#### **Research Article**

# Pseudo-Riemannian Submanifolds with 3-planar Geodesics

Kadri Arslan<sup>a</sup>, Betül Bulca<sup>a</sup>, Günay Öztürk<sup>\*b</sup>

 <sup>a</sup> Uludağ University, Faculty of Arts and Sciences, Department of Mathematics, Bursa 16059, Turkey
 <sup>b</sup> Kocaeli University, Faculty of Arts and Sciences, Department of Mathematics, Koaceli 41380, Turkey

#### Abstract

In the present paper, we study pseudo-Riemannian submanifolds which have 3-planar geodesic normal sections. Further, we consider W-curves (helices) on pseudo-Riemannian submanifolds. Finally, we give necessary and sufficient condition for a normal section to be a W-curve on pseudo-Riemannian submanifolds.

Keywords: Pseudo-Riemannian submanifold, geodesic normal section, W-curve, planar geodesic.

## 3-Düzlemsel Geodezikli Yarı-Riemann Altmanifoldlar

#### Öz

Bu çalışmada, 3-düzlemsel geodezik normal kesitlere sahip yarı-Riemann almanifoldlar ele alınmıştır. Daha sonra, yarı-Riemann altmanifoldları üzerindeki W-eğrileri (helisler) incelenmiştir. Son olarak, yarı-Riemann altmanifoldları üzerindeki normal kesitlerin W-eğrisi olması için gerek ve yeter şartlar elde edilmiştir.

Anahtar Kelimeler : Yarı-Riemann altmanifold, geodezik normal kesit, W-eğrisi, düzlemsel geodezik

#### Introduction

Let  $M^n$  be an n-dimensional Riemannian manifold. A regular curve  $\gamma$  in

 $M^n$  is called a helix if its first and second curvatures are constant and the third curvature is zero. It has been shown that every helix in a Riemannian submanifold  $M^n$  is also a helix in the ambient space [1]. For the pseudo-Riemannian manifold  $M_r^n$ , helices are defined almost the same way as the Riemannian case. The helices are characterized in Lorentzian submanifold  $M_r^n \subset N_s^m$  [2].

A submanifold  $M_r^n \subset N_s^m$  is said to have planar geodesics if the image of each geodesic of  $M_r^n$  lies in a 2-plane of  $N_s^m$ [3]. In the Riemannian case such submanifolds were studied in [4], [5], [6], and [7]. Recently, Kim studied minimal surfaces of pseudo-Euclidean spaces with

> **Received:** 06.10.2016 **Accepted:** 21.02.2017

<sup>\*</sup> Corresponding author : e-mail: ogunay@kocaeli.edu.tr

geodesic normal sections [8].

In the present study, we give some results toward a characterization of 3-planar geodesic immersions  $f: M_r^n \to N_s^m$  from an n-dimensional, connected pseudo-Riemannian manifold  $M_r^n$  into an m-dimensional pseudo-Riemannian manifold  $N_s^m$ . Further, we consider W-curves (helices) on pseudo-Riemannian submanifolds. Finally, we give necessary and sufficient condition for a normal section to be a W-curve on pseudo-Riemannian submanifold  $M_r^n$ .

#### **Basic Concepts**

Let  $M_r^n \subset N_s^m$  be a submanifold in an m-dimensional pseudo-Riemannian manifold  $N_s^m$  of index s. Let  $\nabla$  and  $\tilde{\nabla}$ denote the covariant derivatives of  $M_r^n$  and  $N_s^m$  respectively. Then, for  $X, Y \in T_p(M_r^n)$  the second fundamental form *h* of  $M_r^n$  is defined by

$$h(X,Y) = \widetilde{\nabla}_X Y - \nabla_X Y. \tag{1}$$

For a normal vector field  $\xi \in N(M_r^n)$  we put

$$\widetilde{\nabla}_X \xi = -A_{\xi} X + D_X \xi, \qquad (2)$$

where  $A_{\xi}$  is the shape operator and *D* is the normal connection of  $M_r^n$ .

