



Q-Curvature Tensor on f -Kenmotsu 3-Manifolds

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Abstract

The object of the present paper is to consider f -Kenmotsu 3-manifolds fulfilling certain curvature conditions on Q -curvature tensor with the Schouten-van Kampen connection. Certain consequences of Q -curvature tensor on such manifolds bearing Ricci soliton in perspective of Schouten-van Kampen association are likewise displayed. In the last segment, examples are given.

1. Introduction

Let \vec{M} be a $(2n+1)$ -dimensional almost contact manifold with an almost contact metric structure $(\check{\phi}, \xi, \eta, g)$ [1]. We denote by $\vec{\Omega}$, the fundamental 2-form of \vec{M} i.e., $\vec{\Omega}(\vec{X}, \vec{Y}) = g(\vec{X}, \check{\phi}\vec{Y})$, $\vec{X}, \vec{Y} \in \chi(\vec{M})$, where $\chi(\vec{M})$ being the Lie algebra of the differentiable vector fields on \vec{M} . Furthermore, we recall the following definitions [1, 2].

The manifold \vec{M} and its structure $(\check{\phi}, \xi, \eta, g)$ is said to be:

- (i) normal if the almost complex structure defined on the product manifold $\vec{M} \times \mathfrak{R}$ is integrable (equivalently $[\check{\phi}, \check{\phi}] + 2d\eta \otimes \xi = 0$),
- (ii) almost cosymplectic if $d\eta = 0$ and $d\check{\phi} = 0$,
- (iii) cosymplectic if it is normal and almost cosymplectic (equivalently, $\vec{\nabla}\check{\phi} = 0$, $\vec{\nabla}$ being covariant differentiation with respect to the Levi-Civita connection).

Olszak and Rosca [3] contemplated normal locally conformal almost cosymplectic manifold and gave the geometric translation of f -Kenmotsu manifolds and its curvature tensors. Among others, they proved that a Riccissymmetric f -Kenmotsu manifold is an Einstein manifold.

The Schouten-van Kampen connection is quite possibly the most widely recognized connection acclimated to two or three necessary allocations on a differentiable manifold conceding with a relative connection [4, 5]. Solov'ev has investigated hyperdistributions in Riemannian manifolds using the Schouten-van Kampen connection [6, 7]. From that point, Olszak has contemplated the Schouten-van Kampen connection with an almost contact metric structure [8]. He has depicted a few classes of almost contact metric manifolds bearing the Schouten-van Kampen connection and closed some particular curvature properties of this connection on such manifolds.

Let \vec{M} be a $(2n+1)$ -dimensional Riemannian manifold. On the off chance that there exists a balanced correspondence between each facilitate neighborhood of \vec{M} and an area in Euclidean space with the end goal that any geodesic of the Riemannian manifold compares to a straight line in the Euclidean space, at that point \vec{M} is supposed to be locally projectively flat. For $n \geq 1$, \vec{M} is locally projectively flat if and just if the notable projective curvature tensor P vanishes. Truth be told, P is projectively flat (i. e., $P=0$) if and just if the manifold is of consistent curvature [9]. ξ -conformally flat K -contact manifolds have been concentrated by Zhen et al. [10]. Yıldız et al. [11] considered f -Kenmotsu 3-manifolds with the Schouten-van Kampen connection and demonstrated that such manifold is consistently ξ -projectively flat. The projective curvature tensor is characterized by [12]:

$$P(\vec{X}, \vec{Y})\vec{Z} = \vec{R}(\vec{X}, \vec{Y})\vec{Z} - \frac{1}{2n} \{ \vec{Ric}(\vec{Y}, \vec{Z})\vec{X} - \vec{Ric}(\vec{X}, \vec{Z})\vec{Y} \}, \quad (1.1)$$



where \vec{Ric} is the Ricci tensor on \vec{M} .

A change in a $(2n + 1)$ -dimensional Riemannian manifold \vec{M} , which changes each geodesic circle of \vec{M} into a geodesic circle of \vec{M} , is supposed to be a concircular change [13, 14]. A concircular change is consistently a conformal change [13]. It means a geodesic circle by a bend in \vec{M} whose first curvature is steady and second arch is indistinguishably zero. Subsequently the geometry of concircular change is a speculation of intrusive geometry as in the difference in measurement is more broad than incited by a circle safeguarding diffeomorphism. A significant invariant of concircular transformation is the concircular curvature tensor C , characterized by [14]

$$C(\vec{X}, \vec{Y})\vec{Z} = \vec{R}(\vec{X}, \vec{Y})\vec{Z} - \frac{\vec{scal}}{2n(2n + 1)} \{g(\vec{Y}, \vec{Z})\vec{X} - g(\vec{X}, \vec{Z})\vec{Y}\}, \tag{1.2}$$

for all $\vec{X}, \vec{Y}, \vec{Z} \in \chi(\vec{M})$, where \vec{R} is the Riemannian curvature tensor and \vec{scal} is the scalar curvature with respect to the Levi-Civita connection. An $(2n + 1)$ -dimensional Riemannian manifold (\vec{M}^n, g) , the Q -curvature tensor is defined as [15]

$$Q(\vec{X}, \vec{Y})\vec{Z} = \vec{R}(\vec{X}, \vec{Y})\vec{Z} - \frac{\vec{\psi}}{2n} \{g(\vec{Y}, \vec{Z})\vec{X} - g(\vec{X}, \vec{Z})\vec{Y}\}, \tag{1.3}$$

where $\vec{\psi}$ is an arbitrary scalar function. If $\vec{\psi} = \frac{\vec{scal}}{(2n+1)}$, then Q -curvature tensor reduces to concircular curvature tensor. Mantica and Suh [15] have studied pseudo- Q -symmetric Riemannian manifolds.

In a Riemannian manifold (\vec{M}, g) , the metric g is called a Ricci soliton if [16]

$$\frac{1}{2} \mathfrak{L}_{\vec{V}}g + \vec{Ric} + \lambda g = 0, \tag{1.4}$$

where \mathfrak{L} is the Lie derivative, \vec{Ric} the Ricci tensor, \vec{V} a complete vector field on \vec{M} and λ is a constant. Compact Ricci solitons are the fixed points of the Ricci flow $\frac{\partial}{\partial t}g = -2\vec{Ric}$ projected from the space of metrics onto its quotient modulo diffeomorphisms and scalings, and often arise as blow-up limits for the Ricci flow on compact manifolds. The Ricci soliton is said to be shrinking, steady and expanding if λ is negative, zero and positive respectively. A Ricci soliton with $\vec{V}=0$ is reduced to Einstein equation. During the last two decades, the geometry of Ricci solitons have been light up by the several mathematicians [17–19]. It has become more important after Perelman applied Ricci solitons to solve the long standing Poincare conjecture posed in 1904.

Our paper is structured as follows: After the introduction. In section 2 we recall the fundamental results of the Schouten-van Kampen connection and f -Kenmotsu 3-manifolds. In the portion 3 we review the thought of Ricci soliton on f -Kenmotsu 3-manifolds with the Schouten-van Kampen connection. In segment 4 we study ξ - Q flat f -Kenmotsu 3-manifolds with the Schouten-van Kampen connection. We demonstrate the some results on f -Kenmotsu 3-manifolds with the Schouten-van Kampen connection under the condition $\vec{Q} \cdot \vec{Ric} = 0, \vec{Q} \cdot \vec{R} = 0, \vec{Q} \cdot \vec{P} = 0, \vec{Q}(\xi, \vec{X}) \cdot \vec{Q} = 0$ and $((\xi \wedge_{\vec{Ric}} \vec{X}) \cdot \vec{Q}) = 0$ in the sections 5-9, respectively. In the last segment, we give the examples.

2. Preliminaries

Let \vec{M} be a real $(2n + 1)$ -dimensional differentiable manifold endowed with an almost contact structure $(\check{\phi}, \xi, \eta, g)$ satisfying

$$\check{\phi}^2 = I - \eta \otimes \xi, \quad \eta(\xi) = 1, \quad \check{\phi}\xi = 0, \quad \eta \circ \check{\phi} = 0, \quad \eta(\vec{X}) = g(\vec{X}, \xi), \tag{2.1}$$

and

$$g(\check{\phi}\vec{X}, \check{\phi}\vec{Y}) = g(\vec{X}, \vec{Y}) - \eta(\vec{X})\eta(\vec{Y}), \tag{2.2}$$

for any vector fields $\vec{X}, \vec{Y} \in \chi(\vec{M})$, where I is the identity of the tangent bundle $T\vec{M}$, $\check{\phi}$ is a tensor field of $(1, 1)$ -type, η is a 1-form, ξ is a vector field and g is a metric tensor of \vec{M} . We say that $(\check{\phi}, \xi, \eta, g)$ is a f -Kenmotsu manifold [20, 21] if the covariant differentiation of $\check{\phi}$ satisfies

$$(\nabla_{\vec{X}}\check{\phi})\vec{Y} = f\{g(\check{\phi}\vec{X}, \vec{Y})\xi - \eta(\vec{Y})\check{\phi}\vec{X}\}, \tag{2.3}$$

where $f \in C^\infty(\vec{M})$ such that $df \wedge \eta = 0$. If $f = \alpha (\neq 0) = \text{constant}$, then the manifold (\vec{M}, g) is an α -Kenmotsu manifold [21]. Kenmotsu manifold is an example of f -Kenmotsu manifold with $f=1$ [22, 23]. If $f=0$, then the manifold (\vec{M}, g) reduces to cosymplectic [21]. An f -Kenmotsu manifold is said to be regular if $f^2 + \dot{f} \neq 0$, where $\dot{f} = \xi f$. For an f -Kenmotsu manifold from (2.3) it follows that

$$\nabla_{\vec{X}}\xi = f\{\vec{X} - \eta(\vec{X})\xi\}. \tag{2.4}$$

The condition $df \wedge \eta = 0$ holds if $\dim \vec{M} \geq 5$. In general this relation does not hold if $\dim \vec{M}=3$ [23]. It is well-known that in a Riemannian 3-manifold.

