



SPLIT SEMI-QUATERNIONS ALGEBRA IN SEMI-EUCLIDEAN 4-SPACE

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ABSTRACT. The aim of this paper is to study the split semi-quaternions, H_{ss} , and to give some of their algebraic properties. We show that the set of unit split semi-quaternions is a subgroup of H_{ss}° . Furthermore, with the aid of De Moivre's formula, any powers of these quaternions can be obtained.

Keywords De Moivre's formula, Split semi-quaternion, Euler's formula.

1. Introduction

Quaternions were invented by Sir William Rowan Hamilton as an extension to the complex number in 1843. Hamilton's defining relation is most succinctly written as

$$i^2 = j^2 = k^2 = ijk = -1.$$

Quaternions have provided a successful and elegant means for the representation of three dimensional rotations, Lorentz transformations of special relativity, robotics, computer vision, problems of electrical engineering and so on. The Euler's and De-Moivre's formulas for the complex numbers are generalized for quaternions. Obtaining the roots of a quaternion was given by Niven[3] and Brand [1]. Brand proved De Moivre's theorem and used it to find n-th roots of a quaternion. These formulas are also investigated in the cases of split and semi-quaternions [2, 4]. A brief introduction of the split semi-quaternions is provided in [5]. In this paper, we investigate some algebraic properties of split semi-quaternions. Moreover, we obtain De-Moivre's and Euler's formulas for these quaternions in different cases. We use De-Moivre's formula to find n -th roots of a split semi-quaternion. Finally, we give some example for the purpose of more clarification.

2. Splitsemi-quaternions

Definition 2.1. A split semi-quaternion q is defined as

$$q = a_0 + a_1i + a_2j + a_3k$$

where a_0, a_1, a_2 and a_3 are real numbers and i, j, k are quaternionic units with the properties that

$$\begin{aligned} i^2 &= 1, & j^2 &= k^2 = 0 \\ ij &= k = -ji, & jk &= 0 = kj \end{aligned}$$

and

$$ki = -j = -ik.$$

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The set of all split semi-quaternions are denoted by H_{ss} . A split semi-quaternion q is a sum of a scalar and a vector, called scalar part, $S_q = a_0$, and vector part $V_q = a_1i + a_2j + a_3k$. The set of split semi-quaternions $H_{ss} - \{[0, (0, 0, 0)]\}$ is written H_{ss}° .

Let $q, p \in H_{ss}$, where $q = S_q + V_q$ and $p = S_p + V_p$. The addition operator, $+$, is defined

$$\begin{aligned} q + p &= (S_q + S_p) + (V_p + V_q) \\ &= (a_0 + b_0) + (a_1 + b_1)i + (a_2 + b_2)j + (a_3 + b_3)k. \end{aligned}$$

This rule preserves the associativity and commutativity properties of addition. The product of scalar and a split semi-quaternion is defined in a straightforward manner. If c is a scalar and $q \in H_{ss}$,

$$cq = cS_q + cV_q = (ca_0)1 + (ca_1)i + (ca_2)j + (ca_3)k.$$

The multiplication rule for split semi-quaternions is defined as

$$qp = S_q S_p - \langle V_q, V_p \rangle + S_q V_p + S_p V_q + V_q \times V_p,$$

where

$$\langle V_q, V_p \rangle = -a_1b_1, \quad V_p \times V_q = 0i - (a_3b_1 - a_1b_3)j + (a_1b_2 - a_2b_1)k.$$

It could be written as

$$qp = \begin{bmatrix} a_0 & a_1 & 0 & 0 \\ a_1 & a_0 & 0 & 0 \\ a_2 & -a_3 & a_0 & a_1 \\ a_3 & -a_2 & a_1 & a_0 \end{bmatrix} \begin{bmatrix} b_0 \\ b_1 \\ b_2 \\ b_3 \end{bmatrix}.$$

Split semi-quaternion multiplication is not generally commutative. We state the following properties of quaternion multiplication:

