

Conformal Hemi-Slant Riemannian Maps

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Abstract: In this study, we define conformal hemi-slant Riemannian maps from an almost Hermitian manifold to a Riemannian manifold as a generalization of conformal anti-invariant Riemannian maps, conformal semi-invariant Riemannian maps and conformal slant Riemannian maps. Then, we obtain integrability conditions for certain distributions which are included in the notion of hemi-slant Riemannian maps and investigate their leaves. Also, we get totally geodesic conditions for this type maps. Lastly, we introduce some geometric properties under the notion of pluri-harmonic map.

Keywords: Riemannian submersion, Riemannian map, conformal Riemannian map, conformal hemi-slant Riemannian map.

1. Introduction

Particularly, the concept of Riemannian submersions [6] and isometric immersions [5] were studied by Falcitelli and Chen. Then, Riemannian submersions were studied in various types as an antiinvariant, a semi-invariant, a slant and a hemi-slant [16]. Then, this concept generalized to the notion of Riemannian map by Fischer [7]. Riemannian maps between Riemannian manifolds are generalization of isometric immersions and Riemannian submersions. Let $\Phi: (M_1, g_1) \longrightarrow (M_2, g_2)$ be a smooth map between Riemannian manifolds such that $0 < \operatorname{rank} \Phi < \min\{\dim(M_1), \dim(M_2)\}$. Then, the tangent bundle TM_1 of M_1 has the following decomposition:

$$TM_1 = ker\Phi_* \oplus (ker\Phi_*)^{\perp}.$$

Since $rank\Phi < min\{dim(M_1), dim(M_2)\}$, always we have $(range\Phi_*)^{\perp}$. In this way, tangent bundle TM_2 of M_2 has the following decomposition:

$$TM_2 = (range\Phi_*) \oplus (range\Phi_*)^{\perp}.$$

A smooth map $\Phi: (M_1^m, g_1) \longrightarrow (M_2^n, g_2)$ is called Riemannian map at $p_1 \in M_1$ if the horizontal restriction $\Phi_{*p_1}^h: (ker\Phi_{*p_1})^{\perp} \longrightarrow (range\Phi_*)$ is a linear isometry. Hence, a Riemannian map

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satisfies the equation

$$g_1(X,Y) = g_2(\Phi_*(X), \Phi_*(Y))$$
(1)

for $X, Y \in \Gamma((ker\Phi_*)^{\perp})$. So that isometric immersions and Riemannian submersions are particular Riemannian maps, respectively, with $ker\Phi_* = \{0\}$ and $(range\Phi_*)^{\perp} = \{0\}$ [6]. An important application field of Riemannian maps is the eikonal equation. It acts as a bridge between geometric optics and physical optics. Also, Riemannian maps and their applications studied by Garcia-Rio and Kupeli in semi-Riemannian geometry [8].

Moreover, Şahin introduced any other types of Riemannian maps [13–16]. In further studies, in particular Akyol, Şahin and Yanan searched this type submersions [1–3] and Riemannian maps [18–21] under conformality case, see also [9]. We say that $\Phi : (M^m, g_M) \longrightarrow (N^n, g_N)$ is a conformal Riemannian map at $p \in M$ if $0 < rank \Phi_{*p} \leq min\{m, n\}$ and Φ_{*p} maps the horizontal space $(ker(\Phi_{*p})^{\perp})$ conformally onto $range(\Phi_{*p})$, i.e., there exist a number $\lambda^2(p) \neq 0$ such that

$$g_N(\Phi_{*p}(X), \Phi_{*p}(Y)) = \lambda^2(p)g_M(X, Y)$$

$$\tag{2}$$

for $X, Y \in \Gamma((ker(\Phi_{*p})^{\perp}))$. Also, Φ is called conformal Riemannian if Φ is conformal Riemannian at each $p \in M$ [17].

An even-dimensional Riemannian manifold (M, g_M, J) is called an almost Hermitian manifold if there exists a tensor field J of type (1,1) on M such that $J^2 = -I$ where I denotes the identity transformation of TM and

$$g_M(X,Y) = g_M(JX,JY), \forall X,Y \in \Gamma(TM).$$
(3)

Let (M, g_M, J) is an almost Hermitian manifold and its Levi-Civita connection is ∇ with respect to g_M . If J is parallel with respect to ∇ , i.e.,

$$(\nabla_X J)Y = 0,\tag{4}$$

we say M is a Kähler manifold [22].

Therefore, in Section 2; we present background concepts to be used in this paper. In Section 3; we study conformal hemi-slant Riemannian maps from almost Hermitian manifolds to Riemannian manifolds as a generalization of conformal semi-invariant Riemannian maps and conformal slant Riemannian maps. In Section 4; we use the concept of pluriharmonicity to introduce geometric properties.

2. Preliminaries

In this section, we give several definitions and results to be used throughout the study for conformal hemi-slant Riemannian maps. Let $\Phi: (M, g_M) \longrightarrow (N, g_N)$ be a smooth map between Riemannian

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manifolds. The second fundamental form of Φ is defined by

$$(\nabla\Phi_*)(X,Y) = \nabla^N_X \Phi_*(Y) - \Phi_*(\nabla^M_X Y)$$
(5)

for $X, Y \in \Gamma(TM)$. The second fundamental form $\nabla \Phi_*$ is symmetric [10].

Then, we define O'Neill's tensor fields \mathcal{T} and \mathcal{A} for Riemannian submersions as

$$\mathcal{A}_X Y = h_{\nabla_h X}^M v Y + v_{\nabla_h X}^M h Y, \tag{6}$$

$$\mathcal{T}_X Y = h \nabla_{vX} v Y + v \nabla_{vX} h Y \tag{7}$$

for $X, Y \in \Gamma(TM)$ with the Levi-Civita connection $\stackrel{M}{\nabla}$ of g_M [12]. As usual, we denote by v and h the projections on the vertical distribution $ker\Phi_*$ and the horizontal distribution $(ker\Phi_*)^{\perp}$, respectively. For any $X \in \Gamma(TM)$, \mathcal{T}_X and \mathcal{A}_X are skew-symmetric operators on $(\Gamma(TM), g)$ reversing the horizontal and the vertical distributions. Also, \mathcal{T} is vertical, $\mathcal{T}_X = \mathcal{T}_{vX}$, and \mathcal{A} is horizontal, $\mathcal{A}_X = \mathcal{A}_{hX}$. Note that the tensor field \mathcal{T} is symmetric on the vertical distribution [12]. Additionally, from (6) and (7) we have

$$\overset{M}{\nabla}_{U}V = \mathcal{T}_{U}V + \hat{\nabla}_{U}V, \qquad (8)$$

$$\nabla_U X = h \nabla_U X + \mathcal{T}_U X,$$
(9)

$$\overset{M}{\nabla}_{X}V = \mathcal{A}_{X}V + v\overset{M}{\nabla}_{X}V,$$
 (10)

for $X, Y \in \Gamma((\ker \Phi_*)^{\perp})$ and $U, V \in \Gamma(\ker \Phi_*)$, where $\hat{\nabla}_U V = v \nabla_U^M V$ [6].

