



A STUDY ON A PARTIALLY NULL CURVE IN \mathbb{E}_2^4

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ABSTRACT. In this paper, we study with Frenet equations which are given in [3] of a partially null curve in Semi- Euclidean 4-space \mathbb{E}_2^4 with index 2. By using the Frenet equations, we give some theorem and corollary. A characterization of a hyperbolic partially null curve in \mathbb{E}_2^4 is given. Additionally, we examine harmonic curvatures and curvatures of this curve in \mathbb{E}_2^4 .

1. INTRODUCTION

Semi-Euclidean 4–space \mathbb{E}_2^4 with index 2 is the Euclidean 4–space \mathbb{E}^4 equipped with an indefinite flat metric g given by

$$g = -dx_1^2 - dx_2^2 + dx_3^2 + dx_4^2,$$

where (x_1, x_2, x_3, x_4) is a rectangular coordinate system of \mathbb{E}_2^4 . A vector $v = (v_1, v_2, v_3, v_4)$ in \mathbb{E}_2^4 is called a spacelike, a timelike or a null (lightlike), if respectively holds $g(v, v) > 0$, $g(v, v) < 0$ or $g(v, v) = 0$ and $v \neq 0 = (0, 0, 0, 0)$. The norm of a vector v is given by $\|v\| = \sqrt{|g(v, v)|}$. Two vectors v and w in \mathbb{E}_2^4 are said to be orthogonal, if $g(v, w) = 0$.

An arbitrary curve $\alpha = \alpha(s)$ in \mathbb{E}_2^4 can locally be spacelike, timelike or null, if respectively all of its velocity $\alpha'(s)$ are spacelike, timelike or null. Spacelike or timelike curve $\alpha(s)$ is said to be parametrized by arclength functions s , if $g(\alpha'(s), \alpha'(s)) = \pm 1$. Let a, b be two spacelike vectors in \mathbb{E}_2^4 , then, there is unique real number $0 \leq \delta \leq \pi$, called angle between a and b , such that $g(a, b) = \|a\| \|b\| \cos \delta$.

We also recall that the pseudosphere S_2^3 and the pseudohyperbolic space H_1^3 are the hyperquadrics in \mathbb{E}_2^4 , defined respectively by:

$$\begin{aligned} S_2^3(c, r) &= \{ \alpha \in \mathbb{E}_2^4 : g(\alpha - c, \alpha - c) = r^2 \}, \\ H_1^3(c, -r) &= \{ \alpha \in \mathbb{E}_2^4 : g(\alpha - c, \alpha - c) = -r^2 \}, \end{aligned}$$

where center c and radius $r \in \mathbb{R}^+$ [1].

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Let $a = (a_1, a_2, a_3, a_4)$, $b = (b_1, b_2, b_3, b_4)$ and $c = (c_1, c_2, c_3, c_4)$ be vectors in \mathbb{E}_2^4 . The vector product in \mathbb{E}_2^4 is defined with the determinant

$$a\Lambda b\Lambda c = - \begin{vmatrix} -e_1 & -e_2 & e_3 & e_4 \\ a_1 & a_2 & a_3 & a_4 \\ b_1 & b_2 & b_3 & b_4 \\ c_1 & c_2 & c_3 & c_4 \end{vmatrix},$$

where e_1, e_2, e_3 , and e_4 are coordinate direction vectors. Also, Frenet apparatus of a partially null curve in \mathbb{E}_2^4 are

$$T = \alpha'(s), \quad N(s) = \frac{\alpha''(s)}{\|\alpha''(s)\|}, \quad B_2 = \frac{T\Lambda N\Lambda\alpha'''}{\|T\Lambda N\Lambda\alpha'''\|}, \quad B_1 = N\Lambda T\Lambda B_2$$

[4]

