

# Normal-like Curves with Respect to the Special Case of the ED-frame in Euclidean 4-space

Özcan BEKTAŞ 

## Abstract

The aim of this study is to present normal-like curves with respect to the special case of the ED-frame in Euclidean 4-space. Furthermore, the relationship between geodesic torsion and curvature is given so that a curve lying on an oriented surface  $M$  in 4-dimensional Euclidean space is congruent to a normal-like curve according to the special case of the ED-frame. Finally, an example of the study is presented.

## Keywords and 2020 Mathematics Subject Classification

Keywords: Normal-like curve — extended Darboux frame — geodesic curvature — geodesic torsion.  
MSC: 53A04, 53A07

Recep Tayyip Erdogan University, Faculty of Arts and Sciences, Department of Mathematics, Rize, Turkey.

✉ozcan.bektas@erdogan.edu.tr

Corresponding author: Özcan BEKTAŞ

Article History: Received 06 June 2022; Accepted 18 July 2022

## 1. Introduction

Some special curves in differential geometry are quite remarkable for researchers. One of them is normal curve. After Chen [1] defined the rectifying curve in Euclidean space, Ilarslan and Nesovic [2] defined the osculating, rectifying and normal curve as a curve in Euclidean 4-space according to the definition of the rectifying curve in Euclidean 3-space, [3]. This definition given for the normal curve has been used in some studies in Minkowski space [4–6]. In addition, the generalization of normal curves to  $n$ -dimensional space was made by Bektaş [7].

Frame fields are very useful for defining curves and examining properties. One of these frame fields is the Frenet frame fields. The Frenet frame along a curve is a moving (right-handed) coordinate system determined by the tangent line and curvature [8, 9]. Another important frame field is known as Darboux frame [10]. In addition to these frame fields, a new frame fields has been introduced to the literature. This frame fields was defined by Döldül et al. and named as extended Darboux frame field (ED-frame field) [11]. In this study, we define normal-like curves with respect to the special case of the ED-frame in Euclidean 4-space and an example of the study is presented.

## 2. Preliminaries

**Definition 1.** Let  $x = \sum_{i=1}^4 x_i e_i$ ,  $y = \sum_{i=1}^4 y_i e_i$ ,  $z = \sum_{i=1}^4 z_i e_i$  be vectors in Euclidean 4-space  $\mathbb{E}^4$ , where  $\{e_i\}$ ,  $1 \leq i \leq 4$  is the standart basis vectors of  $\mathbb{E}^4$ . The vector product of three vectors is given by [12]

$$x \otimes y \otimes z = \begin{vmatrix} e_1 & e_2 & e_3 & e_4 \\ x_1 & x_2 & x_3 & x_4 \\ y_1 & y_2 & y_3 & y_4 \\ z_1 & z_2 & z_3 & z_4 \end{vmatrix}.$$

Let  $\mathcal{M}$  be an orientable hypersurface and the curve  $\gamma$  lies on  $\mathcal{M}$ . On the other hand, if the unit tangent vector field of the curve is  $T$ , the unit normal vector field of the hypersurface restricted to the curve  $\gamma$  is  $N$  and the unit normal field vector of  $\mathcal{M}$  is  $\mathcal{N}$ , then  $T$  is given as  $T = \gamma'(s)$  and  $N(s) = \mathcal{N}(\gamma(s))$  [11].

**Case 1.** Let  $\{N, T, \gamma''\}$  be linearly independent. In this case, the orthonormal set  $\{N, T, E\}$  with

$$E = \frac{\gamma'' - \langle \gamma'', N \rangle N}{\|\gamma'' - \langle \gamma'', N \rangle N\|},$$

is obtained [11].

**Case 2.** Let  $\{N, T, \gamma''\}$  be linearly dependent. In this case, the orthonormal set  $\{N, T, E\}$  with

$$E = \frac{\gamma'' - \langle \gamma'', N \rangle N - \langle \gamma'', T \rangle T}{\|\gamma'' - \langle \gamma'', N \rangle N - \langle \gamma'', T \rangle T\|},$$

is obtained [11]. If  $D = N \otimes T \otimes E$ , then we obtain orthonormal frame field  $\{T, E, D, N\}$  along the curve  $\gamma$  [11].

One can easily see that the vector fields  $E$  and  $D$  are tangent to  $\mathcal{M}$ . Also,  $\{T, E, D\}$  spans the tangent hyperplane of the hypersurface at the point  $\gamma(s)$  [11].

