# Oscillation criteria for a certain class of fractional order integro-differential equations 

Serkan Aslıyüce ${ }^{* \ddagger \dagger}$, A. Feza Güvenilir ${ }^{\ddagger}$ and Ağacık Zafer ${ }^{\S}$


#### Abstract

In this paper, we shall give some new results about the oscillatory behavior of nonlinear fractional order integro-differential equations with forcing term $v(t)$ of form $$
D_{a}^{\alpha} x(t)=v(t)-\int_{a}^{t} K(t, s) F(s, x(s)) d s, 0<\alpha<1, \lim _{t \rightarrow a^{+}} J_{a}^{1-\alpha} x(t)=b_{1}
$$ where $v, K$ and $F$ are continuous functions, $b_{1} \in \mathbb{R}$, and $D_{a}^{\alpha}$ and $J_{a}^{1-\alpha}$ denote the Riemann-Liouville fractional order differential and integral operators respectively.

Keywords: fractional integro-differential equations, oscillation, Riemann-Liouville fractional operators, Caputo fractional derivative.


2000 AMS Classification: Primary 34A08, 26A33; Secondary 34C10, 65R20.

Received : 10.02.2016 Accepted : 12.05.2016 Doi: 10.15672/HJMS. 20164518619

[^0]
## 1. Introduction

Fractional order differential equations have gained more importance in last two decades because of their various applications in different disciplines of science and engineering, such as in control theory, viscoelasticity, electromagnetic, etc. [5, 9, 14, 18]. Many mathematicians have studied the existence and uniqueness of solutions, the stability of solutions, the methods of explicit and numerical solutions of fractional order differential equations [3, 11, 13, 20, 24, 25]. For a background of the subject, we refer in particular to the books $[2,10,19,22,23]$.

As far as the oscillation theory of fractional order differential equations are concerned, there are only a few papers. To the best of our knowledge, the paper by Grace et al. [15] has initiated the study of oscillation theory for fractional differential equations. In mentioned paper, the authors established several results criteria for solutions of equations in the form

$$
D_{a}^{\alpha} x+f_{1}(t, x)=v(t)+f_{2}(t, x)
$$

satisfying the initial condition

$$
\lim _{t \rightarrow a^{+}} J_{a}^{1-\alpha} x(t)=b_{1}
$$

where $D_{a}^{\alpha}$ denotes the Riemann-Liouville fractional differential operator of order $\alpha$ with $0<\alpha<1$. The operator $J_{a}^{\alpha}$ defined by

$$
J_{a}^{\alpha} x(t):=\int_{a}^{t} \frac{(t-s)^{\alpha-1}}{\Gamma(\alpha)} x(s) d s
$$

is called the Riemann-Liouville fractional integral operator of order $\alpha$. Note that

$$
\begin{equation*}
f \leq g \Longrightarrow J_{a}^{\alpha}(f) \leq J_{a}^{\alpha}(g) \tag{*}
\end{equation*}
$$

The Riemann-Liouville fractional differential operator of order $\alpha$ with $m-1<\alpha<$ $m, m \in \mathbb{N}$, is given by

$$
D_{a}^{\alpha} x(t):=\frac{d^{m}}{d t^{m}} J_{a}^{m-\alpha} x(t)
$$

as a special case for $0<\alpha<1$, Riemann-Liouville fractional differential operator is given by

$$
D_{a}^{\alpha} x(t):=\frac{d}{d t} J_{a}^{1-\alpha} x(t) .
$$

Following the work developed in [15], Chen et al. in the [6] studied the fractional differential equation

$$
\left\{\begin{array}{l}
\left(D_{a}^{\alpha} x\right)(t)+f_{1}(t, x)=v(t)+f_{2}(t, x), \quad t>a \geq 0, \\
\left(D_{a}^{\alpha-k} x\right)(t)=b_{k}(k=1,2, \ldots, m-1), \quad \lim _{t \rightarrow a^{+}}\left(I_{a}^{m-\alpha} x\right)(t)=b_{m} .
\end{array}\right.
$$

and established some new results different than the ones obtained in [15]. Here, $I_{a}^{m-\alpha}$ is also a Riemann- Liouville fractional integral operator.