2. A PARTIALLY NULL CURVE IN \mathbb{E}_2^4

Denote by $\{T(s), N(s), B_1(s), B_2(s)\}$ the moving Frenet frame along the curve $\alpha = \alpha(s)$ in \mathbb{E}_2^4 . Then T, N, B_1, B_2 are, respectively, the tangent, the principal normal, the first binormal and the second binormal vector fields. Recall that spacelike curve with timelike principal normal and a null first and second binormal is called a partially null curve in \mathbb{E}_2^4 . Then for a partially null curve α in \mathbb{E}_2^4 , the following Frenet equations are given in [3]

$$\left\{ \begin{array}{l} T'(s) = k_1(s)N(s), \\ N'(s) = k_1(s)T(s) + k_2(s)B_1(s), \\ B_1'(s) = k_3(s)B_1(s), \\ B_2'(s) = -\varepsilon_2 k_2(s)N(s) - k_3(s)B_2(s). \end{array} \right\} \quad (2.1)$$

where T, N, B_1 and B_2 are mutually orthogonal vectors satisfying equations

$$\left\{ \begin{array}{l} g(T, T) = \varepsilon_1 = \pm 1, \quad g(N, N) = \varepsilon_2 = \pm 1, \quad \text{whereby } \varepsilon_1\varepsilon_2 = -1, \\ g(B_1, B_2) = 1, \quad g(B_1, B_1) = g(B_2, B_2) = 0, \\ g(T, N) = g(T, B_1) = g(T, B_2) = g(N, B_1) = g(N, B_2) = 0. \end{array} \right\} \quad (2.2)$$

And here,

$$\left\{ \begin{array}{l} k_1(s) = g(T'(s), N(s))\varepsilon_2, \\ k_2(s) = g(N'(s), B_2(s)), \\ k_3(s) = g(B_1'(s), B_2(s)) \end{array} \right\}$$

are first, second and third curvature of the curve α , respectively. In the sequel, in [3] prove that $k_3(s) = 0$ for each s . Consequently, there are only two curvatures $k_1(s)$ and $k_2(s)$ in this case. Thus, Frenet equations are as follows:

$$\left\{ \begin{array}{l} T'(s) = k_1(s)N(s), \\ N'(s) = k_1(s)T(s) + k_2(s)B_1(s), \\ B_1'(s) = 0, \\ B_2'(s) = -\varepsilon_2 k_2(s)N(s). \end{array} \right\} \quad (2.3)$$

Theorem 1. [3] Let α be a partially null curve in \mathbb{E}_2^4 . $\{T, N, B_1, B_2\}$ is the Frenet frame of α . T, N, B_1, B_2 are, respectively, the tangent, the principal normal, the first binormal and the second binormal vector fields. Then

$$\left\{ \begin{array}{l} g(T', T) = g(N', N) = g(B_1', B_1) = g(B_2', B_2) = 0, \\ g(T', N) = -g(N', T), \\ g(T', B_1) = -g(T, B_1'), \\ g(N', B_1) = -g(N, B_1'), \\ g(B_1', B_2) = -g(B_1, B_2'), \\ g(T, B_2') = -g(T', B_2), \\ g(N', B_2) = -g(N, B_2'). \end{array} \right. \quad (2.4)$$

Theorem 2. Let α be a partially null curve in \mathbb{E}_2^4 with curvatures $k_1(s) \neq 0$, $k_2(s) \neq 0$ and $k_3(s) = 0$ for each s . $\{T, N, B_1, B_2\}$ is the Frenet frame of α . T, N, B_1, B_2 are, respectively, the tangent, the principal normal, the first binormal and the second binormal vector fields. Then

$$\left\{ \begin{array}{l} g(T', T) = g(T', B_1) = g(T', B_2) = g(N', B_1) = g(N', N) = 0, \\ g(B_1', T) = g(B_1', N) = g(B_1', B_1) = g(B_1', B_2) = 0, \\ g(B_2', T) = g(B_2', B_1) = g(B_2', B_2) = 0, \\ g(T', N) = \varepsilon_2 k_1, \\ g(N', T) = \varepsilon_1 k_1, \\ g(N', B_2) = -g(B_2', N). \end{array} \right. \quad (2.5)$$

Corollary 1. There is only one curvature k_1 in a previous theorem.

Corollary 2. i) If $\varepsilon_2 = 1$, then $g(T', N) = k_1$.

ii) If $\varepsilon_2 = -1$, then $g(T', N) = -k_1$.

iii) If $\varepsilon_1 = 1$, then $g(N', T) = k_1$.

iv) If $\varepsilon_1 = -1$, then $g(N', T) = -k_1$.