If a vector field X on M is related to a vector field X' on N, we say X is a projectable vector field. If X is both a horizontal and a projectable vector field, we say X is a basic vector field on M. From now on, when we mention a horizontal vector field, we always consider a basic vector field [4].

On the other hand, let $\Phi: (M^m, g_M) \longrightarrow (N^n, g_N)$ be a conformal Riemannian map between Riemannian manifolds. Then, we have

$$(\nabla \Phi_*)(X,Y)|_{range\Phi_*} = X(\ln \lambda)\Phi_*(Y) + Y(\ln \lambda)\Phi_*(X)$$

- $g_M(X,Y)\Phi_*(grad(\ln \lambda)),$ (12)

where $X, Y \in \Gamma((ker\Phi_*)^{\perp})$. Hence from (12), we obtain $\nabla^N_X \Phi_*(Y)$ as

$$\nabla^{N}_{X} \Phi_{*}(Y) = \Phi_{*}(h^{M}_{\nabla X}Y) + X(\ln\lambda)\Phi_{*}(Y) + Y(\ln\lambda)\Phi_{*}(X)$$
$$- g_{M}(X,Y)\Phi_{*}(grad(\ln\lambda)) + (\nabla\Phi_{*})^{\perp}(X,Y),$$
(13)

where $(\nabla \Phi_*)^{\perp}(X,Y)$ is the component of $(\nabla \Phi_*)(X,Y)$ on $(range\Phi_*)^{\perp}$ for $X,Y \in \Gamma((ker\Phi_*)^{\perp})$ [18, 19].

Lastly, a map Φ from a complex manifold (M, g_M, J) to a Riemannian manifold (N, g_N) is a pluriharmonic map if Φ satisfies the following equation

$$(\nabla\Phi_*)(X,Y) + (\nabla\Phi_*)(JX,JY) = 0 \tag{14}$$

for $X, Y \in \Gamma(TM)$ [11].

3. Conformal Hemi-slant Riemannian Maps

We define conformal hemi-slant Riemannian maps from almost Hermitian manifolds and give some examples. We examine integrability and totally geodesicity conditions.

Definition 3.1 A conformal Riemannian map $\Phi : (M, g_M, J) \longrightarrow (N, g_N)$ is called a conformal hemi-slant Riemannian map if the vertical distribution $\ker \Phi_*$ of Φ admits two orthogonal complementary distributions \mathcal{D}_{θ} and \mathcal{D}_{\perp} such that \mathcal{D}_{θ} is slant and \mathcal{D}_{\perp} is anti-invariant, i.e., we have

$$ker\Phi_* = \mathcal{D}_\theta \oplus \mathcal{D}_\perp. \tag{15}$$

Hence, the angel θ is called the hemi-slant angle of the conformal Riemannian map.

Here, if we denote the dimension of \mathcal{D}_{θ} and \mathcal{D}_{\perp} by m_{θ} and m_{\perp} , respectively, then we get:

- i) If $m_{\theta} = 0$, then Φ is a conformal anti-invariant Riemannian map [18].
- ii) If $m_{\perp} = 0$ and $\theta = 0$, then Φ is a conformal invariant Riemannian map.
- iii) If $m_{\perp} = 0$ and $\theta \neq 0, \frac{\pi}{2}$, then Φ is a proper conformal slant Riemannian map [21].
- iv) If $\theta=\frac{\pi}{2},$ then Φ is a conformal anti-invariant Riemannian map.

Now, we give some examples for conformal hemi-slant Riemannian maps.

Example 3.2 Every conformal slant submersion [3] from an almost Hermitian manifold to a Riemannian manifold is a conformal hemi-slant Riemannian map with $\mathcal{D}_{\perp} = \{0\}$ and $(range \Phi_*)^{\perp} = \{0\}$.

Example 3.3 Every conformal hemi-slant submersion [9] from an almost Hermitian manifold to a Riemannian manifold is a conformal hemi-slant Riemannian map with $(range \Phi_*)^{\perp} = \{0\}$.

Example 3.4 Every conformal slant Riemannian map [21] from an almost Hermitian manifold to a Riemannian manifold is a conformal hemi-slant Riemannian map with $\mathcal{D}_{\perp} = \{0\}$.

Example 3.5 Every conformal semi-invariant submersion [2] from an almost Hermitian manifold to a Riemannian manifold is a conformal hemi-slant Riemannian map with $\theta = \frac{\pi}{2}$ and $(range \Phi_*)^{\perp} = \{0\}$.

Example 3.6 Every conformal semi-invariant Riemannian map [19] from an almost Hermitian manifold to a Riemannian manifold is a conformal hemi-slant Riemannian map with $\theta = \frac{\pi}{2}$.

If $\mathcal{D}_{\perp} \neq \{0\}$ and $\theta \neq 0, \frac{\pi}{2}$, then we say Φ is a proper conformal hemi-slant Riemannian map. Hence, we give an explicit example to proper case.

Example 3.7 Define a map $\Phi : \mathbb{R}^8 \longrightarrow \mathbb{R}^5$ by

$$\Phi(x_1, x_2, x_3, x_4, x_5, x_6, x_7, x_8) = e(x_2, x_3, \frac{x_6 + x_7}{\sqrt{2}}, x_8, 0)$$

with $\theta \in (0, \frac{\pi}{2})$. We obtain the horizontal distribution

$$(ker\Phi_*)^{\perp} = \{Z_1 = e\frac{\partial}{\partial x_2}, Z_2 = e\frac{\partial}{\partial x_3}, Z_3 = \frac{e}{\sqrt{2}}(\frac{\partial}{\partial x_6} + \frac{\partial}{\partial x_7}), Z_4 = e\frac{\partial}{\partial x_8}\}$$

and the vertical distribution

$$ker\Phi_*=\{W_1=\frac{\partial}{\partial x_1}, W_2=\frac{\partial}{\partial x_4}, W_3=\frac{\partial}{\partial x_5}, W_4=\frac{\partial}{\partial x_6}-\frac{\partial}{\partial x_7}\},$$

respectively. If the complex structure of \mathbb{R}^8 is $J = (-a_2, a_1, -a_4, a_3, -a_6, a_5, -a_8, a_7)$, we have

$$JW_1 = \frac{1}{e}Z_1, \quad JW_2 = -\frac{1}{e}Z_2, \quad JW_3 = \frac{\sqrt{2}}{2e}Z_3 + \frac{1}{2}W_4, \quad JW_4 = -\frac{1}{e}Z_4 - W_3.$$

Hence, we obtain $\mathcal{D}_{\perp} = span\{W_1, W_2\}$ and $\mathcal{D}_{\theta} = span\{W_3, W_4\}$. So, Φ is a proper conformal hemi-slant Riemannian map with slant angle $\theta = \frac{\pi}{4}$, $\lambda = e$ and $rank\Phi = 4$.