$$\vec{R}(\vec{X}, \vec{Y})\vec{Z} = g(\vec{Y}, \vec{Z})\vec{Q}\vec{X} - g(\vec{X}, \vec{Z})\vec{Q}\vec{Y} + \vec{Ric}(\vec{Y}, \vec{Z})\vec{X} - \vec{Ric}(\vec{X}, \vec{Z})\vec{Y} - \frac{\vec{scal}}{2} \{g(\vec{Y}, \vec{Z})\vec{X} - g(\vec{X}, \vec{Z})\vec{Y}\}. \tag{2.5}$$

In a f -Kenmotsu 3-manifold, we have [3].

$$\vec{R}(\vec{X}, \vec{Y})\vec{Z} = (\frac{\vec{scal}}{2} + 2f^2 + 2\dot{f})(\vec{X} \wedge \vec{Y})\vec{Z} - (\frac{\vec{scal}}{2} + 3f^2 + 3\dot{f})\{\eta(\vec{X})(\xi \wedge \vec{Y})\vec{Z} + \eta(\vec{Y})(\vec{X} \wedge \xi)\vec{Z}\}, \tag{2.6}$$

$$\vec{Ric}(\vec{X}, \vec{Y}) = (\frac{\vec{scal}}{2} + f^2 + \dot{f})g(\vec{X}, \vec{Y}) - (\frac{\vec{scal}}{2} + 3f^2 + 3\dot{f})\eta(\vec{X})\eta(\vec{Y}), \tag{2.7}$$

where \vec{scal} is the scalar curvature of \vec{M} . From (2.6) and (2.7) we obtain

$$\vec{R}(\vec{X}, \vec{Y})\xi = -(f^2 + f)[\eta(\vec{Y})\vec{X} - \eta(\vec{X})\vec{Y}], \quad (2.8)$$

$$\vec{Ric}(\vec{X}, \xi) = -2(f^2 + f)\eta(\vec{X}), \quad (2.9)$$

$$\vec{Ric}(\xi, \xi) = -2(f^2 + f), \quad (2.10)$$

$$\vec{Q}\xi = -2(f^2 + f)\xi, \quad (2.11)$$

for any vector fields \vec{X}, \vec{Y} on \vec{M} .

On the other hand \vec{H} and \vec{V} are two complementary, orthogonal distributions on \vec{M} such that $\dim \vec{H} = n - 1$, $\dim \vec{V} = 1$, and the distribution \vec{V} is non-null. Thus $T\vec{M} = \vec{H} \oplus \vec{V}$, $\vec{H} \cap \vec{V} = \{0\}$ and $\vec{H} \perp \vec{V}$. Assume that ξ is a unit vector field and η is a linear form such that $\eta(\xi) = 1$, $g(\xi, \xi) = \epsilon = \pm 1$ and

$$\vec{H} = \ker \eta, \quad \vec{V} = \text{span}\{\xi\}. \quad (2.12)$$

For any $X \in T\vec{M}$, by \vec{X}^h and \vec{X}^v we denote the projections of \vec{X} onto \vec{H} and \vec{V} , respectively. Thus, we have $\vec{X} = \vec{X}^h + \vec{X}^v$ with

$$\vec{X}^h = \vec{X} - \eta(\vec{X})\xi, \quad \vec{X}^v = \eta(\vec{X})\xi. \quad (2.13)$$

The Schouten-van Kampen connection $\tilde{\nabla}$ associated to the Levi-Civita connection $\vec{\nabla}$ and adapted to the pair of the distributions (\vec{H}, \vec{V}) is defined by [5]

$$\tilde{\nabla}_{\vec{X}}\vec{Y} = (\vec{\nabla}_{\vec{X}}\vec{Y}^h)^h + (\vec{\nabla}_{\vec{X}}\vec{Y}^v)^v. \quad (2.14)$$

From (2.13), we compute

$$(\vec{\nabla}_{\vec{X}}\vec{Y}^h)^h = \vec{\nabla}_{\vec{X}}\vec{Y} - \eta(\vec{\nabla}_{\vec{X}}\vec{Y})\xi - \eta(\vec{Y})\vec{\nabla}_{\vec{X}}\xi, \quad (2.15)$$

$$(\vec{\nabla}_{\vec{X}}\vec{Y}^v)^v = \eta(\vec{\nabla}_{\vec{X}}\vec{Y})\xi + \eta(\vec{\nabla}_{\vec{X}}\vec{Y})\xi, \quad (2.16)$$

which enables us to express the Schouten-van Kampen connection with help of the Levi-Civita connection in the following way [6]

$$\tilde{\nabla}_{\vec{X}}\vec{Y} = \vec{\nabla}_{\vec{X}}\vec{Y} - \eta(\vec{Y})\vec{\nabla}_{\vec{X}}\xi + (\vec{\nabla}_{\vec{X}}\eta)(\vec{Y})\xi. \quad (2.17)$$

In view of the Schouten-van Kampen connection (2.17), many properties of some geometric objects connected with the distributions \vec{H}, \vec{V} can be characterized [6, 7]. For example $\tilde{\nabla}g = 0$, $\tilde{\nabla}\xi = 0$, $\tilde{\nabla}\eta = 0$.

Proposition 2.1 ([24]). *Let \vec{M} be a f -Kenmotsu 3-manifold with the Schouten-van Kampen connection $\tilde{\nabla}$ we have*

$$\tilde{\nabla}_{\vec{X}}\vec{Y} = \vec{\nabla}_{\vec{X}}\vec{Y} + f\{g(\vec{X}, \vec{Y})\xi - \eta(\vec{Y})\vec{X}\}. \quad (2.18)$$

$$\tilde{R}(\vec{X}, \vec{Y})\vec{Z} = \vec{R}(\vec{X}, \vec{Y})\vec{Z} + f^2\{g(\vec{Y}, \vec{Z})\vec{X} - g(\vec{X}, \vec{Z})\vec{Y}\} + f\{g(\vec{Y}, \vec{Z})\eta(\vec{X})\xi - g(\vec{X}, \vec{Z})\eta(\vec{Y})\xi + \eta(\vec{Y})\eta(\vec{Z})\vec{X} - \eta(\vec{X})\eta(\vec{Z})\vec{Y}\}. \quad (2.19)$$

$$\tilde{Ric}(\vec{Y}, \vec{Z}) = \vec{Ric}(\vec{Y}, \vec{Z}) + (2f^2 + f)g(\vec{Y}, \vec{Z}) + f\eta(\vec{Y})\eta(\vec{Z}), \quad (2.20)$$

$$\tilde{Q}\vec{X} = \vec{Q}\vec{X} + (2f^2 + f)\vec{X} + f\eta(\vec{X})\xi, \quad (2.21)$$

$$\widetilde{scal} = \vec{scal} + 6f^2 + 4f, \quad (2.22)$$

where $\tilde{R}, \vec{R}, \tilde{Ric}, \vec{Ric}, \tilde{Q}, \vec{Q}$ and $\widetilde{scal}, \vec{scal}$ are consider as the Riemann curvature, Ricci tensors, Ricci operators and the scalar curvatures of the connection $\tilde{\nabla}$ and $\vec{\nabla}$ respectively.