Theorem 3. Let α be a partially null curve in \mathbb{E}_2^4 with curvatures $k_1(s) \neq 0$, $k_2(s) \neq 0$ and $k_3(s) = 0$ for each s . $\{T, N, B_1, B_2\}$ is the Frenet frame of α . T, N, B_1, B_2 are, respectively, the tangent, the principal normal, the first binormal and the second binormal vector fields. Then

$$\left\{ \begin{array}{l} g(T'', N) = g(T'', B_1) = g(N'', T) = g(N'', B_1) = g(N'', B_2) = 0, \\ g(B_1'', T) = g(B_1'', N) = g(B_1'', B_1) = g(B_1'', B_2) = g(B_2'', N) = g(B_2'', B_1) = 0, \\ g(T'', T) = -\varepsilon_2 k_1^2, \\ g(T'', B_2) = g(B_2'', T) = k_1 k_2, \\ g(N'', N) = -\varepsilon_1 k_1^2, \\ g(B_2'', B_2) = -\varepsilon_2 k_2^2. \end{array} \right.$$

Proof. By using Equations (2.2), (2.3) and (2.5), we obtain the proof of the theorem. \square

Corollary 3. There are only two curvatures k_1 and k_2 in a previous theorem.

Corollary 4. *i) If $\varepsilon_2 = 1$ then $g(T'', T) = -k_1^2$ and $g(B_2'', B_2) = -k_2^2$.
 ii) If $\varepsilon_2 = -1$ then $g(T'', T) = k_1^2$ and $g(B_2'', B_2) = k_2^2$.
 iii) If $\varepsilon_1 = 1$, then $g(N'', N) = -k_1^2$.
 iv) If $\varepsilon_1 = -1$, then $g(N'', N) = k_1^2$.*

3. A HYPERBOLIC PARTIALLY NULL CURVE IN \mathbb{E}_2^4

Theorem 4. [2] *A partially null unit speed curve $\alpha(s)$ in \mathbb{E}_2^4 with curvatures $k_1 \neq 0$, $k_2 \neq 0$ for each $s \in I \subset \mathbb{R}$ has $k_3 = 0$ for each s .*

Theorem 5. [2] *Let $\alpha = \alpha(s)$ be a unit speed partially null curve in \mathbb{E}_2^4 with curvatures $k_1 \neq 0$, $k_2 \neq 0$ for each s . If α lies on \mathbb{S}_2^3 Lorentzian hypersphere, then*

$$\frac{1}{k_2} \frac{d}{ds} \left(\frac{1}{k_1} \right) = \text{constant}.$$

Theorem 6. *Let $\alpha = \alpha(s)$ be a partially null curve in \mathbb{E}_2^4 with curvatures $k_1 \neq 0$, $k_2 \neq 0$ and $k_3 = 0$ for each $s \in I \subset \mathbb{R}$. If α lies on a pseudohyperbolic space $\mathbb{H}_1^3(c, -r)$, then*

$$k_1 = \frac{\varepsilon_2}{r} = \text{constant}; \text{ if } \varepsilon_2 = 1,$$

where radius $r \in \mathbb{R}^+$ and with center c in \mathbb{E}_2^4 .

Proof. Let us suppose that $\alpha = \alpha(s)$ lies on \mathbb{H}_1^3 with center c . By the definition, we have

$$g(\alpha - c, \alpha - c) = -r^2, \quad (3.1)$$

for every $s \in I \subset \mathbb{R}$. Differentiating (3.1), four times with respect to s and using Frenet equations, we have, respectively,

$$\begin{cases} g(T, \alpha - c) = 0, \\ g(N, \alpha - c) = -\frac{\varepsilon_1}{k_1}, \\ g(B_1, \alpha - c) = 0, \\ g(B_2, \alpha - c) = 0. \end{cases}$$