Further results on the oscillation theory of fractional order differential equations can be found in $[1,4,7,8,12,16,21]$.

In the present work, we study the oscillatiory behavior of solutions of nonlinear fractional order integro-differential equations with forcing term $v(t)$ of form

$$
\begin{equation*}
D_{a}^{\alpha} x(t)=v(t)-\int_{a}^{t} K(t, s) F(s, x(s)) d s, 0<\alpha<1, \lim _{t \rightarrow a^{+}} J_{a}^{1-\alpha} x(t)=b_{1} \tag{1.1}
\end{equation*}
$$

where $v, K$ and $F$ are continuous functions, $b_{1} \in \mathbb{R}$, and $D_{a}^{\alpha}$ and $J_{a}^{1-\alpha}$ denotes the Riemann-Liouville fractional order differential and integral operators, respectively. The equation that we considered above is more general than those investigated before in the literature.

By a solution of Eq.(1.1), we mean a nontrivial function $x \in C(J, \mathbb{R})$, with $J=$ $(a, \infty)$, satisfies Eq.(1.1) for $t \geq a \geq 0$. A solution is said to be oscillatory if it has arbitrarily large zeros on $(0, \infty)$; otherwise, it is called nonoscillatory.

## 2. Results for Riemann-Liouville derivative

With regard to Eq. (1.1) we assume that
(i) $v: J \rightarrow \mathbb{R}$ and $K: J \times J \rightarrow \mathbb{R}$ are continuous functions with $K(t, s) \geq 0$ for $t>s$;
(ii) there exist continuous functions $p, q: J \rightarrow[0, \infty)$ such that

$$
K(t, s) \leq p(t) q(s) \text { for all } t \geq s
$$

(iii) $F: J \times \mathbb{R} \rightarrow \mathbb{R}$, with $F(t, x):=f_{1}(t, x)-f_{2}(t, x)$, is continuous and there exist continuous functions $f_{1}, f_{2}: J \times \mathbb{R} \rightarrow \mathbb{R}$ such that $x f_{i}(t, x)>0(i=1,2)$ for $x \neq 0$ and $t \geq a$,
(iv) there exist real constants $\beta, \gamma$ and continuous functions $p_{1}, p_{2}: J \rightarrow(0, \infty)$ such that

$$
f_{1}(t, x) \geq p_{1}(t) x^{\beta} \text { and } f_{2}(t, x) \leq p_{2}(t) x^{\gamma}, x \neq 0, t \geq a .
$$

We will make use of the following lemma, extracted from [17].
2.1. Lemma. If $X$ and $Y$ are nonnegative, then

$$
\begin{equation*}
X^{\lambda}+(\lambda-1) Y^{\lambda}-\lambda X Y^{\lambda-1} \geq 0, \lambda>1 \tag{2.1}
\end{equation*}
$$

and

$$
\begin{equation*}
X^{\lambda}-(1-\lambda) Y^{\lambda}-\lambda X Y^{\lambda-1} \leq 0, \lambda<1 \tag{2.2}
\end{equation*}
$$

with equality holds if and only if $X=Y$.
Our first result is as follows.
2.2. Theorem. Let conditions (i)-(iii) hold with $f_{2}=0$. If for every constant $k>0$
(2.3) $\quad \limsup _{t \rightarrow \infty} J_{a}^{\alpha}[v(t)-k p(t)]=+\infty$
and

$$
\begin{equation*}
\liminf _{t \rightarrow \infty}^{\alpha} J_{a}^{\alpha}[v(t)+k p(t)]=-\infty, \tag{2.4}
\end{equation*}
$$

then every solution of Eq.(1.1) is oscillatory.
Proof. Let $x(t)$ be a nonoscillatory solution of Eq.(1.1) with $f_{2}=0$. We may assume that $x(t)>0$ for $t \geq t_{1}$ for some $t_{1} \geq a$. The case where $x(t)<0$ for $t \geq t_{1}$ is similar. From Eq.(1.1), we have

$$
\begin{aligned}
D_{a}^{\alpha} x(t) & =v(t)-\int_{a}^{t} K(t, s) F(s, x(s)) d s \\
& =v(t)-\int_{a}^{t_{1}} K(t, s) f_{1}(s, x(s)) d s-\int_{t_{1}}^{t} K(t, s) f_{1}(s, x(s)) d s
\end{aligned}
$$

