

Poisson Integral Formula For An Elliptic Type Equation

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Abstract : *In this study, Poisson integral formulas are obtained for the GASPT equation and for a partial differential equation of elliptic type defined in a domain with the boundary given by a non-isotropic distance.*

Key Words: GASPT equation, Poisson integral formula, Dirichlet problem

Eliptik Tipten Bir Denklem İçin Poisson İntegral Formülü

Özet: *Bu çalışmada, GASPT denklemi ve sınırı non-izotropik uzaklıkla verilen bir bölgede tanımlı, değişken katsayılı eliptik tipten bir denklemin çözümleri için Poisson integral formülü elde edilmiştir.*

Anahtar Kelimeler: GASPT denklemi, Poisson integral formülü, Dirichlet problemi

1. Introduction

Let us consider the open disc

$$D = \{(x, y) : x^2 + y^2 < a^2\}$$

and its boundary

$$\partial D = \{(x, y) : x^2 + y^2 = a^2\}$$

defined in xy -plane. Here a is a positive constant. The problem

$$\begin{aligned} \Delta u &= u_{xx} + u_{yy} = 0 & \text{in } D \\ u(x, y) &= f(x, y) & \text{on } \partial D \end{aligned} \quad (1)$$

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defines a Dirichlet problem for a circle. Here, Δ shows as usual the Laplace operator

$$\Delta = \frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2}$$

By making the transformations $x = r \cos \theta$, $y = r \sin \theta$, we can redefine the problem in polar coordinates as

$$\Delta u^* = u_{rr}^* + \frac{1}{r} u_r^* + \frac{1}{r^2} u_{\theta\theta}^* = 0 \quad ; \quad 0 < r < a \quad (2)$$

$$u^*(a, \theta) = f(\theta) \quad ; \quad 0 \leq \theta \leq 2\pi$$

The solution of problem (2) is given by the well-known Poisson integral formula [2,3].

$$u^*(r, \theta) = \frac{1}{2\pi} \int_0^{2\pi} \frac{a^2 - r^2}{a^2 - 2ar \cos(\theta - \tau) + r^2} f(\tau) d\tau \quad (3)$$

2. Poisson Integral Formulas

Now let us consider the well-known GASPT (Generally Auxiliary Symmetric Potential Theory) operator [1,4]

$$L = \sum_{i=1}^n \left(\frac{\partial^2}{\partial x_i^2} + \frac{\alpha_i}{x_i} \frac{\partial}{\partial x_i} \right) + \frac{\partial^2}{\partial y^2} \quad (4)$$

where α_i ($i = 1, 2, \dots, n$) is constant, and the elliptic type operator

$$L_1 = \sum_{i=1}^2 \left(\frac{1}{m_i^2} x_i^{2-2m_i} \frac{\partial^2}{\partial x_i^2} - \frac{1}{m_i} \left(1 - \frac{1}{m_i} \right) x_i^{1-2m_i} \frac{\partial}{\partial x_i} \right) \quad (5)$$

and let

$$D_1 = \{ (x_1, \dots, x_n, y) : x_1^2 + \dots + x_n^2 + y^2 < a^2 \}$$

$$\partial D_1 = \{ (x_1, \dots, x_n, y) : x_1^2 + \dots + x_n^2 + y^2 = a^2 \}$$

$$D_2 = \{ (x_1, x_2) : x_1^{2m_1} + x_2^{2m_2} < a^2 \}$$

$$\partial D_2 = \{ (x_1, x_2) : x_1^{2m_1} + x_2^{2m_2} = a^2 \}$$

where a is a positive constant, m_1 and m_2 are positive integers. In [1], some particular solutions of GASPT equation defined by the operator (1) is obtained and in [4], Harnack type inequalities for the positive solutions of the same equation are given.

