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# **SOME EKTENSIONS OF GALLOP'S FORMULAS**

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#### **ABSTRACT**

İn this study, some recurrence relations for a class of functions derived from Lorentzian metric, which can be solutions of a ultra-hyperbolic type linear P.D.E. in p+q dimensional space, are obtained.

## **1. INTRODUCTION**

It is shown by E.G. Gallop [2] that in three dimensional space, the surface spherical harmonics defined by

$$
P(a,b,c) = \frac{(-1)^n}{a!b!c!} r^{n+1} \left(\frac{\partial}{\partial x}\right)^n \left(\frac{\partial}{\partial y}\right)^b \left(\frac{\partial}{\partial z}\right)^c \frac{1}{r}
$$
 (1)

hold the recurrence relation

$$
(a+1)(a+2)P(a+2,b,c)+(b+1)(b+2)P(a,b+2,c)+(c+1)(c+2)P(a,b,c+2) = 0
$$
 (2)

and

$$
\frac{\partial}{\partial x}\left[r^{n}P(a,b,c)\right] = -r^{n-1}[(a+1)P(a+1,b-2,c)+(a+1)P(a+1,b,c-2)-(2n-a)P(a-1,b,c)],\qquad(3)
$$

where  $r^2=x^2+y^2+z^2$  and a, b, c are non-negative integers with n=a+b+c. It is well known that  $P(a,b,c)$  is a homogeneous function of zero degree and satisfîes the Laplace equation [3],

In this study, we obtain some new forms of the formulas (2) and (3) by extending them to the functions whieh are the Solutions of a P.D.E. of ultra-hyperbolic type in  $p+q$  dimension. We use the following notations:

$$
L = \sum_{i=1}^{p} \frac{\partial^{2}}{\partial x_{i}^{2}} - \sum_{j=1}^{q} \frac{\partial^{2}}{\partial y_{j}^{2}}
$$
(4)

$$
s^{2} = \sum_{i=1}^{p} x_{i}^{2} - \sum_{j=1}^{q} y_{j}^{2} = |x|^{2} - |y|^{2}
$$
 (5)

#### 2. SOME RECCURENCE RELATIONS FOR THE SOLUTIONS OF Lu=0

Let  $a_1,...,a_p,b_1,...,b_q$  be non-negative integers and let  $\sum_{i=1}^{p} a_i + \sum_{i=1}^{q} b_j = n$ .<br>Define the function P\* as

$$
P^*(a_1, \dots, a_p, b_1, \dots, b_q) = \frac{1}{a_1! \dots a_p! b_1! \dots b_q!} \left(\frac{\partial}{\partial x_1}\right)^{a_1} \dots \left(\frac{\partial}{\partial x_p}\right)^{a_p} \left(\frac{\partial}{\partial y_1}\right)^{b_1} \dots \left(\frac{\partial}{\partial y_q}\right)^{b_q} G(x_1, \dots, x_p, y_1, \dots, y_q),
$$
(6)

where  $G \in C^{n+2}(D)$  and  $D \subset \mathbb{R}^{p+q}$ .

**Lemma 1.** If  $L(G) = 0$ , then  $L(P^*) = 0$ .

**Proof.** The operator L defined by (4) and the operator T defined by

are linear operators with constant coefficients and they hold the relation  $LT(u) = TL(u)$ . Thus, from (6),

$$
L(P^*) = L\left\{\frac{1}{a_1!...a_p!b_1!...b_q!}T(G)\right\}
$$
  
= 
$$
\frac{1}{a_1!...a_p!b_1!...b_q!}L[T(G)]
$$
  
= 
$$
\frac{1}{a_1!...a_p!b_1!...b_q!}T[L(G)]
$$
 (8)

 $(9)$ 

Since  $L(G) = 0$ , we get  $L(P^*) = 0$  by (8).

**Theorem 1.** If  $L(G) = 0$ , then the function  $P^*(a_1,...,a_p,b_1,...,b_q)$  as being a solution of  $Lu = 0$ , satisfies the recurrence formula  $\sum_{i=1}^{q} (a_i+1)(a_i+2)P^{*}(a_1,...,a_i+2,...,a_p,b_1,...b_q) - \sum_{i=1}^{q} (b_i+1)(b_i+2)P^{*}(a_1,...,a_p,b_1,...,b_j+2,...b_q) = 0.$ 

