



Certain Curvature Conditions on (k, μ) -Paracontact Metric Spaces

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Abstract

The aim of this paper is to classify (k, μ) -paracontact metric spaces satisfying certain curvature conditions. We present the curvature tensors of (k, μ) -Paracontact manifold satisfying the conditions $R \cdot W_6 = 0$, $R \cdot W_7 = 0$, $R \cdot W_8 = 0$ and $R \cdot W_9 = 0$. According these cases, (k, μ) -Paracontact manifolds have been characterized. Also, several results are obtained.

Keywords: (k, μ) -Paracontact Manifold, η -Einstein manifold, Riemannian curvature tensor **2010 AMS:** 53C15, 53C25

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1. Introduction

Paracontact manifolds are smooth manifolds of dimension (2n+1) equipped with a 1-form η , a vector field ξ and a field of endomorphisms of tangent spaces ϕ such that $\eta(\xi) = 1$, $\phi^2 = I - \eta \otimes \xi$ and ϕ induces an almost paracomplex structure by kernel of η [1]. On the other hand, if the manifold is equipped with a pseudo-Riemannian metric g of signature (n+1,n) satisfying

 $g(\phi X, \phi Y) = -g(X, Y) + \eta(X)\eta(Y), \ d\eta(X, Y) = g(X, \phi Y),$

 (M, η) becomes a contact manifold and (ϕ, ξ, η, g) is said to be a paracontact metric structure on *M*. In 1985, Kaneyuki and Williams initiated the perspective of paracontact geometry [5]. Zamkovoy performed a thorough study of paracontact metric Manifolds. [15]. Recently, B. Cappeletti-Montano, I. Küpeli Erken and C. Murathan introduced a new type of paracontact geometry so-called paracontact metric (k, μ) -space, where *k* and μ are constant [4].

M. M. Tripathi and P. Gupta studied T-curvature tensors in semi-Riemannian manifolds. They defined T-conservative semi-Riemannian manifolds and give necessary and sufficient tensor on a Riemannian manifolds to be T-conservative. They proved that every T-flat semi-Riemannian manifold is Einstein. They also gave the conditions for semi-Riemannian manifold to be T-flat [8]. Since then several geometers studied curvature conditions and obtain various important properties [2, 6], [9]-[13].

The object of this paper is to study properties of the some certain curvature tensor in a (k, μ) -paracontact metric manifold. In the present paper we survey $R \cdot W_6 = 0$, $R \cdot W_7 = 0$, $R \cdot W_8 = 0$ and $R \cdot W_9 = 0$, where W_6 , W_7 , W_8 and W_9 denote curvature tensors of manifold, respectively.

2. Preliminaries

An (2n+1)-dimensional manifold *M* is called to have an paracontact structure if it admits a (1,1)-tensor field ϕ , a vector field ξ and a 1-form η satisfying the following conditions [5]:

(*i*) $\phi^2 X = X - \eta(X)\xi$, for any vector field $X \in \chi(M)$, the set of all differential vector fields on M,

(*ii*) $\eta(\xi) = 1, \eta \circ \phi = 0, \phi \xi = 0.$

An almost paracontact structure is called to be normal if and only if the (1,2)-type torsion tensor $N_{\phi} = [\phi, \phi] - 2d\eta \otimes \xi$ vanishes identically, where $[\phi, \phi](X, Y) = \phi^2[X, Y] + [\phi X, \phi Y] - \phi[\phi X, Y] - \phi[X, \phi Y]$. An almost paracontact manifold equipped with a pseudo-Riemannian metric *g* so that

$$g(\phi X, \phi Y) = -g(X, Y) + \eta(X)\eta(Y), \quad g(X, \xi) = \eta(X)$$

$$(2.1)$$

for all vector fields $X, Y \in \chi(M)$ is said almost paracontact metric manifold, where signature of g is (n+1,n). An almost paracontact structure is called to be a paracontact structure if $g(X, \phi Y) = d\eta(X, Y)$ with the associated metric g [15]. We now define a (1,1) tensor field h by $h = \frac{1}{2}L_{\xi}\phi$, where L denotes the Lie derivative. Then h is symmetric and satisfies the conditions

$$h\phi = -\phi h, \quad h\xi = 0, \quad Trh = Tr.\phi h = 0. \tag{2.2}$$

If ∇ denotes the Levi-Civita connection of g, then we have the following relation

$$\nabla_X \xi = -\phi X + \phi h X \tag{2.3}$$

for any $X \in \chi(M)$ [15]. For a paracontact metric manifold $M^{2n+1}(\phi, \xi, \eta, g)$, if ξ is a killing vector field or equivalently, h = 0, then it is called a K-paracontact manifold.

