# Generalized empirical likelihood inference in partially linear errors-in-variables models with longitudinal data 

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#### Abstract

This article is concerned with estimations for longitudinal partial linear models with covariate that is measured with error. We propose a generalized empirical likelihood method by combining correction attenuation and quadratic inference functions. The method takes into account the within-subject correlation without involving direct estimation of nuisance parameters in the correlation matrix. We define a generalized empirical likelihood-based statistic for the regression coefficients and residual adjusted empirical likelihood for the baseline function. The empirical log-likelihood ratios are proven to be asymptotically chisquared, and the corresponding confidence regions are then constructed. Compared with methods based on normal approximations, the generalized empirical likelihood does not require consistent estimators for the asymptotic variance and bias. Furthermore, a simulation study is conducted to evaluate the performance of the proposed method.


Keywords: Longitudinal Data, Generalized Empirical Likelihood, Confidence Region, Measurement Error, Partially Linear Model.

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## 1. Introduction

Longitudinal data analysis has attracted considerable research interest and a large number of inference methods have been proposed in the literature. Consider data from $n$ subjects with $n_{i}$ observations in the $i$ th subject $(i=1, \ldots, n)$ for a total of $N=\sum_{i=1}^{n} n_{i}$. Let $Y_{i j}$ and $X_{i j}, T_{i j}$ respectively be the response variable and the covariates of the $j$ th observation $\left(j=1, \ldots, n_{i}\right)$ in the $i$ th , where $X_{i j}$ is a $p \times 1$ vector and $T_{i j}$ is a scalar or time. Zeger and Diggle [28] proposed a semiparametric regression model of the form

$$
\begin{equation*}
Y_{i j}=X_{i j}^{T} \beta+g\left(T_{i j}\right)+\varepsilon_{i j}, \quad i=1, \ldots, n, j=1, \ldots, n_{i} . \tag{1.1}
\end{equation*}
$$

where $\beta$ is a $p \times 1$ vector of unknown regression coefficients associated with covariate $X_{i j}$, $g(t)$ is an unknown smooth function, $\varepsilon_{i j}$ is random error with $E\left(\varepsilon_{i j} \mid X_{i j}, T_{i j}\right)=0$ and $\sigma_{\varepsilon}^{2}(t)=E\left(\varepsilon_{i j}^{2} \mid T_{i j}=t\right)$. We assume, without loss of generality, that $T_{i j}$ are all scaled into closed interval $[0,1]$. We assume further that the observations from different subjects are independent.
Model (1.1) is especially useful for longitudinal data analysis as the level of response often depends on time in a nonlinear pattern. Many authors have studied models in the form of (1.1), see for example, He et al. [8], You et al. [27] and Xue and Zhu [24], among others. Zeger and Diggle [28] used a semiparametric mixed model to analyse the CD4 cell numbers in HIV seroconverters where $g(t)$ is estimated by a kernel smoother. A major aspect of longitudinal data is the within-subject correlation among the repeated measurements. Ignoring this within-subject correlation causes a loss of efficiency in general problems. Using a working correlation matrix with a small set of nuisance parameters $\alpha$, the generalized estimating equations (GEE) estimator of the regression coefficients proposed by Liang and Zeger [13] are consistent even when the working correlation structure is misspecified. However, Crowder [4] established that there are difficulties with estimating the nuisance parameters $\alpha$ and that in some simple cases, consistent estimators of $\alpha$ do not always exist. To avoid the drawback, Qu et al. [18] introduced a method of quadratic inference functions (QIF). It avoids estimating the nuisance correlation structure parameters by assuming that the inverse of working correlation matrix can be approximated by a linear combination of several known basis matrices. The QIF can efficiently take the within-cluster correlation into account and is more efficient than the GEE approach when the working correlation is misspecified. Bai et al. [2] extended the QIF method to the semiparametric partial linear model. Dziak et al. [6] gave an overview on QIF approaches for longitudinal data. Owen [15] introduced a nonparametric method of inference - an empirical likelihood (EL) mathod. The EL uses only the data to determine the shape and orientation of a confidence region and does not use the estimator of the asymptotic covariance. Hence, EL is indeed appealing for the construction of confidence region.
Owen [17] provided a comprehensive account of empirical likelihood and its properties. For longitudinal data, You et al. [27] constructed a block empirical likelihood method for partially linear regression models with longitudinal data. Xue and Zhu [24] considered the same model, and they provided the EL inference for the baseline function as well as the regression coefficients.
In many practical situations, there often exist covariate measurement errors. Some recently related works include Cui and Chen [5], Liang et al. [11], Liu [14], and Zhao and Xue [29], among others. Zhao and Xue [29] investigated empirical likelihood inferences for semiparametric varying-coefficient partially linear EV models. Liu [14] considered the asymptotic normality for the partially linear EV models with longitudinal data. Yang et al. [26] investigated the empirical likelihood of varying coefficient errors-in-variables models with longitudinal. A common feature of these articles is that the data dependence
within each subject is not taken into consideration. To consider the within correlation, Tian et al. [22] proposed a generalized empirical likelihood (GEL) method by combining quadratic inference functions for generalized linear model with longitudinal data. Tian et al. [21] discussed the variable selection for the partial linear EV model with longitudinal data when some covariates are measured with errors.
We propose a modified generalized empirical log-likelihood ratio function for the regression coefficients and a residual-adjusted empirical likelihood for the baseline function, the empirical log-likelihood ratios are proven to be asymptotically chi-squared. The following three desired features are worth mentioning. First, the method directly incorporates within-subject correlation into model building, but does not require estimation of the nuisance parameters associated with the correlation. Second, the modified generalized empirical log-likelihood ratio function eliminate the effects of measurement errors on parameter estimation. Third, by using the residual adjusted EL ratio, undersmoothing for estimating the baseline function is avoided.
The outline of this paper is organized as follows. In Section 2, we define a generalized empirical log-likelihood ratio for regression coefficients and investigate its asymptotic properties. In Section 3, we discuss the empirical likelihood inference for nonparametric function. In Section 4, we conduct a simulation study to compare the finite sample properties of these suggested estimators. We also apply our method to analyze an AIDS clinical trial dataset in Section 5. The proofs of theorems appear in the Appendix.

## 2. Empirical likelihood for the regression coefficients

2.1. Known measurement error covariance matrix. For model (1.1), the covariates $X_{i j}$ are not always observable without error. If $X_{i j}$ are measured with error, instead of observing $X_{i j}$, we observe

$$
\begin{equation*}
W_{i j}=X_{i j}+U_{i j} . \tag{2.1}
\end{equation*}
$$

where $U_{i j}, i=1, \ldots, n, j=1, \ldots, n_{i}$, are measurement errors. As in Liang et al. [11], we assume that $U_{i j}$ are independent and identically distributed, independent of $\left\{Y_{i j}, X_{i j}, T_{i j}, \varepsilon_{i j}\right\}$. Although this assumption is not the weakest possible condition, it is imposed to facilitate the technical proofs, and it can be satisfied in many applications. We suppose that $E\left(U_{i j}\right)=0, \quad \operatorname{cov}\left(U_{i j}\right)=\Sigma_{u}$.
From the model (1.1), we have $E\left(Y_{i j} \mid T_{i j}\right)=E\left(X_{i j}^{T} \mid T_{i j}\right) \beta+g\left(T_{i j}\right)$. For the sake of descriptive convenience, we denote $Y_{i}=\left(Y_{i 1}, Y_{i 2}, \ldots, Y_{i n_{i}}\right)^{T}$, and $X_{i}, U_{i}, T_{i}, W_{i}$ in a similar fashion. $g\left(T_{i}\right)=\left(g\left(T_{i 1}\right) \ldots, g\left(T_{i n_{i}}\right)\right)^{T}, m_{X}(t)=E\left(X_{i j} \mid T_{i j}=t\right), m_{Y}(t)=E\left(Y_{i j} \mid T_{i j}=t\right)$, $m_{W}(t)=E\left(W_{i j} \mid T_{i j}=t\right), \tilde{Y}_{i}=\varphi\left(T_{i j}\right)\left(Y_{i}-m_{Y}\left(T_{i}\right)\right), \tilde{X}_{i}=\varphi\left(T_{i j}\right)\left(X_{i}-m_{X}\left(T_{i}\right)\right)$, $\tilde{W}_{i}=\varphi\left(T_{i j}\right)\left(W_{i}-m_{W}\left(T_{i}\right)\right)$, where $\varphi(\cdot)$ is a bounded nonnegative weight function with a compact support $[a, b] \in[0,1]$. Motivated by Liang et al. [11], we construct the modified generalized auxiliary random vectors

$$
\begin{equation*}
Z_{i}(\beta)=\tilde{W}_{i}^{T} V_{i}^{-1}\left(\tilde{Y}_{i}-\tilde{W}_{i} \beta\right)+E\left(U_{i}^{T} V_{i}^{-1} U_{i}\right) \beta \tag{2.2}
\end{equation*}
$$

where $V_{i}$ is an arbitrarily specified working covariance matrix with nuisance parameters $\alpha$. Following Liang and Zeger [13], the matrix $V_{i}$ is often modeled as $A_{i}^{1 / 2} R(\alpha) A_{i}^{1 / 2}$, where $A_{i}=\operatorname{diag}\left\{\operatorname{var}\left(Y_{i 1}\right), \ldots, \operatorname{var}\left(Y_{i n_{i}}\right)\right\}, R(\alpha)$ is some working correlation which involves a small number of nuisance parameters $\alpha$. By Qu et al. [18], we model the inverse of the working correlation $R^{-1}(\alpha)$ by the class of matrices

