

Araştırma Makalesi / Research Article

On Involutes of Order k of a Space-like Curve in Minkowski 4-space IE_1^4

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Involute; Space-like Curve; W-curve; Helix.

Abstract

The orthogonal trajectories of the first tangents of a curve x are called the involutes of x. In this study, we give a characterization of involutes of order k of a space-like curve x with time-like principal normal in Minkowski 4-space IE_1^4 .

IE_1^4 Minkowski 4-uzayında bir Space-like Eğrinin k'yinci Mertebeden involütleri Üzerine

Özet

Anahtar kelimeler

involüt; Space-like Eğri; W-eğrisi; Helis.

Bir x eğrisinin birinci teğetlerinin dik yörüngelerine eğrinin involütleri adı verilir. Bu çalışmada, IE_1^4 Minkowski 4-uzayında time-like asli normalli bir space-like eğrinin k'yinci mertebeden involütlerinin bir karakterizasyonunu verdik.

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1. Introduction

IE_1^4 Minkowski space-time IE_1^4 is a pseudo-Euclidean space IE^4 provided with the standart flat metric given by

$$g = -dx_1^2 + dx_2^2 + dx_3^2 + dx_4^2, \tag{1}$$

where (x_1, x_2, x_3, x_4) is a rectangular coordinate system in IE_1^4 . Since g is an indefinite metric, recall that a vector $v \in IE_1^4$ can have one of the three causal characters; it can be space-like if $g(v, v) > 0$ or $v = 0$, time-like if $g(v, v) < 0$, and null (light-like) if $g(v, v) = 0$ and $v \neq 0$. Similarly, an arbitrary curve $x = x(s)$ in IE_1^4 can be locally space-like, time-like or null if all of its velocity vectors $x'(s)$ are respectively space-like, time-like or null. Also, recall the norm of a vector v is given by $\|v\| = \sqrt{|g(v, v)|}$. Therefore, v is a unit vector if $g(v, v) = \pm 1$. Next, vectors v, w in IE_1^4 are said to be orthogonal if $g(v, w) = 0$. The velocity of the curve x(s) is given by $\|x'(s)\|$. Space-like or time-like curve x(s) is said

to be parametrized by arc-length function s, if $g(x'(s), x'(s)) = \pm 1$ (O'Neill, 1983).

Let x(s) be a space-like curve with a time-like principal normal in the space-time IE_1^4 , parametrized by arc-length function s. Then we have the following Frenet equations (Walfare, 1995):

$$\begin{bmatrix} V_1' \\ V_2' \\ V_3' \\ V_4' \end{bmatrix} = \begin{bmatrix} 0 & k_1 & 0 & 0 \\ k_1 & 0 & k_2 & 0 \\ 0 & k_2 & 0 & k_3 \\ 0 & 0 & -k_3 & 0 \end{bmatrix} \begin{bmatrix} V_1 \\ V_2 \\ V_3 \\ V_4 \end{bmatrix}, \tag{2}$$

where V_1, V_2, V_3 and V_4 are the Frenet vectors satisfy the equations:

$$g(V_1, V_1) = g(V_3, V_3) = g(V_4, V_4) = 1, \quad g(V_2, V_2) = -1.$$

Here k_1, k_2, k_3 are respectively, the first, the second and the third curvatures of the curve x(s).

Definition 1. (Yılmaz and Turgut, 2008) Let $a = (a_1, a_2, a_3, a_4)$, $b = (b_1, b_2, b_3, b_4)$ and $c = (c_1, c_2, c_3, c_4)$ be vectors in IE_1^4 . The vector

product in Minkowski space-time IE_1^4 is defined by the determinant

$$a \wedge b \wedge c = - \begin{vmatrix} -e_1 & e_2 & e_3 & e_4 \\ a_1 & a_2 & a_3 & a_4 \\ b_1 & b_2 & b_3 & b_4 \\ c_1 & c_2 & c_3 & c_4 \end{vmatrix}, \quad (3)$$

where e_1, e_2, e_3 and e_4 are mutually orthogonal vectors satisfying the equations

$$e_1 \wedge e_2 \wedge e_3 = e_4, \quad e_2 \wedge e_3 \wedge e_4 = e_1, \\ e_3 \wedge e_4 \wedge e_1 = e_2, \quad e_4 \wedge e_1 \wedge e_2 = -e_3.$$

