

A COMPUTER METHOD FOR PREPARING BETA DIAGRAMS (PROGRAM IN FORTRAN IV-H, USING AN IBM 360/67 COMPUTER)

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ABSTRACT.— A method for preparing beta diagrams has been programmed for the IBM OS/360 (FORTRAN H) computer. The 570 CALCOMP system has been used to output the resultant plots. The program finds spherical coordinates of intersections of traces of individual segments, then projects them on an equatorial plane by using stereographic projection principles. It makes necessary corrections to fit the projected points to an equal area polar net (Billing net). The program, then, to calculate intensity of distribution of projected points performs the following tasks: (a) distributes the additive value of each point to a one percent domain by using the Mellis method; (b) takes care of the values which might fall outside the primitive circle; (c) chooses a suitable contour interval and integrates the values between contours. The final distribution is displayed both by an output from line printer and an output from CALCOMP plotter on a 20-cm Billing net. The computer program described in this report may be used, by slight alterations, to prepare various diagrams used in structural geology and in fabric data analysis in structural petrology.

INTRODUCTION

This study was carried out by the author at Stanford University during the spring of 1968.

The program is prepared to draw beta diagrams, but by slight alterations can be used to prepare other useful diagrams.

Programs in different languages and using somewhat different techniques have been provided by Robinson (1963) and by Noble (1964). The method used in this program is believed by the present author to give more accurate results than the above-mentioned works; however no attempts will be made to compare between them.

In the following chapters the meaning of beta diagrams, the technique in their preparation and the computer program itself will be discussed rather briefly. A listing of the program and outputs from a test run are presented at the end of the text. Operating instructions for the program are given in the program as comment statements in logical steps.

EQUAL AREA NET

The following paragraph which summarizes the use of equal area net is quoted from Turner and Weiss (1963) :

«... Structural analysis is concerned especially with orientation data relating to planes and lines (fabric elements) and their intersections. In study of crystal morphology the relative orientations of planes and lines are conventionally represented and their geometric relations determined by means of the familiar stereographic projection—a tool which is commonly employed, too, in graphic solution of many problems in structural geology. In structural analysis, the necessity to evaluate preferred orientations of fabric elements imposes a peculiar limitation on graphic procedure. All equal area on the surface of the reference sphere must remain equal on the projection itself. This is not true of the stereographic projection, in which centrally situated areas are diminished relatively to peripheral areas of equivalent size on the reference sphere. To obviate this difficulty it is customary in structural analysis to use a type of equal-area projection—also known as the Lambert projection (after its inventor) or the Schmidt projection (after W. Schmidt who first used it in structural geology).

Both types of projection employ a reference sphere in which planes and lines passing through the center intersect the surface as great circles and points respectively. In equal-area projection as in stereographic projection, these are projected—but from the lower hemisphere only—onto the equatorial plane; but the graphic procedure employed maintains the desired equal-area specification which is absent from stereographic projection. Because of this property, density distribution of points on the projection faithfully reflects the preferred orientation of the corresponding lines passing through the center of the reference sphere. Stereographic projection is from a point source, and circles on the reference sphere appear as arcs of circles on the projection. This is not true of the equal-area projection; circles are projected as elliptical arcs, save where they lie in or normal to the plane of projection (the boundary circle and diameters of the projection respectively)...

Figure 1 illustrates the principles of the stereographic projection. For the stereographic projection can the transfer of configuration on sphere of a plane be carried out by direct geometrical construction. In equal-area type of projection the configuration is obtained by computational methods for which such concepts as the plane of projection, the center of projection and line of projection do not have a simple graphical meaning. Both, stereographic net (Wulff net) and equal-area net (Schmidt net or Lambert net) can be prepared as equatorial or polar projection.

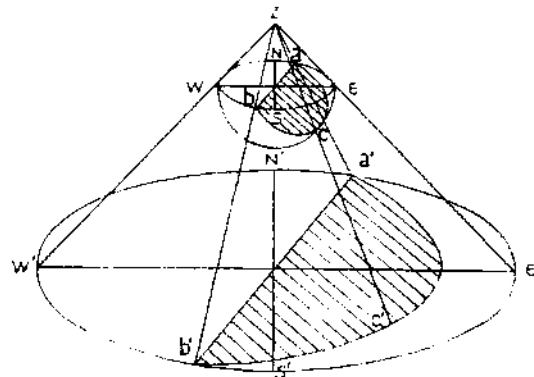
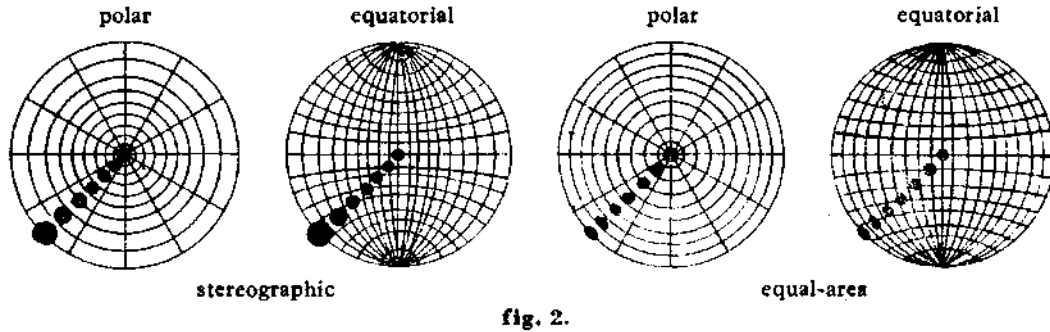


Fig. 1.

Equatorial projection is more often used because it enables the user to evaluate the coordinates of the intersections. In the present program the polar variety of equal-area net (this net is also called Billing equal-area net) is used, because it can be drawn much easier by plotter, and coordinates of intersection vectors are calculated by mathematical methods. Polar and equatorial nets of stereographic and equal-area projection are illustrated in Figure 2. Scale and area distortion on these nets are also presented on the same figure.