Letting

$$
m:=\min \left\{F(t, x(t)): t \in\left[a, t_{1}\right]\right\} \leq 0 \text { and } k:=-m \int_{a}^{t_{1}} q(s) d s \geq 0
$$

(2.5) leads to

$$
\begin{equation*}
D_{a}^{\alpha} x(t) \leq v(t)+k p(t) . \tag{2.6}
\end{equation*}
$$

Using the monotonicity property (*), we have

$$
J_{a}^{\alpha} D_{a}^{\alpha} x(t) \leq J_{a}^{\alpha}[v(t)+k p(t)],
$$

and hence

$$
\begin{equation*}
x(t) \leq \frac{(t-a)^{\alpha-1}}{\Gamma(\alpha)} b_{1}+J_{a}^{\alpha}[v(t)+k p(t)] . \tag{2.7}
\end{equation*}
$$

In view of (2.4), it follows from (2.7) that

$$
\liminf _{t \rightarrow \infty} x(t)=-\infty,
$$

which clearly contradicts the assumption that $x(t)>0$ eventually. This completes the proof.

Next, we have the following results.
2.3. Theorem. Let conditions (i)-(iv) hold with $\beta>1$ and $\gamma=1$. In addition to conditions of Theorem 1, if

$$
\begin{equation*}
\int_{a}^{\infty} \frac{(t-u)^{\alpha-1}}{\Gamma(\alpha)} \int_{a}^{u} K(u, s) p_{1}^{\frac{1}{1-\beta}}(s) p_{2}^{\frac{\beta}{\beta-1}}(s) d s d u<\infty \tag{2.8}
\end{equation*}
$$

then every solution of Eq.(1.1) is oscillatory.
Proof. Let $x(t)$ be a nonoscillatory solution of Eq.(1.1) with $x(t)>0$ for $t \geq t_{1}$. From conditions (iii)-(iv) with $\beta>1$ and $\gamma=1$, we have

$$
\begin{equation*}
D_{a}^{\alpha} x(t) \leq v(t)+k p(t)+\int_{t_{1}}^{t} K(t, s)\left[p_{2}(s) x(s)-p_{1}(s) x^{\beta}(s)\right] d s \tag{2.9}
\end{equation*}
$$

for some $k>0$. If we take in (2.1) $\lambda=\beta, X=p_{1}^{\frac{1}{\beta}} x$ and $Y=\left(\frac{1}{\beta} p_{2} p_{1}^{\frac{-1}{\beta}}\right)^{\frac{1}{\beta-1}}$, then we have

$$
\begin{equation*}
p_{2} x-p_{1} x^{\beta} \leq(\beta-1) \beta^{\frac{\beta}{1-\beta}} p_{1}^{\frac{-1}{\beta-1}} p_{2}^{\frac{\beta}{\beta-1}} . \tag{2.10}
\end{equation*}
$$

Using (2.10) in (2.9), we have

$$
\begin{equation*}
D_{a}^{\alpha} x(t) \leq v(t)+k p(t)+\int_{t_{1}}^{t} K(t, s)(\beta-1) \beta^{\frac{\beta}{1-\beta}} p_{1}^{\frac{-1}{\beta-1}}(s) p_{2}^{\frac{\beta}{\beta-1}}(s) d s \tag{2.11}
\end{equation*}
$$

Applying $\alpha$ order fractional operator $J_{a}^{\alpha}$ to (2.11), we have

$$
\begin{align*}
x(t) \leq & \frac{(t-a)^{\alpha-1}}{\Gamma(\alpha)} b_{1}+J_{a}^{\alpha}[v(t)+k p(t)] \\
& +\int_{a}^{t} \frac{(t-u)^{\alpha-1}}{\Gamma(\alpha)} \int_{t_{1}}^{u} K(u, s)(\beta-1) \beta^{\frac{\beta}{1-\beta}} p_{1}^{\frac{-1}{\beta-1}}(s) p_{2}^{\frac{\beta}{\beta-1}}(s) d s d u . \tag{2.12}
\end{align*}
$$

