

Translators of the Mean Curvature Flow in Hyperbolic Einstein's Static Universe

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(Dedicated to Professor Bang-Yen CHEN on the occasion of his 80th birthday)

ABSTRACT

In this study, we deal with non-degenerate translators of the mean curvature flow in the well-known hyperbolic Einstein's static universe. We classify translators foliated by horospheres and rotationally invariant ones, both space-like and time-like. For space-like translators, we show a uniqueness theorem as well as a result to extend an isometry of the boundary of the domain to the whole translator, under simple conditions. As an application, we obtain a characterization of the the bowl when the boundary is a ball, and of certain translators foliated by horospheres whose boundary is a rectangle.

Keywords: Translator, mean curvature flow, hyperbolic Einstein's static universe, horospheres, rotationally invariant, hyperbolic space, elliptic PDEs.

AMS Subject Classification (2020): Primary: 53E10 ; Secondary: 53C21; 53C50; 53C42.

1. Introduction

The dynamic interplay between mean curvature flow (MCF) and the background of the hyperbolic Einstein's static universe (HESU) forms the core of our exploration in this study. The MCF, as a geometric evolution process, has been a pivotal subject of study with applications ranging from physics to mathematics. The study of the MCF traditionally focus on hypersurfaces within Euclidean space \mathbb{R}^n . One approach involves examining specific solutions know as translating solutions or translators, which remain invariant under a subgroup of translations in the ambient space. The fundamental tool is to simplify the MCF to the equation

$$\mathbf{H} = v^\perp, \quad (1.1)$$

where $n \geq 2$, \mathbf{H} represents the mean curvature vector of the immersion, v is a constant (unit) vector, and v^\perp denotes the orthogonal projection of v into the normal bundle of the hypersurface. Some authors have simplified the equation (1.1) by examining rotationally invariant hypersurfaces, see [6]. Moreover, in [10] they have adopted a broader approach, incorporating a cohomogeneity one action on M . This action involves the isometries of a Lie group, and it is structured such that the resulting hypersurfaces have constant mean curvature, with at most two exceptions (refer to [1] for further information). For example, in [4] and [5], Bueno considered rotationally invariant translators in the product of the real hyperbolic plane and a real line, denoted as $\mathbb{H}^2 \times \mathbb{R}$. In [11], Lira and Martín generalized the study by Bueno to Riemannian products $M \times \mathbb{R}$. Also, Pipoli considered translators in the solvable group Sol_3 in [14] and the Heisenberg group in [15]. On the other hand, Kim in [9] moved to the Minkowski space, again using some groups of isometries on space-like translators. This Lorentzian setting was studied in much more general Lorentzian spaces in [10]. Some other similar problems have been extensively examined in the existing literature ([2],[6],[8],[12],..., and references therein).

Our approach involves translators of the MCF in HESU. This study takes into account both the hyperbolic nature and static structure of the HESU. The involved techniques in our study are basically three, namely, the action of Lie groups of isometries to simplify some PDE into an ODE, the use of dynamical systems to solve a boundary problem, and general theory of elliptic quasilinear PDE. That is to say, this provides a framework

for understanding translations of MCF in the context of the HESU, aiming to classify specific instances that emerge in this universe.

The structure of this paper is the following: In Section 2, we review basic tools, highlighting that a graphical translator is characterized by a function satisfying the PDE (2.2). We also exhibit a big family of time-like translators in HESU which can be constructed from minimal or totally geodesic hypersurfaces in the hyperbolic space.

In Section 3, we present the classification and properties of space-like and time-like translators foliated by horospheres, in Theorems 3.1 and 3.2.

Section 4 is devoted to exploring rotationally invariant translators, which are those invariant by $SO(n)$. To facilitate it, we first recall the Lorentz space \mathbb{L}^{n+1} as an essential mathematical background. We obtain a full classification of these translators, both space-like and time-like, obtaining 5 types in total, in Theorems 4.1 and 4.2. An important space-like example is known as the *bowl*. Except the bowl, all of them exhibit one conic singularity. The only time-like example is a bigraph, known as the *spindle*, and defined through the construction outlined in Lemma 4.7.

Finally, in Section 5, as an application of our findings, we show a uniqueness result for space-like translators based on the boundary, in Theorem 5.2. The methods employed throughout involves tools from quasilinear elliptic partial differential equations and isometries. As an consequence, we prove that an isometry of the sphere can be extended to the translator under simple conditions. With this tool, we prove that a space-like translator whose boundary is a round ball has to be a compact piece of a bowl. In our last result, we characterize certain translators foliated by horospheres whose boundary is a rectangle in Corollary 5.4.

2. Preliminaries

Let $M = \mathbb{H}^n$, $n \geq 2$, be the hyperbolic space with its usual hyperbolic metric $g_{\mathbb{H}^n}$. We define the metric \langle, \rangle as the usual metric in Euclidean space. We consider the Hyperbolic Einstein Static Universe (HESU), namely, the product $\bar{M} = \mathbb{H}^n \times \mathbb{R}$ with Lorentzian metric $g = g_{\mathbb{H}^n} - dt^2$. Take $(p, t) \in \mathbb{H}^n \times \mathbb{R}$. Given an open subset Ω of \mathbb{H}^n , we consider a function $u \in C^\infty(\Omega, \mathbb{R})$ and construct its graph map $\Gamma : \Omega \rightarrow \bar{M}$, where $\Gamma(p) = (p, u(p))$. Given the metric $\gamma = \Gamma^*\langle, \rangle$ on Ω , we assume that $F : (\Omega, \gamma) \rightarrow (M, g)$ is a non-degenerate hypersurface. Under the usual identifications, for each $X \in TM$, we have

$$dF(X) = (X, du(X)) = (X, \langle \nabla u, X \rangle),$$

where ∇u is the \langle, \rangle -gradient of u . The upward vector field is

$$\nu = \frac{1}{W} (\nabla u, 1), \quad W = +\sqrt{\varepsilon(|\nabla u|^2 - 1)}, \tag{2.1}$$

where $\varepsilon := \text{sign}(|\nabla u|^2 - 1) = \pm 1$ is a constant function on the whole Ω . Note that $g(\nu, \nu) = \varepsilon$. The following proposition is known (see for example [10]).

Proposition 2.1. *Under the previous setting, Γ is a graphical translator if, and only if, function u satisfies the quasilinear PDE*

$$\text{div} \left(\frac{\nabla u}{\sqrt{\varepsilon(|\nabla u|^2 - 1)}} \right) = \frac{1}{\sqrt{\varepsilon(|\nabla u|^2 - 1)}}. \tag{2.2}$$

Example 2.1. Take M a minimal or a totally geodesic hypersurface in \mathbb{H}^n . Then, the product $M \times \mathbb{R}$ is also a time-like translator in $\mathbb{H}^n \times_{-1} \mathbb{R}$, and it is not graphical. Indeed, since it is minimal or a totally geodesic in \mathbb{H}^n , then $M \times \mathbb{R}$ is also minimal or a totally geodesic, so its mean curvature vector $H = 0$. But now, $\partial_t \in T(M \times \mathbb{R})$. Then, $H = 0 = (\partial_t)^\perp$, the projection of ∂_t onto $T(M \times \mathbb{R})$.

