Original Paper



Comparative analysis of various modelling techniques for emission prediction of diesel engine fueled by diesel fuel with nanoparticle additives[§]

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Abstract

In this study, emissions of compression ignition engine fueled by diesel fuel with nanoparticle additives was modeled by regression analysis, artificial neural network (ANN) and adaptive neuro fuzzy inference system (ANFIS) methods. Cetane number (CN) and engine speed (rpm) were selected as input parameters for estimation of carbon monoxide (CO), oxides of nitrogen (NOx), and carbon dioxide (CO₂) emissions. The results of estimation techniques were compared with each other and they showed that regression analysis was not accurate enough for prediction. On the other hand, ANN and ANFIS modelling techniques gave more accurate results with respect to regression analysis; linear and non-linear. Especially ANFIS models can be suggested as estimation method with minimum error compared to experimental results.

Keywords: Adaptive neuro fuzzy inference system; Artificial neural network; Diesel engine; Regression analysis

1. INTRODUCTION

In recent years, depletion of fossil fuels forces researchers to search new alternative fuels. In literature, there are a lot of studies about fuels which have potential to replace fossil fuels used in internal combustion engines. In this respect, various biofuels and alcohols seem as good option [1]. In addition to scarcity of conventional fuels, efforts on performance en-hancement and emission reduction of engines are the other important issues on which engineers and engine manufacturers are working on it. Especially, the stringent emission legislations enforced manufacturers to develop new technologies [2]. Traditional engine research and development studies are both difficult and costly to meet emission limits imposed by legislations. Therefore, these costly studies are replaced by various cost-effective approaches as artificial neural networks (ANN) and computational fluid dynamics (CFD) [3]. ANNs are nonlinear computer algorithms, which can model the behavior of complex nonlinear processes. Recently, this method has been widely applied to various disciplines as automotive engineering [4]. Yusaf et al. studied the effect of using CPO (crude palm oil) - OD (ordinary diesel) blends as fuel on the performance of CI (compression ignition) engine. In addition, engine power output, fuel consumption, and exhaust-gas emission are evaluated and then predicted using ANN technique [5]. Shanmugam et al. used ANN modeling to predict the performance and exhaust emissions of the diesel engine using hybrid fuel and they revealed that the ANN approach could be confidently used to predict the performance and emissions of the diesel engine accurately [6]. Ghazikhani and Mirzaii predicted soot emission of a waste-gated turbo-charged DI diesel engine using ANN. The results showed the ANN approach can be used to accurately predict soot emis-sion of a turbo-charged diesel engine in different opening ranges of waste-gate (ORWG) [7].

On the other hand, there is another modelling approach called as adaptive neuro fuzzy inference system (ANFIS) which combines the benefits of ANNs and fuzzy logic. ANFIS modelling is very powerful technique with the ability of interpretable if-then rules [8]. Isin and Uzunsoy presented fuzzy logic-based prediction method to reveal the performance and emission characteristics of a single cylinder spark ignition (SI) engine, which uses different fuel mixtures [9]. Ozkan et al. used ANFIS to estimate the effect of methanol mixtures in different proportions on emission and performance of the motor [10]. Al-Hinti et al. used a neuro-fuzzy interface system to study the effect of boost pressure on the efficiency, brake mean effective pressure (BMEP), and the brake specific fuel consumption (BSFC) of a single cylinder diesel engine.

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Results of their study showed that the ANFIS technique can be used adequately to identify the effect of boost pressure on the different engine characteristics.

In this study, experimental studies were taken from the study of Ozgur [12]. He investigated effects of addition of oxygen containing nanoparticle additives to diesel and biodiesel fuels on diesel and biodiesel fuel properties and effects on diesel engine performance and emissions. This study aims to predict exhaust emissions of diesel engine by various approaches as regression analysis, ANN, ANFIS. Finally, performances of models were determined by comparing experimental values and the best estimation technique was stated.

