

ON THE GENERALIZED OF HARMONIC AND BI-HARMONIC MAPS

M. DJAA, A. M. CHERIF, K. ZEGGA AND S. OUAKKAS

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ABSTRACT. In this note, we extend the definition of harmonic and biharmonic maps between two Riemannian manifolds, and we present some properties for f -harmonic maps and f -biharmonic maps.

1. F-HARMONIC MAPS

Definition 1.1. Consider a smooth map $\varphi : (M^m, g) \rightarrow (N^n, h)$ between Riemannian manifolds and $f : (x, y) \in M \times N \rightarrow f(x, y) \in (0, +\infty)$ be a smooth positive function. The f -energy functional of φ is defined by

$$(1.1) \quad E_f(\varphi) = \frac{1}{2} \int_M f(x, \varphi(x)) |d\varphi|^2 v_g$$

(or over any compact subset $K \subset M$).

A map is called f -harmonic if it is a critical point of the f -energy functional over any compact subset of M .

Remark 1.1. :

- Definition 1.1, is a natural generalization of harmonic map ([2], [6], [7]) and f -harmonic map ([5], [10]).
- Definition 1.1, is also a generalization of p -harmonic map ([3]) and F -harmonic map [1]), when φ has no critical points.

1.1. The first variation of the f -energy. Let $\varphi : (M^m, g) \rightarrow (N^n, h)$ be a smooth map, we denote by :

$$\tau(\varphi) = \text{trace}_g \nabla d\varphi$$

the tension field of φ , and $e(\varphi) = \frac{1}{2}|d\varphi|^2$ the energy density of φ (for more detail, see [2], [4], [6] and [7]).

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Theorem 1.1. *Let $I = (-\epsilon, \epsilon) \subset \mathbb{R}$ and $\{\varphi_t\}_{t \in I}$ be a smooth variation of φ . Then*

$$(1.2) \quad \left. \frac{d}{dt} E_f(\varphi_t) \right|_{t=0} = - \int_M h(\tau_f(\varphi), v) v_g,$$

where

$$(1.3) \quad \tau_f(\varphi) = f_\varphi \tau(\varphi) + d\varphi(\text{grad}^M f_\varphi) - e(\varphi)(\text{grad}^N f) \circ \varphi,$$

f_φ is the smooth function $x \in M^m \rightarrow f_\varphi(x) = f(x, \varphi(x)) \in (0, +\infty)$,

and $v = \left. \frac{\partial \varphi_t}{\partial t} \right|_{t=0}$ denotes the variation vector field of $\{\varphi_t\}_{t \in I}$.

Proof:

Let $\phi : I \times M \rightarrow N$ be a smooth map satisfying for all $t \in I$ and all $x \in M$

$$\phi(t, x) = \varphi_t(x),$$

and

$$\phi(0, x) = \varphi(x).$$

The variation vector field $v \in \Gamma(\varphi^{-1}TN)$ associated to the variation $\{\varphi_t\}_{t \in I}$ is given for all $x \in M$, by

$$v(x) = d_{(0,x)}\phi\left(\frac{\partial}{\partial t}\right),$$

We have

$$(1.4) \quad \begin{aligned} \left. \frac{d}{dt} E_f(\varphi_t) \right|_{t=0} &= \frac{1}{2} \int_M \left. \frac{\partial}{\partial t} (f(x, \varphi_t(x)) |d_x \varphi_t|^2) \right|_{(0,x)} v_g \\ &= \frac{1}{2} \int_M \left\{ \left. \frac{\partial}{\partial t} f(x, \varphi_t(x)) \right|_{(0,x)} |d_x \varphi|^2 \right. \\ &\quad \left. + f(x, \varphi(x)) \left. \frac{\partial}{\partial t} |d_x \varphi_t|^2 \right|_{(0,x)} \right\} v_g \end{aligned}$$

First, note that:

$$\begin{aligned} \left. \frac{\partial}{\partial t} f(x, \varphi_t(x)) \right|_{(0,x)} &= \left. \frac{\partial}{\partial t} f(x, \phi(t, x)) \right|_{(0,x)} \\ &= d_{(x, \varphi(x))} f(0, v(x)) \\ &= d_{\varphi(x)} f_x(v(x)). \end{aligned}$$

where f_x is the smooth function $y \in N \rightarrow f_x(y) = f(x, y) \in (0, +\infty)$. Hence

$$(1.5) \quad \begin{aligned} \left. \frac{1}{2} \frac{\partial}{\partial t} f(x, \varphi_t(x)) \right|_{(0,x)} |d_x \varphi|^2 &= d_{\varphi(x)} f_x(v(x)) e(\varphi)_x \\ &= h((\text{grad}^N f_x)_{\varphi(x)}, v(x)) e(\varphi)_x \\ &= h(e(\varphi)_x (\text{grad}^N f_x)_{\varphi(x)}, v(x)). \end{aligned}$$

Other hand:

Let $\{e_i\}_{i=1}^m$ be an orthonormal frame with respect to g on M , such that $\nabla_{e_i}^M e_j = 0$, at $x \in M$ for all $i, j = 1, \dots, m$. from equality

$$d_x \varphi_t(e_i) = d_{(t,x)} \phi(0, e_i),$$

Summing over the index i , we obtain

$$\begin{aligned}
\frac{1}{2} \frac{\partial}{\partial t} |d_x \varphi_t|^2 \Big|_{(0,x)} &= \frac{1}{2} \frac{\partial}{\partial t} h(d_x \varphi_t(e_i), d_x \varphi_t(e_i)) \Big|_{(0,x)} \\
&= \frac{1}{2} \frac{\partial}{\partial t} h(d\phi(0, e_i), d\phi(0, e_i)) \Big|_{(0,x)} \\
&= h(\nabla_{\frac{\partial}{\partial t}}^\phi d\phi(0, e_i), d\phi(0, e_i)) \Big|_{(0,x)} \\
&= h(\nabla_{(0,e_i)}^\phi d\phi(\frac{\partial}{\partial t}), d\phi(0, e_i)) \Big|_{(0,x)} \\
&= (0, e_i)(h(d\phi(\frac{\partial}{\partial t}), d\phi(0, e_i))) \Big|_{(0,x)} \\
&\quad - h(d\phi(\frac{\partial}{\partial t}), \nabla_{(0,e_i)}^\phi d\phi(0, e_i)) \Big|_{(0,x)} \\
&= e_i(h(v, d\varphi(e_i)))_x - h(v, \tau(\varphi))_x.
\end{aligned}$$

Let X be a vector field with compact support on M , such that for any vector field Y on M , we have

$$g(X, Y) = h(v, d\varphi(Y)),$$

then

$$\frac{1}{2} \frac{\partial}{\partial t} |d_x \varphi_t|^2 \Big|_{(0,x)} = (div X)_x - h(v, \tau(\varphi))_x.$$

So :

$$\begin{aligned}
\frac{1}{2} f(x, \varphi(x)) \frac{\partial}{\partial t} |d_x \varphi_t|^2 \Big|_{(0,x)} &= \left[f_\varphi div X - h(v, f_\varphi \tau(\varphi)) \right]_x \\
(1.6) \qquad \qquad \qquad &= \left[div(f_\varphi X) - h(v, d\varphi(grad^M f_\varphi)) - h(v, f_\varphi \tau(\varphi)) \right]_x.
\end{aligned}$$

Substituting (1.5) and (1.6) in (1.4), and consider the divergence theorem (see [2]) we obtain

$$\begin{aligned}
\frac{d}{dt} E_f(\varphi_t) \Big|_{t=0} &= \int_M h \left(e(\varphi)_x (grad^N f_x)_{\varphi(x)} - d\varphi(grad^M f_\varphi)_x \right. \\
&\quad \left. - f(x, \varphi(x)) \tau(\varphi)_x, v(x) \right) v_g.
\end{aligned}$$

Definition 1.2. The field $\tau_f(\varphi)$ defined by :

$$\begin{aligned}
(1.7) \qquad \tau_f(\varphi) &= f_\varphi \tau(\varphi) + d\varphi(grad^M f_\varphi) - e(\varphi)(grad^N f) \circ \varphi \\
&= trace_g \nabla f_\varphi d\varphi - e(\varphi)(grad^N f) \circ \varphi.
\end{aligned}$$

is called the f -tension field of φ .

From Theorem 1.1, we deduce

Theorem 1.2. Let $\varphi : (M^m, g) \rightarrow (N^n, h)$ be a smooth map,. Then φ is f -harmonic, if and only if

$$\tau_f(\varphi) = f_\varphi \tau(\varphi) + d\varphi(grad^M f_\varphi) - e(\varphi)(grad^N f) \circ \varphi = 0$$

Particular Cases

- (1) If $f = 1$, then $\tau_f(\varphi) = \tau(\varphi)$, is the natural tension field of φ (see [2], [6], [7]).
- (2) Let $f_1 : M \rightarrow (0, +\infty)$, be a smooth positif function. If $f(x, y) = f_1(x)$ for all $(x, y) \in M \times N$, then $\tau_f(\varphi) = \tau_{f_1}(\varphi)$, and φ is f -harmonic map, if and only if, φ is f_1 -harmonic map (see [5], [10]).
- (3) Let $f_2 : N \rightarrow (0, +\infty)$, be a smooth positif function. If $f(x, y) = f_2(y)$ for all $(x, y) \in M \times N$, then $\tau_f(\varphi) = f_2 \circ \varphi \cdot \tilde{\tau}(\varphi)$, where $\tilde{\tau}(\varphi)$ denote the tension field of φ between the Riemannian manifolds (M^m, g) and (N^n, \tilde{h}) equipped with the conform metric $\tilde{h} = f_2 \cdot h$.
So $\varphi : (M^m, g) \rightarrow (N^n, h)$ is f -harmonic map if and only if $\varphi : (M^m, g) \rightarrow (N^n, \tilde{h})$ is harmonic map.
- (4) Let $f_1 : M \rightarrow (0, +\infty)$ and $f_2 : N \rightarrow (0, +\infty)$ be smooth positif functions. If $f(x, y) = f_1(x)f_2(y)$ for all $(x, y) \in M \times N$, then

$$\tau_f(\varphi) = f_2 \circ \varphi \{ f_1 \cdot \tilde{\tau}(\varphi) + d\varphi(\text{grad}^M f_1) \}$$
- (5) If $\varphi : (M^m, g) \rightarrow (N^n, h)$ has no critical points (i.e. $|d_x\varphi| \neq 0$, then harmonic maps, p-harmonic maps and exponential harmonic maps are f-harmonic map with $f = 1$, $f = |d\varphi|^{p-2}$ and $f = \exp(\frac{|d\varphi|^2}{2})$ respectively.
- (6) If $\varphi : (M^m, g) \rightarrow (N^n, h)$ has no critical points, then any F-harmonic map is f-harmonic map with $f = F'(\frac{|d\varphi|^2}{2})$.