**Proof.** By the equality (6), we have\n
$$
\sum_{i=1}^{p} (a_i+1)(a_i+2)P^*(a_1,...,a_i+2,...,a_p,b_1,...b_q) - \sum_{j=1}^{q} (b_j+1)(b_j+2)P^*(a_1,...,a_p,b_1,...,b_j+2,...b_q)
$$

$$
= \sum_{i=1}^{p} \frac{(a_{i}+1)(a_{i}+2)}{a_{1}!...(a_{i}+2)!...(a_{p}!b_{1}!...(b_{q}!} \left(\frac{\partial}{\partial x_{1}}\right)^{a_{1}} \left(\frac{\partial}{\partial x_{1}}\right)^{a_{1}+2} \left(\frac{\partial}{\partial x_{p}}\right)^{a_{p}} \left(\frac{\partial}{\partial y_{1}}\right)^{b_{1}} \left(\frac{\partial}{\partial y_{q}}\right)^{b_{q}} dG
$$
  

$$
- \sum_{j=1}^{q} \frac{(b_{j}+1)(b_{j}+2)}{a_{1}!...(a_{p}!b_{1}!...(b_{j}+2)!...(b_{q}!} \left(\frac{\partial}{\partial x_{1}}\right)^{a_{1}} \left(\frac{\partial}{\partial x_{p}}\right)^{b_{1}} \left(\frac{\partial}{\partial y_{1}}\right)^{b_{1}} \left(\frac{\partial}{\partial y_{j}}\right)^{b_{1}} \left(\frac{\partial}{\partial y_{q}}\right)^{b_{q}} G
$$
  

$$
= \frac{1}{a_{1}!...(a_{p}!b_{1}!...(b_{q}!} \left(\frac{\partial}{\partial x_{1}}\right)^{a_{1}} \left(\frac{\partial}{\partial x_{p}}\right)^{a_{p}} \left(\frac{\partial}{\partial y_{1}}\right)^{b_{1}} \left(\frac{\partial}{\partial y_{q}}\right)^{b_{q}} \left(\frac{\partial}{\partial x_{i}}\right)^{b_{q}} \left(\frac{\partial}{\partial x_{i}}\right)^{c_{q}} \left(\frac{\partial}{\partial x_{i}}\right)^{c_{q}} G
$$
  

$$
= \frac{1}{a_{1}!...(a_{p}!b_{1}!...(b_{q}!} \left(\frac{\partial}{\partial x_{1}}\right)^{a_{1}} \left(\frac{\partial}{\partial x_{p}}\right)^{a_{p}} \left(\frac{\partial}{\partial y_{1}}\right)^{b_{1}} \left(\frac{\partial}{\partial y_{q}}\right)^{b_{q}} G.
$$

Since  $L(G) = 0$ , the result follows.

**Corollary 1.** The function  $P_0^*$  defined by

$$
P_0^*(a_1,...,a_p,b_1,...,b_q) = \frac{1}{a_1!...a_p!b_1!...b_q!} \left(\frac{\partial}{\partial x_1}\right)^{a_1} \cdot \left(\frac{\partial}{\partial x_p}\right)^{a_p} \left(\frac{\partial}{\partial y_1}\right)^{b_1} \cdot \left(\frac{\partial}{\partial y_q}\right)^{b_q} \frac{1}{s^{p+q^2}}
$$
(10)

satisfies the recurrence formula (9). Here s is the Lorentzian distance defined by (5).

**Proof.** Since  $L(s^{2p\cdot q}) = L(\frac{1}{s^{2p-1}}) = 0$  (see [1]), by letting  $G = \frac{1}{s^{2p-1}}$  in Theorem 1, we get the result.<sup> $P+q-2$ </sup>  $\left\{\right\}$ 

**Theorem 2.** Let  $D \subset \mathbb{R}^{p+q}$ , F $\in C(D)$  and G $\in C^{n}(D)$ . For  $L(G) = 0$  the function P\*\* defined by

function P<sup>\*\*</sup> defined by  
\nP<sup>\*\*</sup>(a<sub>1</sub>,...,a<sub>p</sub>,b<sub>1</sub>,...,b<sub>q</sub>)
$$
= \frac{F(x_1,...,x_p,y_1,...,y_q)}{a_1!...a_p!b_1!...b_q!} \left(\frac{\partial}{\partial x_1}\right)^{a_1} \cdot \left(\frac{\partial}{\partial x_p}\right)^{b_1} \cdot \left(\frac{\partial}{\partial y_1}\right)^{b_q} G(x_1,...,x_p,y_1,...,y_q)
$$
\n(11)

satisfies the recurrence relation

$$
\sum_{i=1}^{p} (a_{i}+1)(a_{i}+2)P^{**}(a_{1},...,a_{i}+2,...,a_{p},b_{1},...b_{q}) - \sum_{j=1}^{q} (b_{j}+1)(b_{j}+2)P^{**}(a_{1},...,a_{p},b_{1},...,b_{j}+2,...b_{q}) = 0
$$
\n(12)

**Proof.** Multiplying both side of the equality (9) by  $F(x_1,...,x_p,y_1,...,y_q)$ and by observing the relation  $FP^* = P^{**}$  from (6) and (11), we get (12).