Let  $\kappa_n$  be the normal curvature of the hypersurface in the direction of the tangent vector  $T$ ,  $\kappa_g^i$  and  $\tau_g^i$  be the geodesic curvature and the geodesic torsion of order  $i$  ( $i=1,2$ ), respectively, [11]. The derivative equations for Case 1 and Case 2

$$\begin{bmatrix} T' \\ E' \\ D' \\ N' \end{bmatrix} = \begin{bmatrix} 0 & \kappa_g^1 & 0 & \kappa_n \\ -\kappa_g^1 & 0 & \kappa_g^2 & \tau_g^1 \\ 0 & -\kappa_g^2 & 0 & \tau_g^2 \\ -\kappa_n & -\tau_g^1 & -\tau_g^2 & 0 \end{bmatrix} \begin{bmatrix} T \\ E \\ D \\ N \end{bmatrix}, \quad (1)$$

and

$$\begin{bmatrix} T' \\ E' \\ D' \\ N' \end{bmatrix} = \begin{bmatrix} 0 & 0 & 0 & \kappa_n \\ 0 & 0 & \kappa_g^2 & \tau_g^1 \\ 0 & -\kappa_g^2 & 0 & 0 \\ -\kappa_n & -\tau_g^1 & 0 & 0 \end{bmatrix} \begin{bmatrix} T \\ E \\ D \\ N \end{bmatrix}. \quad (2)$$

On the other hand, for Case 1 and Case 2 the following statements hold, respectively [11]:

$$\langle T', D \rangle = \langle D', T \rangle = 0,$$

$$\langle T', E \rangle = \kappa_g^1, \langle T', N \rangle = \kappa_n, \langle E', T \rangle = -\kappa_g^1, \langle E', D \rangle = \kappa_g^2, \langle E', N \rangle = \tau_g^1, \langle D', N \rangle = \tau_g^2,$$

$$\langle N', T \rangle = -\kappa_n, \langle N', E \rangle = \tau_g^1, \langle N', D \rangle = -\tau_g^2, \quad (3)$$

$$\langle T', E \rangle = \langle T', D \rangle = \langle E', T \rangle = \langle D', T \rangle = \langle D', N \rangle = \langle N', D \rangle = 0,$$

$$\langle T', N \rangle = \kappa_n, \langle E', N \rangle = \tau_g^1, \langle E', D \rangle = \kappa_g^2, \langle D', E \rangle = -\kappa_g^2, \langle N', T \rangle = -\kappa_n, \langle N', E \rangle = -\tau_g^1. \quad (4)$$

### 3. Normal-like curves with respect to the special case of the ED-frame in Euclidean 4-space

In this section, we define the normal curves according to the Case 2 ED-frame in Euclidean 4-space. And then, we find the relationship between the curvatures for any unit speed curve which lies on the orientable hypersurface  $\mathcal{M}$  to be congruent to this normal curves in  $\mathbb{E}^4$ .

**Definition 2.** Let  $\alpha : I \subset \mathbb{R} \rightarrow \mathcal{M}$  be a unit speed curve on an oriented hypersurface  $\mathcal{M}$  in Euclidean 4-space and  $\{T, E, D, N\}$  denote the ED-frame field of  $\alpha(s)$ . Then we define the normal curve according to the ED-frame in the Euclidean space  $\mathbb{E}^4$  as a curve whose position vector always lies in the orthogonal complement  $T^\perp$  of tangent vector field  $T$ , and we express it with

$$\alpha(s) = \lambda(s)E(s) + \mu_1(s)D(s) + \mu_2(s)N(s) \tag{5}$$

for some differentiable functions  $\lambda(s), \mu_1(s)$  and  $\mu_2(s)$  of  $s \in I \subset \mathbb{R}$ .

**Theorem 3.** Let  $\alpha : I \subset \mathbb{R} \rightarrow \mathcal{M}$  be a unit speed curve on an oriented hypersurface  $\mathcal{M}$  in Euclidean 4-space and  $\{T, E, D, N\}$  denote the Case 2 ED-frame field of  $\alpha(s)$ . Then  $\alpha(s)$  is congruent to a normal curve if and only if

$$\left\{ \frac{1}{\kappa_g^2(s)} \left[ \frac{\tau_g^1(s)}{\kappa_n(s)} + \left( \frac{1}{\tau_g^1(s)} \left( \frac{1}{\kappa_n(s)} \right)' \right)' \right] \right\}' + \frac{\kappa_g^2(s)}{\tau_g^1(s)} \left( \frac{1}{\kappa_n(s)} \right)' = 0$$

where  $\kappa_n, \kappa_g^1, \kappa_g^2$  and  $\tau_g^1 \neq 0$ .