Taking limit inferior on both sides of (2.12) as $t \rightarrow \infty$, and using (2.4) and (2.8), we have

$$
\liminf _{t \rightarrow \infty} x(t)=-\infty,
$$

a contradiction with $x(t)>0$ eventually. This completes the proof.
2.4. Theorem. Let conditions (i)-(iv) hold with $\beta=1$ and $\gamma<1$. In addition to conditions of Theorem 1, if

$$
\begin{equation*}
\int_{a}^{\infty} \frac{(t-u)^{\alpha-1}}{\Gamma(\alpha)} \int_{a}^{u} K(u, s) p_{1}^{\frac{\gamma}{\gamma-1}}(s) p_{2}^{\frac{1}{1-\gamma}}(s) d s d u<\infty \tag{2.13}
\end{equation*}
$$

then every solution of Eq.(1.1) is oscillatory.
Proof. Let $x(t)$ be a nonoscillatory solution of Eq.(1.1) with $x(t)>0$ for $t \geq t_{1}$. From conditions (iii)-(iv) with $\beta=1$ and $\gamma<1$, we have

$$
\begin{equation*}
D_{a}^{\alpha} x(t) \leq v(t)+k p(t)+\int_{t_{1}}^{t} K(t, s)\left[p_{2}(s) x^{\gamma}(s)-p_{1}(s) x(s)\right] d s \tag{2.14}
\end{equation*}
$$

for some $k>0$. If we take $\lambda=\gamma, X=p_{2}^{\frac{1}{\gamma}} x$ and $Y=\left(\frac{1}{\gamma} p_{1} p_{2}^{\frac{-1}{\gamma}}\right)^{\frac{1}{\gamma-1}}$ in (2.2), then we have
(2.15) $\quad p_{2} x^{\gamma}-p_{1} x \leq(1-\gamma) \gamma^{\frac{\gamma}{1-\gamma}} p_{1}^{\frac{\gamma}{\gamma-1}} p_{2}^{\frac{1}{1-\gamma}}$.

Using (2.15) in (2.14), we have

$$
\begin{equation*}
D_{a}^{\alpha} x(t) \leq v(t)+k p(t)+\int_{t_{1}}^{t} K(t, s)(1-\gamma) \gamma^{\frac{\gamma}{1-\gamma}} p_{1}^{\frac{\gamma}{\gamma-1}}(s) p_{2}^{\frac{1}{1-\gamma}}(s) d s \tag{2.16}
\end{equation*}
$$

The rest of the proof is similar to the proof of Theorem 2.3. and will be omitted.
Finally, we consider the case $\beta>1$ and $\gamma<1$.
2.5. Theorem. Let conditions (i)-(iv) hold with $\beta>1$ and $\gamma<1$. In addition to conditions of Theorem 1, assume that there exists a continuous function $\xi: \mathbb{R} \rightarrow(0, \infty)$ such that

$$
\begin{equation*}
\int_{a}^{\infty} \frac{(t-u)^{\alpha-1}}{\Gamma(\alpha)} \int_{a}^{u} K(u, s) p_{1}^{\frac{1}{1-\beta}}(s) \xi^{\frac{\beta}{\beta-1}}(s) d s d u<\infty \tag{2.17}
\end{equation*}
$$

and

$$
\begin{equation*}
\int_{a}^{\infty} \frac{(t-u)^{\alpha-1}}{\Gamma(\alpha)} \int_{a}^{u} K(u, s) \xi^{\frac{\gamma}{\gamma-1}}(s) p_{2}^{\frac{1}{1-\gamma}}(s) d s d u<\infty \tag{2.18}
\end{equation*}
$$

then every solution of Eq.(1.1) is oscillatory.
Proof. Let $x(t)$ be a nonoscillatory solution of Eq.(1.1) with $x(t)>0$ for $t \geq t_{1}$. Using the approach above, from conditions (iii)-(iv) with $\beta>1$ and $\gamma<1$, we have

