



On μsp -Continuous Maps in Topological Spaces

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Abstract — In this paper, we introduce a new class of continuous maps called μsp -continuous maps and study their properties in topological spaces.

Keywords — Topological space, μsp -closed set, μsp -continuous map, μsp -irresolute map

1. Introduction and Preliminaries

Several authors [1–7] working in the field of general topology have shown more interest in studying the concepts of generalizations of continuous maps. A weak form of continuous maps called g -continuous maps were introduced by Balachandran et al. [8]. As generalizations of closed sets, μsp -closed sets were introduced and studied by the same author [9]. In this paper, we first introduce μsp -continuous maps and study their relations with various generalized continuous maps. We also discuss some properties of μsp -continuous maps. We introduce μsp -irresolute maps in topological spaces and discuss some of their properties. Various properties and characterizations of such maps are discussed by using μsp -closure and μsp -interior under certain conditions. Throughout this paper, (X, τ) , (Y, σ) , and (Z, η) (or X , Y , and Z) represent topological spaces on which no separation axioms are assumed unless otherwise mentioned. For a subset A of a space (X, τ) , $cl(A)$, $int(A)$, and A^C denote the closure of A , the interior of A , and complement of A , respectively.

We recall the following definitions which are useful in the sequel.

Definition 1.1. A subset A of a space (X, τ) is called:

1. α -open set [10] if $A \subseteq int(cl(int(A)))$.
2. semi-open set [11] if $A \subseteq cl(int(A))$.
3. pre-open set [5] if $A \subseteq int(cl(A))$.
4. β -open set [1] (= semi-pre-open set [12]) if $A \subseteq cl(int(cl(A)))$.

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The complements of the above mentioned open sets are called their respective closed sets. The α -closure [10](resp. semi-closure [13], pre-closure [14], semi-pre-closure [12]) of a subset A of X , denoted by $\alpha cl(A)$ (resp. $scl(A)$, $pcl(A)$, $spcl(A)$) is defined to be the intersection of all α -closed (resp. semi-closed, pre-closed, semi-pre-closed) sets of (X, τ) containing A .

Definition 1.2. A subset A of a space (X, τ) is called:

1. a generalized closed (briefly g -closed) set [15] if $cl(A) \subseteq U$ whenever $A \subseteq U$ and U is open in (X, τ) . The complement of g -closed set is called g -open set.
2. a generalized semi-closed (briefly gs -closed) set [16] if $scl(A) \subseteq U$ whenever $A \subseteq U$ and U is open in (X, τ) . The complement of gs -closed set is called gs -open set.
3. an α -generalized closed (briefly αg -closed) set [17] if $\alpha cl(A) \subseteq U$ whenever $A \subseteq U$ and U is open in (X, τ) . The complement of αg -closed set is called αg -open set.
4. a generalized α -closed (briefly $g\alpha$ -closed) set [18] if $\alpha cl(A) \subseteq U$ whenever $A \subseteq U$ and U is α -open in (X, τ) . The complement of $g\alpha$ -closed set is called $g\alpha$ -open set.
5. a $g^\#$ -closed set [19] if $cl(A) \subseteq U$ whenever $A \subseteq U$ and U is αg -open in (X, τ) . The complement of $g^\#$ -closed set is called $g^\#$ -open set.
6. a generalized semi-preclosed (briefly gsp -closed) set [20] if $spcl(A) \subseteq U$ whenever $A \subseteq U$ and U is open in (X, τ) . The complement of gsp -closed set is called gsp -open set.
7. a \hat{g} -closed set [7] (= ω -closed set [6]) if $cl(A) \subseteq U$ whenever $A \subseteq U$ and U is semi-open in (X, τ) . The complement of \hat{g} -closed set is called \hat{g} -open set.
8. a $*g$ -closed set [21] if $cl(A) \subseteq U$ whenever $A \subseteq U$ and U is \hat{g} -open in (X, τ) . The complement of $*g$ -closed set is called $*g$ -open set.
9. a $\#g$ -semi-closed (briefly $\#gs$ -closed) set [22] if $scl(A) \subseteq U$ whenever $A \subseteq U$ and U is $*g$ -open in (X, τ) . The complement of $\#gs$ -closed set is called $\#gs$ -open set.
10. a $g\alpha^*$ -closed set [18, 23] if $\alpha cl(A) \subseteq int(U)$ whenever $A \subseteq U$ and U is α -open in (X, τ) . The complement of $g\alpha^*$ -closed set is called $g\alpha^*$ -open set.
11. a μ -closed set [24] if $cl(A) \subseteq U$ whenever $A \subseteq U$ and U is $g\alpha^*$ -open in (X, τ) . The complement of μ -closed set is called μ -open set.
12. a μp -closed set [25] if $pcl(A) \subseteq U$ whenever $A \subseteq U$ and U is $g\alpha^*$ -open in (X, τ) . The complement of μp -closed set is called μp -open set.
13. a μs -closed set [26] if $scl(A) \subseteq U$ whenever $A \subseteq U$ and U is $g\alpha^*$ -open in (X, τ) . The complement of μs -closed set is called μs -open set.
14. a μsp -closed set [9] if $spcl(A) \subseteq U$ whenever $A \subseteq U$ and U is $g\alpha^*$ -open in (X, τ) . The complement of μsp -closed set is called μsp -open set.

