



## Evolution of complex waves via Davey-Stewartson equation

Yusuf Pandir <sup>1\*</sup>, Nail Turhan <sup>2</sup>

<sup>1</sup> Yozgat Bozok University, Faculty of Science and Letters, Department of Mathematics, 66100, Yozgat, Türkiye

<sup>2</sup> Erciyes University, Institute of Science, 38039, Kayseri, Türkiye

\*Correspondence: yusuf.pandir@bozok.edu.tr

Received: 27/03/2025

Accepted: 20/05/2025

Final Version: 28/05/2025

### Abstract

Davey-Stewartson equations (DSEs) have been discussed to examine the features of wave motion in finite depth water which is affected by gravitational force and surface tension. The new versions of the generalized F-expansion method and the generalized -expansion method are suggested to evaluate the analytical solutions of the DSEs. Thus, single, combined and mixed non-degenerative Jacobi elliptic function solutions (JEFSs) and degenerative solutions of the DSEs are obtained to contribute to the literature. These wave solutions are fresh and unexplored. The visual representations of some solutions are also shown in three and two dimensions.

**Keywords:** New version of the generalized F-expansion method; New version of the generalized  $\frac{F'}{F}$ -expansion method; Davey-Stewartson equations; Single combined and mixed JEFSs

### 1. INTRODUCTION

Nonlinear evolution equations (NLEEs) involving time derivative are more common in applied sciences. The progress of the methods to discover the exact solutions of this kind of equations has enhanced the significance of nonlinear models. Sometimes these methods offer similar solutions, and sometimes they can come up with different solutions. These solutions have important benefits in understanding the physical event corresponding to differential equations. The applicability of the solutions of NLEEs can be delineated via wave notion serving to perceive various physical phenomena. Particularly, presenting the motion of a wave by a mathematical function provides us comprehension of physical issues. For example, these wave movements are manifested in a certain order in flexible environments, fluid spaces, optical transmission environments. Therefore, many researches in the field of applied sciences have been carried out to investigate the exact solutions of the NLEEs.

Solitons are one of the vital solution types of the NLEEs having extensive applications in nonlinear optics, biology, fluid mechanics and etc. Thus, many techniques have been proposed and they have been developed over time to discover much more different wave structures for NLEEs. Some of them can be given as, inverse expansion method (Ablowitz 1991), Darboux transformation method (Matveev 1991), sine-cosine technique (Chuntao 1996), tanh function method (Fan 2000), first integral method (Feng 2002), Exp- function method (He 2006), trial equation method (Liu 2005, Liu 2006, Liu 2010, Gurefe 2011, Gurefe 2012), extended trial equation method (Pandir 2012, Pandir 2013, Pandir 2014, Gurefe 2014), Jacobian elliptical function method (Fu 2001, Shen 2003, Chen 2006), Weierstrass elliptical function expansion method (Chen 2006), F-expansion method (Wang 2005, Yang 2004, Abdou 2008, Zhang 2008, Cai 2006, Zhang 2006, Zhang 2007, Zhang 2008) and  $\frac{G'}{G}$ -expansion method (Wang 2007, Guo 2010, Lu 2010).

Due to the importance of the JEFSs of NLEEs, the Jacobi elliptic F-expansion method (Liu 2001, Yong 2004, Qi 2005, Chunhuan 2011), improved Jacobi elliptic F-expansion method (Yafeng 2012, Alofi 2012, Baojian 2009), generalized Jacobi elliptic F- expansion method (Enam 2010, Inc 2005), extended Jacobi elliptical F- Expansion method (Yafeng 2012) has been developed.

In the present paper, the new versions of the generalized F-expansion method and the generalized  $\frac{F'}{F}$ -expansion method have been considered which allow us to reveal combined and mixed JEFSSs together. The solutions obtained are fresh in this sense.

