



ON RICCI PSEUDO-SYMMETRIC SUPER QUASI-EINSTEIN HERMITIAN MANIFOLDS

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ABSTRACT. The present paper deals the study of a Bochner Ricci pseudo-symmetric super quasi-Einstein Hermitian manifold and a holomorphically projective Ricci pseudo-symmetric super quasi-Einstein Hermitian manifold.

1. INTRODUCTION

An even dimensional differentiable manifold M^n is said to be a Hermitian manifold if a complex structure J of type $(1, 1)$ and a pseudo-Riemannian metric g of the manifold satisfy [13, 20]

$$J^2 = -I, \quad (1.1)$$

and

$$g(JX, JY) = g(X, Y), \quad (1.2)$$

where $X, Y \in \chi(M)$ and $\chi(M)$ is Lie algebra of vector fields on the manifold.

The notion of an Einstein manifold was introduced by Albert Einstein in differential geometry and mathematical physics. An Einstein manifold is a Riemannian or pseudo-Riemannian manifold $(M^n, g)(n \geq 2)$ in which Ricci tensor be a scalar multiple of the Riemannian metric i.e.

$$S(X, Y) = \alpha g(X, Y), \quad (1.3)$$

where S denote the Ricci tensor of the manifold $(M^n, g)(n \geq 2)$ and α is a non-zero scalar. According to [3], equation (1.3) is called the Einstein metric condition. An Einstein manifold plays a important role in the study of Riemannian geometry and general theory of relativity.

From the equation (1.3), we get

$$r = n\alpha. \quad (1.4)$$

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In 2000, M. C. Chaki and R.K. Maity [8] introduced a new type of a non-flat Riemannian manifold whose non-zero Ricci tensor satisfies

$$S(X, Y) = \alpha g(X, Y) + \beta A(X)A(Y), \tag{1.5}$$

and they called it a quasi-Einstein manifold, where α, β are scalars such that $\beta \neq 0$ and A is a non-zero 1-form associated with unit vector field ρ defined by $g(X, \rho) = A(X)$, for every vector field X . ρ is also called generator of the manifold. An n -dimensional quasi-Einstein manifold is denoted by $(QE)_n$. Contraction of the equation (1.5), gives

$$r = \alpha n + \beta. \tag{1.6}$$

From the equations (1.2) and (1.5), we can easily write

$$\begin{aligned} S(X, \rho) &= (\alpha + \beta)A(X), \quad S(\rho, \rho) = (\alpha + \beta), \\ g(J\rho, \rho) &= 0 \quad \text{and} \quad S(J\rho, \rho) = 0. \end{aligned} \tag{1.7}$$

A quasi-Einstein manifold came in existence during the study of exact solutions of Einstein fields equations as well as considerations of a quasi-umbilical hypersurfaces of semi-Euclidean space. The Walker-space time is an example of a quasi-Einstein manifold. Also a quasi-Einstein manifolds can be taken as a model of the perfect fluid space time in general theory of relativity [17].

In 2001, M. C. Chaki [9] introduced the notion of generalised quasi-Einstein manifolds. A Riemannian manifold $(M^n, g)(n \geq 2)$ is said to be a generalised quasi-Einstein manifold if a non-zero Ricci tensor of type $(0, 2)$ satisfies the condition

$$S(X, Y) = \alpha g(X, Y) + \beta A(X)A(Y) + \gamma C(X)C(Y), \tag{1.8}$$

where α, β and γ are scalars such that $\beta \neq 0, \gamma \neq 0$ and A, C are non-vanishing 1-forms associated with two orthogonal unit vectors ρ and μ by

$$\begin{aligned} g(X, \rho) &= A(X), \quad g(X, \mu) = C(X), \\ g(\rho, \rho) &= g(\mu, \mu) = 1. \end{aligned} \tag{1.9}$$

An n -dimensional generalised quasi-Einstein manifold is denoted by $G(QE)_n$. After contraction of equation (1.8), we get

$$r = \alpha n + \beta + \gamma. \tag{1.10}$$

From the equations (1.2), (1.8) and (1.9), we can easily write

$$\begin{aligned} S(X, \rho) &= (\alpha + \beta)A(X), \quad S(X, \mu) = (\alpha + \gamma)C(X), \quad S(\mu, \mu) = \alpha + \gamma, \\ S(\rho, \rho) &= \alpha + \beta, \quad g(J\rho, \rho) = g(J\mu, \mu) = 0, \quad \text{and} \quad S(J\mu, \mu) = S(J\rho, \rho) = 0. \end{aligned} \tag{1.11}$$