3. Ricci Soliton on f -Kenmotsu 3-Manifold with the Schouten-Van Kampen Connection

In this section, we study the nature of Ricci soliton on f -Kenmotsu 3-manifold with respect to the Schouten-van Kampen connection $\tilde{\nabla}$. Let $(\tilde{M}^3, \phi, \xi, \eta, g)$ be a f -Kenmotsu 3-manifold with the Schouten-van Kampen connection, since $\tilde{\nabla}g=0$ and $\tilde{T} \neq 0$ then from [25], we have

$$(\tilde{\mathcal{L}}_{\tilde{V}}g)(\tilde{X}, \tilde{Y}) = g(\tilde{\nabla}_{\tilde{X}}\tilde{V}, \tilde{Y}) + g(\tilde{X}, \tilde{\nabla}_{\tilde{Y}}\tilde{V}) = (\mathcal{L}_{\tilde{V}}g)(\tilde{X}, \tilde{Y}), \tag{3.1}$$

where $\tilde{\mathcal{L}}$ denotes the Lie derivative on the manifold with respect to the Schouten-van Kampen connection. Thus from (1.4) we can write

$$(\tilde{\mathcal{L}}_{\tilde{V}}g + 2\tilde{Ric} + 2\lambda g)(\tilde{X}, \tilde{Y}) = 0, \tag{3.2}$$

that is

$$g(\tilde{\nabla}_{\tilde{X}}\tilde{V}, \tilde{Y}) + g(\tilde{X}, \tilde{\nabla}_{\tilde{Y}}\tilde{V}) + 2\tilde{Ric}(\tilde{X}, \tilde{Y}) + 2\lambda g(\tilde{X}, \tilde{Y}) = 0, \tag{3.3}$$

Putting $\tilde{V}=\xi$ in (3.3) and using (2.4) we obtain

$$\tilde{Ric}(\tilde{X}, \tilde{Y}) = -(\lambda + f)g(\tilde{X}, \tilde{Y}) + f\eta(\tilde{X})\eta(\tilde{Y}) \tag{3.4}$$

In view of (2.20) and (3.4), we get

$$\tilde{Ric}(\tilde{X}, \tilde{Y}) = -(\dot{f} + 2f^2 + f + \lambda)g(\tilde{X}, \tilde{Y}) + (-\dot{f} + f)\eta(\tilde{X})\eta(\tilde{Y}) \tag{3.5}$$

Thus we can state the following:

Proposition 3.1. *A f -Kenmotsu 3-manifold with respect to the Schouten-van Kampen connection $\tilde{\nabla}$ admitting Ricci soliton then the manifold is an η -Einstein manifold with the Schouten-van Kampen connection $\tilde{\nabla}$ and Levi-Civita connection $\tilde{\nabla}$.*

Proposition 3.2. *A Ricci soliton on an f -Kenmotsu 3-manifold with respect to the Schouten-van Kampen connection $\tilde{\nabla}$ is always steady.*

Also from (3.4), we get

$$\tilde{scal} = -2f - 3\lambda. \tag{3.6}$$

In view of (2.22) and (3.6), one can easily bring out that

$$\lambda = -\frac{1}{3}(\tilde{scal} + 6f^2 + 4\dot{f} + 2f). \tag{3.7}$$

We have the following:

Proposition 3.3. *A Ricci soliton on f -Kenmotsu 3-manifold with the Schouten-van Kampen connection $\tilde{\nabla}$ is an expanding, steady or shrinking according as $\tilde{scal} < -6f^2 - 4\dot{f} - 2f$, $\tilde{scal} = -6f^2 - 4\dot{f} - 2f$ or $\tilde{scal} > -6f^2 - 4\dot{f} - 2f$.*

Proposition 3.4. *A Ricci soliton on α -Kenmotsu 3-manifold with the Schouten-van Kampen connection $\tilde{\nabla}$ is an expanding, steady or shrinking according as $\tilde{scal} < -6\alpha^2 - 2\alpha$, $\tilde{scal} = -6\alpha^2 - 2\alpha$ or $\tilde{scal} > -6\alpha^2 - 2\alpha$.*

Proposition 3.5. *A Ricci soliton on cosymplectic 3-manifold with respect to the Schouten-van Kampen connection $\tilde{\nabla}$ is an expanding, steady or shrinking according as $\tilde{scal} < 0$, $\tilde{scal} = 0$ or $\tilde{scal} > 0$.*

In [24], Yildiz et al. demonstrated that f -Kenmotsu 3-manifold is projectively flat with respect to the Schouten-van Kampen connection if and only if \tilde{M} is a Ricci-flat manifold with respect to the Schouten-van Kampen connection $\tilde{\nabla}$. Therefore in perspective on this outcome and utilizing (3.4) we express the following:

Corollary 3.6. *A Ricci soliton on a projectively flat f -Kenmotsu 3-manifold with respect to the Schouten-van Kampen connection $\tilde{\nabla}$ is always steady.*

With the help of Theorem 6.1. of [24] and (3.4) we have the following:

Corollary 3.7. *A Ricci soliton on a conharmonically flat f -Kenmotsu 3-manifold with respect to the Schouten-van Kampen connection $\tilde{\nabla}$ is always steady.*

4. ξ - \tilde{Q} Flat f -Kenmotsu 3-Manifold with the Schouten-Van Kampen Connection

In this section, we consider ξ - \tilde{Q} flat f -Kenmotsu 3-manifold admitting the Schouten-van Kampen connection $\tilde{\nabla}$. Now we state the following definitions and result:

Definition 4.1. *A f -Kenmotsu 3-manifold is said to be ξ - \tilde{Q} flat if $\tilde{Q}(\tilde{X}, \tilde{Y})\xi = 0$ on \tilde{M} .*

Theorem 4.2. *A f -Kenmotsu 3-manifold with the Schouten-van Kampen connection $\tilde{\nabla}$ is ξ - \tilde{Q} flat if and only if $\tilde{\psi}=0$.*

Proof. From (1.3) we have

$$\tilde{Q}(\vec{X}, \vec{Y})\xi = \tilde{R}(\vec{X}, \vec{Y})\xi - \frac{\tilde{\Psi}}{2}[\eta(\vec{Y})\vec{X} - \eta(\vec{X})\vec{Y}], \quad (4.1)$$

for any for any vector fields \vec{X} and $\vec{Y} \in \chi(\tilde{M})$. With the help of (2.6) and (2.19), equation (4.1) reduces

$$\tilde{Q}(\vec{X}, \vec{Y})\xi = -\frac{\tilde{\Psi}}{2}[\eta(\vec{Y})\vec{X} - \eta(\vec{X})\vec{Y}]. \quad (4.2)$$

This completes the proof. \square

If $\tilde{\Psi} = \frac{\text{scal}}{3}$ then Q -curvature tensor reduces to concircular curvature tensor. Thus keeping in mind Theorem 4.2 and making use of (1.2) we obtain the followings:

Corollary 4.3. A f -Kenmotsu 3-manifold with the Schouten-van Kampen connection $\tilde{\nabla}$ is ξ -concircularly flat if and only if the scalar curvature of the manifold is zero.

Corollary 4.4. A ξ -concircularly flat complete Einstein f -Kenmotsu 3-manifold is Ricci flat.

Corollary 4.5. A Ricci soliton on ξ -concircularly flat complete Einstein f -Kenmotsu 3-manifold is always steady.

If $0 \neq f = \text{constant}$ (we assume $f = \alpha$) then $\dot{f} = 0$. Thus we state the followings:

Corollary 4.6. An α -Kenmotsu 3-manifold with the Schouten-van Kampen connection $\tilde{\nabla}$ is ξ - \tilde{Q} flat if and only if $\tilde{\Psi} = 0$.

Corollary 4.7. In a ξ - \tilde{Q} flat α -Kenmotsu 3-manifold with the Schouten-van Kampen connection $\tilde{\nabla}$ the Q -curvature tensor is equal to the Riemannian curvature tensor.

Corollary 4.8. In a ξ - \tilde{Q} flat α -Kenmotsu 3-manifold with the Schouten-van Kampen connection $\tilde{\nabla}$ the concircular curvature tensor is equal to the Riemannian curvature tensor.

Corollary 4.9. A Ricci soliton on ξ -concircularly flat α -Kenmotsu 3-manifold with respect to the Schouten-van Kampen connection $\tilde{\nabla}$ is always shrinking.

5. f -Kenmotsu 3-Manifolds Satisfying $\tilde{Q} \cdot \tilde{Ric} = 0$ with the Schouten-Van Kampen Connection

In this section we restrict our study to f -Kenmotsu 3-manifolds satisfying $\tilde{Q} \cdot \tilde{Ric} = 0$ with the Schouten-van Kampen connection $\tilde{\nabla}$. We conclude the following:

Theorem 5.1. A f -Kenmotsu 3-manifolds with the Schouten-van Kampen connection $\tilde{\nabla}$ satisfying $\tilde{Q} \cdot \tilde{Ric} = 0$, then either Q -curvature tensor is equal to the Riemannian curvature or the manifold is an η -Einstein manifold.

Proof. Let \tilde{M} satisfies the condition $\tilde{Q}(\xi, \vec{X}) \cdot \tilde{Ric} = 0$. So it implies that

$$\tilde{Ric}(\tilde{Q}(\xi, \vec{X})\vec{Y}, \vec{Z}) + \tilde{Ric}(\vec{Y}, \tilde{Q}(\xi, \vec{X})\vec{Z}) = 0, \quad (5.1)$$

for any $\vec{X}, \vec{Y}, \vec{Z}$ on \tilde{M} . Using (1.3), (2.6) and (2.19) in (5.1), we have

$$\frac{\tilde{\Psi}}{2} \left\{ g(\vec{X}, \vec{Y})\tilde{Ric}(\xi, \vec{Z}) - \tilde{Ric}(\vec{X}, \vec{Z})\eta(\vec{Y}) + g(\vec{X}, \vec{Z})\tilde{Ric}(\xi, \vec{Y}) - \tilde{Ric}(\vec{X}, \vec{Y})\eta(\vec{Z}) \right\} = 0. \quad (5.2)$$

For $\vec{Z} = \xi$ and keeping in mind (2.9) and (2.20), we obtain

$$\tilde{\Psi}\tilde{Ric}(\vec{X}, \vec{Y}) = 0, \quad (5.3)$$

which implies that either $\tilde{\Psi} = 0$, or $\tilde{Ric}(\vec{X}, \vec{Y}) = 0$. Thus we have:

Case (i) In particular, if $\tilde{\Psi} = 0$, and $\tilde{Ric}(\vec{X}, \vec{Y}) \neq 0$ then from (1.3) we get $Q(\vec{X}, \vec{Y})\vec{Z} = \tilde{R}(\vec{X}, \vec{Y})\vec{Z}$.