Example 1.1. Let $M = (\mathbb{R}^*, dx^2)$, $N = (\mathbb{R}, dy^2)$, $\varphi : M \rightarrow N$ be a smooth function, and let $f : M \times N \rightarrow \mathbb{R}_+$ be a C^2 function. From Definition 1.2 (formula (1.7)), we have

$$\tau_f(\varphi) \Big|_x = \left[f(x, \varphi(x))\varphi''(x) + \frac{\partial f}{\partial x}(x, \varphi(x))\varphi'(x) + \frac{1}{2}\varphi'(x)^2 \frac{\partial f}{\partial y}(x, \varphi(x)) \right] \frac{d}{dy} \Big|_{\varphi(x)}.$$

If $f(x, y) = e^{xy}$, by (1.8), φ is harmonic if and only if

$$(1.8) \quad \varphi''(x) + \varphi(x)\varphi'(x) + \frac{1}{2}x\varphi'(x)^2 = 0.$$

A local solution of the equation (1.8) is $\varphi(x) = \frac{4}{x}$.

Example 1.2. Let $\varphi = Id : x \in \mathbb{R}^n \rightarrow \varphi(x) = x \in \mathbb{R}^n$, then we have $\tau(\varphi) = 0$, $e(\varphi) = \frac{n}{2}$ and from formula (1.7), we obtain :

$$\tau_f(\varphi) = \left\{ \frac{\partial f}{\partial x^i} + \frac{(2-n)}{2} \frac{\partial f}{\partial y^i} \right\} \frac{\partial}{\partial x^i}$$

1.2. The second variation of the f -energy.

Theorem 1.3. Let $\varphi : (M^m, g) \rightarrow (N^n, h)$ be an f -harmonic map between Riemannian manifolds, and $\varphi_{t,s} : M \rightarrow N$ ($-\varepsilon < t, s < \varepsilon$) be a two-parameter variation with compact support, such that $\varphi_{0,0} = \varphi$. Set

$$v = \frac{\partial \varphi_{t,s}}{\partial t} \Big|_{t,s=0} \quad \text{and} \quad w = \frac{\partial \varphi_{t,s}}{\partial s} \Big|_{t,s=0}.$$

Under the notation above we have the following:

$$\frac{\partial^2}{\partial t \partial s} E_f(\varphi_{t,s}) \Big|_{t,s=0} = \int_M h(J_{\varphi, f}(v), w) v_g,$$

where

$$(1.9) \quad \begin{aligned} J_{\varphi,f}(v) = & -f_{\varphi} \text{trace}_g R^N(v, d\varphi) d\varphi - \text{trace}_g \nabla^{\varphi} f_{\varphi} \nabla^{\varphi} v \\ & + e(\varphi)(\nabla_v^N \text{grad}^N f) \circ \varphi - d\varphi(\text{grad}^M v(f)) \\ & - v(f)\tau(\varphi) + \langle \nabla^{\varphi} v, d\varphi \rangle (\text{grad}^N f) \circ \varphi, \end{aligned}$$

and

$$\text{trace}_g \nabla^{\varphi} f_{\varphi} \nabla^{\varphi} v = \sum_{i=1}^m \left(\nabla_{e_i}^{\varphi} f_{\varphi} \nabla_{e_i}^{\varphi} v - f_{\varphi} \nabla_{\nabla_{e_i}^M e_i}^{\varphi} v \right).$$

for any orthonormal frame $(e_i)_i$ on (M, g) . Here \langle , \rangle denote the inner product on $T^*M \otimes \varphi^{-1}TN$ and R^N is the curvature tensor on (N, h) .

Definition 1.3. $J_{\varphi,f}$ is called the f -Jacobi operator corresponding to φ .

Proof of Theorem 1.3 :

Let $\phi : (-\varepsilon, \varepsilon) \times (-\varepsilon, \varepsilon) \times M \rightarrow N$ is a map defined by

$$\phi(t, s, x) = \varphi_{t,s}(x),$$

where $(-\varepsilon, \varepsilon) \times (-\varepsilon, \varepsilon) \times M$ is equipped with the product metric. If we extend the vector fields $\frac{\partial}{\partial t}$ on $(-\varepsilon, \varepsilon)$ and $\frac{\partial}{\partial s}$ on $(-\varepsilon, \varepsilon)$, then

$$v = d\phi\left(\frac{\partial}{\partial t}\right)\Big|_{t,s=0} \quad \text{and} \quad w = d\phi\left(\frac{\partial}{\partial s}\right)\Big|_{t,s=0}.$$

