Iğdır Üniversitesi Fen Bilimleri Enstitüsü Dergisi, 11(4): 3086-3097, 2021 Journal of the Institute of Science and Technology, 11(4): 3086-3097, 2021

	15511. 2140-0574, (15511. 2550-4010	
Matematik / Mathematics	DOI: 10.21597/jist.958229	
Araștırma Makalesi / Research Article		
Geliş tarihi / Received: 27.06.2021	Kabul tarihi / Accepted: 17.09.2021	
To Cite: Kırcı Ö, Aktürk T, Bulut H, 2021. Simulation	of Wave Solutions of a Mathematical Model Representing	
Communication Signals, Journal of the Institute of Science and Technology, 11(4): 3086-3097.		

ISSN: 2146-0574 eISSN: 2536-4618

Simulation of Wave Solutions of a Mathematical Model Representing Communication Signals

Özlem KIRCI<sup>1\*</sup>, Tolga AKTÜRK<sup>2</sup>, Hasan BULUT<sup>3</sup>

**ABSTRACT:** In this study, the Lonngren-wave equation is considered to be analyzed for its wave solutions. To implement this purpose the modified exponential function method is used and ultimately new hyperbolic, trigonometric and rational forms of the exact solutions are obtained. Furthermore, it was tested whether these forms satisfy the Lonngren-wave equation or not and it was seen that they verify the equation. Besides this, the two and three dimensional graphics together with the contour and density plots are presented.

**Keywords:** Longren-wave equation, the modified exponential function method, exact wave solutions, nonlinear partial differential equation, the hyperbolic, trigonometric and rational functions

<sup>3</sup>Hasan BULUT (Orcid ID:0000-0002-6089-1517), Fırat Üniversitesi, Fen Fakültesi, Matematik Bölümü, Elazığ, Türkiye

\*Corresponding Author: Özlem KIRCI, e-mail: ozlem.isik@klu.edu.tr

<sup>&</sup>lt;sup>1</sup> Özlem KIRCI (**Orcid ID:** 0000-0003-2986-952X), Kırklareli Üniversitesi, Fen-Edebiyat Fakültesi, Matematik Bölümü, Kırklareli, Türkiye

<sup>&</sup>lt;sup>2</sup> Tolga AKTÜRK (<u>Orcid ID: 0000-0002-8873-0424</u>), Ordu Üniversitesi, Eğitim Fakültesi, Matematik ve Fen Bilimleri Eğitimi Bölümü, Ordu, Türkiye

### **INTRODUCTION**

The nonlinear partial differential equations (NLPDEs) interest a wide range of applied scientists due to their potential of being extensively arisen in all the fields of engineering and science. Thus various powerful and effective methods are implemented for the exact solutions of the evolution equations owing to their importance in nonlinear science and their broad usage area. The solutions obtained as a result of applying these techniques allow commenting on the behavior of mathematical models. Some of them are the (G'/G)-expansion technique and its modifications (Wang et al., 2008; Naher, 2012; Naher and Abdullah, 2013; Akbar et al., 2016; Duran, 2020; Duran, 2021), the (1/G')expansion method (Duran, 2021), sine-Gordon expansion method and (m + G'/G)-expansion method (Ismael et al., 2020), the improved Bernoulli sub-equation function method (Bulut et al., 2016; Duran et al., 2021), the Riccati-Bernoulli sub-ODE method (Yang et al., 2015), the  $exp(-\phi(\xi))$ -expansion method and its improved forms (Misirli and Gurefe, 2011; Arshed et al., 2019; Chen et al., 2019; Yel et al., 2019; Baskonus, 2021; Duran, 2021), the generalized Kudryashov method (Demiray et al., 2015; Mahmud et al., 2017; Rahman et al., 2019), the new function method (Aktürk et al., 2017), the Hirota's bilinear transformation (Hietarinta, 2005), the Backlund transformation method (Hirota and Satsuma, 1977; Lu et al., 2006), rational sine-cosine method (Marwan et al. 2011; Qawasmeh and Alquran, 2014) the tanh method and its various extension (Fan, 2000; Elwakil et al., 2005; Yang and Hon, 2006), the tanh-coth expansion method (Wazwaz, 2007a, 2007b; Parkes, 2010), the homotopy perturbation method (He, 2006a, 2006b, 2008; Biazar et al., 2009), the simplified Hirota's method (Wazwaz, 2016), the extended sinh-Gordon equation expansion method (Kumar et al., 2018; Gao et al., 2019), Lie transformation method and singular manifold method (Saleh et al., 2021), the power index method (Shrauner, 2019),  $\phi^6$  -model expansion method (Seadawy et al., 2021), the truncated Painleve expansion (Radha et al., 2007), the Jacobi elliptic-function method (Parkes et al., 2002), etc.