Case (ii) Also if $\tilde{\Psi} \neq 0$ and $\tilde{Ric}(\vec{X}, \vec{Y}) = 0$, then from (2.20), the manifold is an η -Einstein manifold. This completes the proof. \square

Again, if $\tilde{\Psi} = \frac{\text{scal}}{3}$ then Q -curvature tensor reduces to concircular curvature tensor. So from Theorem 5.1 and making use of (1.2), we can mention the following:

Corollary 5.2. A f -Kenmotsu 3-manifolds with the Schouten-van Kampen connection $\tilde{\nabla}$ satisfying $\tilde{C} \cdot \tilde{Ric} = 0$ then either Q -curvature tensor is equal to concircular curvature tensor or the manifold is an η -Einstein manifold.

Also, if $0 \neq f = \text{constant}$ (we assume $f = \alpha$), then $\dot{f} = 0$. Thus we state the followings:

Corollary 5.3. A f -Kenmotsu 3-manifolds satisfying $\tilde{Q} \cdot \tilde{Ric} = 0$ with the Schouten-van Kampen connection $\tilde{\nabla}$ then either the Q -curvature tensor is equal to the Riemannian curvature or the manifold is an η -Einstein manifold.

Corollary 5.4. An α -Kenmotsu 3-manifolds with the Schouten-van Kampen connection $\tilde{\nabla}$ satisfying $\tilde{C} \cdot \tilde{Ric} = 0$ then either Q -curvature tensor reduces to concircular curvature tensor or the manifold is an η -Einstein manifold.

Again, in view of (5.3) and (3.4), we have the followings:

Corollary 5.5. A Ricci soliton on f -Kenmotsu 3-manifolds with the Schouten-van Kampen connection $\tilde{\nabla}$ satisfying $\tilde{Q} \cdot \tilde{Ric} = 0$, then either the soliton is steady or Q -curvature tensor is equal to the Riemannian curvature tensor.

Corollary 5.6. A Ricci soliton on f -Kenmotsu 3-manifold with the Schouten-van Kampen connection $\tilde{\nabla}$ satisfying $\tilde{C} \cdot \tilde{Ric} = 0$, then either the soliton is steady or concircular curvature tensor is equal to the Riemannian curvature tensor.

6. f -Kenmotsu 3-Manifolds Satisfying $\tilde{Q} \cdot \tilde{R}=0$ with the Schouten-Van Kampen Connection

At this stage we consider f -Kenmotsu 3-manifolds with the Schouten-van Kampen connection $\tilde{\nabla}$ satisfying $\tilde{Q} \cdot \tilde{R}=0$. Therefore we illustrate the following:

Theorem 6.1. *A f -Kenmotsu 3-manifolds satisfying $\tilde{Q} \cdot \tilde{R}=0$ with the Schouten-van Kampen connection $\tilde{\nabla}$ then either Q -curvature tensor is equal to the Riemannian curvature, or it has the sectional curvature $-(f^2 + \dot{f})$.*

Proof. Suppose that f -Kenmotsu 3-manifolds with the Schouten-van Kampen connection $\tilde{\nabla}$ satisfying

$$\tilde{Q}(\xi, \vec{X})\tilde{R}(\vec{Y}, \vec{Z})\vec{U} = 0. \tag{6.1}$$

Equation (6.1) can be written as

$$\tilde{Q}(\xi, \vec{X})\tilde{R}(\vec{Y}, \vec{Z})\vec{U} - \tilde{R}(\tilde{Q}(\xi, \vec{X})\vec{Y}, \vec{Z})\vec{U} - \tilde{R}(\vec{Y}, \tilde{Q}(\xi, \vec{X})\vec{Z})\vec{U} - \tilde{R}(\vec{Y}, \vec{Z})\tilde{Q}(\xi, \vec{X})\vec{U} = 0, \tag{6.2}$$

for any vector fields $\vec{X}, \vec{Y}, \vec{Z}$ and \vec{U} on \vec{M} . Using (1.3), (2.6) and (2.19) in (6.2), we obtain

$$\frac{\tilde{\Psi}}{2}[-g(\vec{X}, \tilde{R}(\vec{Y}, \vec{Z})\vec{U})\xi + \eta(\tilde{R}(\vec{Y}, \vec{Z})\vec{U}) - \eta(\vec{Y})\tilde{R}(\vec{X}, \vec{Z})\vec{U} - \eta(\vec{Z})\tilde{R}(\vec{Y}, \vec{X})\vec{U} - \eta(\vec{U})\tilde{R}(\vec{Y}, \vec{Z})\vec{X}] = 0. \tag{6.3}$$

Taking the inner product with ξ of (6.3) and using (2.19) we get

$$\frac{\tilde{\Psi}}{2}[g(\vec{X}, \tilde{R}(\vec{Y}, \vec{Z})\vec{U}) + (f^2 + \dot{f})\{g(\vec{Z}, \vec{U})g(\vec{X}, \vec{Y}) - g(\vec{Y}, \vec{U})g(\vec{X}, \vec{Z})\} + \dot{f}\{g(\vec{X}, \vec{Y})\eta(\vec{Z})\eta(\vec{U}) - g(\vec{X}, \vec{Z})\eta(\vec{Y})\eta(\vec{U})\}] = 0. \tag{6.4}$$

It follows that either $\tilde{\Psi}=0$, or it has the sectional curvature $-(f^2 + \dot{f})$.

This completes the proof. □

In particular, if $\tilde{\Psi}=\frac{scal}{3}$ then Q -curvature tensor reduces to concircular curvature tensor. Therefore in view of the first result of the above Theorem 6.1 and making use of (1.2), we can mention the following:

Corollary 6.2. *If a f -Kenmotsu 3-manifolds with the Schouten-van Kampen connection $\tilde{\nabla}$ satisfying $\tilde{C} \cdot \tilde{R}=0$ then either concircular curvature tensor is equal to the Riemannian curvature or it has the sectional curvature $-(f^2 + \dot{f})$.*

Also with the help of (3.7) and Theorem 6.1, we conclude that:

Corollary 6.3. *If a f -Kenmotsu 3-manifolds with the Schouten-van Kampen connection $\tilde{\nabla}$ satisfying $\tilde{C} \cdot \tilde{R}=0$ then either Ricci soliton is shrinking or it has the sectional curvature $-(f^2 + \dot{f})$.*

If $0 \neq f=constant$ (we assume $f=\alpha$), then $\dot{f}=0$. Thus we state the followings:

Corollary 6.4. *If an α -Kenmotsu 3-manifolds with the Schouten-van Kampen connection $\tilde{\nabla}$ satisfying $\tilde{C} \cdot \tilde{R}=0$ then either concircular curvature tensor is equal to the Riemannian curvature or it has the sectional curvature α^2 .*

Corollary 6.5. *If an α -Kenmotsu 3-manifolds with the Schouten-van Kampen connection $\tilde{\nabla}$ satisfying $\tilde{C} \cdot \tilde{R}=0$ then either Ricci soliton is shrinking or it has the sectional curvature α^2 .*

7. f -Kenmotsu 3-Manifolds Satisfying $\tilde{Q} \cdot \tilde{P}=0$ with the Schouten-Van Kampen Connection

We consider f -Kenmotsu 3-manifolds with the Schouten-van Kampen connection $\tilde{\nabla}$ satisfying the condition $\tilde{Q} \cdot \tilde{P}=0$. Then we have:

Theorem 7.1. *A f -Kenmotsu 3-manifolds satisfying $\tilde{Q} \cdot \tilde{P}=0$ with the Schouten-van Kampen connection $\tilde{\nabla}$ is either the Q -curvature tensor is equal to the Riemannian curvature or it has the sectional curvature $\frac{1}{2}(\frac{scal}{2} + f^2 + 2\dot{f})$.*