STATISTICAL USE OF EQUAL-AREA NET

The nature and degree of preferred orientation of a given type of planar or linear fabric element are expressed graphically by the distribution on an equal-area projection of points (poles, in the case of planar elements), representing the individual orientations of a large number of representative measured elements of



the kind in question. The points so plotted constitute a pattern of preferred orientation or an orientation diagram of the given element. A statistically random orientation is expressed by a pattern in which there is no obvious tendency for reproducible local concentration of plotted points. Most orientation diagrams representing tectonite subfabric show marked reproducible local concentration and complementary voids or sparsely populated areas. These are graphic evidence of preferred orientation.

To sharpen the pattern of preferred orientation expressed by points on a net, it is customary in structural analysis to draw density contours on the point diagrams. Each contour delineates an area within which the density of distribution of plotted points exceeds some minimum value, e.g. 5 % of the total points per 1 % of the projection area.

To count the points lying within any one percent circular area of the projection and to draw the contour, several contouring procedures are currently used: *Schmidt method* is by far widely used. In this method a contouring counter (Fig. 3a) is the principle device. It is a card with a circular hole 1/100 of the area of the complete equal-area net. This counter is placed on the net and the number of points which can be seen within the circle are counted and the percentage concentration is calculated (Fig. 3b). For example if there were 500 poles on the net, and at one position of the counter 10 occurred within the hole, then the percentage at the center of the counting circle would be $(10 \times 100/500)$ 2 percent. These percentages are recorded from place to place (usually controlled with a grid) on the net and the density distribution contoured. At the periphery of the net the percentages are calculated with a special counter (Fig. 36) so that a complete one percent area is used. *Mellis method* or circle method is another tool to contour the population density. Circles of 1 percent are drawn around each point taking the point as the center (Fig. 4a and 46). Overlapping area between two circles have a 2 percent concentration, those between

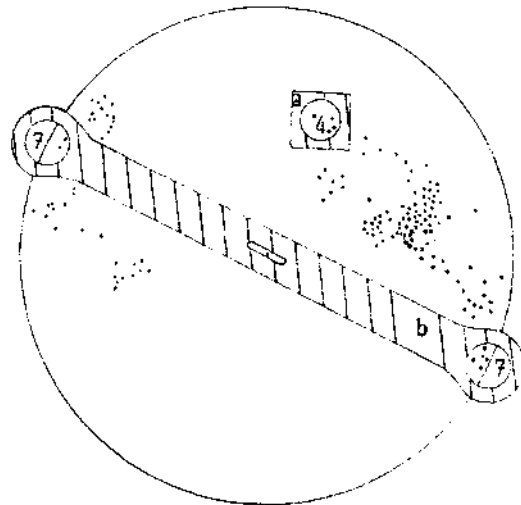


Fig. 3 (a-b).

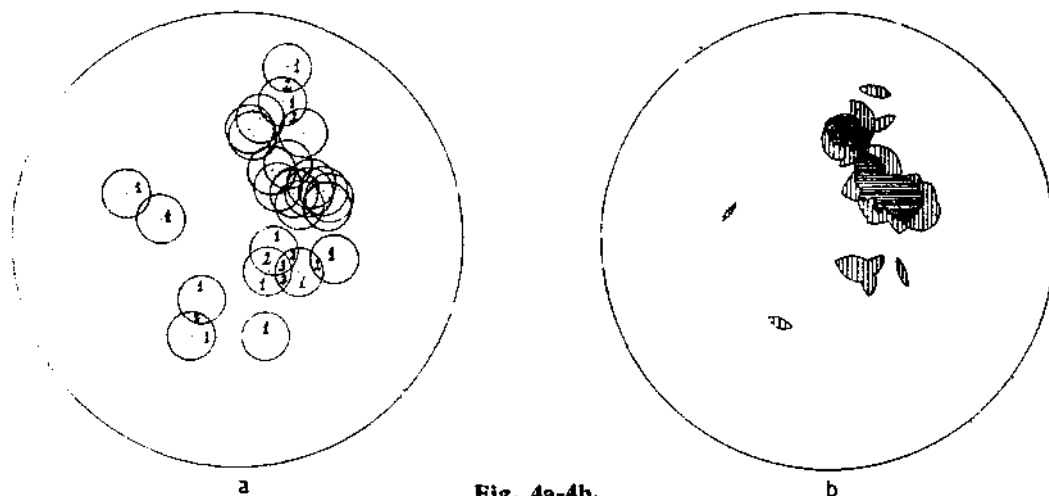


Fig. 4a-4b.

three circles have 3 percent concentration, etc. This method has sounder statistical meaning; also, it is the least subjective method of contouring: the only one by which strictly identical diagrams will be produced from the same point diagram by independent workers. But its application is limited because it becomes almost impossible to count the number of overlapping circles. However this inconvenience is overcome by using computer (in our program we have used this method).

The object of counting is to draw density contours connecting centers of circular areas within which the measured points are equally concentrated. Contouring is an arbitrary procedure the statistical significance of which has not been rigorously evaluated. The following rules are recommended by Turner and Weiss (1963): (1) On any diagram the number of contours should not be more than six. (2) The highest contour is chosen to emphasize and differentiate maxima large enough to stand out clearly on a projection 2 to 3 inches in diameter. For instance, if the areas of local concentration of 10 to 12 percent are small, it may be advisable to draw the highest contour at 8 percent. (3) In any diagram contour intervals should preferably be uniform.

BETA DIAGRAMS

The following paragraph is quoted from Ramsay (1967) :

«...Surfaces within a cylindrical fold contain a line parallel to the rectilinear generator and therefore the intersections of any two observations of measured tangent planes to the folded surface intersect in a line parallel to this generator. This line is known as a beta axis and is parallel to the fold axis. The stereogram or equal-area projection offers a very convenient way for graphic determination of the orientation of such beta axes. All the beta axes computed in this manner should have a parallel orientation (i.e., all the great circles representing individual surfaces in the fold should pass through a single point). In practice, however, folds rarely have a perfectly cylindrical form and the measurements of the fold surfaces are always subject to a certain error. This means that the computed beta axes do not generally coincide, but they are unimodally grouped around a point which gives the best fit orientation for the mean beta axis or fold axis. The number of beta intersection produced by the intersection of n observed planes (tangent planes) in the fold is given by the arithmetic progression:

$$S = 0 + 1 + 2 + 3 + \dots + (n-1) = \frac{n(n-1)}{2}$$

If $n > 3$, the number of beta intersections outnumbers the observation and in practice it may be almost impossible to determine their position in a single diagram (for example, if $n = 500$, then $S = 124,750$)...

