

Constructions of Type III^+ Helicoidal Surfaces in Minkowski Space with Density

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ABSTRACT

In this paper, we construct a helicoidal surface of type III^+ with prescribed weighted mean curvature and weighted Gaussian curvature in the Minkowski 3–space R_1^3 with a positive density function. We get a result for minimal case. Also we give examples of helicoidal surface with prescribed weighted mean curvature and Gaussian curvature.

Keywords: Minkowski space; manifold with density; weighted curvature; helicoidal.

AMS Subject Classification (2010): Primary: 53A10 ; Secondary: 53C50.

1. Introduction

It is well known that a helicoidal surface is a generalization of a rotation surface. There are many studies about these surfaces under some given certain conditions [1, 7, 9, 16, 19]. Recently, the popular question is whether a helicoidal surface can be constructed when its curvatures are prescribed. Several researchers worked on this problem and obtained useful results. Firstly, helicoidal surfaces with prescribed mean and Gaussian curvature in \mathbb{R}^3 have been studied by Baikoussis et. al [2]. Then, Beneki et. al [3] and Ji et. al [10] have studied the similar work in \mathbb{R}_1^3 . This problem is extended to manifolds with density. Dae Won Yoon et. al have studied the helicoidal surfaces with prescribed weighted mean and weighted Gaussian curvature in \mathbb{R}^3 with density [22]. Furthermore, Yıldız et. al have constructed the type I^+ helicoidal surfaces with prescribed weighted curvatures in \mathbb{R}_1^3 with density [20].

A manifold with a positive density function ψ used to weight the volume and the hypersurface area. In terms of the underlying Riemannian volume dV_0 and area dA_0 , the new, weighted volume and area are given by $dV = \psi dV_0$ and $dA = \psi dA_0$, respectively. One of the most important examples of manifolds with density, with applications to probability and statistics, is Gauss space with density $\psi = e^{a(-x^2-y^2-z^2)}$ for $a \in \mathbb{R}$, $(x, y, z) \in \mathbb{R}^3$ [15]. For more details on manifolds with density, see [8, 12, 13, 14, 15, 17, 18].

In the Minkowski 3–space with density e^φ , the weighted mean curvature is given with

$$H_\varphi = H - \frac{1}{2} \langle N, \nabla \varphi \rangle$$

where H is the mean curvature of the surface, N is the unit normal vector of the surface and $\nabla \varphi$ is the gradient vector of φ [17]. If $H_\varphi = 0$ then the surface is called weighted minimal surface. The weighted Gaussian curvature with density e^φ is

$$G_\varphi = G - \Delta \varphi$$

where G is the Gaussian curvature of the surface and Δ is the Laplacian operator [5].

In this paper, we study helicoidal surfaces in the Minkowski 3–space R_1^3 with density e^φ , where $\varphi = -x_2^2 - x_3^2$. Firstly, we consider helicoidal surfaces of type III^+ , defined in [3]. Then, we construct a helicoidal surface of type III^+ with prescribed weighted mean and weighted Gaussian curvature. We give the classification of weighted minimal helicoidal surfaces. Finally, we give examples to illustrate our result.

2. Preliminaries

The Minkowski 3–space \mathbb{R}_1^3 is the real vector space \mathbb{R}^3 provided with the standard flat metric given by

$$ds^2 = -dx_1^2 + dx_2^2 + dx_3^2$$

where (x_1, x_2, x_3) is a rectangular coordinate system of \mathbb{R}_1^3 .

For a given plane curve and an axis in the plane in \mathbb{R}_1^3 , a helicoidal surface can be constructed by the plane curve under helicoidal motions $g_t : \mathbb{R}_1^3 \rightarrow \mathbb{R}_1^3, t \in \mathbb{R}$ around the axis. So, a helicoidal surface is non-degenerate and invariant under $g_t, t \in \mathbb{R}$ for which one parameter subgroup of rigid motions is in \mathbb{R}_1^3 . There exist four kinds of helicoidal surfaces in \mathbb{R}_1^3 which are defined by Beneki et. al [3] and these are called type *I*, type *II*, type *III*, type *IV*. In this study, type *III*⁺ is considered which has the timelike axis of revolution and the profile curve in x_1x_2 –plane. In addition, the helicoidal surface is called type *III*⁺ since the discriminant of the first fundamental form $u^2(1 - g'^2) - c^2$ is positive [3].