In this study the Lonngren wave Equation (1), which is one of the NLPDEs, is considered and the new forms of the exact solutions are obtained by modified exponential function method (MEFM).

 $(u_{xx}-\alpha u+\beta u^2)_{tt}+u_{xx}=0.$ 

The Lonngren wave equation is used in the field of telecommunication and network engineering. For this equation, Akcagil and Aydemir have presented (G'/G)-expansion method, the modified extended tanh method and the unified method to reveal the new exact solutions (Akcagil and Aydemir, 2016; Akcagil and Aydemir, 2018). Kayum et al. have investigated the soliton solutions through the modified simple equation method (Kayum et al., 2020). Then it comes out that the Lonngren-wave equation is not taken into consideration by the modified exponential function method. In the light of those papers, the aim of this study is to present the new form of solutions to this equation. The flow of the manuscript is as follows: The materials and methods section includes the description of the MEFM and the application of the method for the Lonngren-wave equation, in results and discussion section the graphical results are given, finally it is ended with the conclusion part.

## MATERIALS AND METHODS

## Methodology

In this section, the application of the modified exponential function method to a NLPDE will be described. According to the method, the general form of a nonlinear evolution equation is written as follows;

$$P(U, U_x, U_t, U_{xx}, U_{xt}, U_{tt}, U_{xxtt}, ...) = 0,$$
<sup>(2)</sup>

where P is a function of U = U(x, t) and its partial derivatives in which the highest order derivatives and nonlinear terms are involved.

(1)

Özlem KIRCI et al.	11(4): 3086-3097, 2021
Simulation of Wave Solutions of a Mathematical Model Representing Communication Signals	

**Step1:** In order to obtain the solution functions of a NLPDE, the equation must be reduced into a nonlinear ordinary differential equation (NLODE) module. Therefore according to the method the wave transformation given below can be used for equation (1)

$$U(x,t) = U(\xi), \xi = k(x - ct),$$
 (3)

where k represents the wave height and c represents the wave frequency. The derivative terms required in equation (1) are obtained using the wave transformation (3) above. These terms are then substituted in equation (1) and as a result (1) reduced to a NLODE whose general form can be given as in the following,

$$N(U, U^2, U', U'', ...) = 0. (4)$$

Step2: According to the method the solution of Equation (1) is

$$U(\xi) = \frac{\sum_{i=0}^{n} A_i [exp(-\Omega(\xi))]^i}{\sum_{j=0}^{m} B_j [exp(-\Omega(\xi))]^j} = \frac{A_0 + A_1 exp(-\Omega(\xi)) + \dots + A_n exp(-n\Omega(\xi))}{B_0 + B_1 exp(-\Omega(\xi)) + \dots + B_m exp(-m\Omega(\xi))'}$$
(5)

where  $A_i, B_j, (0 \le i \le n, 0 \le j \le m)$  are constants to be determined.

In order to state equation (5) clearly, it is necessary to determine the upper limits of the summation symbols, the omega function and the coefficients, respectively. The balancing principle is used in the process of determining the upper limits, namely m and n. For this, a relation is obtained between m and n by balancing the term containing the highest order derivative and the highest order nonlinear term in equation (4). Then, the upper limits of the summation symbols are determined by giving values to the parameters so that they can provide the correlation. The expansion of the sums in (5) are provided up to the upper limit values after determination of m and n. After explicitly expressing  $U(\xi)$  in (5), the derivative terms required in Equation (4) are obtained from here. Substituting (5) together with the required derivatives into (4) creates the need of the omega function and its first order derivative. Therefore it is utilized from the following ordinary differential equation whose solution is  $\Omega(\xi)$ .

$$\Omega'(\xi) = \exp(-\Omega(\xi)) + \mu \exp(\Omega(\xi)) + \lambda.$$
(6)

**Step3:** The substitution of (5) into (4), taking into consideration (6), results in a system of algebraic equation. From this system the coefficients are determined using the package program. By writing the obtained coefficients in equation (4), the solution functions are investigated according to the following family states (Bulut and Baskonus, 2016). **Family1:** When  $\mu \neq 0$ ,  $\lambda^2 - 4\mu > 0$ ,

$$\Omega(\xi) = \ln\left(\frac{-\sqrt{\lambda^2 - 4\mu}}{2\mu} \tanh\left(\frac{\sqrt{\lambda^2 - 4\mu}}{2}(\xi + E)\right) - \frac{\lambda}{2\mu}\right).$$
(7)

