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# 8 MHz high efficient resonant sepic converter design for LED driver of endoscopy systems

## *Endoskopi sistemlerinin LED sürücüsü için 8 mhz yüksek verimli rezonans sepic dönüştürücü tasarımı*

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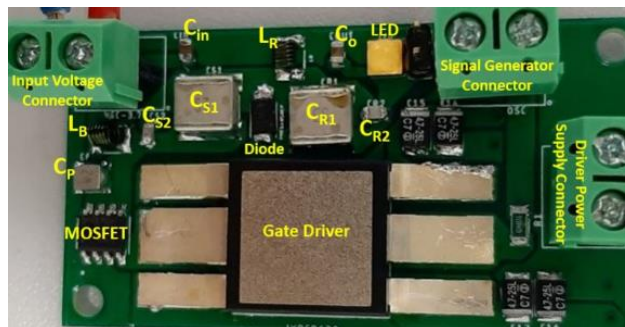
# 8 MHz High Efficient Resonant SEPIC Converter Design for LED Driver of Endoscopy Systems

## Highlights

- ❖ High Efficiency
- ❖ SEPIC Converter
- ❖ LED Driver
- ❖ Endoscopic

## Graphical Abstract

In this work, a LED driver design based on resonant SEPIC converter is presented for using in Endoscopy Systems.



**Figure.** The picture of the built prototype.

## Aim

In this work, high-efficiency and high-power density resonant SEPIC DC-DC converter design is aimed for light emitting diode (LED) driver of the LED integrated endoscopy device.

## Design & Methodology

In the design procedure, low power consumption and low volume are taken into consideration. The operation frequency is selected high enough, 8 MHz, to provide high power density. First, a LED which has high power density, is determined to adapt the distal tip of an endoscopy device. Then, the design procedure presented in the literature is applied to the resonant SEPIC converter to drive selected LED.

## Originality

In this work, the resonant SEPIC converter is designed for endoscopic LED driver with high efficiency and high power density. The design of the converter is carried out based on the voltage/current characteristic of a real high power density LED by Cree to be placed distal tip of an endoscopy device. The operation of the converter is provided at 8 MHz operation frequency while its peak efficiency is high enough as 84.5%.

## Findings

The presented design was validated on a prototype and the output voltage is provided at 2.82 V to provide typical voltage of the LED while the load current is around 1 A.

## Conclusion

According to obtained results, the peak efficiency is measured around 84.5% while the output voltage 2.82 V.

## Declaration of Ethical Standards

The author(s) of this article declare that the materials and methods used in this study do not require ethical committee permission and/or legal-special permission.

# 8 MHz High Efficient Resonant SEPIC Converter Design for LED Driver of Endoscopy Systems

*Araştırma Makalesi/Research Article*

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## ABSTRACT

In this work, a light emitting diode (LED) driver design based on resonant SEPIC converter is presented for using in Endoscopy Systems. The resonant SEPIC converter operating with soft switching is good candidate to reduce the power consumption and increase the efficiency. In the design of the converter, the operation frequency is selected as 8 MHz in order to increase power density as well. The design of the converter is built based on voltage driven rectifier proposed in the literature to simplify the design procedure. Finally, the performance of the converter is verified on a prototype loaded with a LED, which has high power density. The maximum efficiency of the converter is measured around 84.5% while the output voltage is 2.82 V and the output current is around 1.02 A.

**Key Words:** LED Driver, SEPIC converter, high frequency, high efficiency.

# Endoskopi Sistemlerinin LED Sürücüsü için 8 MHz Yüksek Verimli Rezonans SEPIC Dönüştürücü Tasarımı

## ÖZ

Bu çalışmada, endoskopi sistemlerinde kullanılmak üzere rezonanslı SEPIC dönüştürücü tabanlı bir LED sürücü tasarımı sunulmaktadır. Yumuşak anahtarlama ile çalışan rezonanslı SEPIC dönüştürücü, güç tüketimini azaltmak ve verimliliği artırmak için iyi bir alternatiftir. Dönüştürücünün tasarımında güç yoğunluğunu artırmak için çalışma frekansı 8 MHz olarak seçilmiştir. Dönüştürücünün tasarımı, tasarım prosedürünü basitleştirmek için literatürde önerilen gerilim tahrikli doğrultucu temel alınarak yapılmıştır. Son olarak, dönüştürücünün performansı, LED yüklü yüksek güç yoğunluğuna sahip bir prototip üzerinde doğrulanmıştır. Dönüştürücünün maksimum verimi %84,5 civarında ölçülürken çıkış gerilimi 2,82 V ve çıkış akımı 1,02 A civarındadır.