$$
\begin{align*}
D_{a}^{\alpha} x(t) \leq & v(t)+k p(t)+\int_{t_{1}}^{t} K(t, s)\left[x(s) \xi(s)-p_{1}(s) x^{\beta}(s)\right] d s \\
& +\int_{t_{1}}^{t} K(t, s)\left[p_{2}(s) x^{\gamma}(s)-x(s) \xi(s)\right] d s, \tag{2.19}
\end{align*}
$$

for some $k>0$. Taking $p_{2}(s)=\xi(s)$ in (2.10), and $p_{1}(s)=\xi(s)$ in (2.15), (2.19) yields

$$
\begin{align*}
D_{a}^{\alpha} x(t) \leq & v(t)+k p(t)+\int_{t_{1}}^{t} K(t, s)(\beta-1) \beta^{\frac{\beta}{1-\beta}} p_{1}^{\frac{-1}{\beta-1}}(s) \xi^{\frac{\beta}{\beta-1}}(s) d s \\
& +\int_{t_{1}}^{t} K(t, s)(1-\gamma) \gamma^{\frac{\gamma}{1-\gamma}} \xi^{\frac{\gamma}{\gamma-1}}(s) p_{2}^{\frac{1}{1-\gamma}}(s) d s . \tag{2.20}
\end{align*}
$$

The rest of the proof is similar to that of Theorem 2.3.
2.6. Example. Consider the integro-differential equation with Riemann-Liouville fractional derivative

$$
\begin{equation*}
D_{0}^{1 / 3} x(t)=\frac{t^{2 / 3}}{\Gamma(5 / 3)}+\frac{t^{4}}{3}-t \int_{0}^{t} s x(s) d s, \lim _{t \rightarrow 0^{+}} J_{0}^{2 / 3} x(t)=0 \tag{2.21}
\end{equation*}
$$

Comparing with Eq.(1.1) with $f_{2}=0$, we have

$$
\alpha=\frac{1}{3}, a=b_{1}=0, f_{1}(t, x)=x, v(t)=\frac{t^{2 / 3}}{\Gamma(5 / 3)}+\frac{t^{4}}{3}, K(t, s)=t s .
$$

Conditions (i) $-(i i i)$ are satisfied. But, condition (2.4) fails, since

$$
\liminf _{t \rightarrow \infty}\left[t+\frac{8 t^{13 / 3}}{\Gamma(16 / 3)}\right]=\infty
$$

One can easily verify that $x(t)=t$ is a nonoscillatory solution of Eq.(2.21). Here,

$$
\lim _{t \rightarrow 0^{+}} J_{0}^{2 / 3} x(t)=\lim _{t \rightarrow 0^{+}} \frac{9 t^{5 / 3}}{10 \Gamma(2 / 3)}=0
$$

Note that here $m=k=0$.
2.7. Example. Consider the integro-differential equation with Riemann-Liouville fractional derivative

$$
\begin{equation*}
D_{0}^{1 / 2} x(t)=\frac{8 t^{3 / 2}}{3 \sqrt{\pi}}+\frac{t^{5}}{4}-\frac{t^{4}}{3}-t \int_{0}^{t} s\left[x(s)-\frac{x(s)}{s}\right] d s, \lim _{t \rightarrow 0^{+}} J_{0}^{1 / 2} x(t)=0 \tag{2.22}
\end{equation*}
$$

Now we have
$\alpha=\frac{1}{2}, a=b_{1}=0, f_{1}(t, x)=x, f_{2}(t, x)=\frac{x}{t}, v(t)=\frac{8 t^{3 / 2}}{3 \sqrt{\pi}}+\frac{t^{5}}{4}-\frac{t^{4}}{3}, K(t, s)=t s$.