Let $x(s)$ be a space-like curve in IE_1^4 . The Frenet frame vectors V_1, V_2, V_3, V_4 and Frenet curvatures k_1, k_2, k_3 are given by

$$V_1(s) = \frac{x'(s)}{\|x'(s)\|}, \\ V_4(s) = \frac{x'(s) \wedge x''(s) \wedge x'''(s)}{\|x'(s) \wedge x''(s) \wedge x'''(s)\|}, \\ V_3(s) = \frac{V_4 \wedge x'(s) \wedge x''(s)}{\|V_4 \wedge x'(s) \wedge x''(s)\|}, \quad (4) \\ V_2(s) = \frac{V_3 \wedge V_4 \wedge x'(s)}{\|V_3 \wedge V_4 \wedge x'(s)\|}$$

and

$$k_1(s) = \frac{g(V_2(s), x''(s))}{\|x'(s)\|^2}, \\ k_2(s) = \frac{g(V_3(s), x'''(s))}{\|x'(s)\|^3 k_1(s)}, \quad (5) \\ k_3(s) = \frac{g(V_4(s), x^{(iv)}(s))}{\|x'(s)\|^4 k_1(s)k_2(s)},$$

respectively, where \wedge is vector product in IE_1^4 (Gluck, 1966).

A curve which has constant first Frenet curvature IE_1^4 is called a Salkowski curve (Salkowski, 1909). (or T.C-curve (Kılıç et al. 2008)). An arbitrary curve is called W-curve or (circular) helix if it has constant Frenet curvatures (Klein and

Lie, 1871). Meanwhile, a curve with constant curvature ratios IE_1^4 is called a ccr-curve (Monterde, 2007), (Öztürk et al. 2008).

In (Öztürk et al.) (2016), the authors gave a characterization of involutes of order k of a given curve in IE^n . They obtain some results about the involutes of order 1, 2, 3 of a given curve in IE^3, IE^4 , respectively.

In the present study, we give a characterization of involutes of order k of a space-like curve x in Minkowski space-time IE_1^4 .

2. Involute curves of order k

Definition 2. Let $x(s)$ be a regular space-like curve in IE_1^4 given with arc-length parameter s . Then the curves which are orthogonal to the system of k -dimensional osculating hyperplanes of x are called the involutes of k (or k^{th} involute) of the curve x (Balazenska and Zeljka 1999). For simplicity, we call the involutes of order 1, the involute of the given curve.

In order to find the parametrization of involutes $\bar{x}(s)$ of order k of the curve x in IE_1^4 , we put

$$\bar{x}(s) = x(s) + \sum_{i=1}^k \lambda_i(s) V_i(s), \quad k \leq 3, \quad (6)$$

where λ_i is a differentiable function and s , which is not necessarily an arc-length parameter, is the parameter of $\bar{x}(s)$.

Furthermore, the involutes \bar{x} of order k of the curve x in IE_1^4 are determined by

$$g(\bar{x}'(s), V_i(s)) = 0, \quad 1 \leq i \leq k \leq 3. \quad (7)$$

2.1. Involute curves of order 1

Theorem 1. Let $x(s)$ be a space-like curve with time-like principal normal in IE_1^4 given with the

Frenet curvatures k_1, k_2, k_3 . Then, the involute \bar{x} of the curve x is a time-like curve with the Frenet frame vectors $\bar{V}_1, \bar{V}_2, \bar{V}_3, \bar{V}_4$ and Frenet curvatures $\bar{k}_1, \bar{k}_2, \bar{k}_3$ which are given by

$$\begin{aligned} \bar{V}_1(s) &= V_2, \\ \bar{V}_2(s) &= \frac{k_1 V_1 + k_2 V_3}{\sqrt{k_1^2 + k_2^2}}, \\ \bar{V}_3(s) &= \frac{1}{W\sqrt{k_1^2 + k_2^2}} \begin{pmatrix} -k_2(k_2 A - k_1 C)V_1 \\ +k_1(k_2 A - k_1 C)V_3 \\ -D(k_1^2 + k_2^2)V_4 \end{pmatrix}, \quad (8) \\ \bar{V}_4(s) &= \frac{1}{W}(-k_2 D V_1 + k_1 D V_3 + (k_2 A - k_1 C)V_4), \end{aligned}$$