**Remark.** We note that the function P\*\* defined by (11) need not be a solution of the equation  $Lu = 0$ . But, if we choose, in (11),

$$
F = (-1)^n s^{n+p+q-2}
$$
 and  $G = \frac{1}{s^{p+q-2}}$ ,

then the resulted function

$$
P(a_1, \dots, a_p, b_1, \dots, b_q) = \frac{(-1)^n s^{n+p+q-2}}{a_1! \dots a_p! b_1! \dots b_q!} \left(\frac{\partial}{\partial x_1}\right)^{a_1} \dots \left(\frac{\partial}{\partial x_p}\right)^{a_p} \left(\frac{\partial}{\partial y_1}\right)^{b_1} \dots \left(\frac{\partial}{\partial y_q}\right)^{b_q} \frac{1}{s^{p+q-2}} \tag{13}
$$

is a zero-degree homogeneous solution of the ultra-hyperbolic eguation Lu=0. By taking P instead of  $P^{**}$  in (12), the function P as a special case of P\*\* satisfies the recurrence relation

$$
\sum_{i=1}^{p} (a_i+1)(a_i+2)P(a_1,...,a_i+2,...,a_p,b_1,...b_q) - \sum_{j=1}^{q} (b_j+1)(b_j+2)P(a_1,...,a_p,b_1,...,b_j+2,...b_q) = 0.
$$
\n(14)

The formula (14) is the extension of the recurrence relation (2), which is satisfied by the surface spherical harmonics as zero degree homogeneous solutions of Laplace equation to the similar type solutions of the equation  $Lu = 0$ .

# **3. EXTENSION OF (3)**

In this section, some extensions of the recurrence formula (3) are obtained. Let us first give the following lemma.

**Lemma 2.** Let us define the function Q as

Q(a,,...3 l),,...,b) = 1 a, '1 *a öx* p a ay 1'1 (15) *d* s

where s is the Lorentzian distance and  $\phi$  is a real constant. Then we have

$$
s^{2}Q(a_{1},...,a_{p},b_{1},...,b_{q}) = -\sum_{i=1}^{p} \left\{ a_{i}(a_{i}-1)Q(a_{1},...,a_{i}-2,...,a_{p},b_{1},...,b_{q})+2a_{i}x_{i}Q(a_{1},...,a_{i}-1,...,a_{p},b_{1},...,b_{q}) \right\} + \sum_{j=1}^{q} \left\{ b_{j}(b_{j}-1)Q(a_{1},...,a_{p},b_{1},...,b_{j}-2,...,b_{q})+2b_{j}y_{j}Q(a_{1},...,a_{p},b_{1},...,b_{j}-1,...,b_{q}) \right\}
$$
(16)  
+(-0+2)\left\{ (a\_{1}-1)Q(a\_{1}-2,...,a\_{p},b\_{1},...,b\_{q})+x\_{1}Q(a\_{1}-1,...,a\_{p},b\_{1},...,b\_{q}) \right\},

where  $a_i$ ,  $b_i$  (i=1,...,p,j=1,...q) are non-negative integers.

**Proof.** By the definition of s, we have

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$$
\frac{\partial}{\partial x_1} (s^{-\phi+2}) = (-\phi+2) \frac{x_1}{s^{\phi}}.
$$

Applying the operator

$$
\left(\frac{\partial}{\partial x_1}\right)^{a_1-1} \cdot \left(\frac{\partial}{\partial x_1}\right)^{a_p} \left(\frac{\partial}{\partial y_1}\right)^{b_1} \cdot \left(\frac{\partial}{\partial y_1}\right)^{b_q}
$$

to the both sides of the above equality we get

$$
\left(\frac{\partial}{\partial x_1}\right)^{a_1} \cdot \cdot \cdot \left(\frac{\partial}{\partial x_p}\right)^{a_p} \left(\frac{\partial}{\partial y_1}\right)^{b_1} \cdot \cdot \left(\frac{\partial}{\partial y_q}\right)^{b_q} s^{+b+2} = (-\phi + 2) \left(\frac{\partial}{\partial x_1}\right)^{a_1-1} \cdot \cdot \cdot \left(\frac{\partial}{\partial x_p}\right)^{a_p} \left(\frac{\partial}{\partial y_1}\right)^{b_1} \cdot \cdot \cdot \left(\frac{\partial}{\partial y_q}\right)^{b_q} \frac{x_1}{s^{\phi}}.
$$