However usage of high speed digital computers overcomes this impracticability.

Figures 5a and 5b illustrate the use of beta diagram.

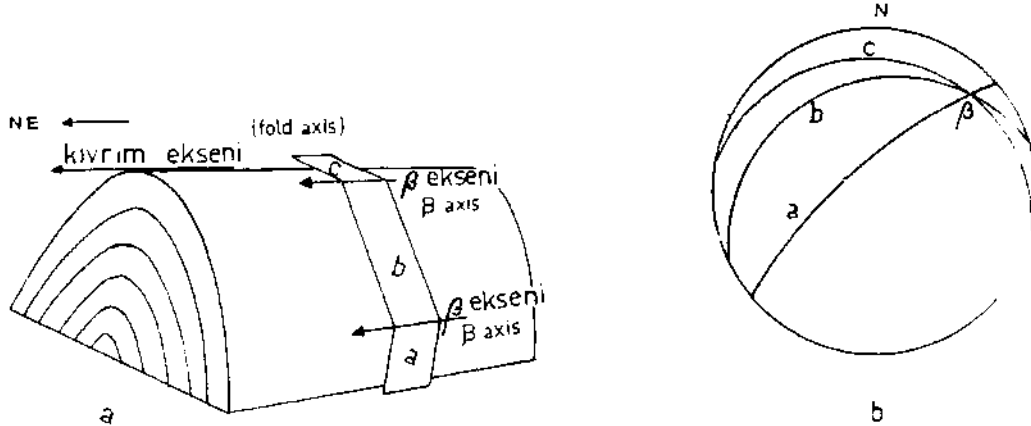


Fig. 5a-5b.

Beta diagrams can also be used to solve complex folding by dividing it to cylindrical portions. A fan of cleavage can be analysed by using beta diagrams. Other orientation studies can be performed by making slight changes in the present program or/and using only parts of it. (The function of every part in the program is explained by comment statements in the program itself and also in the next chapter so that one could modify the program.)

MAJOR STEPS IN THE PROGRAM

A real (100 X 100) array is used to fill in the values to be used in plotting, and an integer array KAR (100 X 100) is used to transfer values in real array to the corresponding percentage.

In PART ONE¹ the cells of the array outside the projection circle (net) are filled with 10,000 (Fig. 6).

In PART TWO angles representing measured form surfaces are read in (see chapter explaining the

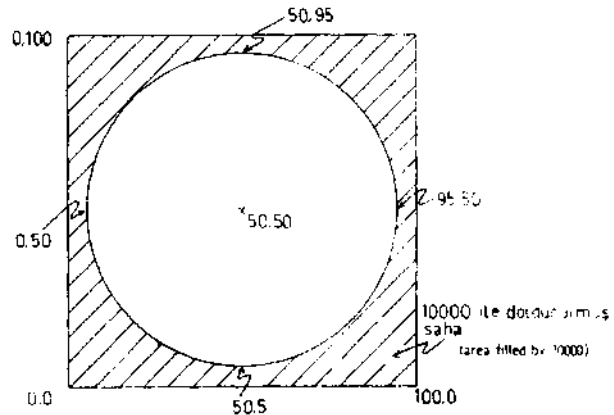


Fig. 6

¹ The beginning and end of parts are indicated in the program by means of comment statements.

inputs to the program). Pole of these surfaces are computed and direction cosines of the computed poles are stored in X, Y, Z arrays. (Positive X direction is to the north, Y to the east and Z downward.) These arrays are declared with 200 spaces each. This means one has to adjust this size if he wants to deal with more than 200 measurements. No other change in the program is required for such a modification. But it should be remembered that number (IS) of intersection is related to the number of the measurements by the formula mentioned above. IS might be a little smaller than the value predicted by the formula, because for surfaces having the same attitude, intersection is not possible. This fact is taken into account in the program (see Part Three).

In PART THREE direction cosines of vectors generated by the intersection of every two surfaces are evaluated using the following relations :

$$\begin{aligned} X' A + Y' B + Z' C &= 0 \text{ (cross product)} \\ X'' A + Y'' B + Z'' C &= 0 \text{ (cross product)} \\ A^2 + B^2 + C^2 &= 1 \text{ (theorem for direction cos.)} \end{aligned}$$

where X', Y', Z' are direction cosines of one and X'', Y'', Z'' are direction cosines of another vector. A, B, C are the corresponding direction cosines of the vector generated by intersection. Then these coordinates on the sphere are projected to an equatorial plane. Billing equal-area net is used in this case. For the equal-area projection the basic equation connecting the radius vector ρ with the polar distance (θ) has the form

$$\rho' = 2 R \sin \frac{\theta}{2} \quad (\text{Vistelius 1966})$$

In the program A and B are transformed using the above formula and geometrical relations (Fig. 7).

$$\rho = \overline{OR}^2 - C^2 = 1 - C^2 \quad (\text{OR is radius and equals 1})$$

$$\rho' = 2 \sin \frac{\theta}{2} \quad (\text{OR} = 1)$$

$$2 \sin \frac{\theta}{2} = 2 \sqrt{\frac{1 - \cos \theta}{2}} \quad \text{trigonometric relation}$$

$$\frac{\rho'}{\rho} = \frac{2 \sqrt{\frac{1 - \cos \theta}{2}}}{\sqrt{1 - C^2}}$$

But $\cos \theta = C$ and the formula takes the following form :

$$\frac{\rho'}{\rho} = \sqrt{\frac{2}{1 + C}}$$

From similar triangles shown on Fig. 8

AA/A and BB/B ratios can be calculated

$$AA = A \sqrt{\frac{2}{1 + C}} \quad BB = B \sqrt{\frac{2}{1 + C}}$$

The next step is to fill the AR array by using AA and BB coordinates

In PART FIVE values of AR array are transported to integer KAR array and in the mean time values in each cell are divided by (total number of points in the net/100) to find representative percentage value.