An almost paracontact manifold is said to be para-Sasakian if and only if the following condition holds [15].

$$(\nabla_X \phi) Y = -g(X,Y)\xi + \eta(Y)X$$

for all $X, Y \in \chi(M)$ [15]. A normal paracontact metric manifold is para-Sasakian and satisfies

$$R(X,Y)\xi = -(\eta(Y)X - \eta(X)Y)$$
(2.4)

for all $X, Y \in \chi(M)$, but this is not a sufficient condition for a para-contact manifold to be para-Sasakian. It is clear that every para-Sasakian manifold is K-paracontact. But the converse is not always true[3].

A paracontact manifold *M* is said to be η -Einstein if its Ricci tensor *S* of type (0,2) is of the from $S(X,Y) = ag(X,Y) + b\eta(X)\eta(Y)$, where *a*, *b* are smooth functions on *M*. If *b* = 0, then the manifold is also called Einstein and if *a* = 0, then it is called special type of η -Einstein manifolds [14].

A paracontact metric manifold is said to be a (k, μ) -paracontact manifold if the curvature tensor \widetilde{R} satisfies

$$R(X,Y)\xi = k[\eta(Y)X - \eta(X)Y] + \mu[\eta(Y)hX - \eta(X)hY]$$

$$(2.5)$$

for all $X, Y \in \chi(M)$, where *k* and μ are real constants.

This class is very wide containing the para-Sasakian manifolds as well as the paracontact metric manifolds satisfying $R(X,Y)\xi = 0$ [16].

In particular, if $\mu = 0$, then the paracontact metric (k, μ) -manifold is called paracontact metric N(k)-manifold. Thus for a paracontact metric N(k)-manifold the curvature tensor satisfies the following relation

$$R(X,Y)\xi = k\eta(Y)X - k\eta(X)Y$$
(2.6)

for all $X, Y \in \chi(M)$. Though the geometric behavior of paracontact metric (k, μ) -spaces is different according as k < -1, or k > -1, but there are some common results for k < -1 and k > -1[4].

Lemma 2.1. There does not exist any paracontact (k,μ) -manifold of dimension greater than 3 with k > -1 which is Einstein whereas there exits such manifolds for k < -1 [4].

In a paracontact metric (k, μ) -manifold $M^{2n+1}(\phi, \xi, \eta, g), n > 1$, the following relation hold :

$$h^2 = (k+1)\phi^2$$
, for $k \neq -1$, (2.7)

$$(\overline{\nabla}_X \phi)Y = -g(X - hX, Y)\xi + \eta(Y)(X - hX), \tag{2.8}$$

$$S(X,Y) = [2(1-n) + n\mu]g(X,Y) + [2(n-1) + \mu]g(hX,Y) + [2(n-1) + n(2k-\mu)]\eta(X)\eta(Y),$$
(2.9)

$$S(X,\xi) = 2nk\eta(X), \tag{2.10}$$

$$QY = [2(1-n)+n\mu]Y + [2(n-1)+\mu]hY + [2(n-1)+n(2k-\mu)]\eta(Y)\xi, \qquad (2.11)$$

$$Q\xi = 2nk\xi, \tag{2.12}$$

$$Q\phi - \phi Q = 2[2(n-1) + \mu]h\phi$$
(2.13)

for any vector fields X, Y on M^{2n+1} , where Q and S denotes the Ricci operator and Ricci tensor of (M^{2n+1}, g) , respectively[4].

