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**An Integral Formula And Inverse Fundamental Forms On
Hypersurfaces In Riemannian Manifolds**

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An Integral Formula And Inverse Fundamental Forms On Hypersurfaces In Riemannian Manifolds

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ABSTRACT

In this study, the coefficients of the p-fundamental forms of a hypersurface N imbedded in n-dimensional Riemannian space M were expressed in terms of the coefficients of first and second fundamental forms. Then, by means of Cayley-Hamilton theorem, the inverse S^{-1} of the shape operator S on the hypersurface N was written as the combinations of the powers of S and the curvatures K_1, \dots, K_{n-1} . Thus the new fundamental forms and some properties of them called the inverse fundamental forms, were defined and investigated. As a result of an application of the generalized divergence theorem of Gauss to the divergence relations of certain tensor fields over the region R of N that can be expressed in terms of polynomials involving the new defined curvatures of M an integral formula was obtained.

I. INTRODUCTION

Let N be a hypersurface imbedded in an n-dimensional Riemannian space M and S be the shape operator defined on N. The metric tensor g_{ij} of M is assumed to be of class C^3 , it induces a metric on N defined by

$$g_{\alpha\beta} = \sum_{i,j=1}^n g_{ij} \frac{\partial x^i}{\partial u^\alpha} \frac{\partial x^j}{\partial u^\beta} \quad (1.1)$$

Where it is supposed that M refers to local coordinates x^i and that the hypersurface N is represented parametrically by the equations

$$x^i = x^i(u^\alpha), \quad i = 1, \dots, n; \quad \alpha = 1, \dots, n-1 \quad (1.2)$$

in which the variables u^α denote the parameters of N, the functions x^i are assumed to be of class C^2 in all their arguments and it is supposed that

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$$\text{rank} \begin{bmatrix} \frac{\partial x^1}{\partial u^1} & \cdots & \frac{\partial x^1}{\partial u^{n-1}} \\ \cdot & & \cdot \\ \cdot & & \cdot \\ \frac{\partial x^n}{\partial u^1} & \cdots & \frac{\partial x^n}{\partial u^{n-1}} \end{bmatrix} = n - 1 \quad (1.3)$$

That is $\det S \neq 0$. We will denote $\frac{\partial x^i}{\partial u^\alpha}$ by X^i_α .

Mixed covariant derivatives of M will be denoted by a pair of vertical bars. Γ^h_{pq} and $\Gamma^\lambda_{\alpha\beta}$ denote the Christoffel symbols of M and induced metric tensor, respectively. Mixed covariant derivative of X^h_α with respect to u^β had been given by H. Rund [2] as

$$X^h_{\alpha||\beta} = \frac{\partial X^h_\alpha}{\partial u^\beta} - \sum_{\lambda=1}^{n-1} \Gamma^\lambda_{\alpha\beta} X^h_\lambda + \sum_{p,q=1}^n \Gamma^h_{pq} X^p_\alpha X_\beta^q \quad (1.4).$$

And furthermore, it is known that [2]

$$X^j_{\alpha||\beta} = \Omega_{\alpha\beta} \xi^j, \quad j = 1, \dots, n. \quad (1.5)$$

where the $\Omega_{\alpha\beta}$ are the coefficients of the usual second fundamental form and $\xi^j, j = 1, \dots, n$, define the unique unit normal vector field to N . If we differentiate the expressions

$$\sum_{i,j=1}^n g_{ij} \xi^i \xi^j = 1 \quad \text{and} \quad \sum_{i,j=1}^n g_{ij} X^i_\alpha \xi^j = 0$$

with respect to u^β and by using the equation (1.5) [4], we obtain

$$\Omega^\varepsilon_\beta = \sum_{\alpha=1}^{n-1} g^{\varepsilon\alpha} \Omega_{\alpha\beta} \quad (1.6)$$

and

$$\xi^j_{||\beta} = - \sum_{\varepsilon=1}^{n-1} \Omega^\varepsilon_\beta X^\varepsilon_j \quad (1.7)$$

Now, let $I^{(p)}_{\alpha\beta}$ denote the coefficients of the p^{th} - fundamental form, then we know that [3],

$$I^{(p)}_{\alpha\beta} = \sum_{\lambda=1}^{n-1} I^{(p-1)}_{\alpha\lambda} \Omega_{\beta}^{\lambda}, \quad 2 \leq p \leq n, \quad (1.8).$$