*Proof.* Let  $\alpha : I \subset \mathbb{R} \rightarrow \mathcal{M}$  be a unit speed curve on an oriented hypersurface  $\mathcal{M}$  in Euclidean 4-space and  $\{T, E, D, N\}$  denote the ED-frame field of  $\alpha(s)$ . If the derivative of both sides of equation (5) with respect to  $s$  is taken and the derivative equation (2) is applied, the following expression for Case 2 is obtained that

$$\begin{aligned} \alpha'(s) &= (-\mu_2(s)\kappa_n(s))T(s) + \left( \lambda'(s) - \mu_1(s)\kappa_g^2(s) - \mu_2(s)\tau_g^1(s) \right)E(s) \\ &+ \left( \mu_1'(s) + \lambda(s)\kappa_g^2(s) \right)D(s) + \left( \mu_2'(s) + \lambda(s)\tau_g^1(s) \right)N(s). \end{aligned}$$

We know that  $\alpha'(s) = T(s)$ . So, using the equality of both sides, we get the following expressions for the coefficients of  $T(s), E(s), D(s)$  and  $N(s)$

**Case 2**

$$-\mu_2(s)\kappa_n(s) = 1, \tag{6}$$

$$\lambda'(s) - \mu_1(s)\kappa_g^2(s) - \mu_2(s)\tau_g^1(s) = 0, \tag{7}$$

$$\mu_1'(s) + \lambda(s)\kappa_g^2(s) = 0, \tag{8}$$

$$\mu_2'(s) + \lambda(s)\tau_g^1(s) = 0. \tag{9}$$

From (6), we can find the following coefficient function:

$$\mu_2(s) = -\frac{1}{\kappa_n(s)}. \tag{10}$$

When the coefficient function (10) is used in equation (9), the other coefficient function is as follows:

$$\lambda(s) = \frac{1}{\tau_g^1(s)} \left( \frac{1}{\kappa_n(s)} \right)'. \tag{11}$$

The coefficient function  $\mu_1(s)$  is given similarly with the help of the related coefficient functions

$$\mu_1(s) = \frac{1}{\kappa_g^2(s)} \left[ \frac{\tau_g^1(s)}{\kappa_n(s)} + \left( \frac{1}{\tau_g^1(s)} \left( \frac{1}{\kappa_n(s)} \right)' \right)' \right]. \tag{12}$$

Substituting (11) and (12) into (8), we get the following relations:

$$\left\{ \frac{1}{\kappa_g^2(s)} \left[ \frac{\tau_g^1(s)}{\kappa_n(s)} + \left( \frac{1}{\tau_g^1(s)} \left( \frac{1}{\kappa_n(s)} \right)' \right) \right] \right\}' + \frac{\kappa_g^2(s)}{\tau_g^1(s)} \left( \frac{1}{\kappa_n(s)} \right)' = 0 \quad (13)$$

where  $\kappa_n, \kappa_g^1, \kappa_g^2$  and  $\tau_g^1 \neq 0$ .

Conversely, consider an arbitrary unit speed curve on an oriented hypersurface  $\mathcal{M}$  in Euclidean 4-space for which the curvature functions satisfy the relations (13) and (11). Then, we consider the vector  $X \in \mathbb{E}^4$  defined by

$$X(s) = \alpha(s) - \frac{1}{\tau_g^1(s)} \left( \frac{1}{\kappa_n(s)} \right)' E(s) - \frac{1}{\kappa_g^2(s)} \left[ \frac{\tau_g^1(s)}{\kappa_n(s)} + \left( \frac{1}{\tau_g^1(s)} \left( \frac{1}{\kappa_n(s)} \right)' \right) \right] D(s) + \frac{1}{\kappa_n(s)} N(s).$$

It can be seen that  $X(s) = 0$  through the relations (2), (13). Thus,  $X$  is a constant vector. This implies that  $\alpha$  is congruent to a normal curve. ■