Let $\{e_i\}_{i=1}^m$ be an orthonormal frame with respect to g on M , such that $\nabla_{e_i}^M e_j = 0$, at fixed point $x \in M$ for all $i, j = 1, \dots, m$. We compute

$$\frac{\partial^2}{\partial t \partial s} E_f(\varphi_{t,s}) = \frac{1}{2} \int_M \frac{\partial^2}{\partial t \partial s} \left[f(x, \varphi_{t,s}(x)) h(d\varphi_{t,s}(e_i), d\varphi_{t,s}(e_i)) \right] v_g,$$

here summing over the index i . We have

$$(1.10) \quad \begin{aligned} \frac{1}{2} \frac{\partial^2}{\partial t \partial s} \left[f(x, \varphi_{t,s}(x)) h(d\varphi_{t,s}(e_i), d\varphi_{t,s}(e_i)) \right] = & \\ & \frac{1}{2} \frac{\partial^2}{\partial t \partial s} f(x, \varphi_{t,s}(x)) \cdot h(d\varphi_{t,s}(e_i), d\varphi_{t,s}(e_i)) \\ & + \frac{\partial}{\partial t} f(x, \varphi_{t,s}(x)) \cdot h(\nabla_{\frac{\partial}{\partial s}}^{\phi} d\varphi_{t,s}(e_i), d\varphi_{t,s}(e_i)) \\ & + \frac{\partial}{\partial s} f(x, \varphi_{t,s}(x)) \cdot h(\nabla_{\frac{\partial}{\partial t}}^{\phi} d\varphi_{t,s}(e_i), d\varphi_{t,s}(e_i)) \\ & + f(x, \varphi_{t,s}(x)) \cdot h(\nabla_{\frac{\partial}{\partial s}}^{\phi} \nabla_{\frac{\partial}{\partial t}}^{\phi} d\varphi_{t,s}(e_i), d\varphi_{t,s}(e_i)) \\ & + f(x, \varphi_{t,s}(x)) \cdot h(\nabla_{\frac{\partial}{\partial t}}^{\phi} d\varphi_{t,s}(e_i), \nabla_{\frac{\partial}{\partial s}}^{\phi} d\varphi_{t,s}(e_i)). \end{aligned}$$

Now we calculate each term of right part in the above equation (1.10):

1.

$$\begin{aligned}
\frac{\partial^2}{\partial t \partial s} f(x, \varphi_{t,s}(x)) &= \frac{\partial}{\partial s} \left[d_{(x, \varphi_{t,s}(x))} f(0, d_{(t,s,x)} \phi \left(\frac{\partial}{\partial t} \right)) \right] \\
&= \frac{\partial}{\partial s} \left[d_{\varphi_{t,s}(x)} f_x(d_{(t,s,x)} \phi \left(\frac{\partial}{\partial t} \right)) \right] \\
&= \frac{\partial}{\partial s} \left[h(\text{grad}^N f_x, d_{(t,s,x)} \phi \left(\frac{\partial}{\partial t} \right)) \right] \\
&= h(\nabla_{\frac{\partial}{\partial s}}^\phi \text{grad}^N f_x \circ \phi, d_{(t,s,x)} \phi \left(\frac{\partial}{\partial t} \right)) \\
&\quad + h(\text{grad}^N f_x \circ \phi, \nabla_{\frac{\partial}{\partial s}}^\phi d_{(t,s,x)} \phi \left(\frac{\partial}{\partial t} \right)),
\end{aligned}$$

then

$$\begin{aligned}
(1.11) \quad \frac{1}{2} \frac{\partial^2}{\partial t \partial s} f(x, \varphi_{t,s}(x)) \cdot h(d\varphi_{t,s}(e_i), d\varphi_{t,s}(e_i)) \Big|_{t=s=0} &= \\
h(\nabla_w^N \text{grad}^N f_x, v)e(\varphi) + h\left((\text{grad}^N f_x)_{\varphi(x)}, \nabla_{\frac{\partial}{\partial s}}^\phi d\phi \left(\frac{\partial}{\partial t} \right) \Big|_{t=s=0}\right) e(\varphi).
\end{aligned}$$

2.

$$\begin{aligned}
\frac{\partial}{\partial t} f(x, \varphi_{t,s}(x)) \cdot h(\nabla_{\frac{\partial}{\partial s}}^\phi d\varphi_{t,s}(e_i), d\varphi_{t,s}(e_i)) \Big|_{t=s=0} &= \\
&= h(\text{grad}^N f_x, v) h(\nabla_{\frac{\partial}{\partial s}}^\phi d\phi(e_i), d\phi(e_i)) \Big|_{t=s=0} \\
&= v(f_x) h(\nabla_{e_i}^\phi d\phi \left(\frac{\partial}{\partial s} \right), d\phi(e_i)) \Big|_{t=s=0} \\
&= v(f_x) \left[e_i(h(w, d\varphi(e_i))) - h(w, \tau(\varphi)) \right].
\end{aligned}$$

If X is the compactly supported vector field on M such for any vector field Y on M :

$$g(X, Y) = h(w, d\varphi(Y)),$$

then

$$\begin{aligned}
\frac{\partial}{\partial t} f(x, \varphi_{t,s}(x)) \cdot h(\nabla_{\frac{\partial}{\partial s}}^\phi d\varphi_{t,s}(e_i), d\varphi_{t,s}(e_i)) \Big|_{t=s=0} &= \\
&= v(f_x) \text{div} X - h(w, v(f_x) \tau(\varphi)) \\
(1.12) \quad &= \text{div}(v(f_x) X) - h(w, d\varphi(\text{grad}^M v(f_x))) - h(w, v(f_x) \tau(\varphi)) \quad .
\end{aligned}$$

