# A Study on Lorentzian $\alpha$-Sasakian Manifolds 

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#### Abstract

The object of the present paper is to study the geometric properties of Concircular curvature tensor on Lorentzian $\alpha$-Sasakian manifold admitting a type of quarter-symmetric metric connection. In the last, we provide an example of 3-dimensional Lorentzian $\alpha$-Sasakian manifold endowed with the quarter-symmetric metric connection which is under consideration is an $\eta$-Einstein manifold with respect to the quarter-symmetric metric connection.


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## 1. Introduction

In 1975, Golab [5] defined and studied quarter-symmetric connection in differentiable manifolds. A linear connection $\bar{\nabla}$ on an $n$-dimensional Riemannian manifold $(M, g)$ is said to be a quarter-symmetric connection [5] if its torsion tensor $T$ defined by
$T(X, Y)=\bar{\nabla}_{X} Y-\bar{\nabla}_{Y} X-[X, Y]$
satisfies
$T(X, Y)=\eta(Y) \phi X-\eta(X) \phi Y$,
where $\phi$ is a $(1,1)$ tensor field, $\eta$ is a 1-form and $X, Y$ are vector fields on $\Gamma(T M), \Gamma(T M)$ is the set of all differentiable vector fields on $M$. In particular, if $\phi X=X$, then the quarter-symmetric connection reduces to the semi-symmetric connection [4].
Thus the notion of the quarter-symmetric connection generalizes the notion of the semi-symmetric connection. If moreover, a quartersymmetric connection $\bar{\nabla}$ satisfies the condition

$$
\begin{equation*}
\left(\bar{\nabla}_{X} g\right)(Y, Z)=0 \tag{1.3}
\end{equation*}
$$

for all $X, Y, Z$ on $\Gamma(T M)$, then $\bar{\nabla}$ is said to be a quarter-symmetric metric connection, otherwise it is said to be a quarter symmetric non-metric connection. Recently quarter-symmetric metric connection have been studied by several authors ([8], [9], [12]).
A differentiable manifold $M$ is said to be a Lorentzian manifold, if $M$ has a Lorentzian metric $g$, which is a symmetric non-degenerate $(0,2)$ tensor field of index 1 . Since the Lorentzian metric $g$ is of index 1 therefore Lorentzian manifold $M$ has not only spacelike vector fields but also lightlike and timelike vector fields. On a Lorentzian manifold this difference with Riemannian case gives interesting results. In 1989 , K. Matsumoto used a structure vector field $-\xi$ instead of $\xi$ in an almost para contact manifold and associated a Lorentzian metric with this resulting structure, called it as Lorentzian almost para contact manifold.

Yildiz and Murathan studied [15] Lorentzian $\alpha$-Sasakian manifolds in 2005 and obtained results for conformally flat and quasi-conformally flat Lorentzian $\alpha$-Sasakian manifolds. In 2009, Yildiz et al. ([16, 17]), further studied on three dimensional Lorentzian $\alpha$-Sasakian manifolds and a class of Lorentzian $\alpha$-Sasakian manifolds and obtained some important results. In 2013, U.C. De and K. De ([3]) studied on Lorentzian Trans-Sasakian manifolds, which is a generalization of Lorentzian $\alpha$-Sasakian manifolds.
A concircular transformation ([7], [13]) on an $n$-dimensional Riemannian manifold $M$ is a transformation under which every geodesic circle of $M$ transforms into a geodesic circle. Every concircular transformation is always a conformal transformation [7]. Thus the concircular geometry, is a generalization of inversive geometry in the sense that the change of metric is more general than that induced by a circle
preserving diffeomorphism (see also [2]). An interesting invariant of a concircular transformation is the concircular curvature tensor $\bar{C}$. It is defined by ([13], [14])
$\bar{C}(X, Y) Z=\bar{R}(X, Y) Z-\frac{\bar{r}}{2 n(2 n+1)}[g(Y, Z) X-g(X, Z) Y]$.
for all vector fields $X, Y, Z \in \Gamma(T M)$, where $\bar{R}$ and $\bar{r}$ be the curvature tensor and scalar curvature with respect to the quarter-symmetric metric connection $\bar{\nabla}$ respectively.
Using (1.4), we obtain
$` \bar{C}(X, Y, Z, W)=` \bar{R}(X, Y, Z, W)-\frac{\bar{r}}{2 n(2 n+1)}[g(Y, Z) g(X, W)-g(X, Z) g(Y, W)]$,
where ' $\bar{C}(X, Y, Z, W)=g(\bar{C}(X, Y) Z, W),{ }^{`}(X, Y, Z, W)=g(\bar{R}(X, Y) Z, W)$, where $X, Y, Z, W \in \Gamma(T M)$ and $\bar{C}$ is the concircular curvature tensor and $\bar{r}$ is the scalar curvature with respect to the quarter-symmetric metric connection respectively. Riemannian manifolds with vanishing concircular curvature tensor are of constant curvature. Thus the concircular curvature tensor is a measure of the failure of a Riemannian manifold to be of constant curvature.