**Theorem 4.** Let  $\alpha : I \subset \mathbb{R} \rightarrow \mathcal{M}$  be a unit speed curve on an oriented hypersurface  $\mathcal{M}$  in Euclidean 4-space and  $\{T, E, D, N\}$  denote the Case 2 ED-frame field of  $\alpha(s)$ . Then  $\alpha$  is a normal curve if and only if

$$\langle \alpha(s), E(s) \rangle = \frac{1}{\tau_g^1(s)} \left( \frac{1}{\kappa_n(s)} \right)', \langle \alpha(s), N(s) \rangle = -\frac{1}{\kappa_n(s)}, \tau_g^1(s), \kappa_n(s) \neq 0. \quad (14)$$

*Proof.* Let  $\alpha : I \subset \mathbb{R} \rightarrow \mathcal{M}$  be a unit speed curve on an oriented hypersurface  $\mathcal{M}$  in Euclidean 4-space and  $\{T, E, D, N\}$  denote the Case 2 ED-frame field of  $\alpha(s)$ . Substituting (10), (11) and (12) into (5), we get

$$\alpha(s) = \frac{1}{\tau_g^1(s)} \left( \frac{1}{\kappa_n(s)} \right)' E(s) + \frac{1}{\kappa_g^2(s)} + \frac{\tau_g^1(s)}{\kappa_n(s)} + \left( \frac{1}{\tau_g^1(s)} \left( \frac{1}{\kappa_n(s)} \right)' \right)' D(s) - \frac{1}{\kappa_n(s)} N(s).$$

When the inner product of both sides of the equation with respect to  $E(s)$  and  $N(s)$ , respectively, is taken, the expressions  $\langle \alpha(s), E(s) \rangle = \frac{1}{\tau_g^1(s)} \left( \frac{1}{\kappa_n(s)} \right)'$  and  $\langle \alpha(s), N(s) \rangle = -\frac{1}{\kappa_n(s)}, \tau_g^1(s), \kappa_n(s) \neq 0$  are found.

Conversely the statement (14) holds. Differentiating equation  $\langle \alpha(s), N(s) \rangle = -\frac{1}{\kappa_n(s)}$  with respect to  $s$  and by applying (2), we find  $\langle \alpha(s), T(s) \rangle = 0$  which means that  $\alpha$  is a normal curve. ■

**Example 5.** Let  $\alpha(s) = \left( \frac{2s}{\sqrt{11}}, \sin \left( \sqrt{\frac{2}{11}}s \right), \sqrt{\frac{5}{11}}s, -\cos \left( \sqrt{\frac{2}{11}}s \right) \right)$  be a unit speed curve on an hypersurface

$\mathcal{M} \dots x_2^2 + x_4^2 = 1$  in Euclidean 4-space. The unit normal vector of  $\mathcal{M}$  along  $\alpha$  is  $N(s) = (0, x_2, 0, x_4)$ . If we calculate the unit tangent vector field we can find as follows:

$$T(s) = \left( \frac{2}{\sqrt{11}}, \sqrt{\frac{2}{11}} \cos \left( \sqrt{\frac{2}{11}}s \right), \sqrt{\frac{5}{11}}, \sqrt{\frac{2}{11}} \sin \left( \sqrt{\frac{2}{11}}s \right) \right).$$

The derivative of  $T(s)$  is given by

$$T'(s) = \alpha''(s) = \left( 0, -\frac{2}{11} \sin \left( \sqrt{\frac{2}{11}}s \right), 0, \frac{2}{11} \cos \left( \sqrt{\frac{2}{11}}s \right) \right).$$

Considering  $T'(s)$  and  $N(s) = \mathcal{N}(\alpha(s)) = (0, \sin \left( \sqrt{\frac{2}{11}}s \right), 0, -\cos \left( \sqrt{\frac{2}{11}}s \right))$ ,  $(T'(s) = -\frac{2}{11}N(s))$  they appear to be linearly dependent. Therefore, Case 2 applies. Thus, we get

$$E(s) = \left( \frac{4}{3\sqrt{22}}, \frac{-3}{\sqrt{11}} \cos \left( \sqrt{\frac{2}{11}}s \right), \frac{2\sqrt{5}}{3\sqrt{22}}, \frac{-3}{\sqrt{11}} \sin \left( \sqrt{\frac{2}{11}}s \right) \right),$$

and

$$D(s) = \left( \frac{-\sqrt{5}}{3}, 0, \frac{2}{3}, 0 \right).$$

If we use the equation (4) we get

$$\langle T', N \rangle = \kappa_n = -\frac{2}{11}, \langle E', N \rangle = \tau_g^1 = \frac{3\sqrt{2}}{11}, \langle E', D \rangle = \kappa_g^2 = 0.$$

According to the results obtained from here, it is concluded that the given unit speed curve cannot be congruent to a normal curve, since  $\kappa_g^2 = 0$ .