On the other hand, rewriting the term  $s^{\phi+2}$  of the first side of the equality as  $s^2 \frac{1}{\phi}$  and taking the first derivative with respect to  $x_1$  we obtain obtain

$$
\left(\frac{\partial}{\partial x_1}\right)\left(s^2\frac{1}{s^{\phi}}\right) = 2x_1\frac{1}{s^{\phi}} + s^2\frac{\partial}{\partial x_1}\left(\frac{1}{s^{\phi}}\right),
$$

and hence the second derivative gives

$$
\left(\frac{\partial}{\partial x_1}\right)^2 \left(s^2 \frac{1}{s^{\phi}}\right) = 2 \frac{1}{s^{\phi}} + 4x_1 \frac{\partial}{\partial x_1} \left(\frac{1}{s^{\phi}}\right) + s^2 \frac{\partial^2}{\partial x_1^2} \left(\frac{1}{s^{\phi}}\right)
$$

By repeating derivation  $a_1$  times, we obtain, by induction,

$$
\left(\frac{\partial}{\partial x_1}\right)^{a_1}\left(s^2 \frac{1}{s^{\phi}}\right) = (a_1 - 1)a_1\left(\frac{\partial}{\partial x_1}\right)^{a_1 - 2}\left(\frac{1}{s^{\phi}}\right) + 2a_1x_1\left(\frac{\partial}{\partial x_1}\right)^{a_1 - 1}\left(\frac{1}{s^{\phi}}\right) + s^2\left(\frac{\partial}{\partial x_1}\right)^{a_1}\frac{1}{s^{\phi}}
$$

Similarly, in the last expression, taking the derivatives  $a_2$  times with respect to  $x_2$  gives us

$$
\left(\frac{\partial}{\partial x_1}\right)^{a_2} \left(\frac{\partial}{\partial x_1}\right)^{a_1} \left(s^2 \frac{1}{s^{\phi}}\right) = \left(\frac{\partial}{\partial x_1}\right)^{a_1} \left(\frac{\partial}{\partial x_2}\right)^{a_2} \left(s^2 \frac{1}{s^{\phi}}\right)
$$
\n
$$
= (a_1 - 1)a_1 \left(\frac{\partial}{\partial x_2}\right)^{a_2} \left(\frac{\partial}{\partial x_1}\right)^{a_1 - 2} \left(\frac{1}{s^{\phi}}\right) + 2a_1 x_1 \left(\frac{\partial}{\partial x_1}\right)^{a_1 - 1} \left(\frac{\partial}{\partial x_1}\right)^{a_2} \left(\frac{1}{s^{\phi}}\right)
$$
\n
$$
+ (a_2 - 1)a_2 \left(\frac{\partial}{\partial x_2}\right)^{a_2 - 2} \left(\frac{\partial}{\partial x_1}\right)^{a_1} \left(\frac{1}{s^{\phi}}\right) + 2a_2 x_2 \left(\frac{\partial}{\partial x_1}\right)^{a_1} \left(\frac{\partial}{\partial x_2}\right)^{a_2 - 1} \left(\frac{1}{s^{\phi}}\right) + s^2 \left(\frac{\partial}{\partial x_2}\right)^{a_2} \left(\frac{\partial}{\partial x_1}\right)^{a_1} \left(\frac{1}{s^{\phi}}\right)
$$
\nProceeding in this manner, taking the derivatives with respect to x ...

this manner, taking the derivatives respect to  $x_3,...,x_p$ respectively  $a_3,...,a_p$  times, finally we obtain

= (aı-l)a,<sup>I</sup> .a <sup>+</sup> 2ajXj(«t a p ''± s\* p <sup>s</sup> <'(«( a p 3 a, + 2ajXj ,"3-' P' **»1** p p + 2a <sup>X</sup> p p p p p