The concept of W_6 -curvature tensor was defined by [7]. W_6 -curvature tensor, W_7 -curvature tensor, W_8 -curvature tensor and W_9 -curvature tensor, of a (2n + 1)-dimensional Riemannian manifold are, respectively, defined as

$$W_6(X,Y)Z = R(X,Y)Z - \frac{1}{2n}[S(Y,Z)X - g(X,Y)QZ],$$
(2.14)

$$W_7(X,Y)Z = R(X,Y)Z - \frac{1}{2n}[S(Y,Z)QX - g(Y,Z)QX],$$
(2.15)

$$W_8(X,Y)Z = R(X,Y)Z - \frac{1}{2n}[S(Y,Z)X - S(X,Y)Z],$$
(2.16)

$$W_{9}(X,Y)Z = R(X,Y)Z + \frac{1}{2n}[S(X,Y)Z - g(Y,Z)QX],$$
(2.17)

for all $X, Y, Z \in \chi(M)$ where, $\chi(M)$ is set of all vector spaces [7].

3. Certain Curvature Conditions on (k, μ) -Paracontact metric spaces

We will provide the significant themes of this work in this part.

Let *M* be (2n+1)-dimensional (k, μ) -paracontact metric manifold and we explain *W*₆ curvature tensor from (2.14), we have

$$W_6(X,Y)\xi = k(g(X,Y)\xi - \eta(X)Y) + \mu(\eta(Y)hX - \eta(X)hY).$$
(3.1)

Putting $X = \xi$, in (3.1), we get

$$W_{6}(\xi, Y)\xi = k(\eta(Y)\xi - Y) - \mu hY.$$
(3.2)

In (2.15) choosing $Z = \xi$ and using (2.5), we obtain

$$W_7(X,Y)\xi = k\eta(X)Y + \frac{1}{2n}\eta(Y)QX + \mu(\eta(Y)hX - \eta(X)hY).$$
(3.3)

It follows

$$W_7(\xi, Y)\xi = k(\eta(Y)\xi - Y) - \mu hY.$$
(3.4)

In the same way, putting $Z = \xi$ in (2.16) and using (2.5), we have

$$W_8(X,Y)\xi = \frac{1}{2n}S(X,Y)\xi - k\eta(X)Y + \mu(\eta(Y)hX - \eta(X)hY).$$
(3.5)

In (2.16), choosing $X = \xi$, we get

$$W_8(\xi, Y)\xi = k(\eta(Y)\xi - Y) - \mu hY.$$
(3.6)

In (2.17), choosing $Z = \xi$, we obtain

$$W_{9}(X,Y)\xi = k(\eta(Y)X - \eta(X)Y) + \mu(\eta(Y)hX - \eta(X)hY) + \frac{1}{2n}(S(X,Y)\xi - \eta(Y)QX).$$
(3.7)

In(3.7) it follows

$$W_9(\xi, Y)\xi = k(\eta(Y)\xi - Y) - \mu hY.$$
(3.8)

In (2.5), we arrive

$$R(\xi, Y)Z = k(g(Y, Z)\xi - \eta(Z)Y) + \mu(g(hY, Z)\xi - \eta(Z)hY),$$
(3.9)

choosing $Z = \xi$, in (3.9)

$$R(\xi, Y)\xi = k(\eta(Y)\xi - Y) - \mu hY.$$
(3.10)

Theorem 3.1. Let $M^{2n+1}(\phi, \xi, \eta, g)$ be a (k, μ) -paracontact space. Then M is a W_6 semi-symmetric if and only if M is an Einstein manifold.