**Family2:** When  $\mu \neq 0$ ,  $\lambda^2 - 4\mu < 0$ ,

$$\Omega(\xi) = \ln\left(\frac{\sqrt{-\lambda^2 + 4\mu}}{2\mu} \tan\left(\frac{\sqrt{-\lambda^2 + 4\mu}}{2}(\xi + E)\right) - \frac{\lambda}{2\mu}\right).$$
(8)

**Family3:** When  $\mu = 0$ ,  $\lambda \neq 0$  and  $\lambda^2 - 4\mu > 0$ ,

$$\Omega(\xi) = -\ln\left(\frac{\lambda}{\exp(\lambda(\xi+E))-1}\right).$$
(9)

Family4: When  $\mu \neq 0$ ,  $\lambda \neq 0$  and  $\lambda^2 - 4\mu = 0$ ,  $\Omega(\xi) = \ln\left(-\frac{2\lambda(\xi+E)+4}{\lambda^2(\xi+E)}\right).$ (10)

Family5: When  $\mu = 0$ ,  $\lambda = 0$  and  $\lambda^2 - 4\mu = 0$ ,  $\Omega(\xi) = \ln(\xi + E)$ ,
(11)

where  $A_0, A_1, \dots, A_n, B_0, B_1, \dots, B_m, E, \lambda, \mu$  are constants.

3088

Özlem KIRCI et al.	11(4): 3086-3097, 2021
Simulation of Wave Solutions of a Mathematical Model Representing Communication Signals	

## **Application of MEFM to Lonngren-wave equation**

If the wave transformation (3) is applied to the equation (1), the following NLODE model is obtained,

$$c^{2}k^{2}U'' + (1 - \alpha c^{2})U + \beta c^{2}U^{2} + R = 0, \qquad (12)$$

where *R* is the integral constant. Balancing the terms including the highest order derivative U'' and the highest power nonlinear term  $U^2$  in (12) results in the following equation

$$n = m + 2. \tag{13}$$

According to this equation for the values m=1, n=3, the solution function and the derivatives sought for equation (12) are as follows;

$$U(\xi) = \frac{\psi}{\varphi} = \frac{A_0 + A_1 e^{-\Omega(\xi)} + A_2 e^{-2\Omega(\xi)} + A_3 e^{-3\Omega(\xi)}}{B_0 + B_1 e^{-\Omega(\xi)}}, U'(\xi) = \frac{\psi'\varphi - \psi\varphi'}{\varphi^2},$$
  
$$U''(\xi) = \frac{\psi''\varphi^3 - \varphi^2 \psi'\varphi' - (\psi\varphi'' + \psi'\varphi')\varphi^2 + 2(\psi')^2 \psi\varphi}{\varphi^4}.$$
(14)

If the derivative concepts obtained above are written into equation (4), the following coefficient states and the solution functions depending on them are obtained. **Case1:** 

$$A_{0} = \frac{\left(1 + c^{2}\left(-\alpha + k^{2}\left(\lambda^{2} + 8\mu\right)\right)\right)A_{2}B_{0}}{12c^{2}k^{2}(B_{0} + \lambda B_{1})}, A_{1} = \frac{A_{2}\left(B_{1} + c^{2}\left(12k^{2}\lambda B_{0} + \left(-\alpha + k^{2}\left(\lambda^{2} + 8\mu\right)\right)B_{1}\right)\right)}{12c^{2}k^{2}(B_{0} + \lambda B_{1})}, A_{3} = \frac{A_{2}B_{1}}{B_{0} + \lambda B_{1}}, \beta = -\frac{6k^{2}(B_{0} + \lambda B_{1})}{A_{2}}, R = \frac{\left(-1 + 2c^{2}\alpha + c^{4}\left(-\alpha^{2} + k^{4}\left(\lambda^{2} - 4\mu\right)^{2}\right)\right)A_{2}}{24c^{2}k^{2}(B_{0} + \lambda B_{1})}.$$
(15)