In this paper, we study a type of quarter-symmetric metric connection on Lorentzian $\alpha$-Sasakian manifolds. The paper is organized as follows: After introduction section two gives some prerequisites of a Lorentzian $\alpha$-Sasakian manifold. In section three, we obtain a relation between the quarter-symmetric metric connection and Levi-civita connection. In section four, curvature tensor and Ricci tensor of Lorentzian $\alpha$-Sasakian manifold with respect to quarter-symmetric metric connection are given. Section five is devoted to the study of $\xi$-concircularly flat Lorentzian $\alpha$-Sasakian manifold with respect to the quarter-symmetric metric connection. Quasi-concircularly flat and $\phi$-concircularly flat Lorentzian $\alpha$-Sasakian manifolds with respect to the quarter-symmetric metric connection have been studied in section six and seven respectively. In the next section, we study a Lorentzian $\alpha$-Sasakian manifold satisfying $\bar{C} \cdot \bar{S}=0$ with respect to a quarter-symmetric metric connection. In the last, we construct an example of a 3-dimensional Lorentzian $\alpha$-Sasakian manifold endowed with the quarter-symmetric metric connection.

## 2. Preliminaries

An $(2 n+1)$-dimensional differentiable manifold $M$ is said to be a Lorentzian $\alpha$-Sasakian manifold, if it admits a structure $(\phi, \xi, \eta, g)$ consisting of a $(1,1)$ tensor field $\phi$, vector field $\xi, 1$-form $\eta$ and a Lorentzian metric $g$ satisfying
$\phi^{2} X=X+\eta(X) \xi$,
$\phi \circ \xi=0, \quad \eta \circ \phi=0, \eta(\xi)=-1, g(X, \xi)=\eta(X)$,
$g(\phi X, \phi Y)=g(X, Y)+\eta(X) \eta(Y)$,

$$
\begin{equation*}
\left(\nabla_{X} \phi\right) Y=\alpha\{g(X, Y) \xi+\eta(Y) X\} \tag{2.4}
\end{equation*}
$$

for any vector field $X, Y$ on $M$, where $\nabla$ denotes the covariant differentiation with respect to Lorentzian metric $g$.
Also a Lorentzian $\alpha$-Sasakian manifold satisfies [16]
$\nabla_{X} \xi=\alpha \phi X$,
$\left(\nabla_{X} \eta\right) Y=\alpha g(X, \phi Y)$
for $X, Y$ tangent to $M$.
Moreover, the curvature tensor $R$, the Ricci tensor $S$ and the Ricci operator $Q$ in a Lorentzian $\alpha$-Sasakian manifold $M$ with respect to the Levi-Civita connection $\nabla$, satisfies following relations [16]
$R(\xi, X) Y=\alpha^{2}\{g(X, Y) \xi-\eta(Y) X\}$,
$R(X, Y) \xi=\alpha^{2}\{\eta(Y) X-\eta(X) Y\}$,
$R(\xi, X) \xi=-R(X, \xi) \xi=\alpha^{2}\{X+\eta(X) \xi\}$,
$S(X, \xi)=2 n \alpha^{2} \eta(X)$,
$S(\xi, \xi)=-2 n \alpha^{2}, \quad Q \xi=2 n \alpha^{2} \xi$,
$S(\phi X, \phi Y)=S(X, Y)-2 n \alpha^{2} g(X, Y)$,
for all vector fields $X, Y \in \Gamma(T M)$.

## 3. Relation Between the Quarter-Symmetric Metric Connection and Riemannian Connection

Let $\nabla$ be a Riemannian connection and $\bar{\nabla}$ be a linear connection on Lorentzian $\alpha$-Sasakian manifold $M$ such that
$\bar{\nabla}_{X} Y=\nabla_{X} Y+H(X, Y)$,
where $H$ is a tensor of type $(1,2)$. Now if $\bar{\nabla}$ be a quarter-symmetric connection on $M$, then we have [5]
$H(X, Y)=\frac{1}{2}\left[T(X, Y)+T^{\prime}(X, Y)+T^{\prime}(Y, X)\right]$,
where
$g\left(T^{\prime}(X, Y), Z\right)=g(T(Z, X), Y)$.

Using (1.2) in (3.3), we get
$T^{\prime}(X, Y)=\eta(X) \phi Y-g(\phi X, Y) \xi$.
In view of (1.2) and (3.4), equation (3.2) gives
$H(X, Y)=\eta(Y) \phi X-g(\phi X, Y) \xi$.
Hence from (3.1), a quarter-symmetric connection $\bar{\nabla}$ on a Lorentzian $\alpha$-Sasakian manifold $M$ is given by
$\bar{\nabla}_{X} Y=\nabla_{X} Y+\eta(Y) \phi X-g(\phi X, Y) \xi$.