For any $W \in \Gamma(ker\Phi_*)$, we get

$$W = \tilde{P}W + \tilde{Q}W, \qquad (16)$$

where $\tilde{P}W \in \Gamma(\mathcal{D}_{\theta})$ and $\tilde{Q}W \in \Gamma(\mathcal{D}_{\perp})$, and have

$$JW = \phi W + \psi W,\tag{17}$$

where $\phi W \in \Gamma(ker\Phi_*)$ and $\psi W \in \Gamma((ker\Phi_*)^{\perp})$. Lastly, for $Z \in \Gamma((ker\Phi_*)^{\perp})$, we have

$$JZ = BZ + CZ,\tag{18}$$

where $BZ \in \Gamma(ker\Phi_*)$ and $CZ \in \Gamma((ker\Phi_*)^{\perp})$. Hence, we obtain decomposition of $(ker\Phi_*)^{\perp}$ as

$$(ker\Phi_*)^{\perp} = \psi \mathcal{D}_{\theta} \oplus J \mathcal{D}_{\perp} \oplus \mu, \tag{19}$$

where μ is the orthogonal complement of $\psi \mathcal{D}_{\theta} \oplus J \mathcal{D}_{\perp}$ and it is invariant under J. From equations (16)-(19), we obtain followings:

$$\phi \mathcal{D}_{\theta} = \mathcal{D}_{\theta}, \quad \phi \mathcal{D}_{\perp} = \{0\}, \quad B \psi \mathcal{D}_{\theta} = \mathcal{D}_{\theta}, \quad B J \mathcal{D}_{\perp} = \mathcal{D}_{\perp}$$
(20)

and

$$\phi^2 + B\psi = -I, \quad \psi\phi + C\psi = \{0\}, \quad \phi B + BC = \{0\}, \quad \psi B + C^2 = -I.$$
(21)

The proof of the next theorem is exactly same with hemi-slant submanifolds like hemi-slant Riemannian maps; see Theorem 3.6 of [15].

Theorem 3.8 Let Φ be a conformal Riemannian map from an almost Hermitian manifold (M, g_M, J) to a Riemannian manifold (N, g_N) . Then, Φ is a conformal hemi-slant Riemannian map if and only if there exists a constant $\lambda \in [0, 1]$ and a distribution \mathcal{D} on ker Φ_* such that

- *i*) $\mathcal{D} = \{ W \in \Gamma(ker\Phi_*) | \phi^2 W = \lambda W \},$
- ii) we have $\phi W = 0$, for any $W \in \Gamma(ker\Phi_*)$ orthogonal to \mathcal{D} .

Further, we have $\lambda = -\cos^2 \theta$ where θ is the slant angle of Φ .

The next expressions are easy to see their validity

$$g_M(\phi U_1, \phi U_2) = \cos^2 \theta g_M(U_1, U_2),$$
 (22)

$$g_M(\psi U_1, \psi U_2) = \sin^2 \theta g_M(U_1, U_2)$$
(23)

for any $U_1, U_2 \in \Gamma(\mathcal{D}_{\theta})$.

Now, we give some integrability conditions for leaf of the distributions.

Theorem 3.9 Let Φ be a conformal hemi-slant Riemannian map from a Kähler manifold (M, g_M, J) to a Riemannian manifold (N, g_N) . Then, the slant distribution \mathcal{D}_{θ} is integrable if and only if

$$\lambda^{2} \{ g_{M}(\mathcal{T}_{U_{1}}JV,\phi U_{2}) - g_{M}(\mathcal{T}_{U_{2}}JV,\phi U_{1}) \} = g_{N}(\nabla_{U_{2}}^{\Phi}\Phi_{*}(JV) + \Phi_{*}(\mathcal{A}_{JV}U_{2}),\Phi_{*}(\psi U_{1})) \\ - g_{N}(\nabla_{U_{1}}^{\Phi}\Phi_{*}(JV) + \Phi_{*}(\mathcal{A}_{JV}U_{1}),\Phi_{*}(\psi U_{2}))$$

for any $U_1, U_2 \in \Gamma(\mathcal{D}_{\theta})$ and $V \in \Gamma(\mathcal{D}_{\perp})$.

Proof Since g_M is the Kähler metric from (9) and (17), we get

$$g_M(\stackrel{M}{\nabla}_{U_1}U_2, V) = -g_M(\mathcal{T}_{U_1}JV, \phi U_2) - g_M(h\stackrel{M}{\nabla}_{U_1}JV, \psi U_2)$$
(24)

for any $U_1, U_2 \in \Gamma(\mathcal{D}_{\theta})$ and $V \in \Gamma(\mathcal{D}_{\perp})$. Now, using (5) and symmetry condition of $\nabla \Phi_*$, we get

$$\Phi_*(h^M_{\nabla U_1}JV) = \nabla^N_{U_1}\Phi_*(JV) + \Phi_*(\mathcal{A}_{JV}U_1).$$
(25)

Putting (25) in (24), we have

$$g_{M}(\stackrel{M}{\nabla}_{U_{1}}U_{2},V) = -g_{M}(\mathcal{T}_{U_{1}}JV,\phi U_{2}) - \frac{1}{\lambda^{2}}g_{N}(\stackrel{N}{\nabla}_{U_{1}}^{\Phi}\Phi_{*}(JV) + \Phi_{*}(\mathcal{A}_{JV}U_{1}),\Phi_{*}(\psi U_{2})).$$
(26)

Lastly, changing the roles of U_1 and U_2 in (26) we obtain the proof.

The integrability condition of \mathcal{D}_{\perp} is the same with Theorem 3.8 in [15]. Note that, always the distribution $ker\Phi_*$ is integrable. Then, we have the following.