The coefficients obtained by solving the algebraic equation system, are written in (5) and the solution function of equation (1) is analyzed according to the families as mentioned in step3. Graphical results that belong to the solution forms of (1) according to case1 are presented. **Family1:** 

$$\operatorname{Sech}[\vartheta]^{2}(2(1-c^{2}(\alpha+5k^{2}(\lambda^{2}-4\mu)))\mu+(1-c^{2}(\alpha-k^{2}(\lambda^{2}-4\mu)))((\lambda^{2}-2\mu)\operatorname{Cosh}[2\vartheta]) +\lambda\sqrt{\lambda^{2}-4\mu}\operatorname{Sinh}[2\vartheta]))A_{2}$$

$$U_{1,1}(\xi) = \frac{12c^{2}k^{2}(B_{0}+\lambda B_{1})(\lambda+\sqrt{\lambda^{2}-4\mu}\operatorname{Tanh}[\vartheta])^{2}}{12c^{2}k^{2}(B_{0}+\lambda B_{1})(\lambda+\sqrt{\lambda^{2}-4\mu}\operatorname{Tanh}[\vartheta])^{2}},$$

where  $\vartheta = \frac{1}{2}\sqrt{\lambda^2 - 4\mu}(E + \xi)$ , (Figure 1). Family 2:

$$\operatorname{Sec}[\psi]^{2}(2(1-c^{2}(\alpha+5k^{2}(\lambda^{2}-4\mu)))\mu+(1-c^{2}(\alpha-k^{2}(\lambda^{2}-4\mu)))((\lambda^{2}-2\mu)\operatorname{Cosh}[\psi] -\lambda\sqrt{-\lambda^{2}+4\mu}\operatorname{Sinh}[2\psi]))A_{2}$$

$$U_{1,2}(\xi) = \frac{-\lambda\sqrt{-\lambda^{2}+4\mu}\operatorname{Sinh}[2\psi])A_{2}}{12c^{2}k^{2}(B_{0}+\lambda B_{1})\left(\lambda-\sqrt{-\lambda^{2}+4\mu}\operatorname{Tan}[\psi]\right)^{2}},$$

where  $\psi = \frac{1}{2}(E + \xi)\sqrt{-\lambda^2 + 4\mu}$ , (Figure 2). Family 3:

$$U_{1,3}(\xi) = \frac{e^{(E+\xi)\lambda}(-1+c^2(\alpha+5k^2\lambda^2)+(1+c^2(-\alpha+k^2\lambda^2))\text{Cosh}[(E+\xi)\lambda])A_2}{6c^2(-1+e^{(E+\xi)\lambda})^2k^2(B_0+\lambda B_1)}.$$

(Figure3).

Family 4:

$$U_{1,4}(\xi) = \frac{-(((-\theta^2 + c^2(\alpha\theta^2 + 2k^2(\lambda^2(-2 + \phi(\theta + 2)) - 4\theta^2\mu)))A_2)}{12c^2k^2\theta^2(B_0 + \lambda B_1)},$$

3089

Simulation of Wave Solutions of a Mathematical Model Representing Communication Signals

where  $\phi = E\lambda + \xi\lambda$ ,  $\theta = 2 + \phi$ , (Figure 4). **Family 5:** 

$$U_{1,5}(\xi) = \frac{\left(\frac{12}{(E+\xi)^2} + \frac{1}{C^2} - \alpha}{12B_0}\right)A_2}{12B_0}.$$

(Figure5).



Figure 1. The three dimensional graph, contour graph, density graph of solution  $U_{1,1}(\xi)$  for the values  $c = -1, k = 0.5, B_1 = 2, \lambda = 3, \mu = 2, A_2 = 1.25, B_0 = 0.35, \alpha = -1.6, A_0 = 0.203248, A_1 = 1.36811, A_3 = 0.393701, \beta = 0.203248, A_1 = 0.203248, A_2 = 0.210724, B_1 = 0.210724, B_2 = 0.210724, B_2 = 0.210724, B_2 = 0.210724, B_3 = 0.210724, B_4 = 0.2$ 



Figure 2. The three dimensional graph, contour graph, density graph of solution  $U_{1,2}(\xi)$  for the values  $c = -1, k = 0.5, B_1 = 2, \lambda = 1, \mu = 2, A_2 = 1.25, B_0 = 0.35, \alpha = -1.6, A_0 = 0.42089, A_1 = 2.61525, A_3 = 1.06383, \beta = -2.82, R = -0.327793, E = 0.75$  and two-dimensional graph for t = 1



Figure 3. The three dimensional graph, contour graph, density graph of solution  $U_{1,3}(\xi)$  for the values  $c = -1, k = 0.5, B_1 = 2, \lambda = 1, \mu = 0, A_2 = 1.25, B_0 = 0.35, \alpha = -1.6, A_0 = 0.176862, A_1 = 1.19681, A_3 = 1.06383, \beta = -2.82, R = -0.59375, E = 0.75$  and two-dimensional graph for t = 1



