

## LORENTZIAN CIRCLE AS A LIE GROUP AND A $C^\infty$ ACTION ON LORENTZ SPACES OF TWO DIMENSION

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### ABSTRACT

We define a product on Lorentz circle that is similar to Lorentzian inner product. This product is expanded to Lorentz space of two dimension. So we have an  $C^\infty$  action of Lorentz circle on Lorentz space of two dimension. It is noted that this action provides some isometrics of  $L^2$ .

### 1. INTRODUCTION

A Lie group  $G$  is a group which has the structure of a differentiable manifold and for which the group function

$$\circlearrowleft : G \times G \longrightarrow G$$

defined by  $\circlearrowleft(g_1, g_2) = g_1 g_2$  is differentiable. Given an element  $a$  of a Lie group  $G$ , the function  $L : G \rightarrow G$  defined  $g \rightarrow ag$  is called left translation. A Lie group  $G$  is said to act on a differentiable manifold  $M$  as Lie transformation group if we are given a global surjection

$$\phi : G \times M \rightarrow M$$

which is differentiable such that if  $g, h \in G$  and  $m \in M$

$$\phi(g, \phi(h, m)) = \phi(gh, m)$$

$G$  is said act transitively on  $M$  if, given any two points  $m_1, m_2 \in M$  there is an element  $g \in G$  such that  $m_2 = gm_1$ .

By a transformation of a manifold  $M$ , we mean a diffeomorphism of  $M$  onto itself. A group  $G$  is said to act on  $M$  as a transformation group. If there is a global function

$$\phi : G \times M \rightarrow M$$

such that

- i) the function  $\phi_g$ , defined for any given  $g \in G$  by  $m \rightarrow \phi(g, m)$  is a transformation of  $M$ ,
- ii) if  $g, h \in G$ ,  $\phi_g \circ \phi_h = \phi_{gh}$ .

Suppose that  $e$  is the unit element of  $G$ , then  $\phi_e$  is the identity element on  $M$ , for if  $m \in M$  and  $m' = (\phi_e - 1)_m$ . The group is said to act effectively on  $M$  if  $e$  is the only element of  $G$  such that  $\phi_g m = m$  for all  $m \in M$ . It is said to act freely on  $M$  if  $e$  is the only element of  $G$  such that  $\phi_g m = m$  for some  $M$ .

A transformation group  $G$  acting on a manifold  $M$  sets up an equivalence relation on  $M$ . The equivalence class containing a point  $m$  is the range of the function  $\phi_m : G \rightarrow M$  and we call it the orbit of  $m$  [1].

We will denote Lorentzian circle on  $L^2$  by  $L_1^1$ . In this study, it was shown that  $L_1^1$  is a Lie group with a binary operation defined on  $L^1$  as hypercylindrical product defined by [3]. A  $C^\infty$ -action on  $L^2$  of this Lie group is defined and some properties of it were given. Finally, with the help of this  $C^\infty$ -action some isometries of  $L^2$  were obtained.

### 1.1 LORENTZ MANIFOLDS, LORENTZ VECTOR SPACES AND LORENTZ CIRCLE

A metric tensor  $g$  on a differentiable manifold  $M$  is a symmetric nondegenerate  $(0,2)$  tensor field on  $M$  of constant index. A semi-Riemannian manifold is a differentiable manifold  $M$  furnished with a metric tensor  $g$ . Thus a semi-Riemannian manifold is an ordered pair  $(M, g)$ .

The common value  $\nu$  of index  $g_p$  on a semi-Riemannian manifold  $M$  is called the index of  $M$  satisfying  $0 \leq \nu \leq n = \dim M$ . If  $\nu = 0$ ,  $M$  is a Riemannian manifold since each  $g_p$  is an (positive definite) inner product on  $T_p(M)$ . If  $\nu = 1$  and  $n \leq 2$ ,  $M$  is Lorentz manifold.