Remark 1.3. The collection of all g -closed (resp. gs -closed, αg -closed, $g\alpha$ -closed, $g^\#$ -closed, gsp -closed, \hat{g} -closed, $*g$ -closed, $\#gs$ -closed, $g\alpha^*$ -closed, μ -closed, μp -closed, μs -closed, μsp -closed) sets is denoted by $gc(\tau)$ (resp. $gsc(\tau)$, $\alpha gc(\tau)$, $g\alpha c(\tau)$, $g^\# c(\tau)$, $gspc(\tau)$, $\hat{g}c(\tau)$, $*gc(\tau)$, $\#gsc(\tau)$, $g\alpha^*c(\tau)$, $\mu c(\tau)$, $\mu pc(\tau)$, $\mu sc(\tau)$, $\mu spc(\tau)$).

We denote the power set of X by $P(X)$.

Definition 1.4. A map $f : (X, \tau) \rightarrow (Y, \sigma)$ is called:

1. α -continuous [27] if $f^{-1}(V)$ is a α -closed set of (X, τ) for every closed set V of (Y, σ) .
2. semi-continuous [11] if $f^{-1}(V)$ is a semi-closed set of (X, τ) for every closed set V of (Y, σ) .
3. pre-continuous [5] if $f^{-1}(V)$ is a pre-closed set of (X, τ) for every closed set V of (Y, σ) .

4. β -continuous [1] if $f^{-1}(V)$ is a β -closed set of (X, τ) for every closed set V of (Y, σ) .
5. g -continuous [8] if $f^{-1}(V)$ is a g -closed set of (X, τ) for every closed set V of (Y, σ) .
6. gs -continuous [2] if $f^{-1}(V)$ is a gs -closed set of (X, τ) for every closed set V of (Y, σ) .
7. αg -continuous [28] if $f^{-1}(V)$ is a αg -closed set of (X, τ) for every closed set V of (Y, σ) .
8. $g\alpha$ -continuous [28] if $f^{-1}(V)$ is a $g\alpha$ -closed set of (X, τ) for every closed set V of (Y, σ) .
9. $g^\#$ -continuous [19] if $f^{-1}(V)$ is a $g^\#$ -closed set of (X, τ) for every closed set V of (Y, σ) .
10. gsp -continuous [20] if $f^{-1}(V)$ is a gsp -closed set of (X, τ) for every closed set V of (Y, σ) .
11. \hat{g} -continuous [7] if $f^{-1}(V)$ is a \hat{g} -closed set of (X, τ) for every closed set V of (Y, σ) .
12. $*g$ -continuous [21] if $f^{-1}(V)$ is a $*g$ -closed set of (X, τ) for every closed set V of (Y, σ) .
13. $\#g$ -semi-continuous [22] if $f^{-1}(V)$ is a $\#g$ -semi-closed set of (X, τ) for every closed set V of (Y, σ) .
14. μ -continuous [24] if $f^{-1}(V)$ is a μ -closed set of (X, τ) for every closed set V of (Y, σ) .
15. μp -continuous [25] if $f^{-1}(V)$ is a μp -closed set of (X, τ) for every closed set V of (Y, σ) .
16. μs -continuous [26] if $f^{-1}(V)$ is a μs -closed set of (X, τ) for every closed set V of (Y, σ) .