Proof. Suppose that M is a W_6 semi-symmetric. This implies that

$$(R(X,Y)W_6)(U,W)Z = R(X,Y)W_6(U,W)Z - W_6(R(X,Y)U,W)Z - W_6(U,R(X,Y)W)Z - W_6(U,W)R(X,Y)Z = 0,$$
(3.11)

for any $X, Y, U, W, Z \in \chi(M)$. Taking $X = Z = \xi$ in (3.11), making use of (3.1) and (3.9), for $A = \frac{1}{2n}$, we have

$$(R(\xi,Y)W_{6})(U,W)\xi = R(\xi,Y)(k(g(Y,W)\xi - \eta(U)W) + \mu(\eta(W)hU - \eta(U)hW)) - W_{6}(k(g(Y,U)\xi - \eta(U)Y) + \mu(g(hY,U)\xi - \eta(U)hY),W)\xi - \eta(U)hY),W)\xi - W_{6}(U,k(g(Y,W)\xi - \eta(W)Y) + \mu(g(hY,W)\xi - \eta(W)hY)\xi - W_{6}(U,W)(k(\eta(Y)\xi - Y) - \mu hY) = 0.$$
(3.12)

Taking into account (3.1) and (3.2) in (3.12), we have

$$kW_{6}(U,W)Y + \mu W_{6}(U,W)hY + k\mu(\eta(W)g(Y,hU)\xi$$

$$-g(Y,W)hU) + \mu^{2}(1+k)(\eta(W)g(Y,U)\xi$$

$$-\eta(U)g(Y,W)\xi) + k\mu(g(hY,U)W - g(hY,W)hU)$$

$$+\mu k(g(hY,U)hW - g(hY,W)U) + \mu^{2}(g(hY,U)hW$$

$$-g(hY,W)hU) + k^{2}(g(Y,W)\eta(U)\xi - g(Y,W)U)$$

$$+k\mu(g(Y,U)hW + g(U,W)hY) + k^{2}(g(Y,U)W$$

$$-g(U,W)Y) = 0.$$
(3.13)

Putting (2.10), (2.14), choosing $U = \xi$ and taking inner product with $\xi \in \chi(M)$ in (3.13), we arrive

$$AkS(W,Y) + A\mu S(W,hY) + k^2 g(W,Y) + k\mu g(W,hY) = 0.$$
(3.14)

Using (2.7) and replacing hY of Y in (3.14), we get

$$AkS(W,hY) + A\mu(1+k)S(W,Y) - 2nkA(1+k)g(W,hY) + k\mu(1+k)g(W,Y) = 0.$$
(3.15)

From (3.14) and (3.15), we have

S(W,Y) = 2nkg(W,Y).

So, *M* is an Einstein manifold. Conversely, let $M^{2n+1}(\varphi, \xi, \eta, g)$ be an Einstein manifold, i.e. S(W, Y) = 2nkg(W, Y), then from equations (3.15), (3.14), (3.13), (3.12) and (3.11) we obtain *M* is a *W*₆ semi-symmetric. Which verifies our assertion.

Theorem 3.2. Let $M^{2n+1}(\phi, \xi, \eta, g)$ be a (k, μ) -paracontact space. Then M is a W_7 semi-symmetric if and only if M is an η -Einstein manifold.

Proof. Assume that M is a W_7 semi-symmetric. This yields to

$$(R(X,Y)W_7)(U,W)Z = R(X,Y)W_7(U,W)Z - W_7(R(X,Y)U,W)Z - W_7(U,R(X,Y)W)Z - W_7(U,W)R(X,Y)Z = 0,$$
(3.16)

for any $X, Y, U, W, Z \in \chi(M)$. Taking $X = Z = \xi$ in (3.16) and using (3.3), (3.9), (3.10), for $A = -\frac{1}{2n}$, we obtain

$$(R(\xi, Y)W_{7})(U, W)\xi = R(\xi, Y)(k\eta(U)W - A\eta(W)QU + \mu(\eta(W)hU - \eta(U)hW)) - W_{7}(k(g(Y, U)\xi - \eta(U)Y) + \mu(g(hY, U)\xi - \eta(U)hY), W)\xi - \eta(U)hY), W)\xi - W_{7}(U, kg(Y, W)\xi - \eta(W)Y) + \mu(g(hY, W)\xi - \eta(W)hY)\xi - W_{7}(U, W)k(\eta(Y)\xi - Y) - \mu hY) = 0.$$
(3.17)