and

$$\begin{aligned} \bar{k}_1(s) &= \frac{\sqrt{k_1^2 + k_2^2}}{\varphi}, \\ \bar{k}_2(s) &= -\frac{W}{\varphi^2(k_1^2 + k_2^2)}, \quad (9) \\ \bar{k}_3(s) &= -\frac{\sqrt{k_1^2 + k_2^2}}{W^2 \varphi} \begin{pmatrix} (k_2 A - k_1 C)(k_3 C + D') \\ +D(k_1 C' - k_2 A') - k_1 k_3 D^2 \end{pmatrix} \end{aligned}$$

respectively, where

$$\begin{aligned} \varphi &= (c-s)k_1, \\ A &= k_1' \varphi + 2k_1 \varphi', \\ B &= k_1^2 \varphi + \varphi'' + k_2^2 \varphi, \\ C &= k_2' \varphi + 2k_2 \varphi', \\ D &= k_2 k_3 \varphi, \end{aligned}$$

and

$$\begin{aligned} W &= \sqrt{D^2(k_1^2 + k_2^2) + (k_2 A - k_1 C)^2} \\ &= |\varphi| \sqrt{k_2^2 k_3^2 (k_1^2 + k_2^2) + (k_1' k_2 - k_1 k_2')^2}. \quad (10) \end{aligned}$$

Proof. Let $\bar{x}(s)$ be the involute of a space-like curve x with time-like principal normal in IE_1^4 . Then by the use of (6) with (7), we get $1 + \lambda_1'(s) = 0$, and furthermore $\lambda_1(s) = (c-s)$ for some constant c . We have the following parametrization

$$\bar{x}(s) = x(s) + (c-s)V_1(s) \quad (11)$$

Further, differentiating the equation (11), we find

$$\begin{aligned} \bar{x}'(s) &= \varphi V_2, \\ \bar{x}''(s) &= \varphi k_1 V_1 + \varphi' V_2 + \varphi k_2 V_3, \quad (12) \end{aligned}$$

$$\begin{aligned} \bar{x}'''(s) &= (k_1' \varphi + 2k_1 \varphi')V_1 + (k_1^2 \varphi + \varphi'' + k_2^2 \varphi)V_2 \\ &\quad + (k_2' \varphi + 2k_2 \varphi')V_3 + k_2 k_3 V_4 \end{aligned}$$

where $\varphi(s) = \lambda_1(s)k_1(s)$ is a differentiable function. Substituting

$$\begin{aligned} A &= k_1' \varphi + 2k_1 \varphi', \\ B &= k_1^2 \varphi + \varphi'' + k_2^2 \varphi, \\ C &= k_2' \varphi + 2k_2 \varphi', \\ D &= k_2 k_3 \varphi. \end{aligned}$$

in the last equation, we obtain

$$\bar{x}'''(s) = AV_1 + BV_2 + CV_3 + DV_4.$$

Furthermore, differentiating $\bar{x}'''(s)$ with respect to s , we get

$$\begin{aligned} \bar{x}^{(iv)}(s) &= (A' + k_1 B)V_1 + (B' + k_1 A + k_2 C)V_2 \\ &\quad + (C' + k_2 B - k_3 D)V_3 + (k_3 C + D')V_4 \end{aligned}$$

By the use of (12), we find

$$\bar{V}_1(s) = V_2.$$

While $g(V_2, V_2) = -1$, we can write $g(\bar{V}_1, \bar{V}_1) = -1$ which implies that involute \bar{x} is a time-like curve.

Then we can compute the vector form $\bar{x}'(s) \wedge \bar{x}''(s) \wedge \bar{x}'''(s)$ and \bar{V}_4 of \bar{x} as in the following:

$$\bar{x}'(s) \wedge \bar{x}''(s) \wedge \bar{x}'''(s) = \varphi^2 \begin{pmatrix} -k_2 D V_1 + k_1 D V_3 \\ + (k_2 A - k_1 C)V_4 \end{pmatrix}$$