$$
\begin{equation*}
\sum_{k=1}^{s} a_{k} M_{k} \tag{2.3}
\end{equation*}
$$

where $M_{1}, \ldots, M_{s}$ are known matrices and $a_{1}, \ldots, a_{s}$ are unknown constants. This is a sufficiently rich class that accommodates, or at least approximates, the correlation structures most commonly used. Substituting (2.3) to (2.2) and using the idea of QIF, we need not to find the estimators of parameters $a=\left(a_{1}, a_{2}, \ldots, a_{s}\right)$ by optimizing some function of the information matrix. Instead, we define the "extend" generalized auxiliary random vectors

$$
\tilde{Z}_{i}(\beta)=\left(\begin{array}{c}
\tilde{W}_{i}^{T} A_{i}^{-1 / 2} M_{1} A_{i}^{-1 / 2}\left(\tilde{Y}_{i}-\tilde{W}_{i} \beta\right)+D_{i}^{(1)} \beta  \tag{2.4}\\
\vdots \\
\tilde{W}_{i}^{T} A_{i}^{-1 / 2} M_{s} A_{i}^{-1 / 2}\left(\tilde{Y}_{i}-\tilde{W}_{i} \beta\right)+D_{i}^{(s)} \beta
\end{array}\right)
$$

where $D_{i}^{(k)}=E\left(U_{i}^{T} A_{i}^{-1 / 2} M_{k} A_{i}^{-1 / 2} U_{i}\right), k=1, \ldots, s$. Note that $E\left(\tilde{Z}_{i}(\beta)\right)=0$ if $\beta$ is the true parameter. Therefore, using such information, we can define a generalized empirical $\log$-likelihood ratio function $l(\beta)$. If $\beta$ is the true parameter, $l(\beta)$ can be shown to be asymptotically distributed as a chi-square with $p s$ degrees of freedom.
However, the formula above cannot be applied directly, because $m_{Y}\left(T_{i}\right), m_{W}\left(T_{i}\right)$ are unknown. Using kernel estimate method, the estimators of $m_{Y}\left(T_{i}\right)$ and $m_{W}\left(T_{i}\right)$ are, respectively, defined by

$$
\begin{equation*}
\hat{m}_{W}(t)=\sum_{i=1}^{n} \sum_{j=1}^{n_{i}} \omega_{i j}(t) W_{i j}, \hat{m}_{Y}(t)=\sum_{i=1}^{n} \sum_{j=1}^{n_{i}} \omega_{i j}(t) Y_{i j} \tag{2.5}
\end{equation*}
$$

where

$$
\begin{equation*}
\omega_{i j}(t)=K_{h}\left(T_{i j}-t\right) / \sum_{k=1}^{n} \sum_{l=1}^{n_{i}} K_{h}\left(T_{k l}-t\right) \tag{2.6}
\end{equation*}
$$

$h$ is a bandwidth, $K(\cdot)$ is a kernel function and $K_{h}(\cdot)=K(\cdot / h)$. Therefore, an estimator of $Z_{i}(\beta)$,

$$
\hat{Z}_{i}(\beta)=\left(\begin{array}{c}
\hat{W}_{i}^{T} A_{i}^{-1 / 2} M_{1} A_{i}^{-1 / 2}\left(\hat{Y}_{i}-\hat{W}_{i} \beta\right)+D_{i}^{(1)} \beta  \tag{2.7}\\
\vdots \\
\hat{W}_{i}^{T} A_{i}^{-1 / 2} M_{s} A_{i}^{-1 / 2}\left(\hat{Y}_{i}-\hat{W}_{i} \beta\right)+D_{i}^{(s)} \beta
\end{array}\right)
$$

where $\hat{Y}_{i}=\varphi\left(T_{i}\right)\left(Y_{i}-\hat{m}_{Y}\left(T_{i}\right)\right)$, and $\hat{W}_{i}=\varphi\left(T_{i}\right)\left(W_{i}-\hat{m}_{W}\left(T_{i}\right)\right)$. Then a modified generalized empirical log-likelihood ratio function for $\beta$ is defined as

$$
\begin{equation*}
\hat{l}(\beta)=-2 \max _{p_{1}, \ldots, p_{n}}\left\{\sum_{i=1}^{n} \log \left(n p_{i}\right) \mid p_{i} \geq 0, \sum_{i=1}^{n} p_{i}=1, \sum_{i=1}^{n} p_{i} \hat{Z}_{i}(\beta)=0\right\} \tag{2.8}
\end{equation*}
$$

For any given $\beta$, a unique value for $\hat{l}(\beta)$ exists, we assume that 0 is inside the convex hull of the points $\left(\hat{Z}_{1}(\beta), \ldots, \hat{Z}_{n}(\beta)\right)$ (Owen, [15]). By the Lagrange multiplier method, $\hat{l}(\beta)$ can be represented as

$$
\begin{equation*}
\hat{l}(\beta)=2 \sum_{i=1}^{n} \log \left(1+\lambda^{T} \hat{Z}_{i}(\beta)\right) \tag{2.9}
\end{equation*}
$$

where $\lambda=\lambda(\beta)$ is a $p s \times 1$ vector that solves

$$
\begin{equation*}
\frac{1}{n} \sum_{i=1}^{n} \frac{\hat{Z}_{i}(\beta)}{1+\lambda^{T} \hat{Z}_{i}(\beta)}=0 \tag{2.10}
\end{equation*}
$$

The following Theorem 2.1 gives that $\hat{l}(\beta)$ is asymptotically distributed as a chi-square with $p s$ degrees of freedom.
2.1. Theorem. Suppose that the regularity conditions $C 1-C 6$ in the Appendix hold. If $\beta$ is the true parameter, then

$$
\hat{l}(\beta) \xrightarrow{\mathcal{L}} \chi_{p s}^{2},
$$

where $\xrightarrow{\mathcal{L}}$ represents the convergence in distribution, and $\chi_{p s}^{2}$ means the chi-square distribution with ps degrees of freedom.

Let $\chi_{p s}^{2}(1-\alpha)$ be the $1-\alpha$ quantile of $\chi_{p s}^{2}$ for any $0<\alpha<1$. By using Theorem 2.1, we obtain an approximate $1-\alpha$ confidence region for $\beta$, defined by

$$
C_{\alpha}(\beta)=\left\{\beta \mid \hat{l}(\beta) \leq \chi_{p s}^{2}(1-\alpha)\right\} .
$$

We may maximize $\{-\hat{l}(\beta)\}$ to obtain an estimator of the parameter $\beta$, say $\hat{\beta}$, called as the generalized maximum empirical likelihood estimator (GMELE). Denote

$$
\begin{align*}
& \Gamma=\lim _{n \rightarrow \infty} \frac{1}{n} \sum_{i=1}^{n} E\left(\begin{array}{c}
\tilde{X}_{i}^{T} A_{i}^{-1 / 2} M_{1} A_{i}^{-1 / 2} \tilde{X}_{i} \\
\vdots \\
\tilde{X}_{i}^{T} A_{i}^{-1 / 2} M_{s} A_{i}^{-1 / 2} \tilde{X}_{i}
\end{array}\right),  \tag{2.11}\\
& \Sigma=\left(\begin{array}{c}
\Sigma_{11} \cdots \Sigma_{1 s} \\
\vdots \ddots \vdots \\
\Sigma_{s 1} \cdots \Sigma_{s s}
\end{array}\right),
\end{align*}
$$

where for $k, m=1, \ldots, s$,

$$
\begin{aligned}
\Sigma_{k m}= & \lim _{n \rightarrow \infty} \frac{1}{n} \sum_{i=1}^{n}\left\{E\left[\left(X_{i}-m_{X}\left(T_{i}\right)\right)^{T} \Psi_{i} A_{i}^{-1 / 2} M_{k} A_{i}^{-1 / 2}\left(\Psi_{i} \varepsilon_{i}-U_{i} \beta\right)\right]\right. \\
& {\left[\left(X_{i}-m_{X}\left(T_{i}\right)\right)^{T} \Psi_{i} A_{i}^{-1 / 2} M_{m} A_{i}^{-1 / 2}\left(\Psi_{i} \varepsilon_{i}-U_{i} \beta\right)\right]^{T} } \\
& +E\left(U_{i}^{T} A_{i}^{-1 / 2} M_{k} A_{i}^{-1 / 2} \Psi_{i} \varepsilon_{i}\right)\left(U_{i}^{T} A_{i}^{-1 / 2} M_{m} A_{i}^{-1 / 2} \Psi_{i} \varepsilon_{i}\right)^{T} \\
& +E\left(-U_{i} A_{i}^{-1 / 2} M_{k} A_{i}^{-1 / 2} U_{i} \beta+D_{i}^{(k)} \beta\right) \\
& \left(-U_{i} A_{i}^{-1 / 2} M_{m} A_{i}^{-1 / 2} U_{i} \beta+D_{i}^{(m)} \beta\right)^{T} .
\end{aligned}
$$

where $\Psi_{i}=\operatorname{diag}\left\{\psi\left(T_{i 1}\right), \cdots, \psi\left(T_{i n_{i}}\right)\right\}$. If the matrix $\Sigma$ and $\Gamma^{T} \Sigma^{-1} \Gamma$ are invertible, then we can obtain the asymptotic normality for $\hat{\beta}$ in the following Theorem.
2.2. Theorem. Suppose that the regularity conditions $C 1-C 6$ in the Appendix hold. Then when $n \rightarrow \infty$, we have

$$
\sqrt{n}(\hat{\beta}-\beta) \xrightarrow{\mathcal{L}} N\left(0, \Sigma_{\beta}\right),
$$

where $\Sigma_{\beta}=\left[\Gamma^{T} \Sigma^{-1} \Gamma\right]^{-1}$.
To apply Theorem 2.2 to construct the confidence region of $\beta$, we give the consistent estimator of $\Sigma_{\beta}$, say $\hat{\Sigma}_{\beta}=\left[\hat{\Gamma}^{T} \hat{\Sigma}^{-1} \hat{\Gamma}\right]^{-1}$, where

$$
\begin{align*}
& \hat{\Gamma}=\frac{1}{n} \sum_{i=1}^{n}\left(\begin{array}{c}
\hat{W}_{i}^{T} A_{i}^{-1 / 2} M_{1} A_{i}^{-1 / 2} \hat{W}_{i}-D_{i}^{(1)} \\
\vdots \\
\hat{W}_{i}^{T} A_{i}^{-1 / 2} M_{s} A_{i}^{-1 / 2} \hat{W}_{i}-D_{i}^{(s)}
\end{array}\right)  \tag{2.13}\\
& \hat{\Sigma}=\frac{1}{n} \sum_{i=1}^{n} \hat{Z}_{i}(\beta) \hat{Z}_{i}(\beta)^{T} \tag{2.14}
\end{align*}
$$