Let γ be a C^2 –curve on x_1x_2 –plane of type $\gamma(u) = (g(u), u, 0)$ where $u \in I$ for an open interval $I \subset \mathbb{R} - \{0\}$. By using helicoidal motion on γ , we can obtain the helicoidal as

$$X(u, v) = \begin{bmatrix} 1 & 0 & 0 \\ 0 & \cos v & -\sin v \\ 0 & \sin v & \cos v \end{bmatrix} \begin{bmatrix} g(u) \\ u \\ 0 \end{bmatrix} + \begin{bmatrix} cv \\ 0 \\ 0 \end{bmatrix} \tag{2.1}$$

with x_1 –axis and a pitch $c \in \mathbb{R}$. So the parametric equation can be given in the form

$$X(u, v) = (g(u) + cv, u \cos v, u \sin v). \tag{2.2}$$

It is straightforward to see that the mean curvature H , the Gaussian curvature G and the unit normal of surface N are

$$\begin{aligned} H &= \frac{(1 - g'^2)u^2g' + (u^2 - c^2)ug'' - 2c^2g'}{2[u^2(1 - g'^2) - c^2]^{3/2}}, \\ G &= \frac{u^3g'g'' - c^2}{[u^2(1 - g'^2) - c^2]^2}, \\ N &= \frac{1}{\sqrt{u^2(1 - g'^2) - c^2}}(-u, c \sin v - ug' \cos v, -c \cos v - ug' \sin v), \end{aligned}$$

where $u^2(1 - g'^2) - c^2 > 0$ [3]. We assume that M is the surface in \mathbb{R}_1^3 with density e^φ , where $\varphi = -x_2^2 - x_3^2$. By considering density function, we can calculate the weighted mean curvature H_φ and the weighted Gaussian curvature G_φ as

$$H_\varphi = \frac{(u^2 - c^2)ug'' - (u^2 - 2u^4)g'^3 + (u^2 + 2c^2 - 2u^4 + 2c^2u^2)g'}{2(u^2(1 - g'^2) - c^2)^{3/2}} \tag{2.3}$$

and

$$G_\varphi = \frac{u^3g'g'' - c^2}{2(u^2(1 - g'^2) - c^2)^2} + 4. \tag{2.4}$$

3. Helicoidal surfaces with prescribed mean or Gaussian curvature

Theorem 3.1. *Let $\gamma(u)$ be a profile curve of the helicoidal surface given with $X(u, v) = (g(u) + cv, u \cos v, u \sin v)$ in \mathbb{R}_1^3 with density $e^{-x_2^2 - x_3^2}$ and $H_\varphi(u)$ be the weighted mean curvature. Then, there exists a two-parameter family of helicoidal surface given by the curves*

$$\gamma(u, H_\varphi(u), c, c_1, c_2) = \left(\mp \int \frac{e^{u^2} \sqrt{u^2 - c^2} \left(2 \int ue^{-u^2} H_\varphi du + c_1 \right)}{u \sqrt{u^2 + e^{2u^2} \left(2 \int ue^{-u^2} H_\varphi du + c_1 \right)^2}} du + c_2, u, 0 \right).$$

Conversely, for a given smooth function $H_\varphi(u)$, one can obtain the two-parameter family of curves $\gamma(u, H_\varphi(u), c, c_1, c_2)$ being the two-parameter family of helicoidal surfaces, accepting $H_\varphi(u)$ as the weighted mean curvature c as a pitch.

Proof. Let's solve the equation (2.3) which is a second-order nonlinear ordinary differential equation. If we apply $A = \frac{g'(u)}{\sqrt{(u^2(1-g'^2)-c^2)}}$ into the equation, then we get

$$H_\varphi = \frac{u}{2}A' + (1 - u^2) A. \tag{3.1}$$

The equation (3.1) becomes a first-order linear ordinary differential equation with respect to A and we rewrite the equation as follows

$$A' + \left(\frac{2}{u} - 2u\right) A = \frac{2}{u}H_\varphi. \tag{3.2}$$

Then the general solution of (3.2) is

$$A = \frac{e^{u^2}}{u^2} \left(2 \int ue^{-u^2} H_\varphi du + c_1 \right) \tag{3.3}$$

where $c_1 \in \mathbb{R}$. By using $A = \frac{g'(u)}{\sqrt{(u^2(1-g'^2)-c^2)}}$ and the equation (3.3), we obtain

$$\left[u^2 + e^{2u^2} \left(2 \int ue^{-u^2} H_\varphi du + c_1 \right)^2 \right] g'^2(u) = \frac{(u^2 - c^2)}{u^2} \left(2 \int ue^{-u^2} H_\varphi du + c_1 \right)^2. \tag{3.4}$$