and

$$\begin{aligned} \bar{V}_4(s) &= \frac{\bar{x}'(s) \wedge \bar{x}''(s) \wedge \bar{x}'''(s)}{\|\bar{x}'(s) \wedge \bar{x}''(s) \wedge \bar{x}'''(s)\|} \\ &= \frac{1}{W}(-k_2 D V_1 + k_1 D V_3 + (k_2 A - k_1 C)V_4) \end{aligned}$$

where

$$W = \sqrt{D^2(k_1^2 + k_2^2) + (k_2 A - k_1 C)^2}.$$

Similarly, we can compute

$$\bar{V}_4 \wedge \bar{x}'(s) \wedge \bar{x}''(s) = \frac{\varphi^2}{W} \begin{pmatrix} -k_2(k_2 A - k_1 C)V_1 \\ +k_1(k_2 A - k_1 C)V_3 \\ -D(k_1^2 + k_2^2)V_4 \end{pmatrix}$$

and

$$\begin{aligned} \bar{V}_3 &= \frac{\bar{V}_4 \wedge \bar{x}'(s) \wedge \bar{x}''(s)}{\|\bar{V}_4 \wedge \bar{x}'(s) \wedge \bar{x}''(s)\|} \\ &= \frac{1}{W\sqrt{k_1^2+k_2^2}} \begin{pmatrix} -k_2(k_2A-k_1C)V_1 \\ +k_1(k_2A-k_1C)V_3 \\ -D(k_1^2+k_2^2)V_4 \end{pmatrix} \end{aligned}$$

Finally, if we calculate $\bar{V}_3 \wedge \bar{V}_4 \wedge \bar{x}'(s)$ and substitute in (4), we get

$$\bar{V}_2(s) = \frac{k_1V_1+k_2V_3}{\sqrt{k_1^2+k_2^2}}.$$

Consequently, an easy calculation gives

$$\begin{aligned} g(\bar{V}_2(s), \bar{x}''(s)) &= \varphi\sqrt{k_1^2+k_2^2}, \\ g(\bar{V}_3(s), \bar{x}'''(s)) &= -\frac{W}{\sqrt{k_1^2+k_2^2}}, \end{aligned} \tag{13}$$

$$g(\bar{V}_4(s), \bar{x}^{(iv)}(s)) = \frac{1}{W} \left((k_2A-k_1C)(k_3C+D') + D(k_1C'-k_2A')-k_1k_3D^2 \right).$$

Hence, from equations (13) and (5), we get (9), which completes the proof.

For the case x is a W -curve, one can get the following results.

Corollary 1 Let $x(s)$ be a space-like curve with time-like principal normal in IE_1^4 given with the Frenet curvatures k_1, k_2, k_3 . If x is a W -curve, then the Frenet frame vectors $\bar{V}_1, \bar{V}_2, \bar{V}_3, \bar{V}_4$ and Frenet curvatures $\bar{k}_1, \bar{k}_2, \bar{k}_3$ of the involute \bar{x} of the curve x are given by

$$\begin{aligned} \bar{V}_1(s) &= V_2, \\ \bar{V}_2(s) &= \frac{k_1V_1+k_2V_3}{\sqrt{k_1^2+k_2^2}}, \\ \bar{V}_3(s) &= V_4, \\ \bar{V}_4(s) &= \frac{-k_2V_1+k_1V_3}{\sqrt{k_1^2+k_2^2}}, \end{aligned} \tag{14}$$

and

$$\begin{aligned} \bar{k}_1(s) &= \frac{\sqrt{k_1^2+k_2^2}}{(c-s)k_1}, \\ \bar{k}_2(s) &= \frac{k_2k_3}{(c-s)k_1(k_1^2+k_2^2)}, \end{aligned} \tag{15}$$

$$\bar{k}_3(s) = \frac{k_3}{(c-s)\sqrt{k_1^2+k_2^2}},$$

respectively (Turgut et al. 2010).

Corollary 2. Let $\bar{x}(s)$ be an involute of a space-like curve x with time-like principal normal in IE_1^4 given with the Frenet curvatures $\bar{k}_1, \bar{k}_2, \bar{k}_3$. If x is a W -curve, then \bar{x} becomes a ccr-curve.