2. MATERIALS AND METHODS

2.1 Experimental Studies

Engine performance tests were performed on a commercial four cylinder, four-stroke, naturally aspirated, water-cooled direct injection compression ignition engine. Engine gives 89 kW maximum power at 3200 rpm and 295 Nm maximum torque at 1800 rpm engine speed. Before the tests, the engine was operated for 15 minutes with diesel fuel to reach the operation temperature. A hydraulic dynamometer was used for determination of torque output. TESTO 350 XL gas analyzer was used to measure exhaust emissions. Emission data was collected by the help of a computer program. Measurement accuracy of the gas analyzer is ±10 ppm for CO, 1% for CO₂ and ±1 ppm for NOx. Measurement capacity of the device is 0-10000 ppm for CO, 0-50% for CO₂ emission and 0-3000 ppm for NOx. The speed sensor used to detect prime mover speed is the magnetic pickup (MPU). When a magnetic material (usually a gear tooth driven by the prime mover) passes through the magnetic field at the end of the magnetic pickup, a voltage is developed. The frequency of this voltage is translated by the speed into a signal which accurately depicts the speed of the prime mover. The Cetane number and indexes were measured by Zeltex ZX440 type device, which works under the close infrared spectrometer (NIR) principal. With the help of this principal the Cetane number measurement experiment became very fast and cheap with only 3% error compared to the time consuming expensive motor tests.

2.2 Regression Analysis

Regression analysis is commonly used to define quantitative relationships between a response variable and one or more explanatory variables [13]. Regression analysis can be applied to the data in linear and non-linear forms.

Linear relationship between dependent and independent variables can be expressed in form of [14]:

$$Y = \beta_0 + \beta_1 X_1 + \beta_2 X_2 + \dots + \beta_n X_n \tag{1}$$

where is dependent variable, to are equation parameters for linear relationship and to are independent variables.

Nonlinear regression is a form of regression analysis in which observational data are modeled by a nonlinear combination of the model parameters function. Non-linear relationship between dependent and independent variables can be expressed in form of [14]:

$$Y = a_0 \left(X_1^{a_1} \right) \left(X_2^{a_2} \right) \cdots \left(X_n^{a_n} \right)$$

$$\tag{2}$$

where is dependent variable, to are equation parameters for non-linear relationship and to are independent variables.

2.3 Artificial Neural Network

Artificial neural networks inspired by biological neural networks. They behave like human brain. As the brain, ANNs consist of many small, interconnected units [15]. These units called as neuron. A typical biological neuron was shown in Fig. 1.



Figure 1: A typical biological neuron.



Figure 2: Block diagram of model of ANN neuron [16].

Haykin stated mathematically that, we can describe a neuron k by the following equations [16]:

$$u_k = \sum_{j=1}^{N} w_{kj} x_j \tag{3}$$

$$y_k = \varphi(u_k + b_k) \tag{4}$$

Bias, denoted by bk, has the effect of increasing or lowering the net input of the activation function. $x_1, x_2, ..., x_m$ are the inputs; $w_{k1}, w_{k2}, ..., w_{km}$ are the weights of the neuron k; u_k is the linear combiner output due to input signals; $\phi(.)$ is the activation function; y_k is the output signal of the neuron.

2.4 Adaptive Neuro Fuzzy Inference System

Adaptive Neuro Fuzzy Inference System (ANFIS) is combination system of neural networks and fuzzy logic and it has been applied to various application areas and gives more accurate results with respect to conventional techniques [17]. In fuzzy logic, nonlinearity and complexity of modelling can be handled by rules, membership functions and inference processes [9]. ANFIS can construct set-of if-then rules with suitable membership functions to constitute input-output pairs [18].

Jang presented the basics of fuzzy inference system that uses neural network learning algorithm [18]. Fig. 3 shows the main architecture of ANFIS. In this figure, fuzzy inference system with two inputs (x, y) and one output (z) was considered. According to Takagi and Sugeno type inference system, following two fuzzy if-then rules has been supposed:

Rule 1: If x is A₁ and y is B₁ then $f1=p_1x+q_1y+r_1$

Rule 2: If x is A_2 and y is B_2 then $f2=p_2x+q_2y+r_2$

x and y are the input nodes, A and B are linguistic variables (small, large etc.) associated with this node function.

More detail about the layers of the structure can be found in the study of Jang [18].



Figure 3: Architecture of ANFIS [18]

2.5 Details of Models

2.5.1 Regression Models

SPSS software was used to perform regression analysis. It is well-known statistical and data management program. Cetane number (CN) and engine speed (rpm) was selected as predictor (independent) variables. Linear and non-linear form of regression analysis was evaluated separately. The results of the analysis were given in Table 1.