3.

$$\begin{aligned}
\frac{\partial}{\partial s} f(x, \varphi_{t,s}(x)) \cdot h(\nabla_{\frac{\partial}{\partial t}}^\phi d\varphi_{t,s}(e_i), d\varphi_{t,s}(e_i)) \Big|_{t=s=0} &= \\
&= h(\text{grad}^N f_x, w) \cdot \langle \nabla^\varphi v, d\varphi \rangle \\
(1.13) \quad &= h(\langle \nabla^\varphi v, d\varphi \rangle \text{grad}^N f_x, w).
\end{aligned}$$

4.

$$\begin{aligned}
& f(x, \varphi_{t,s}(x)) \cdot h(\nabla_{\frac{\partial}{\partial s}}^\phi \nabla_{\frac{\partial}{\partial t}}^\phi d\varphi_{t,s}(e_i), d\varphi_{t,s}(e_i)) \Big|_{t=s=0} \\
&= f(x, \varphi(x)) h(\nabla_{\frac{\partial}{\partial s}}^\phi \nabla_{e_i}^\phi d\varphi_{t,s}(\frac{\partial}{\partial t}), d\varphi(e_i)) \\
&= f_\varphi h(R^N(d\varphi(\frac{\partial}{\partial s}), d\varphi(e_i)) d\varphi(\frac{\partial}{\partial t}), d\varphi(e_i)) \\
&\quad + f_\varphi h(\nabla_{e_i}^\phi \nabla_{\frac{\partial}{\partial s}}^\phi d\varphi_{t,s}(\frac{\partial}{\partial t}), d\varphi(e_i)) \\
&= -f_\varphi h(R^N(v, d\varphi(e_i)) d\varphi(e_i), w) \\
&\quad + f_\varphi e_i(h(\nabla_{\frac{\partial}{\partial s}}^\phi d\varphi_{t,s}(\frac{\partial}{\partial t}), d\varphi(e_i))) \\
&\quad - f_\varphi h(\nabla_{\frac{\partial}{\partial s}}^\phi d\varphi_{t,s}(\frac{\partial}{\partial t}), \tau(\varphi))
\end{aligned} \tag{1.14}$$

let X_2 be a compactly supported vector field on M such that

$$g(X_2, Y) = h(\nabla_{\frac{\partial}{\partial s}}^\phi d\varphi_{t,s}(\frac{\partial}{\partial t}), d\varphi(Y)) \Big|_{t=s=0},$$

for any vector field Y on M , then the formula (1.14) becomes

$$\begin{aligned}
& f(x, \varphi_{t,s}(x)) \cdot h(\nabla_{\frac{\partial}{\partial s}}^\phi \nabla_{\frac{\partial}{\partial t}}^\phi d\varphi_{t,s}(e_i), d\varphi_{t,s}(e_i)) \Big|_{t=s=0} \\
&= -f_\varphi h(\text{trace}_g R^N(v, d\varphi) d\varphi, w) \\
&\quad + f_\varphi \text{div} X_2 - f_\varphi h(\nabla_{\frac{\partial}{\partial s}}^\phi d\varphi_{t,s}(\frac{\partial}{\partial t}), \tau(\varphi)) \\
&= -f_\varphi h(\text{trace}_g R^N(v, d\varphi) d\varphi, w) + \text{div}(f_\varphi X_2) \\
&\quad - h(\nabla_{\frac{\partial}{\partial s}}^\phi d\varphi_{t,s}(\frac{\partial}{\partial t}) \Big|_{t=s=0}, d\varphi(\text{grad}^M f_\varphi)) \\
&\quad - f_\varphi h(\nabla_{\frac{\partial}{\partial s}}^\phi d\varphi_{t,s}(\frac{\partial}{\partial t}) \Big|_{t=s=0}, \tau(\varphi)).
\end{aligned} \tag{1.15}$$

5.

$$\begin{aligned}
& f(x, \varphi_{t,s}(x)) \cdot h(\nabla_{\frac{\partial}{\partial t}}^\phi d\varphi_{t,s}(e_i), \nabla_{\frac{\partial}{\partial s}}^\phi d\varphi_{t,s}(e_i)) \Big|_{t=s=0} \\
&= f_\varphi h(\nabla_{e_i}^\phi d\varphi_{t,s}(\frac{\partial}{\partial t}), \nabla_{e_i}^\phi d\varphi_{t,s}(\frac{\partial}{\partial s})) \\
&= f_\varphi [e_i(h(\nabla_{e_i}^\varphi v, w)) - h(\nabla_{e_i}^\varphi \nabla_{e_i}^\varphi v, w)].
\end{aligned} \tag{1.16}$$

