



Note on a Allen-Cahn equation with Caputo-Fabrizio derivative

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Abstract

In this short note, we investigate the Allen-Cahn equation with the appearance of the Caputo-Fabrizio derivative. We obtain a local solution when the initial value is small enough. This is an equation that has many practical applications. The power term in the nonlinear component of the source function and the Caputo-Fabrizio operator combine to make finding the solution space more difficult than the classical problem. We discovered a new technique, connecting Hilbert scale and L^p spaces, to overcome these difficulties. Evaluation of the smoothness of the solution was also performed. The research ideas in this paper can be used for many other models.

Keywords: Allen-Cahn equation, Fractional diffusion equation; Caputo-Fabrizio, regularity.

2010 MSC: 35R11, 35B65, 26A33

1. Introduction

Let \mathcal{D} be a \mathcal{C}^2 bounded open set of \mathbb{R}^N with sufficient smooth boundary and $T > 0$. In this paper, we consider the fractional Sobolev equation

$$\begin{cases} {}_{\text{CF}}D_t^\alpha u = \Delta u + u - u^3, & (x, t) \in \mathcal{D} \times (0, T), \\ u = 0, & (x, t) \in \partial\mathcal{D} \times (0, T), \\ u(x, 0) = u_0(x), & x \in \mathcal{D} \end{cases} \quad (1.1)$$

where ${}_{\text{CF}}D_t^\alpha$ is the Caputo-Fabrizio operator for fractional derivatives of order α which is defined as (see [24])

$${}_{\text{CF}}D_t^\alpha v(t) = \frac{H(\alpha)}{1-\alpha} \int_0^t \mathcal{D}_\alpha(t-s) \frac{\partial v(s)}{\partial s} ds, \quad \text{for } t \geq 0,$$

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Received : January 20, 2021; *Accepted:* August 13, 2021; *Online:* August 15, 2021.

where we denote by the kernel $\mathcal{D}_\alpha(z) = \exp\left(-\frac{\alpha}{1-\alpha}z\right)$ and $H(\alpha)$ satisfies $H(0) = H(1) = 1$, (see e.g. [22, 23]). The main goal of this note is to prove the existence of a local solution to the problem given the input data u_0 in the space L^p space. If $\alpha = 1$, Problem (1.1) is called Allen-Cahn equation with classical derivative. If we replace Caputo-Fabrizio derivative by Caputo derivative, Problem (1.1) is studied by [28]. Allen-Cahn model was originally introduced to transform the description of boundaries in coherent solids [29].

Fractional calculus has a long history and has many applications in simulations of physical phenomena or real life for example, mechanics, electricity, chemistry, biology,.. Many mathematical models cannot be expressed in terms of classical derivatives because of the effects of external forces. Therefore, the introduction of fractional calculus has important implications for modeling physical and engineering processes in cases where classical derivatives are not available. Some works are attracting the attention of the community for fractional differential equations, like A. Debbouche and his group [4, 5, 6], E. Karapinar et al [11, 12, 13, 14, 15, 16, 17, 18]. The Caputo-Fabrizio fractional derivative was first introduced by [22] which makes sense to avoid singular kernels. It is determined by the convolution of the exponential function and the first order derivative. This operator has been widely applied to a number of derivative modes in many fields, such as biology, physics, control systems [19, 20, 26].

There are two main challenges and difficulties when we consider this problem. The first difficulty is that it is difficult for us to apply the L^p estimate to the semigroup heat operators because of the appearance of the Caputo-Fabrizio operator. Indeed, in F. Weisler's work [27], they have the advantage of using the L^p evaluation for the half heat group where we do not apply. The second challenge is that we cannot evaluate the function u^p on Hilbert scale spaces but can only estimate on L^p while the Caputo-Fabrizio operator can only handle in Hilbert scale space. Those are the hard points that we need to overcome. Our novel idea is to connect the evaluations together by embeddings between L^p and Hilbert scales. This new technique can be applied to prove the existence of solutions to a wide range of problems.