If we write this expression $(p-1)$ times for $2 \leq p \leq n$ and substitute the coefficients of each fundamental form in those which come later, then we have

$$I^{(p)}_{\alpha\beta} = \sum_{\lambda_1, \dots, \lambda_{p-2}=1}^{n-1} \Omega_{\alpha\lambda_{p-2}}^{\lambda_{p-2}} \Omega_{\lambda_{p-3}}^{\lambda_{p-2}} \Omega_{\lambda_{p-4}}^{\lambda_{p-3}} \dots \Omega_{\lambda_2}^{\lambda_3} \Omega_{\lambda_1}^{\lambda_2} \Omega_{\beta}^{\lambda_1} \quad (1.9)$$

or using Eq (1.6)

$$I^{(p)}_{\alpha\beta} = \sum_{\substack{\lambda_1, \dots, \lambda_{p-2}=1 \\ \alpha_1, \dots, \alpha_{p-2}=1}}^{n-1} g^{\lambda_1\alpha_1} g^{\lambda_2\alpha_2} \dots g^{\lambda_{p-2}\alpha_{p-2}} \Omega_{\alpha_1\beta} \Omega_{\alpha_2\lambda_1} \Omega_{\alpha_3\lambda_2} \dots \Omega_{\alpha_{p-2}\lambda_{p-2}} \quad (1.10)$$

Thus, we have obtained the coefficients of p^{th} - fundamental form in terms of the coefficients of the first and second fundamental forms.

II. INVERSE FUNDAMENTAL FORMS

We will denote the roots of the characteristic equation of S by $\lambda_1, \dots, \lambda_{n-1}$. In addition p^{th} curvature K_p of N is defined to be the p^{th} elementary symmetric functions of $\lambda_1, \dots, \lambda_{n-1}$ by

$$K_p = \sum_{v_1 \leq \dots \leq v_p} \lambda_{v_1} \dots \lambda_{v_p} \quad (11.1).$$

By means of Cayley-Hamilton theorem and the characteristic polynomial of S , we may write

$$(-1)^{n-1} S^{n-1} + \sum_{p=1}^{n-1} (-1)^{n-p-1} K_p S^{n-p-1} = 0 \quad (11.2)$$

or

$$S[S^{n-2} + (-1)^1 K_1 S^{n-3} + (-1)^2 K_2 S^{n-4} + \dots + (-1)^{n-2} K_{n-2} I_{n-1} + (-1)^{n-1} K_{n-1} S^{-1}] = 0. \quad (11.3)$$

where I_{n-1} is the identity matrix having the order $(n-1)$ and S^{-1} is the inverse of S with respect to matrix multiplication. Hence we have

$$S^{-1} = \frac{1}{K_{n-1}} [(-1)^n S^{n-2} + (-1)^{n-1} K_1 S^{n-3} + \dots + (-1)^2 K_{n-2} I_{n-1}] \quad (11.4)$$

since it is supposed that $\det S \neq 0$. This expression have been telling us that the inverse of a regular linear map S is expressed by means of the curvatures K_1, \dots, K_{n-1} and the powers of S . Furthermore, S^{-1} is a symmetric, regular and linear map. Thus, we may define new forms, so-called inverse fundamental forms by using S^{-1} in place of S .

Let $I_{(p)}$ denote the p^{th} inverse fundamental form, particularly we can take $I^{(1)} = I_{(1)}$.

We have similarly, from (11.4)

$$(S^{-1})^2 = \frac{1}{K_{n-1}} [(-1)^n S^{n-3} + (-1)^{n-1} K_1 S^{n-4} + \dots + (-1)^3 K_{n-3} I_{n-1} + (-1)^2 K_{n-2} S^{-1}]. \quad (11.5)$$

Finally, if we denote $(S^{-1})^{n-1} = S^{-(n-1)}$, we obtain

$$S^{-(n-1)} = \frac{1}{K_{n-1}} \left[\sum_{p=1}^{n-1} (-1)^{n-p+1} K_{p-1} S^{-(p-1)} \right]. \quad (11.6)$$

Because of the definition of the fundamental forms, we have a linear relation as

$$\sum_{p=1}^n (-1)^{n-p+1} K_{p-1} I_{(p)} = 0, \quad (11.7)$$

where it is assumed that $K_0 = 1$.