In this study,  $v$  will take the values 1 and 2, and  $L^2$  will denote a Lorentz manifold of two dimension. So, the metric tensor is defined by

$$\langle X, Y \rangle_L = x_1 y_1 - x_2 y_2$$

or

$$\langle X, Y \rangle_L = \langle X, Y_s \rangle_E$$

where  $Y_s$  is symmetry of  $Y$  according to the  $x$ -axes and  $X = (x_1, x_2)$ ,  $Y = (y_1, y_2)$  [4].

## 2 LIE GROUP STRUCTURE OF $L_1^1$

We define a binary operation on  $L_1^1$  by

$$\odot : L_1^1 \times L_1^1 \longrightarrow L_1^1$$

$$\odot (X, Y) = (\langle X, Y \rangle_E, \langle X, Y_s \rangle_E)$$

where  $\langle \cdot, \cdot \rangle_E$  is Euclidean inner product and  $Y_s$  is symmetry of  $Y \in \mathbb{R}^2$  according to the straight line  $y = x$ . We have, the following

**Theorem 1.** The system  $(L_1^1, \odot)$  is a commutative group.

**Proof.** For all  $X, Y \in L_1^1$ ,

1.  $\odot (X, Y) \in L_1^1$ ,
2.  $\odot (X, Y) = (x_1 y_1 + x_2 y_2, x_1 y_2 + x_2 y_1)$   
 $= (x_1 y_1 + x_2 y_2, y_1 x_2 + y_2 x_1)$   
 $= \odot (Y, X)$

3.  $e = (1, 0)$  is the identity element

4. The inverse element of  $X = (x_1, x_2)$  is  $(x_1 - x_2)$ .

By Theorem 1,  $L_1^1$  becomes a Lie group since  $L_1^1 \subset \mathbb{R}^2$  is a differentiable submanifold, and the symmetry function and the inner product are differentiable functions.

For  $r \in \mathbb{R}^+$ , we define the set  $L_r^1$  as

$$L_r^1 = \{(x, y) \in L^2 \mid x^2 - y^2 = r^2\}$$

and action  $\theta : L_1^1 \times L_r^1 \rightarrow L_r^1$ ,  $\theta((x_1, x_2), (y_1, y_2)) = (x_1 y_1 + x_2 y_2, x_1 y_2 + x_2 y_1)$ .

**Theorem 2.**  $L_1^1$  acts transitively on  $L_r^1$ .

**Proof.** For  $p, q \in L_r^1$  we can define an element  $X = (x_1, x_2)$  where

$$x_1 = \frac{\langle p, q \rangle}{r^2} \quad \text{and} \quad x_2 = \frac{\langle p, q_s \rangle}{r^2}.$$

Then, it is clear that  $X \in L_1^1$  and

$$\theta(X, Q) = P$$

This completes the proof.

For  $X \in L_r^1, (\theta)_x$  the orbit of  $X$  under the action  $\theta$  is  $L_r^1$ .

**Theorem 3.**  $L_1^1$  acts effectively on  $L_1^1$ .

**Proof.** We have to show that for all  $m \in L_1^1$  the equation  $\theta(g, m) = m$  is satisfied only for  $g=e$ . In fact

$$\theta(g, m) = m \Rightarrow g_1 m_1 + g_2 m_2 = m_1$$

$$g_1 m_2 + g_2 m_1 = m_2$$

$$\Rightarrow g_1 = \frac{\det \begin{bmatrix} m_1 & m_2 \\ m_2 & m_1 \end{bmatrix}}{r^2} = 1$$

$$g_2 = \frac{\det \begin{bmatrix} m_1 & m_1 \\ m_2 & m_2 \end{bmatrix}}{r^2} = 0$$

so  $g = e$ .