Therefore, by Theorem 2.2, we have

$$
\begin{equation*}
\hat{\Sigma}_{\beta}^{-1 / 2} \sqrt{n}(\hat{\beta}-\beta) \xrightarrow{\mathcal{L}} N\left(0, I_{p}\right), \tag{2.15}
\end{equation*}
$$

where $I_{p}$ is an identity matrix of order $p$. Using Theorem 10.2d in Arnold [1] to obtain

$$
\begin{equation*}
(\hat{\beta}-\beta)^{T} n \hat{\Sigma}_{\beta}^{-1}(\hat{\beta}-\beta) \xrightarrow{\mathcal{L}} \chi_{p}^{2} . \tag{2.16}
\end{equation*}
$$

Therefore, the confidence region of $\beta$ can be constructed by using (2.15) or (2.16).
2.2. Estimated measurement error covariance matrix. Generally, the covariance matrix $\Sigma_{u}$ is unkown and must be estimated. We further assume longitudinal data is a balance data, that is $n_{i}=m$. For unbalanced data, we can use the multiple groups analysis (Shao et al. [20]). The usual method of doing so (Carroll et al. [3], Ch3) is by partial replication, so that we observe $W_{i}^{(r)}=X_{i}+U_{i}^{(r)}, \quad r=1, \ldots, m_{i}$. For notation convenience, we consider here only the case that $m_{i}=2$. Let $\bar{W}_{i}$ is the sample mean of the replicates, and $\bar{U}_{i}$ in a similar fashion. Then a consistent, unbiased moments estimator for $D_{i}^{(k)}$ is

$$
\begin{equation*}
\hat{D}_{i}^{(k)}=n^{-1} \sum_{i=1}^{n} \sum_{r=1}^{2}\left(W_{i}^{(r)}-\bar{W}_{i}\right)^{T} A_{i}^{-1 / 2} M_{k} A_{i}^{-1 / 2}\left(W_{i}^{(r)}-\bar{W}_{i}\right), \tag{2.17}
\end{equation*}
$$

The estimator of $Z_{i}(\beta)$ changes only slightly to accommodate the replicates, becoming

$$
\hat{Z}_{i}^{*}(\beta)=\left(\begin{array}{c}
\hat{\bar{W}}^{T} A_{i}^{-1 / 2} M_{1} A_{i}^{-1 / 2}\left(\hat{Y}_{i}-\hat{\bar{W}} \beta\right)+\hat{D}_{i}^{(1)} \beta / 2  \tag{2.18}\\
\vdots \\
\hat{\bar{W}}^{T} A_{i}^{-1 / 2} M_{s} A_{i}^{-1 / 2}\left(\hat{Y}_{i}-\hat{\bar{W}} \beta\right)+\hat{D}_{i}^{(s)} \beta / 2
\end{array}\right)
$$

where $\hat{\bar{W}}=\psi\left(T_{i}\right)\left(\bar{W}_{i}-\hat{m}_{\bar{W}}\left(T_{i}\right)\right)$ and $\hat{m}_{\bar{W}}\left(T_{i}\right)$ is the kernel estimate of $\hat{m}_{W}\left(T_{i}\right)$ based on the data ( $\bar{W}_{i}, T_{i}$ ). The empirical likelihood ratio function for $\beta$ may be defined as

$$
\begin{equation*}
\hat{l}^{*}(\beta)=-2 \max _{p_{1}, \ldots, p_{n}}\left\{\sum_{i=1}^{n} \log \left(n p_{i}\right) \mid p_{i} \geq 0, \sum_{i=1}^{n} p_{i}=1, \sum_{i=1}^{n} p_{i} \hat{Z}_{i}^{*}(\beta)=0\right\} . \tag{2.19}
\end{equation*}
$$

We may maximize $\left\{-\hat{l}^{*}(\beta)\right\}$ to obtain maximum empirical likelihood estimator $\hat{\beta}^{*}$ of $\beta$. Similarly, we have the following theorem.
2.3. Theorem. Under the general conditions of Theorem 2.1, and $\beta$ is the true parameter, then

$$
\hat{l}^{*}(\beta) \xrightarrow{\mathcal{L}} \chi_{p s}^{2} .
$$

2.4. Theorem. Under the general conditions of Theorem 2.2, the estimator $\hat{\beta}^{*}$ is consistent and asymptotically normal with covariance matrix $\left[\Gamma^{T} \Sigma_{*}^{-1} \Gamma\right]^{-1}$,

$$
\Sigma_{*}=\left(\begin{array}{c}
\Sigma_{* 11} \cdots \Sigma_{* 1 s} \\
\vdots \ddots \vdots \\
\Sigma_{* s 1} \cdots \Sigma_{* s s}
\end{array}\right)
$$

where for $k, m=1, \ldots, s$,

$$
\begin{align*}
\Sigma_{* k m}= & \lim _{n \rightarrow \infty} \frac{1}{n} \sum_{i=1}^{n}\left\{E\left[\left(X_{i}-m_{X}\left(T_{i}\right)\right)^{T} A_{i}^{-1 / 2} M_{k} A_{i}^{-1 / 2}\left(\varepsilon_{i}-\bar{U}_{i} \beta\right)\right]\right. \\
& {\left[\left(X_{i}-m_{X}\left(T_{i}\right)\right)^{T} A_{i}^{-1 / 2} M_{m} A_{i}^{-1 / 2}\left(\varepsilon_{i}-\bar{U}_{i} \beta\right)\right]^{T} } \\
& +E\left(\bar{U}_{i}^{T} A_{i}^{-1 / 2} M_{k} A_{i}^{-1 / 2} \varepsilon_{i}\right)\left(\bar{U}_{i}^{T} A_{i}^{-1 / 2} M_{m} A_{i}^{-1 / 2} \varepsilon_{i}\right)^{T}  \tag{2.20}\\
& +E\left(-\bar{U}_{i} A_{i}^{-1 / 2} M_{k} A_{i}^{-1 / 2} \bar{U}_{i} \beta+\frac{1}{2} D_{i}^{(k)} \beta\right) \\
& \left(-\bar{U}_{i} A_{i}^{-1 / 2} M_{m} A_{i}^{-1 / 2} \bar{U}_{i} \beta+\frac{1}{2} D_{i}^{(m)} \beta\right)^{T} .
\end{align*}
$$

With the replication data, the standard error estimators of $\hat{\beta}^{*}$ can also be derived (Liang, [12]). We omit details here.

## 3. Inference based on empirical likelihood for the nonparametric function

We assume from now on that $t_{0}$ is an interior point of $[0,1]$. Also, we suppose that the time points $T_{i j}, i=1, \ldots, n, j=1, \ldots, n_{i}$, are independent and have identical distribution with common density function $f(t)$. Introduce the following auxiliary random vectors

$$
\begin{equation*}
\hat{\eta}_{i}\left(g\left(t_{0}\right)\right)=\sum_{j=1}^{n_{i}}\left[Y_{i j}-W_{i j}^{T} \hat{\beta}-g\left(t_{0}\right)\right] K_{h}\left(T_{i j}-t_{0}\right) \tag{3.1}
\end{equation*}
$$

An estimated empirical $\log$-likelihood ratio function for $g\left(t_{0}\right)$ can be define by

$$
\begin{equation*}
\tilde{l}\left(g\left(t_{0}\right)\right)=-2 \max _{p_{1}, \ldots, p_{n}}\left\{\sum_{i=1}^{n} \log \left(n p_{i}\right) \mid p_{i} \geq 0, \sum_{i=1}^{n} p_{i}=1, \sum_{i=1}^{n} p_{i} \hat{\eta}_{i}\left(g\left(t_{0}\right)\right)=0\right\} . \tag{3.2}
\end{equation*}
$$