3. Translators foliated by Horospheres

Before going any further, let us introduce the following space $(\mathbb{R}^k, \langle, \rangle) = \text{Flat Euclidean Space}$. We use the following model of the hyperbolic space

$$\mathbb{H}^n = \{(x_1, \dots, x_n) \in \mathbb{R}^n | x_1 > 0\}, \quad n \geq 2,$$

equipped with the hyperbolic metric $g_{\mathbb{H}^n} = g_p = \frac{1}{x_1^2} \langle \cdot, \cdot \rangle_p$, $p \in \mathbb{H}^n$. The $(n - 1)$ -dimensional Horosphere in \mathbb{H}^n is given by

$$H^{n-1} = \{p = (x_1, \dots, x_n) \in \mathbb{H}^n | x_1 = \hat{x}_1\}, \hat{x}_1 > 0.$$

We give a normal vector $N : H^{n-1} \rightarrow T\mathbb{H}^n$, $p \in H^{n-1} \mapsto x_1 \partial_1|_p$. The tangent space $T_p H^{n-1}$ of H^{n-1} can be written as

$$p \in H^{n-1}, T_p H^{n-1} = \{X \in \mathbb{R}^n | X_1 = 0\},$$

where for all $X \in T_p H^{n-1}$, one has $g(X, N) = 0$. Let ∇ be the Levi-Civita connection on \mathbb{H}^n and A is the Shape operator of N (Weingarten's operator). Given $X = \sum_{i=2}^n X_i \partial_i$ (because $X_1 = 0$, $X \in T H^{n-1}$), a simple computation gives

$$AX = X.$$

We get $p \in H^{n-1}$, $h(p) = \text{trace}_g(A) = (n - 1)$.

Take $\Omega \subset \mathbb{H}^n$ open and connected, $u \in C^\infty(\Omega, \mathbb{R})$. Let $\Gamma : \Omega = \mathring{\Omega} \subset \mathbb{H}^n \rightarrow M$, $p \mapsto (p, u(p))$ be a translator, as in Section 2. We wish the graph of Γ to be foliated by horospheres. Therefore, Ω has to be also foliated by horospheres, that is to say $\Omega = I \times \mathbb{R}^{n-1}$, $I \subset \mathbb{R}$ an interval. We wish u to be invariant by horospheres, so that u only depends on one variable, namely,

$$u : \Omega \rightarrow \mathbb{R}, \quad u : I \times \mathbb{R}^{n-1} \rightarrow \mathbb{R}, (x_1, \dots, x_n) \mapsto u(x_1).$$

Let Σ be the Lie group such that the orbits of Σ in \mathbb{H}^n are just the horospheres, that is to say $\Sigma = (\mathbb{R}^{n-1}, +)$. The map

$$\begin{aligned} \Phi : \mathbb{R}^{n-1} \times \mathbb{H}^n &\rightarrow \mathbb{H}^n, \\ ((v_1, \dots, v_{n-1}), (x_1, \dots, v_n)) &\mapsto (x_1, x_2 + v_1, \dots, x_n + v_{n-1}), \end{aligned}$$

is an smooth action of Σ on \mathbb{H} by isometries. The projection map is

$$\rho : \mathbb{H}^n \rightarrow \mathbb{R}, \rho(x_1, \dots, x_n) = \ln(x_1).$$

We put $\rho(\Omega) = I$. In particular, $f : I \subset \mathbb{R} \rightarrow \mathbb{R}$, $u = f \circ \rho$ such that $F(p) = (p, f(\rho(p)))$, and then graph $(f \circ \rho)$ is foliated by horospheres. Take $s \in \mathbb{R}$, $H_s = \rho^{-1}(s)$ one horosphere. We compute the mean curvature of H_s with respect to $-\nabla \rho$.

$$h = \text{div}(\nabla \rho) = \sum_{i=1}^{n-1} g(\nabla_{e_i} \nabla \rho, e_i) = n - 1,$$

where $(e_1, \dots, e_{n-1}, e_n = \nabla \rho)$ is a local orthonormal frame on $T\mathbb{H}^n$ on each level set. According to Theorem 3.5 of paper [10], Γ_u is a translator if, and only if,

$$f''(s) = (1 - f'(s)^2)(1 - f'(s)(n - 1)), \quad n \geq 2. \tag{3.1}$$

Case I. If $\varepsilon = -1$ then, $0 < (-1)(-1 + f'(s)^2)$ therefore, $|f'(s)| < 1$, Γ is space-like.

Case II. If $\varepsilon = +1$ then, $0 < (+1)(-1 + f'(s)^2)$ therefore, $|f'(s)| > 1$, Γ is time-like.

Now, let us take z , we get

$$w'(s) = (1 - w(s)^2)(1 - mw(s)) \quad \text{where } m \in \mathbb{R}, \quad m \geq 1, \tag{3.2}$$

From now, we will discuss all possible solutions to this ODE.

3.1. Case $w(s) = \pm 1$

Function f becomes $f(s) = \pm s + f_0$. We discard this case, because the associated hypersurfaces Γ are degenerate.

3.2. Case $w(s) = \frac{1}{m}$

We obtain the function $f_1(s) = \frac{s}{m} + f_0$.

3.3. Case $w(s) \neq \pm 1$ and $w(s) \neq \frac{1}{m}$

We make some computations:

$$\frac{w'(s)}{(1-w(s)^2)(1-mw(s))} = 1 \Rightarrow \int \frac{w'(s)}{(1-w(s)^2)(1-mw(s))} ds = s - s_0$$

for some $s_0 \in \mathbb{R}$. Take the change of variable $x = w(s)$,

$$\int \frac{dx}{(1-x^2)(1-mx)} = s - s_0. \tag{3.3}$$

3.3.1. Assume that $m=1$ We have from (3.3)

$$\mathbf{P}(x) := \int \frac{dx}{(1-x^2)(1-x)} = -\frac{1}{4} \ln|1-x| + \frac{1}{2} \cdot \frac{1}{1-x} + \frac{1}{4} \ln|1+x|. \tag{3.4}$$

Clearly, we need the following intervals $\mathbb{R} - \{-1, +1\} = (-\infty, -1) \cup (-1, +1) \cup (+1, +\infty)$. and we obtain different functions, by restricting function \mathbf{P} to the different intervals, namely, $P_1 = \mathbf{P}|_{(-\infty, -1)}$, $P_2 = \mathbf{P}|_{(-1, +1)}$, $P_3 = \mathbf{P}|_{(+1, +\infty)}$. We show some properties of them:

1. $\lim_{x \rightarrow -\infty} P_1(x) = 0$, $\lim_{\substack{x \rightarrow -1 \\ x < -1}} P_1(x) = -\infty$; P_1 strictly decreasing, $\text{Im}(P_1) = (-\infty, 0)$.
2. $\lim_{\substack{x \rightarrow -1 \\ x > -1}} P_2(x) = -\infty$, $\lim_{\substack{x \rightarrow 1 \\ x < 1}} P_2(x) = +\infty$; P_2 strictly increasing, $\text{Im}(P_2) = \mathbb{R}$.
3. $\lim_{\substack{x \rightarrow 1 \\ x > 1}} P_3(x) = -\infty$, $\lim_{x \rightarrow +\infty} P_3(x) = 0$; P_3 strictly increasing, $\text{Im}(P_3) = (-\infty, 0)$.

