

## ABOUT VARIATIES OF G-SEQUENTIALLY METHODS, G-HULLS AND G-CLOSURES

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ABSTRACT. In the first countable spaces many topological concepts such as open and closed subsets; and continuous functions are defined for convergent sequences. The concept of limit defines a function from the set of all convergence sequences in  $X$  to  $X$  itself if  $X$  is a Hausdorff space. This is extended not only to topological spaces but also to sets. More specifically a  $G$ -method is defined to be a function defined on a subset of all sequences We say that a sequence  $\mathbf{x} = (x_n)$   $G$ -converges to  $a$  if  $G(\mathbf{x}) = a$ . Then many topological objects such as open and closed subsets and many others including these sets have been extended in terms of  $G$ -convergence.  $G$ -continuity,  $G$ -compactness and  $G$ -connectedness have been studied by several authors ([1], [2], [3], [4]). On the other hand we know that in a topological space  $X$ , a sequence  $(x_n)$  converges to a point  $a \in X$  if any open neighbourhood of  $a$  includes all terms except finite number. Similarly we define a sequence  $(x_n)$  to be  $G$ -sequentially converging to  $a$  if any  $G$ -open neighbourhood of  $a$  includes almost all terms. In this work provided some examples we indicate that  $G$ -convergence and  $G$ -sequentially convergence are different. We will prove that  $G$ -closed and  $G$ -sequentially closed subsets and therefore many others are different.ed.

### 1. INTRODUCTION

Useful tools for defining topological concepts in sequential terms are the convergences of the sequences.

Some authors explored A-continuity for methods of almost convergence and for related approaches, including Savaş and Das [5], Borsik and Salat [6].

The effects of substituting G-methods defined on a subspace of the real sequences for sequential convergence were examined by Connor and Grosse-Erdmann [7]. In order to apply this idea to topological groups, Çakallı extending this concept to

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topological groups, defined  $G$ -continuity in [1] (see also [8] for various additional forms of continuities). In [9] Mucuk and Şahan introduced the concepts of  $G$ -open sets and  $G$ -neighbourhoods in topological groups and looked into additional  $G$ -continuity features. Recently, Lin and Liu in [10] proposed the ideas of  $G$ -methods,  $G$ -submethods and  $G$ -topologies for arbitrary sets as well as topological spaces, and they also looked into the operations involving  $G$ -hulls,  $G$ -closures,  $G$ -kernels and  $G$ -interiors.

Yongxing and Fucai [11] expanded on several findings and discussed some  $G$ -connectedness,  $G$ -hull, and  $G$ -kernel properties. In [12] Brown and Mucuk studied the covering of disconnected topological groups. In their article [13] L. Liu and Z. Ping proposed the idea of the product  $G$ -method on sets, which results in a  $G$ -generalized topology. They also talked about the  $G$ -connectedness of the Cartesian product. We studied  $G$ -connectedness and  $G$ -sequential methods for product spaces in the works [14] and [15]. Authors explore the concepts of countably  $G$ -compact and sequentially  $GO$ -compact spaces in article [16]. The first countable spaces are sequential topological spaces and can be completely characterized by convergent sequences. A subset  $A$  of sequential space  $X$  is said to be closed, whenever any convergence sequence  $\mathbf{x} = (x_n)$  in  $A$  has sequential limit in the same subset  $A$ . Open subsets in sequential spaces can be also defined in terms of sequences. Subset  $A$  is open if and only if any sequence converging to a point  $a \in A$  is almost in  $A$ .

In [17] some counter examples of convergent  $G$ -methods are given; and  $G$ -open,  $G$ -closed subsets for these  $G$ -convergent methods are characterised. The main object of this paper is to define  $G$ -methods as  $G$ -sequential convergence and then to characterize a variety of  $G$ -open,  $G$ -closed subsets associated with these  $G$ -methods.

