Advances in the Theory of Nonlinear Analysis and its Applications 6 (2022) No. 3, 339–346. https://doi.org/10.31197/atnaa.1061019 Available online at www.atnaa.org Research Article



# Properties of Certain Volterra type ABC Fractional Integral Equations

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# Abstract

In this paper we study existence, uniqueness and other properties of solutions of Volterra type ABC fractional integral equations. We have used Banach fixed point theorem with Bielecki type norm and Gronwall inequality in the frame of ABC fractional integral for proving our results.

*Keywords:* Volterra Equation ABC fractional Existence fractional Gronwall inequality. 2010 MSC: 34A08, 58C30, 34K37.

# 1. Introduction

During last few decades many authors have studied the fractional differential and integral equations and its properties by using various techniques. Due to wide applications of fractional calculus in various fields its study has become very interesting [4, 21]. In this paper we consider the Volterra fractional integral equation of the form

$$x(t) = \mathfrak{f}(t, x(t), \ _{a}^{AB} I^{\alpha} k\left(t, \tau, x\left(\tau\right)\right), \tag{1.1}$$

for  $0 < \alpha < 1$ , where  $I = [a, b], k \in C(I \times I \times \mathbb{R}, \mathbb{R})$  and  $\mathfrak{f} \in C(I \times \mathbb{R} \times \mathbb{R} \times \mathbb{R}, \mathbb{R})$ .

Gronwall inequality plays very important role in studying the various properties such as estimates of solution, continuous dependence and others of differential equation. Recently in [6, 25, 27] the authors have obtained the fractional Gronwall inequality using various fractional definition. Fractional calculus is found to be very interesting in modeling the real world situations. Due to the application of fractional calculus various

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definitions of fractional derivative and integral are obtained in the literature such as Generelized fractional derivative and integral with respect to another function that is  $\psi$  fractional, Hadmard, Katungampola, Caputo-Fabrizio, Hilfer and others [5, 9, 11, 15, 17]. Recently Atangana and Balaneu has introduced the new definitions of fractional integral and derivative with Mittag-Lefler function [2]. Using these definitions results on Taylors theorem existence, uniqueness and numerical solution have been obtained in [1, 3, 7, 8, 13, 14, 16, 20, 23]. In [12, 18, 19, 24, 26] authors have given various application of fractional calculus using these definitions.

. Motivated by the above mentioned research work the main objective of this paper is to study the fundamental properties of solutions of (1.1). The well known Banach fixed point theorem with Bielecki type norm and Gronwall type inequality given in [10] is used for presenting the results.

#### 2. Preliminaries

Now in this we give some basic definitions and lemmas used in our discussions The left Riemann-Liouville fractional integral of order  $\alpha$  for  $\alpha > 0$  is defined as [15]:

$$\left({}_{a}I^{\alpha}x\right)\left(t\right) = \frac{1}{\Gamma\left(\alpha\right)}\int\limits_{a}^{t}\left(t-s\right)^{\alpha-1}x\left(s\right)ds.$$

The Atagana-Baleanu fractional derivative and integral is defined as follows:

**Definition 2.1.** [2] Let  $x \in H^1(a, b)$ , a < b and  $\alpha$  in [0, 1]. The Caputo Atangana-Baleanu(ABC) fractional derivative of x of order  $\alpha$  is defined by

$$\begin{pmatrix} ABC\\ a \end{pmatrix} (t) = \frac{B(\alpha)}{1-\alpha} \int_{a}^{t} x'(s) E_{\alpha} \left[ -\alpha \frac{(t-s)^{\alpha}}{1-\alpha} \right] ds,$$

where  $E_{\alpha}$  is the Mittag-Leffler function defined by  $E_{\alpha}(z) = \sum_{n=0}^{\infty} \frac{z^n}{\Gamma(n\alpha+1)}$  and  $B(\alpha)$  is a normalizing positive function satisfying B(0) = B(1) = 1.