Definition 1.5. [9] For a space (X, τ) , the following hold:

1. $T_{\mu sp}$ -space if every μsp -closed set is closed.
2. $\mu T_{\mu sp}$ -space if every μsp -closed set is μ -closed.
3. $pT_{\mu sp}$ -space if every μsp -closed set is pre-closed.
4. $spT_{\mu sp}$ -space if every μsp -closed set is semi-preclosed.
5. $\alpha T_{\mu sp}$ -space if every μsp -closed set is α -closed.
6. $g\alpha T_{\mu sp}$ -space if every μsp -closed set is $g\alpha$ -closed.

Result 1.6. 1. Every closed set (resp. pre-closed set, α -closed set, semi-closed set, β -closed set) is μsp -closed but not conversely [9].

2. Every μ -closed set (resp. μp -closed set, μs -closed set) is μsp -closed but not conversely [9].
3. Every $g\alpha$ -closed set (resp. $g^\#$ -closed set, \hat{g} -closed set) is μsp -closed but not conversely [9].
4. Every open set is μsp -open set but not conversely.

2. μsp -Continuous Maps and Irresolute Maps

We introduce the following definition.

Definition 2.1. A map $f : (X, \tau) \rightarrow (Y, \sigma)$ is called μsp -continuous if $f^{-1}(V)$ is a μsp -closed set of (X, τ) for every closed set V of (Y, σ) .

Proposition 2.2. Every continuous (resp. prec-continuous, α -continuous, semi-continuous, β -continuous) is μsp -continuous but not conversely.

PROOF. The proof follows from Result 1.6 (1).

Example 2.3. Let $X = Y = \{a, b, c\}$, $\tau = \{\phi, \{a\}, \{a, c\}, X\}$, and $\sigma = \{\phi, \{b\}, X\}$. Then, $\mu spc(\tau) = \{\phi, \{b\}, \{c\}, \{a, c\}, \{b, c\}, X\}$ and $pc(\tau) = \alpha c(\tau) = sc(\tau) = spc(\tau) = \{\phi, \{b\}, \{c\}, \{b, c\}, X\}$. Define $f : (X, \tau) \rightarrow (Y, \sigma)$ be the identity map. Then, f is μsp -continuous but not continuous (resp. prec-continuous, α -continuous, semi-continuous, semi-precontinuous), since $f^{-1}(\{a, c\}) = \{a, c\}$ is not closed (resp. preclosed, α -closed, semi-closed, semi-preclosed).

Proposition 2.4. Every μ -continuous (resp. μp -continuous, μs -continuous) is μsp -continuous but not conversely.

PROOF. The proof follows from Result 1.6 (2).

Example 2.5. Let $X = Y = \{a, b, c\}$, $\tau = \{\phi, \{a\}, \{b\}, \{a, b\}, X\}$, and $\sigma = \{\phi, \{a, c\}, X\}$. Then, $\mu spc(\tau) = \{\phi, \{a\}, \{b\}, \{c\}, \{a, c\}, \{b, c\}, X\}$ and $\mu c(\tau) = \mu pc(\tau) = \{\phi, \{c\}, \{a, c\}, \{b, c\}, X\}$. Define $f : (X, \tau) \rightarrow (Y, \sigma)$ be the identity map. Then, f is μsp -continuous but not μ -continuous (resp. μp -continuous), since $f^{-1}(\{b\}) = \{b\}$ is not μ -closed (resp. μp -closed).

Example 2.6. Let $X = Y = \{a, b, c\}$, $\tau = \{\phi, \{a\}, \{b, c\}, X\}$, and $\sigma = \{\phi, \{b\}, X\}$. Then, $\mu spc(\tau) = P(X)$ and $\mu sc(\tau) = \{\phi, \{a\}, \{b, c\}, X\}$. Define $f : (X, \tau) \rightarrow (Y, \sigma)$ be the identity map. Then, f is μsp -continuous but not μs -continuous, since $f^{-1}(\{a, c\}) = \{a, c\}$ is not μs -closed.