Let us consider the following two Dirichlet problems:

$$\begin{aligned} Lu(x_1, x_2, \dots, x_n, y) &= 0 \quad , \quad \text{in } D_1 \\ u(x_1, x_2, \dots, x_n, y) &= f(\sqrt{x_1^2 + x_2^2 + \dots + x_n^2}, y), \quad \text{on } \partial D_1 \end{aligned} \quad (6)$$

and

$$\begin{aligned} L_1 u(x_1, x_2) &= 0 \quad , \quad \text{in } D_2 \\ u(x_1, x_2) &= f(x_1, x_2) \quad , \quad \text{on } \partial D_2 \end{aligned} \quad (7)$$

In this study, we give the solutions of these two problems in terms of an integral which includes the boundary values and a Poisson type kernel. Thus we refer the solutions as Poisson integral formulas for the Dirichlet problems. Let us first give the following lemma.

Lemma 1. Let

$$n - 1 + \sum_{i=1}^n \alpha_i = 0. \quad (8)$$

Then, under the transformation

$$x^2 = x_1^2 + x_2^2 + \dots + x_n^2, \quad (9)$$

the equation

$$Lu = \sum_{i=1}^n \left(\frac{\partial^2 u}{\partial x_i^2} + \frac{\alpha_i}{x_i} \frac{\partial u}{\partial x_i} \right) + \frac{\partial^2 u}{\partial y^2} = 0 \quad (10)$$

is reduced to the Laplace equation.

$$Lu_1^* = \frac{\partial^2 u_1^*}{\partial x^2} + \frac{\partial^2 u_1^*}{\partial y^2} = 0 \quad (11)$$

Proof. Since $x^2 = x_1^2 + x_2^2 + \dots + x_n^2$ and $u(x_1, \dots, x_n, y) = u_1^*(\sqrt{x_1^2 + \dots + x_n^2}, y)$

we have

$$\begin{aligned} \frac{\partial x}{\partial x_i} &= \frac{x_i}{x}, \\ \frac{\partial^2 x}{\partial x_i^2} &= \frac{x^2 - x_i^2}{x^3}. \end{aligned}$$

Thus by the chain rule

$$\frac{\partial u}{\partial x_i} = \frac{x_i}{x} \frac{\partial u_1^*}{\partial x_i},$$

and

$$\frac{\partial^2 u}{\partial x_i^2} = \left(\frac{x_i}{x} \right)^2 \frac{\partial^2 u_1^*}{\partial x_i^2} + \frac{(x^2 - x_i^2)}{x^3} \frac{\partial u_1^*}{\partial x}.$$

By substituting these values in (10), we obtain

$$Lu_1^* = \frac{\partial^2 u_1^*}{\partial x^2} + \frac{n-1 + \sum_{i=1}^n \alpha_i}{x} \frac{\partial u_1^*}{\partial x} + \frac{\partial^2 u_1^*}{\partial y^2} = 0.$$

Since $n-1 + \sum_{i=1}^n \alpha_i = 0$, we get the Laplace equation

$$Lu_1^* = \frac{\partial^2 u_1^*}{\partial x^2} + \frac{\partial^2 u_1^*}{\partial y^2} = 0,$$

which gives the proof.

Theorem 1. The solution of the Dirichlet problem defined by (6) under the condition (8) is given by the Poisson integral formula

$$u^{**}(\rho, \theta) = \frac{1}{2\pi} \int_0^{2\pi} \frac{a^2 - \rho^2}{a^2 - 2a\rho \cos(\theta - \tau) + \rho^2} f(\tau) d\tau$$

where $\rho = \sqrt{x_1^2 + \dots + x_n^2 + y^2}$ and $\theta = \arctan \frac{y}{\sqrt{x_1^2 + \dots + x_n^2}}$

Proof. By Lemma 1, under the condition (8), the equation (10) can be reduced to the Laplace equation

$$Lu_1^* = \frac{\partial^2 u_1^*}{\partial x^2} + \frac{\partial^2 u_1^*}{\partial y^2} = 0$$

and hence with the transformation (9), Dirichlet problem (6) is transformed to the problem

$$\begin{aligned} Lu(x_1, \dots, x_n, y) &= Lu_1^*(\sqrt{x_1^2 + \dots + x_n^2}, y) = 0 \quad ; \text{ in } D \\ u(x_1, \dots, x_n, y) &= u_1^*(\sqrt{x_1^2 + \dots + x_n^2}, y) = f(x, y) \quad ; \text{ on } \partial D \end{aligned}$$