Figure 4. The three dimensional graph, contour graph, density graph of solution  $U_{1,4}(\xi)$  for the values  $c = -1, k = 0.5, B_1 = 2, \lambda = 2, \mu = 1, A_2 = 1.25, B_0 = 0.35, \alpha = -1.6, A_0 = 0.187739, A_1 = 1.27395, A_3 = 0.574713, \beta = -5.22, R = -0.323755, E = 0.75$  and two-dimensional graph for t = 1



Figure 5. The three dimensional graph, contour graph, density graph of solution  $U_{1,5}(\xi)$  for the values  $c = -1, k = 0.5, B_1 = 2, \lambda = 0, \mu = 0, A_2 = 1.25, B_0 = 0.35, \alpha = -1.6, A_0 = 1.08333, A_1 = 6.19048, A_3 = 7.14286, \beta = -0.42, R = -4.02381, E = 0.75$  and two-dimensional graph for t = 1

Another group of coefficient called as case2 is presented below. **Case2:** 

$$A_{0} = \frac{(\sqrt{4R\beta + c^{2}k^{4}(\lambda^{2} - 4\mu)^{2}} - ck^{2}(\lambda^{2} + 8\mu))B_{0}}{2c\beta}, A_{1} = \frac{(-\sqrt{4R\beta + c^{2}k^{4}(\lambda^{2} - 4\mu)^{2}} + ck^{2}(\lambda^{2} + 8\mu))A_{3}}{12ck^{2}} - \frac{6k^{2}\lambda B_{0}}{\beta}$$
$$A_{2} = \lambda A_{3} - \frac{6k^{2}B_{0}}{\beta}, B_{1} = -\frac{\beta A_{3}}{6k^{2}}, \alpha = \frac{1 + c\sqrt{4R\beta + c^{2}k^{4}(\lambda^{2} - 4\mu)^{2}}}{c^{2}}.$$

Now the wave solutions of equation (1) are investigated according to case2 which is a result of the algebraic equation system emerged from MEFM.

# **Family1:** $U_{2,1}(\xi)$

$$= \frac{\operatorname{Sech}[\vartheta]^{2}(2(\eta + 5ck^{2}(\lambda^{2} - 4\mu))\mu + (\eta - ck^{2}(\lambda^{2} - 4\mu))((\lambda^{2} - 2\mu)\operatorname{Cosh}[2\vartheta] + \lambda\sqrt{\lambda^{2} - 4\mu}\operatorname{Sinh}[2\vartheta]))}{2c\beta(\lambda + \sqrt{\lambda^{2} - 4\mu}\operatorname{Tanh}[\vartheta])^{2}},$$
  
where  $\vartheta = \frac{1}{2}\sqrt{\lambda^{2} - 4\mu}(E + \xi), \eta = \sqrt{4R\beta + c^{2}k^{4}(\lambda^{2} - 4\mu)^{2}},$  (Figure 6).  
Family 2:

$$U_{2,2}(\xi) = \frac{\text{Sec}[\psi]^2 (2(\eta - 5ck^2\sigma^2)\mu + (\eta + ck^2\sigma^2)((\lambda^2 - 2\mu)\text{Cos}[2\vartheta] - \lambda\sigma\text{Sin}[2\psi]))}{2c\beta(\lambda - \sigma\text{Tan}[\psi])^2},$$
  
where  $\psi = \frac{1}{2}\sqrt{-\lambda^2 + 4\mu}(E + \xi), \eta = \sqrt{4R\beta + c^2k^4(\lambda^2 - 4\mu)^2}, \sigma = \sqrt{-\lambda^2 + 4\mu},$  (Figure 7).  
Family 3:

$$U_{2,3}(\xi) = \frac{\sqrt{4R\beta + c^2 k^4 \lambda^4}}{c} - k^2 \lambda^2 (1 + 3\mathrm{Csch}[\omega]^2)}{2\beta},$$

where  $\omega = \frac{1}{2}\lambda(EE + \xi)$ , (Figure 8).

#### Özlem KIRCI et al.

Simulation of Wave Solutions of a Mathematical Model Representing Communication Signals

Family4:

$$U_{2,4}(\xi) = \frac{\frac{\eta}{c} + 2k^2(\lambda^2(1 - \frac{6}{\phi^2}) - 4\mu)}{2\beta}$$

where  $\eta = \sqrt{4R\beta + c^2k^4(\lambda^2 - 4\mu)^2}$ ,  $\phi = E\lambda + \xi\lambda$ ,  $\theta = 2 + \phi$ , (Figure 9). Family 5:

$$U_{2,5}(\xi) = \frac{-\frac{6k^2}{(E+\xi)^2} + \frac{\sqrt{R\beta}}{c}}{\beta}$$

(Figure10).