Proof. The condition $\tilde{Q}(\xi, \vec{X})\tilde{P} = 0$ reflect that

$$(\tilde{Q}(\xi, \vec{X})\tilde{P})(\vec{Y}, \vec{Z})\vec{U} = \tilde{Q}(\xi, \vec{X})\tilde{P}(\vec{Y}, \vec{Z})\vec{U} - \tilde{P}(\tilde{Q}(\xi, \vec{X})\vec{Y}, \vec{Z})\vec{U} - \tilde{P}(\vec{Y}, \tilde{Q}(\xi, \vec{X})\vec{Z})\vec{U} - \tilde{P}(\vec{Y}, \vec{Z})\tilde{Q}(\xi, \vec{X})\vec{U} = 0, \tag{7.1}$$

for any vector fields $\vec{X}, \vec{Y}, \vec{Z}$ and \vec{U} on \vec{M} . On the other hand from (1.3), we have

$$\tilde{Q}(\xi, \vec{X})\tilde{P}(\vec{Y}, \vec{Z})\vec{U} = -\frac{\tilde{\Psi}}{2}\{g(\vec{X}, \tilde{P}(\vec{Y}, \vec{Z})\vec{U})\xi - \eta(\tilde{P}(\vec{Y}, \vec{Z})\vec{U})\vec{X}\}, \tag{7.2}$$

$$\tilde{P}(\tilde{Q}(\xi, \vec{X})\vec{Y}, \vec{Z})\vec{U} = -\frac{\tilde{\Psi}}{2}\{g(\vec{X}, \vec{Y})\tilde{P}(\xi, \vec{Y})\vec{Z} - \eta(\vec{Y})\tilde{P}(\vec{X}, \vec{Z})\vec{U}\}, \tag{7.3}$$

$$\tilde{P}(\vec{Y}, \tilde{Q}(\xi, \vec{X})\vec{Z}, \vec{U}) = -\frac{\tilde{\Psi}}{2}\{g(\vec{X}, \vec{Z})\tilde{P}(\vec{Y}, \xi)\vec{U} - \eta(\vec{Z})\tilde{P}(\vec{Y}, \vec{X})\vec{U}\}, \tag{7.4}$$

$$\tilde{P}(\vec{Y}, \vec{Z}, \tilde{Q}(\xi, \vec{X})\vec{U}) = -\frac{\tilde{\Psi}}{2}\{g(\vec{X}, \vec{U})\tilde{P}(\vec{Y}, \vec{Z})\xi - \eta(\vec{U})\tilde{P}(\vec{Y}, \vec{Z})\vec{X}\}. \tag{7.5}$$

Using (7.2), (7.3), (7.4) and (7.5) in (7.1), we get

$$\frac{\check{\Psi}}{2} \{-g(\vec{X}, \tilde{P}(\vec{Y}, \vec{Z})\vec{U})\xi + \eta(\tilde{P}(\vec{Y}, \vec{Z})\vec{U})\vec{X} + g(\vec{X}, \vec{Y})\tilde{P}(\xi, \vec{Y})\vec{Z} - \eta(\vec{Y})\tilde{P}(\vec{X}, \vec{Z})\vec{U} + g(\vec{X}, \vec{Z})\tilde{P}(\vec{Y}, \xi)\vec{U} - \eta(\vec{Z})\tilde{P}(\vec{Y}, \vec{X})\vec{U} + g(\vec{X}, \vec{U})\tilde{P}(\vec{Y}, \vec{Z})\xi - \eta(\vec{U})\tilde{P}(\vec{Y}, \vec{Z})\vec{X}\} = 0. \quad (7.6)$$

Taking the inner product of (7.6) with ξ and using (1.1), (2.6), (2.8) and (2.19), which implies

$$\frac{\check{\Psi}}{2} \{g(\vec{X}, \vec{R}(\vec{Y}, \vec{Z})\vec{U}) - \frac{1}{2}(\frac{scal}{2} + f^2 + 2f)(g(\vec{X}, \vec{Y})g(\vec{Z}, \vec{U}) - g(\vec{X}, \vec{Z})g(\vec{Y}, \vec{U}))\} = 0. \quad (7.7)$$

It is clear that either $\check{\Psi}=0$, or it has the sectional curvature $\frac{1}{2}(\frac{scal}{2} + f^2 + 2f)$. \square

This leads to the proof of the Theorem 7.1.

For $\check{\Psi}=\frac{scal}{3}$ then Q -curvature tensor reduces to concircular curvature tensor. Therefore in view of the first result of the above Theorem 7.1 and use of (1.2), we can mention the following:

Corollary 7.2. *A f -Kenmotsu 3-manifolds with the Schouten-van Kampen connection $\tilde{\nabla}$ satisfying $\tilde{C} \cdot \tilde{Ric}=0$ then either concircular curvature tensor is equal to the Riemannian curvature tensor or it has the sectional curvature $\frac{1}{2}(f^2 + 2f)$.*

Again from Corollary 7.2, and (3.7), we have the following:

Corollary 7.3. *A f -Kenmotsu 3-manifolds with the Schouten-van Kampen connection $\tilde{\nabla}$ satisfying $\tilde{C} \cdot \tilde{Ric}=0$ then either Ricci soliton is shrinking or it has the sectional curvature $\frac{1}{2}(f^2 + 2f)$.*

If $0 \neq f = \text{constant}$ (we assume $f = \alpha$), then $\dot{f}=0$. Thus we state the followings:

Corollary 7.4. *An α -Kenmotsu 3-manifolds with the Schouten-van Kampen connection $\tilde{\nabla}$ satisfying $\tilde{C} \cdot \tilde{Ric}=0$ then either concircular curvature tensor is equal to the Riemannian curvature tensor or it has the sectional curvature $\frac{\alpha^2}{2}$.*

Corollary 7.5. *An α -Kenmotsu 3-manifolds with the Schouten-van Kampen connection $\tilde{\nabla}$ satisfying $\tilde{C} \cdot \tilde{Ric}=0$ then either Ricci soliton is shrinking or it has the sectional curvature $\frac{\alpha^2}{2}$.*

8. f -Kenmotsu 3-Manifolds Satisfying $\tilde{Q}(\xi, \vec{X}) \cdot \tilde{Q}=0$ with the Schouten-Van Kampen Connection

In this section we study f -Kenmotsu 3-manifolds with the Schouten-van Kampen connection $\tilde{\nabla}$ satisfying $\tilde{Q}(\xi, \vec{X}) \cdot \tilde{Q}=0$. We have the following:

Theorem 8.1. *A f -Kenmotsu 3-manifolds satisfying $\tilde{Q}(\xi, \vec{X}) \cdot \tilde{Q}=0$ with the Schouten-van Kampen connection $\tilde{\nabla}$ then either the Q -curvature tensor is equal to the Riemannian curvature or it has the sectional curvature $-(f^2 + f)$.*

Proof. The condition $(\tilde{Q}(\xi, \vec{X}) \cdot \tilde{Q})(\vec{Y}, \vec{Z})\vec{U}=0$ implies that

$$\tilde{Q}(\xi, \vec{X})\tilde{Q}(\vec{Y}, \vec{Z})\vec{U} - \tilde{Q}(\tilde{Q}(\xi, \vec{X})\vec{Y}, \vec{Z})\vec{U} - \tilde{Q}(\vec{Y}, \tilde{Q}(\xi, \vec{X})\vec{Z})\vec{U} - \tilde{Q}(\vec{Y}, \vec{Z})\tilde{Q}(\xi, \vec{X})\vec{U} = 0, \quad (8.1)$$

for any vector fields $\vec{X}, \vec{Y}, \vec{Z}$ and \vec{U} on \tilde{M} .

In view of (2.6) and (2.19), equation (1.3) reduces to

$$\tilde{Q}(\vec{Y}, \vec{Z})\vec{U} = \left\{ \frac{scal}{2} + 3f^2 + 2f - \frac{\check{\Psi}}{2} \right\} [g(\vec{Z}, \vec{U})\vec{Y} - g(\vec{Y}, \vec{U})\vec{Z}] - \left\{ \frac{scal}{2} + 3f^2 + 2f \right\} [g(\vec{Z}, \vec{U})\eta(\vec{Y})\xi - g(\vec{Y}, \vec{U})\eta(\vec{Z})\xi + \eta(\vec{Z})\eta(\vec{U})\vec{Y} - \eta(\vec{Y})\eta(\vec{U})\vec{Z}]. \quad (8.2)$$

Then we have

$$\tilde{Q}(\xi, \vec{Z})\vec{U} = -\frac{\check{\Psi}}{2} [g(\vec{Z}, \vec{U})\xi - \eta(\vec{U})\vec{Z}], \quad (8.3)$$

$$\tilde{Q}(\xi, \vec{X})\tilde{Q}(\vec{Y}, \vec{Z})\vec{U} = -\frac{\check{\Psi}}{2} [g(\vec{X}, \tilde{Q}(\vec{Y}, \vec{Z})\vec{U})\xi - \eta(\tilde{Q}(\vec{Y}, \vec{Z})\vec{U})\vec{X}], \quad (8.4)$$

$$\tilde{Q}(\tilde{Q}(\xi, \vec{X})\vec{Y}, \vec{Z})\vec{U} = -\frac{\check{\Psi}}{2} [g(\vec{X}, \vec{Y})\tilde{Q}(\xi, \vec{Z})\vec{U} - \eta(\vec{Y})\tilde{Q}(\vec{X}, \vec{Z})\vec{U}], \quad (8.5)$$

$$\tilde{Q}(\vec{Y}, \tilde{Q}(\xi, \vec{X})\vec{Z})\vec{U} = -\frac{\check{\Psi}}{2} [g(\vec{X}, \vec{Z})\tilde{Q}(\vec{Y}, \xi)\vec{U} - \eta(\vec{Z})\tilde{Q}(\vec{Y}, \vec{X})\vec{U}], \quad (8.6)$$

$$\tilde{Q}(\vec{Y}, \vec{Z})\tilde{Q}(\xi, \vec{X})\vec{U} = -\frac{\check{\Psi}}{2} [g(\vec{X}, \vec{U})\tilde{Q}(\vec{Y}, \vec{Z})\xi - \eta(\vec{U})\tilde{Q}(\vec{Y}, \vec{Z})\vec{X}]. \quad (8.7)$$

