



# Malcev Yang-Baxter equation, weighted $\mathcal{O}$ -operators on Malcev algebras and post-Malcev algebras

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## Abstract

The purpose of this paper is to study the  $\mathcal{O}$ -operators on Malcev algebras and discuss the solutions of Malcev Yang-Baxter equation by  $\mathcal{O}$ -operators. Furthermore we introduce the notion of weighted  $\mathcal{O}$ -operators on Malcev algebras, which can be characterized by graphs of the semi-direct product Malcev algebra. Then we introduce a new algebraic structure called post-Malcev algebras. Therefore, post-Malcev algebras can be viewed as the underlying algebraic structures of weighted  $\mathcal{O}$ -operators on Malcev algebras. A post-Malcev algebra also gives rise to a new Malcev algebra. Post-Malcev algebras are analogues for Malcev algebras of post-Lie algebras and fit into a bigger framework with a close relationship with post-alternative algebras.

**Mathematics Subject Classification (2020).** 17D10, 17A01, 17A30, 17B10, 17B38

**Keywords.** alternative algebra, Malcev algebra, weighted  $\mathcal{O}$ -operator, Rota-Baxter operator, representation, Malcev Yang-Baxter equation

## 1. Introduction

Malcev algebras play an important role in the geometry of smooth loops. Just as the tangent algebra of a Lie group is a Lie algebra, the tangent algebra of a locally analytic Moufang loop is a Malcev algebra [18, 21, 27, 28]. A Malcev algebra is a non-associative algebra  $A$  with an anti-symmetric multiplication  $[\cdot, \cdot]$  that satisfies the Sagle's identity

$$[[x, z], [y, t]] = [[x, y], [z], t] + [[[y, z], t], x] + [[[z, t], x], y] + [[[t, x], y], z], \forall x, y, z, t \in A.$$

Pre-Malcev algebras have been studied extensively since [26] which are the generalization of pre-Lie algebras, in the sense that any pre-Lie algebra is a pre-Malcev algebra but the converse is not true. Studying pre-Malcev algebras independently is significant not only to its own further development, but also to develop the areas closely connected with such

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Received: 07.06.2022; Accepted: 31.12.2022

algebras. A pre-Malcev algebra is a vector space  $A$  endowed with a bilinear product  $\triangleright$  satisfying the following identity for  $x, y, z, t \in A$ ,

$$[y, z] \triangleright (x \triangleright t) + [[x, y], z] \triangleright t + y \triangleright ([x, z] \triangleright t) - x \triangleright (y \triangleright (z \triangleright t)) + z \triangleright (x \triangleright (y \triangleright t)) = 0, \tag{1.1}$$

where  $[x, y] = x \triangleright y - y \triangleright x$ . The existence of subadjacent Malcev algebras and compatible pre-Malcev algebras was given in [26, Proposition 5]. For a given pre-Malcev algebra  $(A, \triangleright)$ , there is a Malcev algebra  $A^C$  defined by the commutator  $[x, y] = x \triangleright y - y \triangleright x$ , and the left multiplication operator in  $A$  induces a representation of Malcev algebra  $A^C$ .

Rota-Baxter operators were introduced by G. Baxter [7] in 1960 in the study of fluctuation theory in Probability. These operators were then further investigated, by G.-C. Rota [30], Atkinson [1], Cartier [9] and others. In the 1980s, the notion of Rota-Baxter operator of weight 0 was introduced in terms of the classical Yang-Baxter equation for Lie algebras (see [4, 5, 13–15, 17, 23] for more details). Later on, B. A. Kupershmidt [19] introduced the notion of  $\mathcal{O}$ -operator as generalized Rota-Baxter operators to understand classical Yang-Baxter equations and related integrable systems. In fact, a skew-symmetric solution of the CYBE (see [2]) is exactly a special  $\mathcal{O}$ -operator (associated to the coadjoint representation). Our first goal is to study the connections between  $\mathcal{O}$ -operators and symmetric solutions of the analogue of CYBE on Malcev algebras motivated by the point of Kupershmidt and Bai.

The notion of post-algebras goes back to Rosenbloom in [29] (1942). An equivalent formulation of the class of post-algebras was given by Rousseau in [31] (1969, 1970) which became a starting point for deep research. Post-Lie algebras have been introduced by Vallette in 2007 [33] in connection with the homology of partition posets and the study of Koszul operads. However, J. L. Loday studied pre-Lie algebras and post-Lie algebras within the context of algebraic operad triples, see for more details [24, 25]. In the last decade, many works [8, 10, 34] intrested in post-Lie algebra structures, motivated by the importance of pre-Lie algebras in geometry and in connection with generalized Lie algebra derivations.

Recently, Post-Lie algebras which are non-associative algebras played an important role in different areas of pure and applied mathematics. They consist of a vector space  $A$  equipped with a Lie bracket  $[\cdot, \cdot]$  and a binary operation  $\triangleright$  satisfying the following axioms

$$x \triangleright [y, z] = [x \triangleright y, z] + [y, x \triangleright z], \tag{1.2}$$

$$[x, y] \triangleright z = as_{\triangleright}(x, y, z) - as_{\triangleright}(y, x, z). \tag{1.3}$$

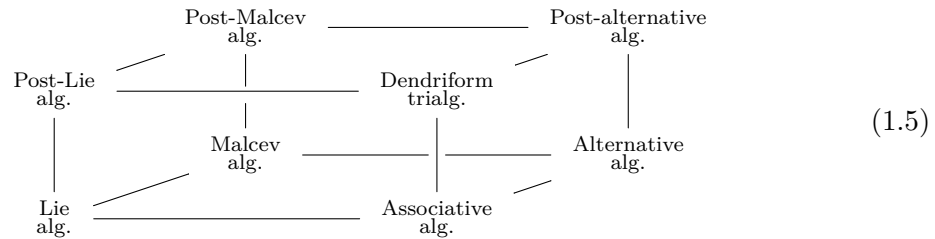
If the bracket  $[\cdot, \cdot]$  is zero, we have exactly a pre-Lie structure. It is worth to note that, in spite the post-Lie product does not yield a Lie bracket by antisymmetrization, the bilinear product  $\{\cdot, \cdot\} : A \otimes A \rightarrow A$ , defined for all  $x, y \in A$  by

$$\{x, y\} = x \triangleright y - y \triangleright x + [x, y]. \tag{1.4}$$

defines on  $A$  another Lie algebra structure. The varieties of pre- and post-Lie algebras play a crucial role in the definition of any pre and post-algebra through black Manin operads product, see details in [3, 12]. Whereas pre-Lie algebras are intimately associated with euclidean geometry, post-Lie algebras occur naturally in the differential geometry of homogeneous spaces, and are also closely related to Cartan’s method of moving frames. Ebrahimi-Fard, Lundervold and Munthe-Kaas [10] studied universal enveloping algebras of post-Lie algebras and the free post-Lie algebra.

In this paper we use weighted  $\mathcal{O}$ -operators to split operations, although a generalization exists in the alternative setting in terms of bimodules. Diagram (1.5) summarizes the

results of the present work.



In Section 2, we study the relationship between  $\mathcal{O}$ -operators and Malcev Yang-Baxter equation. We construct in Section 3 alternative algebras structure associated to any post-alternative algebra. The multiplication is given by

$$x \star y = x \prec y + y \succ x + x \cdot y.$$

In addition, in Section 4 we investigate the notion of a weighted  $\mathcal{O}$ -operator to construct a post-alternative algebra structure on the  $A$ -bimodule  $\mathbb{K}$ -algebra of an alternative algebra  $(A, \cdot)$ . Section 4 is devoted to introduce the notion of post-Malcev algebra and we show that weighted  $\mathcal{O}$ -operators can be used to construct post-Malcev algebras. We also reveal a relation between post-Malcev algebras and post-alternative algebras by the commutative diagram (1.5).

Throughout this paper, all algebras are finite-dimensional and over a field  $\mathbb{K}$  of characteristic 0.

## 2. $\mathcal{O}$ -operators and Malcev Yang-Baxter equation

In this section, we recall the classical result that a skew-symmetric solution of CYBE in a Malcev algebra gives an  $\mathcal{O}$ -operator through a duality between tensor product and linear maps. Not every  $\mathcal{O}$ -operator on a Malcev algebra comes from a solution of CYBE in this way. However, any  $\mathcal{O}$ -operator can be recovered from a solution of CYBE in a larger Malcev algebra.

We first recall the concept of a representation (see [20]) and construct the dual representation.

**Definition 2.1** ([20]). A **representation** (or a **module**) of a Malcev algebra  $(A, [\cdot, \cdot])$  on a vector space  $V$  is a linear map  $\rho : A \rightarrow \text{End}(V)$  such that, for all  $x, y, z \in A$ ,

$$\rho([[x, y], z]) = \rho(x)\rho(y)\rho(z) - \rho(z)\rho(x)\rho(y) + \rho(y)\rho([z, x]) - \rho([y, z])\rho(x). \quad (2.1)$$

We denote this representation by  $(V, \rho)$ .

For all  $x, y \in A$ , define the map  $ad : A \rightarrow \text{End}(A)$  by  $ad_x(y) = [x, y]$ . Then  $ad$  is a representation of the Malcev algebra  $(A, [\cdot, \cdot])$  on  $A$ , which is called the adjoint representation.

Let  $(A, [\cdot, \cdot])$  be a Malcev algebra and  $(V, \rho)$  is a representation on  $A$ . Consider the dual space  $V^*$  of  $V$  and  $\text{End}(V^*)$ . Define the linear map  $\rho^* : A \rightarrow \text{End}(V^*)$  by

$$\langle \rho^*(x)a^*, b \rangle = -\langle a^*, \rho(x)b \rangle, \quad \forall x \in A, b \in V, a^* \in V^*, \quad (2.2)$$

where  $\langle \cdot, \cdot \rangle$  is the canonical pairing between  $V^*$  and  $V$ .

**Proposition 2.1.** *With the above notations,  $(V^*, \rho^*)$  is a representation of  $A$  which is called the dual representation of  $(V, \rho)$ .*

**Proof.** By (2.1), we have, for  $x, y, z \in A$ ,

$$\rho([[y, x], z]) = -\rho([[x, y], z]) = \rho(z)\rho(y)\rho(x) - \rho(y)\rho(x)\rho(z) - \rho(x)\rho([z, y]) + \rho([x, z])\rho(y).$$

So, for any  $x, y, z \in A$ ,  $a^* \in V^*$ ,  $b \in V$ , we have

$$\begin{aligned} \langle \rho^*([x, y], z)a^*, b \rangle &= -\langle a^*, \rho([x, y], z)b \rangle = -\langle a^*, -\rho([y, x], z)b \rangle \\ &= -\langle a^*, (\rho(y)\rho(x)\rho(z) - \rho(z)\rho(y)\rho(x) + \rho(x)\rho([z, y]) - \rho([x, z])\rho(y))b \rangle \\ &= -\langle (-\rho^*(z)\rho^*(x)\rho^*(y) + \rho^*(x)\rho^*(y)\rho^*(z) + \rho^*([z, y])\rho^*(x) - \rho^*(y)\rho^*([x, z]))a^*, b \rangle. \end{aligned}$$

Hence, since  $\langle \cdot, \cdot \rangle$  is nondegenerate, we obtain

$$\rho^*([x, y], z) = \rho^*(x)\rho^*(y)\rho^*(z) - \rho^*(z)\rho^*(x)\rho^*(y) + \rho^*(y)\rho^*([z, x]) - \rho^*([y, z])\rho^*(x). \quad \square$$

**Definition 2.2.** Let  $(A, [\cdot, \cdot])$  be a Malcev algebra and  $r = \sum_i x_i \otimes y_i \in A \otimes A$ .  $r$  is called a solution of Malcev Yang-Baxter equation in  $A$  if  $r$  satisfies

$$[r_{12}, r_{13}] + [r_{12}, r_{23}] + [r_{13}, r_{23}] = 0, \quad (2.3)$$

where

$$r_{12} = \sum_i x_i \otimes y_i \otimes 1, \quad r_{13} = \sum_i x_i \otimes 1 \otimes y_i, \quad r_{23} = \sum_i 1 \otimes x_i \otimes y_i, \quad (2.4)$$

and

$$\begin{aligned} [r_{12}, r_{13}] &= \sum_{i,j} [x_i, x_j] \otimes y_i \otimes y_j, & [r_{13}, r_{23}] &= \sum_{i,j} x_i \otimes x_j \otimes [y_i, y_j], \\ [r_{12}, r_{23}] &= \sum_{i,j} x_i \otimes [y_i, x_j] \otimes y_j. \end{aligned}$$

Let  $V$  be a vector space. The **twisting operator**  $\sigma : V^{\otimes 2} \rightarrow V^{\otimes 2}$  is defined for all  $a, b \in V$  by

$$\sigma(a \otimes b) = b \otimes a.$$

We call  $r = \sum_i a_i \otimes b_i \in V^{\otimes 2}$  **skew-symmetric** (resp. **symmetric**) if  $r = -\sigma(r)$  (resp.  $r = \sigma(r)$ ). Furthermore,  $r$  can be regarded as a linear map from  $V^*$  to  $V$  in the following way

$$\langle a^*, r(b^*) \rangle = \langle a^* \otimes b^*, r \rangle, \quad \forall a^*, b^* \in V^* \quad (2.5)$$

Equation (2.3) gives the tensor form of Malcev Yang-Baxter equation. What we will do next is to replace the tensor form by a linear operator satisfying some conditions.