**Anahtar Kelimeler:** LED sürücü, SEPIC dönüştürücü, yüksek frekans, yüksek verimlilik.

## 1. INTRODUCTION

Endoscopy systems are widely used to observe tissues and internal organs. They can also be used in minimally invasive surgery (MIS) and imaging in the diagnosis and treatment of diseases [1].

An endoscopy system includes illumination and imaging units. In the conventional endoscopy system, the light is directed from an external source to the tip of the endoscopy device, while the imaging optics captures the light reflected from the surgical field and directs it to the processing of images [2]. The light is directed to the tip of endoscopy device by a fiber bundle, which is connected to the external light source with limited acceptance angle. Therefore, the most of the light is lost due to the way of the connection. Besides, an infrared heat energy caused by fiber bundle can be transmitted to the patient and results in danger during the process [3-5].

The overall efficiency of the systems including an external light source and endoscope is around 16%-19% as well [2]. Therefore, there is a need for integrated new systems to replace external light sources in endoscopy systems.

The xenon, halogen or light emitting diodes (LEDs) are usually used as endoscopic light source. However, xenon and halogen lamps generate a lot of heat, they are expensive and short-lived. Approximately 300 W electrical power is needed to provide only 1 W optical power [6]. Recently, LEDs have started to replace halogen and xenon lamps for endoscopic light source [3, 6]. LEDs have entered the lighting industry and provided noticeable advantage in terms of energy saving [7]. They can be integrated into the endoscope system due to their small volume. Thus, closer light source to the processing area can be obtained. In addition, LEDs have advantages of low cost, light weight, high energy saving and low heat generation compared to xenon and halogen lamps for endoscopy systems [5].

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For safe operation of LEDs, drivers controlling the current and the voltage of LEDs are required. It is also important that LED drivers should be designed to not limit the performance of the LED [8]. Therefore, design stage of the selected driver topology is important task to provide the best performance of the LED. The power converters are usually used for LED drive process. The low power consumption, high efficiency, high power density and thermal management are the key issues for the power converters designed to be used as LED drivers in the endoscopy system.

In the power converters, the most of the volume is usually occurred by passive components which are reducing the power density [9-11]. Therefore, the operation of the selected LED driver at high frequency is required to provide small volume and high power density. The stored energy in the passive components reduces at high switching frequency due to their reduced volume and values [12, 13]. However, operation at high frequency increases the switching losses causing lower efficiency. Thus, in order to reduce or eliminate the switching losses, the use of soft switching techniques or soft switched converters is unavoidable [14, 15]. The soft switching techniques keep the voltage across the power semiconductors at a very low level during the turn-on and turn-off transitions [16-19]. The recovering the energy stored in the output capacitance of the power semiconductor plays important role to increase the efficiency at high operation frequency [16, 20].

In the resonant converter topologies, the output capacitance of the power semiconductor switches can be discharged by resonance [9, 21-23]. Thus, switching losses are minimized or eliminated at high operation frequency.

One of the resonant converter topologies, the LLC resonant converter has the advantage of zero voltage switching (ZVS) for all load conditions in inductive operation region [24], [25]. High frequency inductor-inductor-capacitor (LLC) resonant converter applications are presented in [22-27]. As seen in these studies, LLC resonant converters have high efficiency, but their magnetic components are complex and bulky. It is not suitable for low power applications and is costly. Also, not having a ground referenced switch reduces the reliability of the drive circuit. The circuit topologies, which have active switches with ground reference, are usually preferred in high frequency applications. [9, 28].

