



# Fixed Point Theorem Through $\Omega$ -distance of Suzuki Type Contraction Condition

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## ABSTRACT

In this article, we utilize the notion of  $\Omega$ -distance in the sense of Saadati et al [ R. Saadati, S.M. Vaezpour, P. Vetro and B.E. Rhoades, Fixed point theorems in generalized partially ordered G-metric spaces, Mathematical and Computer Modeling, 52, 797-801, 2010 ] to introduce and prove some fixed point results of self-mapping under contraction conditions of the form  $\Omega$ -Suzuki-contractions.

**Key Words:**  $\Omega$ -Distance, Fixed Point Theory, G-Metric Space.

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## 1. INTRODUCTION

G-metric space was introduced by Mustafa and Sims [1] in 2006, which is a generalization of metric space. Since 2006, many researchers have worked on G-metric spaces; see for example [2]-[10].

Samet et al in [11] and [12] proved that many results in G-metric spaces can be derived from known results of the corresponding usual metric space. Moreover, the notion of  $\Omega$ -distance related to a complete G-metric space was considered by Saadati *et.al.* [13] in 2010.

Recently, many researchers studied several fixed point results using  $\Omega$ -distance mappings; see for example, [14]-[17]. It is worth mentioning that the interesting method of Samet et. al. [11] and [12] doesn't work in the fixed point results involving  $\Omega$ -distance.

In this paper, we prove new results of fixed point theorem using the map  $\Omega$  in a complete G-metric space under contractive conditions of the form  $\Omega$ -Suzuki-contraction.

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**Definition 1.1.** [1]. Let  $X$  be a nonempty set, and let  $G : X \times X \times X \rightarrow \mathbf{R}^+$  be a function that satisfies the following conditions:

- (G1)  $G(x, y, z) = 0$  if  $x = y = z$ ;  
 (G2)  $G(x, x, y) > 0$  for all  $x, y \in X$  with  $x \neq y$ ;  
 (G3)  $G(x, y, z) \leq G(x, y, z)$  for all  $x, y, z \in X$  with  $y \neq z$ ;  
 (G4)  $G(x, y, z) = G(p\{x, y, z\})$ , for any permutation of  $x, y, z$ ;  
 (G5)  $G(x, y, z) \leq G(x, a, a) + G(a, y, z)$  for all  $x, y, z, a \in X$ .

Then the function  $G$  is called a generalized metric space, or more specifically  $G$ -metric on  $X$ , and the pair  $(X, G)$  is called a  $G$ -metric space.

The notion of convergence and Cauchy sequences in the setting of a  $G$ -metric space are given as follows:

**Definition 1.2.** [1]. Let  $(X, G)$  be a  $G$ -metric space, and let  $(x_n)$  be a sequence of points of  $X$ . We say that  $(x_n)$  is  $G$ -convergent to  $x$  if for any  $\epsilon > 0$ , there exists  $k \in \mathbf{N}$  such that  $G(x, x_n, x_m) < \epsilon$  for all  $n, m \geq k$ .

**Definition 1.3.** [1]. Let  $(X, G)$  be a  $G$ -metric space. A sequence  $(x_n)$  in  $X$  is said to be  $G$ -Cauchy if for every  $\epsilon > 0$ , there exists  $k \in \mathbf{N}$  such that  $G(x_n, x_m, x_l) < \epsilon$  for all  $n, m, l \geq k$ .

**Definition 1.4.** [5]. A  $G$ -metric space  $(X, G)$  is said to be  $G$ -complete or complete  $G$ -metric space if every  $G$ -Cauchy sequence in  $(X, G)$  is  $G$ -convergent in  $(X, G)$ .

In 2010, Saadati *et al.* [13] introduced the notion of  $\Omega$ -distance related to a complete  $G$ -metric space and proved many results.

**Definition 1.5.** [13]. Let  $(X, G)$  be a  $G$ -metric space. Then a function  $\Omega : X \times X \times X \rightarrow [0, \infty)$  is called an  $\Omega$ -distance on  $X$  if the following conditions are satisfied:

- (a)  $\Omega(x, y, z) \leq \Omega(x, a, a) + \Omega(a, y, z)$  for all  $x, y, z, a \in X$ ;  
 (b) for any  $x, y \in X$ , the functions  $\Omega(x, y, \cdot)$ ,  $\Omega(x, \cdot, y) : X \rightarrow [0, \infty)$  are lower semi continuous,  
 (c) for each  $\epsilon > 0$ , there exists  $\delta > 0$  such that if  $\Omega(x, a, a) \leq \delta$  and  $\Omega(a, y, z) \leq \delta$ , then  $\Omega(x, y, z) \leq \epsilon$ .