Let v_1, \dots, v_{n-1} be this basis vectors of the characteristic spaces corresponding to characteristic values $\lambda_1, \dots, \lambda_{n-1}$, then, we have

$$S(v_\alpha) = \lambda_\alpha v_\alpha, \quad \alpha = 1, \dots, n-1. \quad (11.8)$$

or

$$S^{-1}(\lambda_\alpha v_\alpha) = v_\alpha, \quad \alpha = 1, \dots, n-1.$$

For S^{-1} is a linear map, we have

$$S^{-1}(v_\alpha) = \frac{1}{\lambda_\alpha} v_\alpha, \alpha = 1, \dots, n-1. \tag{11.9}$$

Therefore $\frac{1}{\lambda_\alpha}$ scalars are the characteristic values of S^{-1} and the basis vectors of the characteristic subspaces corresponding them are the same vectors Y_1, \dots, Y_{n-1} . The matrix of S^{-1} with respect to this basis is

$$S^{-1} = \begin{bmatrix} \frac{1}{\lambda_1} & 0 & \dots & 0 \\ 0 & \frac{1}{\lambda_2} & \dots & 0 \\ \cdot & \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot & \cdot \\ 0 & 0 & \dots & \frac{1}{\lambda_{n-1}} \end{bmatrix}. \tag{11.10}$$

Thus, we can define the new curvatures under the auspices of S^{-1} as

$$IK_p = \sum_{v_1 \leq \dots \leq v_p} \frac{1}{\lambda_{v_1}} \dots \frac{1}{\lambda_{v_p}}, p = 1, \dots, n-1. \tag{11.11}$$

Consequently there exists a relation between K_p and IK_p represented by

$$IK_p = (K_{n-1})^{-1} K_{n-(p+1)} \tag{11.2}$$

where $(K_{n-1})^{-1}$ denotes the inverse function of K_{n-1} .

In that case, we can write the relation (11.7), being $K_{n-1} \neq 0$, as

$$\sum_{p=1}^n (-1)^{n-p} IK_{n-p} I_{(p)} = 0. \tag{11.3}$$

III. A GENERALIZED INTEGRAL FORMULA

Let $I_{(p)}$ denote the coefficients of the p^{th} inverse fundamental form. Let us define the coefficients of the associated inverse fundamental form by the relations

$$(-1)^{\varepsilon+1} Q_{(\varepsilon)\lambda'} \varepsilon' = \sum_{\gamma=1}^{\varepsilon} (-1)^{\gamma} IK_{n-\gamma-1} I_{(\gamma)\lambda'} \varepsilon', \quad \varepsilon = 1, \dots, n-1. \quad (111.1)$$

By the aid of those, we will define an integral formula over an $(n-1)$ -dimensional region R of M and its boundary ∂R , which is an $(n-2)$ dimensional manifold. It is supposed that R refers to local coordinates u^α , and that the boundary ∂R is represented parametrically by the equations

$$u^\alpha = u^\alpha(v^{\beta'}), \quad (\alpha = 1, \dots, n-1; \beta' = 1, \dots, n-2), \quad (111.2)$$

where the variables $v^{\beta'}$ denote the parameters of ∂R . The functions u^α in (III.2) are assumed to be of class C^2 in all their arguments. Metric tensors of R and ∂R , $g_{\alpha\beta}$ and $g_{\alpha'\beta'}$ respectively, are assumed to be of class C^3 , $g_{\alpha\beta}$ induces the metric tensor $g_{\alpha'\beta'}$ on ∂R defined as, [2],

$$g_{\alpha'\beta'} = \sum_{\alpha, \beta=1}^{n-1} g_{\alpha\beta} \frac{\partial u^\alpha}{\partial v^{\alpha'}} \frac{\partial u^\beta}{\partial v^{\beta'}}. \quad (111.3)$$

The volume elements of R and ∂R are also, defined by

$$\begin{aligned} ds &= \det(g_{\alpha\beta}) du^1 \dots du^{n-1}, \\ ds' &= \det(g_{\alpha'\beta'}) dv^1 \dots dv^{n-2}, \end{aligned} \quad (111.4)$$

respectively. These can be written as

$$\sum_{\alpha, \beta=1}^{n-1} g_{\alpha\beta} n^\alpha \frac{\partial u^\beta}{\partial v^{\alpha'}} = 0 \quad \text{and} \quad \sum_{\alpha, \beta=1}^{n-1} g_{\alpha\beta} n^\alpha n^\beta = 1, \quad (III.5)$$

where n^α ($\alpha = 1, \dots, n-1$) are the components of unit normal vector field over R and the restriction of this vector field over ∂R has the component $n^{\alpha'}$.