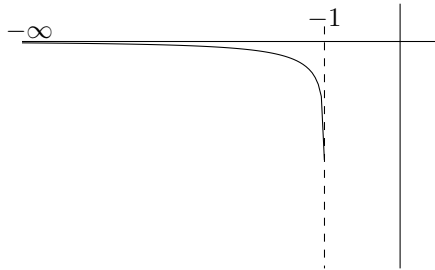


Figure 1. Function P_1

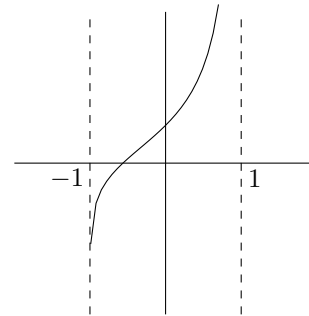


Figure 2. Function P_2

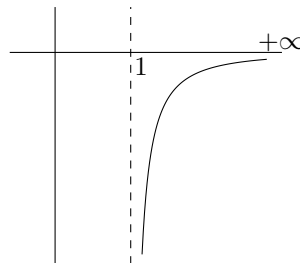


Figure 3. Function P_3

Now, we are going to construct the inverse function of $P_1 : (-\infty, -1) \rightarrow \mathbb{R}$. Recall $P_1(w(s)) = s - s_0 \in (-\infty, 0)$ so that $s < s_0$. Therefore, given $s_0 \in \mathbb{R}$, we define

$$t_1 : (-\infty, s_0) \rightarrow (-\infty, -1), s \mapsto t_1(s) = P_1^{-1}(s - s_0).$$

We can now define f_2 ,

$$f_2 : (-\infty, s_0) \rightarrow \mathbb{R}, s \mapsto f_2(s) = \int_{s_0}^s t_1(v)dv + \widehat{f}_2, \widehat{f}_2 \in \mathbb{R}.$$

We construct the inverse function of $P_2 : (-1, +1) \rightarrow \mathbb{R}$. Recall $P_2(w(s)) = s - s_0 \in (-\infty, +\infty)$. Therefore, given $s_0 \in \mathbb{R}$, we define

$$t_2 : \mathbb{R} \rightarrow (-1, 1), s \mapsto t_2(s) = P_2^{-1}(s - s_0).$$

We can define f_3 ,

$$f_3 : \mathbb{R} \rightarrow \mathbb{R}, s \mapsto f_3(s) = \int_{s_0}^s t_2(r)dr + \widehat{f}_3, \widehat{f}_3 \in \mathbb{R}.$$

Similarly, given $s_0 \in \mathbb{R}$, we define

$$t_3 : (-\infty, s_0) \rightarrow (1, +\infty), s \mapsto t_3(s) = P_3^{-1}(s - s_0).$$

We can define f_4 ,

$$f_4 : (-\infty, s_0) \rightarrow \mathbb{R}, s \mapsto f_4(s) = \int_{s_0}^s t_3(k)dk + \widehat{f}_4, \widehat{f}_4 \in \mathbb{R}.$$

3.3.2. Assume that $m > 1$ We have from (3.3)

$$\mathbf{Q}(x) := \int \frac{dx}{(1-x^2)(1-mx)} = \frac{1}{2m-2} \ln|1-x| + \frac{1}{2m+2} \ln|1+x| - \frac{m}{m^2-1} \ln|1-mx|. \quad (3.5)$$

For $m > 1$, it is clear that we need the following intervals

$$\mathbb{R} - \{-1, +1, 1/m\} = (-\infty, -1) \cup (-1, 1/m) \cup (1/m, +1) \cup (+1, +\infty),$$

and we obtain different functions, by restricting function \mathbf{Q} to the different intervals, namely, $Q_1 = \mathbf{Q}|_{(-\infty, -1)}$, $Q_2 = \mathbf{Q}|_{(-1, 1/m)}$, $Q_3 = \mathbf{Q}|_{(1/m, +1)}$, $Q_4 = \mathbf{Q}|_{(+1, +\infty)}$. We show some properties of them:

1. $\lim_{x \rightarrow -1} Q_1(x) = -\infty$, $\lim_{x \rightarrow -\infty} Q_1(x) = -\frac{m}{m^2-1} \ln(m) < 0$; decreasing, $\text{Im}(Q_1) = (-\infty, \frac{m}{1-m^2} \ln(m))$.
2. $\lim_{x \rightarrow -1} Q_2(x) = -\infty$, $\lim_{\substack{x \rightarrow \frac{1}{m} \\ x < \frac{1}{m}}} Q_2(x) = +\infty$; $Q_2(x)$ increasing, $\text{Im}(Q_2) = \mathbb{R}$.
3. $\lim_{\substack{x \rightarrow \frac{1}{m} \\ x > \frac{1}{m}}} Q_3(x) = +\infty$, $\lim_{x \rightarrow +1} Q_3(x) = -\infty$; $Q_3(x)$ decreasing, $\text{Im}(Q_3) = \mathbb{R}$.
4. $\lim_{x \rightarrow +1} Q_4(x) = -\infty$, $\lim_{x \rightarrow +\infty} Q_4(x) = \frac{m}{1-m^2} \ln(m) < 0$; $Q_4(x)$ increasing, $\text{Im}(Q_4) = (-\infty, \frac{m}{1-m^2} \ln(m))$.

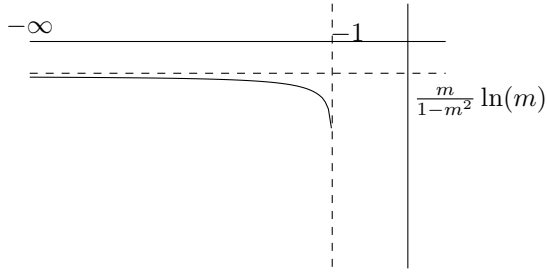


Figure 4. Function Q_1

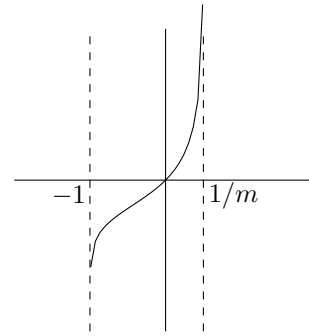


Figure 5. Function Q_2

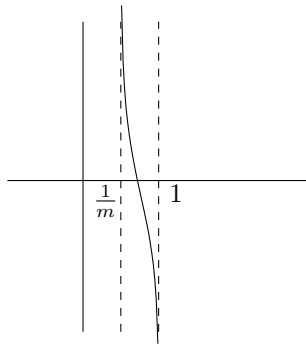


Figure 6. Function Q_3

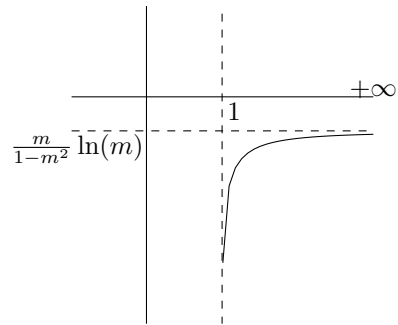


Figure 7. Function Q_4

Theorem 3.1. Consider a space-like translator $\Gamma : \Omega \rightarrow \mathbb{H}^n \times_{-1} \mathbb{R}$, $\Gamma(p) = (p, u(p))$ for all $p \in \Omega$, where $u \in C^2(\Omega)$. Then, Γ is foliated by horospheres if, and only if, there exists $f \in C^2(I)$, $I \subseteq \mathbb{R}$ such that $u = f \circ \rho$ and f is one of the following:

1. $f_1 : \mathbb{R} \rightarrow \mathbb{R}$, $f_1(s) = \frac{s}{n-1} + f_0$, $f_0 \in \mathbb{R}$.
2. $n = 2$, $f_3 : \mathbb{R} \rightarrow \mathbb{R}$, $f_3(s) = \int P_2^{-1}(s)ds + f_0$, $f_0 \in \mathbb{R}$.
3. $n > 2$, $f_6 : \mathbb{R} \rightarrow \mathbb{R}$, $f_6(s) = \int Q_2^{-1}(s)ds + f_0$, $f_0 \in \mathbb{R}$.
4. $n > 2$, $f_7 : \mathbb{R} \rightarrow \mathbb{R}$, $f_7(s) = \int Q_3^{-1}(s)ds + f_0$, $f_0 \in \mathbb{R}$.