Also we have
$\left(\bar{\nabla}_{X} g\right)(Y, Z)=X g(Y, Z)-g\left(\bar{\nabla}_{X} Y, Z\right)-g\left(Y, \bar{\nabla}_{X} Z\right)$

With the help of (3.6), after simplification (3.7) gives
$\left(\bar{\nabla}_{X} g\right)(Y, Z)=0, \quad \forall Y, Z \in \Gamma(T M)$.

By virtue of (3.6) and (3.8), we conclude that $\bar{\nabla}$ is a quarter-symmetric metric connection. Therefore (3.6) is the relation between Riemannian connection and quarter-symmetric metric connection on a Lorentzian $\alpha$-Sasakian manifold.

## 4. Curvature Tensor and Ricci Tensor of Lorentzian $\alpha$-Sasakian Manifold with respect to the

## Quarter-Symmetric Metric Connection

Let $R(X, Y) Z$ and $\bar{R}(X, Y) Z$ be the curvature tensors of a Lorentzian $\alpha$-Sasakian manifold $M$ with respect to the Riemannian connection $\nabla$ and quarter-symmetric metric connection $\bar{\nabla}$ respectively, then relation between $R(X, Y) Z$ and $\bar{R}(X, Y) Z$ is given by

$$
\begin{align*}
\bar{R}(X, Y) Z= & R(X, Y) Z+\alpha \eta(Z)[\eta(Y) X-\eta(X) Y]  \tag{4.1}\\
& +(2 \alpha-1)[g(\phi X, Z) \phi Y-g(\phi Y, Z) \phi X] \\
& -\alpha[g(X, Z) \eta(Y)-g(Y, Z) \eta(X)] \xi
\end{align*}
$$

From (4.1), we have
$\bar{R}(\xi, X) Y=\left(\alpha^{2}-\alpha\right)[g(X, Y) \xi-\eta(Y) X]$,
$\bar{R}(X, Y) \xi=\left(\alpha^{2}-\alpha\right)[\eta(Y) X-\eta(X) Y]$,
$\bar{R}(\xi, Y) \xi=\left(\alpha^{2}-\alpha\right)[Y+\eta(Y) \xi]$.
Let $\left\{e_{1}, e_{2}, \ldots, e_{2 n}, e_{2 n+1}=\xi\right\}$ be a local orthonormal basis of vector fields in $M$. Since on a semi-Riemannian manifold, we have [10]
$\sum_{i=1}^{2 n+1} \varepsilon_{i} g\left(R\left(e_{i}, Y\right) Z, e_{i}\right)=S(Y, Z)$,
$\sum_{i=1}^{2 n+1} \varepsilon_{i} S\left(e_{i}, Y\right) g\left(e_{i}, Z\right)=S(Y, Z)$,
$\sum_{i=1}^{2 n+1} \varepsilon_{i} g\left(e_{i}, Y\right) g\left(e_{i}, Z\right)=g(Y, Z)$,
and
$\sum_{i=1}^{2 n+1} \varepsilon_{i} g\left(\phi e_{i}, e_{i}\right)=\operatorname{trace}(\phi)$,
where $\varepsilon_{i}=g\left(e_{i}, e_{i}\right), i=1,2, \ldots, 2 n+1$. Using above results on a Lorentzian $\alpha$-Sasakian manifold, it can be easily verify that
$\sum_{i=1}^{2 n} g\left(R\left(e_{i}, Y\right) Z, e_{i}\right)=S(Y, Z)-\alpha^{2} g(\phi Y, \phi Z)$,
$\sum_{i=1}^{2 n} S\left(e_{i}, Y\right) g\left(e_{i}, Z\right)=S(Y, Z)+2 n \alpha^{2} \eta(Y) \eta(Z)$,
$\sum_{i=1}^{2 n} g\left(e_{i}, e_{i}\right)=2 n$,
$\sum_{i=1}^{2 n} g\left(e_{i}, Y\right) g\left(e_{i}, Z\right)=g(\phi Y, \phi Z)$,
$\sum_{i=1}^{2 n} g\left(\phi e_{i}, e_{i}\right)=\operatorname{trace}(\phi)$
and

$$
\begin{equation*}
\sum_{i=1}^{2 n} g\left(\bar{R}\left(e_{i}, Y\right) Z, e_{i}\right)=\bar{S}(Y, Z)-\left(\alpha^{2}-\alpha\right) g(\phi Y, \phi Z) \tag{4.10}
\end{equation*}
$$