We can also maximize $\left\{-\tilde{l}\left(g\left(t_{0}\right)\right)\right\}$ to obtain the maximum empirical likelihood estimator of $g\left(t_{0}\right)$, says $\hat{g}\left(t_{0}\right)$. It can be proved that

$$
\begin{equation*}
\hat{g}\left(t_{0}\right)=\sum_{i=1}^{n} \sum_{j=1}^{n_{i}} \omega_{i j}\left[Y_{i j}-W_{i j}^{T} \hat{\beta}\right]+o_{P}\left((N h)^{-1 / 2}\right), \tag{3.3}
\end{equation*}
$$

where $\omega_{i j}$ is defined in (2.6). If we define that

$$
\begin{align*}
& b\left(t_{0}\right)=h_{0}^{5 / 2}\left[g^{\prime}\left(t_{0}\right) f^{\prime}\left(t_{0}\right)+(1 / 2) g^{\prime \prime}\left(t_{0}\right) f\left(t_{0}\right)\right] \int_{-1}^{1} u^{2} K(u) d u,  \tag{3.4}\\
& v^{2}\left(t_{0}\right)=\sigma_{\varepsilon, u, \delta}^{2}\left(t_{0}\right) f\left(t_{0}\right) \int_{-1}^{1} K^{2}(u) d u, \tag{3.5}
\end{align*}
$$

where $\sigma_{\varepsilon, u, \delta}^{2}\left(t_{0}\right)=E\left[\left(\varepsilon_{i j}-U_{i j}^{T} \beta\right)^{2} \mid T_{i j}=t_{0}\right]$ and $h_{0}$ is the constant satisfying Condition $C 1$ in the Appendix. The following theorem gives the asymptotical property of $\hat{g}\left(t_{0}\right)$.
3.1. Theorem. Suppose that the regularity conditions $C 1-C 6$ in the Appendix hold, Then

$$
\sqrt{N h}\left[\hat{g}\left(t_{0}\right)-g\left(t_{0}\right)\right]-b\left(t_{0}\right)\left(f\left(t_{0}\right)\right)^{-1} \xrightarrow{\mathcal{L}} N\left(0, \sigma^{2}\left(t_{0}\right)\right),
$$

where $\sigma^{2}\left(t_{0}\right)=v^{2}\left(t_{0}\right)\left(f\left(t_{0}\right)\right)^{-2}, b\left(t_{0}\right)$ and $v^{2}\left(t_{0}\right)$ are defined in (3.4) and (3.5).

Similar to Xue and Zhu [24], we can show that if we substitute Condition $C 1$ in Theorem 3.1, with $N h^{2} / \log N \rightarrow \infty$ and $N h^{5} \rightarrow 0$, that is, if undersmoothing is adopted, then the biased term $b\left(t_{0}\right)$ vanished asymptotically. Denote that

$$
\begin{align*}
& \hat{f}\left(t_{0}\right)=\frac{1}{N h} \sum_{i=1}^{n} \sum_{j=1}^{n_{i}} K_{h}\left(T_{i j}-t_{0}\right),  \tag{3.6}\\
& \hat{v}^{2}\left(t_{0}\right)=\frac{1}{N h} \sum_{i=1}^{n} \hat{\eta}_{i}^{2}\left(\hat{g}\left(t_{0}\right)\right) . \tag{3.7}
\end{align*}
$$

Then, a consistent estimator of $\sigma^{2}\left(t_{0}\right)$ can be given by $\hat{\sigma}^{2}\left(t_{0}\right)=\hat{v}^{2}\left(t_{0}\right) /\left(\hat{f}\left(t_{0}\right)\right)^{2}$.
If we define that

$$
\begin{equation*}
\hat{b}\left(t_{0}\right)=\frac{1}{\sqrt{N h}} \sum_{i=1}^{n} \sum_{j=1}^{n_{i}}\left[\hat{g}\left(T_{i j}\right)-\hat{g}\left(t_{0}\right)\right] K_{h}\left(T_{i j}-t_{0}\right) \tag{3.8}
\end{equation*}
$$

from the Lemma 6.7 in Appendix, $\hat{b}\left(t_{0}\right)$ is a consistent estimator $b\left(t_{0}\right)$. Then, an approximate $1-\alpha$ confidence interval for $g\left(t_{0}\right)$ can be given by

$$
\hat{g}\left(t_{0}\right)-(N h)^{-1 / 2} \hat{b}\left(t_{0}\right)\left(\hat{f}\left(t_{0}\right)\right)^{-1} \pm z_{\alpha / 2}(N h)^{-1 / 2} \hat{\sigma}\left(t_{0}\right)
$$

where $z_{\alpha / 2}$ is the $1-\alpha / 2$ quantile of the standard normal distribution.
Theorem 3.1 together Lemma 6.6 in the Appendix, implies that $\tilde{l}\left(g\left(t_{0}\right)\right)$ is asymptotically non-central chi-squared if optimal bandwidth is used, and this increases the difficulty of the study. In a manner similar to Xue and Zhu [24], we can adjust the weighted residuals $\hat{\eta}_{i}\left\{g\left(t_{0}\right)\right\}$ and then obtain an adjusted empirical likelihood ratio without undersmoothing. Introduce the auxiliary random vectors

$$
\hat{\eta}_{i}^{*}\left\{g\left(t_{0}\right)\right\}=\hat{\eta}_{i}\left\{g\left(t_{0}\right)\right\}-\sum_{j=1}^{n_{i}}\left[\hat{g}\left(T_{i j}\right)-\hat{g}\left(t_{0}\right)\right] K_{h}\left(T_{i j}-t_{0}\right) .
$$

A residual-adjusted generalized empirical likelihood ratio can be defined as

$$
\tilde{l}^{*}\left(g\left(t_{0}\right)\right)=-2 \max \left\{\sum_{i=1}^{n} \log \left(n p_{i}\right) \mid p_{i} \geq 0, \sum_{i=1}^{n} p_{i}=1, \sum_{i=1}^{n} p_{i} \hat{\eta}_{i}^{*}\left(g\left(t_{0}\right)\right)=0\right\}
$$

Then, the asymptotic result of $\tilde{l}^{*}(g(t))$ is stated in the following theorem.
3.2. Theorem. Suppose that the regularity conditions $C 1-C 6$ in the Appendix hold, if $g\left(t_{0}\right)$ is the true value of the baseline function, we have

$$
\tilde{l}^{*}\left(g\left(t_{0}\right)\right) \xrightarrow{\mathcal{L}} \chi_{1}^{2}
$$

Applying Theorem 3.2, the approximate $1-\alpha$ confidence interval for $g(t)$ is defined as $\tilde{I}_{\alpha}\left(g\left(t_{0}\right)\right)=\left\{g(t) \mid \tilde{l}^{*}\left(g\left(t_{0}\right)\right) \leq \chi_{1}^{2}(1-\alpha)\right\}$.

## 4. Simulation studies

We simulated data from the semiparametric regression model

$$
Y_{i j}=X_{1 i j} \beta_{1}+X_{2 i j} \beta_{2}+\sin \left(\pi T_{i j} / 2+\pi / 2\right)+\varepsilon_{i j}, \quad i=1, \ldots, n ; j=1, \ldots, 5,
$$

where $\beta_{1}=\beta_{2}=1, n=100, X_{1 i j} \sim N(1,1), X_{2 i j} \sim N(2,1), T_{i j} \sim U(-1,1)$, and error vector $\varepsilon_{i}=\left(\varepsilon_{i 1}, \ldots, \varepsilon_{i 5}\right)^{T} \sim N\left(0, \sigma^{2} \operatorname{corr}\left(\varepsilon_{i}, \rho\right)\right)$, where $\sigma^{2}=0.6, \rho=0.5$ and $\operatorname{corr}\left(\varepsilon_{i}, \rho\right)$ is a known correlation matrix with parameter $\rho$ used to determine the strength of withsubject dependence. Here we consider $\varepsilon_{i j}$ has the compound symmetry (CS) correlation. Considering the measurement error models $W_{1 i j}=X_{1 i j}+U_{1 i j}, W_{2 i j}=X_{2 i j}+U_{2 i j}$, where $U_{1 i j} \sim N(0,0.04), U_{2 i j} \sim N(0,0.04)$.

For each simulated dataset, we computed the empirical likelihood ratio and the estimators of $\beta$ and $g(t)$. The kernel function was taken to be $K(u)=0.75\left(1-u^{2}\right)_{+}$and the crossvalidation bandwidth $h_{C V}$ was obtained by minimizing

$$
C V(h)=\frac{1}{n} \sum_{i=1}^{n} \sum_{j=1}^{n_{i}}\left\{Y_{i j}-X_{i j}^{T} \hat{\beta}_{[i]}-\hat{g}_{[i]}\left(t_{i j}\right)\right\}^{2},
$$

where $\hat{g}_{[i]}(\cdot)$ and $\hat{\beta}_{[i]}$ are estimators of $g(\cdot)$ and $\beta$ which are computed with all of the measurements but not the $i$ th subject. We experimented with bandwidths around the selected values, and the results did not change significantly. To estimate the variance of $U_{i j}$, we generated duplicate samples of $W_{i j}$.

## FIGURE 1

Figure 1: The averages of $95 \%$ confidence regions for $\left(\beta_{1}, \beta_{2}\right)$.


For the confidence region of $\beta$, two methods were compared: the generalized empirical likelihood (GEL) and the normal approximation (NA) in terms of coverage accuracy and area of the confidence region with 1000 simulation runs. The simulation results are presented in Figure 1. Figure 1 shows that the GEL gives smaller confidence region than the NA method. The coverage probability for the GEL is 0.943 , while that for the NA is 0.939 . This also shows the GEL has higher accuracy than the NA for the confidence region.

Figure 2:The 95\% confidence intervals and coverage probabilities for $g(t)$. The left panel shows the pointwise confidence intervals and the true curve (solid curve) for $g(t)$. The right panel is for coverage probabilities.