Theorem 3.2. Consider a graphical time-like translator $\Gamma : \Omega \rightarrow \mathbb{H}^n \times_{-1} \mathbb{R}$, $\Gamma(p) = (p, u(p))$ for all $p \in \Omega$, where $u \in C^2(\Omega)$. Then, Γ is foliated by horospheres if, and only if, there exists $f \in C^2(I)$, $I \subseteq \mathbb{R}$ such that $u = f \circ \rho$ and f is one of the following:

1. $n = 2$, $f_2 : (-\infty, s_0) \rightarrow \mathbb{R}$, $f_2(s) = \int P_1^{-1}(s)ds + f_0$, $f_0 \in \mathbb{R}$.
2. $n = 2$, $f_4 : (-\infty, s_0) \rightarrow \mathbb{R}$, $f_4(s) = \int P_3^{-1}(s)ds + f_0$, $f_0 \in \mathbb{R}$.
3. $n > 2$, $f_5 : (-\infty, \frac{1-n}{n^2-2n} \ln(n-1)) \rightarrow \mathbb{R}$, $f_5(s) = \int Q_1^{-1}(s)ds + f_0$, $f_0 \in \mathbb{R}$.
4. $n > 2$, $f_8 : (-\infty, \frac{n-1}{2n-n^2} \ln(n-1)) \rightarrow \mathbb{R}$, $f_8(s) = \int Q_4^{-1}(s)ds + f_0$, $f_0 \in \mathbb{R}$.

4. Rotationally Invariant Translators

We introduce the Lorentzian Space

$$\mathbb{L}^{n+1} = \mathbb{R}^{n+1}, \langle (x_1, \dots, x_{n+1}), (y_1, \dots, y_{n+1}) \rangle_L = x_1 y_1 + \dots + x_n y_n - x_{n+1} y_{n+1}, n \geq 2,$$

We consider the model of the hyperbolic space

$$\mathbb{H}^n = \{p \in \mathbb{L}^{n+1} / \langle p, p \rangle_L = -1, p_{n+1} > 0\}.$$

Simple computations provide $T_p\mathbb{H}^n = \{V \in \mathbb{R}^{n+1} / \langle V, p \rangle_L = 0\}$. Now, let us define $\chi : \mathbb{H}^n \rightarrow \mathbb{R}^{n+1}$, $\chi(p) = p$ the position vector, which is a unit normal time-like vector field to \mathbb{H}^n on \mathbb{L}^{n+1} . Since $A_\chi V = +V$, equivalently $A_\chi = +id_{T_p\mathbb{H}^n}$, it is clear that $\mathbb{H}^n \rightarrow \mathbb{L}^{n+1}$ is *totally umbilical*. We define

$$\rho : \mathbb{H}^{n+1} \rightarrow [1, +\infty), (p_1, \dots, p_n) \mapsto p_{n+1}.$$

We have $\rho^{-1}\{s\} = \{p \in \mathbb{H}^n | p_{n+1} = s, s \geq 1\}$, so that this set is a $(n-1)$ sphere of radius $\sqrt{s^2 - 1}$. Simple computations show

$$\begin{aligned} \nabla\rho &= -\partial_{n+1} - \langle \partial_{n+1}, \chi \rangle_L \chi, \\ \langle \nabla\rho, \nabla\rho \rangle_L &= \langle -\partial_{n+1} - \langle \partial_{n+1}, \chi \rangle_L \chi, -\partial_{n+1} - \langle \partial_{n+1}, \chi \rangle_L \chi \rangle = \langle \partial_{n+1}, \chi \rangle_L^2 - 1 \neq +1. \end{aligned}$$

We reparametrize the projection, obtaining

$$\tau : \mathbb{H}^n \rightarrow (0, +\infty), \quad \tau = \ln(\sqrt{\rho^2 - 1} + \rho).$$

Clearly, $\rho = \cosh(\tau)$, and now $\nabla\tau = \frac{1}{\sqrt{\rho^2 - 1}} \nabla\rho$, is a unit normal to each level set. We compute the mean curvature of each level set, namely,

$$h = \operatorname{div}(\nabla\tau) = \operatorname{div}\left(\frac{\nabla\rho}{\sqrt{\rho^2 - 1}}\right) = (n-1) \coth(\tau).$$

Assume that $u = f \circ \rho$ for some $f : I \rightarrow \mathbb{R}$. This means that Γ_u is foliated by spheres. According to *Theorem 3.5* of paper [10], we have:

Proposition 4.1. *A function $u = f \circ \tau$ provides a graphical, rotationally invariant, translator Γ_u if, and only if, the function $f : I \subset (0, +\infty) \rightarrow \mathbb{R}$ is a solution to the following ODE:*

$$f''(s) = (1 - (f'(s))^2)(1 - (n-1) \coth(s) f'(s)). \quad (4.1)$$

Our next target is to study the solutions to (4.1). For this aim, we take $w = f'$ in (4.1) and deal with the following ODE

$$w'(s) = (1 - w^2(s))(1 - (n-1) \coth(s)w(s)). \quad (4.2)$$

Remark 4.1. Given a solution w to this ODE, each primitive $f = \int w$ will provide a graphical rotationally invariant translator in the following way. Define $u := f \circ \tau$, being Γ_u its graph.

Firstly, we have the trivial solutions

$$w_{+1}, w_{-1} : (0, +\infty) \rightarrow \mathbb{R}, \quad w_{+1}(s) = +1, \quad w_{-1}(s) = -1.$$

The primitives $f_{\pm 1} = \int w_{\pm 1}$ will provide degenerate hypersurfaces, but we will need them in the computations of rest of this section.

From now, we will use the book [17]. Indeed, we define the following dynamical system:

$$X : \mathbb{R}^2 \rightarrow \mathbb{R}^2, \quad X(s, z) = (\sinh(s), (1 - z^2)(\sinh(s) - (n-1) \cosh(s)z)). \quad (4.3)$$

The zeros of X are

$$p_0 = (0, 0), \quad p_1 = (0, 1), \quad p_{-1} = (0, -1).$$

We need to compute

$$\begin{aligned} \frac{\partial X}{\partial s} &= (\cosh(s), (1 - z^2)(\cosh(s) - (n-1) \sinh(s)z)), \\ \frac{\partial X}{\partial z} &= (0, -2z(\sinh(s) - (n-1) \cosh(s)z) + (1 - z^2)((1-n) \coth(s))). \end{aligned}$$

We denote the differential of X at p by $DX(p)$. We classify the points p_0 , p_1 and p_{-1} according to the eigenvalues of $DX(p)$:

$$DX(p_0) = \begin{pmatrix} 1 & 0 \\ 1 & 1-n \end{pmatrix}, \quad DX(p_1) = \begin{pmatrix} 1 & 0 \\ 0 & 2(n-1) \end{pmatrix}, \quad DX(p_{-1}) = \begin{pmatrix} 1 & 0 \\ 0 & 2(n-1) \end{pmatrix}, \quad n \geq 2.$$

Clearly, p_1 and p_{-1} are *sources* because both eigenvalues are positive. But p_0 is a *saddle point*. We introduce $\xi = \{(s, z) \in \mathbb{R}^2 | s \geq 0\}$, $\xi_+ = \{(s, z) \in \mathbb{R}^2 | z > 1\}$, $\xi_- = \{(s, z) \in \mathbb{R}^2 | z < -1\}$, and $\xi_0 = \{(s, z) \in \mathbb{R}^2 | -1 < z < 1\}$.