Among the resonant converters, the resonant SEPIC converter, class E resonant converter, resonant boost converter and class  $\Phi^2$  resonant converter have ground-referenced switch. When these converters evaluated based on [9], [12], [28] and [29], resonant SEPIC converter is more advantageous at high operation frequency compared to the others. Because the resonant SEPIC converter does not include a bulk inductor and operates at constant operation frequency. Thus, it has improved response speed and allows low loss resonant gate drive [30]. Based on these features, in this work,

resonant SEPIC converter is selected to drive the LED of an endoscopy system.

The resonant SEPIC converter applications have been presented in different works, in the literature [9], [21], [28], [30]-[33]. In [9], a new design method is presented for the high frequency resonant SEPIC converter operating at 30 MHz. The new design procedure redivided the resonant SEPIC topology into two subsystems to provide independent tuning the amplitude and the phase. In this way, the voltage-driven rectifier with series capacitor replaces the current-driven rectifier and the design is simplified. The analysis and design procedure of a self-oscillating resonant SEPIC converter that can operate at very high frequencies ranging from 30 MHz to 300 MHz is presented in [21]. The presented circuit has complex design which is built with two resonant SEPICs and required an interconnection network. In [28], a SEPIC converter design method and its control are presented to provide operation at very high frequencies. The proposed method allows high efficiency over wide input and output voltage range. In [30], different SEPIC topologies are discussed and the superiority of the resonant SEPIC topology over other SEPIC topologies is explained, and simulation results are presented. In [33], a self-oscillating SEPIC converter is proposed for LED drive application. The use of the phase shift burst mode control method make the control circuitry of the converter complicated. The peak efficiency is obtained around %81 at 10.5 W power rate. In order to reduce voltage stress of the semiconductors and increase the voltage transformation ratio, another self-oscillating SEPIC converter is proposed in [34]. The target of the method is provided with the use of additional component in conventional SEPIC converter. In [35], a quasi-resonant converter is discussed in terms of distributed maximum power point trackers. The maximum efficiency of the converter is evaluated in a medium frequency range. In [36], ZVS resonant SEPIC converter is evaluated for photovoltaic applications. The closed-loop operation of the converter is tested by simulation.

In this work, high-efficiency and high-power density resonant SEPIC converter design is proposed for LED driver of the LED integrated endoscopy device. In the design procedure, low power consumption and low volume are taken into consideration. First, a LED which has high power density, is determined to adapt the distal tip of an endoscopy device. Then, the design procedure presented in [9] is applied to the resonant SEPIC converter to drive selected LED. The spotlight of this paper is the carrying out the high efficiency design of the converter based on the voltage and current characteristic of a real high power density LED by Cree, to be placed to the distal tip of the endoscopy device. The obtained design procedure was validated on a prototype which has 2.82 V output voltage and 1.02 A output current. The operation of the converter was provided at 8 MHz operation frequency while its efficiency is high enough. According to the obtained results, the peak efficiency

was measured around 84.5% while the output voltage is 2.82 V.

## 2. PRINCIPLES OF THE RESONANT SEPIC CONVERTER

The circuit diagram of the resonant SEPIC converter is given in Figure 1. The circuit topology of the resonant SEPIC converter is similar with the conventional SEPIC converter in [37] and with the multi resonant SEPIC converter given in [38]. However, component size, operation principle and placement of the component in the resonant SEPIC converter are very different. The conventional SEPIC converter operates with hard switching and has two bulk inductors. The multiresonant SEPIC converter also has bulk inductors but it achieves ZVS for the switch and diode. The resonant SEPIC converter requires only two inductors as shown in Figure 1. The resonant SEPIC converter operates at the constant operation frequency and duty ratio [28, 30] with the use of on/off control. Thus, bulky inductors are eliminated compared to previous designs presented in [37] and [38].

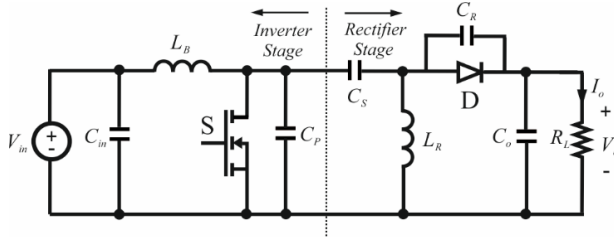


Figure 1. The resonant SEPIC Converter.