In PART SIX the final value of each cell is printed out. Coordinate axes are also printed. The circle is deformed to an ellipse, due to rectangular form of the characters. Area outside of the primitive circle is filled with = sign. The values smaller than 1 are not printed. Values larger than

9 are represented by alphabetical symbols. A table of these symbols is given at the bottom of the map. The maximum value on the map is also printed below them. The main objective of printing out such a map, despite the great distortion, is to furnish user with a reference table showing actual values in each cell.

In PART SEVEN 'CALCOMP' plotter subroutines are called to draw a 20-cm Billing equal-area net. 10° interval is used.

In PART EIGHT 'CALCOMP' plotter subroutines are called to plot the cell values by classifying them as it is shown in the table below. Symbols used in plotting are :

N, S, E, W for north, south, east, west.

★ for values $> 4/5$ of the max. value.

○ for values $> 3/5$ but $\leq 4/5$ of max.

△ for values $> 2/5$ but $\leq 3/5$ of max.

✱ for values $> 1/5$ but $\leq 2/5$ of max.

□ for values $\leq 1/5$

values less than one are ignored and left blank.

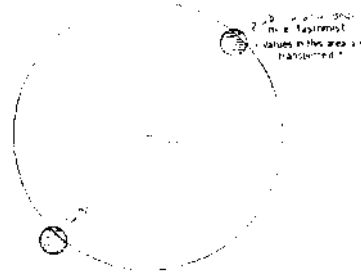


Fig. 10

INPUTS TO THE PROGRAM

The number N of measurements to be used should be punched in the very first data card. 15 format is used for this purpose. The upper limit for this N number is limited with the size of X, Y, Z arrays and it is set to 200 in this program. It could be augmented by simply changing the size of these arrays,.

N data cards must follow the very first card bearing the value of N. 215 format is used in these cards. First number being the azimuth and the second latitude of vectors representing dips. Azimuth value is the angle (from 0 to 360°) which the direction of the dip of measured plane makes with the north (clockwise direction being positive). It is expressed as integer degrees. Latitude is also expressed as integer degrees. It is the angle that the dip vector makes with the horizontal (from 0 to 90°).

JCL card must contain a special sign to cause page ejects to be suppressed, thus permitting to obtain a map printed without gap across page margins.

Another job control statement should designate that plotter is going to be used. One should examine the listing of the program for detail, but should also keep in mind that these formats are subject to change any time.

The program consumed maximum 2 minutes computer time for a data set of 50 measurements.

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R E F E R E N C E S

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- RAMSAY, J.G. (1967) : Folding and fracturing of rocks. *McGraw-Hill Co*, 568 p.
- ROBINSON, P.; ROBINSON, R. & GARLAND, S. (1963) : Preparation of beta diagrams in structural geology by digital computer. *Am. Journal Sci.*, v. 261, pp. 913-928.
- TURNER, F.J. & WEISS, L.E. (1963) : Structural analysis of metamorphic tectonites. *McGraw-Hill Co.*, 545 p.
- VISTELIUS, A.B. (1966) : Structural diagrams. *Pergamon Press*, 178 p.

COMPUTER PROGRAM LISTING

LEVEL 13 (23 MAY 67)