The covariant derivatives of *h* is given by

$$(\overline{\nabla}_X h)(Y,Z) = D_X h(Y,Z) -h(\nabla_X Y,Z) - h(Y,\nabla_X Z),$$
(3)

where  $X, Y, Z \in T_p(M_r^n)$  and  $\overline{\nabla}$  is the

Vander Waerden-Bortolotti connection [9]. Then the Codazzi equation

$$(\overline{\nabla}_{X}h)(Y,Z) = (\overline{\nabla}_{Y}h)(X,Z) = (\overline{\nabla}_{Z}h)(X,Y). \tag{4}$$

holds. If  $\overline{\nabla}h = 0$ , then *h* is said to be parallel [10].

The mean curvature vector field H of  $M_r^n$  is defined by

$$H = \frac{1}{n} \sum \langle e_{i}, e_{i} \rangle h(e_{i}, e_{i}), i = 1,..., n, \qquad (5)$$

where  $\{e_1, e_2, ..., e_n\}$  is an orthonormal frame field of  $M_r^n$ . Consequently, *H* is called parallel when DH = 0 holds.

If the second fundamental form h satisfies

$$g(X,Y)H = h(X,Y),$$
(6)

for any  $X, Y \in T_p(M_r^n)$ , then  $M_r^n$  is called a totally umbilical. A totally umbilical submanifold with parallel mean curvature vector fields is said to be an extrinsic sphere [11].

### Helices in a Pseudo-Riemannian Manifold

Let  $\gamma$  be a regular curve in a pseudo-Riemannian manifold  $M_r^n$ . We denote  $\gamma'(s) = X$ , when  $\langle X, X \rangle = \varepsilon; \varepsilon = \pm 1$  $\gamma$  is called a unit speed curve. The curve  $\gamma$ is called a Frenet curve of rank  $d (0 \le d \le n)$ , if its derivatives  $\gamma'(s), \gamma''(s), \dots, \gamma^{(d)}(s)$ are linearly independent and  $\gamma'(s), \gamma''(s), ..., \gamma^{(d+1)}(s)$ are no longer linearly independent for all  $s \in I$  [7]. To each Frenet curve of order d we can associate an orthonormal d frame  $\{V_1, V_2, ..., V_d\}$  along  $\gamma$ , called the Frenet

÷

frame, and  $k_1, k_2, ..., k_{d-1}$  are curvature functions of  $\gamma$ .

We have the following result.

**Proposition 1:** Let  $\gamma: I \to M_r^n$  be a nonnull smooth curve of osculating order *d* in of  $M_r^n$ , and  $\{V_1 = X, V_2, ..., V_d\}$  its Frenet frame. Then the following Frenet equations are hold;

$$V_1' = \nabla_X X = \varepsilon_2 k_1 V_2, \tag{7}$$

$$V_2' = \nabla_X V_2 = -\varepsilon_1 k_1 V_1 + \varepsilon_3 k_2 V_3, \tag{8}$$

$$V'_{d-1} = \nabla_X V_{d-1} = -\varepsilon_{d-2} k_{d-2} V_{d-2} + \varepsilon_d k_{d-1} V_d, \qquad (9)$$

$$V'_d = \nabla_X V_d = -\varepsilon_{d-1} k_{d-1} V_{d-1}, \tag{10}$$

where  $\varepsilon_i = \langle V_i, V_i \rangle = \pm 1, 1 \le i \le d - 1$  and  $k_i$  are curvature functions of  $\gamma$ .

**Definition 2:** A smooth curve  $\gamma$  of rank d on  $M_r^n$  is called a W-curve of rank d if its curvatures  $k_1, k_2, ..., k_{d-1}$  are all constant and  $k_d = 0$  [7].

**Proposition 3:** Let  $\gamma$  be a non-null Wcurve of rank 2 in  $M_r^n$ . Then the third derivative  $\gamma'''$  of  $\gamma$  is a scalar multiple of  $\gamma'$ . In this case necessarily  $\gamma'''(s) = -\varepsilon_1 \varepsilon_2 k_1^2 \gamma'(s)$ . (11)

**Proof:** By the use of (7) we have  $\gamma''(s) = \varepsilon_2 k_1 V_2(s)$ . Furthermore, differentiating this equation with respect to *s* and using (8) we obtain

$$\gamma'''(s) = -\epsilon_1 \epsilon_2 k_1^2 X + \epsilon_2 k_1' V_2(s) + \epsilon_2 \epsilon_3 k_1 k_2 V_3(s)$$
(12)

Since  $\gamma$  is a W-curve of rank 2 then by

definition  $k_1$  is constant and  $k_2 = 0$  we get the result.

