ becomes 1 . While $r_{12}$ varies over its possible range, $-1 \leq r_{12} \leq 0.5, R^{2}$ varies over the range $[0.25,1]$. (see Figure 3A)

CASE B: $\mathrm{r}_{\mathrm{y}_{1}}=0.1$ and $\mathrm{r}_{\mathrm{y}_{2}}=0.3$
For this case, we have $\theta_{1}$ and $\theta_{2}$ equal to $84^{\circ} 16^{\prime}$ and $72^{\circ} 33^{\prime}$ respectively. Since $\theta$ varied over the range $\left[11^{\circ} 43^{\prime}, 156^{\circ} 49^{\prime}\right]$, so $\mathrm{r}_{12}$ varies over the range $[-0.9191,0.9791]$.

If we start from the upper limit of the range, namely $r_{12}=0.9791$ and $\theta=11^{\circ} 44^{\prime}, \tilde{\mathbf{Z}}_{2}$ will be in the position 1 . (see Figure 3 B )

Since $\underline{Y}$ is in the estimation space (plane), then $R^{2}=1$. For $r_{12}$ $=-0.9191$ or $\theta=156^{\circ} 49^{\prime}, \tilde{\underline{Z}}_{2}$ will be in position 3 , and $R^{2}$ will be equal to 1 . As $\widetilde{Z}_{2}$ moves from position 1 to position $2, R^{2}$ will decrease, and when it moves from position 2 to position $3, \mathbf{R}^{2}$ will increase.

When $R^{2}$ reaches its minimum value at position 2 , the regression coefficient of a variable, which has a weak correlation with $\underline{\tilde{Y}}$, will vanish and change sign.

## 4. EFFECTS OF MULTICOLLINEARITY ON THE ESTIMATED REGRESSION COEFFICIENTS

Let us assume that variables $Z_{1}$ and $Z_{2}$ are intercorrelated but that all other explanatory variables have zero correlations with each other and with $Z_{1}$ and $Z_{2}$. Then, from equation (13), we have

$$
\begin{equation*}
\hat{\delta}^{*}=\left(r_{y 1}-r_{y 2} r_{12}\right) /\left(1-r_{12}^{2}\right) \tag{17}
\end{equation*}
$$

and

$$
\begin{equation*}
\hat{\mathrm{J}}_{2}^{*}=\left(\mathbf{r}_{\mathrm{y} 2}-\mathbf{r}_{\mathrm{y}_{1}} \mathbf{r}_{12}\right) /\left(\mathbf{l}-\mathbf{r}_{12}^{2}\right) \tag{18}
\end{equation*}
$$

Let us rewrite the expression for $\hat{\delta}^{*}{ }_{1}$ as (see Klein and Nakamura [5]

$$
\begin{aligned}
& \widehat{\boldsymbol{\delta}}_{1}^{*}=\left(\mathbf{r}_{\mathrm{y}^{1}}-\mathbf{r}_{\mathrm{y} 2}\right) /\left(\mathbf{1}+\mathrm{r}_{12}\right)\left(1-\mathbf{r}_{12}\right)+\mathbf{r}_{\mathrm{y} 2} /\left(\mathbf{1}+\mathbf{r}_{12}\right) \\
& \begin{aligned}
= & \left(\underline{Y}^{{ }^{\prime} \prime} \underline{Z}^{*}{ }_{1}-\underline{Y}^{* \prime} \mathbf{Z}^{*}{ }_{2}\right) /\left(\mathbf{I}+\mathbf{r}_{12}\right)\left(\mathbf{Z}^{* \prime}{ }_{1} \mathbf{Z}^{*}-\mathbf{Z}^{*}{ }_{1}^{\prime} \mathbf{Z}^{*}{ }_{2}\right)+\mathbf{r}_{\mathbf{y} 2} / \\
& \left(\mathbf{I}+\mathbf{r}_{12}\right)
\end{aligned} \\
& =\underline{\mathbf{Y}}^{* \prime}\left(\underline{Z}^{*}{ }_{1}-\underline{Z}_{2}^{*}\right) /\left(\mathbf{1}+\mathbf{r}_{12}\right) \underline{Z}^{*}{ }_{1}{ }^{\prime}\left(\underline{Z}^{*}{ }_{1}-\underline{Z}^{*}{ }_{2}\right)+\mathbf{r}_{y_{2}} /\left(\mathbf{l}+\mathbf{r}_{12}\right) .
\end{aligned}
$$

Divide the numerator and denominator of the first term on the right by $\left\|\underline{Z}_{1}{ }_{1}-\underline{Z}^{*}{ }_{2}\right\|$. We have

$$
\begin{equation*}
\hat{\delta}^{*}{ }_{1}=r_{y(1-2)} /\left(1+\mathbf{r}_{12}\right) r_{1(1-2)}+r_{y 2} /\left(1+r_{12}\right) \tag{20}
\end{equation*}
$$