**Definition 1.6.** [13]. Let  $(X, G)$  be a  $G$ -metric space and  $\Omega$  be an  $\Omega$ -distance on  $X$ . Then we say that  $X$  is  $\Omega$ -bounded if there exists  $M > 0$  such that  $\Omega(x, y, z) \leq M$  for all  $x, y, z \in X$ .

The following lemma plays an important role in the development of the results in this article.

**Lemma 1.1.** [13]. Let  $X$  be a metric space with metric  $G$  and  $\Omega$  be an  $\Omega$ -distance on  $X$ . Let  $(x_n), (y_n)$  be sequences in  $X$ , and  $(\alpha_n), (\beta_n)$  be sequences in  $[0, \infty)$  converging to zero. Then for all  $x, y, z, a \in X$ , we have the following:

- (1) If  $\Omega(y, x_n, x_n) \leq \alpha_n$  and  $\Omega(x_n, y, z) \leq \beta_n$  for  $n \in \mathbf{N}$ , then  $\Omega(y, y, z) < s$  and hence  $y = z$ ;  
 (2) If  $\Omega(y_n, x_n, x_n) \leq \alpha_n$  and  $\Omega(x_n, y_m, z) \leq \beta_n$  for all  $m$

$> n \in \mathbf{N}$ , then  $\Omega(y_n, y_m, z) \rightarrow 0$  and hence  $y_n \rightarrow z$ ;

- (3) If  $\Omega(x_n, x_m, x_l) \leq \alpha_n$  then the sequence  $(x_n)$  is a  $G$ -Cauchy sequence, for all  $m, n, l \in \mathbf{N}$  with  $n \leq m \leq l$ ;  
 (4) If  $\Omega(x_n, a, a) \leq \alpha_n$  for any  $n \in \mathbf{N}$ , then  $(x_n)$  is a  $G$ -Cauchy sequence.

## 2. MAIN RESULT

**Definition 2.7.** [19] A nondecreasing continuous function  $\varphi : [0, \infty) \rightarrow [0, \infty)$  is called an altering distance function if the following condition holds;  $\varphi(t) = 0$  if and only if  $t = 0$ .

**Definition 2.8.** A mapping  $T : X \rightarrow X$  of a  $G$ -metric space  $(X, G)$  is called an  $\Omega$ -Suzuki-contraction if there exists  $k \in [0, 1)$  and an altering distance function  $\varphi$  such that for all  $x, y, z \in X$  and  $p, q \in \mathbf{N}$  with  $q \geq p$ , the following condition holds

$$\text{if } (1 - k) \Omega(x, T^p x, T^q x) \leq \Omega(x, y, z), \text{ then } \varphi \Omega(Tx, Ty, Tz) \leq k \varphi \Omega(x, y, z).$$

**Theorem 2.2.** Let  $(X, G)$  be a complete  $G$ -metric space and  $\Omega$  be an  $\Omega$ -distance on  $X$  such that  $X$  is  $\Omega$ -bounded. Let  $T : X \rightarrow X$  be an  $\Omega$ -Suzuki-contraction mapping that satisfies the following condition:

for all  $u \in X$  if  $Tu \neq u$ , then

$$\inf\{\Omega(x, Tx, u) : x \in X\} > 0. \quad (2.1)$$

Then  $T$  has a fixed point in  $X$ . Moreover, for any fixed Point  $z \in X$  of  $T$ , we have  $\Omega(z, z, z) = 0$ .

*Proof.* Let  $x_0 \in X$  and define a sequence  $(x_n)$  in  $X$  inductively by setting  $x_n = T x_{n-1}$ ,  $n \in \mathbf{N}$ .