2. Main results

Before giving the main result, we recall some knowledge about function spaces and embeddings. Note that $A = -\Delta$ is a symmetric uniformly elliptic operator, hence it possesses a non-negative, non-decreasing and discrete spectrum $0 < \lambda_1 \leq \lambda_2 \leq \dots \leq \lambda_n \nearrow \infty$. The corresponding eigenvectors of A are denoted by $e_n \in D(A)$, which satisfy $Ae_n(x) = \lambda_n e_n(x)$ for $x \in \mathcal{D}$. Let us introduce the Hilbert scale space, which is given as follows

$$\mathcal{H}^r(\mathcal{D}) = \left\{ f \in L^2(\mathcal{D}), \sum_{n=1}^{\infty} \lambda_n^{2r} \langle f, e_n \rangle_{L^2(\mathcal{D})}^2 < \infty \right\},$$

for any $r \geq 0$. Here the symbol $\langle \cdot, \cdot \rangle_{L^2(\mathcal{M})}$ denotes the inner product in $L^2(\mathcal{M})$. It is well-known that $\mathcal{H}^r(\mathcal{D})$ is a Hilbert space corresponding to the following norm

$$\|f\|_{\mathcal{H}^r(\mathcal{D})} = \sqrt{\sum_{n=1}^{\infty} \lambda_n^{2r} \langle f, e_n \rangle_{L^2(\mathcal{D})}^2}, \quad f \in \mathcal{H}^r(\mathcal{D}).$$

In view of $\mathcal{H}^r(\mathcal{D}) \equiv D((-\mathbb{A})^r)$ is a Hilbert space. Then $D((-\mathbb{A})^{-r})$ is a Hilbert space with the norm

$$\|v\|_{D((-\mathbb{A})^{-r})} = \left(\sum_{n=1}^{\infty} |\langle v, e_n \rangle|^2 \lambda_n^{-2r} \right)^{\frac{1}{2}},$$

where $\langle \cdot, \cdot \rangle$ in the latter equality denotes the duality between $D((-\mathbb{A})^{-r})$ and $D((-\mathbb{A})^r)$.

Lemma 1. *The following inclusions hold true:*

$$\left. \begin{aligned} L^p(\Omega) &\hookrightarrow D(\mathcal{A}^\sigma), & \text{if } & -\frac{N}{4} < \sigma \leq 0, & p &\geq \frac{2N}{N-4\sigma}, \\ D(\mathcal{A}^\sigma) &\hookrightarrow L^p(\Omega), & \text{if } & 0 \leq \sigma < \frac{N}{4}, & p &\leq \frac{2N}{N-4\sigma}. \end{aligned} \right\} \tag{2.1}$$

Definition 1. *The function v is called a mild solution of Problem (1.1) if it satisfies that*

$$v(t) = \mathbf{S}_\alpha(t)u_0 + \int_0^t \mathbf{S}_\alpha(t-s)G(v(s))ds \tag{2.2}$$

where $G(v) = v - v^3$ and $\mathbf{S}_\alpha(t)$ is defined by

$$\mathbf{S}_\alpha(t)f = (1 + \bar{\alpha}\lambda_n)^{-1} \exp\left(\frac{-\alpha\lambda_n}{1 + \bar{\alpha}\lambda_n}t\right) \langle f, e_n \rangle_{L^2(\mathcal{D})} e_n(x), \quad \bar{\alpha} = 1 - \alpha.$$

for any $w \in L^2(\mathcal{D})$.

Lemma 2. *Let $f \in H^{m-2}(\mathcal{D})$. Then*

$$\|\mathbf{S}_\alpha(t)f\|_{H^m(\mathcal{D})} \leq \frac{1}{1-\alpha} \|f\|_{H^{m-2}(\mathcal{D})}. \tag{2.3}$$

Proof. Using Parseval's equality, we get that

$$\begin{aligned} \|\mathbf{S}_\alpha(t)f\|_{H^m(\mathcal{D})} &= \left(\sum_{n=1}^\infty \lambda_n^m (1 + \bar{\alpha}\lambda_n)^{-2} \exp\left(\frac{-2\alpha\lambda_n}{1 + \bar{\alpha}\lambda_n}t\right) \langle f, e_n \rangle_{L^2(\mathcal{D})}^2 \right)^{1/2} \\ &\leq \frac{1}{\bar{\alpha}} \left(\sum_{n=1}^\infty \lambda_n^{m-2} \langle f, e_n \rangle_{L^2(\mathcal{D})}^2 \right)^{1/2} = \frac{1}{1-\alpha} \|f\|_{H^{m-2}(\mathcal{D})} \end{aligned} \tag{2.4}$$

□

Remark 1. The hardest part about proving the theorem is that we don't immediately get the L^p estimate for the operator $\mathbf{S}_\alpha(t)$. For classical problem, we are available for apply L^p estimate since the ideas of [27]. However, we face the operator $\mathbf{S}_\alpha(t)$ as above, we have difficulty things for considering L^p estimate. The second difficulty is that we cannot evaluate the source function on Hilbert scales space.