Conditions $(i)-(i v)$ are satisfied with $\gamma=1, \beta=2$ and $p_{1}(t)=t^{-3}, p_{2}(t)=t$. But, condition (2.8) is not, because

$$
\lim _{t \rightarrow \infty} \frac{1}{7 \sqrt{\pi}} \int_{0}^{t}(t-u)^{-1 / 2} u^{8} d u=\infty
$$

One can easily verify that $x(t)=t^{2}$ is a nonoscillatory solution of Eq.(2.22), as

$$
\lim _{t \rightarrow 0^{+}} J_{0}^{1 / 2} x(t)=\lim _{t \rightarrow 0^{+}} \frac{16 t^{5 / 2}}{15 \sqrt{\pi}}=0
$$

## 3. Results for Caputo Fractional Derivative

If we replace the Caputo fractional derivative by the Riemann-Liouville fractional derivative defined by

$$
{ }^{C} D_{a}^{q} f(t)=J_{a}^{m-q} f^{(m)}(t), m-1<q<m, m \in \mathbb{N},
$$

Eq.(1.1) turns into

$$
\begin{gather*}
{ }^{C} D_{a}^{\alpha} x(t)=v(t)-\int_{a}^{t} K(t, s) F(s, x(s)) d s, \quad m-1<\alpha<m,  \tag{3.1}\\
D^{i} x(a)=b_{i} \in \mathbb{R}, i=0,1, \ldots, m-1
\end{gather*}
$$

Below we provide corresponding results for (3.1). Since the arguments are similar to the Riemann-Liouville case, we only give the proof of the first theorem.
3.1. Theorem. Let conditions (i)-(iii) hold with $f_{2}=0$. If for every constant $k>0$

$$
\begin{equation*}
\limsup _{t \rightarrow \infty} t^{1-m} J_{a}^{\alpha}[v(t)-k p(t)]=+\infty \tag{3.2}
\end{equation*}
$$

and

$$
\begin{equation*}
\liminf _{t \rightarrow \infty} t^{1-m} J_{a}^{\alpha}[v(t)+k p(t)]=-\infty \tag{3.3}
\end{equation*}
$$

then every solution of Eq.(3.1) is oscillatory.
Proof. Let $x(t)$ be a nonoscillatory solution of Eq.(3.1) with $f_{2}=0$. We may assume that $x(t)>0$ for $t \geq t_{1}$. Proceeding as in the proof of Theorem 1, we have

$$
\begin{equation*}
{ }^{C} D_{a}^{\alpha} x(t) \leq v(t)+k p(t) \tag{3.4}
\end{equation*}
$$

Applying the $\alpha$ order fractional operator $J_{a}^{\alpha}$ to (3.4), we have

$$
\begin{equation*}
t^{1-m} x(t) \leq \sum_{k=0}^{m-1} \frac{D^{k} x(a)}{k!}(t-a)^{k-m+1}+t^{1-m} J_{a}^{\alpha}[v(t)+k p(t)] \tag{3.5}
\end{equation*}
$$

Using (3.3) we see that

$$
\liminf _{t \rightarrow \infty} \frac{x(t)}{t^{m-1}}=-\infty
$$

This however contradicts the fact that $x(t)>0$ eventually. This completes the proof.
3.2. Theorem. Let conditions (i)-(iv) hold with $\beta>1$ and $\gamma=1$. In addition to conditions of Theorem 5, if

$$
\begin{equation*}
\lim _{t \rightarrow \infty} t^{1-m} \int_{a}^{t} \frac{(t-u)^{\alpha-1}}{\Gamma(\alpha)} \int_{a}^{u} K(u, s) p_{1}^{\frac{1}{1-\beta}}(s) p_{2}^{\frac{\beta}{\beta-1}}(s) d s d u<\infty \tag{3.6}
\end{equation*}
$$

then every solution of Eq.(3.1) is oscillatory.
3.3. Theorem. Let conditions (i)-(iv) hold with $\beta=1$ and $\gamma<1$. In addition to conditions of Theorem 5, if

$$
\begin{equation*}
\lim _{t \rightarrow \infty} t^{1-m} \int_{a}^{t} \frac{(t-u)^{\alpha-1}}{\Gamma(\alpha)} \int_{a}^{u} K(u, s) p_{1}^{\frac{\gamma}{\gamma-1}}(s) p_{2}^{\frac{1}{1-\gamma}}(s) d s d u<\infty \tag{3.7}
\end{equation*}
$$