Lemma 4.1. For each solution w to (4.2), there exist an integral curve of X .

Proof. We take $w : I \rightarrow \mathbb{R}$ a solution to (4.2). We consider a solution to $s'(r) = \sinh(s(r))$, say $s(r)$. Take $z(r) = w(s(r))$ so that $\gamma(r) = (s(r), z(r)) = (s(r), w(s(r)))$ is an integral curve of X . \square

Lemma 4.2. For each integral curve $\gamma : K_o \rightarrow \mathbb{R}^2$ such that, $\gamma(r) = (s(r), z(r))$ with s an bijective map, then $w := z \circ s^{-1}$ is a solution to (4.2).

Proof. Since γ is an integral curve of X (that is, $X(\gamma(r)) = \gamma'(r)$), then

$$s'(r) = \sinh(s(r)), \quad z'(r) = (1 - z(r)^2)(\sinh(s(r)) - (n-1)\cosh(s(r))z(r)).$$

As s is bijective, then $s'(s^{-1}(y)) = \sinh(y)$ for any $y \in K_o$. Therefore,

$$w'(y) = \frac{z'(s^{-1}(y))}{s'(s^{-1}(y))} = (1 - w(y)^2)(1 - (n-1)\coth(y)w(y)).$$

This completes the proof. \square

Lemma 4.3. For each solution to the ODE $z'(r) = (1-n)(1-z(r)^2)z(r)$, the curve $\beta(r) = (0, z(r))$ is an integral curve of X .

Proof. We take the curve $\beta(r) = (0, z(r))$. Then, we show that β is an integral curve of X . Indeed, $\beta'(r) = (0, z'(r)) = X(0, z(r)) = (\sinh(0), (1-z(r)^2)(\sinh(0) - (n-1)\cosh(0)z(r))) = (0, (1-z(r)^2)(1-n)z(r))$, that is, $z'(r) = (1-n)(1-z(r)^2)z(r)$. \square

4.1. The Space-like Case

The space-like translators appear when $|f'| < 1$, that is, when $|w| < 1$.

Lemma 4.4. Each solution w to (4.2) with initial condition $(s_0, z_0) \in \xi_0$, namely, $w(s_0) = z_0$, can be extended (as solution) to $w : (0, +\infty) \rightarrow \mathbb{R}$. Also, $\lim_{s \rightarrow 0} w(s) \in \{-1, 0, +1\}$.

Proof. We take a local solution w to (4.2) such that $-1 < w(s) < +1$, which is bounded by the constant solutions $w_{\pm}(s) = \pm 1$. Therefore, w can be extended to $w : (0, +\infty) \rightarrow \mathbb{R}$. By Lemma 4.1, we construct an integral curve $\gamma_w : (0, +\infty) \rightarrow \mathbb{R}^2$ of X from w . By Lemma 4.3, γ_w and β can only coincide at some point p such that $X(p) = 0$. But this only holds when $p \in \{p_0, p_{+1}, p_{-1}\}$, namely, when $\lim_{s \rightarrow 0} w(s) \in \{-1, 0, +1\}$. \square

We define of function $\vartheta : \xi \rightarrow \mathbb{R}$ given by

$$\vartheta(s, z) = (1 - z^2)(\sinh(s) - (n-1)\cosh(s)z). \quad (4.4)$$

We need the set $\alpha = \{(s, z) \in \xi \mid \vartheta(s, z) = 0\} = \{(s, z) \in \xi \mid z = \tanh(s)/(n-1)\}$.

Proposition 4.2. Let $w : (0, +\infty) \rightarrow (-1, 1)$ be a solution to (4.2) such that $|w(s_0)| < 1$ for some $s_0 \in (0, +\infty)$. Then, it is one of the following:

1. There exists a unique $\hat{w} : [0, +\infty) \rightarrow (-1, +1)$ solution to (4.2) such that $\hat{w}(0) = 0$. For all $s \in (0, +\infty)$, it holds $\hat{w}(s) < \frac{\tanh(s)}{n-1}$.
2. If $w(s_0) < \tanh(s_0)/(n-1)$, then $w(s) < \tanh(s)/(n-1)$ for any $s \geq s_0$. In addition, if $w(s_0) < \hat{w}(s_0)$, then $\lim_{s \rightarrow 0} w(s) = -1$.
3. If $w(s_0) > \hat{w}(s_0)$, then $\lim_{s \rightarrow 0} w(s) = +1$.

In all cases, it holds $\lim_{s \rightarrow +\infty} w(s) = \frac{1}{n-1}$.

Proof. 1. We want to solve the boundary problem:

$$w'(s_0) = (1 - w(s)^2)(1 - (n-1)\cosh(s)w(s)), \quad w(0) = 0.$$

If there is a solution, the associated integral curve of X will start at $(0, 0)$. The eigenvalues of $DX(0, 0)$ are $\lambda_1 = 1, \lambda_2 = 1 - n$ and then their eigenvectors are $V_1 = (n, 1)$ and $V_2 = (0, 1)$ respectively. By Theorem 3.2.1. of

the book [17], there exists an integral curve γ of X such that $\gamma(0) = (0, 0)$ and $\gamma'(0) = V_1$ (Integral submanifolds). Then, by Lemma 4.2, we obtain the needed solution to the boundary problem.

In addition, assume by contradiction that there exist $s_0 \in (0, +\infty)$ such that $\hat{w}(s_0) > \frac{\tanh(s_0)}{n-1} > 0$. We have $\hat{w}'(s_0) < 0$ and $\hat{w}(0) = 0$. By continuity, there exist $s_1 \in (0, s_0)$ such that $\hat{w}(s_1) = \frac{\tanh(s_1)}{n-1}$. There exist $s_2 \in (s_1, s_0)$ such that $\hat{w}'(s_1) > 0$ and $\hat{w}'(s_2) > \frac{\tanh(s_2)}{n-1}$. But then,

$$0 < \hat{w}'(s_2) = \left(1 - \hat{w}'(s_2)^2\right) \left(1 - (n-1) \coth(s_0) \hat{w}(s_2)\right) < 0,$$

which is a contradiction.

2. We recall function ϑ , (4.4). Assume that $(s_0, w(s_0))$ satisfies $\vartheta(s_0, w(s_0)) = 0$. Then, $w'(s_0) = (1 - w(s_0)^2)\vartheta(s_0, w(s_0))/\tanh(s_0) = 0$. Moreover, there exists $\delta > 0$ small enough such that if $s \in (s_0 - \delta, s_0)$, then $w'(s) = (1 - w(s_0)^2)\vartheta(s_0, w(s_0))/\tanh(s_0) < 0$; and if $s \in (s_0, s_0 + \delta)$, then $w'(s) > 0$. That is to say, if the graph of w touches the set α , then w has a local minimum. Therefore, if the graph of w is below α at some point, then it remains below α for any other further point.

In addition, if $w(s_0) < \hat{w}(s_0)$, by Lemma 4.4, $\lim_{s \rightarrow 0} w(s) \in \{-1, 0, +1\}$. Since $z_0 < \hat{w}(s_0)$, by uniqueness of solutions to ODE, we have $w(s) < \hat{w}(s)$ for all $s \in (0, +\infty)$. Also, $\hat{w}(0) = 0 > \lim_{s \rightarrow 0} w(s)$ and therefore, $\lim_{s \rightarrow 0} w(s) = -1$.