Using (8.4), (8.5), (8.6) and (8.7) in (8.1), we get

$$\begin{aligned} & \frac{\psi}{2}[-g(\vec{X}, \tilde{Q}(\vec{Y}, \vec{Z})\vec{U}))\xi + \eta(\tilde{Q}(\vec{Y}, \vec{Z})\vec{U})\vec{X} + g(\vec{X}, \vec{Y})\tilde{Q}(\xi, \vec{Z})\vec{U} - \eta(\vec{Y})\tilde{Q}(\vec{X}, \vec{Z})\vec{U} + g(\vec{X}, \vec{Z})\tilde{Q}(\vec{Y}, \xi)\vec{U} - \eta(\vec{Z})\tilde{Q}(\vec{Y}, \vec{X})\vec{U} \\ & + g(\vec{X}, \vec{U})\tilde{Q}(\vec{Y}, \vec{Z})\xi - \eta(\vec{U})\tilde{Q}(\vec{Y}, \vec{Z})\vec{X}] = 0. \end{aligned} \tag{8.8}$$

Taking the inner product of (8.8) with ξ , and using (8.2) and (8.3) we obtain

$$\frac{\psi}{2}[g(\vec{X}, \vec{R}(\vec{Y}, \vec{Z})\vec{U}) + (f^2 + f)[g(\vec{X}, \vec{Y})g(\vec{Z}, \vec{Y}) - g(\vec{X}, \vec{Z})g(\vec{Y}, \vec{U})] = 0. \tag{8.9}$$

This implies that either $\psi=0$, or it has the sectional curvature $-(f^2 + f)$.

If $\psi=0$, then from (1.3) we get $Q(\vec{X}, \vec{Y})\vec{Z} = \vec{R}(\vec{X}, \vec{Y})\vec{Z}$. This complete the proof. □

Further if $\psi = \frac{scal}{3}$ then Q -curvature tensor reduces to concircular curvature tensor. Therefore in view of Theorem 8.1 and use of (1.2), we have the followings:

Corollary 8.2. *A f -Kenmotsu 3-manifolds satisfying $\tilde{C}(\xi, \vec{X}) \cdot \tilde{C}=0$ with the Schouten-van Kampen connection $\tilde{\nabla}$ then either the concircular curvature tensor is equal to the Riemannian curvature or it has the sectional curvature $-(f^2 + f)$.*

Corollary 8.3. *A f -Kenmotsu 3-manifolds satisfying $\tilde{C}(\xi, \vec{X}) \cdot \tilde{C}=0$ with the Schouten-van Kampen connection $\tilde{\nabla}$ then either Ricci soltion is shrinking or it has the sectional curvature $-(f^2 + f)$.*

If $0 \neq f = \text{constant}$ (we assume $f = \alpha$), then $\dot{f} = 0$. Therefore, we have:

Corollary 8.4. *An α -Kenmotsu 3-manifolds satisfying $\tilde{C}(\xi, \vec{X}) \cdot \tilde{C}=0$ with the Schouten-van Kampen connection $\tilde{\nabla}$ then either the concircular curvature tensor is equal to the Riemannian curvature or it has the sectional curvature $-\alpha^2$.*

Corollary 8.5. *An α -Kenmotsu 3-manifolds satisfying $\tilde{C}(\xi, \vec{X}) \cdot \tilde{C}=0$ with the Schouten-van Kampen connection $\tilde{\nabla}$ then either Ricci soltion is shrinking or it has the sectional curvature $-\alpha^2$.*

9. f -Kenmotsu 3-Manifolds Bearing Ricci Soliton Satisfying $((\xi \wedge_{\tilde{Ric}} \vec{X}) \cdot \tilde{Q})=0$ with the Schouten-Van Kampen Connection

In this segment we study f -Kenmotsu 3-manifolds bearing Ricci soliton satisfying $((\xi \wedge_{\tilde{Ric}} \vec{X}) \cdot \tilde{Q})=0$ with the Schouten-van Kampen connection $\tilde{\nabla}$. Therefore, we have the following:

Theorem 9.1. *A f -Kenmotsu 3-manifolds bearing Ricci soliton satisfying $((\xi \wedge_{\tilde{Ric}} \vec{X}) \cdot \tilde{Q})=0$ with the Schouten-van Kampen connection $\tilde{\nabla}$ then either Q -curvature tensor is equal to the Riemannian curvature or soliton is steady.*

Proof. The condition $((\xi \wedge_{\tilde{Ric}} \vec{X}) \cdot \tilde{Q})(\vec{Y}, \vec{Z})\vec{U}=0$ implies that

$$\begin{aligned} & \tilde{Ric}(\vec{X}, \tilde{Q}(\vec{Y}, \vec{Z})\vec{U})\xi - \tilde{Ric}(\xi, \tilde{Q}(\vec{Y}, \vec{Z})\vec{U})\vec{X} - \tilde{Ric}(\vec{X}, \vec{Y})\tilde{Q}(\xi, \vec{Z})\vec{U} \\ & + \tilde{Ric}(\xi, \vec{Y})\tilde{Q}(\vec{X}, \vec{Z})\vec{U} - \tilde{Ric}(\vec{X}, \vec{Z})\tilde{Q}(\vec{Y}, \xi)\vec{U} + \tilde{Ric}(\xi, \vec{Z})\tilde{Q}(\vec{Y}, \vec{X})\vec{U} \\ & - \tilde{Ric}(\vec{X}, \vec{U})\tilde{Q}(\vec{Y}, \vec{Z})\xi + \tilde{Ric}(\xi, \vec{U})\tilde{Q}(\vec{Y}, \vec{Z})\vec{X} = 0. \end{aligned} \tag{9.1}$$

Using (3.4) in (9.1), we get

$$\begin{aligned} & -\lambda g(\vec{X}, \tilde{Q}(\vec{Y}, \vec{Z})\vec{U})\xi + \lambda \eta(\tilde{Q}(\vec{Y}, \vec{Z})\vec{U})\vec{X} + \lambda g(\vec{X}, \vec{Y})\tilde{Q}(\xi, \vec{Z})\vec{U} \\ & - \lambda \eta(\vec{Y})\tilde{Q}(\vec{X}, \vec{Z})\vec{U} + \lambda g(\vec{X}, \vec{Z})\tilde{Q}(\vec{Y}, \xi)\vec{U} - \lambda \eta(\vec{Z})\tilde{Q}(\vec{Y}, \vec{X})\vec{U} \\ & + \lambda g(\vec{X}, \vec{U})\tilde{Q}(\vec{Y}, \vec{Z})\xi - \lambda \eta(\vec{U})\tilde{Q}(\vec{Y}, \vec{Z})\vec{X} = 0. \end{aligned} \tag{9.2}$$

Taking the inner product of (9.2) with ξ and using (8.2) that implies

$$\begin{aligned} & \left\{ \left(\frac{scal}{2} + 3f^2 + 2f - \frac{\psi}{2} \right) [-\lambda g(\vec{Z}, \vec{U})g(\vec{X}, \vec{Y}) + 3\lambda g(\vec{Y}, \vec{U})g(\vec{X}, \vec{Z}) + 3\lambda g(\vec{Z}, \vec{U})\eta(\vec{Y}) \right. \\ & \left. - 3\lambda g(\vec{Y}, \vec{U})\eta(\vec{Z})] - \left\{ \frac{scal}{2} + 3f^2 + 2f \right\} [-3\lambda g(\vec{Z}, \vec{U})\eta(\vec{X})\eta(\vec{Y}) + 3\lambda g(\vec{Y}, \vec{U})\eta(\vec{X})\eta(\vec{Z})] \right. \\ & \left. - 3\lambda g(\vec{X}, \vec{Y})\eta(\vec{Z})\eta(\vec{U}) + 3\lambda g(\vec{X}, \vec{Z})\eta(\vec{Y})\eta(\vec{U}) + 3\lambda g(\vec{Z}, \vec{U})\eta(\vec{Y}) \right. \\ & \left. - 3\lambda g(\vec{Y}, \vec{U})\eta(\vec{Z}) \right\} + \frac{\psi}{2} [-3\lambda g(\vec{X}, \vec{Y})g(\vec{Z}, \vec{U}) + 3\lambda g(\vec{X}, \vec{Y})\eta(\vec{Z})\eta(\vec{U}) \\ & + 3\lambda g(\vec{Z}, \vec{U})\eta(\vec{X})\eta(\vec{Y}) - 3\lambda g(\vec{X}, \vec{U})\eta(\vec{Z})\eta(\vec{Y}) - 3\lambda g(\vec{X}, \vec{Z})\eta(\vec{Y})\eta(\vec{U}) \\ & + 3\lambda g(\vec{X}, \vec{Z})g(\vec{Y}, \vec{U}) + 3\lambda g(\vec{X}, \vec{U})\eta(\vec{Y})\eta(\vec{Z}) - 3\lambda g(\vec{Y}, \vec{U})\eta(\vec{Y})\eta(\vec{X}) \\ & + 3\lambda g(\vec{X}, \vec{Z})\eta(\vec{Y})\eta(\vec{U}) - 3\lambda g(\vec{X}, \vec{Y})\eta(\vec{Z})\eta(\vec{U})] = 0. \end{aligned} \tag{9.3}$$