**Proposition 4:** Let  $\gamma$  be a non-null Wcurve of  $M_r^n$ . If  $\gamma$  is of osculating order 3 then

$$\gamma^{(w)}(s) = -\varepsilon_2(\varepsilon_1 k_1^2 + \varepsilon_3 k_2^2)\gamma''(s)$$
(13)

holds.

**Proof:** Differentiating (12) and using the fact that  $k_1, k_2$  are constant and  $k_3 = 0$  we get the result.

#### **Planar Geodesic Immersions**

Let  $M_r^n \subset N_s^m$  be a submanifold in m-dimensional pseudo-Riemannian an manifold  $N_s^m$  of index s. For  $p \in M_r^n$  and  $X \in T_p(M_r^n)$  the vector X and the normal space  $N_p(M_r^n)$  determine a (m-n+1)dimensional totally geodesic submanifold  $\Gamma$  of  $N_s^n$ . The intersection of  $M_r^n$  with  $\Gamma$ gives rise a curve  $\gamma$  (in a neighborhood of p) called the normal section of  $M_r^n$  at p in the direction of X [12]. The submanifold  $M_r^n$  is said to have *d*-planar normal sections if for each normal section  $\gamma$  the higher derivatives order  $\gamma'(s), \gamma''(s), \dots, \gamma^{(d)}(s), \gamma^{(d+1)}(s), 1 \le d \le m - n + 1$ are linearly dependent as vectors in  $\Gamma$  [12]. The submanifold  $M_r^n$  is said to have dplanar geodesic normal sections if each normal section of  $M_r^n$  is a geodesic of  $M_r^n$ .The immersion in pseudo-Euclidean space with 2-planar geodesic normal section have been studied in [3]. See also [4].

Example 5: [3] Pseudo-Riemannian sphere

$$S_r^n(c) = \left\{ p \in E_r^{n+1} : \left\langle p - a, p - a \right\rangle = \frac{1}{c} \right\}, c > 0, \quad (14)$$

and pseudo-Riemannian hyperbolic space

$$H^{n}_{r}(c) = \left\{ p \in E^{n+1}_{r+1} : \left\langle p - a, p - a \right\rangle = \frac{1}{c} \right\}, c < 0, \quad (15)$$

both have 2-planar geodesic normal sections.

We have the following result.

**Proposition 6:** Let  $\gamma$  be a non-null geodesic normal section of  $M_r^n \subset N_s^m$ . If  $\gamma'(s) = X(s)$ , then we have

$$\gamma''(s) = h(X, X), \tag{16}$$

$$\gamma'''(s) = -A_{h(X,X)}X + (\overline{\nabla}_X h)(X,X), \quad (17)$$

$$\begin{split} \gamma^{(\mathrm{iv})}(s) &= -\nabla_{\mathrm{X}}(\mathrm{A}_{h(\mathrm{X},\mathrm{X})}\mathrm{X}) - h(\mathrm{A}_{h(\mathrm{X},\mathrm{X})}\mathrm{X},\mathrm{X}) \\ &- \mathrm{A}_{(\overline{\nabla}_{\mathrm{X}}h)(\mathrm{X},\mathrm{X})}\mathrm{X} + (\overline{\nabla}_{\mathrm{X}}\overline{\nabla}_{\mathrm{X}}h)(\mathrm{X},\mathrm{X}), \end{split} \tag{18}$$

**Definition 7:** The submanifold  $M_r^n$  (or the isometric immersion *f*) is said to be pseudo-isotropic at *p* if

$$L = \langle h(X, X), h(X, X) \rangle,$$

is independent of the choice of unit vector X tangent to  $M_r^n$  at p. In particular if L is independent of the points then  $M_r^n$  is said to be constant pseudo-isotropic.

The submanifold  $M_r^n$  is pseudoisotropic if and only if

$$\langle h(X,X),h(X,Y)\rangle = 0,$$

for any orthonormal vectors X and Y [3].

The following results are well-known.

**Theorem 8:** [3] If a submanifold  $M_r^n \subset E_s^m$  has 2-planar geodesic normal sections, then it is a submanifold with zero mean curvature in a hypersphere  $S_{s-1}^{m-1}$  or  $H_{s-1}^{m-1}$  if and only if *L* is a non-zero constant.