Theorem 3.10 Let Φ be a conformal hemi-slant Riemannian map from a Kähler manifold (M, g_M, J) to a Riemannian manifold (N, g_N) . Then, the horizontal distribution $(\ker \Phi_*)^{\perp}$ is integrable if and only if

i)

$$g_{N}((\nabla \Phi_{*})(Z_{2}, BZ_{1}) - (\nabla \Phi_{*})(Z_{1}, BZ_{2}) + \nabla_{Z_{1}}^{\Phi} \Phi_{*}(CZ_{2}) - \nabla_{Z_{2}}^{\Phi} \Phi_{*}(CZ_{1}), \Phi_{*}(\psi U))$$

$$= \lambda^{2} \{g_{M}(v \nabla_{Z_{1}}^{M} BZ_{2} + \mathcal{A}_{Z_{1}}CZ_{2} - v \nabla_{Z_{2}}^{M} BZ_{1} - \mathcal{A}_{Z_{2}}CZ_{1}, \phi U)$$

$$-Z_{1}(\ln \lambda)g_{M}(CZ_{2}, \psi U) - CZ_{2}(\ln \lambda)g_{M}(Z_{1}, \psi U) + Z_{2}(\ln \lambda)g_{M}(CZ_{1}, \psi U)$$

$$+CZ_{1}(\ln \lambda)g_{M}(Z_{2}, \psi U) + \psi U(\ln \lambda)(g_{M}(Z_{1}, CZ_{2}) - g_{M}(Z_{2}, CZ_{1}))\},$$

ii) $\tilde{Q}\{B\{A_{Z_1}BZ_2 + h \nabla^M_{Z_1}CZ_2 - A_{Z_2}BZ_1 - h \nabla^M_{Z_2}CZ_1\}\} = 0$

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are provided for any $Z_1, Z_2 \in \Gamma((ker\Phi_*)^{\perp}), U \in \Gamma(\mathcal{D}_{\theta})$ and $V \in \Gamma(\mathcal{D}_{\perp})$.

Proof We search $g_M([Z_1, Z_2], U) = 0$ and $g_M([Z_1, Z_2], V) = 0$ for any $Z_1, Z_2 \in \Gamma((ker\Phi_*)^{\perp})$, $U \in \Gamma(\mathcal{D}_{\theta})$ and $V \in \Gamma(\mathcal{D}_{\perp})$. Firstly, using (10), (11) and (17), we get

$$g_{M}([Z_{1}, Z_{2}], U) = g_{M}(\mathcal{A}_{Z_{1}}BZ_{2} + h \nabla^{M}_{\nabla Z_{1}}CZ_{2} - \mathcal{A}_{Z_{2}}BZ_{1} - h \nabla^{M}_{\nabla Z_{2}}CZ_{1}, \psi U)$$

+
$$g_{M}(v \nabla^{M}_{Z_{1}}BZ_{2} + \mathcal{A}_{Z_{1}}CZ_{2} - v \nabla^{M}_{\nabla Z_{2}}BZ_{1} - \mathcal{A}_{Z_{2}}CZ_{1}, \phi U).$$
(27)

We have $(\nabla \Phi_*)(Z_1, BZ_2) = -\Phi_*(\mathcal{A}_{Z_1}BZ_2)$ from (5) and equality of $\Phi_*(h \nabla^M_{Z_1}CZ_2)$ from (13). In (27), we obtain

$$g_{M}([Z_{1}, Z_{2}], U) = \frac{1}{\lambda^{2}} g_{N}((\nabla \Phi_{*})(Z_{2}, BZ_{1}) - (\nabla \Phi_{*})(Z_{1}, BZ_{2}), \Phi_{*}(\psi U)) \\ + \frac{1}{\lambda^{2}} g_{N}(\nabla_{Z_{1}}^{\Phi} \Phi_{*}(CZ_{2}) - \nabla_{Z_{2}}^{\Phi} \Phi_{*}(CZ_{1}), \Phi_{*}(\psi U)) \\ - Z_{1}(\ln \lambda) g_{M}(CZ_{2}, \psi U) - CZ_{2}(\ln \lambda) g_{M}(Z_{1}, \psi U) \\ + \psi U(\ln \lambda) g_{M}(Z_{1}, CZ_{2}) + Z_{2}(\ln \lambda) g_{M}(CZ_{1}, \psi U) \\ + CZ_{1}(\ln \lambda) g_{M}(Z_{2}, \psi U) - \psi U(\ln \lambda) g_{M}(Z_{2}, CZ_{1}) \\ + g_{M}(v_{\nabla Z_{1}}^{M} BZ_{2} + \mathcal{A}_{Z_{1}}CZ_{2} - v_{\nabla Z_{2}}^{M} BZ_{1} - \mathcal{A}_{Z_{2}}CZ_{1}, \phi U).$$
(28)

We get (i) from (28). Now, for (10) and (11) we obtain

$$g_{M}([Z_{1}, Z_{2}], V) = -g_{M}(B\{\mathcal{A}_{Z_{1}}BZ_{2} + h \nabla^{M}_{Z_{1}}CZ_{2}\}, V)$$

+
$$g_{M}(B\{\mathcal{A}_{Z_{2}}BZ_{1} + h \nabla^{M}_{Z_{2}}CZ_{1}\}, V).$$
(29)

From (16) and (29), we get (ii).

In the rest of the section, we investigate totally geodesicity conditions on total manifold. Recall that Φ is said to be horizontally homothetic map if $h(grad(\ln \lambda)) = 0$ [4] and Φ is said to be totally geodesic map if $(\nabla \Phi_*)(E, F) = 0$ for all $E, F \in \Gamma(TM)$ [16].

Theorem 3.11 Let Φ be a conformal hemi-slant Riemannian map from a Kähler manifold (M, g_M, J) to a Riemannian manifold (N, g_N) . Then, any two conditions below imply the third condition;

- i) $ker\Phi_*$ defines a totally geodesic foliation on M,
- ii) Φ is a horizontally homothetic map,

iii)

$$\nabla^{N} \nabla^{\Phi}_{JW_{1}} \Phi_{*}(\psi W_{2}) = \Phi_{*}(J[JW_{1}, W_{2}]) + (\nabla \Phi_{*})^{\perp}(\psi W_{1}, \psi W_{2})$$

+ $\Phi_{*}(\mathcal{T}_{\phi W_{1}} \phi W_{2} + \mathcal{A}_{\psi W_{2}} \phi W_{1} + \mathcal{A}_{\psi W_{1}} \phi W_{2})$

for any $W_1, W_2 \in \Gamma(ker\Phi_*)$.