Also in 2004, M. C. Chaki [10] introduced the notion of super quasi-Einstein manifolds. A Riemannian manifold $(M^n, g)(n \geq 2)$ is said to be a super quasi-Einstein

manifold if a non-zero Ricci tensor of type (0, 2) satisfies

$$S(X, Y) = \alpha g(X, Y) + \beta A(X)A(Y) + \gamma[A(X)C(Y) + C(X)A(Y)] + \delta D(X, Y), \quad (1.12)$$

where α, β, γ and δ are non-zero scalars, A, C are non-vanishing 1-forms defined as (1.9) and ρ, μ are orthogonal unit vector fields, D is symmetric tensor of type (0, 2) with zero trace which satisfies the condition

$$D(X, \rho) = 0, \forall X. \quad (1.13)$$

An n-dimensional super quasi-Einstein manifold is denoted by $S(QE)_n$.

From the equations (1.2), (1.9), (1.12) and (1.13), we can easily write

$$\begin{aligned} S(X, \rho) &= (\alpha + \beta)A(X) + \gamma C(X), \quad S(X, \mu) = \alpha C(X) + \gamma A(X), \\ S(\mu, \mu) &= \alpha + \delta D(\mu, \mu), \quad S(\rho, \rho) = \alpha + \beta + \delta D(\rho, \rho), \quad g(J\rho, \rho) = g(J\mu, \mu) = 0, \\ S(J\mu, \mu) &= \gamma A(J\mu) + \delta D(J\mu, \mu), \quad S(J\rho, \rho) = \gamma C(J\rho) + \delta D(J\rho, \rho). \end{aligned} \quad (1.14)$$

In 2009, A. A. Shaikh [1] introduced the notion of pseudo quasi-Einstein manifold. A semi-Riemannian manifold (M^n, g) ($n \geq 2$) is said to be a pseudo quasi-Einstein manifold if a non-zero Ricci tensor of type (0, 2) satisfies the condition

$$S(X, Y) = \alpha g(X, Y) + \beta A(X)A(Y) + \delta D(X, Y), \quad (1.15)$$

where α, β , and δ are non-zero scalars and A is a non-zero 1-form defined by $g(X, \rho) = A(X)$. ρ denotes the unit vector called the generator of the manifold and D is symmetric tensor of type (0, 2) with zero trace defined as (1.13). An n-dimensional pseudo quasi-Einstein manifold is denoted by $P(QE)_n$.

From the equations (1.2), (1.9) (1.13) and (1.15), we can easily write

$$\begin{aligned} S(X, \rho) &= (\alpha + \beta)A(X), \quad S(\rho, \rho) = \alpha + \beta, \\ g(J\rho, \rho) &= 0 \text{ and } S(J\rho, \rho) = \delta D(J\rho, \rho). \end{aligned} \quad (1.16)$$

2. SEMI-SYMMETRIC AND RICCI PSEUDO-SYMMETRIC MANIFOLD

Let (M^n, g) be a Riemannian manifold and ∇ be the Levi-Civita connection on (M^n, g) then, a Riemannian manifold is said to be locally symmetric if $\nabla R = 0$, where R is the Riemannian curvature tensor of (M^n, g) . The locally symmetric manifold has been studied by different geometers through different approaches and different notion have been developed e.g., a semi-symmetric manifold by Szabò [18], recurrent manifold by Walker [2], conformally recurrent manifold by Adati and Miyazawa [16].