We know that the solution of this problem, in polar coordinates is given by the Poisson integral formula

$$u^{**}(\rho, \theta) = \frac{1}{2\pi} \int_0^{2\pi} \frac{a^2 - \rho^2}{a^2 - 2a\rho \cos(\theta - \tau) + \rho^2} f(\tau) d\tau.$$

Thus, the function

$$u(x_1, \dots, x_n, y) = u_1^*(x, y) = u^{**} \left(\sqrt{x_1^2 + \dots + x_n^2 + y^2}, \arctan \frac{y}{\sqrt{x_1^2 + \dots + x_n^2}} \right)$$

gives the solution of problem (6).

Now, we obtain the Poisson integral formula for the problem (7).

Lemma 2. The equation

$$L_1 u = \sum_{i=1}^2 \left(\frac{1}{m_i^2} x_i^{2-2m_i} \frac{\partial^2 u}{\partial x_i^2} - \frac{1}{m_i} \left(1 - \frac{1}{m_i} \right) x_i^{1-2m_i} \frac{\partial u}{\partial x_i} \right) = 0 \quad (12)$$

under the change of variables

$$x_1 = (r_1 \cos \theta)^{\frac{1}{m_1}}, \quad x_2 = (r_1 \sin \theta)^{\frac{1}{m_2}}, \quad (13)$$

is transformed to the Laplace equation in polar coordinates

$$L_1 u_1 = \frac{\partial^2 u_1}{\partial r_1^2} + \frac{1}{r_1^2} \frac{\partial^2 u_1}{\partial \theta^2} + \frac{1}{r_1} \frac{\partial u_1}{\partial r_1} = 0 \quad (14)$$

Proof. Since $x_1 = (r_1 \cos \theta)^{1/m_1}$, and $x_2 = (r_1 \sin \theta)^{1/m_2}$ we have

$$r_1^2 = x_1^{2m_1} + x_2^{2m_2}, \quad \theta = \arctan(x_1^{-m_1} x_2^{m_2}). \quad (15)$$

In addition,

$$\begin{aligned} \frac{\partial u}{\partial x_1} &= m_1 (x_1^{2m_1} + x_2^{2m_2})^{-\frac{1}{2}} x_1^{2m_1-1} \frac{\partial u_1}{\partial r_1} - m_1 x_1^{m_1-1} x_2^{m_2} (x_1^{2m_1} + x_2^{2m_2})^{-1} \frac{\partial u_1}{\partial \theta} \\ \frac{\partial u}{\partial x_2} &= m_2 (x_1^{2m_1} + x_2^{2m_2})^{-\frac{1}{2}} x_2^{2m_2-1} \frac{\partial u_1}{\partial r_1} - m_2 x_1^{m_1} x_2^{m_2-1} (x_1^{2m_1} + x_2^{2m_2})^{-1} \frac{\partial u_1}{\partial \theta} \\ \frac{\partial^2 u}{\partial x_1^2} &= m_1^2 (x_1^{2m_1} + x_2^{2m_2})^{-1} x_1^{4m_1-2} \frac{\partial^2 u_1}{\partial r_1^2} - 2m_1^2 (x_1^{2m_1} + x_2^{2m_2})^{-\frac{3}{2}} x_1^{3m_1-2} x_2^{m_2} \frac{\partial^2 u_1}{\partial r_1 \partial \theta} \\ &\quad + m_1^2 x_1^{2m_1-2} x_2^{2m_2} (x_1^{2m_1} + x_2^{2m_2})^{-2} \frac{\partial^2 u_1}{\partial \theta^2} \\ &\quad + \left[m_1 (2m_1 - 1) (x_1^{2m_1} + x_2^{2m_2})^{-\frac{1}{2}} x_1^{2m_1-2} - m_1^2 x_1^{4m_1-2} (x_1^{2m_1} + x_2^{2m_2})^{-\frac{3}{2}} \right] \frac{\partial u_1}{\partial r_1} \\ &\quad + \left[-m_1 (m_1 - 1) x_1^{m_1-2} x_2^{m_2} (x_1^{2m_1} + x_2^{2m_2})^{-1} + 2m_1^2 x_2^{m_2} x_1^{3m_1-2} (x_1^{2m_1} + x_2^{2m_2})^{-2} \right] \frac{\partial u_1}{\partial \theta} \end{aligned}$$