**Theorem 2.1.** Let  $(A, [\cdot, \cdot])$  be a Malcev algebra and  $r \in A \otimes A$ . Then  $r$  is a skew-symmetric solution of Malcev Yang-Baxter equation in  $A$  if and only if  $r$  satisfies for all  $x^*, y^* \in A^*$ ,

$$[r(x^*), r(y^*)] = r(ad^*r(x^*)(y^*) - ad^*r(y^*)(x^*)). \quad (2.6)$$

**Proof.** Let  $\{e_i, \dots, e_n\}$  be a basis of  $A$  and  $\{e_i^*, \dots, e_n^*\}$  be its dual basis. Suppose that  $[e_i, e_j] = \sum_p c_{ij}^p e_p$  and  $r = \sum_{i,j} a_{ij} e_i \otimes e_j$ . Hence  $a_{ij} = -a_{ji}$ . Now, we have

$$\begin{aligned} [r_{12}, r_{13}] &= \left[ \sum_{i,j} a_{ij} e_i \otimes e_j \otimes 1, \sum_{k,l} a_{kl} e_k \otimes 1 \otimes e_l \right] = \sum_{i,j,k,l,p} a_{ij} a_{kl} c_{ik}^p e_p \otimes e_j \otimes e_l, \\ [r_{13}, r_{23}] &= \left[ \sum_{i,j} a_{ij} e_i \otimes 1 \otimes e_j, \sum_{k,l} a_{kl} 1 \otimes e_k \otimes e_l \right] = \sum_{i,j,k,l,p} a_{ij} a_{kl} c_{jl}^p e_i \otimes e_k \otimes e_p, \\ [r_{12}, r_{23}] &= \left[ \sum_{i,j} a_{ij} e_i \otimes e_j \otimes 1, \sum_{k,l} a_{kl} 1 \otimes e_k \otimes e_l \right] = \sum_{i,j,k,l,p} a_{ij} a_{kl} c_{jk}^p e_i \otimes e_p \otimes e_l. \end{aligned}$$

Then  $r$  is a solution of the Malcev Yang-Baxter equation in  $(A, [\cdot, \cdot])$  if and only if (for any  $j, p, l$ )

$$\sum_{i,k} (a_{ij} a_{kl} c_{ik}^p + a_{kp} a_{ij} c_{ki}^l + a_{pi} a_{kl} c_{lk}^j) e_p \otimes e_j \otimes e_l = 0.$$

On the other hand, by (2.5), we get  $r(e_j^*) = \sum_i a_{ij} e_i$ . Then, if we set  $x^* = e_j^*$  and  $y^* = e_l^*$ , by (2.6),

$$\sum_{i,k} \left( a_{ij} a_{kl} c_{ik}^p + a_{kp} a_{ij} c_{ki}^l + a_{pi} a_{kl} c_{ik}^j \right) e_p = 0.$$

Therefore, it is easy to see that  $r$  is a solution of Malcev Yang-Baxter equation in  $A$  if and only if  $r$  satisfies (2.6).  $\square$

**Definition 2.3.** Let  $(A, [\cdot, \cdot])$  be a Malcev algebra. A symmetric bilinear form  $B$  on  $A$  is called *invariant* if, for all  $x, y, z \in A$ ,

$$B([x, y], z) = B(x, [y, z]). \tag{2.7}$$

**Definition 2.4.** Let  $(A, [\cdot, \cdot])$  be a Malcev algebra. A Rota-Baxter operator of weight 0 on  $A$  is a linear map  $\mathcal{R} : A \rightarrow A$  satisfying for all  $x, y \in A$ ,

$$[\mathcal{R}(x), \mathcal{R}(y)] = \mathcal{R}([\mathcal{R}(x), y] + [x, \mathcal{R}(y)]).$$

**Corollary 2.1.** Let  $(A, [\cdot, \cdot])$  be a Malcev algebra and  $r \in A \otimes A$ . Assume  $r$  is skew-symmetric and there exists a nondegenerate symmetric invariant bilinear form  $B$  on  $A$ . Define a linear map  $\varphi : A \rightarrow A^*$  by  $\langle \varphi(x), y \rangle = B(x, y)$  for any  $x, y \in A$ . Then  $r$  is a solution of the Malcev Yang-Baxter equation in  $A$  if and only if  $\mathcal{R} = r\varphi : A \rightarrow A$  is a Rota-Baxter operator.

**Proof.** For any  $x, y, z \in A$ , we have

$$\langle \varphi(ad(x)y), z \rangle = B([x, y], z) = B(z, [x, y]) = -B(y, [x, z]) = \langle ad^*(x)\varphi(y), z \rangle.$$

Hence  $\varphi(ad(x)y) = ad^*(x)\varphi(y)$  for any  $x, y \in A$ . Let  $x^* = \varphi(x)$ ,  $y^* = \varphi(y)$ , then by Theorem 2.1,  $r$  is a solution of the Malcev Yang-Baxter equation in  $A$  if and only if

$$[r\varphi(x), r\varphi(y)] = [r(x^*), r(y^*)] = r(ad^*r(x^*)(y^*) - ad^*r(y^*)(x^*)) = r\varphi([r\varphi(x), y] + [x, r\varphi(y)]).$$

Therefore the conclusion holds.  $\square$

Now, we introduce the notion of  $\mathcal{O}$ -operator of a Malcev algebra.

**Definition 2.5.** Let  $(A, [\cdot, \cdot])$  be a Malcev algebra and let  $(V, \rho)$  be a representation of  $A$ . A linear map  $T : V \rightarrow A$  is called an  $\mathcal{O}$ -operator associated to  $\rho$  if for all  $a, b \in V$ ,

$$[T(a), T(b)] = T(\rho(T(a))b - \rho(T(b))a). \tag{2.8}$$

**Example 2.1.** Let  $(A, [\cdot, \cdot])$  be a Malcev algebra. Then a Rota-Baxter operator (of weight zero) is an  $\mathcal{O}$ -operator of  $A$  associated to the adjoint representation  $(A, ad)$  and a skew-symmetric solution of Malcev Yang-Baxter equation in  $A$  is an  $\mathcal{O}$ -operator of  $A$  associated to the representation  $(A^*, ad^*)$ .

Let  $(A, [\cdot, \cdot])$  be a Malcev algebra. Let  $\rho^* : A \rightarrow gl(V^*)$  be the dual representation of the representation  $\rho : A \rightarrow gl(V)$  of the Malcev algebra  $A$ . A linear map  $T : V \rightarrow A$  can be identified as an element in  $A \otimes V^* \subset (A \ltimes_{\rho^*} V^*) \otimes (A \ltimes_{\rho} V)$  as follows. Let  $\{e_1, \dots, e_n\}$  be a basis of  $A$ . Let  $\{v_1, \dots, v_m\}$  be a basis of  $V$  and  $\{v_1^*, \dots, v_m^*\}$  be its dual basis, that is  $v_i^*(v_j) = \delta_{ij}$ . Set  $T(v_i) = \sum_{j=1}^n a_{ij} e_j, i = 1, \dots, m$ . Since as vector spaces,  $\text{Hom}(V, A) \cong A \otimes V^*$ , we have

$$\begin{aligned} T &= \sum_{i=1}^m T(v_i) \otimes v_i^* = \sum_{i=1}^m \sum_{j=1}^n a_{ij} e_j \otimes v_i^* \\ &\in A \otimes V^* \subset (A \ltimes_{\rho^*} V^*) \otimes (A \ltimes_{\rho} V). \end{aligned} \tag{2.9}$$

**Theorem 2.2.** Let  $(A, [\cdot, \cdot])$  be a Malcev algebra. Then  $T$  is an  $\mathcal{O}$ -operator of  $A$  associated to  $(V, \rho)$  if and only if  $r = T - \sigma(T)$  is a skew-symmetric solution of the Malcev Yang-Baxter equation in  $A \ltimes_{\rho^*} V^*$ .

**Proof.** From (2.9), we have  $r = T - \sigma(T) = \sum_i T(v_i) \otimes v_i^* - v_i^* \otimes T(v_i)$ . Thus,

$$\begin{aligned} [r_{12}, r_{13}] &= \sum_{i,k=1}^m \{ [T(v_i), T(v_k)] \otimes v_i^* \otimes v_k^* - \rho^*(T(v_i))v_k^* \otimes v_i^* \otimes T(v_k) \\ &\quad + \rho^*(T(v_k))v_i^* \otimes T(v_i) \otimes v_k^* \}, \\ [r_{12}, r_{23}] &= \sum_{i,k=1}^m \{ -v_i^* \otimes [T(v_i), T(v_k)] \otimes v_k^* - T(v_i) \otimes \rho^*(T(v_k))v_i^* \otimes v_k^* \\ &\quad + v_i^* \otimes \rho^*(T(v_i))v_k^* \otimes T(v_k) \}, \\ [r_{13}, r_{23}] &= \sum_{i,k=1}^m \{ v_i^* \otimes v_k^* \otimes [T(v_i), T(v_k)] + T(v_i) \otimes v_k^* \otimes \rho^*(T(v_k))v_i^* \\ &\quad - v_i^* \otimes T(v_k) \otimes \rho^*(T(v_i))v_k^* \}. \end{aligned}$$

By the definition of dual representation, we know  $\rho^*(T(v_k))v_i^* = -\sum_{j=1}^m v_i^*(\rho(T(v_k))v_j)v_j^*$ . Thus,

$$\begin{aligned} & - \sum_{i,k=1}^m T(v_i) \otimes \rho^*(T(v_k))v_i^* \otimes v_k^* = - \sum_{i,k=1}^m T(v_i) \otimes \left[ \sum_{j=1}^m -v_i^*(\rho(T(v_k))v_j)v_j^* \right] \otimes v_k^* \\ &= \sum_{i,k=1}^m \sum_{j=1}^m v_j^*(\rho(T(v_k))v_i)T(v_j) \otimes v_i^* \otimes v_k^* = \sum_{i,k=1}^m T \left( \sum_{j=1}^m (v_j^*(\rho(T(v_k))v_i)v_j) \otimes v_i^* \otimes v_k^* \right) \\ &= \sum_{i,k=1}^m T(\rho(T(v_k))v_i) \otimes v_i^* \otimes v_k^*. \end{aligned}$$

Therefore,

$$\begin{aligned} & [r_{12}, r_{13}] + [r_{12}, r_{23}] + [r_{13}, r_{23}] \\ &= \sum_{i,k=1}^m \{ ([T(v_i), T(v_k)] + T(\rho(T(v_k))v_i) - T(\rho(T(v_i))v_k)) \otimes v_i^* \otimes v_k^* \\ &\quad - v_i^* \otimes ([T(v_i), T(v_k)] + T(\rho(T(v_k))v_i) - T(\rho(T(v_i))v_k)) \otimes v_k^* \\ &\quad + v_i^* \otimes v_k^* \otimes ([T(v_i), T(v_k)] + T(\rho(T(v_k))v_i) - T(\rho(T(v_i))v_k)) \}. \end{aligned}$$

So  $r$  is a classical  $r$ -matrix in  $A \ltimes_{\rho^*} V^*$  if and only if  $T$  is an  $\mathcal{O}$ -operator.  $\square$

In fact, Theorem 2.2 gives a relation between  $\mathcal{O}$ -operator and Malcev Yang-Baxter equation. Then, we get a direct conclusion from Theorems 2.1 and 2.2.

**Corollary 2.2.** *Let  $(A, [\cdot, \cdot])$  be a Malcev algebra. Let  $\rho : A \rightarrow gl(V)$  be a representation of  $A$ . Set  $\hat{A} = A \ltimes_{\rho^*} V^*$ . Let  $T : V \rightarrow A$  be a linear map. Then the following three conditions are equivalent:*

- (i)  $T$  is an  $\mathcal{O}$ -operator of  $A$  associated to  $\rho$ ;
- (ii)  $T - \sigma(T)$  is a skew-symmetric solution of the Malcev Yang-Baxter equation in  $\hat{A}$ ;
- (iii)  $T - \sigma(T)$  is an  $\mathcal{O}$ -operator of the Malcev algebra  $\hat{A}$  associated to  $ad^*$ .

### 3. Alternative and post-alternative algebras

In this section, we recall some basic definitions about alternative and pre-alternative algebras studied in [6, 22].

### 3.1. Some basic results on alternative algebras

**Definition 3.1.** An **alternative algebra**  $(A, \cdot)$  is a vector space  $A$  equipped with a bilinear operation  $(x, y) \rightarrow x \cdot y$  satisfying, for all  $x, y, z \in A$ ,

$$as_A(x, x, y) = as_A(y, x, x) = 0, \tag{3.1}$$

where  $as_A(x, y, z) = (x \cdot y) \cdot z - x \cdot (y \cdot z)$  is the **associator**.

**Remark 3.1.** If the characteristic of the field is not 2, then an alternative algebra  $(A, \cdot)$  also satisfies the stronger axioms, for all  $x, y, z \in A$ ,

$$as_A(x, y, z) + as_A(y, x, z) = 0, \tag{3.2}$$

$$as_A(z, x, y) + as_A(z, y, x) = 0. \tag{3.3}$$

Now, recall that an algebra  $(A, \cdot)$  is called **admissible Malcev algebra** if  $(A, [\cdot, \cdot])$  is a Malcev algebra, where  $[x, y] = x \cdot y - y \cdot x$ .