## 2. $G$ -SEQUENTIAL CONVERGENCE

Throughout the text, the letter  $X$  designates a topological space unless otherwise stated. The boldface letters  $\mathbf{x}$ ,  $\mathbf{y}$ ,  $\mathbf{z}$ ,... stand for the sequences of terms  $\mathbf{x} = (x_n)$ ,  $\mathbf{y} = (y_n)$ ,  $\mathbf{z} = (z_n)$ , whereas  $s(X)$  and  $c(X)$  stand for the sequences of all terms and the sequence of all convergent sequences of points in  $X$ , respectively. We define a  $G$ -method of sequential convergence for  $X$  as a map defined on a subset  $c_G(X)$  of  $s(X)$  into  $X$ . When for  $\mathbf{x} \in c_G(X)$  and  $G(\mathbf{x}) = \ell$ , a sequence  $\mathbf{x} = (x_n)$  is said to be  $G$ -convergent to  $\ell$ . In particular, the  $G$ -method with  $G = \lim$  is the  $\lim$  function defined on  $c(X)$ . When a sequence  $\mathbf{x}$  is  $G$ -convergent to  $\ell$ , then any subsequence of  $\mathbf{x}$  is likewise  $G$ -convergent to the same point  $\ell$ , is referred to as the *preservation of the  $G$ -convergence of subsequences*. A sequence  $\mathbf{x}$  is described as *regular* whenever any convergent sequence  $\mathbf{x} = (x_n)$  is  $G$ -convergent with  $G(\mathbf{x}) = \lim \mathbf{x}$ . We remind that in a topological space  $X$ , a sequence  $\mathbf{x} = (x_n)$  has limit  $a$  if and only if every open neighbourhood of  $a$  includes almost all terms of  $\mathbf{x} = (x_n)$ . Parallel to this, we can define a variety of  $G$ -convergence as follows:

For a set  $X$ , we say that a sequence  $\mathbf{x} = (x_n)$  in  $X$  is  *$G$ -sequentially convergent* to a point  $a \in X$ , if every  $G$ -open neighbourhood  $U$  of  $a$  includes almost all terms of the sequence. Note that we here use additionally the word “sequentially” to distinguish from  $G$ -convergence. The notion of  $G$ -sequentially convergence defined in this manner enables us to obtain a variety of  $G$ -open,  $G$ -closed subsets and some others. We keep to use the word “sequentially” additionally for these varieties of the notions.

***G-hull and G-closed subsets*** : The point  $\ell \in X$  is said to be in the *G-hull* of  $A$  if the subset  $A$  has a sequence  $\mathbf{x} = (x_n)$  with  $G(\mathbf{x}) = \ell$ .  $A$  is said to be *G-closed* if  $[A]^G \subseteq A$ , which denotes the *G-hull* of  $A$ .  $A$  is *G-closed* if and only if  $[A]^G = A$  since for a regular method  $G$ , one has  $A \subseteq [A]^G$ . Here it should be noted that  $\emptyset$  is *G-closed* since  $[\emptyset]^G = \emptyset$  and  $X$  is *G-closed* since  $[X]^G \subseteq X$ ; and  $[X]^G = X$  if  $G$  is regular. As seen in Example 2.1, even for a regular  $G$ -method, *G-closure*  $[A]^G$  is not necessarily a *G-closed* subset. A subset  $A$  with  $[A]^G = \emptyset$  is *G-closed*. The union of *G-closed* subsets of  $X$  is not always *G-closed*, but the intersection of *G-closed* subsets is also *G-closed*. The *G-closure* of  $A$  is defined to be the intersection of all *G-closed* subsets containing  $A$ , and denoted by  $\overline{A}^G$  which is a *G-closed* subset. By the fact that  $[A]^G \subseteq [K]^G \subseteq K$  whenever  $A \subseteq K$  and  $K$  is a *G-closed* subset, we can deduce that  $[A]^G \subseteq \overline{A}^G$ .

A subset  $A \subseteq X$  is called *G-open* if  $X \setminus A$  is *G-closed*.

$X$  and  $\emptyset$  are *G-open* since they are both *G-closed*. Eventually the union of *G-open* subsets of  $X$  is *G-open* and the intersection of *G-open* subsets is not necessarily *G-open*. A subset  $A \subseteq X$  is a *G-neighborhood* of  $a$  if there exists a *G-open* subset  $U$  of  $X$  such that  $a \in U \subseteq A$ . The union of *G-open* subsets of  $A$  is called *G-interior* of  $A$  and denoted by  $A^{oG}$  which is the largest *G-open* subset of  $A$  [9].  $A$  is *G-open* if only if  $A = A^{oG}$ .

***G-sequentially hull and G-sequentially closed subsets*** : We say a point  $l \in X$  is in the *G-sequentially hull* of a subset  $A$  if there exists a sequence  $\mathbf{x} = (x_n)$  of the terms in  $A$  which *G-sequentially* converges to  $l$  and write  $[A]_G$  for the set of *G-sequentially hull* points of  $A$ . Since for  $a \in A$ , the constant sequence  $(x_n) = (a, a, \dots)$  is *G-sequentially* convergent to  $a$  we conclude that  $A \subseteq [A]_G$ .  $A$  is *G-sequentially closed* if  $[A]_G \subseteq A$ . Note that  $[X]_G = X$  and  $[\emptyset]_G = \emptyset$ ; and therefore  $\emptyset$  and  $X$  are *G-sequentially closed*.