The DSEs,

$$\begin{aligned} i\phi_t + \phi_{xx} - \lambda\phi_{yy} + 2p(\phi + |\phi|^2)\phi &= 0, \\ \varphi_{xx} + q\varphi_{yy} + 2(|\phi|^2)_{xx} &= 0, \end{aligned} \tag{1}$$

where  $\lambda, p$  and  $q$  are constants have been given in (Liu 2014, Tajiri 2010, Malanyuk 1994, Malanyuk 1991). In Eq. (1)  $\phi$  and  $\varphi$  correspond to the complex amplitude and the real velocity potential of the wave, respectively. Davey and Stewartson (1974) have propound the DSEs to depict the progression of perturbation in the nonlinear regime of plane Poiseuille flow.

To achieve our objective this research is arranged as follows: In Section 2, the general structure of the new versions of the proposed techniques have been given. In Section 3 and Section 4 the aforementioned analytical methods are applied to DSEs. The results of this search are summed up in Section 5.

## 2. METHODOLOGY

### 2.1. General structure of the new version of generalized F-expansion method

In this section, a new version of the generalized F-expansion method is introduced. This proposed method presents more different results than the results obtained with the F-expansion method.

For a given NLEE,

$$\tilde{P}(\psi, \psi_x, \psi_y, \psi_z, \dots, \psi_t, \psi_{xx}, \psi_{xy}, \psi_{xt}, \dots) = 0 \tag{2}$$

where  $\psi(x, y, z, \dots, t)$  is an unknown function,  $x, y, z, \dots, t$  are independent variables and  $\tilde{P}$  is a polynomial of  $u$  and its partial derivatives, in which the highest order derivatives and the nonlinear terms are included. When we apply the following traveling wave transformation to Eq. (2)

$$\psi(x, y, z, \dots, t) = \psi(\xi), \quad \xi = j_1x + j_2y + j_3z + \dots + j_mt, \tag{3}$$

where  $j_h (h = 1, 2, 3, \dots, m)$  are constants to be determined, we can reduce Eq. (2) into a nonlinear ordinary differential equation (NLODE),

$$O(\psi, \psi', \psi'', \psi''', \dots) = 0 \tag{4}$$

The prime denotes the derivation with respect to  $\xi$ . Supposing that a solution of Eq. (4) is as,

$$\psi(\xi) = k_0 + \sum_{i=1}^M \left( k_i F^i + \frac{l_i}{F^i} + m_i \left( \frac{F'}{F} \right)^i + n_i \left( \frac{F}{F'} \right)^i \right) \tag{5}$$

where  $F = F(\xi)$ ,  $F' = F'(\xi)$ . Also  $M$  is a natural number and  $k_0, k_i, l_i, m_i, n_i (i = 1, 2, 3, \dots, M)$  are the coefficients to be evaluated. However, the functions  $F(\xi)$  and  $F'(\xi)$  in Eq. (5) fulfil Eq. (6),

$$(F')^2(\xi) = PF^4(\xi) + QF^2(\xi) + R \tag{6}$$

and accordingly, it can be deduced for  $F(\xi)$  and  $F'(\xi)$ ,

$$\left\{ \begin{array}{l} F''(\xi) = 2PF^3(\xi) + QF(\xi) \\ F'''(\xi) = (6PF^2(\xi) + Q)F'(\xi) \\ F^{(4)}(\xi) = 24P^2F^5(\xi) + 20PQF^3(\xi) + (Q^2 + 12PR)F(\xi) \\ F^{(5)}(\xi) = (120P^2F^4(\xi) + 60PQF^2(\xi) + Q^2 + 12PR)F'(\xi) \\ \dots \end{array} \right. \quad (7)$$

where  $P, Q$  and  $R$  are all parameters. Also, getting support from the derivatives in Eq. (7) the value  $N$  is determined by the balancing procedure which depends on the highest order derivative and highest power nonlinear terms in Eq. (4). After ascertaining  $N$ , Eq. (5) is embed in Eq. (4) by taking account Eq. (6). This leads to a polynomial of  $(F')^r F^p$  ( $r = 0, 1; p = 0, \pm 1, \pm 2, \dots$ ). The related coefficients in this polynomial are matched to zero to reveal an algebraic system of equation. Solving this system, the parameters  $j_h$  ( $h = 1, 2, 3, \dots, m$ ) and  $k_0, k_i, l_i, m_i, n_i$  ( $i = 1, 2, 3, \dots, M$ ) are determined which are necessary for exposing the solution. Thus, the new mixed and combined JEFs are obtained. Considering distinct values of  $P, Q$  and  $R$ , the different JEFs  $F(\xi)$  can be attained from Eq. (6).