Proof Using equations (5) and (13), we get

$$\Phi_{*}(\stackrel{M}{\nabla}_{JW_{1}}JW_{2}) = \stackrel{N}{\nabla}^{\Phi}_{JW_{1}}\Phi_{*}(JW_{2}) - (\nabla\Phi_{*})(JW_{1},JW_{2})$$

$$= \stackrel{N}{\nabla}^{\Phi}_{JW_{1}}\Phi_{*}(\psi W_{2}) - \Phi_{*}(\mathcal{T}_{\phi W_{1}}\phi W_{2} + \mathcal{A}_{\psi W_{2}}\phi W_{1} + \mathcal{A}_{\psi W_{1}}\phi W_{2})$$

$$- \psi W_{1}(\ln\lambda)\Phi_{*}(\psi W_{2}) - \psi W_{2}(\ln\lambda)\Phi_{*}(\psi W_{1})$$

$$+ g_{M}(\psi W_{1},\psi W_{2})\Phi_{*}(grad(\ln\lambda)) - (\nabla\Phi_{*})^{\perp}(\psi W_{1},\psi W_{2})$$
(30)

for any $W_1, W_2 \in \Gamma(\ker \Phi_*)$. On the other hand, we get

$$\Phi_*(\stackrel{M}{\nabla}_{JW_1}JW_2) = \Phi_*(J[JW_1, W_2]) + J\stackrel{M}{\nabla}_{W_1}JW_2)$$
$$= \Phi_*(J[JW_1, W_2]) - \Phi_*(\stackrel{M}{\nabla}_{W_1}W_2).$$
(31)

Putting (31) in (30), we obtain

$$\Phi_{*}(\overset{M}{\nabla}_{W_{1}}W_{2}) = \Phi_{*}(J[JW_{1}, W_{2}]) - \nabla^{\Phi}_{JW_{1}}\Phi_{*}(\psi W_{2}) + \Phi_{*}(\mathcal{T}_{\phi W_{1}}\phi W_{2} + \mathcal{A}_{\psi W_{2}}\phi W_{1} + \mathcal{A}_{\psi W_{1}}\phi W_{2}) + \psi W_{1}(\ln\lambda)\Phi_{*}(\psi W_{2}) + \psi W_{2}(\ln\lambda)\Phi_{*}(\psi W_{1}) - g_{M}(\psi W_{1}, \psi W_{2})\Phi_{*}(grad(\ln\lambda)) + (\nabla\Phi_{*})^{\perp}(\psi W_{1}, \psi W_{2}).$$
(32)

Suppose that (i) and (ii) are provided in (32). Then, we have

$$\Phi_*(\stackrel{M}{\nabla}_{W_1}W_2) = 0$$

and

$$\psi W_1(\ln \lambda)\Phi_*(\psi W_2) + \psi W_2(\ln \lambda)\Phi_*(\psi W_1) - g_M(\psi W_1, \psi W_2)\Phi_*(grad(\ln \lambda)) = 0.$$

Hence, we obtain

$$0 = \Phi_{*}(J[JW_{1}, W_{2}]) - \nabla^{\Phi}_{JW_{1}} \Phi_{*}(\psi W_{2}) + (\nabla \Phi_{*})^{\perp}(\psi W_{1}, \psi W_{2}) + \Phi_{*}(\mathcal{T}_{\phi W_{1}} \phi W_{2} + \mathcal{A}_{\psi W_{2}} \phi W_{1} + \mathcal{A}_{\psi W_{1}} \phi W_{2}).$$
(33)

We get (iii) from (33). One can easily see that if (ii) and (iii) are provided in (32) we obtain $\Phi_*(\nabla_{W_1} W_2) = 0$. So, (i) is satisfied. Lastly, we proof (ii). Suppose that (i) and (iii) are provided in (32). Then, we obtain

$$0 = \psi W_1(\ln \lambda) \Phi_*(\psi W_2) + \psi W_2(\ln \lambda) \Phi_*(\psi W_1)$$

- $g_M(\psi W_1, \psi W_2) \Phi_*(grad(\ln \lambda)).$ (34)

For $\psi W_1 \in \Gamma((ker\Phi_*)^{\perp})$ in (34), we have

$$0 = \lambda^2 \psi W_2(\ln \lambda) g_M(\psi W_1, \psi W_1).$$

So, we obtain $\psi W_2(\ln \lambda) = 0$. It means λ is a constant on $(ker\Phi_*)^{\perp}$. Therefore, Φ is a horizontally homothetic map. The proof is complete.

In a similar way, we have the following.

Theorem 3.12 Let Φ be a conformal hemi-slant Riemannian map from a Kähler manifold (M, g_M, J) to a Riemannian manifold (N, g_N) . Then, any two conditions below imply the third condition;

- i) $(ker\Phi_*)^{\perp}$ defines a totally geodesic foliation on M,
- ii) Φ is a horizontally homothetic map,

iii)

$$\nabla^{\Phi}_{JZ_{1}} \Phi_{*}(CZ_{2}) = \Phi_{*}(J[Z_{1}, JZ_{2}]) - (\nabla \Phi_{*})^{\perp}(CZ_{1}, CZ_{2}) + \Phi_{*}(\mathcal{T}_{BZ_{1}}BZ_{2} + \mathcal{A}_{CZ_{1}}BZ_{2} + \mathcal{A}_{CZ_{2}}BZ_{1})$$

for any $Z_1, Z_2 \in \Gamma((ker\Phi_*)^{\perp})$.

Theorem 3.13 Let Φ be a conformal hemi-slant Riemannian map from a Kähler manifold (M, g_M, J) to a Riemannian manifold (N, g_N) . Then, the slant distribution \mathcal{D}_{θ} defines a totally geodesic foliation on M if and only if

$$\cos^2\theta \mathcal{T}_{U_1}U_2 = \mathcal{T}_{U_1}B\psi U_2$$

is provided for any $U_1, U_2 \in \Gamma(\mathcal{D}_{\theta})$.

Proof From definition of $\nabla \Phi_*$ and (17), we get

$$(\nabla \Phi_{*})(U_{1}, U_{2}) = \Phi_{*}(J^{M}_{\nabla U_{1}}JU_{2})$$

$$= \Phi_{*}(\overset{M}{\nabla}_{U_{1}}J\phi U_{2}) + \Phi_{*}(\overset{M}{\nabla}_{U_{1}}J\psi U_{2})$$

$$= \Phi_{*}(\overset{M}{\nabla}_{U_{1}}\phi^{2}U_{2} + \overset{M}{\nabla}_{U_{1}}\psi\phi U_{2}) + \Phi_{*}(\overset{M}{\nabla}_{U_{1}}B\psi U_{2} + \overset{M}{\nabla}_{U_{1}}C\psi U_{2})$$
(35)

for any $U_1, U_2 \in \Gamma(\mathcal{D}_{\theta})$. Now, from Theorem 3.8 and by using (20) in (34), we obtain

$$(\nabla \Phi_*)(U_1, U_2) = -\cos^2 \theta \Phi_*(\mathcal{T}_{U_1} U_2) + \Phi_*(\mathcal{T}_{U_1} B \psi U_2).$$
(36)

The proof is complete.