Figure 2 depicts the performance of the residual-adjusted GEL and the NA in terms of $95 \%$ pointwise confidence intervals. From Figure 2, the residual-adjusted GEL clearly performs better than the NA because the associated confidence intervals have uinformly higher coverage accuracies and shorter average lengths.

## 5. A real example

We now illustrate the proposed procedures in this paper through analysis of a data set from the Multi-Center AIDS Cohort study. The data set contains the human immunodeficiency virus (HIV) status of 283 homosexual men who were infected with HIV during a follow-up period between 1984 and 1991. The original design was to collect the measurements for all individuals semiannually. More details of the study design and medical implications can be found in Kaslow et al. [10]. Some authors have analyzed the same dataset using varying coefficient and semiparametric models; see for example Wu et al. [23], Huang et al. [9] and Fan and Li [7]. Their analysis aimed to describe the trend of the mean CD4 percentage depletion over time and to evaluate the effects of cigarette smoking, pre-HIV infection CD4 percentage and age at HIV infection on the mean CD4 percentage after the infection. The results of the hypothesis testing of Huang et al. [9] indicate that, at significance level 0.05 , only the baseline function varies over time and preCD4 has a constant effect over time; neither smoking nor age has a significant impact on mean CD4 percentage. This motivates us to use model (1.1) for this dataset.
We considered two covariates: $X_{1 i j}$, the individual's smoking status, which is taken to be 1 if the individual ever smoked cigarettes or 0 if never smoked cigarettes after HIV infection; and $X_{2 i j}$, the centered variable for pre-infection CD4 percentage. For the purpose of demonstration and simplicity, the possible effects of other available covariates are omitted. The response variable $Y\left(t_{i j}\right)$ is the individual's CD4 percentage measured, and both $X_{1 i j}$ and $X_{2 i j}$ are independent. We assume that observation times are independent of covariates because they are not significantly related to the two covariates. The $X_{2 i j}$ are measured with error (Liang et al. [11]), We consider the following semiparametric regression model:

$$
Y\left(t_{i j}\right)=\beta_{1} X_{1 i j}+\beta_{2} X_{2 i j}+g\left(t_{i j}\right)+\varepsilon\left(t_{i j}\right), W_{2 i j}=X_{2 i j}+U_{2 i j},
$$

where $W_{2 i j}$ are the observed CD4 cell counts, and $g\left(t_{i j}\right)$, the baseline CD4 percentage, represents the mean CD4 percentage $t$ years after infection for a non-smoker with average pre-infection CD4 percentage, and $\beta_{1}$ and $\beta_{2}$ describe the effects for cigarette smoking and pre-infection CD4 percentage, respectively, on the post-infection CD4 percentage. We assumed that the measurement errors $U_{2 i j}$ are independent and normally distributed with mean zero and variance $\sigma_{u u}^{2}$. as in Yang et al.[25], we conduct a sensitivity analysis by taking $\sigma_{u u}^{2}=0$, which naively ignores measurement error, $\sigma_{u u}^{2}=0.068$ and $\sigma_{u u}^{2}=$ 0.154 .

FIGURE 3
Figure 3:AIDS study: Estimates of $\left(\beta_{1}, \beta_{2}\right)$ and the averages of $95 \%$ confidence rigions based on the normal approximation (NA) and residual-adjusted generalized empirical likelihood (GEL). The left panel for $\sigma_{u u}^{2}=0$, the middle panel for $\sigma_{u u}^{2}=0.068$ and the right panel for $\sigma_{u u}^{2}=0.135$.


We computed the generalized empirical likelihood ratios for $\left(\beta_{1}, \beta_{2}\right)$ under first-order autoregressive correlation matrix, and the estimators for $g(t)$ by using the Epanechnikov kernel and the cross-validated bandwidth $h_{c v}=0.38$. The $95 \%$ confidence regions for ( $\beta_{1}, \beta_{2}$ ) reported in Figure 3, and it shows that the generalized empirical likelihood again works better than the normal approximation. For $\sigma_{u u}^{2}=0, \sigma_{u u}^{2}=0.068$ and $\sigma_{u u}^{2}=0.135$ , the estimated values of $\beta_{2}$ are $0.3063,0.3248,0.3456$, respectively. As expected, we find a somewhat stronger positive association between the pre-infection CD4 percentage and the percentage of CD4 cells when the possibility of measurement error is taken into account.

## FIGURE 4

Figure 4:AIDS study: The solid curve represents the estimated curve of the baseline function and the dotted line indicate the $95 \%$ pointwise confidence intervals for baseline function, based on the residual-adjusted empirical likelihood.


The curve of the estimated baseline function and the corresponding $95 \%$ pointwise confidence intervals for the case of $\sigma_{u u}^{2}=0$ is shown in Figure 4. The results for the other cases of $\sigma_{u u}^{2}=0.143$ and $\sigma_{u u}^{2}=0.194$ are similar and are therefore not shown. From Figure 4, we find that the mean baseline CD4 percentage for the population decreases rather quickly at the beginning of HIV infection, but the rate of decrease appears to be slowing down four years after the infection. The findings basically agree with that which was discovered by the local linear fitting method of Fan and Li [7] and Xue and Zhu [24].

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## 6. Appendix.

For convenience and simplicity, let $c$ denote a positive constant that may be different at each appearance throughout this paper. Before we state one of the main results, we note the following regularity conditions.
$C 1$. The bandwidth satisfies $h=h_{0} N^{-1 / 5}$ for some constant $h_{0}>0$.
$C 2$. The kernel $K(\cdot)$ is a symmetric probability density function, and is twice continuously differentiable on its support set $[-1,1]$.
$C 3 . \sup _{x, 0 \leq t \leq 1} E\left(\varepsilon_{i j}^{4} \mid X_{i j r}=x, T_{i j}=t\right)<\infty, \sup _{0 \leq t \leq 1} E\left(U_{i j}^{4} \mid T_{i j}=t\right)<\infty, E\left(X_{i j r}^{4}\right)<$ $\infty$ for $i=1, \ldots, n, j=1, \ldots, n_{i}$, and $r=1, \ldots, p$, where $X_{i j r}$ is the $r$ th component of $X_{i j}$.
$C 4$. The density function of $T_{i j}, f(t)$ is bounded away from zero and infinity uniformly over $[0,1]$, and is twice continuously differentiable on $(0,1)$.
$C 5$. $g(t)$ and $m_{X, r}(t)$ are twice continuously differentiable on $(0,1)$ for all $r=1, \ldots, p$, where $m_{X, r}(t)$ is the $r$ th component of $m_{X}(t)$.
$C 6$. The variance function $\sigma_{\varepsilon, u}^{2}(t)$ is continuous at $t_{0}$.
Remark. $C 1-C 6$ are the common conditions used in the literature. $C 1$ ensures that undersmoothing $\hat{g}$ is not needed so that we can use data-driven approach to select the bandwidth. In $C 2$, the compaction by using kernels with small tails; for example, the standard Gaussian kernel. $C 3$ is a necessary moment condition. Smooth conditions $C 4$ and $C 5$ are standard conditions for nonparametric. $C 6$ is a regularity condition.
The proofs of Theorems 2.1 and 2.2 rely on the following some lemmas.
6.1. Lemma. Suppose that conditions C1-C6 hold. Then, for any constants $a$ and $b$ with $0<a<b<1$, we have

$$
\begin{array}{r}
\sup _{a \leq t \leq b} E\left[\left\|m_{W}\left(T_{i j}\right)-\hat{m}_{W}\left(T_{i j}\right)\right\|^{2} \mid T_{i j}=t\right]=O\left(n^{-1} h^{-1}+h^{4}\right) \\
\sup _{a \leq t \leq b} E\left[\left\|g\left(T_{i j}\right)-\hat{g}_{*}\left(T_{i j}\right)\right\|^{2} \mid T_{i j}=t\right]=O\left(n^{-1} h^{-1}+h^{4}\right), \tag{6.1}
\end{array}
$$

where $\hat{g}_{*}(t)=\hat{m}_{Y}(t)-\hat{m}_{W}^{T}(t) \beta$.
The proof of Lemma 6.1 is similar to that of Xue and Zhu [24] and we omit the details.
6.2. Lemma. Suppose that the regularity conditions C1-C6 hold. If $\beta$ is the true parameter, then

$$
\begin{equation*}
\frac{1}{\sqrt{n}} \sum_{i=1}^{n} \hat{Z}_{i}(\beta) \xrightarrow{\mathcal{L}} N(0, \Sigma), \tag{6.2}
\end{equation*}
$$

where $\Sigma$ is defined by (2.12).
Proof. Consider the $k$ th $(k=1, \ldots, s)$ block of $\frac{1}{\sqrt{n}} \sum_{i=1}^{n} \hat{Z}_{i}(\beta)$ :

