

On Lightlike Hypersurfaces of An Indefinite f -Kenmotsu Space Form

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(Communicated by Johann T. DAVIDOV)

Abstract

In the present study, we consider a f -Kenmotsu space form $\overline{M}(c)$ and we investigate its lightlike hypersurfaces. We prove the non-existence of these type hypersurfaces of an f -Kenmotsu space form when f is a constant function and it takes different values from $-c$ or $3c$ and so we give a characterization of lightlike hypersurfaces on a f -Kenmotsu space form. Finally, we obtain some related properties.

Keywords: Indefinite f -Kenmotsu space form; Lightlike hypersurface; Second fundamental form.

AMS Subject Classification (2010): Primary: 53D10 ; Secondary: 53C15; 53C25; 53C35.

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1. Introduction

It is well-known that one has three different types of submanifolds in semi-Riemannian manifolds as spacelike, timelike and lightlike. These conditions are determined by the characteristic structure of the induced metric on the tangent space. When a semi-Riemannian manifold is given, we directly obtain a natural existence of lightlike subspaces, due to the degeneracy of the metric, there are fundamental differences between the study of lightlike submanifolds and classical theory of Riemannian and semi-Riemannian submanifolds ([4] and [8]). Moreover, this topic is quite new and it has a developable aspect. Many authors focus on this topic and they investigate lightlike hypersurfaces in different ambient spaces in ([1]-[3], [5], [6], [10]).

Motivated by the previous works, we investigate the characteristic properties of lightlike hypersurfaces of an indefinite f Kenmotsu space form and we get some conditions on the non-existence of lightlike hypersurfaces of an f -Kenmotsu space form when f is a constant function and it is not equal to $-c$ or $3c$. Thus, we give a characterization of these hypersurfaces on $\overline{M}(c)$ and we obtain some related results. On the other hand, we compute Gauss and Codazzi equations of these type hypersurfaces.

2. Preliminaries

Let \overline{M} be a $(2n + 1)$ -dimensional differentiable manifold. We can say that it has a (φ, ξ, η) -structure if we have a $(1, 1)$ tensor field φ , a vector field ξ and a 1-form η which satisfy

$$\eta(\xi) = 1 \quad \text{and} \quad \varphi^2 = -I + \eta \otimes \xi \quad (2.1)$$

where I denotes the identity transformation. If the \overline{M} endowed with a (φ, ξ, η) -structure admits a compatible semi-Riemannian metric \overline{g} such that

$$\overline{g}(\varphi x, \varphi y) = \overline{g}(x, y) - \varepsilon \eta(x) \eta(y) \quad \text{and} \quad \eta(x) = \varepsilon \overline{g}(x, \xi) \quad (2.2)$$

for all vector fields $x, y \in \chi(\overline{M})$, then we call it an indefinite almost contact metric manifold. Here,

$$\overline{g}(\xi, \xi) = \varepsilon \quad \text{and} \quad \varepsilon = \begin{cases} 1, & \text{if } \xi \text{ is spacelike} \\ -1, & \text{if } \xi \text{ is timelike.} \end{cases}$$

Furthermore an indefinite almost contact metric manifold \overline{M} is called an indefinite f -Kenmotsu manifold if the following properties hold

$$(\overline{\nabla}_x \varphi)y = f \{-\overline{g}(\varphi x, y)\xi + \eta(y)\varphi x\} \quad \text{and} \quad \overline{\nabla}_x \xi = f\varphi^2 x \quad (2.3)$$

where f denotes a smooth function defined on \overline{M} . An indefinite f -Kenmotsu manifold is a natural extension of an f -Kenmotsu manifold defined by Olszak in [7].

Now, for an indefinite f -Kenmotsu manifold \overline{M} , if its Riemannian curvature tensor \overline{R} satisfies

$$\begin{aligned} \overline{R}(x, y)z &= \frac{c-3f}{4} \{\overline{g}(y, z)x - \overline{g}(x, z)y\} \\ &+ \frac{c+f}{4} \{\overline{g}(\varphi y, z)\varphi x - \overline{g}(\varphi x, z)\varphi y \\ &- 2\overline{g}(\varphi x, y)\varphi z + \overline{g}(x, z)\eta(y)\xi \\ &- \overline{g}(y, z)\eta(x)\xi + \eta(x)\eta(z)y - \eta(y)\eta(z)x\} \end{aligned} \quad (2.4)$$

for all vector fields x, y and z on \overline{M} , then it is called an indefinite f -Kenmotsu space form and we denote it $\overline{M}(c)$. Moreover, if f is a constant function which is equal to α then it is also called α -Kenmotsu space form. Also, it is said that Kenmotsu space form is a 1-Kenmotsu space form.