Theorem 3.14 Let Φ be a conformal hemi-slant Riemannian map from a Kähler manifold (M, g_M, J) to a Riemannian manifold (N, g_N) . Then, any two conditions below imply the third condition;

- i) \mathcal{D}_{\perp} defines a totally geodesic foliation on M,
- ii) λ is a constant on $J(\mathcal{D}_{\perp})$,

iii)
$$\nabla^{\Phi}_{JV_1} \Phi_*(JV_2) = (\nabla \Phi_*)^{\perp} (JV_1, JV_2) - \Phi_*(J[V_2, JV_1])$$

for any $V_1, V_2 \in \Gamma(\mathcal{D}_{\perp})$.

Proof From the definition of $\nabla \Phi_*$, we have

$$(\nabla \Phi_{*})(JV_{1}, JV_{2}) = \nabla^{N} \Phi_{JV_{1}} \Phi_{*}(JV_{2}) - \Phi_{*}(\nabla^{M}_{JV_{1}}JV_{2})$$

$$= \nabla^{N} \Phi_{JV_{1}} \Phi_{*}(JV_{2}) + \Phi_{*}(J[V_{2}, JV_{1}] - J\nabla^{M}_{V_{2}}JV_{1})$$

$$= \nabla^{\Phi}_{JV_{1}} \Phi_{*}(JV_{2}) + \Phi_{*}(J[V_{2}, JV_{1}]) + \Phi_{*}(\nabla^{M}_{V_{2}}V_{1})$$
(37)

for any $V_1, V_2 \in \Gamma(\mathcal{D}_1)$. Using (13) in (37), we obtain

$$\Phi_{*}(\overset{M}{\nabla}_{V_{2}}V_{1}) = -\overset{N}{\nabla}^{\Phi}_{JV_{1}}\Phi_{*}(JV_{2}) - \Phi_{*}(J[V_{2}, JV_{1}]) + JV_{1}(\ln\lambda)\Phi_{*}(JV_{2}) + JV_{2}(\ln\lambda)\Phi_{*}(JV_{1}) - g_{M}(JV_{1}, JV_{2})\Phi_{*}(grad(\ln\lambda)) + (\nabla\Phi_{*})^{\perp}(JV_{1}, JV_{2}).$$
(38)

Suppose that (i) and (iii) are satisfies in (38). So, we have

$$0 = \Phi_* \big(\stackrel{M}{\nabla}_{V_2} V_1 \big)$$

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and

$$0 = -\nabla^{\Phi}_{JV_1} \Phi_*(JV_2) - \Phi_*(J[V_2, JV_1]) + (\nabla \Phi_*)^{\perp}(JV_1, JV_2).$$

Therefore, we obtain from (38)

$$0 = JV_{1}(\ln \lambda)\Phi_{*}(JV_{2}) + JV_{2}(\ln \lambda)\Phi_{*}(JV_{1}) - g_{M}(JV_{1}, JV_{2})\Phi_{*}(grad(\ln \lambda)).$$
(39)

Now, we obtain from (39)

$$0 = \lambda^2 J V_2(\ln \lambda) g_M(J V_1, J V_1) \tag{40}$$

for any $V_1 \in \Gamma(\mathcal{D}_{\perp})$. So, we obtain $JV_2(\ln \lambda) = 0$. It means λ is a constant on $J(\mathcal{D}_{\perp})$. The proofs of (i) and (iii) are easy to see from (38).

Lastly, we present totally geodesicity of the map Φ .

Theorem 3.15 Let Φ be a conformal hemi-slant Riemannian map from a Kähler manifold (M, g_M, J) to a Riemannian manifold (N, g_N) . Then, the map Φ defines a totally geodesic foliation on M if and only if

i) Φ is a horizontally homothetic map,

ii)

$$\nabla^{N} \nabla^{\Phi}_{Z_{1}} \Phi_{*}(Z_{2}) = (\nabla \Phi_{*})^{\perp} (Z_{1}, Z_{2}) - \Phi_{*} (C\{\mathcal{A}_{Z_{1}}BZ_{2} + h \nabla^{M}_{Z_{1}}CZ_{2}\}) - \Phi_{*} (\psi\{v \nabla^{M}_{Z_{1}}BZ_{2} + \mathcal{A}_{Z_{1}}CZ_{2}\}),$$

iii)

$$\cos^{2}\theta \mathcal{T}_{W_{1}}\tilde{P}W_{2} = h^{M}_{\nabla W_{1}}\psi\phi\tilde{P}W_{2} + \psi\mathcal{T}_{W_{1}}(\psi\tilde{P}W_{2} + J\tilde{Q}W_{2})$$
$$+ Ch^{M}_{\nabla W_{1}}(\psi\tilde{P}W_{2} + J\tilde{Q}W_{2})$$

are provided for any $Z_1, Z_2 \in \Gamma((ker\Phi_*)^{\perp})$ and $W_1, W_2 \in \Gamma(ker\Phi_*)$.

Proof Because of rank condition of the conformal hemi-slant Riemannian map Φ , we have $(\nabla \Phi_*)(Z_1, Z_2) = (\nabla \Phi_*)^{\perp}(Z_1, Z_2) + (\nabla \Phi_*)^{\top}(Z_1, Z_2)$ for any $Z_1, Z_2 \in \Gamma((ker\Phi_*)^{\perp})$. We know that $(\nabla \Phi_*)^{\perp}(Z_1, Z_2) \in \Gamma((range\Phi_*)^{\perp})$ and $(\nabla \Phi_*)^{\top}(Z_1, Z_2) \in \Gamma(range\Phi_*)$, see (12) and (13). Using these equations, we obtain

$$(\nabla \Phi_*)(Z_1, Z_2) = \nabla^N \Phi_{Z_1} \Phi_*(Z_2) - \Phi_*(\nabla^M_{Z_1} Z_2).$$
(41)

Since $(\nabla \Phi_*)(Z_1, Z_2) = 0$,

$$0 = \nabla^{N} \nabla^{\Phi}_{Z_{1}} \Phi_{*}(Z_{2}) - (\nabla \Phi_{*})^{\perp}(Z_{1}, Z_{2}) + \Phi_{*}(C\mathcal{A}_{Z_{1}}BZ_{2} + \psi v \nabla^{M}_{Z_{1}}BZ_{2}) + \Phi_{*}(\psi \mathcal{A}_{Z_{1}}CZ_{2} + Ch^{M}_{\nabla Z_{1}}CZ_{2}) - Z_{1}(\ln \lambda)\Phi_{*}(Z_{2}) - Z_{2}(\ln \lambda)\Phi_{*}(Z_{1}) + g_{M}(Z_{1}, Z_{2})\Phi_{*}(grad(\ln \lambda)).$$
(42)