15/360 FORTRAN M

DATE 08.159/00.40.05

COMPILER OPTIONS - NAME= MAIN,OPT=00,LINECNT=57,SOURCE,EBCCIC,NOLIST,NOCHECK,LOAD,MAP,NOEDIT,NOED

```

C      PREPARATION OF META DIAGRAMS
C
C
C
C*****BEGINNING OF PART ONE
15N 0002      DIMENSION A(100,100)
15N 0003      GO 2000 M=1,100
15N 0004      DC 2000 L=1,100
15N 0005      2000      AR(L,1)=0.
15N 0006      INI 2100 K=1,5
15N 0007      GO 2100 L=1,100
15N 0008      AR(L,1)=10000.
15N 0009      AR(L,K)=10000.
15N 0010      AR(K+95,L)=10000.
15N 0011      2100      AR(L,K+55)=10000.
15N 0012      EL 2800 IM=1,2
15N 0013      DO 2400 I=N-1,2
15N 0014      M1=55
15N 0015      M1=61
15N 0016      K1=6
15N 0017      IF(I=N,EQ,1) GO TO 21
15N 0018      M1=101-M1
15N 0019      M1=6
15N 0020
15N 0021      IF(I=N,EQ,1) GO TO 22
15N 0022      K1=101-K1
15N 0023      22      DC 2200 K=M1, N1
15N 0024      AR(K,K1)=10000.
15N 0025      2200
15N 0026      M1=65
15N 0027      K1=1
15N 0028      IF(I=N,EQ,1) GO TO 23
15N 0029      M1=101-M1
15N 0030      M1=6
15N 0031      23      IF(I=N,EQ,1) GO TO 24
15N 0032      K1=101-K1
15N 0033      24      DC 2300 K=M1, N1
15N 0034      AR(K,K1)=10000.
15N 0035      DC 2400 K=2,12,2
15N 0036      M1=66+K
15N 0037      K1=2+K/2
15N 0038      IF(I=N,EQ,1) GO TO 25
15N 0039      M1=101-M1
15N 0040      M1=6
15N 0041      25      IF(I=N,EQ,1) GO TO 26
15N 0042      K1=101-K1
15N 0043      26      DC 2400 M=M1, N1
15N 0044      AR(M,K1)=10000.
15N 0045      2400      DO 2500 K=1,10
15N 0046      M1=78+K
15N 0047      K1=12+K
15N 0048      IF(I=N,EQ,1) GO TO 27
15N 0049      M1=101-M1
15N 0050      M1=6
15N 0051      27      IF(I=N,EQ,1) GO TO 28
15N 0052      K1=101-K1
15N 0053      28      DO 2500 M=M1, N1
15N 0054      AR(M,K1)=10000.
15N 0055      2500
15N 0061      DC 2600 K=2,10,2
15N 0062      M1=88+K/2
15N 0063      IF(I=N,EQ,1) GO TO 29
15N 0064      M1=101-M1
15N 0065      M1=6
15N 0066      29      DO 2600 I=K+1,2
15N 0067      K1=21+K+K
15N 0068      IF(I=N,EQ,1) GO TO 31
15N 0069      K1=101-K1
15N 0070      31      DC 2600 M=M1, N1
15N 0071      AR(M,K1)=10000.
15N 0072      2600
15N 0073      M1=94
15N 0074      IF(I=N,EQ,1) GO TO 32
15N 0075      M1=101-M1
15N 0076      M1=6
15N 0077      32      DC 2700 L=M1, N1
15N 0078      DO 2700 K=1,3
15N 0079      K1=33+K
15N 0080      IF(I=N,EQ,1) GO TO 2700
15N 0081      K1=101-K1
15N 0082      2700      AR(L,K1)=10000.
15N 0083      M1=95
15N 0084      K1=36
15N 0085      IF(I=N,EQ,1) GO TO 33
15N 0086      M1=6
15N 0087      33      IF(I=N,EQ,1) GO TO 34
15N 0088      K1=60
15N 0089      34      DC 2800 K=1,4
15N 0090      AR(M,K1+K)=10000.
15N 0091      2800
C*****END OF PART ONE
C
C

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Z
C*****BEGINNING OF PART TWO /
ISN 0096 INTEGER AZIMUT, DIP, G
ISN 0097 DIMENSION X(200), Y(200), Z(200)
ISN 0098 READ(5,1) A
ISN 0099 READ(5,10) A
ISN 0100 DO 100 I=1,A
ISN 0101 READ(5,10) AZIMUT, DIP
C*****THE DIRECTION OF THE PERPENDICULAR TO THE PLANE IS CALCULATED
C*****IN THE NEXT 5 LINES
ISN 0103 IF(AZIMUT+4E.180) GO TO 1
ISN 0104 READ(1,1) AZIMUT-180) *RAD
ISN 0105 GO TO 2
ISN 0106 1 READ(1,1) AZIMUT+180) *RAD
ISN 0107 2 READ(1,1) (90-DIP) *RAD
C*****SPHERICAL COORDINATES OF THE POLE IS CALCULATED IN THE NEXT 4 LINES AND
C*****STORED IN X, Y, Z ARRAYS
ISN 0109 COSDIP=COS(DIP)
ISN 0110 X(1)=COSDIP * COS(AZIMUT)
ISN 0111 Y(1)=COSDIP * SIN(AZIMUT)
ISN 0112 Z(1)=SIN(DIP)

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C*****END OF PART TWO
C
C*****BEGINNING OF PART THREE
ISN 0113 IS=0
ISN 0114 M=N-1
ISN 0115 DIMENSION E(1)
ISN 0116 DATA E/0.03,0.52,0.49,1.0,0.49,0.52,0.03/
ISN 0117 DO 200 K=1,M
ISN 0118 J=K+1
ISN 0119 DO 200 I=J,N
C*****IN THE NEXT 4 LINES POLES WITH SAME COORDINATES ARE CHOSEN AND JUMPED
ISN 0120 IF(X(K).NE.X(J)) GO TO 3
ISN 0121 IF(Y(K).NE.Y(J)) GO TO 3
ISN 0122 IF(Z(K).NE.Z(J)) GO TO 3
ISN 0123 GO TO 200
C*****IN THE NEXT 12 LINES THE SPHERICAL COORDINATES OF THE INTERSECTION ARE
C*****CALCULATED
ISN 0124 3 X122=X(K)*Z(J)