On the other hand, the normal like curve is obtained as follows:

$$\alpha(s) = \lambda(s) \left( \frac{4}{3\sqrt{22}}, \frac{-3}{\sqrt{11}} \cos \left( \sqrt{\frac{2}{11}} s \right), \frac{2\sqrt{5}}{3\sqrt{22}}, \frac{-3}{\sqrt{11}} \sin \left( \sqrt{\frac{2}{11}} s \right) \right) + \mu_1(s) \left( \frac{-\sqrt{5}}{3}, 0, \frac{2}{3}, 0 \right) + \mu_2(s) \left( 0, \sin \left( \sqrt{\frac{2}{11}} s \right), 0, -\cos \left( \sqrt{\frac{2}{11}} s \right) \right)$$

or

$$\alpha(s) = \left( \frac{4}{3\sqrt{22}} \lambda(s) - \frac{\sqrt{5}}{3} \mu_1(s), -\frac{3}{11} \lambda(s) \cos \left( \sqrt{\frac{2}{11}} s \right), \frac{2\sqrt{5}}{3\sqrt{22}} \lambda(s) + \frac{2}{3} \mu_1(s), \frac{-3}{\sqrt{11}} \sin \left( \sqrt{\frac{2}{11}} s \right) \lambda(s) - \mu_1(s) \cos \left( \sqrt{\frac{2}{11}} s \right) \right)$$

for some differentiable functions  $\lambda(s)$ ,  $\mu_1(s)$  and  $\mu_2(s)$  of  $s \in I \subset \mathbb{R}$ .

## 4. Acknowledgements

The author would like to thank the reviewers for their insightful comments and suggestions that helped to improve the paper.

## References

- [1] Chen, B.Y. (2003). *When does the position vector of a space curve always lie in its rectifying plane*. The Amer. Math. Monthly, 110(2), 147-152.
- [2] İlarıslan, K., & Nesovic, E. (2008). *Some characterizations of osculating curves in the Euclidean spaces*. Demonstratio Mathematica, 41(4), 931-939.
- [3] İlarıslan, K., & Nesovic, E. (2008). *Some characterizations of rectifying curves in the Euclidean space  $E^4$* . Turkish Journal of Mathematics, 32(1), 21-30.
- [4] İlarıslan, K., & Nesovic, E. (2004). *Timelike and null normal curves in Minkowski space  $E_1^3$* . Indian Journal of Pure and Applied Mathematics, 35(7), 881-888.
- [5] İlarıslan, K. (2005). *Spacelike normal curves in Minkowski space  $E_1^3$* . Turkish Journal of Mathematics, 29(1), 53-63.
- [6] İlarıslan, K., & Nesovic, E. (2009). *Spacelike and timelike normal curves in Minkowski space-time*. Publications de l'Institut Mathematique, (105), 111-118.
- [7] Bektař, Ö. (2018). *Normal Curves in n-dimensional Euclidean Space*. Advances in Difference Equations, 2018(1), 1-12.
- [8] Gluck, H. (1966). *Higher curvatures of curves in Euclidean space*. The Amer. Math. Monthly, 73(7), 699-704.
- [9] Guggenheimer, H. (1989). *Computing frames along a trajectory*. Computer Aided Geometric Design, 6(1), 77-78.
- [10] Darboux, G. (1896). *Leçons sur la théorie générale des surfaces et les applications géométriques du calcul infinitésimal: ptie. Déformation infiniment petite et représentation sphérique. Notes et additions: I. Sur les méthodes d'approximations successives dans la théorie des équations différentielles, par E. Picard. II. Sur les géodésiques à intégrales quadratiques, par G. Koenigs. III. Sur la théorie des équations aux dérivées partielles du second ordre, par E. Cosserat. IV-XI. Par l'auteur, 4, Gauthier-Villars.*
- [11] Dıldül, M., Uyar Dıldül, B., Kuruođlu, N., & Özdamar, E. (2017). *Extension of the Darboux frame into Euclidean 4-space and its invariants*. Turkish Journal of Mathematics, 41(6), 1628-1639.
- [12] Williams, M.Z., & Stein, F. (1964). *A triple product of vectors in four-space*. Mathematics Magazine, 37(4), 230-235.