Let X_3 be a compactly supported vector field on M such that

$$g(X_3, Y) = h(\nabla_Y^\varphi v, w),$$

for any vector field Y on M , then the formula (1.16) becomes

$$\begin{aligned}
& f(x, \varphi_{t,s}(x)) \cdot h(\nabla_{\frac{\partial}{\partial t}}^\phi d\varphi_{t,s}(e_i), \nabla_{\frac{\partial}{\partial s}}^\phi d\varphi_{t,s}(e_i)) \Big|_{t=s=0} \\
&= f_\varphi [\text{div} X_3 - h(\text{trace}_g (\nabla^\varphi)^2 v, w)] \\
&= \text{div}(f_\varphi X_3) - h(\nabla_{\text{grad}^M f_\varphi}^\varphi v, w) \\
&\quad - h(f_\varphi \text{trace}_g (\nabla^\varphi)^2 v, w) \\
&= \text{div}(f_\varphi X_3) - h(\text{trace}_g \nabla^\varphi f_\varphi \nabla^\varphi v, w).
\end{aligned} \tag{1.17}$$

Substituting the formulas (1.11), (1.12), (1.13), (1.15) and (1.17) in (1.10), and integrate it, the Theorem 1.3 follows.

2. f -BIHARMONIC MAPS

A natural generalization of f -harmonic maps is given by integrating the square of the norm of the f -tension field. More precisely, the f -bi-energy functional of a smooth map $\varphi : (M^m, g) \longrightarrow (N^n, h)$ is defined by

$$E_{2,f}(\varphi) = \frac{1}{2} \int_M |\tau_f(\varphi)|^2 v_g.$$

A map φ is called f -biharmonic if it is a critical point of the f -energy functional.

2.1. First variation of the f -bi-energy.

Theorem 2.1. *Let $\varphi : (M^m, g) \longrightarrow (N^n, h)$ be a smooth map and let $\{\varphi_t\}_t$ ($-\varepsilon < t < \varepsilon$), be a smooth variation of φ . Then*

$$\left. \frac{d}{dt} E_{2,f}(\varphi_t) \right|_{t=0} = - \int_M h(\tau_{2,f}(\varphi), v) v_g,$$

where $v = \left. \frac{\partial \varphi_t}{\partial t} \right|_{t=0}$ denotes the variation vector field of $\{\varphi_t\}_t$,

$$\begin{aligned} \tau_{2,f}(\varphi) &= -f_\varphi \text{trace}_g R^N(\tau_f(\varphi), d\varphi) d\varphi - \text{trace}_g \nabla^\varphi f_\varphi \nabla^\varphi \tau_f(\varphi) \\ &\quad + e(\varphi)(\nabla_{\tau_f(\varphi)}^N \text{grad}^N f) \circ \varphi - d\varphi(\text{grad}^M \tau_f(\varphi)(f)) \\ &\quad - \tau_f(\varphi)(f) \tau(\varphi) + \langle \nabla^\varphi \tau_f(\varphi), d\varphi \rangle (\text{grad}^N f) \circ \varphi. \end{aligned}$$

and

$$\text{trace}_g \nabla^\varphi f_\varphi \nabla^\varphi \tau_f(\varphi) = \sum_{i=1}^m \left(\nabla_{e_i}^\varphi f_\varphi \nabla_{e_i}^\varphi \tau_f(\varphi) - f_\varphi \nabla_{\nabla_{e_i}^M e_i}^\varphi \tau_f(\varphi) \right).$$

for any orthonormal frame $(e_i)_i$ on (M, g)

Definition 2.1. $\tau_{2,f}(\varphi)$ is called the f -bi-tension field of φ .

Proof of Theorem 2.1 :

Let $\phi : (-\varepsilon, \varepsilon) \times M \longrightarrow N$ be defined by $\phi(t, x) = \varphi_t(x)$, where $(-\varepsilon, \varepsilon) \times M$ is equipped with the product metric. We extend the vector fields $\frac{\partial}{\partial t}$ naturally on $(-\varepsilon, \varepsilon) \times M$, then

$$(2.1) \quad \frac{d}{dt} E_{2,f}(\varphi_t) = \int_M h(\nabla_{\frac{\partial}{\partial t}}^\phi \tau_f(\varphi_t), \tau_f(\varphi_t)) v_g,$$

choose a local orthonormal frame $\{e_i\}_{1 \leq i \leq m}$, such that $\nabla_{e_i} e_j = 0$ for all $i, j = 1, \dots, m$ at a fixed point $x \in M$, then by (1.7) we have

$$\nabla_{\frac{\partial}{\partial t}}^\phi \tau_f(\varphi_t) = \nabla_{\frac{\partial}{\partial t}}^\phi \nabla_{e_i}^\phi f_{\varphi_t} d\varphi_t(e_i) - \nabla_{\frac{\partial}{\partial t}}^\phi e(\varphi_t)(\text{grad}^N f) \circ \varphi_t,$$

First, from formula of curvature tensor, we obtain

$$(2.2) \quad \begin{aligned} \nabla_{\frac{\partial}{\partial t}}^\phi \nabla_{e_i}^\phi f_{\varphi_t} d\varphi_t(e_i) &= R^N(d\phi(\frac{\partial}{\partial t}), d\phi(e_i)) f_{\varphi_t} d\varphi_t(e_i) \\ &\quad + \nabla_{e_i}^\phi \nabla_{\frac{\partial}{\partial t}}^\phi f_{\varphi_t} d\varphi_t(e_i). \end{aligned}$$