Proposition 2.1. *Let $q, q', p \in H_{ss}$ and $r \in \mathbb{R}$. Then*

$$\begin{aligned} (pq)q' &= p(qq') && \text{(Quaternion multiplication is associative.)} \\ p(q + q') &= pq + pq' && \text{(Quaternion multiplication distributes} \\ (q + q')p &= qp + q'p && \text{across addition.)} \end{aligned}$$

Corollary 2.1. *H_{ss} with addition and multiplication has all the properties of a number field expect commutativity of the multiplication. It is therefore called the skew field of quaternions.*

3. Some properties of split semi-quaternions

Definition 3.1. Let $q \in H_{ss}$. Then \bar{q} is called the conjugate of q is defined by

$$\bar{q} = a_0 - (a_1i + a_2j + a_3k) = S_q - V_q.$$

It is clear the scalar and vector part of q is denoted by $S_q = \frac{q+\bar{q}}{2}$ and $V_q = \frac{q-\bar{q}}{2}$.

The above definition would lead to the following properties:

Proposition 3.1. Let $q, p \in H_{ss}$. Then

$$i) \bar{\bar{q}} = q \quad ii) \overline{pq} = \bar{q}\bar{p} \quad iii) \overline{q+p} = \bar{q} + \bar{p} \quad iv) q\bar{q} = \bar{q}q.$$

Definition 3.2. Let $q \in H_{ss}$ and let the mapping $\|\cdot\| : H_{ss} \rightarrow \mathbb{R}$ be defined by $\|q\| = q\bar{q} = a_0^2 - a_1^2 \in \mathbb{R}$. This mapping is called the norm and $\|q\| (= N_q)$ is norm of q . If $\|q\| = a_0^2 - a_1^2 = 1$, then q is called a unit split semi-quaternion. We will use H_{ss}^1 to denote the set of unit split semi-quaternion.

A split semi-quaternion q for which $\|q\| = 0$ has the form $q = a_2j + a_3k$, ($a_0 = a_1 = 0$) and it is a zero divisor, but not all zero divisors of this algebra have this form.

Definition 3.3. Let $q \in H_{ss}$ and $\|q\| \neq 0$. Then there exists $q^{-1} \in H_{ss}$ such that $qq^{-1} = q^{-1}q = I$. Furthermore q^{-1} is unique and it is given by

$$q^{-1} = \frac{\bar{q}}{\|q\|}.$$

Proposition 3.2. Let $p, q \in H_{ss}$ and $\lambda \in \mathbb{R}$. The following three equations hold:

$$i) (qp)^{-1} = p^{-1}q^{-1}, \quad ii) (\lambda q)^{-1} = \frac{1}{\lambda}q^{-1}, \quad iii) \|q^{-1}\| = \frac{1}{\|q\|}.$$

Proposition 3.3. The set H_{ss}^1 of unit split semi-quaternions is a subgroup of the group H_{ss}° .

Proof. Let $q, q' \in H_{ss}^1$. We have $\|qq'\| = 1$, i.e. $qq' \in H_{ss}^1$ and thus the first subgroup requirement is satisfied. Also, by proposition 3.2,

$$\|q\| = \|\bar{q}\| = \|q^{-1}\| = 1.$$

and thereby the second subgroup requirement $q^{-1} \in H_{ss}^1$.

4) To divide a split semi-quaternion p by the semi-quaternion q ($N_q \neq 0$), one simply has to resolve the equation

$$xq = p \quad \text{or} \quad qy = p,$$

with the respective solutions

$$\begin{aligned} x &= pq^{-1} = p \frac{\bar{q}}{N_q}, \\ y &= q^{-1}p = \frac{\bar{q}}{N_q} p \end{aligned}$$

and the relation $N_x = N_y = \frac{N_p}{N_q}$.