Similarly, we obtain

$$
\begin{equation*}
\hat{\delta}^{*}{ }_{2}=-\mathbf{r}_{\mathbf{y}(1-2)} /\left(1+\mathbf{r}_{12}\right) \mathbf{r}_{1(1-2)}+\mathbf{r}_{\mathrm{y}_{1}} /\left(1+\mathbf{r}_{12}\right) \tag{21}
\end{equation*}
$$

where $\mathrm{r}_{(1(-2)}$ is the correlation between $\mathrm{Y}^{*}$ and $\mathrm{Z}^{*}{ }_{1}-\mathrm{Z}_{2}^{*}$, and $\mathbf{r}_{(1-2)}$ is the correlation between $Z^{*}{ }_{1}$ and $Z^{*}{ }_{1}-Z^{*}{ }_{2}$.

When $\mathrm{r}_{12} \rightarrow 1$, the measure of the angle between the vectors $\underline{Z}^{*}{ }_{1}$ and $\underline{Z}_{2}^{*}$ approaches zero. Then, the measure of the angle between the vectors $Z^{*}{ }^{*}, \underline{Z}^{*}-\underline{Z}_{2}^{*}$ approaches $90^{\circ}$, thus $\mathrm{r}_{1(1-))}$ necessarily approaches zero as $\mathrm{r}_{12} \rightarrow \mathrm{l}$.

In equations (20) and (21), the numerator, $\mathbf{r}_{\mathrm{y}(1-2)}$ may approaches to either zero or a nonzero value depending on the given vector $\underline{Y}^{*}$ and the direction in wich $\underline{\underline{Z}}^{*}{ }_{1}$ approaches $\underline{Z}_{2}{ }_{2}$.

If $r_{y 1}=r_{y 2}$, then the value of $r_{12}$ is resticted to the range [ $2 r^{2}{ }_{y 1}-1$, 1] by the condition $\mathbf{R}^{2} \leq 1$. Hence, from equations (20) and (21), we get the limiting values of $\hat{\delta}_{1}{ }^{*}$ and $\hat{\delta}^{*}{ }_{2}$ as

$$
\lim _{\mathbf{r}_{12} \rightarrow 1} \hat{\delta}_{1}^{*}{ }_{1}=\lim _{\mathbf{r}_{12} \rightarrow 1} \hat{\delta}^{*}{ }^{2}=\mathbf{r}_{\mathrm{y}_{1}} / 2=\mathbf{r}_{\mathrm{y} 2} / 2 .
$$

(see for example Sastry [8])
When $\mathbf{r}_{\mathrm{y}^{1}}=\mathbf{r}_{\mathrm{y}_{2}}$, the perpendicular projection, $\hat{\mathrm{Y}}^{*}$ of $\mathrm{Y}^{*}$ can be written as a linear combination of the vectors $Z^{*}$, and $\underline{Z}^{*}{ }_{2}$ (see Figure 4A) that is, $\underline{\hat{Y}}^{*}=\hat{\delta}^{*} \underline{Z}_{\underline{Z}}{ }^{*}+\hat{\delta}^{*}{ }_{2} \underline{\underline{Z}}^{*}{ }_{2}$. In the limiting case, we get

$$
\begin{aligned}
& \mathrm{r}_{12} \rightarrow 1 \quad \mathrm{r}_{12} \rightarrow \mathrm{l}
\end{aligned}
$$

When $r_{y 1} \neq r_{y_{2}}\left(\right.$ but $r_{y 1} \rightarrow r_{y 2}$ ), while $r_{12}$ approaches its maximum positive value over the possible range, in other words, while the vector $\mathbb{Z}^{*}{ }_{z}$ moves from position 2 to position 1, (see Figure 4B) then absolute value of each of the estimated regression coefficients, $\delta^{*}{ }_{1}$ and $\delta^{*}{ }_{2}$, will be large and in opposite signs.


Fig 4 A


Fig 4 B

## 5. CONCLUSIONS

This paper has attempted to disclose to the users of regression procedures a better understanding of the limitations of ordinary least squares when multicollinearity is present in the data. Hence, geometric representations are helpful in revealing the sources of collinearity. The results of this paper show that, in general, the multiple coefficient of determination is not monotonic function of the multicollinearity for fixed pairwise correlations.

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## OZET

Bu çalışmada iç ilişkinin çoklu belirleyicilik katsayısı ve kestirilmiş regresyon katsayıları üzerindeki etkileri araşturlmıştır. Dik izdüş̈̈mler yardımyla kusmi korelasyon katsayları araemdaki bağıntılar incelenmiştir.

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