Now, we recall some fundamental properties which we use in the next section from [9]. Let $(M, g, S(TM))$ be a lightlike hypersurface of semi-Riemannian manifold $(\overline{M}, \overline{g})$ and $\overline{\nabla}$ be the Levi-Civita connection on \overline{M} with respect to \overline{g} , where $S(TM)$ denotes the screen distribution. Then we have

$$\overline{\nabla}_x y = \nabla_x y + h(x, y) \quad (2.5)$$

and

$$\overline{\nabla}_x V = -A_V x + \nabla_x^\perp V \quad (2.6)$$

for all vector fields $x, y \in \Gamma(TM)$ and $V \in \Gamma(ltr(TM))$, where $ltr(TM)$ is the lightlike transversal vector bundle of M . Moreover, it is said that $\nabla_x y, A_V x \in \Gamma(TM)$ and $h(x, y), \nabla_x^\perp V \in \Gamma(ltr(TM))$ and also it can be easily seen that ∇ is a torsion free linear connection on M , h is a $\Gamma(ltr(TM))$ -valued symmetric $F(M)$ -bilinear form on $\Gamma(TM)$, A_V is a $F(M)$ -linear operator on $\Gamma(TM)$ and ∇^\perp is a linear connection on the vector bundle $ltr(TM)$.

Let us suppose that $\{\tilde{E}, \tilde{N}\}$ is a pair of sections on $U \subset M$. Thus one can define a symmetric $F(U)$ -bilinear form \tilde{B} and a 1-form ρ on U as follows:

$$\tilde{B}(x, y) = \overline{g}(h(x, y), \tilde{E}) \quad (2.7)$$

and

$$\rho(x) = \overline{g}(\nabla_x^\perp \tilde{N}, \tilde{E}) \quad (2.8)$$

for each $x, y \in \Gamma(TM|_U)$. Hence, by using (2.5), (2.6) we locally get

$$\overline{\nabla}_x y = \nabla_x y + \tilde{B}(x, y)\tilde{N} \quad (2.9)$$

and

$$\overline{\nabla}_x V = -A_{\tilde{N}} x + \rho(x)\tilde{N} \quad (2.10)$$

respectively, where \tilde{B} is called a local second fundamental form, $A_{\tilde{N}}$ denotes a shape operator and ∇ is the induced linear torsion free connection. Furthermore, (2.9) and (2.10) are called Gauss and Weingarten formulas of the lightlike hypersurface of \overline{M} , respectively.

Now, let \tilde{P} be the projection of TM on $S(TM)$. Then the local Gauss and Weingarten formulas can be given by

$$\nabla_x \tilde{P}y = \nabla_x^\circ \tilde{P}y + \tilde{C}(x, \tilde{P}y)\tilde{E} \quad (2.11)$$

and

$$\nabla_x \tilde{E} = -A_E^\circ x - \rho(x) \tilde{E} \quad (2.12)$$

where $\nabla_x \tilde{P}y$, $A_E^\circ x \in S(TM)$ and \tilde{C} denotes a 1-form on U . Then we obtain

$$g(A_{\tilde{N}}x, \tilde{P}y) = \tilde{C}(x, \tilde{P}y), \quad \bar{g}(A_{\tilde{N}}x, \tilde{N}) = 0 \quad (2.13)$$

and

$$g(A_E^\circ x, \tilde{P}y) = \tilde{B}(x, \tilde{P}y), \quad \bar{g}(A_E^\circ x, \tilde{N}) = 0 \quad (2.14)$$

for all vector fields $x, y \in \Gamma(TM)$.

Let \bar{R} and R be curvature tensors with respect to the connections $\bar{\nabla}$ and ∇ , respectively. So we get a relation between \bar{R} and R as

$$\begin{aligned} \bar{R}(x, y)z &= R(x, y)z + A_{h(x, z)}y - A_{h(y, z)}x \\ &\quad + (\nabla_x h)(y, z) - (\nabla_y h)(x, z). \end{aligned} \quad (2.15)$$

Also, we state that the induced connection on M satisfies

$$(\nabla_x g)(y, z) = \tilde{B}(x, y)\tilde{\omega}(z) + \tilde{B}(x, z)\tilde{\omega}(y) \quad (2.16)$$

for any $x, y, z \in \Gamma(TM)$, where $\tilde{\omega}$ is a differential 1-form locally defined on M as follow:

$$\tilde{\omega}(x) = \bar{g}(x, \tilde{N}) \quad (2.17)$$

for each $x \in \Gamma(TM)$.