**Theorem 9:** [8] The surface  $M_r^2 \subset E_s^m$  with 2-planar geodesic normal sections is constant pseudo-isotropic.

**Theorem 10:** [13] Let  $M_r^n$  be a pseudo-Riemannian submanifold of index r of a pseudo-Euclidean space  $E_s^m$  of index s with geodesic normal sections. Then

$$\left\langle (\overline{\nabla}_X h)(X, X), (\overline{\nabla}_X h)(X, X) \right\rangle$$
 (19)

is constant on the their tangent bundle UM of  $M_r^n$ .

**Theorem 11:** [13] Let  $M_r^2$  be a minimal surface of  $E_s^5$  with geodesics normal sections. Then we have

i)  $M_r^2$  has parallel second fundamental form and 0-pseudo isotropic (i.e. L=0),

ii)  $M_r^2$  has 2-planar geodesic normal sections,

**iii**)  $M_r^2$  is flat.

#### **Main Results**

Submanifolds  $M^n$  in  $E^{n+d}$  with 3planar normal sections have been studied by S.J. Li for the case  $M^n$  is isotropic [14] and sphered [15]. See also [16] for the case  $M^n$ is a product manifold in  $E^{n+d}$ . In [17] the authors consider submanifolds in a real space form  $N^{n+d}(c)$  with 3-planar geodesic normal sections. We proved the following results.

**Proposition 12:** Let  $M_r^n \subset N_s^m$  be a submanifold with 3-planar geodesic normal sections then  $M_r^n$  is constant pseudo-isotropic.

**Proof:** Similar to the proof of Lemma 4.1 in [18].

**Proposition 13:** Let  $M_r^n \subset N_s^m$  be a submanifold with 3-planar geodesic normal sections then we have

$$(\overline{\nabla}_X h)(X, X) = \varepsilon_2(Xk_1)V_2 + \varepsilon_2\varepsilon_3k_1k_2V_3, (20)$$

and

$$A_{h(X,X)}X = \varepsilon_1 \varepsilon_2 {k_1}^2 X, \qquad (21)$$

hold.

**Proof:** Let  $\gamma$  be a normal section of  $M_r^n$  at point  $p = \gamma(s)$  in the direction of X. Further, we suppose that  $k_1(s)$  is positive. Then  $k_1$  is also smooth and there exists a unit vector field  $V_2$  along  $\gamma$  normal to  $M_r^n$ such that

$$h(X,X) = \langle V_2, V_2 \rangle k_1 V_2.$$
<sup>(22)</sup>

Since  $\overline{\nabla}_X V_2$  is also tangent to  $M_r^n$ , there exists a vector field  $V_3$  normal to  $M_r^n$  and mutually orthogonal to X and  $V_2$  such that

$$\widetilde{\nabla}_X V_2 = -\langle X, X \rangle k_1 X + \langle V_3, V_3 \rangle k_2 V_3.$$
(23)

Differentiating (22) covariantly and using (23) we get

$$(\overline{\nabla}_{x}h)(X,X) = -\varepsilon_{1}\varepsilon_{2}k_{1}^{2}X + \varepsilon_{2}(Xk_{1})V_{2} + \varepsilon_{2}\varepsilon_{3}k_{1}k_{2}V_{3}, \qquad (24)$$

where  $\langle V_i, V_i \rangle = \varepsilon_i = \pm 1$ . Comparing (24) with (17) we get the result.

**Proposition 14:** Let  $\gamma$  be a normal section of  $M_r^n$  at point  $p = \gamma(s)$  in the direction of *X*.  $\gamma$  is a non-null W-curve of rank 2 in  $M_r^n$ if and only if

$$\nabla_{X}\nabla_{X}X + g(\nabla_{X}X, \nabla_{X}X)g(X, X)X = 0$$
 (25)

holds.

**Proof:** Since  $\gamma'(s) = X(s)$ ,  $\gamma''(s) = \nabla_X \nabla_X X$  and

$$g(X, X) = \varepsilon_1, g(\nabla_X X, \nabla_X X) = \varepsilon_2 k_1^2$$

So, by the use of the equality  $\gamma''(s) = \varepsilon_2 k_1 V_2(s)$  we get the result.