**Example 3.1.** Any alternative algebra is Malcev admissible. That is if  $(A, \cdot)$  be an alternative algebra, then  $(A, [\cdot, \cdot])$  is a Malcev algebra, where  $[x, y] = x \cdot y - y \cdot x$ , for all  $x, y \in A$ .

**Definition 3.2** ([32]). Let  $(A, \cdot)$  be an alternative algebra and  $V$  be a vector space. Let  $\mathfrak{l}, \mathfrak{r} : A \rightarrow \text{End}(V)$  be two linear maps. Then,  $(V, \mathfrak{l}, \mathfrak{r})$  is called a **representation** or a **bimodule** of  $A$  if, for any  $x, y \in A$ ,

$$\mathfrak{r}(x)\mathfrak{r}(y) + \mathfrak{r}(y)\mathfrak{r}(x) - \mathfrak{r}(x \cdot y) - \mathfrak{r}(y \cdot x) = 0, \tag{3.4}$$

$$\mathfrak{l}(x \cdot y) + \mathfrak{l}(y \cdot x) - \mathfrak{l}(x)\mathfrak{l}(y) - \mathfrak{l}(y)\mathfrak{l}(x) = 0, \tag{3.5}$$

$$\mathfrak{l}(x \cdot y) + \mathfrak{r}(y)\mathfrak{l}(x) - \mathfrak{l}(x)\mathfrak{l}(y) - \mathfrak{l}(x)\mathfrak{r}(y) = 0, \tag{3.6}$$

$$\mathfrak{r}(y)\mathfrak{l}(x) + \mathfrak{r}(y)\mathfrak{r}(x) - \mathfrak{l}(x)\mathfrak{r}(y) - \mathfrak{r}(x \cdot y) = 0. \tag{3.7}$$

**Definition 3.3.** A **pre-alternative algebra** is a triple  $(A, \prec, \succ)$ , where  $A$  is a vector space,  $\prec, \succ : A \otimes A \rightarrow A$  are bilinear maps satisfying for all  $x, y, z \in A$  and  $x \cdot y = x \prec y + x \succ y$ ,

$$(x \succ y) \prec z - x \succ (y \prec z) + (y \prec x) \prec z - y \prec (x \cdot z) = 0, \tag{3.8}$$

$$(x \succ y) \prec z - x \succ (y \prec z) + (z \cdot x) \succ y - z \succ (x \succ y) = 0, \tag{3.9}$$

$$(x \cdot y) \succ z - x \succ (y \succ z) + (y \cdot x) \succ z - y \succ (x \succ z) = 0, \tag{3.10}$$

$$(z \prec x) \prec y - z \prec (x \star y) + (z \prec y) \prec x - z \prec (y \cdot x) = 0. \tag{3.11}$$

**Proposition 3.1.** Let  $(A, \prec, \succ)$  be a pre-alternative algebra. Then the product  $x \cdot y = x \prec y + x \succ y$  defines an alternative algebra  $A$ . Furthermore,  $(A, L_\succ, R_\prec)$ , where  $L_\succ(x)y = x \succ y$  and  $R_\prec(x)y = y \prec x$ , gives a representation of the associated alternative algebra  $(A, \cdot)$  on  $A$ .

**Proposition 3.2.** Let  $(A, \prec, \succ)$  be a pre-alternative algebra. Then the product  $x \triangleright y = x \succ y - y \prec x$  defines a pre-Malcev structure in  $A$ .

### 3.2. $A$ -bimodule alternative algebras, weighted $\mathcal{O}$ -operators and post-alternative algebras

**Definition 3.4.** Let  $(A, \cdot)$  be an alternative algebra. Let  $(V, \cdot_V)$  be an alternative algebra and  $\mathfrak{l}, \mathfrak{r} : A \rightarrow \text{End}(V)$  be two linear maps. We say that  $(V, \cdot_V, \mathfrak{l}, \mathfrak{r})$  is an **A-bimodule alternative algebra** if  $(V, \mathfrak{l}, \mathfrak{r})$  is a representation of  $(A, \cdot)$  such that the following compatibility conditions hold (for all  $x \in A, a, b \in V$ )

$$\mathfrak{r}(x)(a \cdot_V b) - a \cdot_V (\mathfrak{r}(x)b) + \mathfrak{r}(x)(b \cdot_V a) - b \cdot_V (\mathfrak{r}(x)a) = 0, \tag{3.12}$$

$$(\mathfrak{l}(x)a) \cdot_V b - \mathfrak{l}(x)(a \cdot_V b) + (\mathfrak{l}(x)b) \cdot_V a - \mathfrak{l}(x)(b \cdot_V a) = 0, \tag{3.13}$$

$$(\mathfrak{l}(x)a) \cdot_V b - a \cdot_V (\mathfrak{l}(x)b) + (\mathfrak{r}(x)a) \cdot_V b - \mathfrak{l}(x)(a \cdot_V b) = 0, \quad (3.14)$$

$$(\mathfrak{r}(x)a) \cdot_V b - a \cdot_V (\mathfrak{l}(x)b) + \mathfrak{r}(x)(a \cdot_V b) - a \cdot_V (\mathfrak{r}(x)b) = 0. \quad (3.15)$$

**Proposition 3.3.** Let  $(A, \cdot)$  and  $(V, \cdot_V)$  be two alternative algebras and  $\mathfrak{l}, \mathfrak{r} : A \rightarrow \text{End}(V)$  be two linear maps. Then  $(V, \cdot_V, \mathfrak{l}, \mathfrak{r})$  is an  $A$ -bimodule alternative algebra if and only if the direct sum  $A \oplus V$  of vector spaces is an alternative algebra (the semi-direct sum) with the product on  $A \oplus V$  defined for all  $x, y \in A$ ,  $a, b \in V$  by

$$(x + a) * (y + b) = x \cdot y + \mathfrak{l}(x)b + \mathfrak{r}(y)a + a \cdot_V b. \quad (3.16)$$

We denote this algebra by  $A \rtimes_{\mathfrak{l}, \mathfrak{r}} V$  or simply  $A \rtimes V$ . Further, if  $(A, \cdot)$  is an alternative algebra, then it is easy to see that  $(A, \cdot, L, R)$  is an  $A$ -bimodule alternative algebra, where  $L$  and  $R$  are the left and right multiplication operators corresponding to the multiplication  $\cdot$ .

**Proof.** For any  $x, y, z \in A, a, b, c \in V$

$$\begin{aligned} & as_{A \oplus V}(x + a, y + b, z + c) + as_{A \oplus V}(y + b, x + a, z + c) \\ &= ((x + a) * (y + b)) * (z + c) - (x + a) * ((y + b) * (z + c)) + ((y + b) * (x + a)) * (z + c) \\ &\quad - (y + b) * ((x + a) * (z + c)) \\ &= (x \cdot y + \mathfrak{l}(x)b + \mathfrak{r}(y)a + a \cdot_V b) * (z + c) - (x + a) * (y \cdot z + \mathfrak{l}(y)c + \mathfrak{r}(z)b + b \cdot_V c) \\ &\quad + (y \cdot x + \mathfrak{l}(y)a + \mathfrak{r}(x)b + b \cdot_V a) * (z + c) - (y + b) * (x \cdot z + \mathfrak{l}(x)c + \mathfrak{r}(z)a + a \cdot_V c) \\ &= (x \cdot y) \cdot z + \mathfrak{l}(x \cdot y)c + \mathfrak{r}(z)(\mathfrak{l}(x)b + \mathfrak{r}(y)a + a \cdot_V b) + (\mathfrak{l}(x)b + \mathfrak{r}(y)a + a \cdot_V b) \cdot_V c \\ &\quad - x \cdot (y \cdot z) - \mathfrak{l}(x)(\mathfrak{l}(y)c + \mathfrak{r}(z)b + b \cdot_V c) - \mathfrak{r}(y \cdot z)a - a \cdot_V (\mathfrak{l}(y)c + \mathfrak{r}(z)b + b \cdot_V c) \\ &\quad + (y \cdot x) \cdot z + \mathfrak{l}(y \cdot x)c + \mathfrak{r}(z)(\mathfrak{l}(y)a + \mathfrak{r}(x)b + b \cdot_V a) + (\mathfrak{l}(y)a + \mathfrak{r}(x)b + b \cdot_V a) \cdot_V c \\ &\quad - y \cdot (x \cdot z) - \mathfrak{l}(y)(\mathfrak{l}(x)c + \mathfrak{r}(z)a + a \cdot_V c) - \mathfrak{r}(x \cdot z)b - b \cdot_V (\mathfrak{l}(x)c + \mathfrak{r}(z)a + a \cdot_V c). \end{aligned}$$

Hence,  $as_{A \oplus V}(x + a, y + b, z + c) + as_{A \oplus V}(y + b, x + a, z + c) = 0$  if and only if (3.2), (3.12) and (3.14) hold.

Analogously,  $as_{A \oplus V}(z + c, x + a, y + b) + as_{A \oplus V}(z + c, y + b, x + a) = 0$  if and only if (3.3), (3.13) and (3.15) hold.  $\square$

**Definition 3.5** ([3]). A **post-alternative algebra**  $(A, \prec, \succ, \cdot)$  is a vector space  $A$  equipped with bilinear operations  $\prec, \succ, \cdot : A \otimes A \rightarrow A$  obeying the following equations for  $\star = \prec + \succ + \cdot$  and all  $x, y, z \in A$ ,

$$(x \cdot y) \cdot z - x \cdot (y \cdot z) + (y \cdot x) \cdot z - y \cdot (x \cdot z) = 0, \quad (3.17)$$

$$(z \cdot x) \cdot y - z \cdot (x \cdot y) + (z \cdot y) \cdot x - z \cdot (y \cdot x) = 0, \quad (3.18)$$

$$(x \cdot y) \prec z - x \cdot (y \prec z) + (y \cdot x) \prec z - y \cdot (x \prec z) = 0, \quad (3.19)$$

$$(x \succ y) \cdot z - x \succ (y \cdot z) + (x \succ z) \cdot y - x \succ (z \cdot y) = 0, \quad (3.20)$$

$$(y \succ x) \cdot z - x \cdot (y \succ z) + (x \prec y) \cdot z - y \succ (x \cdot z) = 0, \quad (3.21)$$

$$(z \prec x) \cdot y - z \cdot (x \succ y) + (z \cdot y) \prec x - z \cdot (y \prec x) = 0, \quad (3.22)$$

$$(x \succ y) \prec z - x \succ (y \prec z) + (y \prec x) \prec z - y \prec (x \star z) = 0, \quad (3.23)$$

$$(x \succ y) \prec z - x \succ (y \prec z) + (z \star x) \succ y - z \succ (x \succ y) = 0, \quad (3.24)$$

$$(x \star y) \succ z - x \succ (y \succ z) + (y \star x) \succ z - y \succ (x \succ z) = 0, \quad (3.25)$$

$$(z \prec x) \prec y - z \prec (x \star y) + (z \prec y) \prec x - z \prec (y \star x) = 0. \quad (3.26)$$

**Remark 3.2.** Let  $(A, \prec, \succ, \cdot)$  be a post-alternative algebra. If the operation  $\cdot$  is trivial, then it is a pre-alternative algebra.

Let  $(A, \prec, \succ, \cdot)$  be a post-alternative algebra, it is obvious that  $(A, \cdot)$  is an alternative algebra. On the other hand, it is straightforward to get the following conclusion:



**Theorem 3.1.** *If  $(A, \prec, \succ, \cdot)$  is a post-alternative algebra, then with a new bilinear operation  $\star : A \times A \rightarrow A$  on  $A$  defined for all  $x, y \in A$  by*

$$x \star y = x \prec y + x \succ y + x \cdot y, \tag{3.27}$$

*$(A, \star)$  becomes an alternative algebra. It is called the associated alternative algebra of  $(A, \prec, \succ, \cdot)$ .*

**Proof.** In fact, for any  $x, y, z \in A$ , we have

$$\begin{aligned} as_A(x, y, z) + as_A(y, x, z) &= (x \star y) \star z - x \star (y \star z) + (y \star x) \star z - y \star (x \star z) \\ &= (x \star y) \prec z + (x \star y) \succ z + (x \star y) \cdot z - x \prec (y \star z) - x \succ (y \star z) - x \cdot (y \star z) \\ &\quad + (y \star x) \prec z + (y \star x) \succ z + (y \star x) \cdot z - y \prec (x \star z) - y \succ (x \star z) - y \cdot (x \star z) \\ &= (x \prec y) \prec z + (x \succ y) \prec z + (x \cdot y) \prec z + (x \star y) \succ z + (x \prec y) \cdot z + (x \succ y) \cdot z \\ &\quad + (x \cdot y) \cdot z - x \prec (y \star z) - x \succ (y \prec z) - x \succ (y \succ z) - x \succ (y \cdot z) - x \cdot (y \prec z) \\ &\quad - x \cdot (y \succ z) - x \cdot (y \cdot z) + (y \prec x) \prec z + (y \succ x) \prec z + (y \cdot x) \prec z + (y \star x) \succ z \\ &\quad + (y \prec x) \cdot z + (y \succ x) \cdot z + (y \cdot x) \cdot z - y \prec (x \star z) - y \succ (x \prec z) - y \succ (x \succ z) \\ &\quad - y \succ (x \cdot z) - y \cdot (x \prec z) - y \cdot (x \succ z) - y \cdot (x \cdot z) = 0, \end{aligned}$$

and then replacing  $(x, y, z)$  in this computation by  $(z, x, y)$  yields  $as_A(z, x, y) + as_A(z, y, x) = 0$ , which completes the proof according to Definition 3.1 and Remark 3.1.  $\square$

The following terminology is motivated by the notion of  $\lambda$ -weighted  $\mathcal{O}$ -operator as a generalization of (the operator form of) the classical Yang-Baxter equation in [2, 19].