The *G-sequentially closure* of  $A$ , denoted by  $\overline{A}_G$ , is the intersection of all *G-sequentially closed* subsets containing  $A$ , which is also a *G-sequentially closed* subset. If  $A \subseteq K$  and  $K$  is a *G-sequentially closed* subset, then  $[A]_G \subseteq [K]_G \subseteq K$  and therefore  $[A]_G \subseteq \overline{A}_G$ .

We remark that a point  $a$  in a first countable space  $X$  is an interior point of the subset  $A$  if any sequence  $\mathbf{x} = (x_n)$  converging to  $a$  is almost in  $A$ . Hence we can extend this notion to a  $G$ -method as follows: A point  $a$  is said to be a *G-sequentially interior point* of  $A$  and write  $a \in A_G^o$  whenever any sequence  $\mathbf{x} = (x_n)$  with *G-sequentially* convergence to  $a$  is almost in  $A$  or equivalently there is no any sequence  $\mathbf{x} = (x_n)$  in  $X \setminus A$  with *G-sequentially* convergence to  $a$ . By the fact that the constant sequence  $(x_n) = (a, a, \dots)$  is *G-sequentially* convergent to  $a$ , one can see that  $A_G^o \subseteq A$  and therefore  $A$  is *G-sequentially open* when  $A \subseteq A_G^o$ .

We can state following theorems to support the idea of *G-sequential* convergence.

**Theorem 2.1.** [3] *Let  $X$  be a set with a  $G$ -method. A subset  $A$  is  $G$ -sequentially open if and only if  $X \setminus A$  is  $G$ -sequentially closed.*

Equivalently we can state the following theorem.

**Theorem 2.2.**  *$A$  is  $G$ -sequentially closed if and only if  $X \setminus A$  is  $G$ -sequentially open.*

In the following examples, we shall define two  $G$ -methods and the compare  $G$ -convergence and *G-sequential* convergence together with associated features of *G-sequentially closed* subsets.

**Example 2.1.** Let  $G$  be a convergent method on  $\mathbb{R}$  defined by  $G(\mathbf{x}) = \lim \frac{x_n + x_{n+1}}{2}$  for some sequences  $\mathbf{x} = (x_n)$ . We can check the following properties for  $G$ -convergence.

- (i)  **$G$ -closed and  $G$ -open subsets.** Since  $A$  is regular we have  $A \subseteq \overline{A}^G$ . Hence a subset  $A$  is  $G$ -closed if and only if  $A = \overline{A}^G$ . For the subset  $A = \{0, 1\}$  one has  $\overline{A}^G = \{0, \frac{1}{2}, 1\}$ . Here note that since the sequence  $(x_n) = (0, 1, 0, 1, \dots)$  is  $G$ -converging to  $1/2$  one has  $1/2 \in \overline{A}^G$ . Hence  $A$  is not  $G$ -closed.

If  $A = \{x\}$  and  $y \in \overline{A}^G$ , then there exists a sequence  $\mathbf{x} = (x_n)$  in  $A$  with  $G(\mathbf{x}) = y$ . But  $\mathbf{x} = (x_n) = (x, x, \dots)$  and since  $G$  is regular  $G(\mathbf{x}) = \lim(\mathbf{x}) = x$  and therefore  $y = x$ . Hence  $A = \{x\}$  is  $G$ -closed and therefore  $G$ -open subsets are the complements  $\mathbb{R} \setminus \{x\}$  for  $x \in \mathbb{R}$ .

- (ii)  **$G$ -convergence and  $G$ -sequential convergence** This method is  $G$  converging for some sequences but it is not  $G$ -sequentially converging to any point. In below we give different types of examples for the  $G$ -sequentially convergence of sequences.

(a) For example the sequence  $\mathbf{x} = (x_n) = (1, 3, 1, 3, \dots)$  is  $G$ -convergent to 2 but not  $G$ -sequentially converging to any point, because for any point  $x \in \mathbb{R}$ , we can choose a  $G$ -open neighbourhood  $\mathbb{R} \setminus \{a\}$  of  $x$ , which does not include almost all terms of  $\mathbf{x} = (x_n)$ .

(b) For a constant  $a \in X$  consider the sequence  $\mathbf{x} = (x_n)$  defined by

$$x_n = \begin{cases} n, & \text{if } n \text{ is odd} \\ a, & \text{if } n \text{ is even} \end{cases}$$

Then  $\mathbf{x} = (x_n)$  is not  $G$ -convergent to any point but  $G$ -sequentially convergent to the point  $a$  because any  $G$ -open neighbourhood  $\mathbb{R} \setminus \{x\}$  of  $a$  includes almost all terms of the sequence. For any point  $x$ , which is different from  $a$ , the subset  $\mathbb{R} \setminus \{a\}$  is a  $G$ -open neighbourhood of  $x$  but it does not include almost all terms and therefore  $\mathbf{x} = (x_n)$  does not  $G$ -sequentially convergent to  $x$ .