Now, let $Y_\alpha = Y_\alpha(u^\beta)$ be a covariant vector field defined over the region R . The components of Y_α vector field are assumed to be of class C^1 throughout R . The projection of Y_α vector field on ∂R boundary has the components

$$Y_{\beta'} = \sum_{\alpha=1}^{n-1} Z^{\alpha\beta'} Y_\alpha, \quad \beta' = 1, \dots, n-2 \quad (III.6)$$

where $Z^{\alpha\beta'} = \frac{\partial u^\alpha}{\partial v^{\beta'}}$.

The length of the projection on the unit normal vector field of Y_α vector field is

$$q = \sum_{\alpha=1}^{n-1} Y_\alpha n^\alpha. \tag{III.7}$$

Replacing this in Eq (III.6) we have the mixed covariant derivative of Y_β' with respect to $v^{\alpha'}$

$$Y_{\beta'} ||_{\alpha'} = q I^{(2)}_{\beta' \alpha'} + \sum_{\alpha:\beta=1}^{n-1} Y_{\alpha\beta} Z^{\alpha\beta'} Z^{\beta\alpha'} \tag{III.8}$$

where $Y_{\alpha\beta}$ denotes the covariant derivative of Y_α with respect to v^β . Let assume that

$$P_{\alpha' \beta'} = \sum_{\alpha:\beta=1}^{n-1} Y_{\alpha\beta} Z^{\alpha\beta'} Z^{\beta\alpha'} \tag{III.9}$$

then we have

$$Y_{\beta'} ||_{\alpha'} = q I^{(2)}_{\beta' \alpha'} + P_{\alpha' \beta'} \tag{III.10}$$

We may define the new functions for $1 \leq \alpha \leq n-2$ by

$$\begin{aligned} H^2_\alpha &= H^2_\alpha (|K_{n-(\alpha+2)}), \\ H^3_\alpha &= H^3_\alpha (|K_{n-(\alpha+2)}, |K_{n-(\alpha+3)}) \end{aligned} \tag{III.11}$$

⋮

$$H_\alpha^{n-1} = H_\alpha^{n-1} (|K_{n-(\alpha+2)}, |K_{n-(\alpha+3)}, \dots, |K_{n-(\alpha+n-2)}).$$

It is easy to express these functions more explicitly. Hence, we can write the inverse fundamental forms as a linear combination of the ordinary fundamental forms in terms of the functions

$$I_{(\varepsilon)\alpha' \beta'} = \sum_{\alpha=1}^{n-1} H_\alpha^\varepsilon I^{(\alpha)}_{\alpha' \beta'} \tag{III.12}$$

So we can obtain from (III.1) the following:

$$(-1)^{\varepsilon+1} Q_{(\varepsilon)\lambda'} \varepsilon' = \sum_{\gamma=1}^{\varepsilon} \sum_{\alpha=1}^{n-1} (-1)^\gamma |K_{n-\gamma-1} H^\gamma_\alpha I^{(\alpha)}_{\lambda'} \varepsilon'. \tag{III.13}$$

On the other hand it is written from elementary tensor calculus [4]

$$Q_{(\varepsilon)}^{\alpha'\beta'} = \sum_{\lambda', \varepsilon'=1}^{n-2} g^{\alpha'\lambda'} g^{\beta'\varepsilon'} Q_{(\varepsilon)\lambda'\varepsilon'} \quad (\text{III.14})$$

or from (III.13),

$$Q_{(\varepsilon)}^{\alpha'\beta'} = \sum_{\lambda', \varepsilon'=1}^{n-2} \sum_{\gamma=1}^{\varepsilon} \sum_{\alpha=1}^{n-1} (-1)^{\gamma-\varepsilon-1} g^{\alpha'\lambda'} g^{\beta'\varepsilon'} |K_{n-\gamma-1} H^\gamma_\alpha I^{(\alpha)\lambda'\varepsilon'}|. \quad (\text{III.15})$$