Proposition 2.7. Every $g\alpha$ -continuous (resp. $g^\#$ -continuous, \hat{g} -continuous) is μsp -continuous but not conversely.

PROOF. The proof follows from Result 1.6 (3).

Example 2.8. Let X, Y, τ, σ , and f be as in the Example 2.5. Then, $g\alpha c(\tau) = g^\# c(\tau) = \hat{g} c(\tau) = \{\phi, \{c\}, \{a, c\}, \{b, c\}, X\}$. Then, f is μsp -continuous but not $g\alpha$ -continuous (resp. $g^\#$ -continuous, \hat{g} -continuous), since $f^{-1}(\{b\}) = \{b\}$ is not $g\alpha$ -closed (resp. $g^\#$ -closed, \hat{g} -closed).

Theorem 2.9. μsp -continuity is independent of g -continuity, αg -continuity, gs -continuity, gsp -continuity, $*g$ -continuity, and $\#gs$ -continuity.

PROOF. It follows from the following Example.

Example 2.10.

1. Let $X = Y = \{a, b, c\}$, $\tau = \{\phi, \{a\}, \{a, b\}, X\}$, and $\sigma = \{\phi, \{c\}, Y\}$. Then, $\mu spc(\tau) = \{\phi, \{b\}, \{c\}, \{a, b\}, \{b, c\}, X\}$, $gc(\tau) = *gc(\tau) = \{\phi, \{c\}, \{a, c\}, \{b, c\}, X\}$, and $\alpha gc(\tau) = gsc(\tau) = gspc(\tau) = \#gsc(\tau) = \{\phi, \{b\}, \{c\}, \{a, c\}, \{b, c\}, X\}$. Define $f : (X, \tau) \rightarrow (Y, \sigma)$ be the identity map. Then, f is μsp -continuous but not g -continuous (resp. αg -continuous, gs -continuous, gsp -continuous, $*g$ -continuous, and $\#gs$ -continuous), since $f^{-1}(\{a, b\}) = \{a, b\}$ is not g -closed (resp. αg -closed, gs -closed, gsp -closed, $*g$ -closed, and $\#gs$ -closed).
2. Let X and τ be defined as an Example 2.10 (1). Let $Y = \{a, b, c\}$ and $\sigma = \{\phi, \{b\}, \{a, b\}, Y\}$. Define $f : (X, \tau) \rightarrow (Y, \sigma)$ be the identity map. Then, f is g -continuous (resp. αg -continuous, gs -continuous, gsp -continuous, $*g$ -continuous and $\#gs$ -continuous) but not μsp -continuous, since $f^{-1}(\{a, c\}) = \{a, c\}$ is not μsp -closed.

Remark 2.11. The composition of two μsp -continuous maps need not be μsp -continuous and this is shown from the following example.

Example 2.12. Let X and τ be as in Example 2.3. Let $Y = Z = \{a, b, c\}$, $\sigma = \{\phi, \{a\}, Y\}$, and $\eta = \{\phi, \{a, b\}, Z\}$. Define $f : (X, \tau) \rightarrow (Y, \sigma)$ by $f(a) = b$, $f(b) = a$, and $f(c) = c$. Define $g : (Y, \sigma) \rightarrow (Z, \eta)$ by $g(a) = b$, $g(b) = c$, and $g(c) = a$. Clearly, f and g are μsp -continuous but their $g \circ f : (X, \tau) \rightarrow (Z, \eta)$ is not μsp -continuous, because $V = \{c\}$ is closed in (Z, η) but $(g \circ f^{-1}(\{c\})) = f^{-1}(g^{-1}(\{c\})) = f^{-1}(\{b\}) = \{a\}$, which is not μsp -closed in (X, τ) .

Theorem 2.13. If $f : (X, \tau) \rightarrow (Y, \sigma)$ is μsp -continuous and $g : (Y, \sigma) \rightarrow (Z, \eta)$ is continuous, then $g \circ f : (X, \tau) \rightarrow (Z, \eta)$ is μsp -continuous.

PROOF. Clearly follows from definitions.

Proposition 2.14. A map $f : (X, \tau) \rightarrow (Y, \sigma)$ is μsp -continuous if and only if $f^{-1}(U)$ is μsp -open in (X, τ) for every open set U in (Y, σ) .