$$\begin{aligned} \frac{\partial^2 u}{\partial x_2^2} &= m_2^2 (x_1^{2m_1} + x_2^{2m_2})^{-1} x_2^{4m_1-2} \frac{\partial^2 u_1}{\partial r_1^2} - 2m_2^2 (x_1^{2m_1} + x_2^{2m_2})^{\frac{-3}{2}} x_1^{m_1} x_2^{3m_2-2} \frac{\partial^2 u_1}{\partial r_1 \partial \theta} \\ &+ m_2^2 x_1^{2m_1} x_2^{2m_2-2} (x_1^{2m_1} + x_2^{2m_2})^{-2} \frac{\partial^2 u_1}{\partial \theta^2} \\ &+ \left[m_2(2m_2 - 1)(x_1^{2m_1} + x_2^{2m_2})^{\frac{-1}{2}} x_2^{2m_1-2} - m_2^2 x_2^{4m_1-2} (x_1^{2m_1} + x_2^{2m_2})^{\frac{-3}{2}} \right] \frac{\partial u_1}{\partial r_1} \\ &+ \left[m_2(m_2 - 1)x_1^{m_1} x_2^{m_2-2} (x_1^{2m_1} + x_2^{2m_2})^{-1} - 2m_2^2 x_1^{m_2} x_2^{3m_2-2} (x_1^{2m_1} + x_2^{2m_2})^{-2} \right] \frac{\partial u_1}{\partial \theta} \end{aligned}$$

Substituting these values in (12) we obtain (14).

Theorem 2. The solution of the problem defined by (7) is

$$u_1(r_1, \theta) = \frac{1}{2\pi} \int_0^{2\pi} \frac{a^2 - r_1^2}{a^2 - 2ar_1 \cos(\theta - \tau) + r_1^2} f_1(\tau) d\tau$$

where $r_1^2 = x_1^{2m_1} + x_2^{2m_2}$, $\theta = \arctan(x_1^{-m_1} x_2^{m_2})$.

Proof. By Lemma 2, we have

$$L_1 u_1 = \frac{\partial^2 u_1}{\partial r_1^2} + \frac{1}{r_1^2} \frac{\partial^2 u_1}{\partial \theta^2} + \frac{1}{r_1} \frac{\partial u_1}{\partial r_1} = 0$$

and by (13), the boundary condition is

$$\begin{aligned} u\left((a \cos \theta)^{\frac{1}{m_1}}, (a \sin \theta)^{\frac{1}{m_2}}\right) &= f\left((a \cos \theta)^{\frac{1}{m_1}}, (a \sin \theta)^{\frac{1}{m_2}}\right) \\ u_1(a, \theta) &= f_1(\theta) \quad ; \quad 0 \leq \theta \leq 2\pi \end{aligned}$$

Hence by (2), the solution of this problem is given by Poisson integral formula

$$u_1(r_1, \theta) = \frac{1}{2\pi} \int_0^{2\pi} \frac{a^2 - r_1^2}{a^2 - 2ar_1 \cos(\theta - \tau) + r_1^2} f_1(\tau) d\tau.$$

Thus

$$u(x_1, x_2) = u_1\left((x_1^{2m_1} + x_2^{2m_2}), \arctan(x_1^{-m_1} x_2^{m_2})\right)$$

gives the solution of problem (7).

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