Definition 3.4. Let $q, p \in H_{ss}$, $q = S_q + V_q$ and $p = S_p + V_p$. The inner product is defined as

$$\begin{aligned} g(q, p) &= S_q S_p + \langle V_q, V_p \rangle \\ &= S(q\bar{p}). \end{aligned}$$

Theorem 3.1. *The inner product has the properties;*

- 1) $g(pq_1, pq_2) = N_p \cdot g(q_1, q_2)$
- 2) $g(q_1 p, q_2 p) = N_p \cdot g(q_1, q_2)$
- 3) $g(pq_1, q_2) = g(q_1, \bar{p}q_2)$
- 4) $g(pq_1, q_2) = g(p, q_2 \bar{q}_1)$.

Proof. We will prove the identities (1) and (3).

$$\begin{aligned} g(pq_1, pq_2) &= S(pq_1 \bar{p}q_2) = S(pq_1 \bar{q}_2 \bar{p}) \\ &= S(\bar{q}_2 \bar{p}pq_1) = N_p S(\bar{q}_2 q_1) \\ &= N_p S(q_1 \bar{q}_2) = N_p \cdot g(q_1, q_2), \end{aligned}$$

and

$$\begin{aligned} g(pq_1, q_2) &= S(pq_1 \bar{q}_2) = S(q_1 \bar{q}_2 p) \\ &= S(q_1 \bar{p}q_2) = g(q_1, \bar{p}q_2). \end{aligned}$$

Theorem 3.2. *The algebra H_{ss} is isomorphic to the subalgebra of the algebra \mathbb{C}'_2 consisting of the (2×2) -matrices*

$$\hat{A} = \begin{bmatrix} A & B \\ 0 & \bar{A} \end{bmatrix},$$

and to the subalgebra of the algebra \mathbb{C}^2_2 consisting of the (2×2) -matrices

$$\tilde{A} = \begin{bmatrix} A & B \\ 0 & A \end{bmatrix},$$

where $A, B \in \mathbb{C}$.

Proof. The proof can be found in [5].

4. De Moivre's formula for split semi-quaternions

In this section, we express De-Moivre's formula for split semi-quaternions. For this, we can consider two different cases:

Case 1: Let the norm of split semi-quaternion be positive.

Definition 4.1. Every nonzero split semi-quaternion $q = a_0 + a_1i + a_2j + a_3k$ can be written in the polar form

$$q = r(\cosh \varphi + \vec{w} \sinh \varphi)$$

where $r = \sqrt{N_q}$ and

$$\cosh \varphi = \frac{|a_0|}{r}, \quad \sinh \varphi = \frac{\sqrt{a_1^2}}{r} = \frac{|a_1|}{\sqrt{a_0^2 - a_1^2}}.$$

The unit vector \vec{w} is given by

$$\vec{w} = \frac{1}{\sqrt{a_1^2}}(a_1i + a_2j + a_3k), \quad a_1 \neq 0.$$

Euler's formula for a unit split semi-quaternion holds. Since $\vec{w}\vec{w} = 1$, we have

$$\begin{aligned} e^{\vec{w}\varphi} &= 1 + \vec{w}\varphi + \frac{(\vec{w}\varphi)^2}{2!} + \frac{(\vec{w}\varphi)^3}{3!} + \dots \\ &= \left(1 + \frac{\varphi^2}{2!} + \frac{\varphi^4}{4!} + \dots\right) + \vec{w}\left(\varphi + \frac{\varphi^3}{3!} + \frac{\varphi^5}{5!} + \dots\right) \\ &= \cosh \varphi + \vec{w} \sinh \varphi. \end{aligned}$$

Moreover, this can be shown by using the following method.

$$\begin{aligned} q &= \cosh \varphi + \vec{w} \sinh \varphi \Rightarrow dq = (\sinh \varphi + \vec{w} \cosh \varphi)d\varphi \\ dq &= \vec{w}(\cosh \varphi + \vec{w} \sinh \varphi)d\varphi = \vec{w}q d\varphi. \end{aligned}$$

thus, we get $\int \frac{dq}{q} = \int \vec{w} d\varphi \Rightarrow \ln q = \vec{w}\varphi \Rightarrow q = e^{\vec{w}\varphi} = \cosh \varphi + \vec{w} \sinh \varphi$.