 $\int_{a}^{b_q}$  successively to both Now, by applying the operators sides of the last expression, we get  $\frac{(\mathcal{O}_{\mathfrak{X}_1})^{\mathfrak{Y}_1}(\mathcal{O}_{\mathfrak{X}_1})}{\mathfrak{Y}_1}$ 

$$
\left(\frac{\partial}{\partial x_1}\right)^{a_1} \cdot \left(\frac{\partial}{\partial x_p}\right)^{b_1} \cdot \left(\frac{\partial}{\partial y_1}\right)^{b_1} \cdot \left(\frac{\partial}{\partial y_q}\right)^{b_q} \cdot \left(\frac{\partial}{\partial x_1}\right)^{b_q} \cdot \left(\frac{\partial}{\partial x_1}\right)^{b_q} \cdot \left(\frac{\partial}{\partial x_1}\
$$

$$
\begin{aligned}&-2b_qy_q\left(\frac{\partial}{\partial x_1}\right)^{a_1}\left(\frac{\partial}{\partial x_2}\right)^{a_2}\cdot\left(\frac{\partial}{\partial x_p}\right)^{a_p}\left(\frac{\partial}{\partial y_1}\right)^{b_1}\cdot\left(\frac{\partial}{\partial y_q}\right)^{b_q-1}\frac{1}{s^{\phi}}\\&+s^2\left(\frac{\partial}{\partial x_1}\right)^{a_1}\cdot\left(\frac{\partial}{\partial x_p}\right)^{a_p}\left(\frac{\partial}{\partial y_1}\right)^{b_1}\cdot\left(\frac{\partial}{\partial y_q}\right)^{b_q-1}\frac{1}{s^{\phi}}.\end{aligned}
$$

By using the definition of Q, we can rewrite the right hand side of the last cquality in terms of Q as follows:

$$
\left(\frac{\partial}{\partial x_1}\right)^{a_1} \cdot \left(\frac{\partial}{\partial x_p}\right)^{a_p} \left(\frac{\partial}{\partial y_1}\right)^{b_1} \cdot \left(\frac{\partial}{\partial y_q}\right)^{b_q} \left(s^2 \frac{1}{s^{\phi}}\right)
$$
\n
$$
= \sum_{i=1}^{p} \left\{a_1(a_1-1)Q(a_1,...,a_1-2,...,a_p,b_1,...,b_q)+2a_1x_1Q(a_1,...,a_1-1,...,a_p,b_1,...,b_q)\right\}
$$
\n
$$
- \sum_{j=1}^{q} \left\{b_j(b_j-1)Q(a_1,...,a_p,b_1,...,b_j-2,...,b_q)+2b_jy_jQ(a_1,...,a_p,b_1,...,b_q)\right\}
$$
\n
$$
+ s^2Q(a_1,...,a_p,b_1,...,b_q)
$$
\n
$$
\left(\frac{\partial}{\partial x_1}\right)^{a_{p_1}} \cdot \left(\frac{\partial}{\partial x_2}\right)^{b_{p_2}} \cdot \left(\frac{\partial}{\partial x_1}\right)^{a_{p_1}} \cdot \left(\frac{\partial}{\partial x_2}\right)^{b_{p_2}} \cdot \left(\frac{\partial}{\partial x_1}\right)^{b_q} \cdot \left(\frac{\partial}{\partial x_2}\right)^{b_q} \cdot \left(\frac{\partial}{\partial x_1}\right)^{b_q} \cdot \left(\frac{\partial
$$

Similarly, applying the operatoı <sup>M</sup>' <sup>H</sup> «' P'S Kİ hand side of the equality (17) takes the form q <sup>4</sup> to  $\frac{x_1}{s^{\phi}}$ , the right

$$
(-\varphi+2)\left(\frac{\partial}{\partial x_1}\right)^{a_1-1} \cdot \left(\frac{\partial}{\partial x_p}\right)^{a_p}\left(\frac{\partial}{\partial y_1}\right)^{b_1} \cdot \left(\frac{\partial}{\partial y_q}\right)^{b_q} \frac{x_1}{s^{\varphi}} =
$$
\n
$$
(-\varphi+2)\left\{(a_1-1)\left(\frac{\partial}{\partial x_1}\right)^{a_1-2} \cdot \left(\frac{\partial}{\partial x_p}\right)^{a_p}\left(\frac{\partial}{\partial y_1}\right)^{b_1} \cdot \left(\frac{\partial}{\partial y_q}\right)^{b_q} \frac{1}{s^{\varphi}} + x_1\left(\frac{\partial}{\partial x_1}\right)^{a_1-1} \cdot \left(\frac{\partial}{\partial x_p}\right)^{a_p}\left(\frac{\partial}{\partial y_1}\right)^{b_1} \cdot \left(\frac{\partial}{\partial y_q}\right)^{b_q} \frac{1}{s^{\varphi}}\right\}.
$$

Again by using the definition of Q, we get  
\n
$$
(-\phi+2)\left(\frac{\partial}{\partial x_1}\right)^{a_1-1} \cdot \left(\frac{\partial}{\partial x_p}\right)^{a_p}\left(\frac{\partial}{\partial y_1}\right)^{b_1} \cdot \left(\frac{\partial}{\partial y_q}\right)^{b_q} \frac{x_1}{s^{\phi}}
$$
\n
$$
= (-\phi+2)\left\{(a_1-1)Q(a_1-2,...a_p,b_1,...,b_q)+x_1Q(a_1-1,...,a_p,b_1,...,b_q)\right\}.
$$
\n(19)

Hence in view of  $(17)$   $(18)$  and  $(19)$  we obtain  $(16)$ .