According to Z. I. Szabò [18], if the manifold M satisfies the condition

$$(R(X, Y).R)(U, V)W = 0, \quad X, Y, U, V, W \in \chi(M) \quad (2.1)$$

for all vector fields X and Y, then the manifold is called a semi-symmetric manifold. For a (0, k)- tensor field T on M, $k \geq 1$ and a symmetric (0, 2)-tensor field A on

M, the $(0, k + 2)$ -tensor fields R.T and Q(A, T) are defined by

$$\begin{aligned} (R.T)(X_1, \dots, X_k; X, Y) &= -T(R(X, Y)X_1, X_2, \dots, X_k) \\ &- \dots - T(X_1, \dots, X_{k-1}, R(X, Y)X_k), \end{aligned} \tag{2.2}$$

and

$$\begin{aligned} Q(A, T)(X_1, \dots, X_k; X, Y) &= -T((X \wedge_A Y)X_1, X_2, \dots, X_k) \\ &- \dots - T(X_1, \dots, X_{k-1}, (X \wedge_A Y)X_k), \end{aligned} \tag{2.3}$$

where $X \wedge_A Y$ is the endomorphism given by

$$(X \wedge_A Y)Z = A(Y, Z)X - A(X, Z)Y. \tag{2.4}$$

Definition 2.1. ([19]) An n-dimensional Riemannian manifold (M^n, g) is said to be Ricci pseudo-symmetric if and only if the tensors R.S and Q(g, S) are linearly dependent, i.e.

$$(R(X, Y).S)(Z, W) = L_S Q(g, S)(Z, W; X, Y), \tag{2.5}$$

holds on U_S , where $U_S = [x \in M : S \neq \frac{r}{n}g \text{ at } x]$ and L_S is a certain function on U_S .

The above developments allow to several authors for the generalisation of the notion of quasi Einstein manifolds. In this process generalized quasi-Einstein manifolds are studied by Prakasha and Venkatesha [7] and N(k)-quasi Einstein manifolds are studied by [6, 11]. In 2012, S. K. Hui and R. S. Lemence [15] discussed generalised quasi-Einstein manifold admitting a W_2 - curvature tensor and they proved that if a W_2 - curvature tensor satisfies $W_2.S = 0$, then either the associated scalars β and γ are equal or the curvature tensor R satisfies a definite condition. D. G. Prakasha and H. Venkatesha [7] studied some results on generalised quasi-Einstein manifolds and they proved that in generalised quasi-Einstein manifold if a conharmonic curvature tensor satisfies $L.S = 0$, then either M is a nearly quasi-Einstein manifold $N(QE)_n$ or the curvature tensor R satisfies a definite condition. Recently B. B. Chaturvedi and B. K. Gupta [4] studied Bochner Ricci semi-symmetric Hermitian manifold and B. K. Gupta, B. B. Chaturvedi and M. A. Lone [5] studied Ricci semi-symmetric mixed super quasi-Einstein Hermitian manifold. We have gone through the above developments in quasi-Einstein manifold $(QE)_n$, generalised quasi-Einstein manifold $G(QE)_n$, a super quasi-Einstein manifold and decide to study Bochner Ricci pseudo-symmetric super quasi-Einstein Hermitian manifold and holomorphically projective Ricci pseudo-symmetric super quasi-Einstein Hermitian manifold.

3. BOCHNER RICCI PSEUDO-SYMMETRIC SUPER QUASI-EINSTEIN HERMITIAN MANIFOLD

The notion of Bochner curvature tensor was introduced by S. Bochner [14]. The Bochner curvature tensor B is defined by

$$\begin{aligned}
 B(Y, Z, U, V) = & R(Y, Z, U, V) - \frac{1}{2(n+2)} \left\{ S(Y, V)g(Z, U) - S(Y, U)g(Z, V) \right. \\
 & + g(Y, V)S(Z, U) - g(Y, U)S(Z, V) + S(JY, V)g(JZ, U) \\
 & - S(JY, U)g(JZ, V) + S(JZ, U)g(JY, V) - g(JY, U)S(JZ, V) \\
 & \left. - 2S(JY, Z)g(JU, V) - 2g(JY, Z)S(JU, V) \right\} \\
 & + \frac{r}{(2n+2)(2n+4)} \left\{ g(Z, U)g(Y, V) - g(Y, U)g(Z, V) \right. \\
 & \left. + g(JZ, U)g(JY, V) - g(JY, U)g(JZ, V) - 2g(JY, Z)g(JU, V) \right\},
 \end{aligned} \tag{3.1}$$

where r is a scalar curvature of the manifold.

In a Hermitian manifold a Bochner curvature tensor satisfies the condition

$$B(X, Y, U, V) = -B(X, Y, V, U). \tag{3.2}$$

We introduce the following:

Definition 3.1. A Hermitian manifold is said to be a super quasi-Einstein Hermitian manifold if it satisfies the equation (1.12). Throughout this paper, we denote the super quasi-Einstein Hermitian manifold by $S(QEH)_n$.