The operation of the resonant SEPIC converter can be simplified with two subsystems which are inverter stage and the rectifier stage [9]. According to the design procedure given in [9],  $V_{in}$  input source,  $C_{in}$  input filter capacitor,  $L_B$  filter inductor, S MOSFET and  $C_P$  resonant capacitor consisting of the parasitic capacitor of the S MOSFET constitute the inverter stage. The rectifier stage includes D diode,  $L_R$  resonant inductor,  $C_o$  filter capacitor,  $C_R$  resonant capacitor,  $C_S$  series capacitor and  $R_L$  load. Finally,  $V_o$  is the output voltage. These two subsystems can be given in Figure 2 and Figure 3, as presented in [9]. The key waveforms representing operation of the resonant SEPIC converter is given Figure 4.

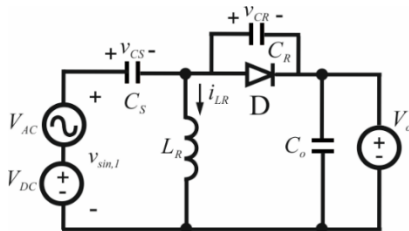


Figure 2. The voltage driven rectifier stage of resonant SEPIC converter.

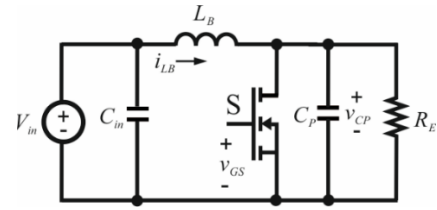


Figure 3. Inverter stage of resonant SEPIC converter.

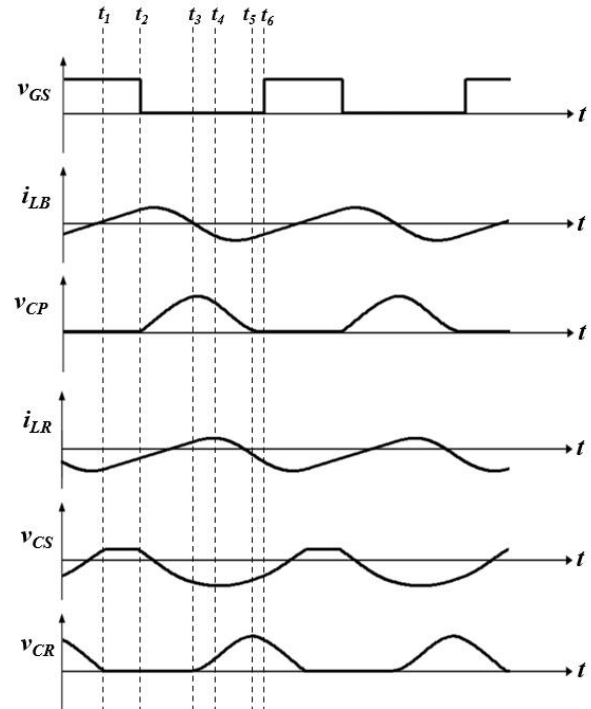


Figure 4. The operational key waveforms of the resonant SEPIC converter.

In the voltage driven rectifier stage, there are three resonant components which are  $L_R$ ,  $C_R$  and  $C_S$ . A resonance occurs between  $C_S$ ,  $L_R$  and  $C_R$  while S MOSFET is on and D diode is off condition. In the resonance operation, the voltage of the diode,  $V_{CR}$ , smoothly decreases and the current of  $L_R$  discharges while the voltage of  $C_S$  increases. At  $t=t_1$ ,  $V_{CR}$  reaches zero,  $V_{CS}$  charges to the output voltage and so S MOSFET is turned-off and D diode is turned-on, at  $t=t_2$ . With the conduction of the D diode, the voltage across the  $L_R$  becomes positive and its current starts to increase. When the current of  $L_R$  exceeds the input current of the rectifier, D diode is turned-off at  $t=t_3$ . After the turn-off of diode, the voltage of  $C_R$  capacitor smoothly starts to increase while the voltage of  $C_S$  capacitor continue to increase in inverse direction. At  $t=t_4$ ,  $i_{LR}$  reaches its maximum value while  $C_S$  reaches own maximum in negative direction. Then,  $L_R$  starts to discharge,  $V_{CR}$  reaches its maximum at  $t=t_5$ . At  $t=t_6$  S MOSFET is on again and cycle repeats. The resonant frequency  $f_{o-rec}$  and the characteristic impedance  $Z_{o-rec}$  can be defined, based on [9], as follows:

$$f_{o-rec} = \frac{1}{2\pi \sqrt{L_R(C_S+C_R)}} \tag{1}$$

$$Z_{o-rec} = \sqrt{\frac{L_R}{C_R + C_S}} \quad (2)$$

In the inverter stage, rectifier stage represented by  $R_E$  equivalent resistance and there are two resonant components which are  $L_B$  and  $C_P$ , as shown in Figure 3. Based on [9], the equivalent resistance of the rectifier stage,  $R_E$ , can be written, as follows:

$$R_E = \frac{8V_{in}^2}{\pi^2} \cdot \frac{1}{P_{in}} \quad (3)$$

Where  $P_{in}$  is the input power of the rectifier stage. When the S MOSFET is turned-off, a resonance occurs between  $L_B$  and  $C_P$ . In order to achieve ZVS for S MOSFET, inductive operation should be provided. For this purpose, resonance frequency can be set by

$$f_{o-inv} = \frac{1}{2\pi\sqrt{L_B C_P}} \quad (4)$$

When the S MOSFET is off condition, the equivalent circuit across the MOSFET shows parallel characteristic including  $L_B$ ,  $C_P$  and  $R_E$ . Thus, switching frequency below resonant frequency provides ZVS for the MOSFET. During the turn-off of the MOSFET, the voltage of  $C_P$  smoothly increases while the current of  $L_B$  decreases and the current of  $L_R$  increases. When the current of  $L_B$  reaches zero, the voltage of  $C_P$  reaches its maximum value, at  $t=t_3$ . Then,  $C_P$  capacitor starts to discharge while the current of  $L_B$  is increasing in negative direction. When the voltage of  $C_P$  reaches zero, at  $t=t_5$ , the body diode of the MOSFET turns-on to achieve ZVS turn-on for the MOSFET. During the turn-on of the MOSFET,  $L_B$  inductor stores the energy for the determined time.

### 3. DESIGN OF THE RESONANT SEPIC LED DRIVER

In the conventional design procedure given in [28], current driven rectifier causes serious coupling between resonant frequency and resonant impedance [9]. Although this design procedure seems easy, it is quite difficult to achieve ZVS, it requires a lot of optimization work. Therefore, design procedure using voltage driven rectifier proposed in [9] is used in this work. In the voltage driven rectifier, the power factor and output power can be designed independently, which simplifies the design. The inverter stage contains only two resonant components. This simplifies the design of the inverter stage as well.

In the design of LED driver, the input voltage is selected as 3.7 V taking into consideration the feeding from a Li-ion battery. For the load of the resonant SEPIC converter, a LED with high power density (XLamp XP-L2 from Cree) is selected. According to determined LED datasheet, the typical voltage is around 2.82 V while its current is 1050 mA.

Based on given design procedure in [9], circuit components of the resonant SEPIC converter for the LED driver are determined as given in Table I. The switching frequency is selected as 8 MHz to provide high power density. In order to achieve ZVS for the MOSFET, inverter resonant frequency is around 27.7 MHz based on equation (4). Resonant SEPIC converter design is realized by combining the designed inverter and rectifier. Different results can be seen in circuit waveforms and output power level due to the non-linear interaction between the two stages. Additional settings can be made by changing resonant component's value to achieve soft switching and the required power level.