Theorem 1. *Let $u_0 \in L^{q/3}(\mathcal{D})$ where $2 \leq q \leq 6$ and $q \geq 2N$. Then problem (1.1) has a local mild solution $u \in \mathbf{X}_{\beta,q} \cap L^p(0, T; L^q(\mathcal{D}))$ where $0 < \beta < 1/3$ and $1 < p < \frac{1}{\beta}$.*

Remark 2. Since the assumption $2 \leq q \leq 6$ and $q \geq 2N$, we can see that $1 \leq N \leq 3$. Hence, we only study the local existence for the dimensional of the domain \mathcal{D} is about 1 to 3.

Proof. It is obvious to see that

$$|G(u) - G(v)| = |(u - v) - (u^3 - v^3)| \leq 2(|u - v|)(1 + |u|^2 + |v|^2). \tag{2.5}$$

Using Hölder inequality, we continue to get the following estimate

$$\begin{aligned} \|G(v_1) - G(v_2)\|_{L^{\frac{q}{3}}(\mathcal{D})} &= \left(\int_{\mathcal{D}} |G(v_1) - G(v_2)|^{\frac{q}{3}} dx \right)^{\frac{3}{q}} \\ &\leq 2 \left(\int_{\mathcal{D}} (|v_1 - v_2|)(|v_1 - v_2|^2 + |v_1 - v_2|^2)^{\frac{q}{3}} dx \right)^{\frac{3}{q}} \end{aligned}$$

$$\begin{aligned}
 &\leq 2 \left(\int_{\mathcal{D}} (|v_1 - v_2|^{\frac{q}{3}})^3 \right)^{\frac{1}{3} \frac{3}{q}} \left(\int_{\mathcal{D}} ((|v_1|^2 + |v_2|^2)^{\frac{q}{3}})^{\frac{3}{2}} \right)^{\frac{2}{3} \frac{3}{q}} \\
 &\leq 2 \|v_1 - v_2\|_{L^q(\mathcal{D})} \left[\left(\int_{\mathcal{D}} (|v_1|^q)^{\frac{2}{q}} + \int_{\mathcal{D}} (|v_2|^q)^{\frac{2}{q}} \right) \right] \\
 &= 2 \|v_1 - v_2\|_{L^q(\mathcal{D})} \left[\|v_1\|_{L^q(\mathcal{D})}^2 + \|v_2\|_{L^q(\mathcal{D})}^2 \right].
 \end{aligned} \tag{2.6}$$

Define the Banach space $\mathbf{X}_{\beta,q}$ of all Bochner integrable functions $u : [0, T] \rightarrow L^q(\mathcal{D})$ such that $t^\varepsilon u$ are bounded continuous functions, endowed with the norm

$$\sup_{0 \leq t \leq T} t^\beta \|u(t, \cdot)\|_{L^q(\mathcal{D})} < \infty.$$

Let the function J be as follows

$$Jv(t) = \mathbf{S}_\alpha(t)u_0 + \int_0^t \mathbf{S}_\alpha(t-s)G(v(s))ds. \tag{2.7}$$

Let $v, w \in \mathbf{X}_{\beta,q}$. Since Sobolev embedding $\mathcal{H}^{\frac{Nq-2N}{4q}}(\mathcal{D}) \hookrightarrow L^q(\mathcal{D})$ for any $q > 2$, we get that

$$\begin{aligned}
 \|Jv - Jw\|_{\mathbf{X}_{\beta,q}} &= \sup_{0 \leq t \leq T} t^\beta \|Jv(\cdot, t) - Jw(\cdot, t)\|_{L^q(\mathcal{D})} \\
 &\leq \sup_{0 \leq t \leq T} t^\beta \|Jv(\cdot, t) - Jw(\cdot, t)\|_{\mathcal{H}^{\frac{Nq-2N}{4q}}(\mathcal{D})}
 \end{aligned} \tag{2.8}$$

It is obvious to see that

$$\begin{aligned}
 &\left\| \int_0^t \mathbf{S}_\alpha(t-s)G(v(s))ds - \int_0^t \mathbf{S}_\alpha(t-s)G(w(s))ds \right\|_{\mathcal{H}^{\frac{Nq-2N}{4q}}(\mathcal{D})} \\
 &\leq \frac{1}{1-\alpha} \int_0^t \|G(v(s)) - G(w(s))\|_{\mathcal{H}^{\frac{Nq-2N}{4q}-2}(\mathcal{D})} ds \\
 &\leq C(N, q) \int_0^t \|G(v(s)) - G(w(s))\|_{\mathcal{H}^{\frac{Nq-6N}{4q}}(\mathcal{D})} ds
 \end{aligned} \tag{2.9}$$

where we note that

$$\mathcal{H}^{\frac{Nq-6N}{4q}}(\mathcal{D}) \hookrightarrow \mathcal{H}^{\frac{Nq-2N}{4q}-2}(\mathcal{D})$$

since the condition $q \geq 2N$.