2.2. Involute of order 2

An involute of order 2 of a space-like curve x in IE_1^4 has the parametrization

$$\bar{x}(s) = x(s) + \lambda_1(s)V_1(s) + \lambda_2(s)V_2(s) \tag{16}$$

where λ_1, λ_2 are differential functions satisfying

$$\begin{aligned} \lambda_1'(s) &= -1 - \lambda_2(s)k_1(s) \\ \lambda_2'(s) &= -\lambda_1(s)k_1(s). \end{aligned} \tag{17}$$

From the differentiable equation system (17), we get the following result.

Corollary 3. Let $x = x(s)$ be a space-like Salkowski curve with time-like principal normal in IE_1^4 . Then the involute \bar{x} of order 2 of the curve x has the parametrization (16) given with the coefficient functions

$$\begin{aligned} \lambda_1(s) &= c_1 \cosh(k_1s) + c_2 \sinh(k_1s) \\ \lambda_2(s) &= -c_1 \sinh(k_1s) - c_2 \cosh(k_1s) - \frac{1}{k_1} \end{aligned}$$

where c_1 and c_2 are real constants.

Theorem 2. Let $x = x(s)$ be a space-like curve with time-like principal normal in IE_1^4 given with Frenet curvatures k_1, k_2, k_3 . Then the involute \bar{x} of order 2 of the curve x is a space-like curve with the Frenet frame vectors $\bar{V}_1, \bar{V}_2, \bar{V}_3, \bar{V}_4$ and Frenet curvatures $\bar{k}_1, \bar{k}_2, \bar{k}_3$ which are given by

$$\begin{aligned} \bar{V}_1(s) &= V_3, \\ \bar{V}_2(s) &= \frac{k_2 V_2 + k_3 V_4}{\sqrt{|k_3^2 - k_2^2|}}, \end{aligned} \tag{18}$$

$$\bar{V}_3(s) = \frac{1}{\bar{W}\sqrt{|k_3^2 - k_2^2|}} \begin{pmatrix} K(k_3^2 - k_2^2)V_1 - k_3(k_2N - k_3L)V_2 \\ -k_2(k_2N - k_3L)V_4 \end{pmatrix}$$

$$\bar{V}_4(s) = \frac{1}{\bar{W}} ((k_2N - k_3L)V_1 - k_3KV_2 - k_2KV_4),$$

and

$$\begin{aligned} \bar{k}_1(s) &= \frac{\sqrt{|k_3^2 - k_2^2|}}{\phi}, \\ \bar{k}_2(s) &= -\frac{\bar{W}}{\phi^2(k_3^2 - k_2^2)}, \\ \bar{k}_3(s) &= -\frac{\sqrt{|k_3^2 - k_2^2|}}{\bar{W}^2\phi} \begin{pmatrix} (k_2N - k_3L)(K' + k_1L) \\ + K(k_3L' - k_2N') \\ + k_1k_3K^2 \end{pmatrix}, \end{aligned} \tag{19}$$

where

$$\begin{aligned} \phi &= \lambda_2 k_2, \\ K &= k_1 k_2 \phi, \\ L &= k_2' \phi + 2k_2 \phi', \\ N &= k_3' \phi + 2k_3 \phi', \end{aligned}$$

and

$$\begin{aligned} \bar{W} &= \sqrt{|(k_2N - k_3L)^2 - K^2(k_3^2 - k_2^2)|} \\ &= |\phi| \sqrt{|(k_2k_3' - k_2'k_3)^2 - k_1^2k_2^2(k_3^2 - k_2^2)|}. \end{aligned}$$

Proof. Let $\bar{x} = \bar{x}(s)$ be the involute of order 2 of a space-like curve with time-like principal normal in IE_1^4 . Then by the use of (16) with (7), we get

$$\bar{x}'(s) = \phi V_3, \tag{20}$$

where $\phi(s) = \lambda_2(s)k_2(s)$ is a differentiable function.

By the use of (20), we find

$$\bar{V}_1(s) = V_3.$$

While $g(V_3, V_3) = 1$, we can write $g(\bar{V}_1, \bar{V}_1) = 1$ which implies that involute \bar{x} of order 2 is a space-like curve.