Then from (4.1), we obtain

$$
\begin{align*}
\bar{S}(Y, Z)= & S(Y, Z)+\{(2 n+1) \alpha-1\} \eta(Y) \eta(Z)  \tag{4.11}\\
& +(\alpha-1) g(Y, Z)-(2 \alpha-1) \operatorname{trace}(\phi) \Phi(Y, Z)
\end{align*}
$$

$\bar{S}(Y, \xi)=2 n\left(\alpha^{2}-\alpha\right) \eta(Y)$,
$\bar{S}(\xi, \xi)=-2 n\left(\alpha^{2}-\alpha\right)$,
$\bar{S}(\phi Y, \phi Z)=\bar{S}(Y, Z)-2 n \alpha^{2} g(Y, Z)-2 n \alpha \eta(Y) \eta(Z)$.
where $\bar{S}$ and $\bar{r}$ be the Ricci tensor and scalar curvature with respect to the quarter-symmetric metric connection $\bar{\nabla}$ respectively.

## 5. $\xi$-Concircularly Flat Lorentzian $\alpha$-Sasakian Manifold with Respect to the Quarter-Symmetric Metric Connection

Definition 5.1. A Lorentzian $\alpha$-Sasakian manifold is said to be $\xi$-concircularly flat [1] with respect to the quarter-symmetric metric connection if $\bar{C}(X, Y) \xi=0$, where $X, Y \in \Gamma(T M)$.

Theorem 5.2. A Lorentzian $\alpha$-Sasakian manifold admitting a quarter-symmetric metric connection $\bar{\nabla}$ is $\xi$-concircularly flat if and only if the scalar curvature $\bar{r}$ with respect to the quarter-symmetric metric connection is equal to $2 n(2 n+1)\left(\alpha^{2}-\alpha\right)$.

Proof. From (1.4), we have
$\bar{C}(X, Y) \xi=\bar{R}(X, Y) \xi-\frac{\bar{r}}{2 n(2 n+1)}[\eta(Y) X-\eta(X) Y]$.
Using (4.3) in (5.1), we have

$$
\begin{align*}
\bar{C}(X, Y) \xi= & \left(\alpha^{2}-\alpha\right)[\eta(Y) X-\eta(X) Y]  \tag{5.2}\\
& -\frac{\bar{r}}{2 n(2 n+1)}[\eta(Y) X-\eta(X) Y] .
\end{align*}
$$

From (5.2), we have
$\bar{C}(X, Y) \xi=\left[\left(\alpha^{2}-\alpha\right)-\frac{\bar{r}}{2 n(2 n+1)}\right][\eta(Y) X-\eta(X) Y]$.
Thus from (5.3), if $\bar{C}(X, Y) \xi=0$, then $\bar{r}=2 n(2 n+1)\left(\alpha^{2}-\alpha\right)$ or $\eta(Y) X-\eta(X) Y=0$, implies that $\eta(X)=0$ which is not possible.
Conversely, if $\bar{r}=2 n(2 n+1)\left(\alpha^{2}-\alpha\right)$, then from (5.3), it follows that $\bar{C}(X, Y) \xi=0$.
This completes the proof of the theorem.

## 6. Quasi-Concircularly Flat Lorentzian $\alpha$-Sasakian Manifold with Respect to the Quarter-Symmetric

## Metric Connection

Definition 6.1. A Lorentzian $\alpha$-Sasakian manifold is said to be quasi-concircularly flat with respect to the quarter-symmetric metric connection if
$‘ \bar{C}(\phi X, Y, Z, \phi W)=0$
where $X, Y, Z, W \in \Gamma(T M)$.
Definition 6.2. A Lorentzian $\alpha$-Sasakian manifold is said to be an $\eta$-Einstein manifold [17] if its Ricci tensor $S$ of the Levi-Civita connection is of the form
$S(X, Y)=a g(X, Y)+b \eta(X) \eta(Y)$,
where $a$ and $b$ are smooth functions on the manifold.
Theorem 6.3. If a Lorentzian $\alpha$-Sasakian manifold admitting a quarter-symmetric metric connection is quasi-concircularly flat, then the manifold with respect to the quarter-symmetric metric connection is an $\eta$-Einstein manifold.