The Riemann Atangana-Baleanu fractional derivative of x of order  $\alpha$  is defined by

$$\begin{pmatrix} ABR\\ a \end{pmatrix} D^{\alpha} x \end{pmatrix} (t) = \frac{B(\alpha)}{1-\alpha} \int_{a}^{t} x(s) E_{\alpha} \left[ -\alpha \frac{(t-s)^{\alpha}}{1-\alpha} \right] ds.$$

The associated fractional integral is defined by:

$$\binom{AB}{a}I^{\alpha}x (t) = \frac{1-\alpha}{B(\alpha)}x(t) + \frac{\alpha}{B(\alpha)}\left( \left(_{a}I^{\alpha}x\right)(t)\right).$$

where  $_{a}I^{\alpha}$  is the left Riemann-Liouville fractional integral.

Now we construct the appropriate metric space. Let  $\xi > 0$  be a constant and consider the space of all continuous function  $C(I, \mathbb{R})$  where I = [a, b]. We denote this special space by  $C_{\xi,\alpha}(I, \mathbb{R})$ 

$$d_{\xi,\alpha}(u,v) = \begin{array}{c} Sup \\ t \in I \end{array} \frac{|u(t) - v(t)|}{E_{\alpha}\left(\xi\left(t-a\right)^{\alpha}\right)}$$

with norm defined by

$$\left|u\right|_{\xi,\alpha} = \sup_{t\in I} \frac{\left|u(t)\right|}{E_{\alpha}\left(\xi\left(t-a\right)^{\alpha}\right)},$$

where  $E_{\alpha} : \mathbb{R} \to \mathbb{R}$  is a one parameter Mittag-Leffler function. The above definitions  $d_{\xi,\alpha}$  and  $|.|_{\xi,\alpha}$  are the variants of Bielecki's metric and norm.

The Gronwall inequality in the frame of fractional integrals associated with the Atangana-Baleanu fractional derivative is given in [10] as follows: **Theorem 2.1.** [10] Suppose that  $\alpha > 0$ ,  $c(t) \left(1 - \frac{1-\alpha}{B(\alpha)}d(t)\right)^{-1}$  is nonnegative, nondecreasing and locally integrable function on [a, b),  $\frac{\alpha d(t)}{B(\alpha)} \left(1 - \frac{1-\alpha}{B(\alpha)}d(t)\right)^{-1}$  is nonnegative and bounded on [a, b) and x(t) is nonnegative and locally integrable on [a, b) with

$$x(t) \le c(t) + d(t) \begin{pmatrix} AB \\ a \end{bmatrix} I^{\alpha} x (t)$$

Then

$$x\left(t\right) \leq \frac{c\left(t\right)B\left(\alpha\right)}{B\left(\alpha\right) - \left(1 - \alpha\right)d\left(t\right)} E_{\alpha}\left(\frac{\alpha d\left(t\right)\left(t - a\right)^{\alpha}}{B\left(\alpha\right) - \left(1 - \alpha\right)d\left(t\right)}\right).$$

## 3. Existence of Solution

Now we give our result on the existence of solution of (1.1)

**Theorem 3.1.** Let  $P > 0, Q \ge 0, \xi > 1$  be constants. Suppose that the functions  $\mathfrak{f}, k$  in (1.1) satisfy the conditions

$$|\mathfrak{f}(t,u,v) - \mathfrak{f}(t,\overline{u},\overline{v})| \le Q \left[ |u - \overline{u}| + |v - \overline{v}| \right],\tag{3.1}$$

$$|k(t, s, u) - k(t, s, \overline{u})| \le P |u - \overline{u}|$$
(3.2)

and

$$m_{1} = \sup_{t \in I} \frac{1}{E_{\alpha} \left(\xi \left(t-a\right)^{\alpha}\right)} \left| f\left(t, 0, {}^{AB}_{a} I^{\alpha} k\left(t, s, 0\right)\right) \right| < \infty.$$
(3.3)

If  $Q\left(1+\frac{P}{\xi}\right) < 1$  then the integral equation (1.1) has a unique solution  $x \in C_{\xi,\alpha}(I,\mathbb{R})$ 