Further, the differentiation of (20) implies that

$$\bar{x}''(s) = \phi k_2 V_2 + \phi' V_3 + \phi k_4 V_4, \tag{21}$$

$$\begin{aligned} \bar{x}'''(s) &= k_1 k_2 \phi V_1 + (k_2' \phi + 2k_2 \phi') V_2 \\ &\quad + (k_2^2 \phi + \phi'' - k_3^2 \phi) V_3 + (k_3' \phi + 2k_3 \phi') V_4. \end{aligned}$$

Consequently, substituting

$$\begin{aligned} K &= k_1 k_2 \phi, \\ L &= k_2' \phi + 2k_2 \phi', \\ M &= k_2^2 \phi + \phi'' - k_3^2 \phi, \\ N &= \phi k_3' \phi + 2k_3 \phi', \end{aligned}$$

in the last vector, we obtain

$$\bar{x}'''(s) = KV_1 + LV_2 + MV_3 + NV_4. \tag{22}$$

Furthermore, differentiating \bar{x}''' with respect to s , we get

$$\begin{aligned} \bar{x}^{(iv)}(s) &= (K' + k_1L)V_1 + (L' + k_1K + k_2M)V_2 \\ &\quad + (M' + k_2L - k_3N)V_3 + (N' + k_3M)V_4 \end{aligned} \tag{23}$$

Hence substituting (20)-(23) into (4) and (5), after making some calculations as in the previous theorem, we obtain the result.

For the case x is a W -curve, one can get the following result.

Corollary 4. Let \bar{x} be an involute of order 2 of a space-like curve with time-like principal normal in IE_1^4 given with the Frenet curvatures $\bar{k}_1, \bar{k}_2, \bar{k}_3$. If x is a W -curve, then the Frenet frame vectors $\bar{V}_1, \bar{V}_2, \bar{V}_3, \bar{V}_4$ and Frenet curvatures $\bar{k}_1, \bar{k}_2, \bar{k}_3$ of the involute \bar{x} of order 2 of the curve x are given by

$$\begin{aligned} \bar{V}_1(s) &= V_3, \\ \bar{V}_2(s) &= \frac{k_2 V_2 + k_3 V_4}{\sqrt{|k_3^2 - k_2^2|}}, \\ \bar{V}_3(s) &= V_1, \\ \bar{V}_4(s) &= \frac{k_3 V_2 + k_2 V_4}{\sqrt{|k_3^2 - k_2^2|}}, \end{aligned} \tag{24}$$

and

$$\begin{aligned} \bar{k}_1(s) &= \frac{\sqrt{|k_3^2 - k_2^2|}}{\phi}, \\ \bar{k}_2(s) &= -\frac{k_1 k_2}{\phi \sqrt{|k_3^2 - k_2^2|}}, \end{aligned} \tag{25}$$

$$\bar{k}_3(s) = -\frac{k_1 k_3}{\phi \sqrt{|k_3^2 - k_2^2|}},$$

where $\phi(s) = \lambda_2(s)k_2(s)$.

Corollary 5. Let \bar{x} be an involute of order 2 of a space-like curve x with time-like principal normal in IE_1^4 given with the Frenet curvatures $\bar{k}_1, \bar{k}_2, \bar{k}_3$. If x is a W-curve, then \bar{x} becomes a ccr-curve.

2.3. Involute of order 3

An involute of order 3 of a space-like curve x in IE_1^4 has the parametrization

$$\bar{x}(s) = x(s) + \lambda_1(s)V_1(s) + \lambda_2(s)V_2(s) + \lambda_3(s)V_3(s) \quad (26)$$

where $\lambda_1, \lambda_2, \lambda_3$ are differentiable functions satisfying

$$\begin{aligned} \lambda_1'(s) &= -1 - \lambda_2(s)k_1(s), \\ \lambda_2'(s) &= -\lambda_1(s)k_1(s) - \lambda_3(s)k_2(s), \\ \lambda_3'(s) &= -\lambda_2(s)k_2(s). \end{aligned} \quad (27)$$

By solving the differential equation system (27), we get the following result.

Corollary 6. Let $x = x(s)$ be a space-like W-curve with time-like principal normal in IE_1^4 . Then the involute \bar{x} of order 3 of the curve x has the parametrization (26) given with the coefficient functions

$$\begin{aligned} \lambda_1(s) &= \frac{k_1(c_3 \cos(ks) - c_2 \sin(ks))}{k} - \frac{k_2^2 s}{k^2} + c_1, \\ \lambda_2(s) &= c_2 \cos(ks) + c_3 \sin(ks) - \frac{k_1}{k^2}, \\ \lambda_3(s) &= \frac{k_2(c_3 \cos(ks) - c_2 \sin(ks))}{k} + \frac{k_1 k_2 s}{k^2} - \frac{c_1 k_1}{k_2}, \end{aligned}$$

where $k = \sqrt{k_1 + k_2}$, c_1, c_2 and c_3 are real constants.