3. Lightlike Hypersurfaces of Indefinite f -Kenmotsu Space Forms

Lemma 3.1. *Let M be a lightlike hypersurface of $\bar{M}(c)$. Then*

(i) *we compute the Gauss formulae of M like that*

$$\begin{aligned} R(x, y)z &= \frac{c-3f}{4} \{ \bar{g}(y, z)x - \bar{g}(x, z)y \} \\ &\quad + \frac{c+f}{4} \{ \bar{g}(\varphi y, z)\tilde{\sigma}x - \bar{g}(\varphi x, z)\tilde{\sigma}y \\ &\quad - 2\bar{g}(\varphi x, y)\tilde{\sigma}z + \bar{g}(x, z)\eta(y)\xi \\ &\quad - \bar{g}(y, z)\eta(x)\xi + \eta(x)\eta(z)y \\ &\quad - \eta(y)\eta(z)x \} - \tilde{B}(x, z)A_{\tilde{N}}y + \tilde{B}(y, z)A_{\tilde{N}}x. \end{aligned} \quad (3.1)$$

(ii) *the Codazzi formulae of M is given as*

$$\begin{aligned} (\nabla_y h)(x, z) - (\nabla_x h)(y, z) &= \frac{c+f}{4} \{ \bar{g}(\varphi y, z)\tilde{v}(x) \\ &\quad - \bar{g}(\varphi x, z)\tilde{v}(y) - 2\bar{g}(\varphi x, y)\tilde{v}(z) \} \tilde{N} \end{aligned} \quad (3.2)$$

for any $x, y, z \in \Gamma(TM)$.

Proof. Let M be a lightlike hypersurface of an indefinite f -Kenmotsu space form $\bar{M}(c)$. For any $x \in \Gamma(TM)$, we directly have

$$\varphi x = \tilde{\sigma}x + \tilde{v}(x)\tilde{N} \quad (3.3)$$

where $\tilde{v}(x) = g(x, V)$, $V = -\varphi\tilde{E}$ and $\tilde{\sigma}$ is a tensor field of type $(1, 1)$ defined on M . From (2.4) and (2.15), we deduce

$$\begin{aligned} \bar{R}(x, y)z &= \frac{c-3f}{4} \{ \bar{g}(y, z)x - \bar{g}(x, z)y \} \\ &\quad + \frac{c+f}{4} \{ \bar{g}(\varphi y, z)\varphi x - \bar{g}(\varphi x, z)\varphi y \\ &\quad - 2\bar{g}(\varphi x, y)\varphi z + \bar{g}(x, z)\eta(y)\xi \\ &\quad - \bar{g}(y, z)\eta(x)\xi + \eta(x)\eta(z)y - \eta(y)\eta(z)x \} \\ &\quad - A_{h(x, z)}y + A_{h(y, z)}x - (\nabla_x h)(y, z) + (\nabla_y h)(x, z). \end{aligned} \quad (3.4)$$

By virtue of (3.3) and from (3.4), then we get (3.1) and (3.2) by considering the tangential and transversal vector bundle parts. \square

Lemma 3.2. For a lightlike hypersurface M of an indefinite f -Kenmotsu space form $\overline{M}(c)$. We have the following

$$\begin{aligned} \bar{g}\left(R\left(x, \tilde{E}\right) z, \tilde{N}\right) &= -\frac{c-3f}{4} \bar{g}(x, z) - \frac{c+f}{4} \{\tilde{v}(z) \tilde{\omega}(\varphi x) \\ &\quad + 2\tilde{v}(x) \tilde{\omega}(\varphi z) - \eta(x) \eta(z)\}. \end{aligned}$$

Proof. It can be easily seen from Lemma 3.1. \square

Lemma 3.3. For a lightlike hypersurface M of an indefinite f -Kenmotsu space form $\overline{M}(c)$. Then we have

$$\tilde{B}(y, U) = \tilde{C}(y, V)$$

for any $y \in \Gamma(TM)$, where $U = -\varphi\tilde{N}$.

Proof. By virtue of definition \tilde{B} , we have

$$\begin{aligned} \tilde{B}(y, \varphi\tilde{N}) &= \bar{g}\left(h\left(y, \varphi\tilde{N}\right), \tilde{E}\right) = \bar{g}\left(\nabla_y \varphi\tilde{N}, \tilde{E}\right) \\ &= -\bar{g}\left(\nabla_y \tilde{N}, \varphi\tilde{E}\right) + \bar{g}\left((\nabla_y \varphi) \tilde{N}, \tilde{E}\right). \end{aligned}$$

From (2.3) and (2.13), it follows that

$$\tilde{B}(y, \varphi\tilde{N}) = -\bar{g}\left(\nabla_y \tilde{N}, \varphi\tilde{E}\right) = g\left(A_N y, \varphi\tilde{E}\right) = \tilde{C}(y, \varphi\tilde{E})$$

which completes the proof. \square

Theorem 3.1. We can not find a lightlike hypersurface of an indefinite f -Kenmotsu space form $\overline{M}(c)$ with parallel second fundamental form where $f \neq -c$ for all values on \overline{M} .