M_ε is called the associated curvatures on ∂R that had been defined by H. Rund [1] in the following way:

$$M_\varepsilon = \sum_{\alpha', \beta'=1}^{n-2} g^{\alpha'\beta'} I_{\alpha'\beta'(\varepsilon+1)}, \quad \varepsilon = 1, \dots, n-3. \quad (\text{III.16})$$

Thus, it can be written

$$I^{(\varepsilon)}_{\alpha'\beta'} = g_{\varepsilon\lambda'} M_{\varepsilon-1} \quad (\text{III.17})$$

then, we have

$$Q_{(\varepsilon)}^{\alpha'\beta'} = \sum_{\gamma=1}^{\varepsilon} \sum_{\alpha=1}^{n-1} (-1)^{\gamma-\varepsilon-1} g^{\alpha'\beta'} M_{\varepsilon-1} |K_{n-\gamma-1} H^\gamma_\alpha|. \quad (\text{III.18})$$

Now, let us define the contravariant vector fields on ∂R as follows,

$$Q^{\alpha'}_{(\varepsilon)} = \sum_{\beta'=1}^{n-2} (-1)^{\varepsilon+1} Q_{(\varepsilon)}^{\alpha'\beta'} Y_{\beta'}. \quad (\text{III.19})$$

The divergence of the $Q^{\alpha'}_{(\varepsilon)}$, with respect to $v^{\alpha'}$, is given by

$$Q^{\alpha'}_{(\varepsilon)}|_{\alpha'} = \sum_{\beta'=1}^{n-2} (-1)^{\varepsilon+1} (Q^{\alpha'\beta'}_{(\varepsilon)}|_{\alpha'} Y_{\beta'} + Q^{\alpha'\beta'}_{(\varepsilon)} Y_{\beta'}|_{\alpha'}), \quad (\text{III.20})$$

Assuming

$$\sum_{\gamma=1}^{\varepsilon} (-1)^\gamma M_{\varepsilon-1} |K_{n-\gamma-1} H^\gamma_\alpha = |R^\gamma_{\varepsilon\alpha}$$

from (III.10) and (III.18) it follows that

$$Q^{\alpha}_{(\varepsilon)}|_{\alpha'} = \sum_{\beta'=1}^{n-2} \sum_{\alpha=1}^{n-1} g^{\alpha'\beta'} |R^\gamma_{\varepsilon\alpha}| Y_{\beta'} + |R^\gamma_{\varepsilon\alpha} (qM_1 + g^{\alpha'\beta'} P_{\alpha'\beta'})|. \quad (\text{III.21})$$

Finally by using the divergence theorem of Gauss and for $n^{\alpha'} = \sum_{\beta'=1}^{n-2} g^{\alpha'\beta'} n_{\beta'}$, we obtain an integral formula as follows,

$$\int_{\partial R} n_{\alpha'} Q^{\alpha'}(\varepsilon) ds' = \int_R \sum_{\alpha=1}^{n-1} \sum_{\beta'=1}^{n-2} [g^{\alpha'\beta'} \frac{\partial}{\partial v^{\alpha'}} R^{\gamma} \varepsilon_{\alpha} Y_{\beta'} + R^{\gamma}_{\varepsilon_{\alpha}} (qM_1 + g^{\alpha'\beta'} P_{\alpha'\beta'})] ds. \quad (III.22)$$

ÖZET

Riemann Manifoldlarının Hiperyüzeyleri Üzerinde İvers Temel Formlar Ve Bir İntegral Formülü

Bu çalışmada n -boyutlu Riemann uzayı M nin bir N hiperyüzeyinin p tane formu, birinci ve ikinci temel formların katsayıları sayesinde ifade edildi. Sonra N hiperyüzeyi üstünde tanımlanan S şekil operatörünün inversi S^{-1} Cayley-Hamilton teoremi sayesinde S nin kuvvetleri ve yüksek mertebeden K_1, \dots, K_{n-1} Gauss eğrilikleri cinsinden yazıldı. Böylece invers temel formlar dediğimiz yeni temel formlar ve onların bazı özellikleri tanımlandı ve incelendi. Daha sonra N nin bir R bölgesi üzerinde bazı tensör alanlarının divergensinin M nin yeni tanımlanan eğriliklerini kapsayan polinomlar cinsinden olan ifadesine Gauss'un geliştirilmiş divergens teoremini uygulamak suretiyle genel bir integral formülü elde edildi.

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