Taking into account that (3.4) and (3.9) in (3.17), we get

$$kW_{7}(U,W)Y + \mu W_{7}(U,W)hY + k\mu(\eta(U)g(hY,W)\xi -g(Y,W)hU) + \mu^{2}(1+k)(\eta(W)g(Y,U)\xi -\eta(U)g(Y,W)\xi) - Ak(S(Y,U)\eta(W)\xi + \eta(W)\eta(U)QY) +A\mu(2nk\eta(W)\eta(U)hY - S(hY,U)\eta(W)\xi) +k^{2}(\eta(U)g(Y,W)\xi - \eta(W)g(Y,U)\xi) + k\mu(g(Y,U)hW -g(hY,W)U) + \mu^{2}(g(hY,U)hW - g(hY,W)hU) +\mu(kg(hY,U)W - A\eta(U)\eta(W)QhY) + k^{2}(g(Y,W)\eta(U)\xi +2nA\eta(U)\eta(W)Y) + k^{2}(g(Y,U)W - g(Y,W)U) = 0.$$
(3.18)

Putting $U = \xi$ and using (3.3) in (3.18), we get

$$AS(Y,W) + \mu S(W,hY) + 2kg(Y,W) - 2nkAg(Y,W) + \mu g(W,hY) = 0.$$
(3.19)

Replacing hY of Y in (3.19) and making use of (2.7), we have

$$AS(Y,hW) + \mu(1+k)S(Y,W) - 2nk\mu(1+k)\eta(Y)\eta(W) -2nkAg(Y,hW) + \mu(1+k)g(Y,hW) - \mu(1+k)\eta(Y)\eta(W) = 0.$$
(3.20)

From (3.19), (3.20) and by using (2.9), for the sake of brevity, we set

$$\begin{array}{lll} p_1 &=& (2nkA^2 - 2kA + \mu^2(1+k))[2(n-1) + \mu] + (A\mu + 2nkA\mu - 2k\mu)[2(1-n) + n\mu], \\ p_2 &=& (A^2 - \mu^2(1+k))[2(n-1) + \mu] + (2k\mu - 2nkA\mu - A\mu), \\ p_3 &=& (A\mu + 2nkA\mu - 2k\mu)[2(n-1) + n(2k - \mu)] - \\ & & (\mu^2(1+k)(2n+1))[2(n-1) + \mu] \end{array}$$

we conclude

$$p_2S(Y,W) = p_1g(Y,W) + p_3\eta(Y)\eta(W).$$

Thus, *M* is an η -Einstein manifold. Conversely, let $M^{2n+1}(\varphi, \xi, \eta, g)$ be an η -Einstein manifold, i.e. $p_2S(Y,W) = p_1g(Y,W) + p_3\eta(Y)\eta(W)$, then from equations (3.20), (3.19), (3.18), (3.17) and (3.16) we obtain *M* is a W_7 semi-symmetric.

Theorem 3.3. Let $M^{2n+1}(\phi, \xi, \eta, g)$ be a (k, μ) -paracontact space. Then M is a W_8 semi-symmetric if and only if M is an η -Einstein manifold.

Proof. Suppose that M is a W_8 semi-symmetric. This implies that

$$(R(X,Y)W_8)(U,W)Z = R(X,Y)W_8(U,W)Z - W_8(R(X,Y)U,W)Z - W_8(U,R(X,Y)W)Z - W_8(U,W)R(X,Y)Z = 0,$$
(3.21)

for any $X, Y, U, W, Z \in \chi(M)$. Setting $X = Z = \xi$ in (3.21) and making use of (3.5), (3.9), (3.10), for $A = -\frac{1}{2n}$, we obtain

$$(R(\xi, Y)W_{8})(U, W)\xi = R(\xi, Y)(-k\eta(U)W - AS(U, W)\xi + \mu(\eta(W)hU - \eta(U)hW)) - W_{8}(k(g(Y, U)\xi - \eta(U)Y) + \mu(g(hY, U)\xi - \eta(U)hY), W)\xi - \eta(W)H) + \mu(g(hY, W)\xi - \eta(W)H) + \mu(g(hY, W)\xi - \eta(W)hY))\xi - W_{8}(U, W)(k(\eta(Y)\xi - Y) - \mu hY) = 0.$$
(3.22)