Figure 6. The three dimensional graph, contour graph, density graphs of solution  $U_{2,1}(\xi)$  for the values  $c = -1, k = 0.5, B_1 - 1.33333, \lambda = 3, \mu = 2, A_2 = 3.42188, B_0 = 0.35, \alpha = 0.161847, A_0 = -0.775267, A_1 = 1.96902, A_3 = 1.25, \beta = 1.6, R = 0.1, E = 0.75$  and two-dimensional graph for t = 1



Figure 7. The three dimensional graph, contour graph, density graph of solution  $U_{2,2}(\xi)$  for the values  $c = -1, k = 0.5, B_1 - 1.33333, \lambda = 1, \mu = 2, A_2 = 0.921875, B_0 = 0.35, \alpha = -0.924188, A_0 = -0.675302, A_1 = 2.24445, A_3 = 1.25, \beta = 1.6, R = 0.1, E = 0.75$  and two-dimensional graph for t = 1



Figure 8. The three dimensional graph, contour graph, density graph of solution  $U_{2,3}(\xi)$  for the values  $c = -1, k = 0.5, B_1 - 1.33333, \lambda = 1, \mu = 0, A_2 = 0.921875, B_0 = 0.35, \alpha = 0.161847, A_0 = -0.119017, A_1 = 0.125272, A_3 = 1.25, \beta = 1.6, R = 0.1, E = 0.75$  and two-dimensional graph for t = 1



**Figure 9.** The three dimensional graph, contour graph, density graph of solution  $U_{2,4}(\xi)$  for the values  $c = -1, k = 0.5, B_1 - 1.33333, \lambda = 2, \mu = 1, A_2 = 2.17188, B_0 = 0.35, \alpha = 0.2, A_0 = -0.415625, A_1 = 0.927083, A_3 = 1.25, \beta = 1.6, R = 0.1, E = 0.75$  and two-dimensional graph for t = 1



Figure 10. The three dimensional graph, contour graph, density graph of solution  $U_{2,5}(\xi)$  for the values  $c = -1, k = 0.5, B_1 - 1.33333, \lambda = 0, \mu = 0, A_2 = -0.328125, B_0 = 0.35, \alpha = 0.2, A_0 = -0.0875, A_1 = 0.33333, A_3 = 1.25, \beta = 1.6, R = 0.1, E = 0.75$  and two-dimensional graph for t = 1

# **RESULTS AND DISCUSSION**

The graphs representing the behavior of the mathematical model are obtained by determining the appropriate parameters, for the solution forms. The 3D, 2D graphs together with the contour and the density plots of  $U_{1,1}, U_{1,2}, U_{1,3}, U_{1,4}, U_{1,5}, U_{2,1}, U_{2,2}, U_{2,3}, U_{2,4}, U_{2,5}$  are illustrated in Figures 1-10. Additionally, these forms are tested whether they are the exact solution of (1) or not with the help of a package program and verification is acquired.

# CONCLUSION

We have determined the new exact solution forms of the Lonngren-wave equation as hyperbolic, trigonometric and rational functions via the modified exponential function method which is an effective and functioning method. It is observed that the MEFM is not applied for this equation before. The process of plotting the graphs and the computations are overcome with the aid of a package program. The Lonngren wave equation is used in the field of telecommunication and network engineering. Therefore the newly obtained wave solutions may be useful for analyzing and understanding the information as signals for transmission. This shows that the method is a very effective technique for the NLPDEs.

# **Conflict of Interest**

The article authors declare that there is no conflict of interest between them.

# **Author's Contributions**

The authors declare that they have contributed equally to the article.

# REFERENCES

- Akbar MA, Alam MdN, Hafez MdG, 2016. Application of the novel (G'/G)-expansion method to construct traveling wave solutions to the positive Gardner-KP equation. Indian Journal of Pure Applied Mathematics, 47(1):85-96.
- Akcagil S, Aydemir T, 2016. Comparison between the (G'/G) -expansion method and the modified extended tanh method. Open Physics, 14(1):88-94.
- Akcagil S, Aydemir T, 2018. A new application of the unified method. New Trends in Mathematical Sciences, 6(1):185-199.