Proof. From (1.4), we have

$$
\begin{align*}
{ }_{C}^{C}(X, Y, Z, W)= &  \tag{6.3}\\
& \bar{R}(X, Y, Z, W)-\frac{\bar{r}}{2 n(2 n+1)}[g(Y, Z) g(X, W) \\
& -g(X, Z) g(Y, W)] .
\end{align*}
$$

where ${ }^{`} \bar{C}(X, Y, Z, W)=g(\bar{C}(X, Y) Z, W)$ and ${ }^{\prime} \bar{R}(X, Y, Z, W)=g(\bar{R}(X, Y) Z, W)$.
Now putting $X=\phi X$ and $W=\phi W$ in (6.3), we get

$$
\begin{align*}
‘ \bar{C}(\phi X, Y, Z, \phi W)= & ‘ \bar{R}(\phi X, Y, Z, \phi W)-\frac{\bar{r}}{2 n(2 n+1)}[g(Y, Z) g(\phi X, \phi W)  \tag{6.4}\\
& -g(\phi X, Z) g(Y, \phi W)] .
\end{align*}
$$

Using (6.1) in (6.4), we get
$‘ \bar{R}(\phi X, Y, Z, \phi W)=\frac{\bar{r}}{2 n(2 n+1)}[g(Y, Z) g(\phi X, \phi W)-g(\phi X, Z) g(Y, \phi W)]$.
Let $\left\{e_{1}, e_{2}, \ldots ., e_{2 n}, \xi\right\}$ be a local orthonormal basis of vector fields in $M$, then $\left\{\phi e_{1}, \phi e_{2}, \ldots ., \phi e_{2 n}, \xi\right\}$ is also a local orthonormal basis. Putting $X=W=e_{i}$ in (6.5) and summing over $i=1$ to $2 n$, we obtain
$\sum_{i=1}^{2 n} \cdot \bar{R}\left(\phi e_{i}, Y, Z, \phi e_{i}\right)=\frac{\bar{r}}{2 n(2 n+1)} \sum_{i=1}^{2 n}\left[g(Y, Z) g\left(\phi e_{i}, \phi e_{i}\right)-g\left(\phi e_{i}, Z\right) g\left(Y, \phi e_{i}\right)\right]$,
So by virtue of $(2.3),(4.7),(4.8)$ and (4.10), the equation (6.6) takes the form
$\bar{S}(Y, Z)=\left[\frac{\bar{r}(2 n-1)}{2 n(2 n+1)}+\left(\alpha^{2}-\alpha\right)\right] g(Y, Z)-\left[\frac{\bar{r}}{2 n(2 n+1)}-\left(\alpha^{2}-\alpha\right)\right] \eta(Y) \eta(Z)$.
or
$\bar{S}(Y, Z)=a g(Y, Z)+b \eta(Y) \eta(Z)$,
where $a=\left[\frac{\bar{r}(2 n-1)}{2 n(2 n+1)}+\left(\alpha^{2}-\alpha\right)\right]$ and $b=-\left[\frac{\bar{r}}{2 n(2 n+1)}-\left(\alpha^{2}-\alpha\right)\right]$.
From which it follows that the manifold is an $\eta$-Einstein manifold with respect to the quarter-symmetric metric connection.
This completes the proof of the theorem.

## 7. $\phi$-Concircularly Flat Lorentzian $\alpha$-Sasakian Manifold with Respect to the Quarter-Symmetric Metric Connection

Definition 7.1. A Lorentzian $\alpha$-Sasakian manifold is said to be $\phi$-concircularly flat [11] with respect to the quarter-symmetric metric connection if
${ }^{`} \bar{C}(\phi X, \phi Y, \phi Z, \phi W)=0$,
where $X, Y, Z, W \in \Gamma(T M)$.
Theorem 7.2. If a Lorentzian $\alpha$-Sasakian manifold admitting a quarter-symmetric metric connection is $\phi$-concircularly flat, then the manifold with respect to the quarter-symmetric metric connection is an $\eta$-Einstein manifold.

Proof. From (1.4), we have

$$
\begin{align*}
‘ \bar{C}(X, Y, Z, W)= & ‘ \bar{R}(X, Y, Z, W)-\frac{\bar{r}}{2 n(2 n+1)}[g(Y, Z) g(X, W)  \tag{7.2}\\
& -g(X, Z) g(Y, W)]
\end{align*}
$$

where ' $\bar{C}(X, Y, Z, W)=g(\bar{C}(X, Y) Z, W)$ and ' $\bar{R}(X, Y, Z, W)=g(\bar{R}(X, Y) Z, W)$.
Now putting $X=\phi X, Y=\phi Y, Z=\phi Z, W=\phi W$ in (7.2), we get

$$
\begin{align*}
‘ \bar{C}(\phi X, \phi Y, \phi Z, \phi W)= & ‘ \bar{R}(\phi X, \phi Y, \phi Z, \phi W)-\frac{\bar{r}}{2 n(2 n+1)}[g(\phi Y, \phi Z) g(\phi X, \phi W) \\
& -g(\phi X, \phi Z) g(\phi Y, \phi W)] \tag{7.3}
\end{align*}
$$