then every solution of Eq.(3.1) is oscillatory.
3.4. Theorem. Let conditions (i)-(iv) hold with $\beta>1$ and $\gamma<1$. In addition to conditions of Theorem 5, assume that there exists a continuous function $\xi: \mathbb{R} \rightarrow(0, \infty)$ such that

$$
\begin{equation*}
\lim _{t \rightarrow \infty} t^{1-m} \int_{a}^{t} \frac{(t-u)^{\alpha-1}}{\Gamma(\alpha)} \int_{a}^{u} K(u, s) p_{1}^{\frac{1}{1-\beta}}(s) \xi^{\frac{\beta}{\beta-1}}(s) d s d u<\infty \tag{3.8}
\end{equation*}
$$

and

$$
\begin{equation*}
\lim _{t \rightarrow \infty} t^{1-m} \int_{a}^{t} \frac{(t-u)^{\alpha-1}}{\Gamma(\alpha)} \int_{a}^{u} K(u, s) \xi^{\frac{\gamma}{\gamma-1}}(s) p_{2}^{\frac{1}{1-\gamma}}(s) d s d u<\infty \tag{3.9}
\end{equation*}
$$

then every solution of Eq.(3.1) is oscillatory.,
3.5. Example. Consider the integro-differential equation with Caputo fractional derivative

$$
\begin{equation*}
{ }^{C} D_{0}^{3 / 2} x(t)=\frac{2 t^{1 / 2}}{\sqrt{\pi}}+\frac{t^{5}}{4}-t \int_{0}^{t} s x(s) d s, x(0)=0, x^{\prime}(0)=0 \tag{3.10}
\end{equation*}
$$

Comparing with Eq.(3.1) with $f_{2}=0$, we see

$$
\alpha=\frac{3}{2}, a=b_{1}=b_{2}=0, f_{1}(x, t)=x, v(t)=\frac{2 t^{1 / 2}}{\sqrt{\pi}}+\frac{t^{5}}{4}, K(t, s)=t s
$$

Conditions $(i)-(i i i)$ are satisfied. But, condition (3.3) does not satisfy, because

$$
\liminf _{t \rightarrow \infty}\left[\frac{t}{2}+\frac{256 t^{11 / 2}}{9009 \sqrt{\pi}}\right]=\infty
$$

One can effortlessly verify that $x(t)=t^{2}$ is a nonoscillatory solution of Eq.(3.1).
We end this work with following remark.
3.6. Remark. We noting that the function

$$
K(t, s)=\frac{(t-s)^{\alpha-1}}{\Gamma(\alpha)}
$$

satisfies assumptions $(i)$ and $(i i)$. Therefore, the results given above are valid for equations of the form

$$
D_{a}^{\alpha} x(t)=v(t)-J_{a}^{\alpha} F(t, x(t)), 0<\alpha<1, \lim _{t \rightarrow a^{+}} J_{a}^{1-\alpha} x(t)=b_{3}
$$