PROOF. Let $f : (X, \tau) \rightarrow (Y, \sigma)$ be μsp -continuous and U be an open set in (Y, σ) . Then, U^c is closed in (Y, σ) and since f is μsp -continuous, $f^{-1}(U^c)$ is μsp -closed in (X, τ) . But $f^{-1}(U^c) = f^{-1}((U)^c)$ and so $f^{-1}(U)$ is μsp -open in (X, τ) .

Conversely, assume that $f^{-1}(U)$ is μsp -open in (X, τ) for each open set U in (Y, σ) . Let F be a closed set in (Y, σ) . Then, F^c is open in (Y, σ) and by assumption, $f^{-1}(F^c)$ is μsp -open in (X, τ) . Since $f^{-1}(F^c) = f^{-1}((F)^c)$, we have $f^{-1}(F)$ is closed in (X, τ) and so f is μsp -continuous.

We introduce the following definition

Definition 2.15. A map $f : (X, \tau) \rightarrow (Y, \sigma)$ is called μsp -irresolute if $f^{-1}(V)$ is a μsp -closed set of (X, τ) for every μsp -closed set V of (Y, σ) .

Theorem 2.16. Every μsp -irresolute map is μsp -continuous but not conversely.

PROOF. Let $f : (X, \tau) \rightarrow (Y, \sigma)$ be a μsp -irresolute map. Let V be a closed set of (Y, σ) . Then, by the Result 1.6 (1), V is μsp -closed. Since f is μsp -irresolute, then $f^{-1}(V)$ is a μsp -closed set of (X, τ) . Therefore, f is μsp -continuous.

Example 2.17. Let X, Y, τ, σ , and f be as in the Example 2.12. $\{b\}$ is μsp -closed set of (Y, σ) but $f^{-1}(\{b\}) = \{a\}$ is not a μsp -closed set of (X, τ) . Thus, f is not μsp -irresolute map. However, f is μsp -continuous map.

Theorem 2.18. Let $f : (X, \tau) \rightarrow (Y, \sigma)$ and $g : (Y, \sigma) \rightarrow (Z, \eta)$ be any two maps. Then,

1. $g \circ f$ is μsp -continuous if g is continuous and f is μsp -continuous.
2. $g \circ f$ is μsp -irresolute if both f and g are μsp -irresolute.
3. $g \circ f$ is μsp -continuous if g is μsp -continuous and f is μsp -irresolute.

PROOF. Omitted.

Theorem 2.19. Let $f : (X, \tau) \rightarrow (Y, \sigma)$ be an μsp -continuous map. If (X, τ) , the domain of f is an $T_{\mu sp}$ -space, then f is continuous.

PROOF. Let V be a closed set of (Y, σ) . Then, $f^{-1}(V)$ is a μsp -closed set of (X, τ) , since f is μsp -continuous. Since (X, τ) is an $T_{\mu sp}$ -space, then $f^{-1}(V)$ is a closed set of (X, τ) . Therefore, f is continuous.

Theorem 2.20. Let $f : (X, \tau) \rightarrow (Y, \sigma)$ be a μsp -continuous map. If (X, τ) , the domain of f is an $\alpha T_{\mu sp}$ -space, then f is α -continuous.

PROOF. Let V be a closed set of (Y, σ) . Then, $f^{-1}(V)$ is a μsp -closed set of (X, τ) , since f is μsp -continuous. Since (X, τ) is an $\alpha T_{\mu sp}$ -space, then $f^{-1}(V)$ is a α -closed set of (X, τ) . Therefore, f is α -continuous.

Theorem 2.21. Let $f : (X, \tau) \rightarrow (Y, \sigma)$ be a μsp -continuous map. If (X, τ) , the domain of f is an $pT_{\mu sp}$ -space, then f is pre-continuous.

PROOF. Let V be a closed set of (Y, σ) . Then, $f^{-1}(V)$ is a μsp -closed set of (X, τ) , since f is μsp -continuous. Since (X, τ) is an $pT_{\mu sp}$ -space, then $f^{-1}(V)$ is a pre-closed set of (X, τ) . Therefore, f is pre-continuous.

