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Comparison of Performance on the Different Classifiers of the Locating Protected Projection (LPP) Dimension Reduction Method Based LBP Features

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ABSTRACT

Image cells have taken with Light Microscope help. The local binary pattern (LBP) features have obtained for original images. High-dimensional of these LBP features is reduced to lower-dimensional with Locality Preserving Projections (LPP). These low dimensional data are classified by the Random Forest (RF), Naive Bayes (NB), and Artificial Neural Networks (ANN) classifiers. The classification results are compared with previous studies. The performance achieved with the ANN classifier is higher than the RF and NB classifiers. Moreover, feature vector size used in ANN classifier is a lower than feature vector size used in RF and NB classifiers. The success rates achieved with the ANN, RF, and NB classifiers is respectively 96.29%, 74.44%, and 70.00% according to LPP Method.

Keywords: local binary pattern features, lpp, random forest, Artificial Neural Networks, Naive Bayes

1. INTRODUCTION

Gastric cancer is a type of cancer that occurs in the Gastric tissue and gastric wall. According to studies conducted by the Ministry of Health in our country, gastric cancer was identified as the second most common cancer type. Endoscopy is the most important factor in the early diagnosis of this disease. Endoscopic examination of the endometrium and biopsy specimens are taken and diagnosed as pathological examinations. It is seen that half of the people who have this disease are late in the diagnosis and doctors can not apply any treatment [1]. The most common sites of this disease in the world are distant countries such as Japan and China. Japan, the number of people with Gastric cancer accounts for about 30% of other cancer diseases. In the Americas, the number of Gastric cancer people increases every year [2,3].

According to research conducted worldwide, 26% of males and 11% of females have Gastric cancer. Gastric cancer is located in the third place after lung and breast cancer in women and second place after lung cancer in males. According to the number of new Gastric cancer caught is estimated to be around 30 thousand a year [4]. S. Yoshihiro and colleagues [5] studied Gastric cancer by developing computer-based systems that can predict the risk factor. In the system developed, endoscopy images were taken from patients carrying *H. pylori* bacteria. 15 parameters were used to classify the gastric mucosa with 3 parameters on the back panel. The classification data were processed by Bayesian theorem and outputs were obtained. This study is the source for the treatment of patients who are at risk of gastric cancers or patients who have to undergo endoscopy. D.Ahmadzadeh [6] developed a cancer diagnosis system by using KDM (decision support machine) and local pattern algorithm methods for

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Gastric cancer diagnosis. By using the feature identification, feature extraction and noise reduction steps in the system they have developed the results of estimation of 91,8% of 55 randomly selected samples were found. The common feature of both systems used in the study is that it is a system that helps the doctor in time and material sense. Akbari et al. [7] developed a Gastric cancer diagnosis system by using infrared ultra-spectral imaging method. This study was performed by selecting patients with gastric cancer. Spectral features were extracted from cancerous and normal tissues and compared with this, KDM method was used to determine the detection of cancerous regions by spectral diagram It was performed. High performance was obtained from the system by using HFD and Log transformation in the direction of the obtained data. In the study performed, 25 patients with indole cancer were detected in 30 patients and 83,3119% of the obtained system was mathematically successful. Is a type of cancer that, when diagnosed late, leads the patient to death [8]. Gastric cancer usually begins with ulcer and gastritis complaints. Cancer can affect lymph nodes and other peripheral organs [9].

Theory and Method of the article are explained in Section 2. Section 3 explains the Experiment results of the article. Section 4 describes the conclusions of the article.

It is the main purpose of this article to support with computer programs to early detection of stomach cancer by using histopathology images. The contribution of this article is that the RF, ANN, and NB classifiers are based on the LBP feature selection and the LPP size reduction method. The data is supplied to the RF, ANN, and NB classifiers input supported by the LBP feature account method and the LPP size reduction method. Until today, it is not compared of performance on the different classifiers of the locating protected projection (LPP) dimension reduction method based LBP features.

1. THEORY AND METHOD

The steps of this article is shown in Figure. 1.