- Aktürk T, Gurefe Y, Pandır Y, 2017. An application of the new function method to the Zhiber-Shabat equation. An Interntional Journal of Optimization and Control: Theories & Applications, 7(3):271-274.
- Arshed S, Biswas A, Zhou Q, Khan S, Adesynya S, Moshokoa SP, et al., 2019. Optical Solitons perturbation with Fokas-Lenells equation by  $exp(-\phi(\xi))$ -expansion method. Optik, 179:341–345.
- Baskonus HM, 2021. Dark and trigonometric soliton solutions in asymmetrical Nizhnik-Novikov-Veselov equation with (2+ 1)-dimensional. An International Journal of Optimization and Control: Theories & Applications, 11(1):92-99.
- Biazar J, Badpeima F, Azimi F, 2009. Application of the homotopy perturbation method to Zakharov–Kuznetsov equations. Computers&Mathematics with Applications 58(11-12):2391-2394.
- Bulut H, Baskonus HM, 2016. Exponential prototype structures for (2+1)-dimensional Boiti-Leon-Pempinelli systems in mathematical physics. Waves in Random and Complex Media, 26(2):189-196.
- Bulut H, Baskonus HM, 2016. New Complex Hyperbolic Function Solutions for the (2+1)-Dimensional Dispersive Long Water-Wave System. Mathematical and Computational Applications, 21(2): 6.
- Chen G, Xin X, Liu H, 2019. The Improved exp  $(-\phi(\xi))$ -Expansion Method and New Exact Solutions of Nonlinear Evolution Equations in Mathematical Physics. Advances in Mathematical Physics, Article ID 4354310.
- Demiray ST, Pandır Y, Bulut H, 2015. New solitary wave solutions of Maccari system. Ocean Engineering, 103:153-159.
- Duran S, 2020. Solitary Wave Solutions of the Coupled Konno-Oono Equation by using the Functional Variable Method and the Two Variables (G'/G,1/G) -Expansion Method. Adayaman University Journal of Science, 10(2):585-594.
- Duran S, 2021. Dynamic interaction of behaviors of time-fractional shallow water wave equation system. Modern Physics Letters B, 35(22):2150353.
- Duran S, 2021. Travelling wave solutions and simulation of the Lonngren wave equation for tunnel diode. Optical and Quantum Electronics, 53, Article number: 458.
- Duran S, 2021. Breaking theory of solitary waves for the Riemann wave equation in fluid dynamics. International Journal of Modern Physics B, 35(9): 2150130.
- Duran S, Karabulut B, 2021. Nematicons in liquid crystals with Kerr Law by sub-equation method. Alexandria Engineering Journal, https://doi.org/10.1016/j.aej.2021.06.077.
- Elwakil SA, El-Labany SK, Zahran MA, Sabry R, 2005. Modified extended tanh-function method and its applications to nonlinear equations. Applied Mathematics and Computation, 161(2):403–412.
- Fan E, 2000. Extended tanh-function method and its applications to nonlinear equations. Physics Letters A, 277(4-5):212-218.
- Gao W, Ismael H F, Mohammed SA, Baskonus HM, Bulut H, 2019. Complex and real optical soliton properties of the paraxial non-linear Schrödinger equation in Kerr media with M-fractional. Frontiers in Physics, https://doi.org/10.3389/fphy.2019.00197.
- He JH, 2006a. Addendum: new interpretation of homotopy perturbation method. International Journal of Modern Physics B, 20(18): 2561-2568.
- He JH, 2006b. Homotopy perturbation method for solving boundary value problems. Physics Letters A, 350(1): 87-88.
- He JH, 2008. Recent development of the homotopy perturbation method. Topological Methods in Nonlinear Analysis, 31(2):205-209.
- Hietarinta J, 2005. Hirota's bilinear method and soliton solutions. Physics AUC, 15(1):31-37.
- Hirota R, Satsuma J, 1977. Nonlinear Evolution Equations Generated from the Bäcklund Transformation for the Boussinesq Equation. Progress of Theoretical Physics, 57(3):797-807.
- Ismael HF, Bulut H, Baskonus HM, 2020. Optical soliton solutions to the Fokas–Lenells equation via sine-Gordon expansion method and (m + (G'/G))-expansion method. Pramana-Journal of Physics, 94:35.
- Kayum MdA, Ara S, Barman HK, Akbar MA, 2020. Soliton solutions to voltage analysis in nonlinear electrical transmission lines and electric signals in telegraph lines. Results in Physics, 18:103269.
- Kumar D, Manafian J, Hawlader F, Ranjbaran A, 2018. New closed form soliton and other solutions of the Kundu– Eckhaus equation via the extended sinh-Gordon equation expansion method. Optik, 160:159-167.