Example 4.1. The polar form of split semi-quaternions $q_1 = 2 + \sqrt{2}i - j + 2k$, $q_2 = 3 + 2i + j + k$, $q_3 = 4 + i - j + 2k$ are $q_1 = \sqrt{2}(\cosh \theta_1 + \vec{w} \sinh \theta_1)$ where $\theta_1 = \ln(\sqrt{2}+1)$, $q_2 = \sqrt{5}(\cosh \theta_2 + \vec{u} \sinh \theta_2)$ where $\theta_2 = \ln(\sqrt{5})$, and $q_3 = \sqrt{15}(\cosh \theta_3 + \vec{e} \sinh \theta_3)$ where $\theta_3 = \ln(\frac{5}{\sqrt{15}})$, respectively.

Lemma 4.1. Let \vec{w} be a unit vector, then we have

$$(\cosh \varphi + \vec{w} \sinh \varphi)(\cosh \psi + \vec{w} \sinh \psi) = \cosh(\varphi + \psi) + \vec{w} \sinh(\varphi + \psi).$$

Now, let's prove De Moivre's formula for a split semi-quaternion.

Theorem 4.1. (De-Moivre's formula) Let $q = \cosh \varphi + \vec{w} \sinh \varphi$ be a unit split semi-quaternion. Then for every integer n ;

$$q^n = \cosh n\varphi + \vec{w} \sinh n\varphi.$$

Proof. We use induction on positive integers n . Assume that $q^n = \cosh n\varphi + \vec{w} \sinh n\varphi$ holds. Then

$$\begin{aligned} q^{n+1} &= (\cosh \varphi + \vec{w} \sinh \varphi)^n (\cosh \varphi + \vec{w} \sinh \varphi) \\ &= (\cosh n\varphi + \vec{w} \sinh n\varphi) (\cosh \varphi + \vec{w} \sinh \varphi) \\ &= \cosh(n\varphi + \varphi) + \vec{w} \sinh(n\varphi + \varphi) \\ &= \cosh(n+1)\varphi + \vec{w} \sinh(n+1)\varphi. \end{aligned}$$

The formula holds for all integer n , since

$$\begin{aligned} q^{-1} &= \cosh \varphi - \vec{w} \sinh \varphi, \\ q^{-n} &= \cosh(-n\varphi) + \vec{w} \sinh(-n\varphi) \\ &= \cosh n\varphi - \vec{w} \sinh n\varphi. \end{aligned}$$

Example 4.2. Let $q = 3 - 2i - j + 3k$ be a split semi-quaternion. Then, we can write it as $q = \sqrt{5}(\cosh \theta + \vec{w} \sinh \theta)$ where $\theta = \ln(\sqrt{5})$. Every power of this quaternion is found with the aid of Theorem 4.2, for example, 10-th power of

$$q^{10} = 5^5 [\cosh 10\theta + \vec{w} \sinh 10\theta].$$

where $\cosh 10\theta = \frac{5^5 + 5^{-5}}{2}$ and $\sinh 10\theta = \frac{5^5 - 5^{-5}}{2}$.

Theorem 4.2. Let $q = \cosh \varphi + \vec{w} \sinh \varphi$ be a unit split semi-quaternion. The equation $x^n = q$ has only one root:

$$x = \cosh \frac{\varphi}{n} + \vec{w} \sinh \frac{\varphi}{n}.$$

Proof. If $x^n = q$, q will have the same unit vector as \vec{w} . So, we assume that $x = \cosh \chi + \vec{w} \sinh \chi$ is a root of the equation $x^n = q$. From Theorem 4.2, we have

$$x^n = \cosh n\chi + \vec{w} \sinh n\chi,$$

Thus, $\chi = \frac{\varphi}{n}$. So, $x = \cosh \frac{\varphi}{n} + \vec{w} \sinh \frac{\varphi}{n}$ is a root of the equation $x^n = q$.