From (42), we have

$$\nabla^{\Phi}_{Z_{1}} \Phi_{*}(Z_{2}) = (\nabla \Phi_{*})^{\perp} (Z_{1}, Z_{2}) - \Phi_{*} (C\{\mathcal{A}_{Z_{1}}BZ_{2} + h \nabla^{M}_{Z_{1}}CZ_{2}\}) - \Phi_{*} (\psi\{v \nabla^{M}_{Z_{1}}BZ_{2} + \mathcal{A}_{Z_{1}}CZ_{2}\})$$
(43)

and

$$0 = Z_{1}(\ln \lambda)\Phi_{*}(Z_{2}) + Z_{2}(\ln \lambda)\Phi_{*}(Z_{1})$$

- $g_{M}(Z_{1}, Z_{2})\Phi_{*}(grad(\ln \lambda)).$ (44)

In (44), for any $Z_1 \in \Gamma((ker\Phi_*)^{\perp})$ we get

$$0 = \lambda^{2} Z_{1}(\ln \lambda) g_{M}(Z_{2}, Z_{1}) + \lambda^{2} Z_{2}(\ln \lambda) g_{M}(Z_{1}, Z_{1})$$

- $\lambda^{2} g_{M}(Z_{1}, Z_{2}) Z_{1}(\ln \lambda)$
= $\lambda^{2} Z_{2}(\ln \lambda) g_{M}(Z_{1}, Z_{1}).$ (45)

So, from (45) we obtain $Z_2(\ln \lambda) = 0$. It means Φ is a horizontally homothetic map. We obtain (ii) and (i) from (43) and (45), respectively. In a similar way, we get

$$(\nabla \Phi_{*})(W_{1}, W_{2}) = \Phi_{*}(J_{\nabla W_{1}}^{M} J \tilde{P} W_{2} + J \tilde{Q} W_{2})$$

$$= \Phi_{*}(\overset{M}{\nabla}_{W_{1}} \phi^{2} \tilde{P} W_{2} + \overset{M}{\nabla}_{W_{1}} \psi \phi \tilde{P} W_{2})$$

$$+ \Phi_{*}(\psi \mathcal{T}_{W_{1}} \psi \tilde{P} W_{2} + Ch \overset{M}{\nabla}_{W_{1}} \psi \tilde{P} W_{2})$$

$$+ \Phi_{*}(\psi \mathcal{T}_{W_{1}} J \tilde{Q} W_{2} + Ch \overset{M}{\nabla}_{W_{1}} J \tilde{Q} W_{2})$$

$$= -\cos^{2} \theta \Phi_{*}(\mathcal{T}_{W_{1}} \tilde{P} W_{2}) + \Phi_{*}(h \overset{M}{\nabla}_{W_{1}} \psi \phi \tilde{P} W_{2})$$

$$+ \Phi_{*}(\psi \mathcal{T}_{W_{1}}(\psi \tilde{P} W_{2} + J \tilde{Q} W_{2}))$$

$$+ \Phi_{*}(Ch \overset{M}{\nabla}_{W_{1}}(\psi \tilde{P} W_{2} + J \tilde{Q} W_{2})) \qquad (46)$$

for any $W_1, W_2 \in \Gamma(ker\Phi_*)$. We obtain (iii) from (46). The proof is complete.

4. Pluriharmonic Conformal Hemi-slant Riemannian Maps

In this section, we use the notion of pluriharmonic map on the distributions of a conformal hemislant Riemannian map to introduce their geometric properties. Φ is said to be \mathcal{D}_{θ} -pluriharmonic map $(\mathcal{D}_{\perp}, ker\Phi_{*}, (ker\Phi_{*})^{\perp})$ or *mixed*-pluriharmonic, respectively) if

$$(\nabla \Phi_*)(E,F) + (\nabla \Phi_*)(JE,JF) = 0$$

for $E, F \in \Gamma(\mathcal{D}_{\theta})$ $(\mathcal{D}_{\perp}, ker\Phi_{\star}, (ker\Phi_{\star})^{\perp}$ or $(ker\Phi_{\star})^{\perp} \times ker\Phi_{\star}$, respectively) [19].

Theorem 4.1 Let Φ be a conformal hemi-slant Riemannian map from a Kähler manifold (M, g_M, J) to a Riemannian manifold (N, g_N) . Then, any two conditions below imply the third condition;

- i) Φ is a \mathcal{D}_{θ} -pluriharmonic map,
- ii) λ is a constant on $\psi(\mathcal{D}_{\theta})$ and $(\nabla \Phi_*)^{\perp}(\psi U_1, \psi U_2) = 0$,
- *iii)* $\sin^2 \theta \mathcal{T}_{U_1} U_2 + \mathcal{A}_{\psi U_2} \phi U_1 + \mathcal{A}_{\psi U_1} \phi U_2 = 0$

for any $U_1, U_2 \in \Gamma(\mathcal{D}_{\theta})$.

Proof Using definition of \mathcal{D}_{θ} -pluriharmonic map and symmetry condition of $\nabla \Phi_*$, we get

$$0 = (\nabla \Phi_{*})(U_{1}, U_{2}) + (\nabla \Phi_{*})(\phi U_{1}, \phi U_{2}) + (\nabla \Phi_{*})(\psi U_{2}, \phi U_{1}) + (\nabla \Phi_{*})(\psi U_{1}, \phi U_{2}) + (\nabla \Phi_{*})(\psi U_{1}, \psi U_{2})$$
(47)

for any $U_1, U_2 \in \Gamma(\mathcal{D}_{\theta})$. From Theorem 3.8 and (12), we obtain

$$0 = -\sin^{2}\theta \Phi_{*}(\mathcal{T}_{U_{1}}U_{2}) - \Phi_{*}(\mathcal{A}_{\psi U_{2}}\phi U_{1} + \mathcal{A}_{\psi U_{1}}\phi U_{2}) + \psi U_{1}(\ln \lambda) \Phi_{*}(\psi U_{2}) + \psi U_{2}(\ln \lambda) \Phi_{*}(\psi U_{1}) - g_{M}(\psi U_{1}, \psi U_{2}) \Phi_{*}(grad(\ln \lambda)) - (\nabla \Phi_{*})^{\perp}(\psi U_{1}, \psi U_{2}).$$
(48)