Theorem 2.22. Let $f : (X, \tau) \rightarrow (Y, \sigma)$ be a μsp -continuous map. If (X, τ) , the domain of f is an $\mu T_{\mu sp}$ -space, then f is μ -continuous.

PROOF. Let V be a closed set of (Y, σ) . Then, $f^{-1}(V)$ is a μsp -closed set of (X, τ) , since f is μsp -continuous. Since (X, τ) is an $\mu T_{\mu sp}$ -space, then $f^{-1}(V)$ is a μ -closed set of (X, τ) . Therefore, f is μ -continuous.

Theorem 2.23. Let $f : (X, \tau) \rightarrow (Y, \sigma)$ be a μsp -continuous map. If (X, τ) , the domain of f is an $\mu pT_{\mu sp}$ -space, then f is μp -continuous.

PROOF. Let V be a closed set of (Y, σ) . Then, $f^{-1}(V)$ is a μsp -closed set of (X, τ) , since f is μsp -continuous. Since (X, τ) is an $\mu pT_{\mu sp}$ -space, then $f^{-1}(V)$ is a μp -closed set of (X, τ) . Therefore, f is μp -continuous.

Theorem 2.24. Let $f : (X, \tau) \rightarrow (Y, \sigma)$ be a μsp -continuous map. If (X, τ) , the domain of f is an $spT_{\mu sp}$ -space, then f is β -continuous.

PROOF. Let V be a closed set of (Y, σ) . Then $f^{-1}(V)$ is a μsp -closed set of (X, τ) , since f is μsp -continuous. Since (X, τ) is an $spT_{\mu sp}$ -space, then $f^{-1}(V)$ is a β -closed set of (X, τ) . Therefore, f is β -continuous.

Theorem 2.25. Let $f : (X, \tau) \rightarrow (Y, \sigma)$ be a μsp -continuous map. If (X, τ) , the domain of f is an $g\alpha T_{\mu sp}$ -space, then f is $g\alpha$ -continuous.

PROOF. Let V be a closed set of (Y, σ) . Then, $f^{-1}(V)$ is a μsp -closed set of (X, τ) , since f is μsp -continuous. Since (X, τ) is an $g\alpha T_{\mu sp}$ -space, then $f^{-1}(V)$ is a $g\alpha$ -closed set of (X, τ) . Therefore, f is $g\alpha$ -continuous.

3. Characterization of μsp -Continuous Maps

In this section we introduce μsp -interior and μsp -closure of a set and obtain the characterization theorem for μsp -continuous maps under certain conditions.

Definition 3.1. For any $A \subseteq X$, $\mu sp\text{-int}(A)$ is defined as the union of all μsp -open sets contained in A , i.e., $\mu sp\text{-int}(A) = \cup\{G : G \subseteq A \text{ and } G \text{ is } \mu sp\text{-open}\}$.

Lemma 3.2. For any $A \subseteq X$, $\text{int}(A) \subseteq \mu sp\text{-int}(A) \subseteq A$.

PROOF. The proof follows from Result 1.6 (4).

The following two Propositions are easy consequences from definitions.

Proposition 3.3. For any $A \subseteq X$, the following holds.

1. $\mu sp\text{-int}(A)$ is the largest μsp -open set contained in A .
2. A is μsp -open if and only if $\mu sp\text{-int}(A) = A$.

Proposition 3.4. For any subsets A and B of (X, τ) , the following holds.

1. $\mu sp\text{-int}(A \cap B) = \mu sp\text{-int}(A) \cap \mu sp\text{-int}(B)$.
2. $\mu sp\text{-int}(A \cup B) \supseteq \mu sp\text{-int}(A) \cup \mu sp\text{-int}(B)$.
3. If $A \subseteq B$, then $\mu sp\text{-int}(A) \subseteq \mu sp\text{-int}(B)$.
4. $\mu sp\text{-int}(X) = X$ and $\mu sp\text{-int}(\phi) = \phi$.

Definition 3.5. For every set $A \subseteq X$, we define the μsp -closure of A to be the intersection of all μsp -closed sets containing A , i.e., $\mu sp\text{-cl}(A) = \cap\{F : A \subseteq F \in \mu spc(\tau)\}$.

Lemma 3.6. For any $A \subseteq X$, $A \subseteq \mu sp\text{-cl}(A) \subseteq cl(A)$.