From the above equation, we get

$$g(u) = \mp \int \frac{e^{u^2} \sqrt{u^2 - c^2} \left(2 \int ue^{-u^2} H_\varphi du + c_1 \right)}{u \sqrt{u^2 + e^{2u^2} \left(2 \int ue^{-u^2} H_\varphi du + c_1 \right)^2}} du + c_2 \tag{3.5}$$

where $c_2 \in \mathbb{R}$.

On the contrary, for a given smooth function $H_\varphi(u)$, it is clear that there exists a two-parameter family of the curves as

$$\gamma(u, H_\varphi(u), c, c_1, c_2) = \left(\mp \int \frac{e^{u^2} \sqrt{u^2 - c^2} \left(2 \int ue^{-u^2} H_\varphi du + c_1 \right)}{u \sqrt{u^2 + e^{2u^2} \left(2 \int ue^{-u^2} H_\varphi du + c_1 \right)^2}} du + c_2, u, 0 \right).$$

□

The following corollary is an immediate consequence of the Theorem 3.1 and the definition of a minimal surfaces.

Corollary 3.1. *Let M be a minimal helicoidal surface in \mathbb{R}_1^3 with density $e^{-x_2^2 - x_3^2}$. Then M is an open part of either a helicoid or a surface parametrized by*

$$X(u, v) = \left(\mp \int \frac{c_1 e^{u^2} \sqrt{u^2 - c^2}}{u \sqrt{u^2 + c_1^2 e^{2u^2}}} du + c_2 + cv, u \cos v, u \sin v \right)$$

where $c_1, c_2 \in \mathbb{R}$.

Example 3.1. Consider a helicoidal surface with the weighted mean curvature

$$H_\varphi(u) = -\frac{\sqrt{3}u}{4}$$

and the pitch $c = 1$ in \mathbb{R}_1^3 with density $e^{-x_2^2 - x_3^2}$. By considering the equation (3.5), we get $\gamma(u)$. So we obtain the parametrization of the surface as follows

$$X(u, v) = \left(\frac{\sqrt{3} \left(\sqrt{-1 + u^2} + \arctan \left(\frac{1}{\sqrt{-1 + u^2}} \right) \right)}{2} + v, u \cos v, u \sin v \right)$$

and the figure of the domain

$$\begin{cases} 1 < u < 5 \\ -5 < v < 5 \end{cases}$$

is given in Figure 1.

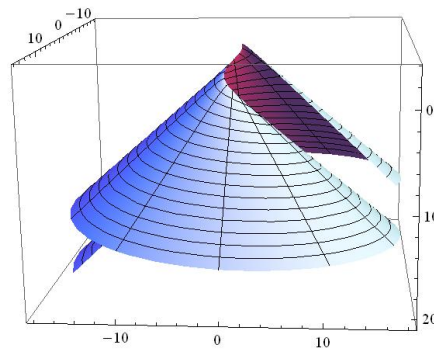


Figure 1. The helicoidal surface with the weighted mean curvature.

Theorem 3.2. Let $\gamma(u)$ be a profile curve of the helicoidal surface given with $X(u, v) = (g(u) + cv, u \cos v, u \sin v)$ in \mathbb{R}_1^3 with density $e^{-x_2^2 - x_3^2}$ and $G_\varphi(u)$ be the weighted Gaussian curvature at $(g(u), u, 0)$. Then, there exists two-parameter family of the helicoidal surface given by the curves

$$\gamma(u, G_\varphi(u), c, c_1, c_2) = \left(\mp \int \frac{1}{u} \left[\frac{(u^2 - c^2)(4u^2 - 2 \int u G_\varphi du + c_1) + c^2}{-1 + 4u^2 - 2 \int u G_\varphi du + c_1} \right]^{\frac{1}{2}} du + c_2, u, 0 \right)$$

where, c_1 and c_2 are constants. Conversely, for a given smooth function $G_\varphi(u)$, one can obtain the two-parameter family of curves $\gamma(u, G_\varphi(u), c, c_1, c_2)$ being the two-parameter family of helicoidal surfaces, accepting $G_\varphi(u)$ as the weighted Gaussian curvature c as a pitch.