Definition 3.2. An even dimensional Hermitian manifold (M^n, g) is said to be a Bochner Ricci pseudo-symmetric super quasi-Einstein Hermitian manifold if and only if the tensors B, S and $Q(g, S)$ are linearly dependent i.e.

$$(B(X, Y).S)(Z, U) = L_S Q(g, S)(Z, U; X, Y), \tag{3.3}$$

holds on U_S , where $U_S = [x \in M : S \neq \frac{r}{n}g \text{ at } x]$ and L_S is a certain function on U_S . If we take a Bochner Ricci pseudo-symmetric super quasi-Einstein Hermitian manifold, then from equation (3.3) and (1.12), we have

$$\begin{aligned}
 & S(B(X, Y)Z, U) + S(Z, B(X, Y)U) \\
 & = L_S [g(Y, Z)S(X, U) - g(X, Z)S(Y, U) + g(Y, U)S(X, Z) - g(X, U)S(Y, Z)].
 \end{aligned} \tag{3.4}$$

Using equation (1.12) in equation (3.4), we get

$$\begin{aligned}
 & \alpha[g(B(X, Y)Z, U) + g(Z, B(X, Y)U)] \\
 & + \beta[A(B(X, Y)Z)A(U) + A(B(X, Y)U)A(Z)] \\
 & + \gamma[A(B(X, Y)Z)C(U) + A(U)C(B(X, Y)Z) \\
 & + A(Z)C(B(X, Y)U) + A(B(X, Y)U)C(Z)] \\
 & + \delta[D(B(X, Y)Z, U) + D(Z, B(X, Y)U)] \\
 & = L_S \left(\beta[g(Y, Z)A(X)A(U) - g(X, Z)A(Y)A(U) \right. \\
 & + g(Y, U)A(X)A(Z) - g(X, U)A(Y)A(Z)] \\
 & + \gamma[g(Y, Z)[(A(X)C(U) + A(U)C(X)) - g(X, Z)[A(Y)C(U) + A(U)C(Y)] \\
 & + g(Y, U)[A(X)C(Z) + A(Z)C(X)] - g(X, U)[A(Y)C(Z) + A(Z)C(Y)]] \\
 & \left. + \delta[g(Y, Z)D(X, U) - g(X, Z)D(Y, U) + g(Y, U)D(X, Z) - g(X, U)D(Y, Z)] \right). \tag{3.5}
 \end{aligned}$$

Using equation (3.2) in equation (3.5) we infer

$$\begin{aligned}
 & \beta[A(B(X, Y)Z)A(U) + A(B(X, Y)U)A(Z)] \\
 & + \gamma[A(B(X, Y)Z)C(U) + A(U)C(B(X, Y)Z) \\
 & + A(Z)C(B(X, Y)U) + A(B(X, Y)U)C(Z)] \\
 & + \delta[D(B(X, Y)Z, U) + D(Z, B(X, Y)U)] \\
 & = L_S \left\{ \beta[g(Y, Z)A(X)A(U) - g(X, Z)A(Y)A(U) \right. \\
 & + g(Y, U)A(X)A(Z) - g(X, U)A(Y)A(Z)] \\
 & + \gamma[g(Y, Z)[(A(X)C(U) + A(U)C(X)) - g(X, Z)[A(Y)C(U) + A(U)C(Y)] \\
 & + g(Y, U)[A(X)C(Z) + A(Z)C(X)] - g(X, U)[A(Y)C(Z) + A(Z)C(Y)]] \\
 & + \delta[g(Y, Z)D(X, U) - g(X, Z)D(Y, U) \\
 & \left. + g(Y, U)D(X, Z) - g(X, U)D(Y, Z)] \right\}. \tag{3.6}
 \end{aligned}$$

Now putting $U = Z = \rho$, we have

$$2\gamma \left\{ B(X, Y, \rho, \mu) - L_S[C(X)A(Y) - C(Y)A(X)] \right\} = 0. \tag{3.7}$$

This implies either $\gamma = 0$ or

$$B(X, Y, \rho, \mu) = L_S[C(X)A(Y) - C(Y)A(X)]. \tag{3.8}$$

If $\gamma = 0$, then from equation (1.12), we obtain

$$S(X, Y) = \alpha g(X, Y) + \beta A(X)A(Y) + \delta D(X, Y). \tag{3.9}$$

This is the condition of a pseudo quasi-Einstein manifold.