Using (7.1) in (7.3), we get
$‘ \bar{R}(\phi X, \phi Y, \phi Z, \phi W)=\frac{\bar{r}}{2 n(2 n+1)}[g(\phi Y, \phi Z) g(\phi X, \phi W)-g(\phi X, \phi Z) g(\phi Y, \phi W)]$.
Let $\left\{e_{1}, e_{2}, \ldots, e_{2 n}, \xi\right\}$ be a local orthonormal basis of vector fields in $M$, then $\left\{\phi e_{1}, \phi e_{2}, \ldots, \phi e_{2 n}, \xi\right\}$ is also a local orthonormal basis. Putting $X=W=e_{i}$ in (7.4) and summing over $i=1$ to $2 n$, we obtain
$\sum_{i=1}^{2 n} ‘ \bar{R}\left(\phi e_{i}, \phi Y, \phi Z, \phi e_{i}\right)=\frac{\bar{r}}{2 n(2 n+1)} \sum_{i=1}^{2 n}\left[g(\phi Y, \phi Z) g\left(\phi e_{i}, \phi e_{i}\right)-g\left(\phi e_{i}, \phi Z\right) g\left(\phi Y, \phi e_{i}\right)\right]$,
So by virtue of (4.7), (4.8) and (4.10), the equation (7.5) takes the form
$\bar{S}(\phi Y, \phi Z)=\left[\frac{\bar{r}(2 n-1)}{2 n(2 n+1)}+\left(\alpha^{2}-\alpha\right)\right] g(\phi Y, \phi Z)$.
By making use of (2.3) and (4.14) in equation (7.6), we obtain

$$
\begin{align*}
\bar{S}(Y, Z)= & {\left[\frac{\bar{r}(2 n-1)}{2 n(2 n+1)}+\left(\alpha^{2}-\alpha\right)+2 n \alpha^{2}\right] g(Y, Z) }  \tag{7.7}\\
& +\left[\frac{\bar{r}(2 n-1)}{2 n(2 n+1)}+\left(\alpha^{2}-\alpha\right)+2 n \alpha\right] \eta(Y) \eta(Z)
\end{align*}
$$

or
$\bar{S}(Y, Z)=a g(Y, Z)+b \eta(Y) \eta(Z)$,
where $a=\left[\frac{\bar{r}(2 n-1)}{2 n(2 n+1)}+\left(\alpha^{2}-\alpha\right)+2 n \alpha^{2}\right]$ and $b=\left[\frac{\bar{r}(2 n-1)}{2 n(2 n+1)}+\left(\alpha^{2}-\alpha\right)+2 n \alpha\right]$.
From which it follows that the manifold is an $\eta$-Einstein manifold with respect to the quarter-symmetric metric connection.
This completes the proof of the theorem.

## 8. Lorentzian $\alpha$-Sasakian Manifold Satisfying $\bar{C} \cdot \bar{S}=0$ with Respect to the Quarter-Symmetric Metric Connection

Definition 8.1. A Lorentzian $\alpha$-Sasakian manifold is said to be an Einstein manifold if its Ricci tensor $S$ of the Levi-Civita connection is of the form
$S(X, Y)=a g(X, Y)$,
where $a$ is a constant on the manifold.
Theorem 8.2. If Lorentzian $\alpha$-Sasakian manifold satisfying $\bar{C} \cdot \bar{S}=0$ with respect to a quarter-symmetric metric connection, then the manifold is an Einstein manifold with respect to the quarter-symmetric metric connection.

Proof. We consider Lorentzian $\alpha$-Sasakian manifolds with respect to a quarter-symmetric metric connection $\bar{\nabla}$ satisfying the curvature condition $\bar{C} \cdot \bar{S}=0$. Then
$(\bar{C}(X, Y) \cdot \bar{S})(Z, W)=0$.
So,
$\bar{S}(\bar{C}(X, Y) Z, W)+\bar{S}(Z, \bar{C}(X, Y) W)=0$.
Putting $X=\xi$ in (8.3), we get
$\bar{S}(\bar{C}(\xi, Y) Z, W)+\bar{S}(Z, \bar{C}(\xi, Y) W)=0$.
From equation (1.4), we have
$\bar{C}(\xi, Y) Z=\bar{R}(\xi, Y) Z-\frac{\bar{r}}{2 n(2 n+1)}[g(Y, Z) \xi-\eta(Z) Y]$.
Using (4.2) in the equation (8.5), we obtain
$\bar{C}(\xi, Y) Z=\left\{\alpha^{2}-\alpha-\frac{\bar{r}}{2 n(2 n+1)}\right\}[g(Y, Z) \xi-\eta(Z) Y]$.
Using (8.6) and putting $Z=\xi$ in (8.4) and using the equations (2.2), (4.12), we obtain
$\left\{\alpha^{2}-\alpha-\frac{\bar{r}}{2 n(2 n+1)}\right\}\left[\bar{S}(Y, W)-2 n\left(\alpha^{2}-\alpha\right) g(Y, W)\right]=0$.
Therefore,
$\bar{S}(Y, W)=2 n\left(\alpha^{2}-\alpha\right) g(Y, W)$
provided $\bar{r} \neq 2 n(2 n+1)\left(\alpha^{2}-\alpha\right)$.
This means that the manifold is an Einstein manifold with respect to the quarter-symmetric metric connection.
This completes the proof.