For fix $\vec{U}=\xi$ in (9.3) and on simplification, we get

$$3\lambda \psi [g(\vec{X}, \vec{Z})\eta(\vec{Y}) - g(\vec{X}, \vec{Y})\eta(\vec{Z})] = 0. \tag{9.4}$$

This implies that either $\lambda=0$, or $\psi=0$. If $\lambda=0$, and $\psi \neq 0$, then the Ricci soliton is steady. Whereas if $\lambda \neq 0$ and $\psi=0$, so from (1.3), we obtain $Q(\vec{X}, \vec{Y})\vec{Z}=\vec{R}(\vec{X}, \vec{Y})\vec{Z}$. This complete the proof. □

As per consequence if $\psi = \frac{scal}{3}$ then Q -curvature tensor reduces to concircular curvature tensor. Therefore in view of Theorem 9.1 and use of (1.2), we have the following:

Corollary 9.2. *A f -Kenmotsu 3-manifolds bearing Ricci soliton satisfying $((\xi \wedge_{\tilde{Ric}} \vec{X}) \cdot \tilde{C})=0$ with the Schouten-van Kampen connection $\tilde{\nabla}$ then either concircular curvature tensor is equal to the Riemannian curvature or Ricci soliton is steady.*

10. Examples

Example 10.1. We consider the 3-dimensional manifold $\vec{M} = \{(u, v, w) \in \mathfrak{R}^3, w \neq 0\}$, where (u, v, w) are the standard coordinate in \mathfrak{R}^3 . Let $(\vec{e}_1, \vec{e}_2, \vec{e}_3)$ be linearly independent vector fields at each point of \vec{M} , given by

$$\vec{e}_1 = \frac{1}{w} \frac{\partial}{\partial u}, \quad \vec{e}_2 = \frac{1}{w} \frac{\partial}{\partial v}, \quad \vec{e}_3 = -\frac{\partial}{\partial w}$$

are linearly independent at each point of \vec{M} . Let g be the Riemannian metric defined

$$g(\vec{e}_1, \vec{e}_2) = g(\vec{e}_2, \vec{e}_3) = g(\vec{e}_1, \vec{e}_3) = 0, \quad g(\vec{e}_1, \vec{e}_1) = g(\vec{e}_2, \vec{e}_2) = g(\vec{e}_3, \vec{e}_3) = 1.$$

and given by

$$g = w^2 [du \otimes du + dv \otimes dv + \frac{1}{w^2} dw \otimes dw].$$

Let η be the 1-form have the significance

$$\eta(\vec{U}) = g(\vec{U}, \vec{e}_3)$$

for any $\vec{U} \in \Gamma(T\vec{M})$ and $\check{\phi}$ be the $(1, 1)$ -tensor field defined by

$$\check{\phi}\vec{e}_1 = -\vec{e}_2, \quad \check{\phi}\vec{e}_2 = \vec{e}_1, \quad \check{\phi}\vec{e}_3 = 0.$$

Making use of the linearity of $\check{\phi}$ and g we have

$$\eta(\vec{e}_3) = 1, \quad \check{\phi}^2(\vec{U}) = -\vec{U} + \eta(\vec{U})\vec{e}_3, \quad g(\check{\phi}\vec{U}, \check{\phi}\vec{V}) = g(\vec{U}, \vec{V}) - \eta(\vec{U})\eta(\vec{V}),$$

for any $\vec{U}, \vec{V} \in \Gamma(T\vec{M})$. Now we can easily calculate

$$[\vec{e}_1, \vec{e}_2] = 0, \quad [\vec{e}_1, \vec{e}_3] = -\frac{1}{w}\vec{e}_2, \quad [\vec{e}_2, \vec{e}_3] = -\frac{1}{w}\vec{e}_1.$$

The Riemannian connection $\vec{\nabla}$ of the metric tensor g is given by the Koszul's formula, i. e.,

$$2g(\vec{\nabla}_{\vec{U}}\vec{V}, \vec{W}) = \vec{U}(g(\vec{V}, \vec{W})) + \vec{V}(g(\vec{W}, \vec{X})) - \vec{W}(g(\vec{U}, \vec{V})) - g(\vec{U}, [\vec{V}, \vec{W}]) - g(\vec{V}, [\vec{U}, \vec{W}]) + g(\vec{W}, [\vec{U}, \vec{V}]).$$

Making use of Koszul's formula we get the following:

$$\begin{aligned} \vec{\nabla}_{\vec{e}_2}\vec{e}_3 &= -\frac{1}{w}\vec{e}_2, & \vec{\nabla}_{\vec{e}_2}\vec{e}_2 &= \frac{1}{w}\vec{e}_3, & \vec{\nabla}_{\vec{e}_2}\vec{e}_1 &= 0, \\ \vec{\nabla}_{\vec{e}_3}\vec{e}_3 &= 0, & \vec{\nabla}_{\vec{e}_3}\vec{e}_2 &= 0, & \vec{\nabla}_{\vec{e}_3}\vec{e}_1 &= 0, \\ \vec{\nabla}_{\vec{e}_1}\vec{e}_3 &= -\frac{1}{w}\vec{e}_1, & \vec{\nabla}_{\vec{e}_1}\vec{e}_2 &= 0, & \vec{\nabla}_{\vec{e}_1}\vec{e}_1 &= \frac{1}{w}\vec{e}_3. \end{aligned}$$

Consequently it is clear that \vec{M} satisfies the condition $\vec{\nabla}_{\vec{U}}\xi = f\{\vec{U} - \eta(\vec{U})\xi\}$ for $\vec{e}_3 = \xi$, where $f = -\frac{1}{w}$. Thus we conclude that \vec{M} leads to f -Kenmotsu manifold. Also $f^2 + \check{f} = \frac{2}{w^2} \neq 0$. That implies \vec{M} is a regular f -Kenmotsu 3-manifold. Also the Schouten-van Kampen connection $\tilde{\nabla}$ on \vec{M} as follows

$$\begin{aligned} \tilde{\nabla}_{\vec{e}_2}\vec{e}_3 &= -(\frac{1}{w} + f)\vec{e}_2, & \tilde{\nabla}_{\vec{e}_2}\vec{e}_2 &= (\frac{1}{w} + f)\vec{e}_3, & \tilde{\nabla}_{\vec{e}_2}\vec{e}_1 &= 0, \\ \tilde{\nabla}_{\vec{e}_3}\vec{e}_3 &= 0, & \tilde{\nabla}_{\vec{e}_3}\vec{e}_2 &= 0, & \tilde{\nabla}_{\vec{e}_3}\vec{e}_1 &= 0, \\ \tilde{\nabla}_{\vec{e}_1}\vec{e}_3 &= -(\frac{1}{w} + f)\vec{e}_1, & \tilde{\nabla}_{\vec{e}_1}\vec{e}_2 &= 0, & \tilde{\nabla}_{\vec{e}_1}\vec{e}_1 &= (\frac{1}{w} + f)\vec{e}_3. \end{aligned}$$

It is clear that for $\vec{e}_3 = \xi$ and $f = -\frac{1}{w}$, we get $\tilde{\nabla}_{\vec{e}_i}\vec{e}_j = 0$ ($1 \leq i, j \leq 3$). So the manifold \vec{M} is a f -Kenmotsu 3-manifold with the Schouten-van Kampen connection $\tilde{\nabla}$. Also one can see that $\tilde{R} = 0$. Thus the manifold \vec{M} is a flat manifold with respect to the Schouten-van Kampen connection $\tilde{\nabla}$. Since a flat manifold is a Ricci-flat manifold with respect to the Schouten-van Kampen connection $\tilde{\nabla}$. So from (3.4), we get $\lambda = 0$, that is Ricci soliton is always steady on regular f -Kenmotsu 3-manifold with the Schouten-van Kampen connection $\tilde{\nabla}$. In case of Ricci soliton, from (3.4) it is sufficient to verify that

$$\tilde{Ric}(\vec{e}_i, \vec{e}_i) = -(\lambda + f)g(\vec{e}_i, \vec{e}_i) + f\eta(\vec{e}_i)\eta(\vec{e}_i), \quad i = 1, 2, 3. \quad (10.1)$$

It is clear that $\lambda = 0$, that is Ricci soliton is always steady on regular f -Kenmotsu 3-manifold with the Schouten-van Kampen connection $\tilde{\nabla}$. Hence Proposition 3.2, Corollary 3.6 and Corollary 3.7 are hold.