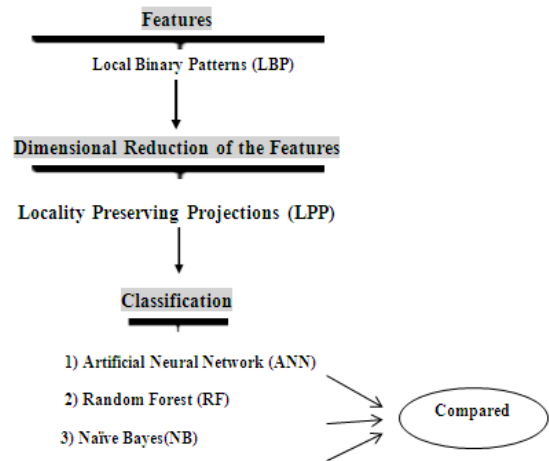


Figure. 1. Steps for classification of normal, benign, and malign gastric cancer images

In this article has been used the Local Binary Patterns (LBP) features. The dimensions of these properties were reduced to lower dimensions by the Locality Preserving Projections (LPP) method. These low dimensional features have been classified by Random Forest (RF), Naive Bayes (NB), and Artificial Neural Networks (ANN) methods.

1.1. Local Binary Patterns (LBP) Features

LBP code is combine eight binary numbers or zero binary code for the center pixel. As a threshold the value of a center pixel is LBP operator [9]. If the value is lower than the center pixel, A neighboring pixel has a lower rank [10]. That pixel is assigned one, otherwise it becomes zero. LBP operators are in different sizes. The middle pixel was made with radius L. This middle pixel value has been compared with points on the edge of chamber. Interpolation is required to get the values of any sampling points of any number of pixels in the environment and any radius [9]. The notation (K, L) represents the neighborhood. The coordinates of the neighbors are (x_k, y_k) and the coordinates of the pixel in the middle are (x_c, y_c) [9].

$$x_k = x_c + L \cos\left(\frac{2\pi p}{K}\right) \quad (1)$$

$$y_k = y_c + L \sin\left(\frac{2\pi p}{K}\right) \quad (2)$$

The gray values of neighbors is p_k , and the gray value of the middle pixel is p_c . Based on this, M texture adjacent to the local pixel (x_c, y_c) can be expressed as:

$$M = m(p_c, p_0 - p_c, \dots, p_{k-1}) \quad (3)$$

$$k = 0, \dots, k - 1$$

It is also possible to define the texture in another way when the values of these points are obtained. The middle pixel's value and differences can be expressed as:

$$M = m(p_c, p_0 - p_c, \dots, p_{k-1} - p_c) \quad (4)$$

$$M \approx (p_0 - p_c, \dots, p_{k-1} - p_c) \quad (5)$$

Textural properties in original distribution in the Equation 3 are conserved in the common disparity. Because, an image that does not deal with the $M(p_c)$ total brightness value does not provide useful information for tissue analysis.

$$M \approx (r(p_0 - p_c), \dots, s(p_{k-1} - p_c)) \quad (6)$$

$$r(x) = \begin{cases} 1, & x \geq 0 \\ 0, & x < 0 \end{cases}$$

Each $r(p_k - p_c)$ values in the Equation (7) are multiplied with 2^k . and These binomial weights are summed. LBP for pixel (x_c, y_c) are obtained as

$$LBP_{K,L}(x_c, y_c) = \sum_{k=0}^{k-1} r(p_k - p_c) 2^k \quad (7)$$

1.2. Locality Preserving Projections (LPP) Dimension Reduction

LPP [11-14] is a linear method that attempts to preserve the knowledge of local neighborhood in an ideal way. In this method, a data set of d dimensional n starts with the creation of a neighborhood graph G consisting of n nodes for $X = [x_1, x_2, \dots, x_n]$. The i x data instance corresponds to i . When constructing the neighborhood graph, ϵ -neighborhood or k -neighborhood of a data sample is used. Put an edge that connects the nodes of neighboring data samples. Using the generated neighborhood graph, a symmetric $N \times N$ weight matrix W is found. W_{ij} can be found in two different ways:

- 1) If x_i ve x_j are interconnected in the neighborhood graph ($t \in R$):

$$W_{ij} = e^{-\frac{\|x_i - x_j\|^2}{t}} \quad (8)$$

- 2) If x_i ve x_j are interconnected in the neighborhood graph:

$$W_{ij} = 1 \quad (9)$$

After these operations, the following generalized eigenvalue problem is solved:

$$XKX^T a = \lambda XLX^T a \quad (10)$$

The L matrix [11-14] is called the laplacian matrix and has the form $K = L - W$. L matrix is a diagonal matrix and each diagonal element is equal to the sum of each column of W weight matrix:

$$L_{ii} = \sum_j W_{ij} \quad (11)$$

1.3. Random Forest (RF) Classifier

RF is a collection of tree type classifiers. In the RF method, tree-type classifiers are used in the $\{h(x, \theta_K) r = 1, \dots\}$ type. where, x is the input data; θ_K represents the random vector. The RF method uses the Gini index. Gini measurements determine the cleavage position having the smallest Gini index [15,16]. Two parameters defined by the user are required to produce a tree with the RF classifier. These parameters, m is the number of variables used in each node. and N is the number of trees that will be developed to determine the best division. The starting m value is randomly selected by the user [15,16]. The next m 's are increased or decreased according to the generalized fault. The generalized error data helps to understand the classification accuracy. K displacement new training data is generated from K training data. The $h(x, K_r)$ classifier is constructed using the new training data set. Only voting with this classifier occurs for each x, y in the training data. K_r does not contain the x and y . Pick a random sample (pixel) for a given K training dataset and belong to class P_i this pixel. According to this situation, the Gini index is expressed as follows.