**Proof.** Consider the equivalent formulation of (1.1) we have

$$x(t) = \mathfrak{f}\left(t, x(t), {}_{a}^{AB}I^{\alpha}k(t, \tau, x(\tau))\right) - \mathfrak{f}\left(t, 0, {}_{a}^{AB}I^{\alpha}k(t, \tau, 0)\right) + \mathfrak{f}\left(t, 0, {}_{a}^{AB}I^{\alpha}k(t, \tau, 0)\right),$$

$$(3.4)$$

for  $t \in I$ . We shall show that (3.4) has unique solution and thus (1.1) must also have unique solution. Let  $x \in C_{\xi,\alpha}(I,\mathbb{R})$  and define the operator  $\mathfrak{T}$  by

$$(\mathfrak{T}x)(t) = \mathfrak{f}\left(t, x(t), {}^{AB}_{a}I^{\alpha}k(t, \tau, x(\tau))\right) - \mathfrak{f}\left(t, 0, {}^{AB}_{a}I^{\alpha}k(t, \tau, 0)\right) + \mathfrak{f}\left(t, 0, {}^{AB}_{a}I^{\alpha}k(t, \tau, 0)\right).$$

$$(3.5)$$

Now we show that  $\mathfrak{T}$  maps  $C_{\xi,\alpha}(I,\mathbb{R})$  into itself. We have

$$\begin{split} |\mathfrak{T}x|_{\xi,\alpha} &= \sup_{t\in I} \frac{|(\mathfrak{T}x)(t)|}{E_{\alpha}\left(\xi\left(t-a\right)^{\alpha}\right)} \\ &\leq \sup_{t\in I} \frac{1}{E_{\alpha}\left(\xi\left(t-a\right)^{\alpha}\right)} \left| \mathfrak{f}\left(t,x\left(t\right),_{a}^{AB}I^{\alpha}k\left(t,\tau,x(\tau)\right)\right) \right| \\ &- \mathfrak{f}\left(t,0,_{a}^{AB}I^{\alpha}k\left(t,\tau,0\right)\right) \right| + \sup_{t\in I} \frac{1}{E_{\alpha}\left(\xi\left(t-a\right)^{\alpha}\right)} \left| \mathfrak{f}\left(t,0,_{a}^{AB}I^{\alpha}k\left(t,\tau,0\right)\right) \right| \\ &\leq m_{1} + \sup_{t\in I} \frac{1}{E_{\alpha}\left(\xi\left(t-a\right)^{\alpha}\right)} Q\left[ |x\left(t\right)| + _{a}^{AB}I^{\alpha}P \left|x\left(\tau\right)| \right] \\ &= m_{1} + Q\left[ \sup_{t\in I} \frac{|x\left(t\right)|}{E_{\alpha}\left(\xi\left(t-a\right)^{\alpha}\right)} \\ &+ P \sup_{t\in I} \frac{1}{E_{\alpha}\left(\xi\left(t-a\right)^{\alpha}\right)} _{a}^{AB}I^{\alpha}E_{\alpha}\left(\xi\left(t-a\right)^{\alpha}\right) \frac{|x\left(\tau\right)|}{E_{\alpha}\left(\xi\left(t-a\right)^{\alpha}\right)} \right] \end{split}$$

$$\leq m_{1} + Q \left[ |x|_{\xi,\alpha} + P |x|_{\xi,\alpha} \sup_{t \in I} \frac{1}{E_{\alpha} \left(\xi \left(t-a\right)^{\alpha}\right)^{a}} A^{B} I^{\alpha} E_{\alpha} \left(\xi \left(t-a\right)^{\alpha}\right) \right) \right]$$

$$\leq m_{1} + Q \left[ |x|_{\xi,\alpha} + P |x|_{\xi,\alpha} \sup_{t \in I} \frac{1}{E_{\alpha} \left(\xi \left(t-a\right)^{\alpha}\right)} \left( \frac{\left(1-\alpha\right)}{B\left(\alpha\right)} E_{\alpha} \left(\xi \left(t-a\right)^{\alpha}\right) + \frac{\alpha}{B\left(\alpha\right)} a^{I} E_{\alpha} \left(\xi \left(t-a\right)^{\alpha}\right) \right) \right) \right]$$