Thus we conclude:

Theorem 3.3. *A Bochner Ricci pseudo-symmetric super quasi-Einstein Hermitian manifold is either a Bochner Ricci pseudo-symmetric pseudo quasi-Einstein Hermitian manifold or*

$$B(X, Y, \rho, \mu) = L_S[C(X)A(Y) - C(Y)A(X)].$$

From equation (3.7), we can also conclude:

Corollary 3.1. *In a Bochner Ricci pseudo-symmetric super quasi-Einstein Hermitian manifold if $\gamma \neq 0$ then $B(X, Y, \rho, \mu) = 0$ if and only if the vector fields ρ and μ corresponding to 1-forms A and C respectively are codirectional.*

4. BOCHNER FLAT RICCI PSEUDO-SYMMETRIC SUPER QUASI-EINSTEIN
HERMITIAN MANIFOLD WITH $(B(X, Y).S)(Z, U)$
 $= L_S Q(g, S)(Z, U; X, Y)$

If we take a Bochner flat curvature tensor then from equation (3.1), we have

$$\begin{aligned} R(Y, Z, U, V) &= \frac{1}{2(n+2)} \left\{ S(Y, V)g(Z, U) - S(Y, U)g(Z, V) \right. \\ &+ g(Y, V)S(Z, U) - g(Y, U)S(Z, V) + S(JY, V)g(JZ, U) \\ &- S(JY, U)g(JZ, V) + S(JZ, U)g(JY, V) - g(JY, U)S(JZ, V) \\ &\left. - 2S(JY, Z)g(JU, V) - 2g(JY, Z)S(JU, V) \right\} \\ &- \frac{r}{(2n+2)(2n+4)} \left\{ g(Z, U)g(Y, V) - g(Y, U)g(Z, V) \right. \\ &\left. + g(JZ, U)g(JY, V) - g(JY, U)g(JZ, V) - 2g(JY, Z)g(JU, V) \right\}. \end{aligned} \quad (4.1)$$

From equations (2.5) and (4.1), we infer

$$\begin{aligned} &\frac{1}{(2n+4)} \left\{ S(QY, V)g(Z, U) - g(Y, U)S(QZ, V) + S(QJY, V)g(JZ, U) \right. \\ &- g(JY, U)S(JQZ, V) - 2g(JY, Z)S(JQU, V) \\ &+ S(QY, U)g(Z, V) - g(Y, V)S(QZ, U) + S(QJY, U)g(JZ, V) \\ &\left. - g(JY, V)S(JQZ, U) - 2g(JY, Z)S(JQV, U) \right\} \\ &- \frac{r}{(2n+2)(2n+4)} \left\{ g(Z, U)S(Y, V) - g(Y, U)S(Z, V) + g(JZ, U)S(JY, V) \right. \\ &- g(JY, U)S(JZ, V) + g(Z, V)S(Y, U) - g(Y, V)S(Z, U) \\ &\left. + g(JZ, V)S(JY, U) - g(JY, V)S(JZ, U) \right\} \\ &= L_S[g(Z, U)S(Y, V) - g(Y, U)S(Z, V) + g(Z, V)S(Y, U) - g(Y, V)S(Z, U)]. \end{aligned} \quad (4.2)$$

If we take λ be an eigen value of Q and JQ corresponding to eigen vectors X and JX respectively then $QX = \lambda X$ and $QJX = \lambda JX$ i.e. $S(X, U) = \lambda g(X, U)$ (where the manifold is not Einstein) and hence

$$S(QX, U) = \lambda S(X, U) \quad \text{and} \quad S(QJX, U) = \lambda S(JX, U). \quad (4.3)$$

Using equation (4.3) in equation (4.2), we infer

$$\begin{aligned} & \left(\frac{\lambda}{(2n+4)} - \frac{r}{(2n+2)(2n+4)} \right) \left\{ S(Y, V)g(Z, U) - g(Y, U)S(Z, V) \right. \\ & + S(Y, U)g(Z, V) - g(Y, V)S(Z, U) + S(JY, V)g(JZ, U) \\ & \left. - S(JZ, V)g(JY, U) + S(JY, U)g(JZ, V) - g(JY, V)S(JZ, U) \right\} \\ & = L_S[g(Z, U)S(Y, V) - g(Y, U)S(Z, V) + g(Z, V)S(Y, U) - g(Y, V)S(Z, U)]. \end{aligned} \quad (4.4)$$