Proof. We assume that M is a lightlike hypersurface of $\overline{M}(c)$ which satisfies our hypothesis conditions. By setting $y = \tilde{E}$ and $z = \varphi\tilde{N}$ in (3.2), it yields that

$$-\frac{3c+3f}{4} \{\tilde{v}(x) - 2\bar{g}(x, \varphi\tilde{E})\} = 0$$

and taking $x = \varphi\tilde{N}$ in the last equation, we deduce that

$$f = -c$$

which is a contradiction. Thus we get desired result. \square

Theorem 3.2. We can not find a lightlike hypersurfaces of an indefinite f -Kenmotsu space form $\overline{M}(c)$ with parallel screen distribution where $f \neq 3c$ for all values on \overline{M} .

Proof. We assume that M is a lightlike hypersurface of $\overline{M}(c)$ which satisfies our hypothesis conditions. By using (2.4), then we derive

$$\bar{g}\left(\bar{R}\left(\tilde{E}, \varphi\tilde{N}\right) \varphi\tilde{E}, \tilde{N}\right) = \frac{3c-f}{4}. \quad (3.5)$$

Furthermore, we have

$$\begin{aligned} \bar{g}\left(\bar{R}(x, y) \tilde{P}z, \tilde{N}\right) &= \bar{g}\left(R(x, y) \tilde{P}z, \tilde{N}\right) \\ &= \left(\nabla_x \tilde{C}\right)(y, \tilde{P}z) - \left(\nabla_y \tilde{C}\right)(x, \tilde{P}z) \\ &\quad + \rho(y) \tilde{C}(x, \tilde{P}z) - \rho(x) \tilde{C}(y, \tilde{P}z). \end{aligned} \quad (3.6)$$

from [3]. By virtue of (3.6), we get

$$\bar{g}\left(\bar{R}\left(\tilde{E}, \varphi\tilde{N}\right)\varphi\tilde{E}, \tilde{N}\right) = 0. \quad (3.7)$$

Now, by considering together (3.5) and (3.7) then it follows that

$$f = 3c$$

which is a contradiction and thus we complete the proof. \square

Lemma 3.4. *Let us assume that M is a lightlike hypersurface of an indefinite f -Kenmotsu manifold \bar{M} . If V is a principle vector field, then we have*

$$\tilde{B}(V, U) = \tilde{C}(V, V) = 0.$$

Proof. By using (2.3) and (2.9), it follows that

$$\bar{\nabla}_x U = -\bar{\nabla}_x \varphi \tilde{N} = -\varphi \bar{\nabla}_x \tilde{N} - (\bar{\nabla}_x \varphi) \tilde{N}$$

which means

$$\nabla_x U + \tilde{B}(x, U) \tilde{N} = \varphi A_{\tilde{N}} x - \rho(x) \varphi \tilde{N} + \bar{g}(x, U) \xi. \quad (3.8)$$

By virtue of (3.3) and from (3.8), then we derive that

$$\nabla_x U + \tilde{B}(x, U) \tilde{N} = \tilde{\sigma} A_{\tilde{N}} x + \tilde{v}(A_{\tilde{N}} x) \tilde{N} - \rho(x) \varphi \tilde{N} + \bar{g}(x, U) \xi.$$

Now by comparing the transversal vector bundle parts of both sides of the last equation, it yields that

$$\tilde{B}(x, U) = \tilde{v}(A_{\tilde{N}} x) = -g(A_{\tilde{N}} x, \varphi \tilde{E}) = \tilde{C}(x, V)$$

which gives us the assertion. \square

Lemma 3.5. *We assume that M is a lightlike hypersurface of an indefinite f -Kenmotsu space form $\bar{M}(c)$. We compute the Codazzi formulae like that*

$$\begin{aligned} (\nabla_x A_{\tilde{N}}) y - (\nabla_y A_{\tilde{N}}) x &= \frac{c-3f}{4} \{\tilde{\omega}(y)x - \tilde{\omega}(x)y\} \\ &+ \frac{c+f}{4} \{\bar{g}(y, U)\varphi x - \bar{g}(x, U)\varphi y\} \\ &+ 2\bar{g}(\varphi x, y)U + \tilde{\omega}(x)\eta(y)\xi \\ &- \tilde{\omega}(y)\eta(x)\xi + \rho(y)A_{\tilde{N}}x - \rho(x)A_{\tilde{N}}y. \end{aligned}$$