**Definition 3.6.** Let  $(A, \cdot)$  be an alternative algebra and  $(V, \cdot_V, \mathfrak{l}, \mathfrak{r})$  be an  $A$ -bimodule alternative algebra. A linear map  $T : V \rightarrow A$  is called a  $\lambda$ -weighted  $\mathcal{O}$ -operator associated to  $(V, \cdot_V, \mathfrak{l}, \mathfrak{r})$  if  $T$  satisfies, for all  $a, b \in V$ ,

$$T(a) \cdot T(b) = T(\mathfrak{l}(T(a))b) + \mathfrak{r}(T(b))a + \lambda a \cdot_V b. \tag{3.28}$$

When  $(V, \cdot_V, \mathfrak{l}, \mathfrak{r}) = (A, \cdot, L, R)$ , the condition (3.28) becomes

$$\mathcal{R}(x) \cdot \mathcal{R}(y) = \mathcal{R}(\mathcal{R}(x) \cdot y) + x \cdot \mathcal{R}(y) + \lambda x \cdot y. \tag{3.29}$$

The property (3.29) implies that  $\mathcal{R} : A \rightarrow A$  is a  $\lambda$ -weighted Rota-Baxter operator on the alternative algebra  $(A, \cdot)$ .

**Theorem 3.2.** *Let  $(A, \cdot)$  be an alternative algebra and  $(V, \cdot_V, \mathfrak{l}, \mathfrak{r})$  be an  $A$ -bimodule alternative algebra. Let  $T : V \rightarrow A$  be a  $\lambda$ -weighted  $\mathcal{O}$ -operator associated to  $(V, \cdot_V, \mathfrak{l}, \mathfrak{r})$ . Define three new bilinear operations  $\prec, \succ, \circ : V \otimes V \rightarrow V$  on  $V$  as follows:*

$$a \succ b = \mathfrak{l}(T(a))b, \quad a \prec b = \mathfrak{r}(T(b))a, \quad a \circ b = \lambda a \cdot_V b. \tag{3.30}$$

*Then  $(V, \prec, \succ, \circ)$  becomes a post-alternative algebra and  $T$  is a homomorphism of alternative algebras.*

**Proof.** Since  $A$  is an alternative algebra, (3.17) and (3.18) obviously hold. Furthermore, for any  $a, b, c \in V$ , we have

$$\begin{aligned} &(a \circ b) \prec c - a \circ (b \prec c) + (b \circ a) \prec c - b \circ (a \prec c) \\ &= (\lambda a \cdot_V b) \prec c - a \circ (\mathfrak{r}(T(c))b) + (\lambda b \cdot_V a) \prec c - b \circ (\mathfrak{r}(T(c))a) \\ &= \lambda(\mathfrak{r}(T(c))(a \cdot_V b) - a \cdot_V (\mathfrak{r}(T(c))b) + \mathfrak{r}(T(c))(b \cdot_V a) - b \cdot_V (\mathfrak{r}(T(c))a)) = 0. \end{aligned}$$

So, (3.19) holds. Moreover, (3.20) holds. Indeed,

$$\begin{aligned} &(a \succ b) \circ c - a \succ (b \circ c) + (a \succ c) \circ b - a \succ (c \circ b) \\ &= (\mathfrak{l}(T(a))b) \circ c - a \succ (\lambda b \cdot_V c) + (\mathfrak{l}(T(a))c) \circ b - a \succ (\lambda c \cdot_V b) \\ &= \lambda((\mathfrak{l}(T(a))b) \cdot_V c - \mathfrak{l}(T(a))(b \cdot_V c) + (\mathfrak{l}(T(a))c) \cdot_V b - \mathfrak{l}(T(a))(c \cdot_V b)) = 0. \end{aligned}$$

To prove identity (3.21), we compute as follows

$$\begin{aligned} & (b \succ a) \circ c - a \circ (b \succ c) + (a \prec b) \circ c - b \succ (a \circ c) \\ &= (\mathfrak{l}(T(b))a) \circ c - a \circ (\mathfrak{l}(T(b))c) + (\mathfrak{r}(T(b))a) \circ c - b \succ (\lambda a \cdot_V c) \\ &= \lambda(\mathfrak{l}(T(b))a) \cdot_V c - a \cdot_V (\mathfrak{l}(T(b))c) + (\mathfrak{r}(T(b))a) \cdot_V c - \mathfrak{l}(T(b))(a \cdot_V c) = 0. \end{aligned}$$

The other identities can be shown similarly.  $\square$

**Corollary 3.1.** *Let  $(A, \cdot)$  be an alternative algebra and  $\mathcal{R} : A \rightarrow A$  be a  $\lambda$ -weighted Rota-Baxter operator for  $A$ . Then  $(A, \prec, \succ, \circ)$  is a post-alternative algebra with the operations*

$$x \prec y = x \cdot \mathcal{R}(y), \quad x \succ y = \mathcal{R}(x) \cdot y, \quad x \circ y = \lambda x \cdot y.$$

#### 4. Weighted $\mathcal{O}$ -operators and post-Malcev algebras

We start this section by introducing the notion of post-Malcev algebra together with some of its basic properties. We will also briefly discuss the post-Malcev algebra structure underneath the  $\lambda$ -weighted  $\mathcal{O}$ -operators. We then show that there is a close relationship between post-Malcev algebras and post-alternative algebras in parallel to the relationship between pre-Malcev and pre-alternative algebras.

##### 4.1. $A$ -module Malcev algebras and weighted $\mathcal{O}$ -operators

Now, we extend the concept of a module to that of an  $A$ -module algebra by replacing the  $\mathbb{K}$ -module  $V$  by a Malcev algebra. Next, we introduce  $\lambda$ -weighted  $\mathcal{O}$ -operators on Malcev algebras and study some basic properties.

**Definition 4.1.** Let  $(A, [\cdot, \cdot])$  and  $(V, [\cdot, \cdot]_V)$  be two Malcev algebras. Let  $\rho : A \rightarrow \text{End}(V)$  be a linear map such that  $(V, \rho)$  is a representation of  $(A, [\cdot, \cdot])$  and the following compatibility conditions hold for all  $x, y, \in A$ ,  $a, b, c \in V$  :

$$\rho([x, y])[a, b]_V = \rho(x)[\rho(y)a, b]_V - [\rho(y)\rho(x)a, b]_V - [\rho(x)\rho(y)b, a]_V + \rho(y)[\rho(x)b, a]_V, \quad (4.1)$$

$$[\rho(x)a, \rho(y)b]_V = [\rho([x, y])a, b]_V - \rho(x)[\rho(y)a, b]_V + \rho(y)\rho(x)[a, b]_V + [\rho(y)\rho(x)b, a]_V, \quad (4.2)$$

$$[\rho(x)a, [b, c]_V]_V = [[\rho(x)b, a]_V, c]_V - \rho(x)[[b, a]_V, c]_V - [\rho(x)[a, c]_V, b]_V - [[\rho(x)c, b]_V, a]_V. \quad (4.3)$$

Then  $(V, [\cdot, \cdot]_V, \rho)$  is called an  **$A$ -module Malcev algebra**.

In the sequel, an  $A$ -module Malcev algebra is denoted by  $(V; [\cdot, \cdot]_V, \rho)$ . It is straightforward to get the following:

**Proposition 4.1.** *Let  $(A, [\cdot, \cdot])$  and  $(V, [\cdot, \cdot]_V)$  be two Malcev algebras and  $(V; [\cdot, \cdot]_V, \rho)$  be an  $A$ -module Malcev algebra. Then  $(A \oplus V, [\cdot, \cdot]_\rho)$  carries a new Malcev algebra structure with bracket*

$$[x + a, y + b]_\rho = [x, y] + \rho(x)b - \rho(y)a + [a, b]_V, \quad \forall x, y \in A, \quad a, b \in V. \quad (4.4)$$

*This is called the semi-direct product, often denoted by  $A \ltimes_\rho V$  or simply  $A \ltimes V$ .*

**Proof.** For  $x, y, z, t \in A$  and  $a, b, c, d \in V$ ,

$$\begin{aligned} & [[x + a, z + c]_\rho, [y + b, t + d]_\rho]_\rho = [[x, z], [y, t]] + \rho([x, z])\rho(y)d - \rho([x, z])\rho(t)b \\ & \quad + \rho([x, z])[b, d]_V - \rho([y, t])\rho(x)c + \rho([y, t])\rho(z)a - \rho([y, t])[a, c]_V + [\rho(x)c, \rho(y)d]_V \\ & \quad - [\rho(x)c, \rho(t)b]_V + [\rho(x)c, [b, d]_V]_V - [\rho(z)a, \rho(y)d]_V + [\rho(z)a, \rho(t)b]_V - [\rho(z)a, [b, d]_V]_V \\ & \quad + [[a, c]_V, \rho(y)d]_V - [[a, c]_V, \rho(t)b]_V + [[a, c]_V, [b, d]_V]_V, \end{aligned}$$

$$[[[x + a, y + b]_\rho, z + c]_\rho, t + d]_\rho = [[[x, y], z], t] + \rho([x, y], z)d - \rho(t)\rho([x, y])c$$

$$\begin{aligned}
 & + \rho(t)\rho(z)\rho(x)b - \rho(t)\rho(z)\rho(y)a + \rho(t)\rho(z)[a, b]_V - \rho(t)[\rho(x)b, c]_V + \rho(t)[\rho(y)a, c]_V \\
 & - \rho(t)[[a, b]_V, c]_V + [\rho([x, y])c, d]_V - [\rho(z)\rho(x)b, d]_V + [\rho(z)\rho(y)a, d]_V - [\rho(z)[a, b]_V, d]_V \\
 & + [[\rho(x)b, c]_V, d]_V - [[\rho(y)a, c]_V, d]_V + [[[a, b]_V, c]_V, d]_V, \\
 [[y + b, z + c]_\rho, t + d]_\rho, x + a]_\rho & = [[[y, z], t], x] + \rho([y, z], t)a - \rho(x)\rho([y, z])d \\
 & + \rho(x)\rho(t)\rho(y)c - \rho(x)\rho(t)\rho(z)b + \rho(x)\rho(t)[b, c]_V - \rho(x)[\rho(y)c, d]_V + \rho(x)[\rho(z)b, d]_V \\
 & - \rho(x)[[b, c]_V, d]_V + [\rho([y, z])d, a]_V - [\rho(t)\rho(y)c, a]_V + [\rho(t)\rho(z)b, a]_V - [\rho(t)[b, c]_V, a]_V \\
 & + [[\rho(y)c, d]_V, a]_V - [[\rho(z)b, d]_V, a]_V + [[[b, c]_V, d]_V, a]_V, \\
 [[z + c, t + d]_\rho, x + a]_\rho, y + b]_\rho & = [[[z, t], x], y] + \rho([z, t], x)b - \rho(y)\rho([z, t])a \\
 & + \rho(y)\rho(x)\rho(z)d - \rho(y)\rho(x)\rho(t)c + \rho(y)\rho(x)[c, d]_V - \rho(y)[\rho(z)d, a]_V + \rho(y)[\rho(t)c, a]_V \\
 & - \rho(y)[[c, d]_V, a]_V + [\rho([z, t])a, b]_V - [\rho(x)\rho(z)d, b]_V + [\rho(x)\rho(t)c, b]_V - [\rho(x)[c, d]_V, b]_V \\
 & + [[\rho(z)d, a]_V, b]_V - [[\rho(t)c, a]_V, b]_V + [[[c, d]_V, a]_V, b]_V, \\
 [[t + d, x + a]_\rho, y + b]_\rho, z + c]_\rho & = [[[t, x], y], z] + \rho([t, x], y)c - \rho(z)\rho([t, x])b \\
 & + \rho(z)\rho(y)\rho(t)a - \rho(z)\rho(y)\rho(x)d + \rho(z)\rho(y)[d, a]_V - \rho(z)[\rho(t)a, b]_V + \rho(z)[\rho(x)d, b]_V \\
 & - \rho(z)[[d, a]_V, b]_V + [\rho([t, x])b, c]_V - [\rho(y)\rho(t)a, c]_V + [\rho(y)\rho(x)d, c]_V - [\rho(y)[d, a]_V, c]_V \\
 & + [[\rho(t)a, b]_V, c]_V - [[\rho(x)d, b]_V, c]_V + [[[d, a]_V, b]_V, c]_V.
 \end{aligned}$$

Then  $A \oplus V$  is a Malcev algebra if and only if  $(V, \rho)$  is a representation on  $A$  satisfying (4.1)-(4.3).  $\square$

**Remark 4.1.** More generally, if we define a  $\lambda$ -semi-direct product denoted by  $A \ltimes^\lambda V$  as follow

$$[x + a, y + b]_\rho^\lambda = [x, y] + \rho(x)b - \rho(y)a + \lambda[a, b]_V, \quad \forall x, y \in A, \quad a, b \in V \quad (4.5)$$

we obtain the same characterization given in the above Proposition.