PROOF. The proof follows from Result 1.6 (1).

Remark 3.7. Both containment relations in Lemma 3.6 may be proper as seen from the following example.

Example 3.8. Let $X = \{a, b, c\}$, $\tau = \{\phi, \{a\}, \{a, b\}, X\}$. Here $\mu spc(\tau) = \{\phi, \{b\}, \{c\}, \{a, b\}, \{b, c\}, X\}$. Let $A = \{a\}$. Then, $\mu sp\text{-cl}(\{a\}) = \{a, b\}$ and so $A \subseteq \mu sp\text{-cl}(A) \subseteq cl(A)$.

The following two Propositions are easy consequences from definitions.

Proposition 3.9. For any $A \subseteq X$, the following holds.

1. $\mu sp\text{-cl}(A)$ is the smallest μsp -closed set containing A .

2. A is μsp -closed if and only if $\mu sp-cl(A) = A$.

Proposition 3.10. For any two subsets A and B of (X, τ) , the following holds.

1. If $A \subseteq B$, then $\mu sp-cl(A) \subseteq \mu sp-cl(B)$.
2. $\mu sp-cl(A \cap B) \subseteq \mu sp-cl(A) \cap \mu sp-cl(B)$.

Proposition 3.11. Let A be a subset of a space X , then the following are true.

1. $(\mu sp-int(A))^c = \mu sp-cl(A^c)$.
2. $\mu sp-int(A) = (\mu sp-cl(A^c))^c$.
3. $\mu sp-cl(A) = (\mu sp-int(A^c))^c$.

PROOF. 1. Clearly follows from definitions.

2. Follows by taking complements in (1).

3. Follows by replacing A by A^c in (1).

Definition 3.12. Let (X, τ) be a topological space. Let x be a point of X and G be a subset of X . Then, G is called an μsp -neighbourhood of x (briefly, μsp -nbhd of x) in X if there exists an μsp -open set U of X such that $x \in U \subseteq G$.

Proposition 3.13. Let A be a subset of (X, τ) . Then, $x \in \mu sp-cl(A)$ if and only if for any μsp -nbhd G_x of x in (X, τ) , $A \cap G_x \neq \phi$.

PROOF. Necessity. Assume $x \in \mu sp-cl(A)$. Suppose that there is an μsp -nbhd G of the point x in (X, τ) such that $G \cap A = \phi$. Since G is μsp -nbhd of x in (X, τ) , by Definition 3.12, there exists an μsp -open set U_x such that $x \in U_x \subseteq G$. Therefore, we have $U_x \cap A = \phi$ and so $A \subseteq (U_x)^c$. Since $(U_x)^c$ is an μsp -closed set containing A , we have by Definition 3.5, $\mu sp-cl(A) \subseteq (U_x)^c$ and therefore $x \notin \mu sp-cl(A)$, which is a contradiction. Sufficiency. Assume for each μsp -nbhd G_x of x in (X, τ) , $A \cap G_x \neq \phi$. Suppose that $x \notin \mu sp-cl(A)$. Then, by Definition 3.5, there exists an μsp -closed set F of (X, τ) such that $A \subseteq F$ and $x \notin F$. Thus, $x \in F^c$ and F^c is μsp -open in (X, τ) and hence F^c is a μsp -nbhd of x in (X, τ) . But $A \cap F^c = \phi$, which is a contradiction.

In the next theorem we explore certain characterizations of μsp -continuous functions.

Theorem 3.14. Let $f : (X, \tau) \rightarrow (Y, \sigma)$ be a map from a topological space (X, τ) into a topological space (Y, σ) . Then the following statements are equivalent.

1. The function f is μsp -continuous.
2. The inverse of each open set is μsp -open.
3. For each point x in (X, τ) and each open set V in (Y, σ) with $f(x) \in V$, there is an μsp -open set U in (X, τ) such that $x \in U$, $f(U) \subseteq V$.
4. The inverse of each closed set is μsp -closed.
5. For each x in (X, τ) , the inverse of every neighbourhood of $f(x)$ is an μsp -nbhd of x .
6. For each x in (X, τ) and each neighbourhood N of $f(x)$, there is an μsp -nbhd G of x such that $f(G) \subseteq N$.
7. For each subset A of (X, τ) , $f(\mu sp-cl(A)) \subseteq cl(f(A))$.
8. For each subset B of (Y, σ) , $\mu sp-cl(f^{-1}(B)) \subseteq f^{-1}(cl(B))$.