ISN 0125 X1Y2=X(K)*Y(J)
ISN 0126 X2Y1=X(J)*Y(K)
ISN 0127 X2Z1=X(J)*Z(K)
ISN 0128 Y122=Y(K)*Z(J)
ISN 0129 Y2Z1=Y(J)*Z(K)
ISN 0130 Z122=Z(K)*Z(J)
ISN 0131 Z2Z1=Z(J)*Z(K)
ISN 0132 E(1)=E(1)+X122+X1Y2+X2Y1+X2Z1+Y122+Y2Z1+Z122+Z2Z1
ISN 0133 E(1)=E(1)/((X122+X1Y2+X2Y1+X2Z1+Y122+Y2Z1+Z122+Z2Z1)**2)**.5
ISN 0134 E(1)=E(1)*.7071067811865475244008443028385
ISN 0135 E(1)=E(1)*.7071067811865475244008443028385
ISN 0136 E(1)=E(1)*.7071067811865475244008443028385
ISN 0137 E(1)=E(1)*.7071067811865475244008443028385
ISN 0138 E(1)=E(1)*.7071067811865475244008443028385
C*****IN THE FOLLOWING PART, UNTIL STATEMENT NUMBERED 200, SPHERICAL COORDI-
C*****NATES ARE TRANSFORMED TO A HILLING NET AND ONE PERCENT CIRCLE AREA ARE
C*****PLotted WITH VALUES
ISN 0139 IAA=5000*(1-2.*E(1)/A)-C**2
ISN 0140 AA=AA*TRANS
ISN 0141 BA=BA*TRANS
ISN 0142 AA1=(AA/0.031426)*50.
ISN 0143 BA1=(BA/0.031426)*50.
ISN 0144 IAA=AA1
ISN 0145 IBA=BA1
ISN 0146 IAA2=IAA-2
ISN 0147 IAA3=IAA+2
ISN 0148 IBB=IBB-3
ISN 0149 IBB2=IBB+3
ISN 0150 IBB3=IBB-2
ISN 0151 IBB4=IBB+2
ISN 0152 DO 3000 L=IAA2, IAA3
ISN 0153 DO 5000 G=IBB3, IBB4
ISN 0154 DO 1000 AR(L,G)=AR(L,G)+1.
ISN 0155 DO 3100 L=IBB2, IBB4
ISN 0156 AR(LAA+3,L)=AR(LAA+3,L)+1.
ISN 0157 AR(LAA+3,L)=AR(LAA+3,L)+1.
ISN 0158 DO 3200 L=1,9,8
ISN 0159 DO 3200 G=1,7
ISN 0160 AR(LAA+5+L,(IBB-4+G)+AR(LAA+5+L,(IBB-4+G)+E(G)
ISN 0161 DO 3300 L=1,9,8
ISN 0162 DO 3300 G=1,7
ISN 0163 AR(LAA+4+G,(IBB-5+L)=AR(LAA+4+G,(IBB-5+L)+E(G)
ISN 0164 DO 3400 L=1,7,6
ISN 0165 DO 3400 G=1,7,6
ISN 0166 AR(LAA+4+L,(IBB-4+G)+AR(LAA+4+L,(IBB-4+G)+.79
ISN 0167 DO 200 CONTINUE
C*****END OF PART THREE
C
C

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C*****BEGINNING OF PART FOUR
LSA 0160 UC 4000 L=1,100
LSA 0161 DC 4000 M=1,100
LSA 0170 IF (AM(L,M).LE.10000.) GO TO 400
LSA 0171 ILL=101-2*M
LSA 0172 KILL=FLCAT(I*LL)
LSA 0174 IMM=101-2*M
LSA 0175 KIMM=FLCAT(I*MM)
LSA 0176 KILLL=SQ./SQRT((KIMM/RILL)**2+1.)
LSA 0177 ILLLL=I*IX(I*ILL)
LSA 0178 KIMM=SQ./SQRT((KILL/RIMM)**2+1.)
LSA 0179 IMM=I*IX(I*IMM)
LSA 0180 IFF(ILL.LT.0.0) GO TO 42
LSA 0182 ILLLL=L+ILL
GO TO 43
LSA 0184 42 ILLLL=L-ILL
LSA 0185 43 IFF(IMM.LT.0.0) GO TO 44
LSA 0187 IMM=I+IMM
GO TO 45
LSA 0189 44 IMM=I-IMM
LSA 0190 45 ARI(ILL,IMM)*KAR(ILL,IMM)*AR(L,M)-10000.
LSA 0191 AR(L,M)=10000.
LSA 0192 4000 CONTINUE
C*****END OF PART FOUR
C
C
C
C*****BEGINNING OF PART FIVE
LSA 0193 INTEGER KAR(100,100)
LSA 0194 A(S)=FLUAT(IIS)
LSA 0195 S=L*IS/100.
LSA 0196 GO 5000 K=1,100
LSA 0197 DC 5000 L=1,100
LSA 0198 IF (KAR(L,L).EQ.10000.) GO TO 52
LSA 0200 IFF(A(L).EQ.0.0) GO TO 51
LSA 0201 KAR (K,L)=KAR(L,I)/S
GO TO 5000
LSA 0204 51 KAR(L,L)=0
GO TO 5000
LSA 0205 52 KAR(L,L)=110
LSA 0206 5000 CONTINUE
LSA 0207 C*****END OF PART FIVE
C
C
C
C*****BEGINNING OF PART SIX
LSA 0208 00 FORMAT(11H)
LSA 0209 01 IE(6,4C)
LSA 0210 20 FORMAT('R',13,100A1)
LSA 0211 DIMENSION PAR(30), RKUM(100)

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C*****VALUES FROM 1 TO NINE WILL BE PRINTED WITH THEIR NUMERICAL VALUES
C*****VALUES GREATER THAN NINE WILL HAVE THEIR CORRESPONDING ALPHABETICAL
C*****NOTATION STORED IN PAR ARRAY
C*****VALUES SMALLER THAN 1 WILL BE LEFT BLANK
LSA 0212 DATA PAR/'1','2','3','4','5','6','7','8','9','A','B','C','D','E','F',
IRKUM/'R','RKUMY','/','RKUPZ'/'
LSA 0213 00 8000 KLL=1,100
LSA 0214 K=101-KLL
LSA 0215 DC 6100 L=1,100
LSA 0216 I=KAR(K,L)
LSA 0217 IFF(I.LT.110) GO TO 64
LSA 0218 RKUM(L)=RKUMZ
LSA 0220 GO TO 6100
LSA 0221 64 IFF(I.GE.11) GO TO 63
LSA 0223 RKUM(L)=KLLMY
LSA 0224 GO TO 6100
LSA 0225 64 IFF(I.LE.30) GO TO 61
LSA 0227 RKUM(L)=KLLMX
LSA 0228 GO TO 6100
LSA 0229 61 RKUM(L)=PAR(I)
LSA 0230 6100 CONTINUE
LSA 0231 WRITE(6,20)K,(RKUM(L),L=1,100)
LSA 0232 6000 CONTINUE
LSA 0233 J=INTE(1000/I)
LSA 0234 DATA JCCR/10*0/
LSA 0235 70 FORMAT(' ',10(10))
LSA 0236 WRITE(6,7C) JCCR
LSA 0237 30 FORMAT(////)
LSA 0238 WRITE(6,3C)
LSA 0239 40 FORMAT(' A=10,B=11,C=12,D=13,E=14,F=15,G=16',/ ' H=17,I=18,J=19,K=2
70,L=21,M=22,N=23',/ ' O=24,P=25,Q=26,R=27,S=28,T=29,U=30',/ ' X=31-1
700')
LSA 0240 WRITE(6,4C)