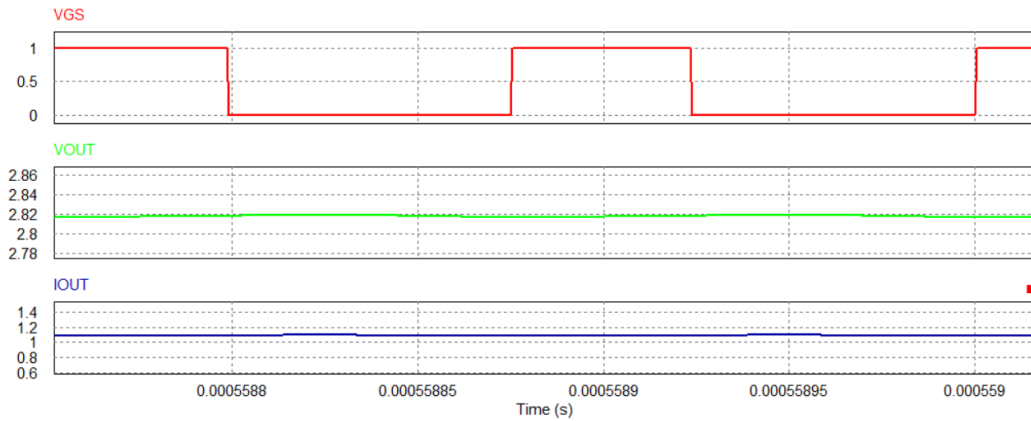
**Table 1.** The determined design parameters of the proposed resonant SEPIC converter.

Parameters	Value
$L_B$	33 nH
$C_P$	1 nF
$C_S$	5.9 nF
$C_R$	5 nF
$L_R$	33 nH
$C_o$	47 $\mu$ F
$C_{in}$	4.7 $\mu$ F
$V_{in}$	3.7 V
$V_o$	2.82 V
$I_o$	1050 mA

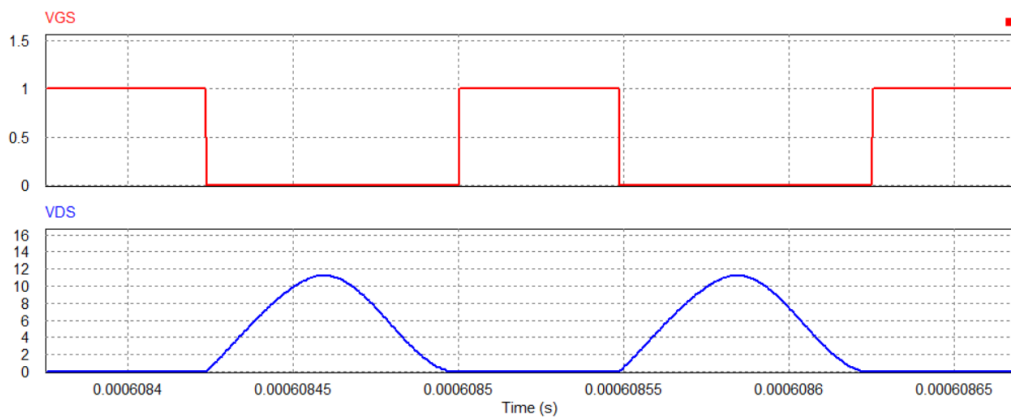
### 4. SIMULATION AND EXPERIMENTAL RESULTS

#### 4.1. Simulation Results

The operation of the converter is firstly tested with a simulation work implemented by PSIM. The LED is modeled with a resistor and Zener diode at the load side. The determined design parameters mentioned earlier were used in the simulation work. The output voltage of the converter and gate-source voltage of the power MOSFET,  $V_{GS}$ , are shown in Figure 5. According to obtained results, 2.8 V output voltage and 1.09 A output current were provided with simulation work. The ZVS operation of the power MOSFET was also tested by simulation as shown in Figure 6. The power MOSFET is turn-on with ZVS, while the drain-source voltage of the power MOSFET,  $v_{DS}$ , is zero



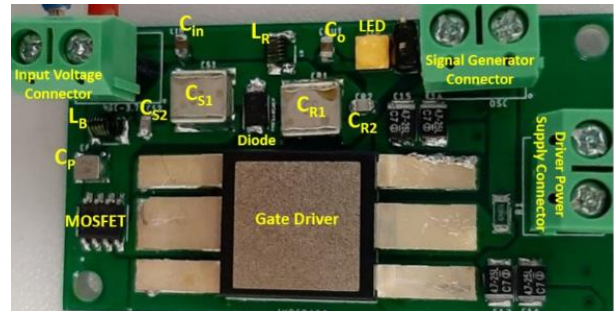
**Figure 5.** The simulated gate-source voltage of the power MOSFET, output voltage and the output current waveforms of the converter.