**Theorem 3.** Q as being in Lemma 2, we have

$$
\frac{\partial}{\partial x_1} \left[ s^{\alpha} Q(a_1, \dots, a_p, b_1, \dots, b_q) \right] = s^{\alpha^2} \left\{ (-\phi + 1 - 2n - a_1)a_1 Q(a_1 - 1, \dots, a_p, b_1, \dots, b_q) \right\}
$$
  
+ (-2n -  $\phi + \alpha$ )x<sub>1</sub>Q(a<sub>1</sub>, \dots, a\_p, b\_1, \dots, b\_q) +  $\sum_{i=2}^{p} a_i (a_i - 1) Q(a_1 + 1, \dots, a_i - 2, \dots, a_p, b_1, \dots, b_q)$ 

$$
-\sum_{j=1}^{q} b_j(b_j-1)Q(a_1+1,...,a_p,b_1,...,b_j-2,...,b_q),
$$
\n(20)

where  $\alpha$  and  $\phi$  are real constants,  $n = \sum_{i=1}^{p} a_i + \sum_{j=1}^{q} b_j$  and s is Lorentzian distance defined in (5).

Proof. Using (15) in (20) and writing the derivative with respect to x, explicitly we have

$$
\frac{\partial}{\partial x_1} \left[ s^{\alpha} Q(a_1,...,a_p,b_1,...,b_q) \right] = \frac{\partial}{\partial x_1} \left[ s^{\alpha} \left( \frac{\partial}{\partial x_1} \right)^{a_1} \cdot \left( \frac{\partial}{\partial x_p} \right)^{a_p} \left( \frac{\partial}{\partial y_1} \right)^{b_1} \cdot \left( \frac{\partial}{\partial y_q} \right)^{b_q} \frac{1}{s^{\phi}} \right]
$$
\n
$$
= s^{\alpha/2} \left[ s^2 \left( \frac{\partial}{\partial x_1} \right)^{a_1+1} \cdot \left( \frac{\partial}{\partial x_p} \right)^{a_p} \left( \frac{\partial}{\partial y_1} \right)^{b_1} \cdot \left( \frac{\partial}{\partial y_q} \right)^{b_q} \frac{1}{s^{\phi}} + \alpha x_1 \left( \frac{\partial}{\partial x_1} \right)^{a_1} \cdot \left( \frac{\partial}{\partial x_p} \right)^{b_p} \left( \frac{\partial}{\partial y_1} \right)^{b_p} \cdot \left( \frac{\partial}{\partial y_q} \right)^{b_q} \frac{1}{s^{\phi}} \right]
$$
\n(21)

On the other hand in (16) replacing  $a_1$  by  $a_1+1$  and using this value in (21), after simplifications wet get

$$
\frac{\partial}{\partial x_1} \left[ s^{\alpha} Q(a_1, \dots, a_p, b_1, \dots, b_q) \right]
$$
\n
$$
= s^{\alpha^2} \left[ (-\phi \cdot a_1 + 1) a_1 Q(a_1 - 1, \dots, a_p, b_1, \dots, b_q) + (-2a_1 - \phi + \alpha) x_1 Q(a_1, \dots, a_p, b_1, \dots, b_q) \right]
$$
\n
$$
- \sum_{i=2}^p \left\{ a_i (a_i - 1) Q(a_1 + 1, \dots, a_i - 2, \dots, a_p, b_1, \dots, b_q) + 2a_i x_i Q(a_1 + 1, \dots, a_i - 1, \dots, a_p, b_1, \dots, b_q) \right\}
$$
\n
$$
- \sum_{j=1}^q \left\{ b_j (b_j - 1) Q(a_1 + 1, \dots, a_p, b_1, \dots, b_j - 2, \dots, b_q) + 2b_j y_j Q(a_1 + 1, \dots, a_p, b_1, \dots, b_q) \right\} \right]
$$
\n(22)