$$\leq m_{1} + Q \left[ |x|_{\xi,\alpha} + P |x|_{\xi,\alpha} \sup_{t \in I} \frac{1}{E_{\alpha} \left(\xi \left(t-a\right)^{\alpha}\right)} \left( \frac{\left(1-\alpha\right)}{B\left(\alpha\right)} E_{\alpha} \left(\xi \left(t-a\right)^{\alpha}\right) + \frac{\alpha}{B\left(\alpha\right)} \frac{E_{\alpha} \left(\xi \left(t-a\right)^{\alpha}\right) - 1}{\xi} \right) \right] \right]$$

$$\leq m_{1} + Q \left| x|_{\xi,\alpha} \left[ 1 + P \frac{1}{B\left(\alpha\right)} \left( \left(1-\alpha\right) + \frac{\alpha}{\xi} \right) \right]. \tag{3.6}$$

Now we show that the operator  $\mathfrak{T}$  is a contraction map. Let  $v, w \in C_{\xi,\alpha}(I,\mathbb{R})$ , from the hypotheses we have

$$\begin{aligned} d_{\xi,\alpha} \left( \mathfrak{T}v, \mathfrak{T}w \right) &= \sup_{t \in I} \frac{\left| (\mathfrak{T}v) \left( t \right) - (\mathfrak{T}w) \left( t \right) \right|}{E_{\alpha} \left( \xi \left( t - a \right)^{\alpha} \right)} \\ &= \sup_{t \in I} \frac{1}{E_{\alpha} \left( \xi \left( t - a \right)^{\alpha} \right)} \left| f \left( t, v \left( t \right), {}_{a}^{AB} I^{\alpha} k \left( t, \tau, v \left( \tau \right) \right) \right) \right) \\ &- f \left( t, w \left( t \right), {}_{a}^{AB} I^{\alpha} k \left( t, \tau, w \left( \tau \right) \right) \right) \right] \\ &\leq \sup_{t \in I} \frac{1}{E_{\alpha} \left( \xi \left( t - a \right)^{\alpha} \right)} Q \left[ |v(t) - w(t)| + {}_{a}^{AB} I^{\alpha} P \left| v(\tau) - w(\tau) \right| \right] \\ &\leq Q \left[ \sup_{t \in I} \frac{|v(t) - w(t)|}{E_{\alpha} \left( \xi \left( t - a \right)^{\alpha} \right)} + \sup_{t \in I} \frac{1}{E_{\alpha} \left( \xi \left( t - a \right)^{\alpha} \right)} \right] \\ &P_{a}^{AB} I^{\alpha} E_{\alpha} \left( \xi \left( t - a \right)^{\alpha} \right) \frac{|v(\tau) - w(\tau)|}{E_{\alpha} \left( \xi \left( t - a \right)^{\alpha} \right)} \right] \\ &\leq Q \left[ d_{\xi,\alpha} \left( v, w \right) + P d_{\xi,\alpha} \left( v, w \right) \sup_{t \in I} \frac{1}{E_{\alpha} \left( \xi \left( t - a \right)^{\alpha} \right)} a^{AB} I^{\alpha} E_{\alpha} \left( \xi \left( t - a \right)^{\alpha} \right) \right] \\ &= Q d_{\xi,\alpha} \left( v, w \right) \\ \left[ 1 + p d_{\xi,\alpha} \left( v, w \right) \sup_{t \in I} \frac{1}{E_{\alpha} \left( \xi \left( t - a \right)^{\alpha} \right)} \left( \frac{E_{\alpha} \left( \xi \left( t - a \right)^{\alpha} \right) - 1}{\xi} \right) \right] \\ &= Q \left| x | d_{\xi,\alpha} \left( v, w \right) \frac{1}{B \left( \alpha \right)} \left[ \left( 1 - \alpha \right) + \frac{\alpha}{\xi} \right] \right]. \end{aligned}$$

It follows from Banach fixed point theorem  $\mathfrak T$  has a unique fixed point.