Inner product both sides of (3.22) by $Z \in \chi(M)$ and using of (3.5), (3.6) and (3.9), we get

$$kg(W_{8}(U,W)Y,Z) + \mu g(W_{8}(U,W)hY,Z) + \mu^{2}(1+k)(\eta(W)\eta(Z)g(Y,U) -\eta(U)\eta(Z)g(Y,W)) + Ak(\eta(Y)\eta(Z)S(U,W) - \eta(Z)\eta(W)S(U,Y)) +A\mu(g(hY,Z)S(U,W) - \eta(W)\eta(Z)S(hY,U)) + Ak(S(U,W)g(Y,Z) -S(U,W)\eta(Y)\eta(Z)) + k^{2}(g(Y,U)g(W,Z) + g(Y,W)g(U,Z)) +\mu^{2}(g(hY,U)g(hW,Z) - g(hY,W)g(hU,Z)) + k\mu(g(hY,U)g(W,Z) -g(hY,W)g(U,Z)) - A(\mu S(hY,W)\eta(U)\eta(Z) + kS(Y,W)\eta(U)\eta(Z)) +k\mu(g(Y,U)g(hW,Z) - g(Y,W)g(hU,Z)) - k(\eta(W)\eta(Z)g(Y,U) +\eta(U)\eta(Z)g(Y,hW)) = 0.$$
(3.23)

Making use of (2.7), (2.16) and choosing $W = Y = e_i$, ξ , $1 \le i \le n$, for orthonormal basis of $\chi(M)$ in (3.23), we have

$$kS(U,Z) + \mu S(U,hZ) + (kAr + 2nA\mu(1+k)[2(n-1) + \mu] -2nk^{2} + \mu^{2}(1+k))g(U,Z) + k\mu(1-2n)g(U,hZ) -(2nk^{2}A + \mu^{2}(1+k)(2n+1) + k^{2} + Akr +2nA\mu(1+k)[2(n-1) + \mu] + 2nkA\mu)\eta(U)\eta(Z) = 0.$$
(3.24)

In (3.24), hZ of Z, we arrive

$$kS(U,hZ) + \mu(1+k)S(U,Z) - 2nk\mu(1+k)\eta(U)\eta(Z) + (kAr + 2nA\mu(1+k)[2(n-1)+\mu] - 2nk^{2} + \mu^{2}(1+k))g(U,hZ) + k\mu(1-2n)(1+k)g(U,Z) - k\mu(1-2n)(1+k)\eta(U)\eta(Z) = 0.$$
(3.25)

From (3.24), (3.25) and by using (2.9), for the sake of brevity, we set

$$\begin{aligned} p_1 &= (kAr + 2nA\mu(1+k)[2(n-1)+\mu] - 2nk^2 + \mu^2(1+k)), \\ p_2 &= k\mu(1-2n), \\ p_3 &= -(2nk^2A + \mu^2(1+k)(2n+1) + k^2 + Akr + 2nA\mu(1+k)[2(n-1)+\mu] + 2nkA\mu), \end{aligned}$$

we conclude

$$\begin{aligned} q_1 &= (p_2\mu(1+k)-kp_1)[2(n-1)+\mu] + (kp_2-p_1\mu)[2(1-n)+n\mu], \\ q_2 &= (k^2-\mu^2(1+k))[2(n-1)+\mu] + (p_1\mu-kp_2), \\ q_3 &= (kp_2-p_1\mu)[2(n-1)+n(2k-\mu)] - (p_3k+2nk\mu^2(1+k)+p_2\mu(1+k))[2(n-1)+\mu], \\ q_2S(U,Z) &= q_1g(U,Z) + q_3\eta(U)\eta(Z), \end{aligned}$$

So, *M* is an η -Einstein manifold. Conversely, let $M^{2n+1}(\varphi, \xi, \eta, g)$ be an η -Einstein manifold, i.e. $q_2S(U,Z) = q_1g(U,Z) + q_3\eta(U)\eta(Z)$, then from equations (3.25), (3.24), (3.23), (3.22) and (3.21) we get *M* is a W_8 semi-symmetric.