For  $p = q = 1$ , since  $(1 - k) \Omega(x, Tx, Tx) \leq \Omega(x, Tx, Tx)$  holds for every  $x \in X$ , we have

$$\varphi \Omega(Tx, T^2 x, T^2 x) \leq k \varphi \Omega(x, Tx, Tx). \quad (2.2)$$

Substituting  $x = x_{n-1}$  in the inequality (2.2), gives us

$$\varphi \Omega(x_n, x_{n+1}, x_{n+1}) = \varphi \Omega(Tx_{n-1}, Tx_n, Tx_n) \leq k \varphi \Omega(x_{n-1}, x_n, x_n). \quad (2.3)$$

Since  $k < 1$  and  $\varphi$  is an altering distance function, the sequence  $(\Omega(x_n, x_{n+1}, x_{n+1}) : n \in \mathbf{N})$  is a non-increasing sequence of nonnegative real numbers. Therefore, there is  $r \geq 0$  such that

$$\lim_{n \rightarrow \infty} \Omega(x_n, x_{n+1}, x_{n+1}) = r.$$

Taking the limit as  $n \rightarrow \infty$  in 2.3, implies that  $\varphi r \leq k \varphi r$  and thus  $r = 0$ , since  $k < 1$ . Hence

$$\lim_{n \rightarrow \infty} \Omega(x_n, x_{n+1}, x_{n+1}) = 0. \quad (2.4)$$

Moreover, for  $p = 1$ , and  $q \geq 1$ , since  $(1 - k) \Omega(x, Tx, T^q x) \leq \Omega(x, Tx, T^q x)$  holds for every  $x \in X$ , then

$$\varphi \Omega(Tx, T^2 x, T^{q+1} x) \leq k \varphi \Omega(x, Tx, T^q x). \quad (2.5)$$

For  $n, s \in \mathbf{N}$  with  $s \geq 1$ , substituting  $x = x_{n-1}$  in (2.5), implies that

$$\begin{aligned} \varphi\Omega(x_n, x_{n+1}, x_{n+s}) &= \varphi\Omega(Tx_{n-1}, Tx_n, Tx_{n+s-1}) \\ &\leq k \varphi\Omega(x_{n-1}, x_n, x_{n+s-1}). \end{aligned} \tag{2.6}$$

Since  $k < 1$  and  $\varphi$  is an altering distance function, the sequence  $(\Omega(x_n, x_{n+1}, x_{n+s}) : n \in \mathbb{N})$  is a non-increasing sequence of nonnegative real numbers. Therefore, there is  $r \geq 0$  such that

$$\lim_{n \rightarrow \infty} \Omega(x_n, x_{n+1}, x_{n+s}) = r.$$

Applying the limit as  $n \rightarrow \infty$  to the inequality 2.6, gives us  $\varphi r \leq k \varphi r$ . Since  $k < 1$ , we have  $r = 0$  and hence

$$\lim_{n \rightarrow \infty} \Omega(x_n, x_{n+1}, x_{n+s}) = 0, \text{ for all } s \geq 1. \tag{2.7}$$

Considering the Definition 1.5, implies that

$$\Omega(x_n, x_m, x_l) \leq \Omega(x_n, x_{n+1}, x_{n+1}) + \Omega(x_{n+1}, x_{n+2}, x_{n+2}) + \dots + \Omega(x_{m-1}, x_m, x_l),$$

for all  $l, m, n \in \mathbb{N}$  with  $l \geq m \geq n$ ,  $m = n + s$  and  $l = m + t$ .

By taking the limit of the above inequality as  $n \rightarrow \infty$ , we get

$$\lim_{n, m, l \rightarrow \infty} \Omega(x_n, x_m, x_l) = 0.$$

Lemma 1.1 implies that  $(x_n)$  is a G-Cauchy sequence and hence  $(x_n)$  converges to an element  $u \in X$ . For all  $\epsilon > 0$ , since  $(x_n)$  is a G-Cauchy sequence, there exists  $N \in \mathbb{N}$  such that  $\Omega(x_n, x_m, x_l) < \epsilon$ , for all  $n, m, l \geq N$ . Thus,

$$\lim_{l \rightarrow \infty} \inf \Omega(x_n, x_m, x_l) \leq \epsilon, \text{ for all } n, m \geq N.$$

The lower semi-continuity of  $\Omega$  implies that

$$\Omega(x_n, x_m, u) \leq \lim_{l \rightarrow \infty} \inf \Omega(x_n, x_m, x_l) \leq \epsilon, \text{ for all } n, m \geq N.$$

Considering  $m = n + 1$  in (2.8), gives us  $\Omega(x_n, x_{n+1}, u) \leq \epsilon$ , for all  $n \geq N$ .

Assume that  $Tu \neq u$ . Then 2.1 implies that

$$0 < \inf\{\Omega(x, Tx, u) : x \in X\} \leq \inf\{\Omega(x_n, x_{n+1}, u) :$$

$$n \geq N\} \leq \epsilon, \text{ for all } \epsilon > 0 \text{ which is a contradiction.}$$

Therefore  $Tu = u$ . Let  $z = Tz$ . Then by (2.2), we have

$$\Omega(z, z, z) = \Omega(Tz, T^2z, T^2z) \leq k \varphi\Omega(z, Tz, Tz) =$$

$$k \varphi\Omega(z, z, z).$$

Since  $k < 1$  and  $\varphi$  is an altering distance function, we have  $\Omega(z, z, z) = 0$ .