$$\sum \sum_{j \neq i} (f(P_i, K) / |K|) (f(P_j, K) / |K|) \quad (12)$$

Here, K is the training data set, P_i is the class to which a randomly selected pixel belongs, $f(P_i, K) / |K|$ indicates the possibility of belonging. to the P_i class of the selected example.

Gini index measures the class homogeneity. While as the GINI index decreases, class homogeneity increases, as the GINI index increases, class heterogeneity increases. That

branch is successful when a lower-node GINI index is less than the upper-node GINI index. When the GINI index reaches zero, that is, when a class is left in each node, tree branching ends. When all N trees are produced, the pixel class is determined based on the prediction results obtained from N trees [15-16].

1.4. Artificial Neural Network (ANN) Classifier

In this article, ann classifier is used to compare the effect of the lpp size reduction method on the random forest classifier. The used ann model is a backpropagation algorithm. Back propagation artificial neural networks consist of 2 basic stages; These are forward feed and back propagation. Forward feed is the stage which input data is given to the network. The outputs obtained at the end of this stage are entered into the error function and the weights are changed by propagating the errors backwards. The gradient approximation method is used to minimize the error function and thus the total error. Since the neural network starts with random initial weights, the results after training vary somewhat each time the sample is run. To avoid this change, the random value is set to produce the same results each time [17]. In this article, this random value is chosen as 1000. The number of hidden layers in the a feed-forward network established for stomach cancer recognition is designated as 38.

1.5. Naive Bayes (NB) Classifier

The Naive Bayes classifier is a probabilistic classifier based on the Bayes theorem and based on independent assumptions. Bayes' theorem is a classifier method that refers to a random variant, showing the relationship between conditional probabilities and marginal probabilities [18].

$$P(X\setminus Y) = \frac{P(Y\setminus A)P(X)}{P(Y)} \quad (13)$$

In Equation (13), $P(X\setminus Y)$ is the probability of occurrence of the X event in the case of Y event. $P(Y\setminus A)$ is the likelihood of the Y event occurring when the X event occurs. $P(X)$ and $P(Y)$ are the prior probabilities of X and Y events [20]. A classification operation consists of many attributes and a target variable.

$$p(T\setminus K_1 \dots K_k) = \frac{P(T)p(K_1, \dots, K_n\setminus T)}{p(K_1, \dots, K_n)} \quad (14)$$

T represents the given target and K properties. Naive bayes classifier is generally the product of all conditional probabilities [18,19].

3. EXPERIMENTAL RESULTS

Normal (n), benign (b), and malign (m) gastric image cells have been taken from faculty of Medicine the Firat University with Light Microscope help. The size of these images is 2592x1944. Total number of images are 180 which be 60 n, 60 b, and 60 m. 90 of these 180 images were used for testing purposes and 90 were used for training purposes. The Local Binary Patterns (LBP) features have been obtained for normal, benign, and malign original images. High-dimensional of these LBP feature vectors is reduced to lower-dimensional with Locality Preserving Projections (LPP). These low-dimensional data is 36x180. These low-dimensional data are classified as normal benign and malign by Random Forest (RF) classification. 60 LBP feature values were primarily calculated with the LBP property calculator for each image. Thus, a data size of 60 * 180 was obtained. Images data in the these 60 * 180 size have been used the 60 * 90 for training purposes and 60 * 90 for test purposes. The 60 feature values of these quantities used for training and testing have been reduced to 36 properties by the LPP size reduction method. The these data in the size of 36*90 have been used for training and testing purposes. 36*90 data have been used for training purposes. 36*90 data have been used for test purposes. In summary, the training data set contains 60 feature vectors for 90 different groups. These feature vectors is reduced to lower-dimensional with LPP. During the training process, 36 feature vectors are given to RF. 3 output which be n, b, and m were obtained.