## 9. Example

In this section we construct an example on Lorentzian $\alpha$-Sasakian manifold endowed with the quarter-symmetric metric connection. We consider the 3-dimensional manifold $M^{3}=\{(x, y, z): x, y, z \in \mathbb{R}\}$, where $(x, y, z)$ are the standard coordinates in $\mathbb{R}^{3}$. We choose the vector fields
$e_{1}=e^{z} \frac{\partial}{\partial y}, e_{2}=e^{z}\left(\frac{\partial}{\partial x}+\frac{\partial}{\partial y}\right), e_{3}=\alpha \frac{\partial}{\partial z}=\xi$,
which are linearly independent at each point of $M^{3}$.
Let $g$ be a Lorentzian metric defined by
$g\left(e_{1}, e_{1}\right)=1, g\left(e_{2}, e_{2}\right)=1, g\left(e_{3}, e_{3}\right)=-1$,
and $g\left(e_{i}, e_{j}\right)=0$ if $i \neq j$.
Let $\phi$ be the (1,1)-tensor field defined by
$\phi e_{1}=-e_{1}, \phi e_{2}=-e_{2}, \phi e_{3}=0$.
and $\eta$ be a 1 -form defined by $\eta(X)=g\left(X, e_{3}\right)$ for any $X \in \Gamma\left(T M^{3}\right)$
Now using the linearity of $\phi$ and $g$, we obtain
$\phi^{2} X=X+\eta(X) \xi$,
$\eta(\xi)=-1$,
and
$g(\phi X, \phi Y)=g(X, Y)+\eta(X) \eta(Y)$,
for any vector fields $X, Y \in \Gamma\left(T M^{3}\right)$. Thus for $e_{3}=\xi$, the structure $(\phi, \xi, \eta, g)$ defines a Lorentzian para-contact metric structure on $M^{3}$. Now, we have
$\left[e_{1}, e_{2}\right]=0,\left[e_{2}, e_{3}\right]=-\alpha e_{2},\left[e_{1}, e_{3}\right]=-\alpha e_{1}$,
Let $\nabla$ be the Levi-Civita connection of the Lorentzian metric $g$ which is given by Koszul's formula defined by
$2 g\left(\nabla_{X} Y, Z\right)=X g(Y, Z)+Y g(Z, X)-Z g(X, Y)-g(X,[Y, Z])-g(Y,[X, Z])+g(Z,[X, Y])$.

Using Koszul's formula, we obtain the following:
$\nabla_{e_{1}} e_{1}=-\alpha e_{3}, \nabla_{e_{1}} e_{2}=0, \nabla_{e_{1}} e_{3}=-\alpha e_{1}$,
$\nabla_{e_{2}} e_{1}=0, \nabla_{e_{2}} e_{2}=-\alpha e_{3}, \nabla_{e_{2}} e_{3}=-\alpha e_{2}$,

$$
\nabla_{e_{3}} e_{1}=0, \nabla_{e_{3}} e_{2}=0, \nabla_{e_{3}} e_{3}=0
$$

In view of the above results, we see that
$\left(\nabla_{X} \eta\right) Y=\alpha g(\phi X, Y) \xi$,
$\nabla_{X} \xi=\alpha \phi X$,
for all $X, Y \in \Gamma\left(T M^{3}\right)$ and $\xi=e_{3}$. Therefore the manifold is a Lorentzian $\alpha$-Sasakian manifold with the structure $(\phi, \xi, \eta, g)$. It is known that
$R(X, Y) Z=\nabla_{X} \nabla_{Y} Z-\nabla_{Y} \nabla_{X} Z-\nabla_{[X, Y]} Z$
Now using (9.1), we can easily obtain the non-zero components of the curvature tensor $R$ as follows:
$R\left(e_{1}, e_{2}\right) e_{1}=-\alpha^{2} e_{2}, R\left(e_{1}, e_{2}\right) e_{2}=\alpha^{2} e_{1}$,
$R\left(e_{1}, e_{3}\right) e_{1}=-\alpha^{2} e_{3}, R\left(e_{1}, e_{3}\right) e_{3}=-\alpha^{2} e_{1}$
$R\left(e_{2}, e_{3}\right) e_{2}=-\alpha^{2} e_{3}, R\left(e_{2}, e_{3}\right) e_{3}=-\alpha^{2} e_{2}$,
Let $X, Y$ and $Z$ be any three vector fields given by
$X=X^{1} e_{1}+X^{2} e_{2}+X^{3} e_{3}$,
$Y=Y^{1} e_{1}+Y^{2} e_{2}+Y^{3} e_{3}$,
$Z=Z^{1} e_{1}+Z^{2} e_{2}+Z^{3} e_{3}$
where $X^{i}, Y^{i}$ and $Z^{i}$, for all $i=1,2,3$ are all non-zero real numbers. Then
$R(X, Y) Z=R\left(X^{1} e_{1}+X^{2} e_{2}+X^{3} e_{3}, Y^{1} e_{1}+Y^{2} e_{2}+Y^{3} e\right)\left(Z^{1} e_{1}+Z^{2} e_{2}+Z^{3} e_{3}\right)$.
Using equation (9.2) in (9.4), we get
$R(X, Y) Z=\alpha^{2}\{g(Y, Z) X-g(X, Z) Y\}$.