## 4. Estimates of Solution

Now we obtain estimates on the solutions of equation (1.1) with some suitable assumptions

**Theorem 4.1**. Suppose that the functions f, k in (1.1) are continuous and satisfy the conditions

$$\left|\mathfrak{f}(t,u,v) - \mathfrak{f}(t,\overline{u},\overline{v})\right| \le G\left[\left|u - \overline{u}\right| + \left|v - \overline{u}\right|\right],\tag{4.1}$$

$$|k(t,\tau,u) - k(t,\tau,v)| \le h(t) |u-v|, \qquad (4.2)$$

where  $0 \le G < 1$  is a constant

$$m_2 = \sup_{t \in I} \left| f\left(t, 0, {}^{AB}_a I^{\alpha} k\left(t, s, 0\right)\right) \right| < \infty.$$

$$\tag{4.3}$$

If x(t) is any solution of (1.1) and  $H(t) = \sup_{t \in I} h(t)$  then

$$|x(t)| \le \frac{m_2}{(1-G)} \frac{B(\alpha)}{\left(B(\alpha) - (1-\alpha)\left(\frac{G}{1-G}\right)H(t)\right)} E_\alpha \left(\frac{\alpha \frac{G}{1-G}H(t)\left(t-\alpha\right)^\alpha}{\left(B(\alpha) - (1-\alpha)\left(\frac{G}{1-G}\right)H(t)\right)}\right).$$
(4.4)

**Proof.** Since the solution x(t) of equation (1.1) satisfies the equation (3.4) and the hypothesis we have

$$|x(t)| \leq \left| f\left(t, 0, {}_{a}^{AB}I^{\alpha}k(t, \tau, 0)\right) \right| + \left| f\left(t, x(t), {}_{a}^{AB}I^{\alpha}k(t, \tau, x(\tau))\right) - f\left(t, 0, {}_{a}^{AB}I^{\alpha}k(t, \tau, 0)\right) \right| \leq m_{2} + G\left[ |x(t)| + {}_{a}^{AB}I^{\alpha}h(\tau)|x(\tau)| \right].$$
(4.5)

From (4.5) and hypotheses  $0 \le G < 1$  we have

$$|x(t)| \le \frac{m_2}{(1-G)} + \frac{G}{1-G} H(t)_a^{AB} I^\alpha |x(\tau)|.$$
(4.6)

Now applying the Gronwall inequality Theorem 2.1 to (4.6) we get (4.4).

#### 5. Continuous dependence

Now in this section we study the continuous dependence of (1.1) and the functions involved therein. Now consider the equation (1.1) and the corresponding equation

$$y(t) = \bar{\mathfrak{f}}\left(t, y(t), {}_{a}^{AB}I^{\alpha}\bar{k}\left(t, \tau, y(\tau)\right)\right), \tag{5.1}$$

for  $t \in I$ ,  $\tau \leq t$  where  $\overline{k} \in C(I \times I \times \mathbb{R}, \mathbb{R})$  and  $\overline{f} \in C(I \times \mathbb{R} \times \mathbb{R}, \mathbb{R})$  and  $y_0$  is a given constant in  $\mathbb{R}^n$ .

Our next theorem deals with continuous dependence of solution of (1.1) and on functions involved therein.

**Theorem 5.1.** Suppose the functions  $\mathfrak{f}, k$  in (1.1) are continuous and satisfy the conditions (4.1) and (4.2). Suppose that

$$\left|\mathfrak{f}\left(t, y\left(t\right), {}^{AB}_{a}I^{\alpha}k\left(t, \tau, y\left(\tau\right)\right)\right) - \overline{\mathfrak{f}}\left(t, y\left(t\right), {}^{AB}_{a}I^{\alpha}\overline{k}\left(t, \tau, y\left(\tau\right)\right)\right)\right| \le \epsilon,$$

$$(5.2)$$

where  $\mathfrak{f}, k$  and  $\overline{\mathfrak{f}}, \overline{k}$  are functions involved in (1.1) and (5.1),  $\epsilon > 0$  is small constant and y(t) is given solution of (5.1). Then the solution  $x(t), t \in I$  of (1.1) depends continuously on the functions involved on the right hand side of (1.1).