Lu D, Hong B, Tian L, 2006. Backlund transformation and N-soliton-like Solutions to the Combined KdV-Burgers

Equation with Variable Coefficients. International. Journal of Nonlinear Sciences, 2(1):3–10. Mahmud F, Samsuzzoha Md, Akbar MA, 2017. The generalized Kudryashov method to obtain exact traveling wave

solutions of the PHI-four equation and Fisher equation. Results in Physics, 7:4296-4302.

Marwan A, Al-Khaled K, Ananbeh H, 2011. New Soliton Solutions for Systems of Nonlinear Evolution Equations by the Rational Sine-Cosine Method. Studies in Mathematical Sciences, 3(1): 1-9.

Misirli E, Gurefe Y, 2011. Exp-Function Method for Solving Nonlinear Evolution Equations. Mathematical and Computational Applications, 16(1): 258-266.

- Naher H, 2012. The Basic (G'/G)-Expansion Method for the Fourth Order Boussinesq Equation. Applied Mathematics, 3(10):1144-1152.
- Naher H, Abdullah FA, 2013. New approach of (G'/G)-expansion method and new approach of generalized (G'/G)expansion method for nonlinear evolution equation. American Institute of Physics Advances, 3(3):032116.
- Parkes EJ, Duffy BR, Abbott PC, 2002. The Jacobi elliptic-function method for finding periodic-wave solutions to nonlinear evolution equations. Physics Letters A, 295(5-6):280-286.
- Parkes EJ, 2010. Observations on the tanh-coth expansion method for finding solutions to nonlinear evolution equations. Applied Mathematics and Computations, 217(4):1749-1754.
- Qawasmeh A, Alquran M, 2014. Reliable Study of Some New Fifth-Order Nonlinear Equations by Means of G'/GExpansion Method and Rational Sine-Cosine Method. Applied Mathematical Sciences, 8(120):5985-5994.
- Radha R, Tang XY, Lou SY, 2007. Truncated Painleve Expansion A Unified Approach to Exact Solutions and Dromion Interactions of (2+1)-Dimensional Nonlinear Systems. Zeitschrift für Naturforsch a, 62(3):107-116.
- Rahman MM, Habib MA, Ali HMS, Miah MM, 2019. The Generalized Kudryashov Method: a Renewed Mechanism for Performing Exact Solitary Wave Solutions of Some NLEEs. Journal of Mechanics of Continua and Mathematical Sciences, 14(1):323-339.
- Saleh R, Mabrouk SM, Wazwaz AM, 2021. Lie symmetry analysis of a stochastic gene evolution in double-chain deoxyribonucleic acid system. Waves in Random and Complex Media, https://doi.org/10.1080/17455030.2020.1871109.
- Seadawy AR, Bilal M, Younis M, Rizvi STR, Althobaiti S, Makhlouf MM, 2021. Analytical mathematical approaches for the double-chain model of DNA by a novel computational technique. Chaos, Solitons and Fractals, 144(17):110669.
- Shrauner BA, 2019. Exact traveling wave solutions of nonlinear evolution equations: indeterminant homogeneous balance and linearizability. Mathematics and Statistics, 7(1):10–13.
- Wang ML, Li X, Zhang JL, 2008. The G'/G-expansion method and travelling wave solutions of nonlinear evolution equations in mathematical physics. Physics Letters A, 372(4):417–423.
- Wazwaz AM, 2007a. Multiple-soliton solutions for the KP equation by Hirota's bilinear method and by the tanh–coth method. Applied Mathematics and Computation, 190(1):633–640.
- Wazwaz AM, 2007b. The tanh-coth method for solitons and kink solutions for nonlinear parabolic equations. Applied Mathematics and Computation, 188(2):1467-1475.
- Wazwaz AM, 2016. The simplified Hirota's method for studying three extended higher-order KdV-type equations. Jornal of Ocean Engineering and Sciences, 1(3):181-185.
- Yang XF, Deng ZC, Wei Y, 2015. A Riccati-Bernoulli sub-ODE method for nonlinear partial differential equations and its application. Advances in Difference Equations, 117(2015).
- Yang Z, Hon YC, 2006. An Improved Modified Extended tanh-Function Method. Zeitschrift für Naturforsch, 61a:103-115.
- Yel G, Baskonus HM, 2019. Solitons in conformable time-fractional Wu–Zhang system arising in coastal design. Pramana, 93(4):1-10.