### 3. THE SET $\tilde{L}_r^1$

We define the set  $\tilde{L}_r^1$  as

$$\tilde{L}_r^1 = \{(x, y) \mid y^2 - x^2 = r^2\}$$

so we can define an action

$$\bar{O} : \tilde{L}_r^1 \times \tilde{L}_r^1 \longrightarrow \tilde{L}_r^1$$

$$\bar{O}(X, Y) = (\langle X, Y \rangle_E, \langle X, Y_S \rangle_E)$$

In this case, we evidently have;

1.  $(\tilde{L}_r^1, \bar{O})$  is a commutative group
2.  $\tilde{L}_r^1$  is a Lie group

3.  $\tilde{L}_r^1$  acts on  $\tilde{L}_r^1$  as a Lie transformation group with the function  $\tilde{\theta}$  defined by  $\tilde{\theta}(g, X) = (\langle g, X \rangle_E, \langle g, X_S \rangle_E)$
4.  $\tilde{L}_r^1$  acts transitively on  $\tilde{L}_r^1$
5.  $\tilde{L}_r^1$  acts effectively on  $\tilde{L}_r^1$
6.  $(\tilde{\theta})_X = \tilde{L}_r^1$ , where  $X \in \tilde{L}_r^1$

### 3.1. AN ACTION ON $L^2$

For all  $X = (x_1, x_2) \in L^2$ , we have

$$x_1^2 - x_2^2 = r^2 \quad \text{or} \quad x_2^2 - x_1^2 = r^2$$

where  $r \in \mathbf{R}^+ \cup \{0\}$ . So, we write

$$\left(\bigcup_r L_r^1\right) \cup \left(\bigcup_r \tilde{L}_r^1\right) \supseteq L^2.$$

Then, we conclude

**Theorem 4.**  $L_1^1$  acts on  $L^2$  as a Lie transformation group with the function  $\theta'$  defined by

$$\theta'(X, Y) = \begin{cases} \theta(X, Y), & \text{if } y_1 \geq y_2 \\ \tilde{\theta}(X, Y), & \text{if } y_1 < y_2 \end{cases}$$

For all  $p \in L^2$ , the orbit of  $p = (p_1, p_2)$  under  $\theta'$  is

$$(L_1^1)_{(p)} = \begin{cases} L_r^1, & p_1 \geq p_2 \\ \tilde{L}_r^1, & p_1 < p_2 \end{cases}.$$

Also, for all  $g \in L^2$  the mappings  $\theta'_g : L^2 \longrightarrow L^2$  defined by

$$\theta'_g(X) = \theta'(g, X)$$

are diffeomorphisms.

**Theorem 5.** The mappings  $\theta'_g$  are isometrics of  $L^2$ .

**Proof.** Let  $X = (x_1, x_2)$ ,  $Y = (y_1, y_2) \in L^2$  and  $g = (g_1, g_2) \in L_1^1$ . Thus

$$d_L(\theta'_g(X), \theta'_g(Y))^2 = d_L[(\langle g, X \rangle, \langle g, X_S \rangle), (\langle g, Y \rangle, \langle g, Y_S \rangle)]^2$$

$$\begin{aligned}
&= (\langle g, X \rangle - \langle g, Y \rangle)^2 - (\langle g, X_S \rangle, \langle g, Y_S \rangle)^2 \\
&= \langle g, X - Y \rangle^2 - \langle g, X_S - Y_S \rangle^2 \\
&= (g_1(x_1 - y_1) + g_2(x_2 - y_2))^2 - (g_1(x_2 - y_2) + g_2(x_1 - y_1))^2 \\
&= g_1^2(x_1 - y_1)^2 + g_2^2(x_2 - y_2)^2 + 2g_1g_2(x_1 - y_1)(x_2 - y_2) \\
&\quad - g_1^2(x_2 - y_2)^2 - g_2^2(x_1 - y_1)^2 - 2g_1g_2(x_2 - y_2)(x_1 - y_1) \\
&= (g_1^2 - g_2^2)(x_1 - y_1)^2 - (g_1^2 - g_2^2)(x_2 - y_2)^2 \\
&= (x_1 - y_1)^2 - (x_2 - y_2)^2 \\
&= d_L(X, Y)^2
\end{aligned}$$

where  $x_1 < x_2$ ,  $y_1 < y_2$ . All other possibilities, which are  $x_1 \geq x_2$ ,  $y_1 < y_2$  or  $x_1 \geq x_2$ ,  $y_1 \geq y_2$  or  $x_1 < x_2$ ,  $y_1 \geq y_2$  can be verified as above.

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