Based on Sobolev embedding $L^{\frac{q}{3}}(\mathcal{D}) \hookrightarrow \mathcal{H}^{\frac{Nq-6N}{4q}}(\mathcal{D})$ for any $q < 6$, we derive that

$$\int_0^t \|G(v(s)) - G(w(s))\|_{\mathcal{H}^{\frac{Nq-6N}{4q}}(\mathcal{D})} ds \leq C(N, q) \int_0^t \|G(v(s)) - G(w(s))\|_{L^{\frac{q}{3}}(\mathcal{D})} ds \tag{2.10}$$

Set the following ball

$$B(R) := \left\{ w : [0, T] \rightarrow L^q(\mathcal{D}), \quad \|w\|_{\mathbf{X}_{\beta,q}} \leq R \right\} \tag{2.11}$$

If $v, w \in \mathbf{X}_{\beta,q}$ then we get

$$\|v(\cdot, s)\|_{L^q(\mathcal{D})} \leq s^{-\beta} \|v\|_{\mathbf{X}_{\beta,q}} \leq s^{-\beta} R. \tag{2.12}$$

In view of (2.6), we obtain

$$\int_0^t \|G(v(s)) - G(w(s))\|_{L^{\frac{q}{3}}(\mathcal{D})} ds$$

$$\begin{aligned}
 &\leq 2 \int_0^t \|v(\cdot, s) - w(\cdot, s)\|_{L^q(\mathcal{D})} \left[\|v(\cdot, s)\|_{L^q(\mathcal{D})}^2 + \|w(\cdot, s)\|_{L^q(\mathcal{D})}^2 \right] \\
 &\leq 4R^2 \int_0^t s^{-2\beta} \|v(\cdot, s) - w(\cdot, s)\|_{L^q(\mathcal{D})} ds \\
 &= 4R^2 \int_0^t s^{-3\beta} s^\beta \|v(\cdot, s) - w(\cdot, s)\|_{L^q(\mathcal{D})} ds \leq 4R^2 \left(\int_0^t s^{-3\beta} ds \right) \|v - w\|_{\mathbf{X}_{\beta,q}}
 \end{aligned} \tag{2.13}$$

Under the condition $\beta < 1/3$, we know that $\int_0^t s^{-3\beta} ds$ is convergent. So, we get that

$$\int_0^t \|G(v(s)) - G(w(s))\|_{L^{\frac{q}{3}}(\mathcal{D})} ds \leq 4R^2 \frac{t^{1-3\beta}}{1-3\beta} \|v - w\|_{\mathbf{X}_{\beta,q}}. \tag{2.14}$$

Combining (2.8), (2.9), (2.14), we arrive at

$$\begin{aligned}
 \|Jv - Jw\|_{\mathbf{X}_{\beta,q}} &\leq \left(\sup_{0 \leq t \leq T} t^{\beta+1-3\beta} \right) C(N, q) 4R^2 \frac{1}{1-3\beta} \|v - w\|_{\mathbf{X}_{\beta,q}} \\
 &\leq \frac{4C(N, q)R^2 T^{1-2\beta}}{1-3\beta} \|v - w\|_{\mathbf{X}_{\beta,q}}.
 \end{aligned} \tag{2.15}$$

Let us choose R, T such that

$$\frac{4C(N, q)R^2 T^{1-2\beta}}{1-3\beta} < 1/2.$$

We next evaluate

$$\|\mathbf{S}_\alpha u_0\|_{\mathbf{X}_{\beta,q}} = \sup_{0 \leq t \leq T} t^\beta \|\mathbf{S}_\alpha(t)u_0\|_{L^q(\mathcal{D})} \leq C(N, q) \sup_{0 \leq t \leq T} t^\beta \|\mathbf{S}_\alpha(t)u_0\|_{\mathcal{H}^{\frac{Nq-2N}{4q}}(\mathcal{D})}. \tag{2.16}$$