Theorem 3.4. Let $M^{2n+1}(\phi, \xi, \eta, g)$ be a (k, μ) -paracontact space. Then M is a W_9 semi-symmetric if and only if M is an Einstein manifold.

Proof. Assume that M is a W_9 semi-symmetric. This means that

$$(R(X,Y)W_9)(U,W,Z) = R(X,Y)W_9(U,W)Z - W_9(R(X,Y)U,W)Z - W_9(U,R(X,Y)W)Z - W_9(U,W)R(X,Y)Z = 0,$$
(3.26)

for any $X, Y, U, W, Z \in \chi(M)$. Setting $X = Z = \xi$ in (3.26) and making use of (3.9), (3.7), for $A = \frac{1}{2n}$, we obtain

$$(R(\xi, Y)W_{9})(U, W)\xi = R(\xi, Y)(k(\eta(W)U - \eta(U)W) + \mu(\eta(W)hU - \eta(U)hW) + A(S(U, W)\xi - \eta(W)QU)) - W_{9}(k(g(Y, U)\xi - \eta(U)Y) + \mu(g(hY, U)\xi - \eta(U)hY, W)\xi - W_{9}(U, k(g(Y, W)\xi - \eta(W)Y) + \mu(g(hY, W)\xi - \eta(W)hY))\xi - W_{9}(U, W)(k(\eta(Y)\xi - Y) - \mu hY) = 0.$$
(3.27)

Using (3.7), (3.8), (3.9) in (3.27), we get

$$\begin{aligned} kW_{9}(U,W)Y + \mu W_{9}(U,W)hY + k\mu(\eta(W)g(Y,hU)\xi \\ &-\eta(U)g(Y,hW)\xi) + \mu^{2}(1+k)(\eta(W)g(Y,U)\xi \\ &-\eta(U)g(Y,W)\xi) + k^{2}(g(Y,U)W - g(Y,W)U) \\ &+kA(\eta(U)S(Y,W)\xi - \eta(W)\eta(U)QY) \\ &+A\mu(\eta(U)S(hY,W)\xi + 2nk\eta(U)\eta(W)hY) \\ &+k\mu(g(Y,U)hW - g(Y,W)hU) + k\mu(g(hY,U)W \\ &-g(hY,W)U) + A\mu(S(U,hY)\eta(W)\xi - \eta(W)\eta(U)QhY) \\ &+\mu^{2}(g(hY,U)hW + g(hY,W)hU) - A\mu(S(U,W)hY \\ &+S(hY,U)\eta(W)\xi) + Ak(2nk\eta(W)\eta(U)Y - S(U,W)Y) = 0. \end{aligned}$$
(3.28)

Making use of (2.17), (2.1) and choosing $U = \xi$, in (3.28), we have

$$kS(Y,W) + \mu S(hY,W) - 2nk^2 g(Y,W) - 2nk\mu g(hY,W) = 0.$$
(3.29)

Replacing hY of Y in (3.29) and taking into account (2.7), we arrive

$$kS(Y,hW) + \mu(1+k)S(Y,W) - 2nk\mu(1+k)\eta(Y)\eta(W) -2nk^{2}g(W,hY) - 2nk\mu(1+k)g(Y,W) +2nk\mu(1+k)\eta(W)\eta(Y) = 0.$$
(3.30)

From (3.29), (3.30) and by using (2.7), we have

S(Y,W) = 2nkg(Y,W).

This tell us, *M* is an Einstein manifold. Conversely, let $M^{2n+1}(\varphi, \xi, \eta, g)$ be an Einstein manifold, i.e. S(Y,W) = 2nkg(Y,W), then from equations (3.26), (3.27), (3.28) and (3.30), we obtain *M* is a *W*₉ semi-symmetric. Which verifies our assertion.