			-			
Y	Linear Regression			Non-linear Regression		
CO	109.993	-1.228	0.099	2.818	-0.089	0.636
NOx	1288.84	5.489	-0.247	11614.49	0.325	-0.484
CO2	8.726	0.03	-0.002	66.37	0.255	-0.428

Table 1 The results of regression analysis

2.5.2 ANN Models

Data set was generated by using the experimental results of previous study of Ozgur [12]. Then, the total data set was divided into two parts, training and testing data. Training part of data was for about 85% of total data. Remaining randomly selected 15% of total data was used to measure the estimation performance of model as testing.

Matlab software was used to perform ANN modelling. The ANN architecture was consisted of input, hidden and output layer as shown in Fig. 4.



Figure 4: Architecture of ANN

Learning algorithm of the present study is Levenberg–Marquardt (LM) algorithm. Logistic sigmoid transfer function (logsig) and linear transfer function (purelin) were used in the hidden layers and output layer of the network as an activation function, respectively. There was an input layer, hidden layer and output layer. Table 2 shows the architecture of ANN models for each estimated parameters.

Estimation	Learning Algorithm	ANN Structure	Hidden Layer Transfer Function	Output Layer Transfer Function	
CO	LM	2-30-1	logsig	purelin	
NOx	LM	2-21-1	logsig	purelin	
CO2	LM	2-19-1	logsig	purelin	

Table 2 Architecture of ANN models

Since there was not a certain number of hidden layer neuron, number of hidden layer was determined by trial and error method. Suitable numbers of hidden layer neuron was supplied in above Table 2.

2.5.3 ANFIS Models

Matlab software was used to perform ANFIS modelling. As ANN modelling, the total data set was divided into two parts, training and testing data. Similar to determining the number of hidden layer neuron, there is no basic rule to define the number and type of membership functions for input parameters. It is an iterative process [17]. Table 3 shows the architecture of ANN models for each estimated parameters.

Estimation	Input		Output			
	MF number	MF type	MF type			
СО	44	trimf	linear			
NOx	44	trimf	linear			
CO2	55	trimf	constant			

3. RESULTS AND DISCUSSIONS

In the following figures, testing periods of the each estimation method for CO, NOx and CO₂ were supplied.

In CO prediction, the worst estimation technique was linear regression with 9.41% error value with respect to experimental data. On the other hand, ANFIS is the best estimation technique with 4.89% error.



Figure 5: Testing Results of (i) regression analysis (ii) ANN (iii) ANFIS for CO

In testing period of NOx prediction, linear regression is worst and ANFIS is best prediction method with 5.65% and 2.72% error, respectively.



Figure 6: Testing Results of (iv) regression analysis (v) ANN (vi) ANFIS for NOx

In CO_2 prediction, the worst estimation technique was linear regression with 17.6% error value with respect to experimental data. ANFIS is the best estimation technique with 3.1% error.



Figure 7: Testing Results of (vii) regression analysis (viii) ANN (ix) ANFIS for CO2

Figs. 5, 6 and 7 showed the testing period of various modelling approaches for CO, NOx and CO_2 emissions, respectively. All predictions were compared with experimental values. Table 4 reveals the performance of both training and testing period of each model for each estimation parameter. Mean absolute percentage error (MAPE) was used as performance parameter.

		MAPE (%)	
		Training	Testing
CO	LR	16.19	9.41
	NLR	14.94	9.16
	ANN	14.81	5.39
	ANFIS	1.5	4.89
NOx	LR	8.87	5.65
	NLR	9.84	5.59
	ANN	9.58	4.6
	ANFIS	1.82	2.72
CO_2	LR	16.61	17.6
	NLR	13.33	10.63
	ANN	7.86	3.91
	ANFIS	4.12	3.1

Table 4 MAPE values of models for both training and testing

4. CONCLUSIONS

The purpose of this paper is to estimate emission of diesel engine by using cetane number of fuel and engine speed. In this respect, three different methods called as regression analysis, ANN and ANFIS were developed for prediction. Data were divided into two parts, training and testing. In training section model details were identified by using experimental data. In testing section, the accuracy and performance of the models were tested. For both emissions, LR and NLR gave worst results. It can clearly be seen from the Table 4. ANN models were more acceptable than regression results. Furthermore, ANFIS approach provided better performance then both regression analysis and ANN.

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