(c) The sequence  $\mathbf{x} = (x_n) = (\frac{1}{n})$  is  $G$ -convergent to 0  $G$ -sequentially convergent to all points  $x$ 's, because any  $G$ -open neighbourhood  $\mathbb{R} \setminus \{a\}$  of  $x$  includes almost all terms of  $\mathbf{x}$ .

- (iii)  **$G$ -sequentially closed and  $G$ -sequentially open subsets**

We can now characterize  $G$ -sequentially closure and hence  $G$ -sequentially closed subsets. Consider the following cases.

(a) If  $A$  is an infinite set, then we have a sequence  $\mathbf{x} = (x_n) = (x_1, x_2, \dots)$  in  $A$  with different terms and  $\mathbf{x} = (x_n)$  is  $G$ -sequentially convergent to every point  $x \in \mathbb{R}$ , since each  $G$ -open neighbourhood  $\mathbb{R} \setminus \{a\}$  of  $x$  includes almost all terms of  $\mathbf{x}$ . Hence all points of  $\mathbb{R}$  are in the  $G$ -sequentially hull of  $A$  and therefore  $[A]_G = \mathbb{R}$ .

(b) Let  $A$  be a finite set and  $x \notin A$ . If  $\mathbf{x} = (x_n)$  is a sequence of the terms of  $A$ , then  $(x_n)$  is in the form  $(x_n) = (\dots, x_{n_0}, \dots, x_{n_0}, \dots)$  and  $G$ -open neighbourhood  $\mathbb{R} \setminus \{x_{n_0}\}$  of  $x$  does not include almost all the terms. Hence  $x \notin [A]_G$  for all  $x \notin A$  and therefore  $[A]_G = A$ . We can write the generalization

$$[A]_G = \begin{cases} \mathbb{R}, & A \text{ is infinite} \\ A, & A \text{ is finite} \end{cases}$$

Hence we can conclude that finite subsets are  $G$ -sequentially closed, cofinite subsets are  $G$ -sequentially open and

$$A_G^0 = \begin{cases} A, & \text{if } A \text{ is cofinite} \\ \emptyset, & \text{otherwise} \end{cases}$$

**Example 2.2.** Let  $c \in X$  be a constant element and  $G$  a method on the set  $X$  defined by  $G(\mathbf{x}) = c$  for any sequence  $\mathbf{x} = (x_n)$ . Then we check the following.

- (i)  **$G$ -closed and  $G$ -open subsets.** One can check that  $[A]^G \subseteq A$  if and only if  $c \in A$ . Hence  $A$  is  $G$ -closed if and only if  $c \in A$ . If  $(a_n) \subseteq A$  and  $G(a_n) = c \in A$ , then  $[A]^G \subseteq A$ . Thus  $[A]^G = \{c\}$ . and therefore we can state  $G$ -closed and  $G$ -open subsets as follows

$$\begin{cases} A \text{ is } G\text{-closed,} & \text{if } c \in A \text{ or } A = \emptyset \\ A \text{ is } G\text{-open,} & \text{if } c \notin A \text{ or } A = X \end{cases}$$

- (ii)  **$G$ - convergence and  $G$ -sequential convergence.** For an  $a \in X$  with  $a \neq c$ , the sequence  $\mathbf{x} = (x_n)$  is  $G$ -sequentially convergent to  $a$  if and only if the terms of  $\mathbf{x} = (x_n)$  is almost  $a$  since by (i)  $\{a\}$  is a  $G$ -open neighbourhood of  $a \in X$ . Moreover by (i) the only  $G$ -open neighbourhood of  $c$  is  $\mathbb{R}$  and therefore any sequence is also  $G$ -sequentially converging to  $c$ .

- (iii)  **$G$ -sequentially closed and  $G$ -sequentially open subsets.**

Let  $a \neq c$ . Then by (i)  $\{a\}$  is a  $G$ -open neighbourhood of  $a$ . Hence a sequence  $\mathbf{x} = (x_n)$  in  $A$  is  $G$ -sequentially convergent to  $a$  if and only if the terms are almost  $a$ , i.e.,  $(x_n) = (a_1, a_2, \dots, a_{n_0}, a, a, \dots)$ . Hence  $[A]^G \subseteq A$  and therefore all subsets are  $G$ -sequentially closed and also  $G$ -sequentially open.

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