**Figure 6.** The simulated gate-source voltage,  $v_{GS}$ , and drain-source voltage,  $v_{DS}$ , of the MOSFET.

#### 4.2. Experimental Results

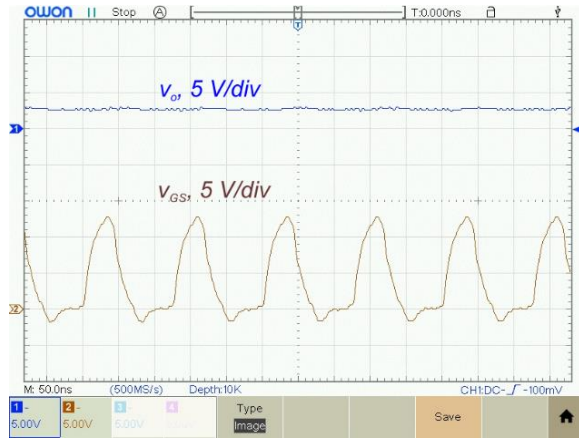
The operation of the resonant SEPIC converter is validated by a prototype built with the design parameters given in Table I. In the determination of the power semiconductors, IRF7473Pbf and PMEG4050EP are used for the power MOSFET and rectifier diodes. To drive power MOSFET, IXRFD630 gate drive is used. An open loop control circuit is design for the power control of the converter. A signal generator is used to produce 8 MHz pulse width modulated (PWM) signals. Then, a gate driver which has high frequency drive capacity, is used to drive the power MOSFET. The IXRFD630, producing 30 A of peak current, was determined as the gate driver. The picture of the built prototype is given in Figure 7.



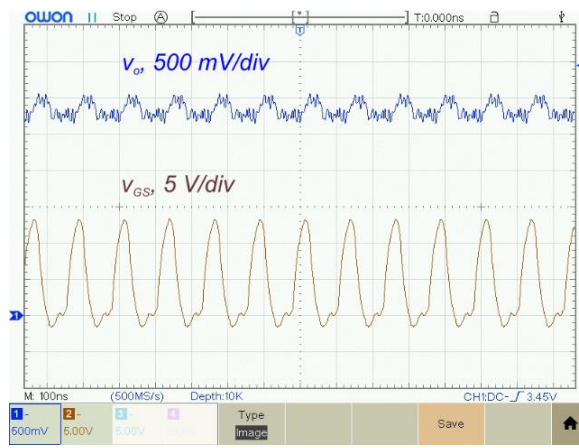
**Figure 7.** The picture of the built prototype.

The measured waveforms of the output voltage and gate-source voltage of the power MOSFET are given in Figure 8. As shown in Figure 8 (a), the output voltage at 2.8 V is experimentally provided while the duty ratio is 0.35 and the output current is 1.02 A. Figure 8 (b) shows 320 mV measured ripple on the output voltage. The ripple can be minimized further with the use of larger filter capacitor at the output of the converter.





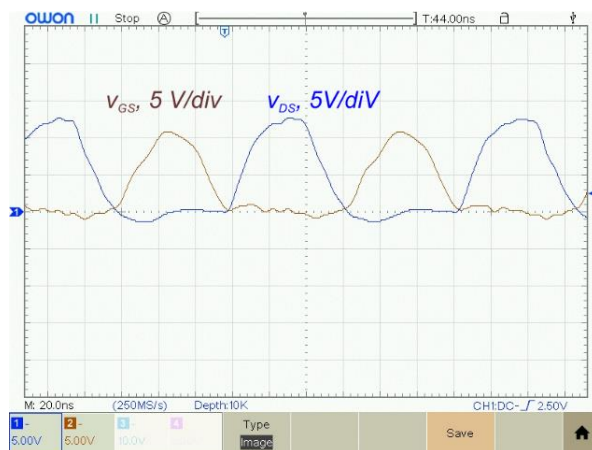
(a)