**Example 4.1.** It is known that  $(A, ad)$  is a representation of  $A$  called the adjoint representation. Then  $(A, [\cdot, \cdot], ad)$  is an  $A$ -module Malcev algebra.

**Proposition 4.2.** Let  $(A, \cdot)$  be an alternative algebra. Then the triplet  $(V; [\cdot, \cdot]_V, \mathfrak{l} - \mathfrak{r})$  defines an  $A$ -module Malcev admissible algebra of  $(A, [\cdot, \cdot])$ .

**Proof.** By Proposition 3.3,  $A \ltimes_{\mathfrak{l}, \mathfrak{r}} V$  is an alternative algebra. For its associated Malcev algebra  $(A \oplus V, \overbrace{[\cdot, \cdot]})$ , we have

$$\begin{aligned}
 \overbrace{[x + a, y + b]} & = (x + a) * (y + b) - (y + b) * (x + a) \\
 & = x \cdot y + \mathfrak{l}(x)b + \mathfrak{r}(y)a + a \cdot_V b - y \cdot x - \mathfrak{l}(y)a - \mathfrak{r}(x)b - b \cdot_V a \\
 & = [x, y] + (\mathfrak{l} - \mathfrak{r})(x)b - (\mathfrak{l} - \mathfrak{r})(y)a + [a, b]_V.
 \end{aligned}$$

According to (4.4), we deduce that  $(V; [\cdot, \cdot]_V, \mathfrak{l} - \mathfrak{r})$  is an  $A$ -module Malcev admissible algebra of  $(A, [\cdot, \cdot])$ .  $\square$

**Definition 4.2.** Let  $(A, [\cdot, \cdot])$  be a Malcev algebra and  $(V; [\cdot, \cdot]_V, \rho)$  be an  $A$ -module Malcev algebra. A linear map  $T : V \rightarrow A$  is said to be a  $\lambda$ -weighted  $\mathcal{O}$ -operator associated to  $(V; [\cdot, \cdot]_V, \rho)$  if for all  $a, b \in V$ ,

$$[T(a), T(b)] = T(\rho(T(a))b - \rho(T(b))a) + \lambda[a, b]_V. \quad (4.6)$$

Obviously, a  $\lambda$ -weighted  $\mathcal{O}$ -operator associated to  $(A, [\cdot, \cdot], ad)$  is just a  $\lambda$ -weighted Rota-Baxter operator on  $A$ . A  $\lambda$ -weighted  $\mathcal{O}$ -operator can be viewed as the relative version of a Rota-Baxter operator in the sense that the domain and range of an  $\mathcal{O}$ -operator might be different.

- Example 4.2.**
- (i) A Rota-Baxter operator on  $A$  is simply a 0-weighted  $\mathcal{O}$ -operator.
  - (ii) The identity map  $id : A \rightarrow A$  is a  $(-1)$ -weighted  $\mathcal{O}$ -operator.
  - (iii) If  $f : A \rightarrow A$  is a Malcev algebra homomorphism and  $f^2 = f$  (idempotent condition), then  $f$  is a  $(-1)$ -weighted  $\mathcal{O}$ -operator.
  - (iv) If  $T$  is a  $\lambda$ -weighted  $\mathcal{O}$ -operator, then for any  $\nu \in \mathbb{K}$ , the map  $\nu T$  is a  $(\nu\lambda)$ -weighted  $\mathcal{O}$ -operator.
  - (v) If  $T$  is a  $\lambda$ -weighted  $\mathcal{O}$ -operator, then  $-\lambda id - T$  is a  $\lambda$ -weighted  $\mathcal{O}$ -operator.

In the following, we characterize  $\lambda$ -weighted  $\mathcal{O}$ -operators in terms of their graph.

**Proposition 4.3.** *Let  $(V; [\cdot, \cdot]_V, \rho)$  be an  $A$ -module Malcev algebra. Then a linear map  $T : V \rightarrow A$  is a  $\lambda$ -weighted  $\mathcal{O}$ -operator associated to  $(V, [\cdot, \cdot]_V, \rho)$  if and only if the graph*

$$\text{Gr}(T) = \{T(a) + a \mid a \in V\}$$

*of the map  $T$  is a subalgebra of the  $\lambda$ -semi-direct product  $A \ltimes^\lambda V$ .*

**Proof.** Let  $T : V \rightarrow A$  be a linear map. For all  $a, b \in V$ , we have

$$[T(a) + a, T(b) + b]_\rho^\lambda = [T(a), T(b)] + \rho(T(a))b - \rho(T(b))a + \lambda[a, b]_V,$$

which implies that the graph  $\text{Gr}(T) = \{T(a) + a \mid a \in V\}$  is a subalgebra of the Malcev algebra  $A \ltimes^\lambda V$  if and only if  $T$  satisfies

$$[T(a), T(b)] = T(\rho(T(a))b - \rho(T(b))a) + \lambda[a, b]_V,$$

which means that  $T$  is a  $\lambda$ -weighted  $\mathcal{O}$ -operator. □

As a consequence of the above proposition, we get the following.

**Corollary 4.1.** *Let  $T : V \rightarrow A$  be a  $\lambda$ -weighted  $\mathcal{O}$ -operator. Since  $\text{Gr}(T)$  is isomorphic to  $V$  as a vector space, we get that  $V$  inherits a new Malcev algebra structure with the bracket*

$$[a, b]_T := \rho(T(a))b - \rho(T(b))a + \lambda[a, b]_V, \quad \text{for } a, b \in V.$$

*In other words,  $(V, [\cdot, \cdot]_T)$  is a Malcev algebra, denoted by  $V_T$  (called the induced Malcev algebra). Moreover,  $T : V_T \rightarrow A$  is a homomorphism of Malcev algebras.*

Let  $T, T' : (A, [\cdot, \cdot]) \rightarrow (V, [\cdot, \cdot]_V)$  be two  $\lambda$ -weighted  $\mathcal{O}$ -operators. A **homomorphism** from  $T$  to  $T'$  consists of Malcev algebra homomorphisms  $\phi : A \rightarrow A$  and  $\psi : V \rightarrow V$  such that

$$\phi \circ T = T' \circ \psi, \tag{4.7}$$

$$\psi(\rho(x)a) = \rho(\phi(x))(\psi(a)), \quad \forall x \in A, a \in V. \tag{4.8}$$

In particular, if both  $\phi$  and  $\psi$  are invertible,  $(\phi, \psi)$  is called an **isomorphism** from  $T$  to  $T'$ .

**Proposition 4.4.** *Let  $(\phi, \psi)$  be a homomorphism of  $\lambda$ -weighted  $\mathcal{O}$ -operators from  $T$  to  $T'$ . Then  $\psi : V \rightarrow V$  is a homomorphism of induced Malcev algebras from  $(V, [\cdot, \cdot]_T)$  to  $(V, [\cdot, \cdot]_{T'})$ .*

**Proof.** For any  $a, b \in V$ , we have

$$\begin{aligned} \psi([a, b]_T) &= \psi(\rho(T(a))b - \rho(T(b))a + \lambda[a, b]_V) \\ &= \rho(\phi(T(a)))(\psi(b)) - \rho(\phi(T(b)))(\psi(a)) + \lambda[\psi(a), \psi(b)]_V \\ &= \rho(T'(\psi(a)))(\psi(b)) - \rho(T'(\psi(b)))(\psi(a)) + \lambda[\psi(a), \psi(b)]_V = [\psi(a), \psi(b)]_{T'}. \end{aligned}$$

This shows that  $\psi : (V, [\cdot, \cdot]_T) \rightarrow (V, [\cdot, \cdot]_{T'})$  is a homomorphism of Malcev algebras. □

In the sequel, we characterize  $\lambda$ -weighted  $\mathcal{O}$ -operators associated to  $(V; [\cdot, \cdot]_V, \rho)$  in terms of the Nijenhuis operators. Recall that a Nijenhuis operator on a Malcev algebra  $(A, [\cdot, \cdot])$  is a linear map  $N : A \rightarrow A$  satisfying, for all  $x, y \in A$ ,

$$[N(x), N(y)] = N([N(x), y] - [N(y), x] - N([x, y])).$$

**Proposition 4.5.** *Let  $(V; [\cdot, \cdot]_V, \rho)$  be an  $A$ -module Malcev algebra. Then a linear map  $T : V \rightarrow A$  is a  $\lambda$ -weighted  $\mathcal{O}$ -operator associated to  $(V; [\cdot, \cdot]_V, \rho)$  if and only if*

$$N_T = \begin{bmatrix} \lambda id & -T \\ 0 & 0 \end{bmatrix} : A \oplus V \rightarrow A \oplus V$$

is a Nijenhuis operator on the semi-direct product Malcev algebra  $A \ltimes V$ .

**Proof.** For all  $x, y \in A, a, b \in V$ , on the one hand, we have

$$\begin{aligned} [N_T(x + a), N_T(y + b)]_\rho &= [\lambda x - T(a), \lambda y - T(b)]_\rho \\ &= \lambda^2[x, y] - \lambda[x, T(b)] - \lambda[T(a), y] + [T(a), T(b)]. \end{aligned}$$

On the other hand, since  $N_T^2 = N_T$ , we have

$$\begin{aligned} &N_T([N_T(x + a), y + b]_\rho - [N_T(y + b), x + a]_\rho - N_T([x + a, y + b]_\rho)) \\ &= N_T([\lambda x - T(a), y + b]_\rho - [\lambda y - T(b), x + a]_\rho - N_T([x, y] + \rho(x)b - \rho(y)a + [a, b]_V)) \\ &= \lambda^2[x, y] - \lambda[x, T(b)] - \lambda[T(a), y] + T(\rho(T(a))b - \rho(T(b))a + \lambda[a, b]_V). \end{aligned}$$

Therefore,  $N_T$  is a Nijenhuis operator on the semi-direct product Malcev algebra  $A \ltimes V$  if and only if (4.6) is satisfied.  $\square$

**Corollary 4.2.** *A linear map  $T : V \rightarrow A$  is a  $\lambda$ -weighted  $\mathcal{O}$ -operator associated to  $(V; [\cdot, \cdot]_V, \rho)$  if and only if the operator*

$$N_T = \begin{bmatrix} id & -T \\ 0 & 0 \end{bmatrix} : A \oplus V \rightarrow A \oplus V$$

is a Nijenhuis operator on the  $\lambda$ -semi-direct product Malcev algebra  $(A \oplus V, [\cdot, \cdot]_\rho^\lambda)$ .

### 4.2. Definition and constructions of post-Malcev algebras

In this section, we introduce the notion of post-Malcev algebras. We show that post-Malcev algebras arise naturally from a  $\lambda$ -weighted  $\mathcal{O}$ -operators. Therefore, post-Malcev algebras can be viewed as the underlying algebraic structures of  $\lambda$ -weighted  $\mathcal{O}$ -operators on Malcev algebras. Finally, we study some properties of post-Malcev algebras.

**Definition 4.3.** A **post-Malcev algebra**  $(A, [\cdot, \cdot], \triangleright)$  is a Malcev algebra  $(A, [\cdot, \cdot])$  together with a bilinear map  $\triangleright : A \otimes A \rightarrow A$  such that for all  $x, y, z \in A$ , and  $\{x, y\} = x \triangleright y - y \triangleright x + [x, y]$ ,

$$\{x, z\} \triangleright [y, t] = x \triangleright [z \triangleright y, t] - [z \triangleright (x \triangleright y), t] - [x \triangleright (z \triangleright t), y] + z \triangleright [x \triangleright t, y], \tag{4.9}$$

$$[x \triangleright z, y \triangleright t] = [\{x, y\} \triangleright z, t] - x \triangleright [y \triangleright z, t] + y \triangleright (x \triangleright [z, t]) + [y \triangleright (x \triangleright t), z], \tag{4.10}$$

$$[x \triangleright z, [y, t]] = [[x \triangleright y, z], t] - x \triangleright [[y, z], t] - [x \triangleright [z, t], y] - [[x \triangleright t, y], z], \tag{4.11}$$

$$\{\{x, y\}, z\} \triangleright t = x \triangleright (y \triangleright (z \triangleright t)) - z \triangleright (x \triangleright (y \triangleright t)) - y \triangleright (\{x, z\} \triangleright t) - \{y, z\} \triangleright (x \triangleright t). \tag{4.12}$$

**Example 4.3.**

- (1) A pre-Malcev algebra is a post-Malcev algebra with an abelian Malcev algebra  $(A, [\cdot, \cdot] = 0, \triangleright)$ . (See [16, 26] for more details.)
- (2) Post-Malcev algebras generalize post-Lie algebras.
- (3) If  $(A, [\cdot, \cdot])$  is a Malcev algebra, then  $(A, [\cdot, \cdot], \triangleright)$  is a post-Malcev algebra, where  $x \triangleright y = [y, x]$  for all  $x, y \in A$ .