Proof. Let's solve the equation (2.4), which is a second-order nonlinear ordinary differential equation. If we apply

$$B = \frac{-u^2 g'^2 - c^2}{(u^2(1 - g'^2) - c^2)} \tag{3.6}$$

into the equation (3.6), then we obtain

$$G_\varphi = -\frac{1}{2u} B' + 4$$

that is,

$$B' = -2uG_\varphi + 8u. \tag{3.7}$$

The general solution of the equation (3.7) becomes

$$B = 4u^2 - 2 \int u G_\varphi du + c_1 \tag{3.8}$$

where $c_1 \in \mathbb{R}$. Combining the equation (3.6) and the equation (3.8), we get

$$u^2 \left(-1 + 4u^2 - 2 \int u G_\varphi du + c_1 \right) g'^2(u) = (u^2 - c^2) \left(4u^2 - 2 \int u G_\varphi du + c_1 \right) + c^2. \tag{3.9}$$

It follows that

$$g(u) = \mp \int \frac{1}{u} \left[\frac{(u^2 - c^2) \left(4u^2 - 2 \int u G_\varphi du + c_1 \right) + c^2}{-1 + 4u^2 - 2 \int u G_\varphi du + c_1} \right]^{\frac{1}{2}} du + c_2 \tag{3.10}$$

where $c_2 \in \mathbb{R}$.

Conversely, for a given $c \in \mathbb{R}$ and a smooth function $G_\varphi(u)$ defined on an open interval $I \subset \mathbb{R}^+$ and an arbitrary $u_0 \in I$, there exists an open sub-interval $I' \subset I$ containing u_0 and an open interval $J \subset \mathbb{R}$ containing

$$\hat{c}_1 = \left(1 + 2 \int u G_\varphi du\right)(u_0)$$

such that

$$F(u, c_1) = -1 + 4u^2 - 2 \int u G_\varphi du > 0$$

is defined on $I' \times J$ and it is easily seen F is positive. Thus, two-parameter family of the curves can be given as

$$\gamma(u, G_\varphi(u), c, c_1, c_2) = \left(\mp \int \frac{1}{u} \left[\frac{(u^2 - c^2)(4u^2 - 2 \int u G_\varphi du + c_1) + c^2}{-1 + 4u^2 - 2 \int u G_\varphi du + c_1} \right]^{\frac{1}{2}} du + c_2, u, 0 \right)$$

where $(u, c_1) \in I' \times J; c_2 \in \mathbb{R}, c \in \mathbb{R}$ and G_φ is smooth function. □

Example 3.2. Consider a helicoidal surface with the weighted Gaussian curvature

$$G_\varphi(u) = \frac{-3 + 2u^2}{3}$$

in R_1^3 with density $e^{-x_2^2 - x_3^2}$. By using the equation (3.10), we obtain

$$g(u) = \sqrt{-1 + 2u^2} + \arctan\left(\frac{1}{\sqrt{-1 + 2u^2}}\right)$$

for $c = 1, c_1 = 0, c_2 = 0$ and the parametrization of the surface as follows

$$X(u, v) = (g(u) + v, u \cos v, u \sin v).$$

The figure of the surface of the domain

$$\begin{cases} 2 < u < 5 \\ -10 < v < 10 \end{cases}$$

is given in Figure 3.

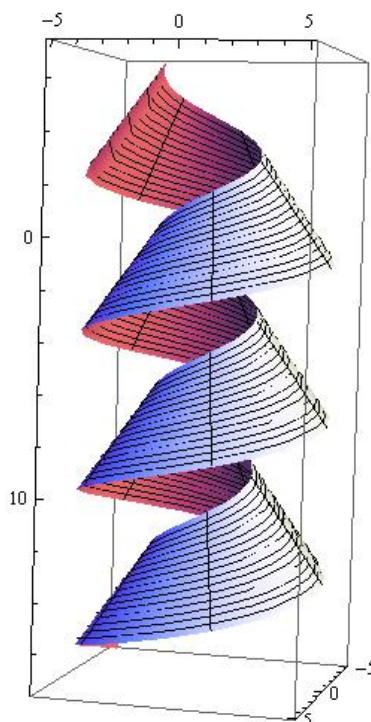


Figure 2. The helicoidal surface with the weighted Gaussian curvature.

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