We have

$$\begin{aligned}
h(\nabla_{e_i}^\phi \nabla_{\frac{\partial}{\partial t}}^\phi f_{\varphi_t} d\varphi_t(e_i), \tau_f(\varphi_t)) &= e_i(h(\nabla_{\frac{\partial}{\partial t}}^\phi f_{\varphi_t} d\varphi_t(e_i), \tau_f(\varphi_t))) \\
&\quad - h(\nabla_{\frac{\partial}{\partial t}}^\phi f_{\varphi_t} d\varphi_t(e_i), \nabla_{e_i}^\phi \tau_f(\varphi_t)) \\
&= e_i(h(\nabla_{\frac{\partial}{\partial t}}^\phi f_{\varphi_t} d\varphi_t(e_i), \tau_f(\varphi_t))) \\
&\quad - \frac{\partial f_{\varphi_t}}{\partial t} \cdot h(d\varphi_t(e_i), \nabla_{e_i}^\phi \tau_f(\varphi_t)) \\
&\quad - f_{\varphi_t} h(\nabla_{\frac{\partial}{\partial t}}^\phi d\varphi_t(e_i), \nabla_{e_i}^\phi \tau_f(\varphi_t)).
\end{aligned}$$

let X be the compactly supported vector field on M such that

$$g(X, Y) = h((\nabla_{\frac{\partial}{\partial t}}^\phi f_{\varphi_t} d\varphi_t)(Y), \tau_f(\varphi_t)) \Big|_{t=0}, \quad \forall Y \in \Gamma(TM),$$

then

$$\begin{aligned}
h(\nabla_{e_i}^\phi \nabla_{\frac{\partial}{\partial t}}^\phi f_{\varphi_t} d\varphi_t(e_i), \tau_f(\varphi_t)) \Big|_{t=0} &= \operatorname{div} X - h(\operatorname{grad}^N f, v) \cdot \langle d\varphi, \nabla^\varphi \tau_f(\varphi) \rangle \\
&\quad - f_\varphi h(\nabla_{\frac{\partial}{\partial t}}^\phi d\varphi_t(e_i), \nabla_{e_i}^\phi \tau_f(\varphi_t)) \Big|_{t=0} \\
&= \operatorname{div} X - h(\operatorname{grad}^N f, v) \cdot \langle d\varphi, \nabla^\varphi \tau_f(\varphi) \rangle \\
&\quad - f_\varphi \left[e_i(h(v, \nabla_{e_i}^\varphi \tau_f(\varphi))) - h(v, \nabla_{e_i}^\phi \nabla_{e_i}^\varphi \tau_f(\varphi)) \right]. \\
&= \operatorname{div} X - h(\operatorname{grad}^N f, v) \cdot \langle d\varphi, \nabla^\varphi \tau_f(\varphi) \rangle \\
&\quad - f_\varphi \left[\operatorname{div} X_2 - h(v, \operatorname{trace}_g(\nabla^\varphi)^2 \tau_f(\varphi)) \right] \\
&= \operatorname{div} X - h(\operatorname{grad}^N f, v) \cdot \langle d\varphi, \nabla^\varphi \tau_f(\varphi) \rangle \\
&\quad - \operatorname{div}(f_\varphi X_2) + h(v, \nabla_{\operatorname{grad}^M f_\varphi}^\varphi \tau_f(\varphi)) \\
&\quad + h(v, f_\varphi \operatorname{trace}_g(\nabla^\varphi)^2 \tau_f(\varphi)).
\end{aligned} \tag{2.3}$$

where X_2 is the compactly supported vector field on M such that

$$g(X_2, Y) = h(v, \nabla_Y^\varphi \tau_f(\varphi)), \quad \forall Y \in \Gamma(TM),$$

By the formulas (2.2) and (2.3), we have

$$\begin{aligned}
h(\nabla_{\frac{\partial}{\partial t}}^\phi \nabla_{e_i}^\phi f_{\varphi_t} d\varphi_t(e_i), \tau_f(\varphi_t)) \Big|_{t=0} &= h(f_\varphi \operatorname{trace}_g R^N(\tau_f(\varphi), d\varphi) d\varphi, v) \\
&\quad + \operatorname{div} X - h(\langle d\varphi, \nabla^\varphi \tau_f(\varphi) \rangle \cdot \operatorname{grad}^N f, v) \\
&\quad - \operatorname{div}(f_\varphi X_2) + h(v, \nabla_{\operatorname{grad}^M f_\varphi}^\varphi \tau_f(\varphi)) \\
&\quad + h(v, f_\varphi \operatorname{trace}_g(\nabla^\varphi)^2 \tau_f(\varphi)) \\
&= h(f_\varphi \operatorname{trace}_g R^N(\tau_f(\varphi), d\varphi) d\varphi, v) \\
&\quad + \operatorname{div} X - h(\langle d\varphi, \nabla^\varphi \tau_f(\varphi) \rangle \cdot \operatorname{grad}^N f, v) \\
&\quad - \operatorname{div}(f_\varphi X_2) + h(\operatorname{trace}_g \nabla^\varphi f_\varphi \nabla^\varphi \tau_f(\varphi), v).
\end{aligned} \tag{2.4}$$