$$
\begin{aligned}
& \frac{1}{\sqrt{n}} \sum_{i=1}^{n} \hat{W}_{i}^{T} A_{i}^{-1 / 2} M_{k} A_{i}^{-1 / 2}\left(\hat{Y}_{i}-\hat{W}_{i} \beta\right)+D_{i}^{(k)} \beta \\
= & \frac{1}{\sqrt{n}} \sum_{i=1}^{n}\left\{\tilde{X}_{i}^{T} A_{i}^{-1 / 2} M_{k} A_{i}^{-1 / 2}\left(\Psi_{i} \varepsilon_{i}-U_{i} \beta\right)+U_{i}^{T} A_{i}^{-1 / 2} M_{k} A_{i}^{-1 / 2} \Psi_{i} \varepsilon_{i}\right. \\
& \left.-U_{i} A_{i}^{-1 / 2} M_{k} A_{i}^{-1 / 2} U_{i} \beta+D_{i}^{(k)} \beta\right\} \\
& +\frac{1}{\sqrt{n}} \sum_{i=1}^{n}\left\{\tilde{X}_{i}^{T} A_{i}^{-1 / 2} M_{k} A_{i}^{-1 / 2} \Psi_{i}\left[g\left(T_{i}\right)-\hat{g}_{*}\left(T_{i}\right)\right]\right\} \\
& +\frac{1}{\sqrt{n}} \sum_{i=1}^{n}\left\{\left[m_{W}\left(T_{i}\right)-\hat{m}_{W}\left(T_{i}\right)\right]^{T} \Psi_{i} A_{i}^{-1 / 2} M_{k} A_{i}^{-1 / 2} \Psi_{i} \varepsilon_{i}\right\} \\
& +\frac{1}{\sqrt{n}} \sum_{i=1}^{n}\left\{U_{i}^{T} A_{i}^{-1 / 2} M_{k} A_{i}^{-1 / 2} \Psi_{i}\left[g\left(T_{i}\right)-\hat{g}_{*}\left(T_{i}\right)\right]\right\} \\
& -\frac{1}{\sqrt{n}} \sum_{i=1}^{n}\left\{\left[m_{W}\left(T_{i}\right)-\hat{m}_{W}\left(T_{i}\right)\right]^{T} \Psi_{i} A_{i}^{-1 / 2} M_{k} A_{i}^{-1 / 2} U_{i} \beta\right\} \\
& +\frac{1}{\sqrt{n}} \sum_{i=1}^{n}\left\{\left[m_{W}\left(T_{i}\right)-\hat{m}_{W}\left(T_{i}\right)\right]^{T} \Psi_{i} A_{i}^{-1 / 2} M_{k} A_{i}^{-1 / 2} \Psi_{i}\left[\left(g\left(T_{i}\right)-\hat{g}_{*}\left(T_{i}\right)\right)\right]\right\}
\end{aligned}
$$

$$
\equiv J_{1}+J_{2}+J_{3}+J_{4}+J_{5}+J_{6}
$$

We first deal with $J_{1}$. Denote $J_{1}=\frac{1}{\sqrt{n}} \sum_{i=1}^{n} \zeta_{i k}$, it is easy to obtain $E \zeta_{i k}=0$ and

$$
\begin{aligned}
\operatorname{Cov}\left(\zeta_{i k}\right)= & E\left(\tilde{X}_{i}^{T} A_{i}^{-1 / 2} M_{k} A_{i}^{-1 / 2}\left(\Psi_{i} \varepsilon_{i}-U_{i} \beta\right)\right)^{\otimes 2} \\
& +E\left(U_{i}^{T} A_{i}^{-1 / 2} M_{k} A_{i}^{-1 / 2} \Psi_{i} \varepsilon_{i}\right)^{\otimes 2} \\
& +E\left(-U_{i} A_{i}^{-1 / 2} M_{k} A_{i}^{-1 / 2} U_{i} \beta+D_{i}^{(k)} \beta\right)^{\otimes 2}+o_{p}(1) \\
= & \Sigma_{k k}+o_{p}(1) .
\end{aligned}
$$

Next, we need to prove $J_{v} \xrightarrow{\mathcal{P}} 0, v=2,3,4,5,6$. We first deal with $J_{2}$. Let $c_{i k}^{j v}$ denote the $(j, v)$ th element of $A_{i}^{-1 / 2} M_{k} A_{i}^{-1 / 2}$. Similar to the proof of (6.1), we can get that

$$
\begin{equation*}
\sup _{a \leq t \leq b} E\left[\left(g\left(T_{i j}\right)-\sum_{k=1}^{n} \sum_{l=1}^{n_{k}} \omega_{k l}\left(T_{i j}\right) g\left(T_{k l}\right)\right)^{2} \mid T_{i j}=t\right]=O\left(n^{-1} h+h^{4}\right), \tag{6.3}
\end{equation*}
$$

Let $J_{2, k}$ and $\tilde{X}_{i j, k}$ denote the $k$ th $(k=1, \ldots, p)$ component of $J_{2}$ and $\tilde{X}_{i j}$. From (6.3) and Conditions $C 1-C 4$ we have

$$
\begin{aligned}
E\left(J_{2, k}^{2}\right) \leq & 2 n^{-1} E\left[\sum_{k=1}^{n} \sum_{l=1}^{n_{k}}\left(\sum_{i=1}^{n} \sum_{j=1}^{n_{i}} \sum_{v=1}^{n_{i}} \psi\left(T_{i j}\right) \omega_{k l}\left(T_{i j}\right) \tilde{X}_{i j, k} c_{i k}^{j v}\right) \varepsilon_{k l}\right]^{2}+2 n^{-1} \\
& E\left[\sum_{i=1}^{n} \sum_{j=1}^{n_{i}} \sum_{v=1}^{n_{i}} \psi\left(T_{i j}\right) \tilde{X}_{i j, k} c_{i k}^{j v}\left(g\left(T_{i j}\right)-\sum_{k=1}^{n} \sum_{l=1}^{n_{k}} \omega_{k l}\left(T_{i j}\right) g\left(T_{k l}\right)\right)\right]^{2} \\
\leq & c\left[(n h)^{-1}+h^{4}\right] \longrightarrow 0 .
\end{aligned}
$$

Hence, we have $J_{2} \longrightarrow 0$. Then, we consider $J_{3}$.

$$
\begin{aligned}
J_{3} & =\frac{1}{\sqrt{n}} \sum_{i=1}^{n}\left\{\left[m_{W}\left(T_{i}\right)-\hat{m}_{W}\left(T_{i}\right)\right]^{T} \Psi_{i} A_{i}^{-1 / 2} M_{k} A_{i}^{-1 / 2} \Psi_{i} \varepsilon_{i}\right\} \\
& =\frac{1}{\sqrt{n}} \sum_{i=1}^{n} \sum_{j=1}^{n_{i}} \sum_{v=1}^{n_{i}} \psi^{2}\left(T_{i j}\right)\left[m_{W}\left(T_{i j}\right)-\hat{m}_{W}\left(T_{i j}\right)\right]^{T} c_{i k}^{j v} \varepsilon_{i j}
\end{aligned}
$$

From Lemma 6.1 and $C 5$ we have

$$
\begin{aligned}
E\left(\left\|J_{3}\right\|^{2}\right) & \leq c n^{-1} \sum_{i=1}^{n} \sum_{j=1}^{n_{i}} \sum_{v=1}^{n_{i}} E\left\{\psi\left(T_{i j}\right)\left(c_{i k}^{j v}\right)^{2} E\left(\left\|m_{w}\left(T_{i j}\right)-\hat{m}_{w}\left(T_{i j}\right)\right\|^{2} \mid T_{i j}\right)\right\} \\
& \leq c\left[(n h)^{-1}+h^{4}\right] \longrightarrow 0
\end{aligned}
$$

Similarly, we can get $J_{4} \xrightarrow{\mathcal{P}} 0, J_{5} \xrightarrow{\mathcal{P}} 0$. From Lemma 6.1 and Cauchy-Schwarz inequality, we have

$$
\begin{aligned}
E\left(\left\|J_{6}\right\|\right) \leq & \frac{1}{\sqrt{n}} \sum_{i=1}^{n} \sum_{j=1}^{n_{i}} \sum_{v=1}^{n_{i}} E\left\{\psi\left(T_{i j}\right) c_{i k}^{j v}\left[E\left(\left\|m_{w}\left(T_{i j}-\hat{m}_{w}\left(T_{i j}\right)\right)\right\|^{2} \mid T_{i j}\right)\right]^{1 / 2}\right. \\
& {\left.\left[E\left(\left\|g\left(T_{i j}\right)-\hat{g}_{*}\left(T_{i j}\right)\right\|^{2} \mid T_{i j}\right)\right]^{1 / 2}\right\} } \\
\leq & c \sqrt{n}\left[(n h)^{-1}+h^{4}\right] \longrightarrow 0
\end{aligned}
$$

This implies $J_{6} \xrightarrow{\mathcal{P}} 0$. So we have

$$
\frac{1}{\sqrt{n}} \sum_{i=1}^{n} \hat{Z}_{i}(\beta)=\frac{1}{\sqrt{n}} \sum_{i=1}^{n} \zeta_{i}+o(1)
$$

where $\varsigma_{i}=\left(\zeta_{i 1}^{T}, \ldots, \zeta_{i s}^{T}\right)^{T}$. Obviously, $E\left(\zeta_{i}\right)=0$ and

$$
\frac{1}{n} \sum_{i=1}^{n} \operatorname{Cov}\left(\zeta_{i}\right)=\left(\begin{array}{c}
\Sigma_{11} \cdots \Sigma_{1 s} \\
\vdots \ddots \\
\Sigma_{s 1} \cdots \Sigma_{s s}
\end{array}\right)
$$

The proof of Lemma 6.2 is completed.
6.3. Lemma. Suppose that Conditions C1-C6 holds. If $\beta$ is the true parameter, then

$$
\hat{\Sigma}=\frac{1}{n} \sum_{i=1}^{n} \hat{Z}_{i}(\beta) \hat{Z}_{i}(\beta)^{T} \xrightarrow{\mathcal{P}} \Sigma .
$$