In Table 1, the LBP_Train value has been obtained by calculating the LBP properties of all 90 original training images. The obtained LBP_Train size is 60*90. In the same way, in Table 1, the LBP_Test value has been obtained by calculating the LBP properties of all 90 original test images. The obtained LBP_Test size is 60*90. The LBP_LPP_TrainData value in the Table 1 has been obtained by applying the LPP size reduction method to the LBP_Train values. In Table 1, the obtained for LBP_LPP_RFTestData size is 36*90. The LBP_LPP_RFTestData value has been obtained by applying the LPP size reduction

method to the LBP_Test values for RF classifier. The obtained for LBP_LPP_ANNTTestData size is 10*90. The LBP_LPP_ANNTTestData value has been obtained by applying the LPP size reduction method to the LBP_Test values for ANN classifier. The obtained for LBP_LPP_NBTestData size is 10*90. The LBP_LPP_NBTestData value has been obtained by applying the LPP size reduction method to the LBP_Test values for NB classifier.

In Table 1, TrainGT is a class number that represents 30 n, 30 b, and 30 m images used for training images. TestGT is a class number that represents 30 n, 30 b, and 30 m images used for test images.

Table 1. Testing and training parameters in the RF, ANN, and NB classifiers for gastric cancer images

Parameters of the gastric cancer images	Parameters Dimensional
LBP_Train	60*90
LBP_Test	60*90
LBP_LPP_RFTrainData	36*90
LBP_LPP_RFTest Data	36*90
LBP_LPP_ANNTTrainData	10*90
LBP_LPP_ANNTTrainData	10*90
LBP_LPP_NBTrainData	10*90
LBP_LPP_NBTrainData	10*90
TrainGT	1*30 2*30 3*30
TestGT	1*30 2*30 3*30
Hidden Layer of ANN	38
Random Value of ANN	1000
LBP_LPP_RF Accuracy	74.44%
LBP_LPP_ANN Accuracy	96.29%
LBP_LPP_NB Accuracy	70.00%

In Table 2, LDA is linear discriminant analysis method. In Table 2, HOG_LDA_ANN [21] accuracy rate has been found as 88,9 %. LBP_LPP_ANN [21] accuracy rate has been found as 85,56 % for selected 30 feature. LBP_LPP_ANN accuracy rate has been found as 96.29 % for selected 10 feature. Method LBP_LPP_RF accuracy Rate has been found as 74.44%. Method LBP_LPP_NB accuracy rate has been found as 70.00%.

Table 2. Comparison of Different Results

Compared	
Method	Accuracy
LBP_LPP_RF	74.44% (36 Features)
HOG_LDA_ANN[21]	88.9% (180Features)
LBP_LPP_ANN[21]	85.56% (30 Features)
LBP_LPP_ANN	96.29% (10 Features)
LBP_LPP_NB	70.00% (10 Features)

4. CONCLUSION

Until today, there have been many studies in the field of health [20-33]. However, there are many patients who can not be diagnosed the early cancer. For this reason, computerized methods are still needed for early cancer diagnosis. In this article, it is aimed to developed a new computer aided approach based on lpp size reduction for early diagnosis. The innovation of this article is comparied of performance on the different classifiers of the locating protected projection (LPP) dimension reduction Method Based LBP Features. n, b, and m gastric image cells have taken from faculty of Medicine the Firat University with Light Microscope help. Total number of gastric images are 180 which be 60 n, 60 b, and 60 m. 90 of these 180 gastric images were used for testing purposes and 90 were used for training purposes. The local binary pattern (LBP) features have obtained for original images. High-dimensional of these LBP features is reduced to lower-dimensional with Locality Preserving Projections (LPP). These low dimensional data are classified by the Random Forest (RF), Naive Bayes (NB), and Artificial Neural Networks (ANN) classifiers. The classification results are compared with previous studies. The Local Binary Patterns (LBP) features have obtained for n, b, and m original Gastric images. The size of these LBP feature vectors is 60x180. High-dimensional of these LBP feature vectors is reduced to lower-dimensional with Locality Preserving Projections (LPP). These low-dimensional data is 36x180 for RF, 10X180 for ANN, and 10x180 for NB. These low-dimensional data are classified as n, b, and m by RF, ANN, and NB classifiers. The success rates achieved with the LBP_LPP_ANN, LBP_LPP_RF, and LBP_LPP_NB classifiers is respectively 96.29%, 74.44%,and 70.00% according to LPP Method. The success performance achieved with the ANN classifier is

higher than the RF and NB classifiers. Moreover, feature vector size used in ANN classifier is a lower than feature vector size used in RF and NB classifiers.

In future studies, an analysis will be performed by applying different feature extraction methods to different cancer images.

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