By looking back Lemma (2), we find that

$$\|\mathbf{S}_\alpha(t)u_0\|_{\mathcal{H}^{\frac{Nq-2N}{4q}}(\mathcal{D})} \leq \frac{1}{1-\alpha} \|u_0\|_{\mathcal{H}^{\frac{Nq-2N-8q}{4q}}(\mathcal{D})} \tag{2.17}$$

Since the condition $q \geq 2N$, we remind the Sobolev embedding

$$\mathcal{H}^{\frac{Nq-6N}{4q}}(\mathcal{D}) \hookrightarrow \mathcal{H}^{\frac{Nq-2N-8q}{4q}}(\mathcal{D})$$

. This allows us to provide that the following estimate

$$\|\mathbf{S}_\alpha u_0\|_{\mathbf{X}_{\beta,q}} \leq \frac{C(N, q)}{1-\alpha} \|u_0\|_{\mathcal{H}^{\frac{Nq-6N}{4q}}(\mathcal{D})} \tag{2.18}$$

The condition $q < 6$ give us the embedding

$$L^{\frac{q}{3}}(\mathcal{D}) \hookrightarrow \mathcal{H}^{\frac{Nq-6N}{4q}}(\mathcal{D})$$

which leads to

$$\|u_0\|_{\mathcal{H}^{\frac{Nq-6N}{4q}}(\mathcal{D})} \leq C(N, q) \|u_0\|_{L^{\frac{q}{3}}(\mathcal{D})} \tag{2.19}$$

Hence, we deduce that

$$\|J(\mathbf{0})\|_{\mathbf{X}_{\beta,q}} = \|\mathbf{S}_\alpha u_0\|_{\mathbf{X}_{\beta,q}} \leq T^\beta C(N, q) \|u_0\|_{L^{\frac{q}{3}}(\mathcal{D})}. \tag{2.20}$$

Let us choose T such that

$$T^\beta C(N, q) \|u_0\|_{L^{\frac{q}{3}}(\mathcal{D})} \leq \frac{R}{2}.$$

It follows from (2.15) that

$$\begin{aligned} \|Jv\|_{\mathbf{X}_{\beta, q}} &\leq \|Jv - J(\mathbf{0})\|_{\mathbf{X}_{\beta, q}} + \|J(\mathbf{0})\|_{\mathbf{X}_{\beta, q}} \\ &\leq \frac{1}{2} \|v\|_{\mathbf{X}_{\beta, q}} + T^\beta C(N, q) \|u_0\|_{L^{\frac{q}{3}}(\mathcal{D})} \end{aligned}$$

for any $v \in \mathbf{X}_{\beta, q}$. This says that

$$\|Jv\|_{\mathbf{X}_{\beta, q}} < R \quad (2.21)$$

which allows us to deduce that J is a mapping from $B(R)$ to itself $B(R)$. Using the Banach mapping theorem, we conclude that J have a fixed point u in $B(R)$.

Our aim is to investigate the regularity of the mild solution u . Indeed, we get

$$\|u\|_{\mathbf{X}_{\beta, q}} \leq \|Ju - J(\mathbf{0})\|_{\mathbf{X}_{\beta, q}} + \|J(\mathbf{0})\|_{\mathbf{X}_{\beta, q}} \leq \frac{1}{2} \|u\|_{\mathbf{X}_{\beta, q}} + T^\beta C(N, q) \|u_0\|_{L^{\frac{q}{3}}(\mathcal{D})}. \quad (2.22)$$

This implies that

$$\|u\|_{\mathbf{X}_{\beta, q}} \leq 2T^\beta C(N, q) \|u_0\|_{L^{\frac{q}{3}}(\mathcal{D})}.$$

Hence, we find that

$$\|u(\cdot, t)\|_{L^q(\mathcal{D})} \leq 2T^\beta t^{-\beta} C(N, q) \|u_0\|_{L^{\frac{q}{3}}(\mathcal{D})} \quad (2.23)$$

The above expression allows us to obtain that

$$\left(\int_0^T \|u(\cdot, t)\|_{L^q(\mathcal{D})}^p dt \right)^{1/p} \leq 2T^\beta C(N, q) \|u_0\|_{L^{\frac{q}{3}}(\mathcal{D})} \left(\int_0^T t^{-\beta p} dt \right)^{1/p} \quad (2.24)$$

Since $1 < p < \frac{1}{\beta}$, we deduce that the proper integral $\int_0^T t^{-\beta p} dt$ is convergent. Therefore, we can say that $u \in L^p(0, T; L^q(\mathcal{D}))$. □

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