Now putting $V = U = \rho$, we get

$$\begin{aligned} & \left(\frac{\lambda}{(2n+4)} - \frac{r}{(2n+2)(2n+4)} \right) \left([S(Y, \rho)g(Z, \rho) - g(Y, \rho)S(Z, \rho)] \right. \\ & \left. + S(JY, \rho)g(JZ, \rho) - S(JZ, \rho)g(JY, \rho) \right) \\ & = L_S[g(Z, \rho)S(Y, \rho) - g(Y, \rho)S(Z, \rho)]. \end{aligned} \quad (4.5)$$

Now using equations (1.9) and (1.14) in equation (4.5), we have

$$\begin{aligned} & \gamma \left(\left(\frac{\lambda}{(2n+4)} - \frac{r}{(2n+2)(2n+4)} \right) - L_S \right) [C(Y)A(Z) - C(Z)A(Y)] \\ & = \gamma \left(\frac{\lambda}{(2n+4)} - \frac{r}{(2n+2)(2n+4)} \right) [A(JY)C(JZ) - A(JZ)C(JY)]. \end{aligned} \quad (4.6)$$

If we take $\lambda = \frac{r}{(2n+2)}$ and $\gamma \neq 0$, then

$$A(Z)C(Y) = A(Y)C(Z). \quad (4.7)$$

If we take $\lambda = \frac{r}{(2n+2)}$ and $\gamma \neq 0$, then from equations (1.2) and (1.9), equation (4.7) imply $g(Z, \rho)g(Y, \mu) = g(Y, \rho)g(Z, \mu)$, therefore we can say that the vector fields ρ and μ corresponding to 1-forms A and C respectively are codirectional.

Thus we conclude:

Theorem 4.1. *In a Bochner flat Ricci pseudo-symmetric super quasi-Einstein Hermitian manifold if $\frac{r}{(2n+2)}$ is an eigen value of the Ricci operator Q and JQ and $\gamma \neq 0$ then the vector fields ρ and μ corresponding to 1-forms A and C respectively are codirectional.*

5. HOLOMORPHICALLY PROJECTIVE RICCI PSEUDO-SYMMETRIC SUPER QUASI-EINSTEIN HERMITIAN MANIFOLD

The holomorphically projective curvature tensor is defined by [20]

$$P(X, Y, Z, W) = R(X, Y, Z, W) - \frac{1}{n-2}[S(Y, Z)g(X, W) - S(X, Z)g(Y, W) + S(JX, Z)g(JY, W) - S(JY, Z)g(JX, W)]. \quad (5.1)$$

This tensor has the following properties

$$P(X, Y, Z, W) = -P(Y, X, Z, W), \quad P(JX, JY, Z, W) = P(X, Y, Z, W). \quad (5.2)$$

Now we introduce the following:

Definition 5.1. An even dimensional Hermitian manifold (M^n, g) is said to be a holomorphically projective Ricci pseudo-symmetric super quasi-Einstein Hermitian manifold if the holomorphically projective curvature tensor of the manifold satisfies $P.S = 0$, i.e.

$$(P(X, Y).S)(Z, W) = L_S Q(g, S)(Z, W; X, Y). \quad (5.3)$$

for all $X, Y, Z, W \in \chi(M^n)$.

If we take a holomorphically projective Ricci pseudo-symmetric super quasi-Einstein Hermitian manifold, then from the equations (1.12) and (5.1), we have

$$\begin{aligned} & \alpha[P(X, Y, Z, W) + P(X, Y, W, Z)] \\ & + \beta[A(P(X, Y)Z)A(W) + A(Z)A(P(X, Y)W)] \\ & + \gamma[A(P(X, Y)Z)C(W) + A(W)C(P(X, Y)Z) \\ & + A(Z)C(P(X, Y)W) + C(Z)A(P(X, Y)W)] \\ & + \delta[D(P(X, Y)Z, W) + D(Z, P(X, Y)W)] \\ & = L_S[g(Y, Z)S(X, W) - g(X, Z)S(Y, W) + g(Y, W)S(X, Z) - g(X, W)S(Y, Z)]. \end{aligned} \quad (5.4)$$