Proof. We also use the notations in the proof of Lemma 6.2, and denote $\hat{Z}_{i, k}(\beta)$ is the $k$ th $(k=1, \ldots, s)$ block of $\hat{Z}_{i}(\beta)$. A simple calculation yields

$$
\hat{Z}_{i, k}(\beta)=\zeta_{i k}+I_{1 k}+I_{2 k}, \hat{Z}_{i, m}(\beta)=\zeta_{i m}+I_{1 m}+I_{2 m}
$$

where

$$
\begin{aligned}
I_{1 k}= & \left(\tilde{X}_{i}+U_{i}\right)^{T} A_{i}^{-1 / 2} M_{k} A_{i}^{-1 / 2} \Psi_{i}\left[g\left(T_{i}\right)-\hat{g}_{*}\left(T_{i}\right)\right], \\
I_{2 k}= & {\left[m_{W}\left(T_{i}\right)-\hat{m}_{W}\left(T_{i}\right)\right]^{T} \Psi_{i} A_{i}^{-1 / 2} M_{k} A_{i}^{-1 / 2} } \\
& {\left[\left(\Psi_{i} \varepsilon_{i}-U_{i} \beta\right)+\Psi_{i}\left(g\left(T_{i}\right)-\hat{g}_{*}\left(T_{i}\right)\right)\right], } \\
I_{1 m}= & \left(\tilde{X}_{i}+U_{i}\right)^{T} A_{i}^{-1 / 2} M_{m} A_{i}^{-1 / 2} \Psi_{i}\left[g\left(T_{i}\right)-\hat{g}_{*}\left(T_{i}\right)\right], \\
I_{2 m}= & {\left[m_{W}\left(T_{i}\right)-\hat{m}_{W}\left(T_{i}\right)\right]^{T} \Psi_{i} A_{i}^{-1 / 2} M_{m} A_{i}^{-1 / 2} } \\
& {\left[\left(\Psi_{i} \varepsilon_{i}-U_{i} \beta\right)+\Psi_{i}\left(g\left(T_{i}\right)-\hat{g}_{*}\left(T_{i}\right)\right)\right] . }
\end{aligned}
$$

Then, consider the $(k, m)$ th block of $\hat{\Sigma}, k, m=1, \ldots, s$,

$$
\begin{aligned}
\frac{1}{n} \sum_{i=1}^{n} \hat{Z}_{i, k}(\beta) \hat{Z}_{i, m}(\beta)^{T}= & \frac{1}{n} \sum_{i=1}^{n} \zeta_{i k} \zeta_{i m}^{T}+\frac{1}{n} \sum_{i=1}^{n} I_{1 k} I_{1 m}^{T}+\frac{1}{n} \sum_{i=1}^{n} I_{2 k} I_{1 m}^{T} \\
& \frac{1}{n} \sum_{i=1}^{n} I_{1 k} I_{2 m}^{T}+\frac{1}{n} \sum_{i=1}^{n} I_{2 k} I_{2 m}^{T}+\frac{1}{n} \sum_{i=1}^{n} \zeta_{i k} I_{1 m}^{T} \\
& +\frac{1}{n} \sum_{i=1}^{n} \zeta_{i k} I_{2 m}^{T}+\frac{1}{n} \sum_{i=1}^{n} I_{1 k} \zeta_{i m}^{T}+\frac{1}{n} \sum_{i=1}^{n} I_{2 k} \zeta_{i m}^{T} \\
= & U_{1}+U_{2}+U_{3}+U_{4}+U_{5}+U_{6}+U_{7}+U_{8}+U_{9}
\end{aligned}
$$

By the law of large numbers, we can derive that $U_{1} \xrightarrow{\mathcal{P}} \Sigma_{k m}$. Thus, if we can prove $U_{\nu} \xrightarrow{\mathcal{P}} 0, \nu=2, \ldots, 9$. For $U_{2}$, let $U_{2, r q}$ denote its $(r, q)$ element, and $I_{i k r}, I_{i m r}$ denote the $r$ th component of $I_{1 k}, I_{1 m}$, respectly. We may use the Cauchy-Schwarz inequality to get

$$
\left|U_{2, r q}\right| \leq\left(\frac{1}{n} \sum_{i=1}^{n} I_{i k r}^{2}\right)^{1 / 2}\left(\frac{1}{n} \sum_{i=1}^{n} I_{i m q}^{2}\right)^{1 / 2} .
$$

By Lemma 6.1, we can derive that $\frac{1}{n} \sum_{i=1}^{n} I_{i k r}^{2} \xrightarrow{\mathcal{P}} 0, \frac{1}{n} \sum_{i=1}^{n} I_{i m q}^{2} \xrightarrow{\mathcal{P}} 0$. Then, we get $U_{2} \xrightarrow{\mathcal{P}} 0$. Similarly, we can prove that $U_{\nu} \xrightarrow{\mathcal{P}} 0, \nu=3, \ldots, 9$. This completes the proof of Lemma 6.3.
6.4. Lemma. Suppose that the regularity conditions $C 1-C 6$ hold. If $\beta$ is the true parameter, then

$$
\begin{array}{r}
\max _{1 \leq i \leq n}\left\|\hat{Z}_{i}(\beta)\right\|=o_{P}\left(n^{1 / 2}\right) \\
\|\lambda\|=O_{P}\left(n^{-1 / 2}\right) \tag{6.5}
\end{array}
$$

Proof. According to the definition of $\hat{Z}_{i}(\beta)$ and Lemma 6.2, For the $k$ th $(k$ $=1, \ldots, s)$ block of $\hat{Z}_{i}^{(k)}(\beta)$ we have

$$
\begin{aligned}
\max _{1 \leq i \leq n}\left\|\hat{Z}_{i}^{(k)}(\beta)\right\| \leq & \max _{1 \leq i \leq n} \| \tilde{X}_{i}^{T} A_{i}^{-1 / 2} M_{k} A_{i}^{-1 / 2}\left(\Psi_{i} \varepsilon_{i}-U_{i} \beta\right)+U_{i}^{T} A_{i}^{-1 / 2} M_{k} \\
& A_{i}^{-1 / 2} \Psi_{i} \varepsilon_{i}-U_{i} A_{i}^{-1 / 2} M_{k} A_{i}^{-1 / 2} U_{i} \beta+D_{i}^{(k)} \beta \| \\
& +\max _{1 \leq i \leq n}\left\|\left(\tilde{X}_{i}+U_{i}\right)^{T} A_{i}^{-1 / 2} M_{k} A_{i}^{-1 / 2} \Psi_{i}\left[g\left(T_{i}\right)-\hat{g}_{*}\left(T_{i}\right)\right]\right\| \\
& +\max _{1 \leq i \leq n} \|\left[m_{W}\left(T_{i}\right)-\hat{m}_{W}\left(T_{i}\right)\right]^{T} \Psi_{i} A_{i}^{-1 / 2} M_{k} A_{i}^{-1 / 2} \\
& {\left[\left(\Psi_{i} \varepsilon_{i}-U_{i} \beta\right)+\Psi_{i}\left(g\left(T_{i}\right)-\hat{g}_{*}\left(T_{i}\right)\right)\right] \| } \\
\equiv & M_{1}+M_{2}+M_{3}
\end{aligned}
$$

From Lemma 11.2 in Owen [17], we can obtain that $M_{1}=o_{P}\left(n^{1 / 2}\right)$. By Lemma 6.1 and Cauchy-Schwarz inequality, $M_{v}=o_{P}(1), v=2,3$. This proves the first equation.
By Lemma 6.2, 6.3 and using the same arguments that are used in the proof of (2.14) in Owen [16], we can prove the second equation. Then the proof follows.

Proof. Proof of the Theorem 2.1. Applying the Taylor expansion to (2.9), and invoking lemmas, we get that

$$
\begin{equation*}
\hat{l}(\beta)=2 \sum_{i=1}^{n}\left\{\lambda^{T} \hat{Z}_{i}(\beta)-\left[\lambda^{T} \hat{Z}_{i}(\beta)\right]^{2} / 2\right\}+o_{P}(1) \tag{6.6}
\end{equation*}
$$

by (2.10), it follows that

$$
\begin{aligned}
0 & =\sum_{i=1}^{n} \frac{\hat{Z}_{i}(\beta)}{1+\lambda^{T} \hat{Z}_{i}(\beta)} \\
& =\sum_{i=1}^{n} \hat{Z}_{i}(\beta)-\sum_{i=1}^{n} \hat{Z}_{i}(\beta) \hat{Z}_{i}(\beta)^{T} \lambda+\sum_{i=1}^{n} \frac{\hat{Z}_{i}(\beta)\left[\lambda^{T} \hat{Z}_{i}(\beta)\right]^{2}}{1+\lambda^{T} \hat{Z}_{i}(\beta)} .
\end{aligned}
$$

This together with Lemma 6.2-6.4 proves that

$$
\sum_{i=1}^{n}\left[\lambda^{T} \hat{Z}_{i}(\beta)\right]^{2}=\sum_{i=1}^{n} \lambda^{T} \hat{Z}_{i}(\beta)+o_{P}(1)
$$

and

$$
\lambda=\left\{\sum_{i=1}^{n} \hat{Z}_{i}(\beta) \hat{Z}_{i}(\beta)^{T}\right\}^{-1} \sum_{i=1}^{n} \hat{Z}_{i}(\beta)+o_{P}\left(n^{-1 / 2}\right)
$$

therefore, we have

$$
\begin{equation*}
\hat{l}(\beta)=\left\{\frac{1}{\sqrt{n}} \sum_{i=1}^{n} \hat{Z}_{i}(\beta)\right\}^{T} \hat{\Sigma}^{-1}\left\{\frac{1}{\sqrt{n}} \sum_{i=1}^{n} \hat{Z}_{i}(\beta)\right\}+o_{P}(1) . \tag{6.7}
\end{equation*}
$$

This together with lemma 6.2 and 6.3 proves Theorem 2.1.