**Definition 2.9.** A mapping  $T : X \rightarrow X$  of a G-metric space  $(X, G)$  is called a generalized  $\Omega$ -Suzuki-contraction if there exists  $k \in [0, 1)$  and an altering distance function  $\varphi$  such that the following condition holds:

If for all  $p, q \in \mathbb{N}$  with  $q \geq p$ ,

$$(1 - k) \Omega(x, T^p x, T^q x) \leq \Omega(x, y, z)$$

then we have

$$\Omega(Tx, Ty, Tz) \leq k \max\{\Omega(x, Tx, Tx), \Omega(y, Ty, Ty), \Omega(z, Tz, Tz)\}$$

for all  $x, y, z \in X$ .

**Lemma 2.3.** Let  $T : X \rightarrow X$  be a generalized  $\Omega$ -Suzuki-contraction. Then

$$\Omega(Tx, T^2x, T^2x) \leq k \Omega(x, Tx, Tx) \text{ for all } x \in X. \tag{2.9}$$

*Proof.* Assume  $p = q = 1$ . Since  $(1 - k)\Omega(x, Tx, Tx) \leq \Omega(x, Tx, Tx)$  holds for every  $x \in X$ , then we have

If  $\max\{\Omega(x, Tx, Tx), \Omega(x, T^2x, T^2x)\} = \Omega(x, T^2x, T^2x)$ , then  $\Omega(x, T^2x, T^2x) \leq k\Omega(x, T^2x, T^2x)$  which is a contradiction, since  $k < 1$ . Therefore,  $\max\{\Omega(x, Tx, Tx), \Omega(x, T^2x, T^2x)\} = \Omega(x, Tx, Tx)$  and hence

$$\Omega(Tx, T^2x, T^2x) \leq k \Omega(x, Tx, Tx) \text{ for all } x \in X. \tag{2.10}$$

**Lemma 2.4.** Let  $q \geq 1$  and  $T : X \rightarrow X$  be a generalized  $\Omega$ -Suzuki-contraction. Then

$$\Omega(T^q x, T^{q+1} x, T^{q+1} x) \leq k^q \Omega(x, Tx, Tx) \text{ for all } x \in X.$$

*Proof.* By substituting  $x$  in Lemma (2.3) by  $T^{q-1}x$ , we get

$$\begin{aligned} \Omega(T^q x, T^{q+1} x, T^{q+1} x) &= \Omega(T(T^{q-1}x), T(T^q x), \\ &\quad T(T^q x)) \\ &\leq k \Omega(T^{q-1}x, T^q x, T^q x) \\ &\quad \cdot \\ &\quad \cdot \\ &\quad \cdot \\ &\leq k^q \Omega(x, Tx, Tx). \end{aligned}$$

Thus (2.8)

$$\Omega(T^q x, T^{q+1} x, T^{q+1} x) \leq k^q \Omega(x, Tx, Tx). \tag{2.11}$$

**Theorem 2.5.** Let  $(X, G)$  be a complete G-metric space and  $\Omega$  be an  $\Omega$ -distance on  $X$  such that  $X$  is  $\Omega$ -bounded. Let  $T$  be a self-mapping on  $X$  that satisfies the following conditions:

- (1)  $T$  is a generalized  $\Omega$ -Suzuki-contraction;
- (2) if for all  $u \in X$ ,  $Tu \neq u$ , then

$$\inf\{\Omega(x, Tx, u) : x \in X\} > 0. \tag{2.12}$$

Then  $T$  has a fixed point in  $X$ .

*Proof.* Let  $x_0 \in X$  and define a sequence  $(x_n)$  in  $X$  inductively by taking  $x_n = Tx_{n-1}$  for  $n \in \mathbb{N}$ .