Proof. It can be easily seen by straightforward computations, thus we omit it. \square

Let us consider an orthonormal basis $\{e_1, \dots, e_{n-2}, \dots, e_{2n-4}, \xi, \tilde{E}, \varphi\tilde{E}, \varphi\tilde{N}\}$ of $\Gamma(TM)$ such that

$$\varphi e_i = e_{n-2+i}, \quad \varphi e_{n-2+i} = -e_i \quad \text{and} \quad \varphi \xi = 0$$

for each $i = 1, \dots, m-2$.

Lemma 3.6. *Let M be a lightlike hypersurface of an indefinite f -Kenmotsu manifold \bar{M} . Then*

$$\begin{aligned} A_{\tilde{N}} U &= \sum_{i=1}^{2n-4} \frac{\tilde{C}(U, e_i)}{\varepsilon_i} e_i + \tilde{C}(U, \xi) \xi \\ &+ \tilde{C}(U, U) V + \tilde{C}(U, V) U \end{aligned} \quad (3.9)$$

and

$$A_{\tilde{N}} \tilde{E} = \sum_{i=1}^{2n-4} \frac{\tilde{C}(\tilde{E}, e_i)}{\varepsilon_i} e_i + \tilde{C}(\tilde{E}, \xi) \xi + \tilde{C}(\tilde{E}, U) V \quad (3.10)$$

where $\{\varepsilon_i\}$ denotes the signature of the basis $\{e_i\}$.

Proof. By virtue of assumption, we can write

$$A_{\tilde{N}}U = \sum_{i=1}^{2n-4} \lambda_i e_i + \gamma \xi + \alpha_1 \tilde{E} + \alpha_2 \varphi \tilde{E} + \alpha_3 \varphi \tilde{N}.$$

By taking into account of (2.13), then we deduce that $\lambda_i = \frac{\tilde{C}(U, e_i)}{\varepsilon_i}$, $\gamma = \tilde{C}(U, \xi)$, $\alpha_1 = 0$, $\alpha_2 = -\tilde{C}(U, U)$ and $\alpha_3 = -\tilde{C}(U, V)$. Thus it yields (3.9). In a similar way, we obtain (3.10). \square

Theorem 3.3. *There are no lightlike hypersurfaces of an indefinite f -Kenmotsu manifold \overline{M} with $f \neq 3c$ satisfying*

$$g((\nabla_{\tilde{E}} A_{\tilde{N}})U, V) = g((\nabla_U A_{\tilde{N}})\tilde{E}, V)$$

and

$$\tilde{B}(U, U) = 0.$$

Proof. Putting $y = U$ and $x = \tilde{E}$ in Lemma 3.5, it follows that

$$(\nabla_{\tilde{E}} A_{\tilde{N}})U - (\nabla_U A_{\tilde{N}})\tilde{E} = -\frac{3c-f}{4}U + \rho(U)A_{\tilde{N}}\tilde{E} - \rho(\tilde{E})A_{\tilde{N}}U.$$

By using (3.9) and (3.10), then we arrive at

$$\begin{aligned} (\nabla_{\tilde{E}} A_{\tilde{N}})U - (\nabla_U A_{\tilde{N}})\tilde{E} &= -\frac{3c-f}{4}U + \rho(U) \left\{ \frac{\tilde{C}(\tilde{E}, e_i)}{\varepsilon_i} e_i \right. \\ &\quad \left. + \tilde{C}(\tilde{E}, \xi)\xi + \tilde{C}(\tilde{E}, U)V \right\} \\ &\quad - \rho(\tilde{E}) \left\{ \frac{\tilde{C}(U, e_i)}{\varepsilon_i} e_i + \tilde{C}(U, \xi)\xi \right. \\ &\quad \left. + \tilde{C}(U, U)V + \tilde{C}(U, V)U \right\}. \end{aligned}$$

By taking into account of Lemma 3.4, then we derive

$$g((\nabla_{\tilde{E}} A_{\tilde{N}})U - (\nabla_U A_{\tilde{N}})\tilde{E}, V) = -\frac{3c-f}{4}U - \rho(\tilde{E})\tilde{B}(U, U)$$

which implies the desired result. \square

Acknowledgement. The author is supported by the Düzce University Scientific Research Projects [Project number 2017.05.04.528]

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