Now, suppose that (i) and (ii) are provided in (48). So, we have

$$(\nabla \Phi_*)(U_1, U_2) + (\nabla \Phi_*)(JU_1, JU_2) = 0,$$

$$\psi U_1(\ln \lambda) \Phi_*(\psi U_2) + \psi U_2(\ln \lambda) \Phi_*(\psi U_1) - g_M(\psi U_1, \psi U_2) \Phi_*(grad(\ln \lambda)) = 0$$

and

$$(\nabla \Phi_*)^{\perp}(\psi U_1, \psi U_2) = 0,$$

respectively. Hence, we easily obtain (iii) from (48). If we suppose that (ii) and (iii) are provided in (48), we obtain (i) from (47) such that Φ is a \mathcal{D}_{θ} -pluriharmonic map. Lastly, we suppose that (i) and (iii) are provided in (48), we get

$$0 = \psi U_{1}(\ln \lambda) \Phi_{*}(\psi U_{2}) + \psi U_{2}(\ln \lambda) \Phi_{*}(\psi U_{1}) - g_{M}(\psi U_{1}, \psi U_{2}) \Phi_{*}(grad(\ln \lambda)) - (\nabla \Phi_{*})^{\perp}(\psi U_{1}, \psi U_{2}).$$
(49)

We obtain $(\nabla \Phi_*)^{\perp}(\psi U_1, \psi U_2) = 0$ from (49). For any $\psi U_1 \in \Gamma(\psi(\mathcal{D}_\theta))$, we obtain

$$0 = \lambda^2 \psi U_2(\ln \lambda) g_M(\psi U_1, \psi U_1).$$
(50)

So, from (50) we get $\psi U_2(\ln \lambda) = 0$. It means λ is a constant on $\psi(\mathcal{D}_{\theta})$. (ii) is provided. The proof is all.

Similarly, we have the following theorems.

Theorem 4.2 Let Φ be a conformal hemi-slant Riemannian map from a Kähler manifold (M, g_M, J) to a Riemannian manifold (N, g_N) . Then, any two conditions below imply the third condition;

- i) \mathcal{D}_{\perp} defines a totally geodesic foliation on M,
- ii) Φ is a \mathcal{D}_{\perp} -pluriharmonic map,
- iii) λ is a constant on $J(\mathcal{D}_{\perp})$ and $(\nabla \Phi_*)^{\perp}(JV_1, JV_2) = 0$

for any $V_1, V_2 \in \Gamma(\mathcal{D}_{\perp})$.

Note that \mathcal{D}_{\perp} -pluriharmonic map and $J(\mathcal{D}_{\perp})$ -pluriharmonic map give same results for a conformal hemi-slant Riemannian map. Since \mathcal{D}_{\perp} is an anti-invariant distribution, we obtain the result from the definition of pluriharmonic map.

Theorem 4.3 Let Φ be a conformal hemi-slant Riemannian map from a Kähler manifold (M, g_M, J) to a Riemannian manifold (N, g_N) . Then, any two conditions below imply the third condition;

- i) Φ is a ker Φ_* -pluriharmonic map,
- ii) Φ is a horizontally homothetic map and $(\nabla \Phi_*)^{\perp}(\psi W_1, \psi W_2) = 0$,
- *iii)* $\sin^2 \theta \mathcal{T}_{W_1} W_2 = \mathcal{A}_{\psi W_2} \phi W_1 + \mathcal{A}_{\psi W_1} \phi W_2$

for any $W_1, W_2 \in \Gamma(ker\Phi_*)$.

Theorem 4.4 Let Φ be a conformal hemi-slant Riemannian map from a Kähler manifold (M, g_M, J) to a Riemannian manifold (N, g_N) . Then, any three conditions below imply the fourth condition;

- i) $(ker\Phi_*)^{\perp}$ defines a totally geodesic foliation on M,
- *ii)* Φ *is a* $(ker\Phi_*)^{\perp}$ *-pluriharmonic map,*
- iii) Φ is a horizontally homothetic map,

iv)
$$\nabla^{\Phi}_{Z_1} \Phi_*(Z_2) = \Phi_*(\mathcal{T}_{BZ_1}BZ_2 + \mathcal{A}_{CZ_1}BZ_2 + \mathcal{A}_{CZ_2}BZ_1) + (\nabla\Phi_*)^{\perp}(CZ_1, CZ_2)$$

for any $Z_1, Z_2 \in \Gamma((ker\Phi_*)^{\perp})$.

Theorem 4.5 Let Φ be a conformal hemi-slant Riemannian map from a Kähler manifold (M, g_M, J) to a Riemannian manifold (N, g_N) . Then, any two conditions below imply the third condition;

- i) Φ is a mixed-pluriharmonic map,
- ii) Φ is a horizontally homothetic map and $(\nabla \Phi_*)^{\perp}(CZ, \psi W) = 0$,
- *iii)* $A_ZW + T_{BZ}\phi W + A_{\psi W}BZ + A_{CZ}\phi W = 0$
- for any $Z \in \Gamma((ker\Phi_*)^{\perp})$ and $W \in \Gamma(ker\Phi_*)$.

Proof From definition of *mixed*-pluriharmonic map, we obtain

$$0 = -\Phi_*(\mathcal{A}_Z W) + (\nabla \Phi_*)^{\perp}(CZ, \psi W)$$

- $\Phi_*(\mathcal{T}_{BZ}\phi W + \mathcal{A}_{\psi W}BZ + \mathcal{A}_{CZ}\phi W)$
+ $CZ(\ln \lambda)\Phi_*(\psi W) + \psi W(\ln \lambda)\Phi_*(CZ)$
- $g_M(CZ, \psi W)\Phi_*(grad(\ln \lambda))$ (51)

for any $Z \in \Gamma((ker\Phi_*)^{\perp})$ and $W \in \Gamma(ker\Phi_*)$. Now, we only proof (ii). Suppose that (i) and (iii) are provided in (51). We obtain easily $(\nabla \Phi_*)^{\perp}(CZ, \psi W) = 0$ and get

$$0 = \lambda^2 \psi W(\ln \lambda) g_M(CZ, CZ) \tag{52}$$

for $CZ \in \Gamma((ker\Phi_*)^{\perp})$ and

$$0 = \lambda^2 C Z(\ln \lambda) g_M(\psi W, \psi W) \tag{53}$$

for $\psi W \in \Gamma((\ker \Phi_*)^{\perp})$. So, we have $\psi W(\ln \lambda) = 0$ and $CZ(\ln \lambda) = 0$ from (52) and (53), respectively. They means λ is a constant on horizontal distribution. Hence, Φ is a horizontally homothetic map. (ii) is provided.

Declaration of Ethical Standards

The author declares that the materials and methods used in their study do not require ethical committee and/or legal special permission.

Conflict of Interest

The author declares no conflicts of interest.

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