Theorem 3. Let $x = x(s)$ be a space-like curve with time-like principal normal in IE_1^4 given with Frenet curvatures k_1, k_2 and k_3 . Then the involute \bar{x} of order 3 of the curve x is a space-like curve with the

Frenet frame vectors $\bar{V}_1, \bar{V}_2, \bar{V}_3, \bar{V}_4$ and Frenet curvatures $\bar{k}_1, \bar{k}_2, \bar{k}_3$ which are given by

$$\begin{aligned} \bar{V}_1(s) &= V_4, \\ \bar{V}_2(s) &= -V_3, \end{aligned} \quad (28)$$

$$\begin{aligned} \bar{V}_3(s) &= V_2, \\ \bar{V}_4(s) &= -V_1 \end{aligned}$$

and

$$\begin{aligned} \bar{k}_1(s) &= \frac{k_3}{\psi}, \\ \bar{k}_2(s) &= -\frac{k_2}{\psi}, \end{aligned} \quad (29)$$

$$\bar{k}_3(s) = -\frac{k_1}{\psi},$$

where $\psi(s) = \lambda_3(s)k_3(s)$.

Proof. Let $\bar{x} = \bar{x}(s)$ be the involute of order 3 of a space-like curve with time-like principal normal in IE_1^4 . Then by the use of (26) with (7), we get

$$\bar{x}'(s) = \psi V_4 \quad (30)$$

where $\psi(s) = \lambda_3(s)k_3(s)$ is a differentiable function. By the use of (30), we find

$$\bar{V}_1(s) = V_4.$$

While $g(V_4, V_4) = 1$, we can write $g(\bar{V}_1, \bar{V}_1) = 1$ which implies that involute \bar{x} of order 3 is a space-like curve.

Further, the differentiation of (29) implies that

$$\begin{aligned} \bar{x}''(s) &= -k_3 \psi V_3 + \psi' V_4, \\ \bar{x}'''(s) &= -k_2 k_3 \psi V_2 - (k_3' \psi + 2k_3 \psi') V_3 \\ &\quad + (\psi'' - k_3^2 \psi) V_4. \end{aligned} \quad (31)$$

Consequently, substituting

$$\begin{aligned} E &= -k_2 k_3 \psi \\ F &= -(k_3' \psi + 2k_3 \psi') \\ G &= \psi'' - k_3^2 \psi \end{aligned}$$

in the last vector, we obtain

$$\bar{x}''''(s) = EV_2 + FV_3 + GV_4. \quad (32)$$

Furthermore, differentiating \bar{x}'''' with respect to s , we get

$$\begin{aligned} \bar{x}^{(v)}(s) &= k_1 EV_1 + (E' + k_2 F) V_2 \\ &\quad + (F' + k_2 E - k_3 G) V_3 + (G' + k_3 F) V_4 \end{aligned} \quad (33)$$

Hence substituting (30)-(33) into (4) and (5), after some calculations as in the previous theorem, we obtain the result.

Corollary 7. The involute \bar{x} of order 3 of a space-like ccr-curve x with time-like principal normal in IE_1^4 is also a ccr-curve in IE_1^4 .

3. Conclusion

In recent years, many authors have studied with the involute-evolute curve couples in many paper. Turgut et al. (2010) gave the characterization of the involute of order 1 (involute) of a W-curve in IE_1^4

In this paper, we study involute curves of order k of a space-like curve x with time-like principal normal in Minkowski 4-space IE_1^4 . First, we investigate an involute curve of order 1 of a given curve. Furthermore, we give the characterizations of the involutes of order 2 and 3. We obtain the Frenet Frame and Frenet curvatures of the involutes of order k of the curve with respect to the Frenet Frame and Frenet curvatures of the given curve.

Nowadays, as known W-curve (or helix) is very important topic in curve theory, we characterize the involutes of order k of a W-curve in IE_1^4 .

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