Example 4.3. Let $q = 2 + \sqrt{3}i - 2j + k = (\cosh \varphi + \vec{w} \sinh \varphi)$ be a split semi-quaternion. The equation $x^3 = q$ has one root and that is

$$x = \left(\cosh \frac{\ln(2 + \sqrt{3})}{3} + \vec{w} \sinh \frac{\ln(2 + \sqrt{3})}{3} \right).$$

Case 2: Let the norm of split semi-quaternion be negative.

Definition 4.2. Every nonzero split semi-quaternion $q = a_0 + a_1i + a_2j + a_3k$ can be written in the polar form

$$q = r(\sinh \psi + \vec{u} \cosh \psi)$$

where $r = \sqrt{|N_q|}$ and

$$\sinh \psi = \frac{|a_0|}{r}, \quad \cosh \psi = \frac{\sqrt{a_1^2}}{r} = \frac{|a_1|}{\sqrt{|a_0^2 - a_1^2}}.$$

The unit vector \vec{u} is given by

$$\vec{u} = \frac{1}{\sqrt{a_1^2}}(a_1i + a_2j + a_3k), \quad a_1 \neq 0.$$

Example 4.4. The polar form of the split semi-quaternions $q_1 = 2 + 3i - j + 2k, q_2 = 1 + \sqrt{2}i + 2j + k$ are $q_1 = \sqrt{5}(\sinh \theta_1 + \vec{u} \cosh \theta_1)$ where $\theta_1 = \ln \sqrt{5}$, $q_2 = \sinh \theta_2 + \vec{u} \cosh \theta_2$ where $\theta_2 = \ln(1 + \sqrt{2})$, respectively.

Theorem 4.3. (De-Moivre's formula) Let $q = \sinh \varphi + \vec{u} \cosh \varphi$ be a unit split semi-quaternion. Then for every integer n ;

$$q^n = \sinh n\varphi + \vec{u} \cosh n\varphi.$$

Example 4.5. Let $q = \sqrt{2} + 2i - j + 3k = \sqrt{2}(\sinh \theta + \vec{u} \cosh \theta)$ be a split semi-quaternion. Every power of this split semi-quaternion is found by the aid of Theorem 4.4, for example, 40-th power is

$$q^{40} = 2^{20}[\sinh 40\theta + \vec{u} \cosh 40\theta],$$

$$\text{where } \sinh 40\theta = \frac{(1+\sqrt{2})^{40} - (1+\sqrt{2})^{-40}}{2} \text{ and } \cosh 40\theta = \frac{(1+\sqrt{2})^{40} + (1+\sqrt{2})^{-40}}{2}.$$

Theorem 4.4. Let $q = \sinh \varphi + \vec{u} \cosh \varphi$ be a unit split semi-quaternion. The equation $x^n = q$ has only one root:

$$x = \sinh \frac{\varphi}{n} + \vec{u} \cosh \frac{\varphi}{n}.$$

Proof. If $x^n = q$, q will have the same unit vector as \vec{u} . So, we assume that $x = \sinh \theta + \vec{u} \cosh \theta$ is a root of the equation $x^n = q$. From Theorem 4.4, we have

$$x^n = \cosh n\chi + \vec{u} \sinh n\chi,$$

Thus, $\theta = \frac{\varphi}{n}$. So, $x = \sinh \frac{\varphi}{n} + \vec{u} \cosh \frac{\varphi}{n}$ is a root of the equation $x^n = q$.

Example 4.6. Let $q = 2 + 3i - 2j + k = (\sinh \varphi + \vec{u} \cosh \varphi)$ be a split semi-quaternion. The equation $x^4 = q$ has one root and that is

$$x = \left(\sinh \frac{\ln(\sqrt{5})}{4} + \vec{u} \cosh \frac{\ln(\sqrt{5})}{4} \right).$$

5. Conclusion

In this paper, we give some of algebraic properties of the split semi-quaternions and investigate the Euler's and De Moivre's formulas for these quaternions in different cases. We use it to find n -th roots of a split semi-quaternion.

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