Substitute  $x = x_{n-1}$  in (2.10), implies that

$$\begin{aligned} \Omega(x_n, x_{n+1}, x_{n+1}) &= \Omega(Tx_{n-1}, Tx_n, Tx_n) \\ &\leq k \Omega(x_{n-1}, x_{n-1}, x_n) \\ &\quad \cdot \\ &\quad \cdot \\ &\quad \cdot \\ &\leq k^n \Omega(x_0, x_1, x_1). \end{aligned}$$

Since  $X$  is  $\Omega$ -bounded, there exists  $M > 0$  such that  $\Omega(x, y, z) \leq M$  for all  $x, y, z \in X$ . Hence

$$\Omega(x_n, x_{n+1}, x_{n+1}) \leq k^n M.$$

By taking the limit as  $n \rightarrow \infty$  for both sides, we get

$$\lim_{n \rightarrow \infty} \Omega(x_n, x_{n+1}, x_{n+1}) = 0. \quad (2.13)$$

since  $k < 1$ . Also, for  $p = 1$ , and  $q \geq 1$ , since  $(1 - k)\Omega(x, Tx, T^q x) \leq \Omega(x, Tx, T^q x)$  holds for every  $x \in X$ , we have

$$\begin{aligned} \Omega(Tx, T^2x, T^{q+1}x) &\leq k \max\{\Omega(x, Tx, Tx), \Omega(Tx, T^2x, T^2x), \Omega(T^q x, T^{q+1}x, T^{q+1}x)\} \\ &= k \max\{\Omega(x, Tx, Tx), \Omega(T^q x, T^{q+1}x, T^{q+1}x)\}. \end{aligned}$$

But from 2.11, we have  $\Omega(T^q x, T^{q+1}x, T^{q+1}x) \leq k^q \Omega(x, Tx, Tx)$  and thus,

$$\Omega(Tx, T^2x, T^{q+1}x) \leq k \max\{\Omega(x, Tx, Tx), k^q \Omega(x, Tx, Tx)\}.$$

Since  $k < 1$ , we have

$$\Omega(Tx, T^2x, T^{q+1}x) \leq k \Omega(x, Tx, Tx). \quad (2.14)$$

For  $n, s \in \mathbb{N}$  with  $s \geq 1$  substitute  $x = x_{n-1}$  in (2.14), implies that

$$\Omega(x_n, x_{n+1}, x_{n+s}) = \Omega(Tx_{n-1}, T^2x_{n-1}, T^{n+s-1}x_{n-1}) \leq k \Omega(x_{n-1}, x_n, x_n).$$

Taking the limit as  $n \rightarrow \infty$  for both sides and using 2.13, we get

$$\lim_{n \rightarrow \infty} \Omega(x_n, x_{n+1}, x_{n+s}) = 0. \quad (2.15)$$

The Definition 1.5 implies that

$$\Omega(x_n, x_m, xl) \leq \Omega(x_n, x_{n+1}, x_{n+1}) + \Omega(x_{n+1}, x_{n+2}, x_{n+2}) + \dots + \Omega(x_{m-1}, x_m, xl),$$

for all  $l, m, n \in \mathbb{N}$  with  $l \geq m \geq n$ ,  $m = n + s$  and  $l = m + t$ .

Applying the limit as  $n \rightarrow \infty$  and using 2.13 and 2.15, we get that

$$\lim_{n, m, l \rightarrow \infty} \Omega(x_n, x_m, xl) = 0.$$

Lemma 1.1 implies that  $(x_n)$  is a G-Cauchy sequence and so  $(x_n)$  converges to some  $u \in X$ . Since  $(x_n)$  is a G-Cauchy sequence, then for all  $\epsilon > 0$ , there exists  $N \in \mathbb{N}$  such that  $\Omega(x_n, x_m, xl) \leq \epsilon$ , for all  $n, m, l \geq N$ . Thus

$$\lim_{l \rightarrow \infty} \inf \Omega(x_n, x_m, xl) \leq \epsilon.$$

Since  $\Omega$  is lower semi-continuous, we have

$$\Omega(x_n, x_m, u) \leq \lim_{l \rightarrow \infty} \inf \Omega(x_n, x_m, xl) \leq \epsilon, \quad (2.16)$$

for all  $n, m \geq N$ .

Considering  $m = n + 1$  in (2.16), we get  $\Omega(x_n, x_{n+1}, u) \leq \epsilon$ , for all  $n \geq N$ . Suppose that  $Tu \neq u$ . Then Condition 2.12 implies that

$$0 < \inf\{\Omega(x, Tx, u) : x \in X\} \leq \inf\{\Omega(x_n, x_{n+1}, u) : n \geq N\} \leq \epsilon, \text{ for all } \epsilon > 0 \text{ which is a contradiction. Therefore } Tu = u.$$

## CONFLICT OF INTEREST

No conflict of interest was declared by the authors.

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