Proof. Proof of the Theorem 2.2. Applying the same argument as in the proof of Theorem 2.2 in Tian and Xue [22], we can prove that

$$
\hat{\beta}-\beta=-\left[\hat{\Gamma}^{T} \hat{\Sigma}^{-1} \hat{\Gamma}\right]^{-1} \hat{\Gamma}^{T} \hat{\Sigma}^{-1} n^{-1} \sum_{i=1}^{n} \hat{Z}_{i}(\beta)+o_{P}\left(n^{-1 / 2}\right)
$$

Similarlly to the proof of Lemma 6.3, we can obtain $\hat{\Gamma} \xrightarrow{\mathcal{P}} \Gamma$. Together this with Lemma 6.2, 6.4 and Slutsky's Theorem, we can prove Theorem 2.2.

The proofs of Theorems 2.3 and 2.4 are similar to the proofs of Theorems 2.1 and 2.2, therefore, we omit their proofs.
6.5. Lemma. Suppose that the regularity conditions $C 1-C 6$ hold. If $g\left(t_{0}\right)$ is the true value of the baseline function, then

$$
\frac{1}{\sqrt{N h}} \sum_{i=1}^{n} \hat{\eta}_{i}\left(g\left(t_{0}\right)\right)-b\left(t_{0}\right) \xrightarrow{\mathcal{L}} N\left(0, v^{2}\left(t_{0}\right)\right) .
$$

Proof. It is easy to see that

$$
\begin{equation*}
\frac{1}{\sqrt{N h}} \sum_{i=1}^{n} \hat{\eta}_{i}\left(g\left(t_{0}\right)\right)-b\left(t_{0}\right)=S_{1}\left(t_{0}\right)+S_{2}\left(t_{0}\right)+S_{3}\left(t_{0}\right), \tag{6.8}
\end{equation*}
$$

where

$$
\begin{aligned}
& S_{1}\left(t_{0}\right)=\frac{1}{\sqrt{N h}} \sum_{i=1}^{n} \sum_{j=1}^{n_{i}}\left(\varepsilon_{i j}-U_{i j}^{T} \beta\right) K_{h}\left(T_{i j}-t_{0}\right), \\
& S_{2}\left(t_{0}\right)=\frac{1}{\sqrt{N h}} \sum_{i=1}^{n} \sum_{j=1}^{n_{i}}\left[g\left(T_{i j}\right)-g\left(t_{0}\right)\right] K_{h}\left(T_{i j}-t_{0}\right), \\
& S_{3}\left(t_{0}\right)=\frac{1}{\sqrt{N h}} \sum_{i=1}^{n} \sum_{j=1}^{n_{i}} K_{h}\left(T_{i j}-t_{0}\right) W_{i j}^{T}(\beta-\hat{\beta}) .
\end{aligned}
$$

It is not difficult to prove $E\left[S_{1}\left(t_{0}\right)\right]=0$ and $\operatorname{var}\left[S_{1}\left(t_{0}\right)\right]=v^{2}\left(t_{0}\right)+o(1)$. We can check that $S_{1}\left(t_{0}\right)$ satisfies the conditions of the Cramer-Wold theorem and the Lindeberg condition (Serfing, [19]). Therefore, we get

$$
\begin{equation*}
S_{1}\left(t_{0}\right) \xrightarrow{\mathcal{L}} N\left(0, v^{2}\left(t_{0}\right)\right) . \tag{6.9}
\end{equation*}
$$

We can also prove that $\operatorname{var}\left(S_{2}\left(t_{0}\right)\right)=o(1)$. Thus
(6.10) $\quad S_{2}\left(t_{0}\right) \xrightarrow{\mathcal{P}} 0$.

By Lemma 6.1 and 6.2 we can get $S_{3}\left(t_{0}\right)=O_{P}\left(h^{1 / 2}\right)$. This together with (6.8)-(6.10) proves Lemma 6.5.
6.6. Lemma. Suppose that the regularity conditions $C 1-C 6$ hold. If $g(t)$ is the true value of the baseline function, then

$$
\begin{aligned}
& \frac{1}{N h} \sum_{i=1}^{n} \hat{\eta}_{i}^{2}\left(g\left(t_{0}\right)\right) \xrightarrow{\mathcal{P}} v^{2}\left(t_{0}\right), \\
& \max _{1 \leq i \leq n}\left\|\hat{\eta}_{i}\left(g\left(t_{0}\right)\right)\right\|=o_{P}\left((N h)^{1 / 2}\right) .
\end{aligned}
$$

Using some arguments similar to those used in the proof of Lemma 6.3 and 6.4, we can prove Lemma 6.6. The proof is omitted.
6.7. Lemma. Suppose that the regularity conditions C1-C6 hold. Then $\hat{b}\left(t_{0}\right) \xrightarrow{\mathcal{P}} b\left(t_{0}\right)$.

Proof. Denote $\left.\varphi_{i j}\left(t_{0}\right)=\left[g\left(T_{i j}\right)-g t_{0}\right)\right] K_{h}\left(T_{i j}-t_{0}\right)$ and $\hat{\varphi}_{i j}\left(t_{0}\right)=\left[\hat{g}\left(T_{i j}\right)-\right.$ $\left.\hat{g}\left(t_{0}\right)\right] K_{h}\left(T_{i j}-t_{0}\right)$. Then, we have

$$
\begin{aligned}
\hat{b}\left(t_{0}\right)-b\left(t_{0}\right)= & \frac{1}{\sqrt{N h}} \sum_{i=1}^{n} \sum_{j=1}^{n_{i}}\left[\hat{\varphi}_{i j}\left(t_{0}\right)-\varphi_{i j}\left(t_{0}\right)\right] \\
& +\frac{1}{\sqrt{N h}} \sum_{i=1}^{n} \sum_{j=1}^{n_{i}}\left[\varphi_{i j}\left(t_{0}\right)-(h / N)^{1 / 2} b\left(t_{0}\right)\right] \\
= & M_{1}\left(t_{0}\right)+M_{2}\left(t_{0}\right) .
\end{aligned}
$$

From Conditions $C 1-C 4$ and the Taylor expansion, we have

$$
\hat{\varphi}_{i j}\left(t_{0}\right)-\varphi_{i j}\left(t_{0}\right)=\left\{\left[\hat{g}^{\prime}\left(t_{0}\right)-g^{\prime}\left(t_{0}\right)\right]\left(T_{i j}-t_{0}\right)+o_{P}\left(\left|\left(T_{i j}-t_{0}\right)\right|^{2}\right)\right\} K_{h}\left(T_{i j}-t_{0}\right) .
$$

Using Conditions C1 and C2, we can prove that

$$
\frac{1}{\sqrt{N h}} \sum_{i=1}^{n} \sum_{j=1}^{n_{i}}\left(T_{i j}-t_{0}\right)^{l} K_{h}\left(T_{i j}-t_{0}\right)=O_{P}(1), l=1,2,
$$

and $\hat{g}^{\prime}\left(t_{0}\right)-g^{\prime}\left(t_{0}\right) \xrightarrow{\mathcal{P}} 0$. Therefore, we have $M_{1}\left(t_{0}\right) \xrightarrow{\mathcal{P}} 0$. It is easy to prove $M_{2}\left(t_{0}\right) \xrightarrow{\mathcal{P}}$ 0 . The proof of Lemma 6.7 is completed.

We now turn to prove Theorems 3.1 and 3.2.
Proof. Proof of the Theorem 3.1. By direct calculation, we can obtain

$$
\sqrt{N h}\left(\hat{g}\left(t_{0}\right)-g\left(t_{0}\right)\right)=\frac{1}{\sqrt{N h}} \sum_{i=1}^{n} \hat{\eta}_{i}\left(g\left(t_{0}\right)\right) / \hat{f}\left(t_{0}\right)+o_{P}(1) .
$$

Note that $\hat{f}\left(t_{0}\right) \rightarrow f(t)$, almost surely. This together with Lemma 6.5 proves Theorem 3.1.

Proof. Proof of the Theorem 3.2. It can be shown by Lemma 6.7 and direction calculation that

$$
\begin{align*}
\frac{1}{\sqrt{N h}} \sum_{i=1}^{n} \hat{\eta}_{i}^{*}\left\{g\left(t_{0}\right)\right\} & =\frac{1}{\sqrt{N h}} \sum_{i=1}^{n} \hat{\eta}_{i}\left\{g\left(t_{0}\right)\right\}-b\left(t_{0}\right)+o_{P}(1),  \tag{6.11}\\
\frac{1}{N h} \sum_{i=1}^{n} \hat{\eta}_{i}^{* 2}\left\{g\left(t_{0}\right)\right\} & =\frac{1}{N h} \sum_{i=1}^{n} \hat{\eta}_{i}^{2}\left\{g\left(t_{0}\right)\right\}+o_{P}(1),  \tag{6.12}\\
\max _{1 \leq i \leq n}\left|\hat{\eta}_{i}^{*}\left\{g\left(t_{0}\right)\right\}\right| & =o_{P}\left\{(N h)^{1 / 2}\right\} . \tag{6.13}
\end{align*}
$$

Similar to the proof of the Theorem 2.1, Theorem 3.2 can be proved by (6.11)-(6.13) and Lemma 6.6.

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