Hence, the 3-dimensional Lorentzian $\alpha$-Sasakian manifold is of constant curvature $\alpha^{2}$. Also from (9.5), we obtain
$S(Y, Z)=2 \alpha^{2} g(Y, Z)$
which gives $S\left(e_{1}, e_{1}\right)=S\left(e_{2}, e_{2}\right)=2 \alpha^{2}, S\left(e_{3}, e_{3}\right)=-2 \alpha^{2}$ and therefore the scalar curvature $r=6 \alpha^{2}$.
Now using (9.1) in (3.7), we obtain the components of quarter-symmetric metric connection $\bar{\nabla}$ as follows:
$\bar{\nabla}_{e_{1}} e_{1}=-(\alpha-1) e_{3}, \bar{\nabla}_{e_{1}} e_{2}=0, \bar{\nabla}_{e_{1}} e_{3}=-(\alpha-1) e_{1}$,
$\bar{\nabla}_{e_{2}} e_{1}=0, \bar{\nabla}_{e_{2}} e_{2}=-(\alpha-1) e_{3}, \bar{\nabla}_{e_{2}} e_{3}=-(\alpha-1) e_{2}$,
$\bar{\nabla}_{e_{3}} e_{1}=0, \quad \bar{\nabla}_{e_{3}} e_{2}=0, \quad \bar{\nabla}_{e_{3}} e_{3}=0$,
Using above results, we can easily obtain the components of curvature tensor $\bar{R}$ with respect to quarter-symmetric metric connection $\bar{\nabla}$ as follows:
$\bar{R}\left(e_{1}, e_{2}\right) e_{1}=-(\alpha-1)^{2} e_{2}, \bar{R}\left(e_{1}, e_{2}\right) e_{2}=(\alpha-1)^{2} e_{1}, \bar{R}\left(e_{1}, e_{2}\right) e_{3}=0$,
$\bar{R}\left(e_{1}, e_{3}\right) e_{1}=-\alpha(\alpha-1) e_{3}, \bar{R}\left(e_{1}, e_{3}\right) e_{2}=0, \bar{R}\left(e_{1}, e_{3}\right) e_{3}=-\alpha(\alpha-1) e_{1}$
$\bar{R}\left(e_{2}, e_{3}\right) e_{1}=0, \bar{R}\left(e_{2}, e_{3}\right) e_{2}=-\alpha(\alpha-1) e_{3}, \bar{R}\left(e_{2}, e_{3}\right) e_{3}=-\alpha(\alpha-1) e_{2}$,
With the help of (9.8), we find the Ricci tensors $\bar{S}$ with respect to the quarter-symmetric metric connection as:
$\bar{S}\left(e_{1}, e_{1}\right)=\bar{S}\left(e_{2}, e_{2}\right)=(2 \alpha-1)(\alpha-1), \bar{S}\left(e_{3}, e_{3}\right)=-2 \alpha(\alpha-1)$.
From above results, it follows that the scalar curvature tensor with respect to the quarter-symmetric metric connection is $\bar{r}=2(3 \alpha-1)(\alpha-1)$.
Using (4.11) and (9.6) in 3-dimensional Lorentzian $\alpha$-Sasakian manifold $M^{3}$, we have
$\bar{S}(Y, Z)=(2 \alpha-1)(\alpha-1) g(Y, Z)-(\alpha-1) \eta(Y) \eta(Z)$.
Thus the three dimensional Lorentzian $\alpha$-Sasakian manifold $M^{3}$ is an $\eta$-Einstein manifold with respect to the quarter-symmetric metric connection $\bar{\nabla}$.
If we take $\alpha=1$ in this example, then 3-dimensional Lorentzian $\alpha$-Sasakian manifold $M^{3}$ becomes flat with respect to the quarter-symmetric metric connection $\bar{\nabla}$.

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