**Proof.** Let v(t) = |x(t) - y(t)| for  $t \in I$ . Since x(t) and y(t) are solutions of equations (1.1), (5.1) and given conditions we have

$$\begin{aligned} v\left(t\right) &\leq \left| \mathfrak{f}\left(t, x(t), {}_{a}^{AB}I^{\alpha}k\left(t, \tau, x\left(\tau\right)\right)\right) - \overline{\mathfrak{f}}\left(t, y(t), {}_{a}^{AB}I^{\alpha}\overline{k}\left(t, \tau, y\left(\tau\right)\right)\right) \right| \\ &+ \left| \mathfrak{f}\left(t, y(t), {}_{a}^{AB}I^{\alpha}k\left(t, \tau, y\left(\tau\right)\right)\right) - \overline{\mathfrak{f}}\left(t, y(t), {}_{a}^{AB}I^{\alpha}\overline{k}\left(t, \tau, y\left(\tau\right)\right)\right) \right| \\ &\leq \varepsilon + G\left[ |v\left(t\right)| + {}_{a}^{AB}I^{\alpha}h\left(\tau\right)|v\left(\tau\right)| \right]. \end{aligned}$$

$$(5.3)$$

From (5.3) and assumption  $0 \le G < 1$  we have

$$v(t) \leq \frac{\varepsilon}{1-G} + \frac{G}{1-G} H(t) {}^{AB}_{a} I^{\alpha} |v(\tau)|.$$
(5.4)

Now by Gronwall's Inequality Theorem 2.1 we have

$$|x(t) - y(t)| \le \frac{\varepsilon}{1 - G} \frac{B(\alpha)}{\left[B(\alpha) - (1 - \alpha)\frac{G}{1 - G}H(t)\right]} E_{\alpha} \left(\frac{\alpha \frac{G}{1 - G}H(t)}{B(\alpha) - (1 - \alpha)\frac{G}{1 - G}H(t)}\right).$$
(5.5)

From (5.5) it follows that the solution of equation (1.1) depends continuously on the functions involved on the right hand side of equation (1.1).

Consider the system of fractional Volterra integral equation

$$w(t) = g\left(t, w(t), {}^{AB}_{a}I^{\alpha}l\left(t, \tau, w(\tau)\right), \mu\right)$$
(5.6)

and

$$w(t) = g\left(t, w(t), {}^{AB}_{a}I^{\alpha}l\left(t, \tau, w(\tau)\right), \mu_{0}\right), \qquad (5.7)$$

for  $t \in I$  where  $l \in C(I \times I \times \mathbb{R}, \mathbb{R})$  and  $g \in C(I \times \mathbb{R} \times \mathbb{R} \times \mathbb{R}, \mathbb{R})$ .

Now in our next theorem we give the dependence of solution of equation (5.6)-(5.7) on parameters.

**Theorem 5.2.** Suppose that the functions g, l in equation (5.6) - (5.7) satisfy the conditions

$$|g(t, v_1, v_2, \mu) - g(t, \overline{v_1}, \overline{v_2}, \mu)| \le \overline{G} \left[ |v_1 - \overline{v_1}| + |v_2 - \overline{v_2}| \right],$$
(5.8)

$$|g(t, v_1, v_2, \mu_0) - g(t, \overline{v_1}, \overline{v_2}, \mu_0)| \le d(t) |\mu - \mu_0|,$$
(5.9)

$$|l(t, s, v) - l(t, s, r)| \le h(t) |v - r|, \qquad (5.10)$$

where  $0 \leq \overline{G} < 1$  is a constant and  $d \in C(I, \mathbb{R})$  such that  $d(t) \leq D < \infty$ , D is a constant and  $\overline{h}(t) \in C(I, \mathbb{R})$ . Let  $w_1(t)$  and  $w_2(t)$  be the solutions of (5.6) and (5.7) respectively then