Next, for  $i = 1,2,...,p$  since sides the operatör  $\mathbf{x}_1 \stackrel{\partial}{=}$  $\alpha_i$  $\mathbf{x}_i \frac{\partial}{\partial \mathbf{x}}$  $\pm = 0$ , applying both

$$
\left(\!\frac{\partial}{\partial x_1}\!\right)^{\!a_1}\!\!\cdot\!\!\cdot\!\!\left(\!\frac{\partial}{\partial x_i}\!\right)^{\!a_1\!1}\!\!\cdot\!\!\cdot\!\!\left(\!\frac{\partial}{\partial x_p}\!\right)^{\!a_p}\!\!\left(\!\frac{\partial}{\partial y_1}\!\right)^{\!b_1}\!\!\cdot\!\!\cdot\!\!\left(\!\frac{\partial}{\partial y_q}\!\right)^{\!b_q}\!,
$$

we get, for  $i=2,...,p$ ,

$$
a_j\left(\frac{\partial}{\partial x_1}\right)^{a_j-1} \cdots \left(\frac{\partial}{\partial x_p}\right)^{a_p}\left(\frac{\partial}{\partial y_1}\right)^{b_j} \cdots \left(\frac{\partial}{\partial y_q}\right)^{b_q}\frac{1}{s^{\varphi}} + x_j\left(\frac{\partial}{\partial x_1}\right)^{a_j-1} \cdots \left(\frac{\partial}{\partial x_p}\right)^{a_p}\left(\frac{\partial}{\partial y_1}\right)^{b_j} \cdots \left(\frac{\partial}{\partial y_q}\right)^{a_p}\left(\frac{1}{\partial y_q}\right)^{b_q}\frac{1}{s^{\varphi}}
$$
  
-  $(a_j-1)\left(\frac{\partial}{\partial x_1}\right)^{a_j+1} \cdots \left(\frac{\partial}{\partial x_j}\right)^{a_j-2} \cdots \left(\frac{\partial}{\partial x_p}\right)^{b_p}\left(\frac{\partial}{\partial y_1}\right)^{b_1} \cdots \left(\frac{\partial}{\partial y_q}\right)^{b_q}\frac{1}{s^{\varphi}}$ 

X, p q l'L"

By using the definition of Q in the above equality we obtain

$$
a_1 Q(a_1-1,...,a_p,b_1,...,b_q)+x_1 Q(a_1,...,a_p,b_1,...,b_q)-(a_1-1)Q(a_1+1,...,a_1-2,...,a_p,b_1,...,b_q)
$$
  
-
$$
x_1 Q(a_1+1,...,a_1-1,...,a_p,b_1,...,b_q) = 0, i = 2,...,p
$$
 (23)

Similarly, applying the operator

$$
\left(\!\frac{\partial}{\partial x_1}\!\right)^{\!a_1}\!\!\cdots\!\left(\!\frac{\partial}{\partial x_p}\!\right)^{\!a_p}\!\!\left(\!\frac{\partial}{\partial y_1}\!\right)^{\!b_1}\!\!\cdots\!\left(\!\frac{\partial}{\partial y_j}\!\right)^{\!b_{j\!-\!1}}\!\!\cdots\!\left(\!\frac{\partial}{\partial y_q}\!\right)^{\!b_q}\!\!
$$

to both sides of  $\left(x \frac{\partial}{\partial x} + y \frac{\partial}{\partial y}\right)$   $\frac{1}{\partial y} = 0$  (i=1.2, q) and again using the  $\begin{bmatrix} x_1 & \frac{1}{\partial y_1} & +y_1 \\ \frac{1}{\partial y_1} & \frac{1}{\partial x_1} \end{bmatrix}$ definition of Q, we get

$$
a_1 Q(a_1-1,...,a_p,b_1,...,b_q)+x_1 Q(a_1,...,a_p,b_1,...,b_q)
$$
  
+ $(b_j-1)Q(a_1+1,...,a_p,b_1,...,b_j-2,...,b_q)+y_j Q(a_1+1,...,a_p,b_j,...,b_j-1,...,b_q) = 0.$  (24)  
Multiplying (23) and (24) respectively, with (23) (i=2, n) and (2b)