Let us decompose $\alpha - c$ by

$$\alpha - c = -\frac{\varepsilon_1}{k_1} N.$$

Finally, if we calculate

$$g(\alpha - c, \alpha - c) = -r^2,$$

we easily obtain

$$k_1 = \frac{\varepsilon_2}{r} = \text{constant},$$

where is $\varepsilon_2 = 1$. □

Corollary 5. *If α is a spacelike curve, that is, $\varepsilon_2 = 1$ then $k_1 = \frac{1}{r}$.*

4. HARMONIC CURVATURES OF A PARTIALLY NULL CURVE IN \mathbb{E}_2^4

Definition 1. [6] Let α be a partially null curve in \mathbb{E}_2^4 . The harmonic functions

$$H_j : I \longrightarrow \mathbb{R} \quad , \quad j = 0, 1$$

defined by

$$\left\{ \begin{array}{l} H_0 = 0, \quad H_1 = \frac{k_1}{k_2}, \quad (k_2 \neq 0), \end{array} \right.$$

are called the harmonic curvatures of α . Here, k_1 and k_2 are Frenet curvatures of α .

Now, the Theorem 2 and the Theorem 3 can be given in terms of harmonic curvatures as follows:

Theorem 7. Let α be a partially null curve in \mathbb{E}_2^4 . T, N, B_2 are, respectively, the tangent, the principal normal and the second binormal vector fields. Then

$$\left\{ \begin{array}{l} g(T', N) = \varepsilon_2 k_2 H_1, \quad g(T'', T) = -\varepsilon_2 k_2^2 H_1^2, \quad g(B_2'', B_2) = -\varepsilon_2 \frac{k_1^2}{H_1^2}, \\ g(N', T) = \varepsilon_1 k_2 H_1, \quad g(N'', N) = -\varepsilon_1 k_2^2 H_1^2, \quad g(T'', B_2) = g(B_2'', T) = k_2^2 H_1, \end{array} \right.$$

where k_1, k_2 are curvatures and H_1 is harmonic curvature of the curve α .

Proof. By using the definition of the harmonic curvatures, we obtain the proof of the theorem. \square

Corollary 6. *i)* If $\varepsilon_1 = 1$ then $g(N', T) = k_2 H_1$ and $g(N'', N) = -k_2^2 H_1^2$.
ii) If $\varepsilon_1 = -1$ then $g(N', T) = -k_2 H_1$ and $g(N'', N) = k_2^2 H_1^2$.
iii) If $\varepsilon_2 = 1$, then

$$g(T', N) = k_2 H_1, \quad g(T'', T) = -k_2^2 H_1^2, \quad g(B_2'', B_2) = -\frac{k_1^2}{H_1^2}.$$

iv) If $\varepsilon_2 = -1$, then

$$g(T', N) = -k_2 H_1, \quad g(T'', T) = k_2^2 H_1^2, \quad g(B_2'', B_2) = \frac{k_1^2}{H_1^2}.$$

Theorem 8. Let α be a partially null curve in \mathbb{E}_2^4 where $\{T, N, B_1, B_2\}$ is the Frenet frame of α and k_1, k_2, k_3 are curvatures of α . If $k_1 \neq 0, k_2 \neq 0$ and $k_3 = 0$ then

$$\nabla_T^4 T - k_1^4 T - \frac{k_1^4}{H_1} B_1 = 0,$$

where $\nabla_T T = T'$ and ∇ is the Levi-Civita connection of \mathbb{E}_2^4 .

Proof. Since $k_3 = 0$, from Equation (2.3), we have

$$\nabla_T T = k_1 N \implies \nabla_T^2 T = k_1 \nabla_T N \implies \nabla_T^3 T = k_1 \nabla_T^2 N \implies \nabla_T^4 T = k_1 \nabla_T^3 N.$$

Since

$$\nabla_T N = k_1 T + k_2 B_1,$$

$$\nabla_T^2 N = k_1^2 N,$$

we have

$$\nabla_T^3 N = k_1^3 T + k_1^2 k_2 B_1.$$

In that case

$$\nabla_T^4 T = k_1 \nabla_T^3 N = k_1^4 T + k_1^3 k_2 B_1.$$

Thus we have

$$\nabla_T^4 T - k_1^4 T - \frac{k_1^4}{H_1} B_1 = 0,$$

where $k_2 = \frac{k_1}{H_1}$.

□

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