3. If $w(s_0) > \hat{w}(s_0)$, then $w'(s_0) = (1 - w(s_0)^2)\vartheta(s_0, w(s_0))/\tanh(s_0) < 0$. Therefore, the graph of w remains above the graph of \hat{w} in $(0, s_0)$. By Lemma 4.2, the only possible limit is $\lim_{s \rightarrow 0} w(s) = +1$.

Finally, when s becomes big, if the graph of w is above α , then w is strictly decreasing. However, if the graph of w is below α , w is strictly increasing. Then, $\lim_{s \rightarrow +\infty} w(s) = \lim_{s \rightarrow +\infty} \tanh(s)/(n-1) = 1/(n-1)$. \square

Definition 4.1. We define the function $\hat{f}(s) = \int \hat{w}(s)ds + f_0$. The associated rotationally invariant translator is called the bowl.

By Proposition 4.2, we immediately have the following result.

Theorem 4.1. Given a rotationally symmetric space-like translator Γ in $\mathbb{H}^n \times_{-1} \mathbb{R}$, there exist $f : (0, +\infty) \rightarrow \mathbb{R}$ such that f is a solution to the ODE (4.2), and $\Gamma(p) = (p, f(\rho(p)))$, for all $p \in \mathbb{H}^n$. There are 3 types of functions $f = \int w$, namely the bowl, those with $\lim_{s \rightarrow 0} w(s) = 1$ and those with $\lim_{s \rightarrow 0} w(s) = -1$.

Remark 4.2. In items 2 and 3 Proposition 4.2, $\lim_{s \rightarrow 0} w(s) = \pm 1$. This means that when approaching to the axis of rotation, the translator will hit the axis with an angle of $\pi/4$. Therefore, there is a conic singularity.

4.2. The Time-like Case

Lemma 4.5. Given $(s_0, z_0) \in \mathbb{R}^2$ such that $s_0 > 0, z_0 > 1$, the associated solution can be extended to $w : [0, s_0 + \varepsilon) \rightarrow [1, +\infty)$ with $\lim_{s \rightarrow 0} w(s) = +1$.

Proof. The constant solution $w_+(s) = +1$ is a bound from below. Since, $\vartheta(s, z) > 0$, for all $(s, z) \in \xi_+$. We know w is increasing. Then, we can extend to $[0, s_0 + \varepsilon)$ similarly to item 2 of Proposition 4.2, $\lim_{s \rightarrow 0} w(s) = +1$. \square

Lemma 4.6. Given $(s_0, z_0) \in \mathbb{R}^2$ such that $s_0 < 0, z_0 < 1$, the associated solution can be extended to $w : [0, s_0 + \varepsilon) \rightarrow (-\infty, -1]$ with $\lim_{s \rightarrow 0} w(s) = -1$. Since, $\vartheta(s, z) < 0$, for all $(s, z) \in \xi_-$.

Proof. The proof is very similar to Lemma 4.5. \square

Take g a function which is the inverse of f . We compute $1 = g'(f(s))f'(s)$ and therefore $0 = g''(f(s))f'(s)^2 + g'(f(s))f''(s)$. Then,

$$g''(f(s)) = -\frac{(1 - f'(s)^2)(1 - \coth(s)f'(s))}{f'(s)^3}.$$

We take $f \circ g(t) = t$, which implies $0 = f''(g(t))g'(t)^2 + f'(g(t))g''(t)$. We obtain the following ODE

$$g''(t) = (g'(t) - 1)(\coth(g(t)) - g'(t)). \tag{4.5}$$

Lemma 4.7. Given a solution $g : (t_0 - \varepsilon, t_0 + \varepsilon) \rightarrow \mathbb{R}$ to ODE (4.5). Then, $g''(t_0) = -\coth(g_0) < 0$, there are two functions $f_{\pm} : (g_0 - \delta, g_0) \rightarrow \mathbb{R}$ solutions to the (4.1), which are inverse functions of g with $\lim_{s \rightarrow g_0} f'_{\pm}(s) = \lim_{s \rightarrow g_0} \frac{1}{g'(f_{\pm}(s))} = \pm\infty$. We construct two graphical translator from f_{\pm} rotationally invariant and together they make a smooth hypersurface.

Proof. Choose $t_0 \in \mathbb{R}$. We consider the following IVP:

$$g''(t) = (\varepsilon' + \tilde{\varepsilon}g'(t)^2) (\coth(g(t) - g'(t))), \quad g'(t_0) = 0, g(t_0) = s_0 \in I.$$

As usual, there exists a smooth solution $\alpha : (t_0 - \varepsilon, t_0 + \varepsilon) \rightarrow \mathbb{R}$. Note that t_0 is a critical point of α and $\alpha''(t_0) = \varepsilon' \coth(s_0)$. Case $\coth(s_0) \neq 0$: Then, t_0 is an extremum of α . The restrictions $g_+ = g|_{(t_0, t_0 + \varepsilon)}$ and $g_- = g|_{(t_0 - \varepsilon, t_0)}$ will be injective, by reducing ε if necessary. Construct their inverse functions f_+ and f_- satisfy (4.1). To do so, we put $f_+(g(t)) = t$, and therefore

$$\begin{aligned} 1 &= f'_+(g(t))g'(t), \quad 0 = f''_+(g(t))g'(t)^2 + f'_+(g(t))g''(t), \\ f''_+(g(t))g'(t)^2 &= -f'_+(g(t))(\varepsilon' + \tilde{\varepsilon}\alpha'(t)^2) (\coth(g(t) - g'(t))). \end{aligned}$$

Next, we change $s = g(t)$, and then $g'(t) = 1/f'_+(s)$, so that

$$\frac{f''_+(s)}{f'_+(s)^2} = \frac{1}{f'_+(s)^2} (\tilde{\varepsilon} + \varepsilon' f'_+(s)^2) (1 - \coth(s)f_+(s)).$$

A similar computation holds for f_- . The union of the corresponding graphical translators and their common boundary provide a smooth translator, because g is a smooth map and f_+, f_- are tools to reparametrize its graph. \square

Definition 4.2. The spindle is the rotationally invariant hypersurface obtained in Lemma 4.7.

Remark 4.3. According to Lemmas 4.5 and 4.6, $\lim_{s \rightarrow 0} w(s) = \pm 1$. Again, we have a conic singularity of angle $\pi/4$.

Theorem 4.2. Any rotationally invariant, time-like translator in $\mathbb{H}^n \times_{-1} \mathbb{R}$ is an open subset of a spindle.