**Theorem 15:** Let  $M_r^n$  be a totally umbilical submanifold of  $N_s^m$  with parallel mean curvature vector field. If the normal section  $\gamma$  is a W- curve of osculating order 2. Then  $\gamma$  is also a W-curve of  $N_s^m$  with the same order.

**Proof:** Suppose  $\gamma$  is a W-curve of rank 2 in  $M_r^n$  then it satisfies the equality (25). Further, by the use of (1) we get

$$\gamma'' = \widetilde{\nabla}_X X = \nabla_X X + h(X, X). \tag{26}$$

Since  $M_r^n$  is totally umbilical then g(X, X)H = h(X, X). So, the equation (26) reduces to

$$\gamma'' = \widetilde{\nabla}_X X = \nabla_X X + g(X, X)H.$$
(27)

Differentiating the equation (27) with respect to *X*, we obtain

$$\gamma''' = \widetilde{\nabla}_{X} \widetilde{\nabla}_{X} X = \nabla_{X} \nabla_{X} X + g(X, \nabla_{X} X) H + g(X, X)(-A_{H} X + D_{X} H).$$
(28)

Further, taking use of DH = 0 and (26)-(28) get

$$\begin{split} \widetilde{\nabla}_{X}\widetilde{\nabla}_{X}X + g(\widetilde{\nabla}_{X}X,\widetilde{\nabla}_{X}X)g(X,X)X \\ &= \nabla_{X}\nabla_{X}X - g(H,H)g(X,X)X \\ &+ \big\{g(\nabla_{X}X,\nabla_{X}X)g(X,X)\big\}g(X,X)X \\ &= \nabla_{X}\nabla_{X}X + g(\nabla_{X}X,\nabla_{X}X)g(X,X)X. \end{split}$$

So, by previous proposition  $\gamma$  is a W-curve of rank 2 in  $N_s^m$ .

#### References

[1] Ikawa T, 1980. On some curves in Riemannian geometry, Soochow J. Math., 7: 37-44.

[2] Ikawa T, 1985. On curves and submanifolds in an indefinite-Riemannian manifold, Tukuba J. Math., 9: 353-371.

[3] Blomstrom C, 1986. Planar geodesic immersions in pseudo-Euclidean space, Math. Ann., 274: 585-598.

[4] Hong S L, 1973. Isometric immersions of manifolds with plane geodesics in Euclidean space, J. Dif. Geo., 8: 259-278.

[5] Little J A, 1976. Manifolds with planar geodesics, J. Diff. Geom., 11: 265-285.

[6] Sakamoto K, 1985. Helical minimal immersions of compact Riemannian manifolds into a unit sphere, Trans. American Math. Soc., 288:765-790.

[7] Ferus D, Schirrmacher S, 1982. Submanifolds in Euclidean space with simple geodesics, Math. Ann., 260:57-62.

[8] Kim Y H, 1995. Minimal surface of pseudo-Euclidean spaces with geodesic

normal sections, Dif. Geo. and Its App., 5:321-329.

[9] Chen B Y, 1973. Geometry of submanifolds, Marcel Dekker Inc., New York.

[10] Ferus, D, 1974. Immersions with parallel second fundamental form, Math. Z., 140:87-92.

[11] Nakanishi Y, 1988. On helices and pseudo-Riemannian submanifolds, Tsukuba J. Math., 12:459-476.

[12] Chen B Y, 1981. Geometry of submanifolds and its applications, Science University of Tokyo.

[13] Kim Y H, 1989. Surfaces in a pseudo-Euclidean space with planar normal sections, J. Geom., 35:120-131.

[14] Li S J, 1987. Isotropic submanifolds with pointwise 3-planar normal sections, Boll. U. M. I., 7:373-385.

[15] Li S J, 1987. Spherical submanifolds with pointwise 3 or 4-planar normal sections, Yokohoma Math. J., 35:21-31.

[16] Arslan K, West A, 1995. Product submanifolds with P.3-PNS., Glasgow J. Math., 37:73-81.

[17] Arslan K, Celik Y, 1997. Submanifolds in real space form with 3planar geodesic normal sections, Far East J.Math.Sci., 5(1):113-120.

[18] Nakagawa H, 1980. On a certain minimal immersion of a Riemannian manifold into a sphere, Kodai Math., 3:321-340.