PROOF. (1) \Leftrightarrow (2). This follows from Proposition 2.14.

(1) \Leftrightarrow (3). Suppose that (3) holds and let V be an open set in (Y, σ) and let $x \in f^{-1}(V)$. Then, $f(x) \in V$ and thus there exists an μsp -open set U_x such that $x \in U_x$ and $f(U_x) \subseteq V$. Now, $x \in U_x \subseteq f^{-1}(V)$ and $f^{-1}(V) = \cup_{x \in f^{-1}(V)} U_x$. By assumption, $f^{-1}(V)$ is μsp -open in (X, τ) and therefore f is μsp -continuous.

Conversely, Suppose that (1) holds and let $f(x) \in V$. Then, $x \in f^{-1}(V) \in \mu sp(\tau)$, since f is μsp -continuous. Let $U = f^{-1}(V)$. Then, $x \in U$ and $f(U) \subseteq V$.

(2) \Leftrightarrow (4). This result follows from the fact if A is a subset of (Y, σ) , then $f^{-1}(A^c) = (f^{-1}(A))^c$.

(2) \Leftrightarrow (5). For x in (X, τ) , let N be a neighbourhood of $f(x)$. Then, there exists an open set U in (Y, σ) such that $f(x) \in U \subseteq N$. Consequently, $f^{-1}(U)$ is an μsp -open set in (X, τ) and $x \in f^{-1}(U) \subseteq f^{-1}(N)$. Thus, $f^{-1}(N)$ is an μsp -nbhd of x .

(5) \Leftrightarrow (6). Let $x \in X$ and let N be a neighbourhood of $f(x)$. Then, by assumption, $G = f^{-1}(N)$ is an μsp -nbhd of x and $f(G) = f(f^{-1}(N)) \subseteq N$.

(6) \Leftrightarrow (3). For x in (X, τ) , let V be an open set containing $f(x)$. Then, V is a neighborhood of $f(x)$. So by assumption, there exists an μsp -nbhd G of x such that $f(G) \subseteq V$. Hence, there exists an μsp -open set U in (X, τ) such that $x \in U \subseteq G$ and so $f(U) \subseteq f(G) \subseteq V$.

(7) \Leftrightarrow (4). Suppose that (4) holds and let A be a subset of (X, τ) . Since $A \subseteq f^{-1}(A)$, we have $A \subseteq f^{-1}(cl(f(A)))$. Since $cl(f(A))$ is a closed set in (Y, σ) , by assumption $f^{-1}(cl(f(A)))$ is an μsp -closed set containing A . Consequently, $\mu sp-cl(A) \subseteq f^{-1}(cl(f(A)))$. Thus, $f(\mu sp-cl(A)) \subseteq f(f^{-1}(cl(f(A)))) \subseteq cl(f(A))$.

Conversely, suppose that (7) holds for any subset A of (X, τ) . Let F be a closed subset of (Y, σ) . Then, by assumption, $f(\mu sp-cl(f^{-1}(F))) \subseteq cl(f(f^{-1}(F))) \subseteq cl(F) = F$, i.e., $\mu sp-cl(f^{-1}(F)) \subseteq f^{-1}(F)$ and so $f^{-1}(F)$ is μsp -closed.

(7) \Leftrightarrow (8). Suppose that (7) holds and B be any subset of (Y, σ) . Then, replacing A by $f^{-1}(B)$ in (7), we obtain $f(\mu sp-cl(f^{-1}(B))) \subseteq cl(f(f^{-1}(B))) \subseteq cl(B)$, i.e., $\mu sp-cl(f^{-1}(B)) \subseteq f^{-1}cl(B)$.

Conversely, suppose that (8) holds. Let $B = f(A)$ where A is a subset of (X, τ) . Then, we have, $\mu sp-cl(A) \subseteq \mu sp-cl(f^{-1}(B)) \subseteq f^{-1}(cl(f(A)))$ and so $f(\mu sp-cl(A)) \subseteq cl(f(A))$.

This completes the proof of the theorem.

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