$$|w_{1}(t) - w_{2}(t)| \leq \frac{D|\mu - \mu_{0}|}{1 - \overline{G}} \frac{B(\alpha)}{\left[B(\alpha) - (1 - \alpha)\frac{G}{1 - \overline{G}}\overline{H}(t)\right]}$$
$$E_{\alpha}\left(\frac{\alpha \frac{\overline{G}}{1 - \overline{G}}\overline{H}(t)(t - a)^{\alpha}}{B(\alpha) - (1 - \alpha)\frac{G}{1 - \overline{G}}\overline{H}(t)}\right).$$
(5.11)

**Proof.** Let  $w(t) = |w_1(t) - w_2(t)|, t \in I$ . Since  $w_1(t)$  and  $w_2(t)$  are solution of equation (5.6) and (5.7) and given conditions we have

$$|w(t)| \leq |g(t, w_{1}(t), {}_{a}^{AB}I^{\alpha}l(t, \tau, w_{1}(\tau)), \mu) - g(t, w_{2}(t), {}_{a}^{AB}I^{\alpha}l(t, \tau, w_{2}(\tau)), \mu_{0})| + |g(t, w_{2}(t), {}_{a}^{AB}I^{\alpha}l(t, \tau, w_{2}(\tau)), \mu) - g(t, w_{2}(t), {}_{a}^{AB}I^{\alpha}l(t, \tau, w_{2}(\tau)), \mu_{0})| \leq \overline{G} [w(t) + {}_{a}^{AB}I^{\alpha}\overline{h}(\tau)w(\tau)].$$
(5.12)

From (5.12) and using the assumption  $0 \leq \overline{G} < 1$  we have

$$|w(t)| \leq \frac{D|\mu - \mu_0|}{1 - \overline{G}} + \frac{\overline{G}}{1 - \overline{G}} H(t) {}^{AB}_a I^\alpha |w(\tau)|.$$
(5.13)

Now an application of Gronwall inequality Theorem 2.1 to (5.13) we get (5.11).

**Example**. In order to illustrate our results we give the following example: Consider the Volterra type ABC fractional integral equation

$$x(t) = \frac{1}{10(t+1)}x(t) + \frac{1}{10^{a}} I^{\alpha} e^{-2t} x(\tau), \qquad (5.14)$$

for  $t \in [0, 1]$ Set

$$f(t, x(\tau), \mathbf{X}x(\tau)) = \frac{1}{10(t+1)}x(t) + \frac{1}{10} {}^{AB}_{a} I^{\alpha} e^{-2t} x(\tau) \,,$$

$$\mathbf{X}x(\tau) = {}^{AB}_{a} I^{\alpha} e^{-2t} x(\tau) \,.$$

From above it can be easy to see that

$$|f(t, u(\tau), \mathbf{X}u(\tau)) - f(t, v(\tau), \mathbf{X}v(\tau))| \le \frac{1}{10} \left[ |u - v| + |\mathbf{X}u - \mathbf{X}v| \right],$$
$$|\mathbf{X}u - \mathbf{X}v| \le \frac{1}{10e^{2t}} a^{AB} I^{\alpha} x\left(\tau\right).$$

Thus from above equation the conditions (3.1) – (3.2) holds we have  $Q = \frac{1}{10}$  and  $P = \frac{1}{10e^{2t}}$  then for  $\xi = 2$  we have

$$Q\left(1+\frac{P}{\xi}\right) \cong 0.10067 < 1$$

Thus the assumptions of the Theorem 3.1 are satisfied and thus the integral equation (5.14) has a unique solution.

Acknowledgements/Funding. : The research of J.J. Nieto has been partially supported by the Agencia Estatal de Investigacion (AEI) of Spain, co-financed by the European Fund for Regional Development (FEDER), project PID2020-113275GB-I00; and by Xunta de Galicia under grant ED431C 2019/02.

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