## References

[1] Alzabut, J.O., Abdeljawad, T. Sufficient conditions for the oscillation of nonlinear fractional difference equations, J. Fract. Calc. Appl. 5, 177-187, 2014.
[2] Baleanu, D., Diethelm, K., Scalas, E., Trujillo, J.J. Fractional calculus models and numerical methods. Series on Complexity, Nonlinearity and Chaos (World Scientific, 2012).
[3] Baleanu, D., Mustafa, O.G., O'Regan, D. On a fractional differential equation with infinitely many solutions, Adv. Difference. Eq. 2012:145, 6pp, 2012.
[4] Baleanu, D., Mustafa, O.G., O'Regan, D. Kamenev-type result for a linear ( $1+\alpha$ )-order fractional differential equation, App. Math. Comput. 259, 374-378, 2015.
[5] Caputo, M. Linear models of dissipation whose $Q$ is almost frequency independent, II. Reprinted from Geophys. J. R. Astr. Soc. 13, 529-539, 1967. Fract. Calc. Appl. Anal. 11, 4-14, 2008.
[6] Chen, D. X., Qu, P. X., Lan, Y.H. Forced oscillation of certain fractional differential equations, Adv. Difference Equ. 125, 10pp, 2013.
[7] Chen, D. X. Oscillation criteria of fractional differential equations, Adv. Difference Equ. 33, 1-18, 2012.
[8] Chen, D. Oscillatory behavior of a class of fractional differential equations with damping, Universitatea Politehnica din Bucuresti Scientific Bulletin A. 75, 107-118, 2013.
[9] Diethelm, K. and Freed, A.D. On the solution of nonlinear fractional differential equations used in the modelling of viscoplasticity, In: F. Keil, W. Mackens, H. Vob and J. Werther (Eds.), Scientific Computing in Chemical Engineering II: Computational Fluid Dynamics, Reaction Engineering and Molecular Properties, Springer, Heidelberg. 217-224, 1999.
[10] Diethelm, K. The Analysis of Fractional Differential Equations (Springer, 2010).
[11] Edwards, J.T., Ford, N.J., Simpson, A.C. The numerical solution of linear multi-term fractional differential equations: systems of equations, J. Comput. Appl. Math. 148, 401-418, 2002.
[12] Feng, Q. and Meng, F. Oscillation of solutions to nonlinear forced fractional differential equation, Electron. J. Differential Equations 169, 10pp, 2013.
[13] Galeone, L. and Garrappa, R. Explicit methods for fractional differential equations and their stability properties, J. Comput. Appl. Math. 228, 548-560, 2009.
[14] Glőckle, W.G. and Nonnenmacher, T.F. A fractional calculus approach to self similar protein dynamics, Biophys. J. 68, 46-53, 1995.
[15] Grace, S.R., Agarwal, R.P., Wong, P.J.Y., Zafer, A. On the oscillation of fractional differential equations, Fract. Calc. Appl. Anal. 15, 222-231, 2012.
[16] Han, Z., Zhao, Y., Sun, Y., Zhang, C. Oscillation for a class of fractional differential equation, Discrete Dyn. Nat. Soc. 2013, Article ID 390282, 6 pp, 2013.
[17] Hardy, G. H., Littlewood, J. E. and Polya, G. Inequalities (Cambridge University Press, 1988).
[18] Mainardi, F. Fractional calculus: some basic problems in continuum and statistical mechanics. In: Carpinteri, A, Mainardi, F (eds.) Fractals and Fractional Calculus in Continuum Mechanics 378 (Springer-Verlag Wien, 1997), 291-348.
[19] Miller K. S. and Ross, B. An Introduction to the Fractional Calculus and Fractional Differential Equations (JohnWiley \& Sons, 1993).
[20] Muslim, M. Existence and approximation of solutions to fractional differential equations, Math. Comput. Modelling. 49, 1164-1172, 2009.
[21] Öğrekçi, S. Interval oscillation criteria for functional differential equations of factional order, Adv. Difference. Eq. 2015:3, 8pp, 2015.
[22] Podlubny, I. Fractional Differential Equations (Academic Press, 1999).
[23] Samko, S.G., Kilbas, A.A. and Marichev, O.I. Fractional Integrals and Derivatives: Theory and Applications (Gordon and Breach, 1993).
[24] Trigeassou, J.C., Maamri, N., Sabatier, J., Oustaloup, A. A Lyapunov approach to the stability of fractional differential equations, Signal Process. 91, 437-445, 2011.
[25] Zhou, Y., Jiao, F. and Li, J. Existence and uniqueness for p-type fractional neutral differential equations, Nonlinear Anal. 71, 2724-2733, 2009.


[^0]:    *Amasya University, Faculty of Sciences and Arts, Department of Mathematics, 05100, Amasya, Turkey, Email: serkan.asliyuce@amasya.edu.tr, sasliyuce@ankara.edu.tr ${ }^{\dagger}$ Corresponding Author.
    $\ddagger$ Ankara University, Faculty of Science, Department of Mathematics, TR-06100 Ankara, Turkey, Email: guvenili@science.ankara.edu.tr
    §Department of Mathematics and Statistics, College of Engineering and Technology, American University of the Middle East, Kuwait, Email: agacik.zafer@aum.edu.kw Middle East Technical University, Department of Mathematics, 06800 Ankara, Turkey, Email: zafer@metu.edu.tr