```

```

C*****END OF PART SIX
C
C
C
C*****BEGINNING OF PART SEVEN
LSA 0241 MAX=KAR(4C,4C)
LSA 0242 GO 8000 K=1,100
LSA 0243 DC 8000 L=1,100
LSA 0244 IF (KAR(K,L).EQ.110) GO TO 8000
LSA 0246 C=KAR(K,L).GT.MAX) MAX=KAR(K,L)
LSA 0248 8000 CONTINUE
LSA 0249 MAX4=(MAX**4)**5
LSA 0250 MAX35=(MAX**3)**5
LSA 0251 MAX25=(MAX**2)**5
LSA 0252 MAX15=MAX**5
LSA 0253 WRITE(6,30)
LSA 0254 50 FORMAT(' MAX=',15)
LSA 0255 WRITE(6,50)MAX
LSA 0256 CALL STRTP(10)
LSA 0257 REAL IEFA,PI,DIA,V,W,P1/3.14159265/,PI18,PI180,DIY,SCFAC
LSA 0258 PI18=PI/18.
LSA 0259 PI180=PI/180.
LSA 0260 QIV=2C./I2.54*90.)

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15N 0261          SCFAC=(10./2.54)/(2.*SIN(90./2.)*RAD)
15A 0262          V=50.*DIV
15A 0263          W=5.0*DIV
15A 0264          CALL PLOT1(V,W,3)
15N 0265          DO 7000 I=1,90,10
15N 0266          DIA=2*SIN(I*PI/2)*PI/180*SCFAC
15A 0267          DO 7000 IF=1,361
15A 0268          FI=I*PI/180
15N 0269          V=SIN(FI)*DIA+50.*DIV
15N 0270          W=CCS(FI)*DIA+50.*DIV
15A 0271          CALL PLOT1(V,W,2)
15N 0272          7000          CONTINUE

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```

C*****END OF PART SEVEN
C
C
C
C
C*****BEGINNING OF PART EIGHT

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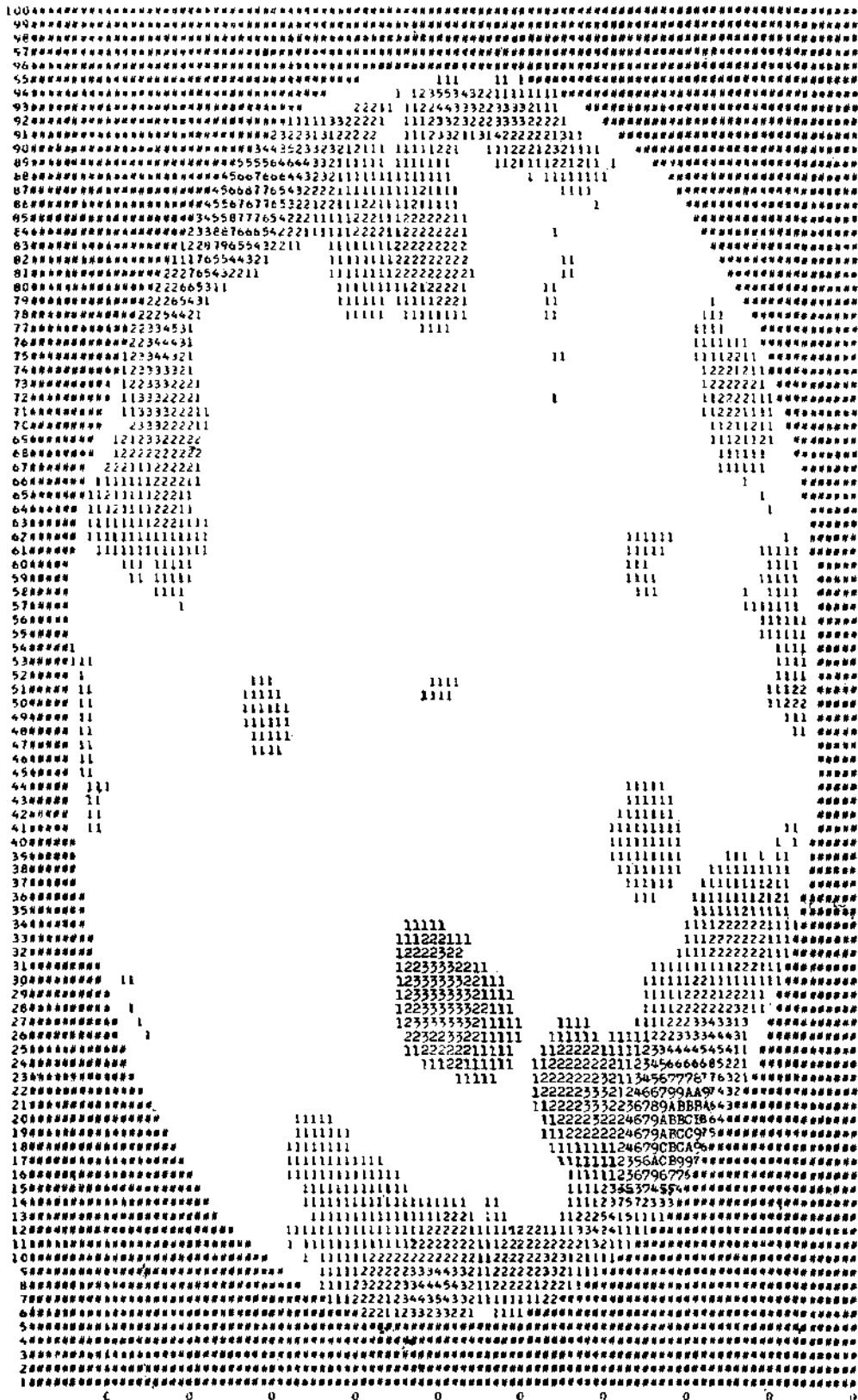
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15A 0273          DIA=2*SIN(90./2.)*RAD*SCFAC
15A 0274          DO 7100 IF=1,19
15A 0275          FI=I*PI/180
15N 0276          V=SIN(FI)*DIA+50.*DIV
15N 0277          W=CCS(FI)*DIA+50.*DIV
15A 0278          CALL PLOT1(V,W,3)
15N 0279          FI=I*PI/180
15A 0280          V=SIN(FI)*DIA+50.*DIV
15A 0281          W=CCS(FI)*DIA+50.*DIV
15N 0282          CALL PLOT1(V,W,2)
15A 0283          7100          CONTINUE
15N 0284          V4=(4.-0.5)*DIV
15A 0285          V5=(5.0-0.5)*DIV
15N 0286          V6=(6.-0.5)*DIV
15N 0287          DIMENSION BCD(10)
15A 0288          DATA BCD/266,295,262,255,20E,270,202,75,247
15N 0289          CALL SYMBL1(V4,V5,0.08,BCD1),0.0,-1)
15N 0290          CALL SYMBL1(V56,V50,0.08,BCD2),0.0,-1)
15N 0291          CALL SYMBL1(V50,V4,0.08,BCD3),0.0,-1)