Multiplying (23) and (24) respectively with  $-2a_i$ ,  $(i=2,...,p)$  and  $(i=1,2,...,q)$  and adding them side by side, and then comparing the result with the right side of (22), we obtain

$$
\frac{\partial}{\partial x_1} \left[ s^{\alpha} \left( \frac{\partial}{\partial x_1} \right)^{a_1} \cdot \cdot \left( \frac{\partial}{\partial x_p} \right)^{a_p} \left( \frac{\partial}{\partial y_1} \right)^{b_1} \cdot \cdot \left( \frac{\partial}{\partial y_q} \right)^{b_q} \frac{1}{s^{\phi}} \right]
$$
\n
$$
= s^{\alpha/2} \left\{ (-\phi + 1 - 2n - a_1)a_1 Q(a_1 - 1, \dots, a_p, b_1, \dots, b_q) + \sum_{i=2}^p a_i (a_i - 1) Q(a_1 + 1, \dots, a_i - 2, \dots, a_p, b_1, \dots, b_q) \right\}
$$
\n
$$
+ \sum_{j=1}^q b_j (b_j - 1) Q(a_1 + 1, \dots, a_p, b_1, \dots, b_j - 2, \dots, b_q) \right\}
$$

**Corollary 2.** Let s and P be as defined in (5) and (13). Then

$$
\frac{\partial}{\partial x_1} \left[ s^n P(a_1, \dots, a_p, b_1, \dots, b_q) \right] = -s^{n-1} \left\{ \sum_{i=2}^p (a_1 + 1) P(a_1 + 1, \dots, a_j - 2, \dots, a_p, b_1, \dots, b_q) \right\}
$$
  
\n
$$
- \sum_{j=1}^q (a_1 + 1) P(a_1 + 1, \dots, a_p, b_1, \dots, b_j - 2, \dots, b_q) - (2n + p + q - 3 - a_1) P(a_1 - 1, \dots, a_p, b_1, \dots, b_q) \right\}
$$
 (25)

**Proof.** Let us take 
$$
\alpha = 2n+p+q-2
$$
, and  $\phi = p+q-2$  in (20). Then

$$
\frac{\partial}{\partial x_1} \left[ s^{2n+p+q-2} Q(a_1,...,a_p, b_1,...,b_q) \right]
$$
\n
$$
= s^{2n+p+q-4} \left\{ (-p-q+3-2n-a_1)a_1 Q(a_1-1,...,a_p, b_1,...,b_q) + (-2n-(p+q+2)+2n+p+q-2)x_1 Q(a_1,...,a_p, b_1,...,b_q) + \sum_{i=2}^p a_i(a_i-1) Q(a_1+1,...,a_i-2,...,a_p, b_1,...,b_q) \right\}
$$

We obtain (25), by multiplying the last equality by taking the equality  $(-1)^n$  $a_1!...a_p!b_1!...b_q!$ and

$$
P(a_1, \dots, a_p, b_1, \dots, b_q) = (-1)^n \frac{s^{n+p+q \cdot 2}}{a_1! \dots a_p! b_1! \dots b_q!} Q(a_1, \dots, a_p, b_1, \dots, b_q)
$$

into account.

**Remark.** Using  $\frac{\partial}{\partial x}$  instead of  $\frac{\partial}{\partial y}$  replaces Theorem 2 and Corollary 1 with followings:  $\frac{\partial}{\partial y_1}$   $\frac{\partial}{\partial x_1}$ 

**Theorem 4.**

$$
\frac{\partial}{\partial y_1} \left[ s^{\alpha} Q(a_1, \dots, a_p, b_1, \dots, b_q) \right] = s^{\alpha \cdot 2} \left[ (\phi \cdot 1 + 2n \cdot b_1) b_1 Q(a_1, \dots, a_p, b_1 \cdot 1, \dots, b_q) \right]
$$
  
+  $(\phi \cdot \alpha + 2n) y_1 Q(a_1, \dots, a_p, b_1, \dots, b_q) + \sum_{i=1}^p a_i (a_i \cdot 1) Q(a_1, \dots, a_i \cdot 2, \dots, a_p, b_1 + 1, \dots, b_q)$   
-  $\sum_{j=2}^q b_j (b_j \cdot 1) Q(a_1, \dots, a_p, b_1 + 1, \dots, b_j \cdot 2, \dots, b_q) \right].$ 

**Corollary 3.**

$$
\frac{\partial}{\partial y_1} \left[ s^n P(a_1, \dots, a_p, b_1, \dots, b_q) \right] = -s^{n-1} \left[ \sum_{i=1}^p (b_1 + 1) P(a_1, \dots, a_i - 2, \dots, a_p, b_1 + 1, \dots, b_q) \right]
$$
  
- 
$$
\sum_{j=2}^q (b_1 + 1) P(a_1, \dots, a_p, b_1 + 1, \dots, b_j - 2, \dots, b_q) + (2n + p + q - 3 - b_1) P(a_1, \dots, a_p, b_1 - 1, \dots, b_q) \right],
$$

p q where  $n = \sum a_i + \sum b_i$  and s and  $P(a_1,...,a_n,b_1,...,b_n)$  are defined as in (5) and (13) respectively.

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