Now putting $Z = W = \rho$ in equation (5.4) and using equation (1.14), we have

$$\begin{aligned} & (\alpha + \beta)P(X, Y, \rho, \rho) + \gamma P(X, Y, \rho, \rho) \\ & = \gamma L_S[A(Y)C(X) - A(X)C(Y)]. \end{aligned} \quad (5.5)$$

Using $Z = W = \rho$ in equation (5.1), we have

$$\begin{aligned} P(X, Y, \rho, \rho) & = -\frac{\gamma}{n-2}[C(Y)A(X) - A(Y)C(X) \\ & + C(JX)A(JY) - C(JY)A(JX)]. \end{aligned} \quad (5.6)$$

Similarly putting $Z = \rho$ and $W = \mu$ in equation (5.1), we get

$$\begin{aligned} P(X, Y, \rho, \mu) & = R(X, Y, \rho, \mu) - \frac{(\alpha + \beta)}{n-2}[A(Y)C(X) - C(Y)A(X) \\ & + C(JX)A(JY) - C(JY)A(JX)]. \end{aligned} \quad (5.7)$$

Using equations (5.6) and (5.7) in (5.5), we get

$$\gamma[R(X, Y, \rho, \mu) - L_S[A(Y)C(X) - A(X)C(Y)]] = 0, \quad (5.8)$$

this implies that either $\gamma = 0$ or $R(X, Y, \rho, \mu) = L_S[A(Y)C(X) - A(X)C(Y)]$. If $\gamma = 0$ then from equation (1.12), we get the condition of a pseudo quasi-Einstein manifolds.

Thus we can conclude:

Theorem 5.2. *A holomorphically projectively Ricci pseudo-symmetric super quasi-Einstein Hermitian manifold is either a holomorphically projective Ricci semi-symmetric pseudo quasi-Einstein Hermitian manifold or*

$$R(X, Y, \rho, \mu) = L_S[A(Y)C(X) - A(X)C(Y)].$$

Corollary 5.1. *In a holomorphically projectively Ricci pseudo-symmetric super quasi-Einstein Hermitian manifold if $\gamma \neq 0$ then $R(X, Y, \rho, \mu) = 0$ if and only if the vector fields ρ and μ corresponding to one form A and C respectively are codirectional.*

Putting $Z = \rho$ and $W = \mu$ in equation (5.4), we get

$$\begin{aligned} & \alpha[P(X, Y, \rho, \mu) + P(X, Y, \mu, \rho)] + \beta P(X, Y, \mu, \rho) \\ & + \gamma[P(X, Y, \rho, \rho) + P(X, Y, \mu, \mu)] = \beta L_S[A(X)C(Y) - A(Y)C(X)]. \end{aligned} \quad (5.9)$$

Putting $Z = U = \mu$ in (5.1), we get

$$\begin{aligned} & P(X, Y, \mu, \mu) \\ & = -\frac{\gamma}{n-2}[A(Y)C(X) - C(Y)A(X) + C(JY)A(JX) - C(JX)A(JY)]. \end{aligned} \quad (5.10)$$

Adding equations (5.6) and (5.10), we get

$$P(X, Y, \mu, \mu) + P(X, Y, \rho, \rho) = 0, \quad (5.11)$$

from equations (5.9) and (5.11), we have

$$\alpha[P(X, Y, \rho, \mu) + P(X, Y, \mu, \rho)] + \beta P(X, Y, \mu, \rho) = \beta L_S[A(X)C(Y) - A(Y)C(X)]. \quad (5.12)$$

From equations (5.1), (5.7) and (5.12), we have

$$\beta[R(X, Y, \mu, \rho) - L_S[A(X)C(Y) - A(Y)C(X)]] = 0. \quad (5.13)$$

This implies either $\beta = 0$ or $R(X, Y, \mu, \rho) = L_S[A(X)C(Y) - A(Y)C(X)]$.

Theorem 5.3. *In a holomorphically projective Ricci pseudo-symmetric super quasi-Einstein Hermitian manifold if $\beta \neq 0$ then $R(X, Y, \mu, \rho) = 0$ if and only if the vector fields ρ and μ corresponding to one form A and C respectively are codirectional.*

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