Example 10.2. We consider the 3-dimensional manifold $\vec{M} = \{(u, v, w) \in \mathfrak{R}^3, w \neq 0\}$, where (u, v, w) are the standard coordinate in \mathfrak{R}^3 . Let $(\vec{e}_1, \vec{e}_2, \vec{e}_3)$ be linearly independent vector fields at each point of \vec{M} , given by

$$\vec{e}_1 = \sin^2 w \frac{\partial}{\partial u}, \quad \vec{e}_2 = \sin^2 w \frac{\partial}{\partial v}, \quad \vec{e}_3 = \sin w \frac{\partial}{\partial w}.$$

are linearly independent at each point of \vec{M} . Let g be the Riemannian metric defined

$$g(\vec{e}_1, \vec{e}_2) = g(\vec{e}_2, \vec{e}_3) = g(\vec{e}_1, \vec{e}_3) = 0, \quad g(\vec{e}_1, \vec{e}_1) = g(\vec{e}_2, \vec{e}_2) = g(\vec{e}_3, \vec{e}_3) = 1.$$

and given by

$$g = \sin^4 w [du \otimes du + dv \otimes dv + \frac{1}{\sin^2 w} dw \otimes dw].$$

Let η be the 1-form have the significance

$$\eta(\vec{U}) = g(\vec{U}, \vec{e}_3)$$

for any $\vec{U} \in \Gamma(TM)$ and $\check{\phi}$ be the (1, 1)-tensor field defined by

$$\check{\phi}\vec{e}_1 = -\vec{e}_2, \quad \check{\phi}\vec{e}_2 = \vec{e}_1, \quad \check{\phi}\vec{e}_3 = 0.$$

Making use of the linearity of $\check{\phi}$ and g we have

$$\eta(\vec{e}_3) = 1, \quad \check{\phi}^2(\vec{U}) = -\vec{U} + \eta(\vec{U})\vec{e}_3, \quad g(\check{\phi}\vec{U}, \check{\phi}\vec{V}) = g(\vec{U}, \vec{V}) - \eta(\vec{U})\eta(\vec{V}),$$

for any $\vec{U}, \vec{V} \in \Gamma(T\vec{M})$. Now we can easily calculate

$$[\vec{e}_1, \vec{e}_2] = 0, \quad [\vec{e}_1, \vec{e}_3] = -2\cos w \vec{e}_2, \quad [\vec{e}_2, \vec{e}_3] = -2\cos w \vec{e}_1.$$

The Riemannian connection $\vec{\nabla}$ of the metric tensor g is given by the Koszul's formula, that is.,

$$2g(\nabla_{\vec{U}}\vec{V}, \vec{W}) = \vec{U}(g(\vec{V}, \vec{W})) + \vec{V}(g(\vec{W}, \vec{X})) - \vec{W}(g(\vec{U}, \vec{V})) - g(\vec{U}, [\vec{V}, \vec{W}]) - g(\vec{V}, [\vec{U}, \vec{W}]) + g(\vec{W}, [\vec{U}, \vec{V}]).$$

Making use Koszul's formula we get the following:

$$\begin{aligned} \vec{\nabla}_{\vec{e}_2}\vec{e}_3 &= -2\cos w \vec{e}_2, & \vec{\nabla}_{\vec{e}_2}\vec{e}_2 &= 2\cos w \vec{e}_3, & \vec{\nabla}_{\vec{e}_2}\vec{e}_1 &= 0, \\ \vec{\nabla}_{\vec{e}_3}\vec{e}_3 &= 0, & \vec{\nabla}_{\vec{e}_3}\vec{e}_2 &= 0, & \vec{\nabla}_{\vec{e}_3}\vec{e}_1 &= 0, \\ \vec{\nabla}_{\vec{e}_1}\vec{e}_3 &= -2\cos w \vec{e}_1, & \vec{\nabla}_{\vec{e}_1}\vec{e}_2 &= 0, & \vec{\nabla}_{\vec{e}_1}\vec{e}_1 &= 2\cos w \vec{e}_3. \end{aligned}$$

Consequently it is clear that \vec{M} satisfies the condition $\vec{\nabla}_U \xi = f\{\vec{U} - \eta(\vec{U})\xi\}$ for $\vec{e}_3 = \xi$, where $f = -2\cos w$. Thus we conclude that \vec{M} leads to f -Kenmotsu manifold. Also $f^2 + f = 2\cos w(2\cos w + \tan w) \neq 0$, which implies that \vec{M} is a regular f -Kenmotsu 3-manifold. It is known that

$$\vec{R}(\vec{X}, \vec{Y})\vec{Z} = \vec{\nabla}_{\vec{X}}\vec{\nabla}_{\vec{Y}}\vec{Z} - \vec{\nabla}_{\vec{Y}}\vec{\nabla}_{\vec{X}}\vec{Z} - \vec{\nabla}_{[\vec{X}, \vec{Y}]} \vec{Z}.$$

Therefore, we find the component of curvature tensor as follows

$$\begin{aligned} \vec{R}(\vec{e}_2, \vec{e}_3)\vec{e}_3 &= -2(\sin w + 2\cos^2 w)\vec{e}_2, & \vec{R}(\vec{e}_3, \vec{e}_2)\vec{e}_2 &= -2(\sin w + 2\cos^2 w)\vec{e}_3, \\ \vec{R}(\vec{e}_1, \vec{e}_3)\vec{e}_3 &= -2(\sin w + 2\cos^2 w)\vec{e}_1, & \vec{R}(\vec{e}_3, \vec{e}_1)\vec{e}_1 &= -2(\sin w + 2\cos^2 w)\vec{e}_2, \\ \vec{R}(\vec{e}_3, \vec{e}_1)\vec{e}_2 &= 0, & \vec{R}(\vec{e}_1, \vec{e}_2)\vec{e}_2 &= -4\cos^2 w \vec{e}_1, & \vec{R}(\vec{e}_1, \vec{e}_2)\vec{e}_3 &= 0, \\ \vec{R}(\vec{e}_2, \vec{e}_3)\vec{e}_1 &= 0, & \vec{R}(\vec{e}_2, \vec{e}_1)\vec{e}_1 &= 4\cos^2 w \vec{e}_3. \end{aligned}$$

The Schouten-van Kampen connection $\vec{\tilde{\nabla}}$ on \vec{M} is given by

$$\begin{aligned} \vec{\tilde{\nabla}}_{\vec{e}_2}\vec{e}_3 &= (-2\cos w - f)\vec{e}_2, & \vec{\tilde{\nabla}}_{\vec{e}_2}\vec{e}_2 &= (-2\cos w - f)\vec{e}_3, & \vec{\tilde{\nabla}}_{\vec{e}_2}\vec{e}_1 &= 0, \\ \vec{\tilde{\nabla}}_{\vec{e}_3}\vec{e}_3 &= 0, & \vec{\tilde{\nabla}}_{\vec{e}_3}\vec{e}_2 &= 0, & \vec{\tilde{\nabla}}_{\vec{e}_3}\vec{e}_1 &= 0, \\ \vec{\tilde{\nabla}}_{\vec{e}_1}\vec{e}_3 &= (-2\cos w - f)\vec{e}_1, & \vec{\tilde{\nabla}}_{\vec{e}_1}\vec{e}_2 &= 0, & \vec{\tilde{\nabla}}_{\vec{e}_1}\vec{e}_1 &= (-2\cos w - f)\vec{e}_3. \end{aligned}$$

It is clear that for $\vec{e}_3 = \xi$ and $f = -2\cos w$, we get $\vec{\tilde{\nabla}}_{\vec{e}_i}\vec{e}_j = 0$ ($1 \leq i, j \leq 3$). So the manifold \vec{M} is a f -Kenmotsu 3-manifold with the Schouten-van Kampen connection $\vec{\tilde{\nabla}}$. Also from above curvature component one can be seen that $\vec{R} = 0$. Thus the manifold \vec{M} is a flat manifold with respect to the Schouten-van Kampen connection $\vec{\tilde{\nabla}}$. Since a flat manifold is a Ricci-flat manifold with respect to the Schouten-van Kampen connection $\vec{\tilde{\nabla}}$.

In case of Ricci soliton, from (3.4) it is sufficient to verify that

$$\vec{Ric}(\vec{e}_i, \vec{e}_i) = -(\lambda + f)g(\vec{e}_i, \vec{e}_i) + f\eta(\vec{e}_i)\eta(\vec{e}_i), \quad i = 1, 2, 3. \tag{10.2}$$

It is clear that $\lambda = 0$, that is Ricci soliton is always steady on regular f -Kenmotsu 3-manifold with the Schouten-van Kampen connection $\vec{\tilde{\nabla}}$. Hence Proposition 3.2, Corollary 3.6 and Corollary 3.7 are hold.

11. Conclusion

In this study, we examine certain new curvature conditions of Q -curvature tensor on f -Kenmotsu 3-manifold admitting the Schouten-van Kampen connection $\vec{\tilde{\nabla}}$ and deduce some geometrical results. Also we explore the nature of Ricci soliton.

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