On the other hand, we have

$$(2.5) \quad \nabla_{\frac{\partial}{\partial t}}^\phi e(\varphi_t)(\operatorname{grad}^N f) \circ \phi = \frac{\partial e(\varphi_t)}{\partial t}(\operatorname{grad}^N f) \circ \phi + e(\varphi_t) \nabla_{\frac{\partial}{\partial t}}^\phi (\operatorname{grad}^N f) \circ \phi,$$

since

$$\begin{aligned}
\left. \frac{\partial e(\varphi_t)}{\partial t} \right|_{t=0} &= \left. h(\nabla_{\frac{\partial}{\partial t}}^\phi d\phi(e_i), d\phi(e_i)) \right|_{t=0} \\
&= \left. h(\nabla_{e_i}^\phi d\phi(\frac{\partial}{\partial t}), d\phi(e_i)) \right|_{t=0} \\
&= e_i(h(v, d\phi(e_i))) - h(v, \tau(\varphi)). \\
(2.6) \qquad &= \operatorname{div} X_3 - h(v, \tau(\varphi))
\end{aligned}$$

where X_3 is the compactly supported vector field on M such that

$$g(X_3, Y) = h(v, d\varphi(Y)), \quad \forall Y \in \Gamma(TM).$$

By the formulas (2.5) and (2.6), we obtain

$$\begin{aligned}
&\left. h(\nabla_{\frac{\partial}{\partial t}}^\phi e(\varphi_t)(\operatorname{grad}^N f) \circ \phi, \tau_f(\varphi_t)) \right|_{t=0} \\
&= \tau_f(\varphi)(f) \operatorname{div} X_3 - \tau_f(\varphi)(f) h(v, \tau(\varphi)) \\
&\quad + e(\varphi) h(\nabla_{\frac{\partial}{\partial t}}^\phi \operatorname{grad}^N f \circ \phi, \tau_f(\varphi_t)) \Big|_{t=0} \\
(2.7) \qquad &= \operatorname{div}(\tau_f(\varphi)(f) X_3) - h(v, d\varphi(\operatorname{grad}^M \tau_f(\varphi)(f))) \\
&\quad - \tau_f(\varphi)(f) h(v, \tau(\varphi)) + e(\varphi) h(\nabla_{\tau_f(\varphi)}^N \operatorname{grad}^N f, v)
\end{aligned}$$

Substituting the formulas (2.4) and (2.7) in (2.1), the Theorem 2.1 follows.

From Theorem 2.1, we deduce

Theorem 2.2. *Let $\varphi : (M^m, g) \rightarrow (N^n, h)$ be a smooth map . Then φ is f -biharmonic if and only if we have:*

$$\begin{aligned}
\tau_{2,f}(\varphi) &= -f_\varphi \operatorname{trace}_g R^N(\tau_f(\varphi), d\varphi) d\varphi - \operatorname{trace}_g \nabla^\varphi f_\varphi \nabla^\varphi \tau_f(\varphi) \\
&\quad + e(\varphi) (\nabla_{\tau_f(\varphi)}^N \operatorname{grad}^N f) \circ \varphi - d\varphi(\operatorname{grad}^M \tau_f(\varphi)(f)) \\
&\quad - \tau_f(\varphi)(f) \tau(\varphi) + \langle \nabla^\varphi \tau_f(\varphi), d\varphi \rangle (\operatorname{grad}^N f) \circ \varphi. \\
&= 0
\end{aligned}$$

Particular Cases

- (1) If $f = 1$, then $\tau_{2,f}(\varphi) = \tau(\varphi)$, is the natural bi-tension field of φ (see [11], [12]).
- (2) Let $f_1 : M \rightarrow (0, +\infty)$, be a smooth positif function. If $f(x, y) = f_1(x)$ for all $(x, y) \in M \times N$, then $\tau_{2,f}(\varphi) = \tau_{2,f_1}(\varphi)$, and φ is f -bi-harmonic map, if and only if, φ is f_1 -biharmonic map (see [10]).
- (3) Let $f_2 : N \rightarrow (0, +\infty)$, be a smooth positif function. If $f(x, y) = f_2(y)$ for all $(x, y) \in M \times N$, then $\varphi : (M^m, g) \rightarrow (N^n, h)$ is f -bi-harmonic map if and only if $\varphi : (M^m, g) \rightarrow (N^n, \tilde{h})$ is bi-harmonic map, where (N^n, \tilde{h}) is equipped with the conform metric $\tilde{h} = f_2 \cdot h$ (see [11]).

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M. DJAA, DEPARTMENT OF MATHEMATICS UNIVERSITY OF RELIZANE, BORMADIA 48000, ALGERIA

E-mail address: Lgaca.Saida2009@hotmail.com

A.M. CHERIF, GEOMETRY ANALYSIS CONTROLE AND APPLICATIONS LABORATORY, BP 138, UNIVERSITY OF SAIDA, BP 138, ALGERIA

E-mail address: med.cherif_ahmed@yahoo.fr

KADDOUR ZEGGA, GEOMETRY ANALYSIS CONTROLE AND APPLICATIONS LABORATORY, UNIVERSITY OF SAIDA, BP 138, ALGERIA

E-mail address: zegga.kaddour@yahoo.fr

S. OUAKKAS, GEOMETRY ANALYSIS CONTROLE AND APPLICATIONS LABORATORY, UNIVERSITY OF SAIDA, BP 138, ALGERIA

E-mail address: souakkas@yahoo.fr