Proof. Take $w : (s_0 - \varepsilon, s_0 + \varepsilon) \rightarrow (1, +\infty)$ a solution to (4.2). By Lemma 4.5, we can extend $w : [0, s_0 + \varepsilon) \rightarrow (1, +\infty)$, and $\lim_{s \rightarrow 0} w(s) = 1$. We will show that there exist $s_1 > s_0 + \varepsilon$ such that $\lim_{s \rightarrow s_1} w(s) = +\infty$ (finite-time blow-up). We have

$$w'(s) = (1 - w(s)^2)(1 - (n-1) \coth(s)w(s)) = \sinh(s)\vartheta(s, w(s)).$$

We can get $F(s, z) = (1 - z^2)(1 - (n-1) \coth(s)z)$. With this, we have $w'(s) = F(s, w(s))$. We define $\Upsilon = (0, +\infty) \times [1, +\infty)$, and $F, G : \Upsilon \rightarrow \mathbb{R}$, we consider $G(s, z) = (z^2 - 1)z$. Clearly, $F(s, z) \geq G(s, z)$, for any $(s, z) \in \Upsilon$. Next, the solution to $z'(s) = G(s, z(s))$ with $z(s_0) = z_0$ is $z : (0, s_0 + A) \rightarrow \mathbb{R}$,

$$z(s) = \frac{1}{\sqrt{1 - e^{2s-2(s_0+A)}}}, \quad A = -\frac{1}{2} \ln \left(1 - \frac{1}{z_0^2} \right), \quad A \in \mathbb{R}.$$

Note that $\lim_{s \rightarrow s_0+A} z(s) = +\infty$. These previous computations imply that there exist $s_1 \in (s_0, s_0 + A)$ such that $\lim_{s \rightarrow s_1} w(s) = +\infty$. We start with f , and then we take $w = f' > 1$. Every w has a finite-time blow-up, so we use Lemma 4.7. Therefore every f is strictly increasing and $g = f'$ so at some point, $\lim_{z \rightarrow z_0} g'(z) = 0$. The same reasoning works when $w = f' < -1$. \square

5. Isometries and a Quasilinear Elliptic PDE

Lemma 5.1. When $\varepsilon = -1$, PDE (2.2) behaves as a quasilinear elliptic operator. Moreover, it is locally uniformly elliptic.

Proof. We use the model of half-plane :

$$\begin{aligned} \mathbb{H}^n &= \{(x_1, \dots, x_n) \in \mathbb{R}^n | x_1 > 0\}, \quad n \geq 2. \\ B_1 &= (\partial_1, \dots, \partial_n), \quad B_2 = (e_i = x_1 \partial_i : i = 1, \dots, n). \end{aligned}$$

We know the hyperbolic metric is $g = g_{\mathbb{H}^n} = \frac{1}{x_1^2} \langle \cdot, \cdot \rangle$; $g(e_i, e_j) = x_1^2 g(\partial_i, \partial_j) = \langle \partial_i, \partial_j \rangle = \delta_{ij}$, where as usual, δ_{ij} denotes the Kronecker's delta. We take $u_i = \partial_i u$, and then

$$\nabla u = x_1^2 \sum_{i=1}^n u_i \partial_i.$$

Take $|\nabla u|^2 = \sum_{i=1}^n x_1^2 u_i^2$; $\nabla_{\partial_i} \partial_j = \sum_{k=1}^n \Gamma_{ij}^k \partial_k$. We assume $|\nabla u|^2 < 1$, then $1 > x_1^2 \sum_{i=1}^n u_i^2$. We make some computations :

$$\begin{aligned} \frac{1}{W} &= \operatorname{div} \left(\frac{\nabla u}{W} \right) = \frac{-(\nabla u)(W)}{W^2} + \frac{1}{W} \operatorname{div}(\nabla u), \\ 1 &= \operatorname{div}(\nabla u) - \frac{(\nabla u)(W)}{W}. \end{aligned} \quad (5.1)$$

$$\operatorname{div}(\nabla u) = \sum_{i=1}^n g(\nabla_{e_i} \nabla u, e_i) = x_1^2 \sum_{i=1}^n u_{ii} + 2u_1 x_1 + \sum_{i,j=1}^n x_1^2 \Gamma_{ij}^i u_j.$$

$$W = (1 - |\nabla u|^2)^{1/2} = \left(1 - \sum_{i=1}^n x_1^2 u_i^2 \right)^{1/2},$$

$$(\nabla u)(W) = \left(x_1^2 \sum_{i=1}^n u_i \partial_i \right) \left(1 - \sum_{j=1}^n x_1^2 u_j^2 \right)^{1/2} = -\frac{x_1^3}{W} u_1 \sum_{j=1}^n u_j^2 - \frac{x_1^4}{W} \sum_{i,j=1}^n u_i u_j u_{ij}.$$

We insert all these computations in (5.1).

$$0 = \sum_{i,j=1}^n \left(\delta_{ij} + \frac{x_1^2 u_i u_j}{W^2} \right) u_{ij} + \frac{2u_1}{x_1} + \frac{x_1 u_1}{W^2} \sum_{i=1}^n u_i^2 + \sum_{i,j=1}^n u_i \Gamma_{ji}^j - \frac{1}{x_1^2}.$$

We multiply by $W^2 x_1^2$. Later, we will that this is not a problem.

$$\begin{aligned} 0 &= \sum_{i,j=1}^n \left(x_1^2 \left(1 - \sum_{k=1}^n x_1^2 u_k^2 \right) \delta_{ij} + x_1^4 u_i u_j \right) u_{ij} + 2u_1 x_1 \left(1 - \sum_{k=1}^n x_1^2 u_k^2 \right) \\ &\quad + x_1^3 u_1 \sum_{i=1}^n u_i^2 + \sum_{i,j=1}^n x_1^2 \left(1 - \sum_{k=1}^n x_1^2 u_k^2 \right) u_i \Gamma_{ji}^i(x) - 1 + \sum_{k=1}^n x_1^2 u_k^2. \end{aligned}$$

We define

$$\begin{aligned} a^{ij}, b : \mathbb{H}^n \times \mathbb{R}^n &\rightarrow \mathbb{R}, \quad a^{ij}(x, p) = x_1^2 \left(1 - \sum_{k=1}^n x_1^2 p_k^2 \right) \delta_{ij} + x_1^4 p_i p_j, \text{ and} \\ b(x, p) &= 2u_1 x_1 \left(1 - \sum_{k=1}^n x_1^2 u_k^2 \right) + x_1^3 u_1 \sum_{i=1}^n u_i^2 + \sum_{i,j=1}^n x_1^2 \left(1 - \sum_{k=1}^n x_1^2 u_k^2 \right) u_i \Gamma_{ji}^i(x) - 1 \\ &\quad + \sum_{k=1}^n x_1^2 u_k^2. \end{aligned}$$

Let us check that the matrix $A = (a^{ij})$ is positive-definite. We rewrite it as

$$A = x_1^2 \left(1 - \sum_{k=1}^n x_1^2 p_k^2 \right) I_n + x_1^4 B, \quad B = p^t p.$$

By taking $p, q \in \mathbb{R}^n$, we see $B = p^t p$, $\langle p, q \rangle = pq^t$, $Bp^t = p^t p p^t = |p|^2 p^t$, and therefore

$$Ap^t = \left(x_1^2 \left(1 - \sum_{k=1}^n x_1^2 p_k^2 \right) + x_1^4 |p|^2 \right) p^t,$$

where I_n is the identity matrix. Clearly, $Bp^t = |p|^2 p^t$, and given $q \perp p$ such that $pq^t = 0$, then, $Aq^t = x_1^2 \left(1 - \sum_{k=1}^n x_1^2 p_k^2 \right) q^t$. Therefore, the eigenvalues of A are:

$$\lambda_1 = x_1^2 \left(1 - \sum_{k=1}^n x_1^2 p_k^2 \right) x_1^4 |p|^2, \quad \lambda_2(p) = x_1^2 \left(1 - \sum_{k=1}^n x_1^2 p_k^2 \right).$$

We define

$$\Lambda = \{(x, p) \in \Omega \times \mathbb{R}^n \mid x_1^2 |p|^2 < 1, x_1 > 0\}, \lambda_1, \lambda_2 : \Lambda \rightarrow \mathbb{R}.$$