Example 3.5. We consider the 3-dimensional manifold $M = \{(x, y, z) \in \mathbb{R}^3, z \neq 0\}$, where (x, y, z) are standard coordinates of \mathbb{R}^3 . The vector fields

$$e_1 = \frac{\partial}{\partial x}, \quad e_2 = 4z^2 \frac{\partial}{\partial x} + \frac{\partial}{\partial y}, \quad e_3 = \frac{\partial}{\partial z}.$$

Let g be the Riemannian metric defined by

$$g(e_1, e_2) = g(e_1, e_3) = g(e_2, e_3) = 0,$$

$$g(e_1, e_1) = g(e_2, e_2) = 1, \quad g(e_3, e_3) = -1$$

Let η be the 1-form defined by $\eta(X) = g(X, e_1)$ for any $X \in \chi(M)$. Let ϕ be the (1,1) tensor field defined by

 $\phi(e_1) = 0, \qquad \phi(e_3) = -e_2, \qquad \phi(e_2) = -e_3.$

Let ∇ be the Levi-Civita connection with respect to the metric tensor g. Then we get

 $[e_3, e_1] = 0, \ [e_1, e_2] = 0, \ [e_2, e_3] = -8ze_1.$

Then we have

$$\eta(e_1) = g(e_1, e_1) = 1, \ \phi^2 X = X - \eta(X)e_1, \ g(\phi X, \phi Y) = -g(X, Y) + \eta(X)\eta(Y),$$

for any $X, Y \in \chi(M)$. Hence, (ϕ, ξ, η, g) defines a paracontact metric structure on M for $e_1 = \xi$. The Levi-Civita connection ∇ of the metric g is given by the Koszul's formula

$$\begin{array}{lll} 2g(\nabla_X Y,Z) &=& Xg(Y,Z)+Yg(Z,X)-Zg(X,Y)\\ && -g(X,[Y,Z])-g(Y,[X,Z])+g(Z,[X,Y]). \end{array}$$

Using the above formula, we obtain.

Comparing the above relations with $\nabla_X e_1 = -\phi X + \phi h X$ *, we get*

$$he_2 = -(4z+1)e_2$$
, $he_3 = -(4z+1)e_3$, $he_1 = 0$.

Using the formula $R(X,Y)Z = \nabla_X \nabla_Y Z - \nabla_Y \nabla_X Z - \nabla_{[X,Y]}Z$, we calculate the following:

$$R(e_2, e_1)e_1 = \left[\frac{1}{(4z-1)^2} - 1\right] \{\eta(e_1)e_2 - \eta(e_2)e_1\} + \left[\frac{1}{(4z-1)^3} - \frac{16z^2 + 1}{4z+1}\right] \{\eta(e_1)he_2 - \eta(e_2)he_1\}$$

= $-16z^2e_2$

$$R(e_3, e_1)e_1 = \left[\frac{1}{(4z-1)^2} - 1\right] \{\eta(e_1)e_3 - \eta(e_3)e_1\} + \left[\frac{1}{(4z-1)^3} - \frac{16z^2 + 1}{4z+1}\right] \{\eta(e_1)he_3 - \eta(e_3)he_1\} = -16z^2e_3$$

$$R(e_2, e_3)e_1 = \left[\frac{1}{(4z-1)^2} - 1\right] \{\eta(e_3)e_2 - \eta(e_2)e_3\} + \left[\frac{1}{(4z-1)^3} - \frac{16z^2 + 1}{4z+1}\right] \{\eta(e_3)he_2 - \eta(e_2)he_3\} = 0.$$

By the above expressions of the curvature tensor and using (2.9), we conclude that *M* is a generalized (k,μ) -paracontact metric manifold with $k = \left[\frac{1}{(4z-1)^2} - 1\right]$ and $\mu = \left[\frac{1}{(4z-1)^3} - \frac{16z^2+1}{4z+1}\right]$.

4. Conclusion

The aim of this paper is to classify (k, μ) -paracontact metric spaces satisfying certain curvature conditions. We present the curvature tensors of (k, μ) -Paracontact manifold satisfying the conditions $R \cdot W_6 = 0$, $R \cdot W_7 = 0$, $R \cdot W_8 = 0$ and $R \cdot W_9 = 0$. According these cases, (k, μ) -Paracontact manifolds have been characterized. Also, several results are obtained.

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Author's contributions

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