Let  $(A, [\cdot, \cdot], \triangleright)$  and  $(A', [\cdot, \cdot]', \triangleright')$  be two post-Malcev algebras. A homomorphism of post-Malcev algebras is a linear map  $f : A \rightarrow A'$  such that  $f([x, y]) = [f(x), f(y)]'$  and  $f(x \triangleright y) = f(x) \triangleright' f(y)$ .

**Proposition 4.6.** *Let  $(A, [\cdot, \cdot], \triangleright)$  be a post-Malcev algebra. Then the bracket*

$$\{x, y\} = x \triangleright y - y \triangleright x + [x, y] \quad (4.13)$$

*defines a Malcev algebra structure on  $A$ . We denote this algebra by  $A^C$  and we call it the sub-adjacent Malcev algebra of  $A$ .*

**Proof.** The skew symmetry is obvious. For all  $x, y, z, t \in A$ , we have

$$\begin{aligned} \{\{x, z\}, \{y, t\}\} &= \{x, z\} \triangleright \{y, t\} - \{y, t\} \triangleright \{x, z\} + [\{x, z\}, \{y, t\}] \\ &= \{x, z\} \triangleright (y \triangleright t) - \{x, z\} \triangleright (t \triangleright y) + \{x, z\} \triangleright [y, t] - \{y, t\} \triangleright (x \triangleright z) \\ &\quad + \{y, t\} \triangleright (z \triangleright x) - \{y, t\} \triangleright [x, z] + [x \triangleright z, y \triangleright t] - [x \triangleright z, t \triangleright y] \\ &\quad + [x \triangleright z, [y, t]] - [z \triangleright x, y \triangleright t] + [z \triangleright x, t \triangleright y] - [z \triangleright x, [y, t]] \\ &\quad + [[x, z], y \triangleright t] - [[x, z], t \triangleright y] + [[x, z], [y, t]], \\ \{\{\{x, y\}, z\}, t\} &= \{\{x, y\}, z\} \triangleright t - t \triangleright \{\{x, y\}, z\} + [\{\{x, y\}, z\}, t] \\ &= \{\{x, y\}, z\} \triangleright t - t \triangleright (\{x, y\} \triangleright z) + t \triangleright (z \triangleright (x \triangleright y)) - t \triangleright (z \triangleright (y \triangleright x)) \\ &\quad + t \triangleright (z \triangleright [x, y]) - t \triangleright [x \triangleright y, z] + t \triangleright [y \triangleright x, z] - t \triangleright [[x, y], z] \\ &\quad + [\{x, y\} \triangleright z, t] - [z \triangleright (x \triangleright y), t] + [z \triangleright (y \triangleright x), t] - [z \triangleright [x, y], t] \\ &\quad + [[x \triangleright y, z], t] - [[y \triangleright x, z], t] + [[[x, y], z], t], \\ \{\{\{y, z\}, t\}, x\} &= \{\{y, z\}, t\} \triangleright x - x \triangleright \{\{y, z\}, t\} + [\{\{y, z\}, t\}, x] \\ &= \{\{y, z\}, t\} \triangleright x - x \triangleright (\{y, z\} \triangleright t) + x \triangleright (t \triangleright (y \triangleright z)) - x \triangleright (t \triangleright (z \triangleright y)) \\ &\quad + x \triangleright (t \triangleright [y, z]) - x \triangleright [y \triangleright z, t] + x \triangleright [z \triangleright y, t] - x \triangleright [[y, z], t] \\ &\quad + [\{y, z\} \triangleright t, x] - [t \triangleright (y \triangleright z), x] + [t \triangleright (z \triangleright y), x] - [t \triangleright [y, z], x] \\ &\quad + [[y \triangleright z, t], x] - [[z \triangleright y, t], x] + [[[y, z], t], x], \\ \{\{\{z, t\}, x\}, y\} &= \{\{z, t\}, x\} \triangleright y - y \triangleright \{\{z, t\}, x\} + [\{\{z, t\}, x\}, y] \\ &= \{\{z, t\}, x\} \triangleright y - y \triangleright (\{z, t\} \triangleright x) + y \triangleright (x \triangleright (z \triangleright t)) - y \triangleright (x \triangleright (t \triangleright z)) \\ &\quad + y \triangleright (x \triangleright [z, t]) - y \triangleright [z \triangleright t, x] + y \triangleright [t \triangleright z, x] - y \triangleright [[z, t], x] \\ &\quad + [\{z, t\} \triangleright x, y] - [x \triangleright (z \triangleright t), y] + [x \triangleright (t \triangleright z), y] - [x \triangleright [z, t], y] \\ &\quad + [[z \triangleright t, x], y] - [[t \triangleright z, x], y] + [[[z, t], x], y], \\ \{\{\{t, x\}, y\}, z\} &= \{\{t, x\}, y\} \triangleright z - z \triangleright \{\{t, x\}, y\} + [\{\{t, x\}, y\}, z] \\ &= \{\{t, x\}, y\} \triangleright z - z \triangleright (\{t, x\} \triangleright y) + z \triangleright (y \triangleright (t \triangleright x)) - z \triangleright (y \triangleright (x \triangleright t)) \\ &\quad + z \triangleright (y \triangleright [t, x]) - z \triangleright [t \triangleright x, y] + z \triangleright [x \triangleright t, y] - z \triangleright [[t, x], y] \\ &\quad + [\{t, x\} \triangleright y, z] - [y \triangleright (t \triangleright x), z] + [y \triangleright (x \triangleright t), z] - [y \triangleright [t, x], z] \\ &\quad + [[t \triangleright x, y], z] - [[x \triangleright t, y], z] + [[[t, x], y], z]. \end{aligned}$$

By the identity of Malcev algebra and (4.9)-(4.12), we have

$$\{\{x, z\}, \{y, t\}\} - \{\{\{x, y\}, z\}, t\} - \{\{\{y, z\}, t\}, x\} - \{\{\{z, t\}, x\}, y\} - \{\{\{t, x\}, y\}, z\} = 0. \quad \square$$

**Remark 4.2.** Let  $(A, [\cdot, \cdot], \triangleright)$  be a post-Malcev algebra. If  $\triangleright$  is commutative,  $x \triangleright y = y \triangleright x$ , then the two Malcev brackets  $[\cdot, \cdot]$  and  $\{\cdot, \cdot\}$  coincide.

**Corollary 4.3.** *If  $(A, [\cdot, \cdot], \triangleright)$  be a post-Malcev algebra, then  $(A, \circ)$  is an admissible Malcev algebra, with the product  $\circ$  defined for all  $x, y \in A$  by*

$$x \circ y = x \triangleright y + \frac{1}{2}[x, y]. \quad (4.14)$$

**Proposition 4.7.** *Let  $(A, [\cdot, \cdot], \triangleright)$  be a post-Malcev algebra. Define  $L_{\triangleright} : A \rightarrow A$  by  $L_{\triangleright}(x)y = x \triangleright y$  for any  $x, y \in A$ . Then  $(A; [\cdot, \cdot], L_{\triangleright})$  is an  $A$ -module Malcev algebra of  $(A^C, \{\cdot, \cdot\})$ .*

**Proof.** By (4.12),  $L_{\triangleright}$  is a representation of  $(A^C, \{\cdot, \cdot\})$ . Indeed, for  $x, y, z, t \in A$ ,  

$$\begin{aligned} L_{\triangleright}(\{\{x, y\}, z\})t &= \{\{x, y\}, z\} \triangleright t \\ &= x \triangleright (y \triangleright (z \triangleright t)) - z \triangleright (x \triangleright (y \triangleright t)) - y \triangleright (\{x, z\} \triangleright t) - \{y, z\} \triangleright (x \triangleright t) \\ &= L_{\triangleright}(x)L_{\triangleright}(y)L_{\triangleright}(z)t - L_{\triangleright}(z)L_{\triangleright}(x)L_{\triangleright}(y)t - L_{\triangleright}(y)L_{\triangleright}(\{x, z\})t \\ &\quad - L_{\triangleright}(\{y, z\})L_{\triangleright}(x)t. \end{aligned}$$

To prove (4.1), according to (4.9) we compute

$$\begin{aligned} L_{\triangleright}(\{x, z\})[y, t] &= \{x, z\} \triangleright [y, t] = x \triangleright [z \triangleright y, t] - [z \triangleright (x \triangleright y), t] - [x \triangleright (z \triangleright t), y] + z \triangleright [x \triangleright t, y] \\ &= L_{\triangleright}(x)[L_{\triangleright}(z)y, t] - [L_{\triangleright}(z)L_{\triangleright}(x)y, t] - [L_{\triangleright}(x)L_{\triangleright}(z)t, y] + L_{\triangleright}(z)[L_{\triangleright}(x)t, y]. \end{aligned}$$

Similarly, by (4.10) and (4.11), we have

$$\begin{aligned} [L_{\triangleright}(x)z, L_{\triangleright}(y)t] &= [x \triangleright z, y \triangleright t] = [\{x, y\} \triangleright z, t] - x \triangleright [y \triangleright z, t] + y \triangleright (x \triangleright [z, t]) + [y \triangleright (x \triangleright t), z] \\ &= [L_{\triangleright}(\{x, y\})z, t] - L_{\triangleright}(x)[L_{\triangleright}(y)z, t] + L_{\triangleright}(y)L_{\triangleright}(x)[z, t] + [L_{\triangleright}(y)L_{\triangleright}(x)t, z], \\ [L_{\triangleright}(x)z, [y, t]] &= [x \triangleright z, [y, t]] = [[x \triangleright y, z], t] - x \triangleright [[y, z], t] - [x \triangleright [z, t], y] - [[x \triangleright t, y], z] \\ &= [[L_{\triangleright}(x)y, z], t] - L_{\triangleright}(x)[[y, z], t] - [L_{\triangleright}(x)[z, t], y] - [[L_{\triangleright}(x)t, y], z]. \end{aligned}$$

Therefore  $(A; [\cdot, \cdot], L_{\triangleright})$  is an  $A$ -module Malcev algebra of  $(A^C, \{\cdot, \cdot\})$ . □

**Proposition 4.8.** *If  $(A, [\cdot, \cdot], \triangleright)$  is a post-Malcev algebra, then  $(A, -[\cdot, \cdot], \blacktriangleright)$  is also a post-Malcev algebra, where for all  $x, y \in A$ ,*

$$x \blacktriangleright y = x \triangleright y + [x, y]. \tag{4.15}$$

Moreover,  $(A, [\cdot, \cdot], \triangleright)$  and  $(A, -[\cdot, \cdot], \blacktriangleright)$  have the same sub-adjacent Malcev algebra  $A^C$ .

**Proof.** We check only that  $(A, -[\cdot, \cdot], \blacktriangleright)$  verifies the first post-Malcev identity. The other identities can be verified similarly. In fact, for all  $x, y, z, t \in A$ ,

$$\begin{aligned} & -\{x, z\} \blacktriangleright [y, t] + x \blacktriangleright [z \blacktriangleright y, t] - [z \blacktriangleright (x \blacktriangleright y), t] - [x \blacktriangleright (z \blacktriangleright t), y] + z \blacktriangleright [x \blacktriangleright t, y] \\ &= -\{x, z\} \triangleright [y, t] - [\{x, z\}, [y, t]] + x \triangleright [z \triangleright y, t] + x \triangleright [[z, y], t] + [x, [z \triangleright y, t]] \\ &\quad + [x, [[z, y], t]] - [z \triangleright (x \triangleright y), t] - [z \triangleright [x, y], t] - [[z, x \triangleright y], t] - [[z, [x, y]], t] \\ &\quad - [x \triangleright (z \triangleright t), y] - [x \triangleright [z, t], y] - [[x, z \triangleright t], y] - [[x, [z, t]], y] + z \triangleright [x \triangleright t, y] \\ &\quad + z \triangleright [[x, t], y] + [z, [x \triangleright t, y]] + [z, [[x, t], y]] = 0. \end{aligned} \tag{□}$$

**Theorem 4.1.** *If  $(A, [\cdot, \cdot], \triangleright)$  is a post-Malcev algebra, then  $(A \times A, \cdot, \cdot)$  is a Malcev algebra, with the double bracket product  $\cdot, \cdot$  on  $A \times A$  defined for all  $a, b, x, y \in A$  by*

$$(a, x), (b, y) = (a \triangleright b - b \triangleright a + [a, b], a \triangleright y - b \triangleright x + [x, y]). \tag{4.16}$$

