DETERMINATION OF THE BASE SURFACE CONNECTED WITH THE CONGRUENCE GENERATED BY THE INSTANTANEOUS SCREWING AXIS

TÜRKAN GÜL

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ABSTRACT

In this paper, it has been shown that in case the base surface \vec{x} is a WEINGARTEN surface (W-surface) and the congruence \vec{y} generated by the instantaneous screwing axes derived in [3] is normal congruence, the surface \vec{x} may only be a helicoid surface which is a special W-surface.

1. INTRODUCTION

The instantaneous \vec{G} of the moving trihedron which is connected with the point \vec{x} on the base surface \vec{x} , which referred to its lines of curvature, for the lines of curvature \vec{v} = const. is

$$\vec{G} = \stackrel{\rightarrow}{g} + \epsilon \stackrel{\rightarrow}{g}_0 \,, \qquad (\epsilon^2 = 0)$$

$$\vec{g} \; = - \; rac{\vec{r} \vec{x_2} \; \; \; q \vec{\xi}}{\sqrt{r^2 + q^2}} \; , \quad \vec{g}_0 \; = \; rac{\vec{x}_{\tau} - \vec{r} \vec{x}_{10} - \; q \vec{\xi}_0}{\sqrt{r^2 + q^2}}$$

and the congruence y generated by G is

$$\vec{y} = \vec{r} + t\vec{g} \quad , \qquad (\vec{g}^2 = 1)$$

$$\vec{r} = \vec{x} + \frac{1}{r} \vec{\xi}, \quad \vec{g} = - \frac{\vec{r}x_2 + q\vec{\xi}}{\sqrt{r^2 + q^2}}$$

[3] and [1].

The condition that y is normal, is

$$\ddot{\mathbf{q}}_1 + \ddot{\mathbf{q}}^2 = 0$$
 , $(\ddot{\mathbf{q}} \neq 0)$.

And it has been shown in [3] that the base surface x cannot be developable canal surface, Mulür surface, the surface which have the lines of curvature v = const. and u = const. considering of plane curves, tube-shaped surface or general cylindrical surface.

2. In this work, we will investigate the base surface \bar{x} considering it as a WEINGARTEN surface. In other words, we will assume $\bar{r}=f(r)$, [2] and [4]. We will use the notation $\sqrt{E}=e$, $\sqrt{G}=g$ for the purpose of abbreviation. According to this, the definitions of q and q become

$$q=rac{-e_{V}}{-e_{g}}\;,\;\; ar{q}=rac{-g_{u}}{e_{g}}$$

instead of

$$q = \ {\textstyle \frac{1}{2}} \quad \frac{E_v}{E\sqrt{G}} \ , \quad \tilde{q} = {\textstyle \frac{1}{2}} \quad \frac{G_u}{G\sqrt{E}} \label{eq:q}$$

3. The condition $\bar{q}_1 + \bar{q}^2 = 0$ may be written as

$$g_u = e.c \; (v)$$

from (2.1).

Here, c(v) may be taken as c(v) = 1 by the transformation

$$(2.2) \qquad \overset{\sim}{\mathbf{u}} = \mathbf{u}, \qquad \overset{\sim}{\mathbf{v}} = \mathbf{c}(\mathbf{v})$$

which does not change the coordinate lines. Therefore, the condition $\bar{q}_1+q^2=0$ may be written as

(2.3)
$$g_u = e$$
.

Considering $\ddot{\mathbf{r}} = \mathbf{f}(\mathbf{r})$ and (2.1) in GAUSS-CODAZZI equations, $\mathbf{r}_2 = \mathbf{q}(\ddot{\mathbf{r}} - \mathbf{r})$ may be written as

$$\frac{\mathbf{e}_{\mathbf{v}}}{\mathbf{e}} = \frac{\mathbf{r}_{\mathbf{v}}}{\mathbf{f}(\mathbf{r}) - \mathbf{r}} .$$

Taking $\psi = \psi$ (r) arbitrarily, when we take

(2.4)
$$f(\mathbf{r}) - \mathbf{r} = \frac{\psi}{\psi'}, (\psi' \neq 0)$$

we arrive at $\psi = e d(u)$

Here, d(u) may be taken as d(u) = 1 if we make the transformation

$$(2.5) \qquad \overset{\sim}{\mathbf{u}} = \mathbf{d}(\mathbf{u}) \,, \, \overset{\sim}{\mathbf{v}} = \mathbf{v}$$

which does not change the coordinate lines.

From there, we find

(2.6)
$$\psi = e$$
.

Considering $\tilde{r}_u=f'(r)$, $r_u,~(2.4)$ and $(2.1),~\tilde{r}_1=\bar{q}~(r-\bar{r})$ may be written as

$$\psi' = \mathbf{g.b} (\mathbf{v})$$

Here the function b(v) may be taken as b(v) = 1 by the transformation (2.2). Therefore, we find

$$(2.7) \qquad \qquad \psi' = \mathbf{g}$$

From (2.6), $t^{2.7}$) and (2.3), we find

(2.8)
$$\mathbf{r}_{\mathbf{u}} = \frac{\psi}{\psi''}, (\psi'' \neq 0).$$

Since we may write the equation $-r\tilde{r}=q_2+q^2$ as

$$-r\tilde{r} = \; \left(\frac{e_{v}}{g}\right)_{v} \cdot \; \frac{1}{eg} \; , \label{eq:rescaled}$$

here considering $\bar{r} = f(r)$, (2.4), (2.3), (2.6), (2.7) and making the necessary abbreviations, we find

(2.9)
$$r^2v + (r\psi)^2 = a(u)$$
.

Considering (2.8) and (2.9), we may write

$$\begin{cases} r_{v} = \sqrt{a(u) - (r\psi)^{2}} \\ r_{u} = \frac{\psi}{\psi''} \end{cases}$$

From the condition of integrability $r_{vu} = r_{uv}$, we find the equation below:

(2.11)
$$\mathbf{a}' - 2 (\mathbf{r}\psi) (\mathbf{r}\psi)' \cdot \frac{\psi}{\psi''} = 2 \left(\frac{\psi}{\psi''}\right)' |\mathbf{a} - (\mathbf{r}\psi)^2|.$$

The solution of this differential equation is as F(r,u) = 0 where r is r=r(u). This case corresponds to $a' \neq 0$. If a' = 0, at the end of appropriate calculations, (2.11) becomes

$$\sqrt{a-(r\psi)^2}=-k\frac{\psi}{\psi''}$$

where k is a parameter. If we consider (2.10) here we find the differential equation

$$(2.12) r_{v} + k r_{u} = 0.$$

The solution of the equation is as

$$(2.13)$$
 $r = r (kv-u)$.

From this, we see that the base surface x is a helicoid surface. The helicoid surface îs a special WEINGARTEN surface.

Therefore the following theorem may be stated:

2.1. THEOREM

If the base surface x of the congruence y is a WEINGARTEN surface, in case this congruence is normal congruence, this surface may only be a helicoid surface which is a special W-surface.

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