15N 0292          CALL SYMBL1(V50,V56,0.08,BCD4),0.0,-1)
15A 0293          GO TO 8100
15N 0294          81          DO 8100 L=1,100
15N 0295          IF (KAR(L),LE,1.08,KAR(L),GT,10) GO TO 8100
15A 0296          IF (KAR(L),LE,MAX5) GO TO 82
15N 0297          ERK1=K
15N 0298          ERK2=(ERK1-0.5)*DIV
15N 0299          ERK1=L
15N 0300          ERK2=(ERK1-0.5)*DIV
15N 0301          CALL SYMBL1(ERK2,ERK2,0.08,BCD5),0.0,-1)
15N 0302          GO TO 8100
15N 0303          82          IF (KAR(L),LE,MAX5) GO TO 84
15N 0304          ERK1=K
15N 0305          ERK2=(ERK1-0.5)*DIV
15N 0306          ERK1=L
15N 0307          ERK2=(ERK1-0.5)*DIV
15N 0308          CALL SYMBL1(ERK2,ERK2,0.08,BCD6),0.0,-1)
15N 0309          GO TO 8100
15N 0310          83          IF (KAR(L),LE,MAX5) GO TO 85
15N 0311          ERK1=K
15N 0312          ERK2=(ERK1-0.5)*DIV
15N 0313          ERK1=L
15N 0314          ERK2=(ERK1-0.5)*DIV
15N 0315          CALL SYMBL1(ERK2,ERK2,0.08,BCD7),0.0,-1)
15N 0316          GO TO 8100
15N 0317          84          IF (MAX(L,5) GO TO 8100
15N 0318          ERK1=K
15N 0319          ERK2=(ERK1-0.5)*DIV
15N 0320          ERK1=L
15N 0321          ERK2=(ERK1-0.5)*DIV
15N 0322          CALL SYMBL1(ERK2,ERK2,0.08,BCD8),0.0,-1)
15N 0323          GO TO 8100
15N 0324          85          IF (MAX(L,5) GO TO 8100
15N 0325          ERK1=K
15N 0326          ERK2=(ERK1-0.5)*DIV
15N 0327          ERK1=L
15N 0328          ERK2=(ERK1-0.5)*DIV
15N 0329          CALL SYMBL1(ERK2,ERK2,0.08,BCD9),0.0,-1)
15N 0330          GO TO 8100
15N 0331          8100          CONTINUE
15N 0332          ALL ENDP
15N 0333          C*****END OF PART EIGHT
15N 0334          *****
15N 0335          END

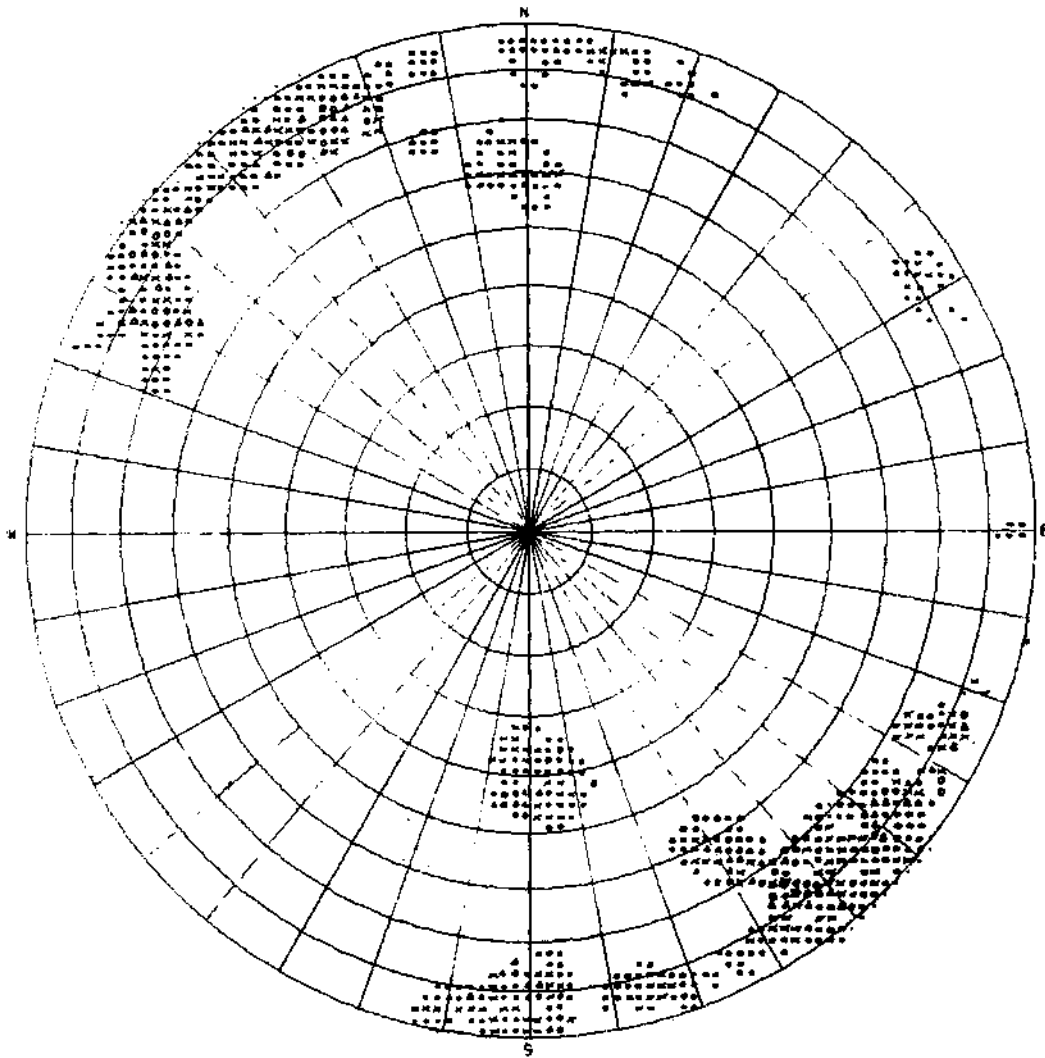
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BETA DIAGRAM DRAWN BY LINE PRINTER DURING A TEST RUN OF
THE PROGRAM



A=10, B=11, C=12, D=13, E=14, F=15, G=16
H=17, I=18, J=19, K=20, L=21, M=22, N=23
O=24, P=25, Q=26, R=27, S=28, T=29, U=30
X=31-100



Beta diagram entirely drawn by CALCOMP plotter during a test run of the program. (Original diameter was 20 cm. The symbols are darkened by hand for printing purposes)