**Proof.** Let  $x, y, z, t, a, b, c, d \in A$ . It is obvious that  $(a, x), (b, y) = -(b, y), (a, x)$ . On the other hand,

$$\begin{aligned} & (a, x), (c, z), (b, y), (d, t) = \\ & \{\{a, c\}, \{b, d\}\}, (a \triangleright c) \triangleright (b \triangleright t) - (a \triangleright c) \triangleright (d \triangleright y) - (c \triangleright a) \triangleright (b \triangleright t) \\ & + (c \triangleright a) \triangleright (d \triangleright y) + [a, c] \triangleright (b \triangleright t) - [a, c] \triangleright (d \triangleright y) + \{a, c\} \triangleright [y, t] \\ & - (b \triangleright d) \triangleright (a \triangleright z) + (b \triangleright d) \triangleright (c \triangleright x) + (d \triangleright b) \triangleright (a \triangleright z) - (d \triangleright b) \triangleright (c \triangleright x) \end{aligned}$$

$$\begin{aligned}
& - [b, d] \triangleright (a \triangleright z) + [b, d] \triangleright (c \triangleright x) - \{b, d\} \triangleright [x, z] + [a \triangleright z, b \triangleright t] \\
& - [a \triangleright z, d \triangleright y] - [c \triangleright x, b \triangleright t] + [c \triangleright x, d \triangleright y] - [a \triangleright z, [y, t]] + [c \triangleright x, [y, t]] \\
& + [[x, z], b \triangleright t] - [[x, z], d \triangleright y] - [[x, z], [y, t]], \\
(a, x), (b, y), (c, z), (d, t) = \\
& \{\{ \{a, b\}, c\}, d\}, ((a \triangleright b) \triangleright c) \triangleright t - ((b \triangleright a) \triangleright c) \triangleright t - (c \triangleright (a \triangleright b)) \triangleright t \\
& + (c \triangleright (b \triangleright a)) \triangleright t + [a \triangleright b, c] \triangleright t - [b \triangleright a, c] \triangleright t + \{[a, b], c\} \triangleright t \\
& - d \triangleright ((a \triangleright b) \triangleright z) + d \triangleright ((b \triangleright a) \triangleright z) - d \triangleright ([a, b] \triangleright z) + d \triangleright (c \triangleright (a \triangleright y)) \\
& - d \triangleright (c \triangleright (b \triangleright x)) + d \triangleright (c \triangleright [x, y]) - d \triangleright [a \triangleright y, z] + d \triangleright [b \triangleright x, z] - d \triangleright [[x, y], z] \\
& + [\{a, b\} \triangleright z, t] - [c \triangleright (a \triangleright y), t] + [c \triangleright (b \triangleright x), t] - [c \triangleright [x, y], t] \\
& + [[a \triangleright y, z], t] - [[b \triangleright x, z], t] + [[[x, y], z], t], \\
(b, y), (c, z), (d, t), (a, x) = \\
& \{\{ \{b, c\}, d\}, a\}, ((b \triangleright c) \triangleright d) \triangleright x - ((c \triangleright b) \triangleright d) \triangleright x - (d \triangleright (b \triangleright c)) \triangleright x \\
& + (d \triangleright (c \triangleright b)) \triangleright x + [b \triangleright c, d] \triangleright x - [c \triangleright b, d] \triangleright x + \{[b, c], d\} \triangleright x \\
& - a \triangleright ((b \triangleright c) \triangleright t) + a \triangleright ((c \triangleright b) \triangleright t) - a \triangleright ([b, c] \triangleright t) + a \triangleright (d \triangleright (b \triangleright z)) \\
& - a \triangleright (d \triangleright (c \triangleright y)) + a \triangleright (d \triangleright [y, z]) - a \triangleright [b \triangleright z, t] + a \triangleright [c \triangleright y, t] - a \triangleright [[y, z], t] \\
& + [\{b, c\} \triangleright t, x] - [d \triangleright (b \triangleright z), x] + [d \triangleright (c \triangleright y), x] - [d \triangleright [y, z], x] \\
& + [[b \triangleright z, t], x] - [[c \triangleright y, t], x] + [[[y, z], t], x], \\
(c, z), (d, t), (a, x), (b, y) = \\
& \{\{ \{c, d\}, a\}, b\}, ((c \triangleright d) \triangleright a) \triangleright y - ((d \triangleright c) \triangleright a) \triangleright y - (a \triangleright (c \triangleright d)) \triangleright y \\
& + (a \triangleright (d \triangleright c)) \triangleright y + [c \triangleright d, a] \triangleright y - [d \triangleright c, a] \triangleright y + \{[c, d], a\} \triangleright y \\
& - b \triangleright ((c \triangleright d) \triangleright x) + b \triangleright ((d \triangleright c) \triangleright x) - b \triangleright ([c, d] \triangleright x) + b \triangleright (a \triangleright (c \triangleright t)) \\
& - b \triangleright (a \triangleright (d \triangleright z)) + b \triangleright (a \triangleright [z, t]) - b \triangleright [c \triangleright t, x] + b \triangleright [d \triangleright z, x] - b \triangleright [[z, t], x] \\
& + [\{c, d\} \triangleright x, y] - [a \triangleright (c \triangleright t), y] + [a \triangleright (d \triangleright z), y] - [a \triangleright [z, t], y] \\
& + [[c \triangleright t, x], y] - [[d \triangleright z, x], y] + [[[z, t], x], y], \\
(d, t), (a, x), (b, y), (c, z) = \\
& \{\{ \{d, a\}, b\}, c\}, ((d \triangleright a) \triangleright b) \triangleright z - ((a \triangleright d) \triangleright b) \triangleright z - (b \triangleright (d \triangleright a)) \triangleright z \\
& + (b \triangleright (a \triangleright d)) \triangleright z + [d \triangleright a, b] \triangleright z - [a \triangleright d, b] \triangleright z + \{[d, a], b\} \triangleright z \\
& - c \triangleright ((d \triangleright a) \triangleright y) + c \triangleright ((a \triangleright d) \triangleright y) - c \triangleright ([d, a] \triangleright y) + c \triangleright (b \triangleright (d \triangleright x)) \\
& - c \triangleright (b \triangleright (a \triangleright t)) + c \triangleright (b \triangleright [t, x]) - c \triangleright [d \triangleright x, y] + c \triangleright [a \triangleright t, y] - c \triangleright [[t, x], y] \\
& + [\{d, a\} \triangleright y, z] - [y \triangleright (d \triangleright x), z] + [y \triangleright (a \triangleright t), z] - [y \triangleright [t, x], z] \\
& + [[d \triangleright x, y], z] - [[a \triangleright t, y], z] + [[[t, x], y], z].
\end{aligned}$$

Hence, using (4.13) of Proposition 4.6 and Definition 4.3, we have

$$\begin{aligned}
& (a, x), (c, z), (b, y), (d, t) - (a, x), (b, y), (c, z), (d, t) \\
& - (b, y), (c, z), (d, t), (a, x) - (c, z), (d, t), (a, x), (b, y) \\
& - (d, t), (a, x), (b, y), (c, z) = (0, 0).
\end{aligned}$$

□

The following results illustrate that a  $\lambda$ -weighted  $\mathcal{O}$ -operator induces a post-Malcev algebra structure.

**Theorem 4.2.** *Let  $(A, [\cdot, \cdot]_A)$  be a Malcev algebra and  $(V; [\cdot, \cdot]_V, \rho)$  an  $A$ -module Malcev algebra. Let  $T : V \rightarrow A$  be a  $\lambda$ -weighted  $\mathcal{O}$ -operator associated to  $(V; [\cdot, \cdot]_V, \rho)$ .*



(i) Define two new bilinear operations  $[\cdot, \cdot], \triangleright : V \times V \rightarrow V$  as follows, for all  $a, b \in V$ ,

$$[a, b] = \lambda[a, b]_V, \quad a \triangleright b = \rho(T(a))b. \quad (4.17)$$

Then  $(V, [\cdot, \cdot], \triangleright)$  is a post-Malcev algebra.

(ii)  $T$  is a Malcev algebra homomorphism from the sub-adjacent Malcev algebra  $(V, \{\cdot, \cdot\})$  given in Proposition 4.6 to  $(A, [\cdot, \cdot]_A)$ .

**Proof.** (i) We use (4.1)-(4.3) of representation of Malcev algebras on  $\mathbb{K}$ -algebra.

$$\begin{aligned} & \{a, c\} \triangleright [b, d] - a \triangleright [c \triangleright b, d] + [c \triangleright (a \triangleright b), d] + [a \triangleright (c \triangleright d), b] - c \triangleright [a \triangleright d, b] \\ &= (\rho(T(a))c - \rho(T(c))a + \lambda[a, c]_V) \triangleright \lambda[b, d]_V - \rho(T(a))[\rho(T(c))b, d] \\ & \quad + [\rho(T(c))\rho(T(a))b, d] + [\rho(T(a))\rho(T(c))d, b] - \rho(T(c))[\rho(T(a))d, b] \\ &= \lambda \left( \rho(T(\rho(T(a))c) - T(\rho(T(c))a) + T(\lambda[a, c]_V)) [b, d]_V - \rho(T(a))[\rho(T(c))b, d]_V \right. \\ & \quad \left. + [\rho(T(c))\rho(T(a))b, d]_V + [\rho(T(a))\rho(T(c))d, b]_V - \rho(T(c))[\rho(T(a))d, b]_V \right) = 0, \end{aligned}$$

$$\begin{aligned} & [a \triangleright c, b \triangleright d] - [\{a, b\} \triangleright c, d] + a \triangleright [b \triangleright c, d] - b \triangleright (a \triangleright [c, d]) - [b \triangleright (a \triangleright d), c] \\ &= [\rho(T(a))c, \rho(T(b))d] - \lambda[(\rho(T(a))b - \rho(T(b))a + \lambda[a, b]_V) \triangleright c, d]_V \\ & \quad + \rho(T(a))[\rho(T(b))c, d] - \rho(T(b))\rho(T(a))[c, d] - [\rho(T(b))\rho(T(a))d, c] \\ &= \lambda \left( [\rho(T(a))c, \rho(T(b))d]_V - [\rho(T(\rho(T(a))b) - T(\rho(T(b))a) + T(\lambda[a, b]_V))c, d]_V \right. \\ & \quad \left. + \rho(T(a))[\rho(T(b))c, d]_V - \rho(T(b))\rho(T(a))[c, d]_V - [\rho(T(b))\rho(T(a))d, c]_V \right) = 0, \end{aligned}$$

$$\begin{aligned} & [a \triangleright c, [b, d]] - [[a \triangleright b, c], d] + a \triangleright [[b, c], d] + [a \triangleright [c, d], b] + [[a \triangleright d, b], c] \\ &= [\rho(T(a))c, [b, d]] - [[\rho(T(a))b, c], d] + \rho(T(a))[[b, c], d] \\ & \quad + [\rho(T(a))[c, d], b] + [[\rho(T(a))d, b], c] \\ &= \lambda^2 \left( [\rho(T(a))c, [b, d]_V]_V - [[\rho(T(a))b, c]_V, d]_V + \rho(T(a))[[b, c]_V, d]_V \right. \\ & \quad \left. + [\rho(T(a))[c, d]_V, b]_V + [[\rho(T(a))d, b]_V, c]_V \right) = 0. \end{aligned}$$

Using the condition (2.1) of Definition 2.1, we check

$$\begin{aligned} & \{\{a, b\}, c\} \triangleright d - a \triangleright (b \triangleright (c \triangleright d)) + c \triangleright (a \triangleright (b \triangleright d)) + b \triangleright (\{a, c\} \triangleright d) + \{b, c\} \triangleright (a \triangleright d) \\ &= \rho(T(\rho(T(\rho(T(a))b))c) - T(\rho(T(\rho(T(b))a))c) - T(\rho(T(c))\rho(T(a))b) \\ & \quad + T(\rho(T(c))\rho(T(b))a) + T(\rho(T(\lambda[a, b]_V))c) - T(\rho(T(c))\lambda[a, b]_V) + T(\lambda[\rho(T(a))b, c]_V) \\ & \quad - T(\lambda[\rho(T(b))a, c]_V) + T(\lambda^2[[a, b]_V, c]_V))d - \rho(T(a))\rho(T(b))\rho(T(c))d \\ & \quad + \rho(T(c))\rho(T(a))\rho(T(b))d + \rho(T(b))\rho(T(\rho(T(a))c) - T(\rho(T(c))a) + T(\lambda[a, c]_V))d \\ & \quad + \rho(T(\rho(T(b))c) - T(\rho(T(c))b) + T(\lambda[b, c]_V))\rho(T(a))d = 0. \end{aligned}$$

(ii) The Malcev bracket  $\{\cdot, \cdot\}$  is defined for all  $a, b \in V$  by

$$\{a, b\} = a \triangleright b - b \triangleright a + [a, b] = \rho(T(a))b - \rho(T(b))a + \lambda[a, b]_V.$$

Then the sub-adjacent Malcev algebra of the above post-Malcev algebra  $(V, [\cdot, \cdot], \triangleright)$  is exactly the Malcev algebra  $(V, [\cdot, \cdot]_T)$  given in Corollary 4.1 Then the result follows.  $\square$

**Proposition 4.9.** Let  $T, T' : (V, [\cdot, \cdot]_V) \rightarrow (A, [\cdot, \cdot]_A)$  be two  $\lambda$ -weighted  $\mathcal{O}$ -operators with respect to an  $A$ -module Malcev algebra  $(V; [\cdot, \cdot]_V, \rho)$ . Let  $(V, \{\cdot, \cdot\}, \triangleright)$  and  $(V, \{\cdot, \cdot\}', \triangleright')$  be the post-Malcev algebras given in Theorem 4.2 and  $(\phi, \psi)$  be a homomorphism from  $T'$  to  $T$ . Then  $\psi$  is a homomorphism from the post-Malcev algebra  $(V, \{\cdot, \cdot\}, \triangleright)$  to the post-Malcev algebra  $(V, \{\cdot, \cdot\}', \triangleright')$ .