In Λ , $\lambda_2 > 0$ and $\lambda_1 > 0$, so that the operator Q is elliptic. Also, given $\mathbb{U} \subset \Lambda$ such that \mathbb{U} is open and $\bar{\mathbb{U}}$ compact, then in \mathbb{U}

$$\frac{\lambda_1}{\lambda_2} = 1 + \frac{x_1^2 |p|^2}{1 - \sum_{k=1}^n x_1^2 p_k^2} \geq 1,$$

is bounded from above and from below. That is to say, Q is locally uniformly bounded. \square

We recover *Theorem 10.2* of paper [7];

Theorem 5.1. *Let Ω be a bounded open domain in \mathbb{R}^n . Let $u, v \in C^0(\bar{\Omega}) \cap C^2(\Omega)$. Let Q be a quasilinear operator such that :*

1. Q is locally uniformly elliptic with respect to either u or v ;
2. a^{ij} do not depend on z ;
3. b is non-increasing in z for each $(x, p) \in \Omega \times \mathbb{R}^n$;
4. a^{ij}, b are continuously differentiable with respect to the p -variables in $\Omega \times \mathbb{R} \times \mathbb{R}^n$.

Assume that $Qu = Qv$ in Ω and $u = v$ on $\partial\Omega$. Then $u \equiv v$ in Ω .

From Lemma 5.1 and Theorem 5.1, we immediately obtain the following uniqueness result.

Theorem 5.2. *Let Ω be a bounded open domain in \mathbb{H}^n . Let $u, v \in C^0(\bar{\Omega}) \cap C^2(\Omega)$ such that Γ_u, Γ_v are space-like translators, and $u = v$ on $\partial\Omega$. Then $u \equiv v$ in Ω .*

Proof. By Lemma 5.1, Our operator Q is quasilinear elliptic and locally uniformly bounded. In addition, Q does not depend on z . We know $a^{ij}, b \in C^\infty(\Omega \times \mathbb{R}^n)$. Clearly, Q is on the conditions of Theorem 5.1. \square

Lemma 5.2. *Let Ω be a suitable subset of \mathbb{H}^n . Take $u : \Omega \rightarrow \mathbb{R}$ such that Γ_u be a graphical translator in $\mathbb{H}^n \times_{-1} \mathbb{R}$. Take σ an isometry of \mathbb{H}^n . Given $\hat{u} := u \circ \sigma$, then $\Gamma_{\hat{u}}$ is also a graphical translator in $\mathbb{H}^n \times_{-1} \mathbb{R}$.*

Proof. We take $W = \sqrt{1 - |\nabla u|^2}$ such that $\operatorname{div}\left(\frac{\nabla u}{W}\right) = \frac{1}{W}$. We denote $\hat{W} = \sqrt{1 - |\nabla \hat{u}|^2}$, and then a long but straightforward computation shows $\operatorname{div}\left(\frac{\nabla \hat{u}}{\hat{W}}\right) = \frac{1}{\hat{W}}$. \square

Corollary 5.1. *Take Ω a bounded open domain in \mathbb{H}^n . Assume that there exists an isometry $\sigma : \mathbb{H}^n \rightarrow \mathbb{H}^n$ such that $\sigma(\bar{\Omega}) = \bar{\Omega}$. Let $u \in C^0(\bar{\Omega}) \cap C^2(\Omega)$ such that $\Gamma(p) = (p, u(p))$ is a space-like translator, and $u \circ \sigma = u$ on $\partial\Omega$. Then, u is also invariant with respect to σ , that is to say, Γ is also invariant by $\sigma \times id$.*

Proof. We define $\hat{u} := u \circ \sigma \in C^0(\bar{\Omega}) \cap C^2(\Omega)$. Clearly, \hat{u} is also a space-like translator, that is, $Q\hat{u} = 0$. Therefore, $Qu = Q\hat{u}$. Given $x \in \partial\Omega$, $\hat{u}(x) = u(\sigma(x)) = c = u(x)$ By Theorem 5.1, $u = \hat{u}$. \square

Remark 5.1. There are no assumptions on the topology of $\partial\Omega$.

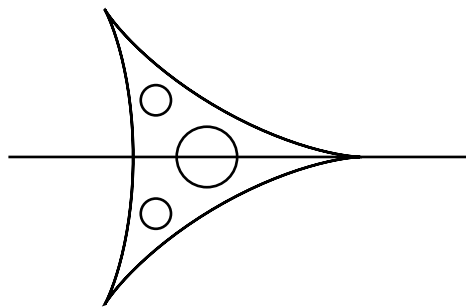


Figure 8. An example of $\bar{\Omega}$ which is symmetric with respect to a hyperplane.

Corollary 5.2. Let Ω be a bounded open domain in \mathbb{H}^n which is invariant by a subgroup G of $\text{Iso}(\mathbb{H}^n)$. Take $u : \bar{\Omega} \rightarrow \mathbb{R}$ such that Γ_u is a space-like translator, and $u \circ \sigma = u$ on $\partial\Omega$, for all $\sigma \in G$. Then, Γ_u is also invariant by $\hat{G} := \{\sigma \times \text{id} : \mathbb{H}^n \times_{-1} \mathbb{R} \rightarrow \mathbb{H}^n \times_{-1} \mathbb{R} \mid \sigma \in G\}$.

We write $B(c, r)$ the ball of center c and radius $r > 0$, and $B^*(c, r) = B(c, r) \setminus \{c\}$.

Corollary 5.3. Let $\Omega = B^*(c, r) \setminus \{c\} \subset \mathbb{H}^n$, $r > 0$, $u : \bar{\Omega} \rightarrow \mathbb{R}$ satisfying Γ_u is a space-like translator with a possible singularity at c , and u is constant on $\partial B(c, r)$. Then Γ_u is a rotationally invariant. In addition, if $u \in C^2(B(c, r))$ then, Γ_u is a compact piece of the bowl.

Proof. The punctured ball Ω is symmetric with respect to all totally geodesic \mathbb{H}^{n-1} passing through the center. By Theorem 5.1, u is symmetric with respect to all totally geodesic \mathbb{H}^{n-1} passing through the center of Ω . This means that Γ_u is rotationally symmetric. So we recall Theorem 4.2. In addition, if u is smooth at c , then Γ_u has to be a piece of a bowl, bearing in mind that this is the only smooth example in the whole Ω . \square

Corollary 5.4. Take $f : [a_1, b_1] \rightarrow \mathbb{R}$, $0 < a_1 < b_1$, one of the solutions in Theorem 3.1. Define $c = f(a_1)$, $d = f(b_1)$ and $a_2, b_2 \in \mathbb{R}$, $a_2 < b_2$. Then, there exists one and only one function $u : \Omega = [a_1, b_1] \times [a_2, b_2] \rightarrow \mathbb{R}$ such that:

- 1) Γ_u is a space-like translator.
- 2) For all $t \in [a_1, b_1]$, $u(t, a_2) = u(t, b_2) = f(t)$; for all $s \in [a_2, b_2]$, $u(a_1, s) = c$, $u(b_1, s) = d$.

Note that Γ_u is foliated by horocycles as in Theorem 3.1.

Proof. Existence is just one of the examples in Theorem 3.1. Uniqueness: Take $u, v \in C^0(\Omega) \cap C^2(\overset{\circ}{\Omega})$ in conditions 1 and 2. We use Theorem 5.1, so $u = v$. \square

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Competing interests

The authors declare that they have no competing interests.

Author's contributions

All authors contributed equally to the writing of this paper. All authors read and approved the final manuscript.

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