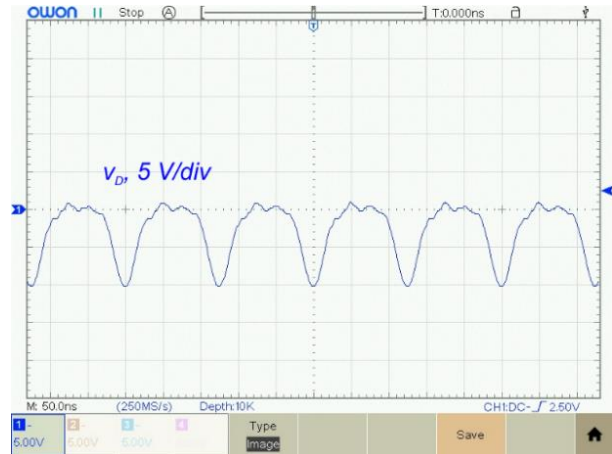
(b)

**Figure 8.** The output voltage waveforms. (a) The measured output voltage at 2.8 V. (b) The output voltage ripple around 320 mV. The output current is 1.02 A, duty ratio is 0.35.

The gate-source voltage,  $v_{GS}$ , and drain-source voltage,  $v_{DS}$ , of the MOSFET, while the duty ratio is 0.35, are measured as given in Figure 9. According to measured results, the power MOSFET operates with soft switching. The measured diode voltage,  $v_D$ , is given in Figure 10. The peak reverse voltage of the diode is measured around 10 V.

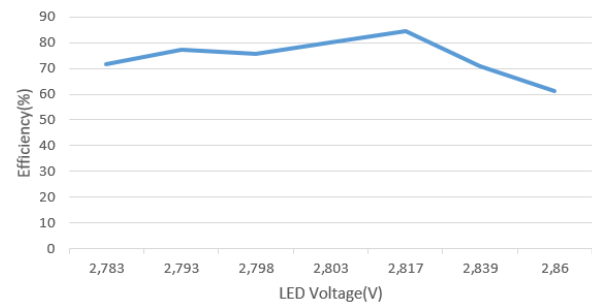


**Figure 9.** The gate-source voltage,  $v_{GS}$ , and drain-source voltage,  $v_{DS}$ , of the MOSFET.



**Figure 10.** The waveforms of the rectifier diode voltage,  $v_D$ .

The efficiency performance of the converter is also tested on the built prototype. The maximum efficiency is measured around 84.5% while the output voltage is 2.82 V and the output current is around 1.02 A. The efficiency variation based on LED voltage was given in Figure 11. The LED starts to heat up in proportion to the power consumed on it. The efficiency was decreased while the LED voltage is reducing due to the temperature increase.



**Figure 11.** The measured efficiency variation of the converter as function of LED voltage.

## 6. CONCLUSION

In this paper, a LED driver design for an endoscopy system is presented. In order to provide high efficiency, resonant SEPIC converter operating with soft switching is used to drive the LED. The operation frequency is selected high enough, 8 MHz, to provide high power density. The design procedure, which is including inverter and rectifier stage, of the resonant SEPIC converter is built based on the methods proposed in literature. Finally, a prototype is built to validate the operation of the LED driver. A real LED with high power density is used as load at the output of the converter. The output voltage is provided at 2.82 V to provide typical voltage of the LED while the load current is around 1.02 A. According to measured results, the maximum efficiency of the converter is measured as 84.5%.



## ACKNOWLEDGEMENT

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## DECLARATION OF ETHICAL STANDARDS

There is no need to obtain permission from the ethics committee for the article prepared. There is no conflict of interest with any person/institution in the article prepared.

## AUTHORS' CONTRIBUTIONS

**Irem Corak:** She put contribution in literature searching, analyzing of the SEPIC converter. She also built the prototype and measured the current, voltage and efficiency results of the SEPIC converter.

**Sevilay Cetin:** She put contribution in the creating idea of the paper and managing the all stages in the paper.

## CONFLICT OF INTEREST

There is no conflict of interest in this study.

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