**Proof.** For all  $a, b \in V$ , by (4.7),(4.8) and (4.17), we have

$$\begin{aligned} \psi(\{a, b\}) &= \psi(\lambda[a, b]_V) = \lambda[\psi(a), \psi(b)]_V = \{\psi(a), \psi(b)\}', \\ \psi(a \triangleright b) &= \psi(\rho(T(a))b) = \rho(\phi(T(a)))(\psi(b)) = \rho(T'(\psi(a)))(\psi(b)) = \psi(a) \triangleright' \psi(b), \end{aligned}$$

which implies that  $\psi$  is a homomorphism between the post-Malcev algebras in Theorem 4.2. □

Given a Malcev algebra, the following result gives a necessary and sufficient condition to have a compatible post-Malcev algebra structure.

**Proposition 4.10.** *Let  $(A, [\cdot, \cdot])$  be a Malcev algebra. Then there exists a compatible post-Malcev algebra structure on  $A$  if and only if there exists an  $A$ -module Malcev algebra  $(V; [\cdot, \cdot]_V, \rho)$  and an invertible 1-weighted  $\mathcal{O}$ -operator  $T : V \rightarrow A$ .*

**Proof.** Let  $(A, [\cdot, \cdot], \triangleright)$  be a post-Malcev algebra and  $(A, [\cdot, \cdot])$  be the associated Malcev algebra. Then the identity map  $id : A \rightarrow A$  is an invertible 1-weighted  $\mathcal{O}$ -operator on  $(A, [\cdot, \cdot])$  associated to  $(A, [\cdot, \cdot], ad)$ .

Conversely, suppose that there exists an invertible 1-weighted  $\mathcal{O}$ -operator of  $(A, [\cdot, \cdot])$  associated to an  $A$ -module Malcev algebra  $(V; [\cdot, \cdot]_V, \rho)$ . Then, using Theorem 4.2, there is a post-Malcev algebra structure on  $T(V) = A$  given by

$$\{x, y\} = \lambda T([T^{-1}(x), T^{-1}(y)]_V), \quad x \triangleright y = T(\rho(x)T^{-1}(y)).$$

This is compatible post-Malcev algebra structure on  $(A, [\cdot, \cdot])$ . Indeed,

$$\begin{aligned} x \triangleright y - y \triangleright x + \{x, y\} &= T(\rho(x)T^{-1}(y) - \rho(y)T^{-1}(x) + [T^{-1}(x), T^{-1}(y)]_V) \\ &= [TT^{-1}(x), TT^{-1}(y)] = [x, y]. \end{aligned} \quad \square$$

An obvious consequence of Theorem 4.2 is the following construction of a post-Malcev algebra in terms of  $\lambda$ -weighted Rota-Baxter operator on a Malcev algebra.

**Corollary 4.4.** *Let  $(A, [\cdot, \cdot])$  be a Malcev algebra and the linear map  $\mathcal{R} : A \rightarrow A$  is a  $\lambda$ -weighted Rota-Baxter operator. Then, there exists a post-Malcev structure on  $A$  given, for all  $x, y \in A$ , by*

$$\{x, y\} = \lambda[x, y], \quad x \triangleright y = [\mathcal{R}(x), y].$$

*If in addition,  $\mathcal{R}$  is invertible, then there is a compatible post-Malcev algebra structure on  $A$  given, for all  $x, y \in A$ , by*

$$\{x, y\} = \mathcal{R}([\mathcal{R}^{-1}(x), \mathcal{R}^{-1}(y)]), \quad x \triangleright y = \mathcal{R}([x, \mathcal{R}^{-1}(y)]).$$

**Example 4.4.** In this example, we calculate  $(-1)$ -weighted Rota-Baxter operators on the Malcev algebra  $A$  and we give the corresponding post-Malcev algebras. Let  $A$  be the simple Malcev algebra over the field of complex numbers  $\mathbb{C}$  [11, Example 3]. In this case  $A$  has a basis  $\{e_1, e_2, e_3, e_4, e_5, e_6, e_7\}$  with the following table of multiplication:

$[\cdot, \cdot]$	$e_1$	$e_2$	$e_3$	$e_4$	$e_5$	$e_6$	$e_7$
$e_1$	0	$2e_2$	$-2e_3$	$2e_4$	$-2e_5$	$2e_6$	$-2e_7$
$e_2$	$-2e_2$	0	$e_1$	$2e_7$	0	$-2e_5$	0
$e_3$	$2e_3$	$-e_1$	0	0	$-2e_6$	0	$2e_4$
$e_4$	$-2e_4$	$-2e_7$	0	0	$e_1$	$2e_3$	0
$e_5$	$2e_5$	0	$2e_6$	$-e_1$	0	0	$-2e_2$
$e_6$	$-2e_6$	$2e_5$	0	$-2e_3$	0	0	$e_1$
$e_7$	$2e_7$	0	$-2e_4$	0	$2e_2$	$-e_1$	0

Now, define the linear map  $\mathcal{R} : A \rightarrow A$  by

$$\mathcal{R}(e_1) = \frac{1}{2}e_1 + 2\alpha e_2 + 2\beta e_5 + 2\gamma e_6, \quad \mathcal{R}(e_2) = 0, \quad \mathcal{R}(e_3) = e_3 - \alpha e_1 + \delta e_5 - 2\beta e_6,$$

$$\mathcal{R}(e_4) = e_4 - \beta e_1 - \delta e_2 + \mu e_6, \quad \mathcal{R}(e_5) = \mathcal{R}(e_6) = 0, \quad \mathcal{R}(e_7) = e_7 - \gamma e_1 + 2\beta e_2 - \mu e_5.$$

Then  $\mathcal{R}$  is a  $(-1)$ -weighted Rota-Baxter operator on  $A$ . Using Corollary 4.4, we can construct a post-Malcev algebra on  $A$  given by

$\{\cdot, \cdot\}$	$e_1$	$e_2$	$e_3$	$e_4$	$e_5$	$e_6$	$e_7$
$e_1$	0	$2\lambda e_2$	$-2\lambda e_3$	$2\lambda e_4$	$-2\lambda e_5$	$2\lambda e_6$	$-2\lambda e_7$
$e_2$	$-2\lambda e_2$	0	$\lambda e_1$	$2\lambda e_7$	0	$-2\lambda e_5$	0
$e_3$	$2\lambda e_3$	$-\lambda e_1$	0	0	$-2\lambda e_6$	0	$2\lambda e_4$
$e_4$	$-2\lambda e_4$	$-2\lambda e_7$	0	0	$\lambda e_1$	$2\lambda e_3$	0
$e_5$	$2\lambda e_5$	0	$2\lambda e_6$	$-\lambda e_1$	0	0	$-2\lambda e_2$
$e_6$	$-2\lambda e_6$	$2\lambda e_5$	0	$-2\lambda e_3$	0	0	$\lambda e_1$
$e_7$	$2\lambda e_7$	0	$-2\lambda e_4$	0	$2\lambda e_2$	$-\lambda e_1$	0

$\triangleright$	$e_1$	$e_2$	$e_3$	$e_4$	$e_5$	$e_6$	$e_7$
$e_1$	$4\beta e_5 - 4\alpha e_2 - 4\gamma e_6$	$e_2 + 4\gamma e_5$	$2\alpha e_1 - e_3 + 4\beta e_6$	$e_4 + 4\alpha e_7 - 2\beta e_1 - 4\gamma e_3$	$-e_5$	$e_6 - 4\alpha e_5$	$2\gamma e_1 - e_7 - 4\beta e_2$
$e_2$	0	0	0	0	0	0	0
$e_3$	$2e_3 + 2\delta e_5 + 4\beta e_6$	$-e_1 - 2\alpha e_2 - 4\beta e_5$	$2\alpha e_3 + 2\delta e_6$	$4\beta e_3 - 2\alpha e_4 - \delta e_1$	$2\alpha e_5 - 2e_6$	$-2\alpha e_6$	$2e_4 + 2\alpha e_7 - 2\delta e_2 - 2\beta e_1$
$e_4$	$2\delta e_2 - 2e_4 - 2\mu e_6$	$2\mu e_5 - 2e_7 - 2\beta e_2$	$2\beta e_3 - \delta e_1$	$-2\beta e_4 - 2\delta e_7 - 2\mu e_3$	$e_1 + 2\beta e_5$	$2e_3 + 2\delta e_5 - 2\beta e_6$	$2\beta e_7 + \mu e_1$
$e_5$	0	0	0	0	0	0	0
$e_6$	0	0	0	0	0	0	0
$e_7$	$2e_7 - 4\beta e_2 - 2\mu e_5$	$-2\gamma e_2$	$2\beta e_1 + 2\gamma e_3 - 2e_4 - 2\mu e_6$	$\mu e_1 - 2\gamma e_4 + 4\beta e_7$	$2e_2 + 2\gamma e_5$	$-e_1 - 2\gamma e_6 - 4\beta e_5$	$2\gamma e_7 + 2\mu e_2$

The following result establishes a close relation between a post-alternative algebra and a post-Malcev algebra.

**Theorem 4.3.** *Let  $T : V \rightarrow A$  be a  $\lambda$ -weighted  $\mathcal{O}$ -operator of alternative algebra  $(A, \cdot)$  with respect to  $(V, \cdot_V, \mathfrak{l}, \mathfrak{r})$  and  $(V, \circ, \prec, \succ)$  be the associated post-alternative algebra given in Theorem 3.2. Then  $T$  is a  $\lambda$ -weighted  $\mathcal{O}$ -operator on the Malcev admissible algebra  $(A, [\cdot, \cdot])$  with respect to an  $A$ -module Malcev algebra  $(V; [\cdot, \cdot]_V, \mathfrak{l} - \mathfrak{r})$ .*

Moreover, if  $(V, \{\cdot, \cdot\}, \triangleright)$  be a post-Malcev algebra associated to the Malcev admissible algebra  $(A, [\cdot, \cdot])$  on  $(V; [\cdot, \cdot]_V, \mathfrak{l} - \mathfrak{r})$ . Then, the products  $(\{\cdot, \cdot\}, \triangleright)$  are related with  $(\circ, \prec, \succ)$  as follow, for all  $a, b \in V$ ,

$$\{a, b\} = a \circ b - b \circ a, \quad a \triangleright b = a \succ b - b \prec a. \tag{4.18}$$

**Proof.** Using the condition of  $\lambda$ -weighted  $\mathcal{O}$ -operator in (3.28) and Proposition 4.2, for  $a, b \in A$ ,

$$\begin{aligned} & [T(a), T(b)] - T(\rho(T(a))b - \rho(T(b))a + \lambda[a, b]_V) \\ &= T(a) \cdot T(b) - T(b) \cdot T(a) - T((\mathfrak{l} - \mathfrak{r})(T(a))b - (\mathfrak{l} - \mathfrak{r})(T(b))a + \lambda(a \cdot_V b - b \cdot_V a)) = 0. \end{aligned}$$

Then  $T$  is a  $\lambda$ -weighted  $\mathcal{O}$ -operator on the Malcev admissible algebra  $(A, [\cdot, \cdot])$  with respect to an  $A$ -module Malcev algebra  $(V; [\cdot, \cdot]_V, \mathfrak{l} - \mathfrak{r})$ .

On the other hand, from (3.30) of Theorem 3.2 and (4.17) of Theorem 4.2 that

$$\begin{aligned} \{a, b\} &= \lambda[a, b]_V = \lambda a \cdot_V b - \lambda b \cdot_V a = a \circ b - b \circ a, \\ a \triangleright b &= (\mathfrak{l} - \mathfrak{r})(T(a))b = \mathfrak{l}(T(a))b - \mathfrak{r}(T(a))b = a \succ b - b \prec a. \quad \square \end{aligned}$$

**Corollary 4.5.** *Let  $(A, \circ, \prec, \succ)$  be a post-alternative algebra given in Corollary 3.1,  $(A, \{\cdot, \cdot\}, \triangleright)$  be a post-Malcev algebra associated to the Malcev algebras  $(A, [\cdot, \cdot])$  and let  $\mathcal{R}$*

be a  $\lambda$ -weighted Rota-Baxter operator of  $(A, \cdot)$ . Then, the operations

$$\{x, y\} = x \circ y - y \circ x, \quad x \triangleright y = x \succ y - y \prec x, \tag{4.19}$$

define a post-Malcev structure in  $A$ .

It is easy to see that (4.13) and (4.19) fit into the commutative diagram

$$\begin{array}{ccc}
 \text{Post-alternative alg.} & \xrightarrow{x \prec y + x \succ y + x \cdot y} & \text{alternative alg.} \\
 \downarrow \{x, y\} = x \circ y - y \circ x \quad x \triangleright y = x \succ y - y \prec x & & \downarrow x \star y - y \star x \\
 \text{post-Malcev alg.} & \xrightarrow{x \triangleright y - y \triangleright x + [x, y]} & \text{Malcev alg.}
 \end{array} \tag{4.20}$$

When the operation  $\cdot$  of the post-alternative algebra and the bracket  $[\cdot, \cdot]$  of the post-Malcev algebra are both trivial, we obtain the following commutative diagram.

$$\begin{array}{ccc}
 \text{Pre-alternative alg.} & \xrightarrow{x \prec y + x \succ y} & \text{Alternative alg.} \\
 \downarrow x \succ y - y \prec x & & \downarrow x \star y - y \star x \\
 \text{Pre-Malcev alg.} & \xrightarrow{x \triangleright y - y \triangleright x} & \text{Malcev alg.}
 \end{array}$$

**Acknowledgment.** The authors would like to thank the referee for valuable comments and suggestions on this article.

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