**2.2. General structure of the new version of generalized F-expansion method**

In this section, it is aimed to obtain different JEFs with the newly developed method. Similarly, when Eq. (3) is applied to Eq. (2), a NLODE is obtained as stated in Eq. (4). When the term  $\frac{F'(\xi)}{F(\xi)}$  is written instead of  $F(\xi)$  in the solution function in Eq. (5), a different new solution can be obtained as follows,

$$\kappa(\xi) = k_0 + \sum_{i=1}^M \left( k_i \left( \frac{F'}{F} \right)^i + l_i \left( \frac{F}{F'} \right)^i + m_i \left( \frac{(F')'}{F} \frac{F}{F'} \right)^i + n_i \left( \left( \frac{(F')'}{F} \right)^{-1} \frac{F}{F'} \right)^i \right) \quad (8)$$

where the  $F(\xi)$  is the JEF solving Eq. (6).  $M$  can be evaluated from Eq. (4) via balancing the related terms. The related derivatives are obtained with the help of Eq. (7) as follows,

$$\left( \frac{(F')'}{F} \right)^2 = \left( \frac{F'}{F} \right)^4 - 2Q \left( \frac{F'}{F} \right)^2 - 4PR + Q^2 \quad (9)$$

$$\left( \frac{F'}{F} \right)'' = 2 \left( \frac{F'}{F} \right)^3 - 2Q \left( \frac{F'}{F} \right)$$

$$\left( \frac{F'}{F} \right)''' = 6 \left( \frac{F'}{F} \right)^2 \left( \frac{F'}{F} \right)' - 2Q \left( \frac{F'}{F} \right)' \quad (10)$$

...

These calculated derivatives are written down in the new solution function in Eq. (8), then a zero polynomial based on the functions

$\left( \frac{(F')'}{F} \right)^r \left( \frac{F'}{F} \right)^p$  ( $r = 0, 1; p = 0, \pm 1, \pm 2, \dots$ ) is constructed. Considering that the coefficients of this polynomial vanish, the

algebraic system of equations is attained. When this system is unfastened with the help of Mathematica package, the values  $k_0, k_i, l_i, m_i, n_i (i = 1, 2, 3, \dots, M)$  and  $j_h (j = 1, 2, 3, \dots, m)$  are evaluated which are essential for the solution of Eq. (2). These coefficients are replaced by the solution function in Eq. (8) and as a result fresh, diverse solution forms involving the JEFs can be obtained. Thus, the new mixed and combined JEFs are occurred. According to the diverse values of  $P, Q$  and  $R$ , the various JEFs  $F(\xi)$  can be achieved from Eq. (6).

### 3. Implementation of the new version of generalized F-expansion method to DSEs

In this section, the new version generalized F-Expansion method is applied to the DSEs. When  $\omega$  is selected, Eq. (1) can be written as in Eq. (11). The proposed algorithm is employed for the DSEs [42-45],

$$\begin{aligned} i\phi_t + \phi_{xx} + \phi_{yy} + 2p(\phi + |\phi|^2)\phi &= 0, \\ \phi_{xx} + q\phi_{yy} + 2(|\phi|^2)_{xx} &= 0. \end{aligned} \tag{11}$$

Generally, the DSE system describes the propagation of weak nonlinear waves propagating in one direction but whose amplitudes occur in two space environments. We introduce traveling wave transformation for this complex equation system

$$\phi(x, y, t) = e^{i\theta} \phi(\omega), \quad \varphi(x, y, t) = \varphi(\omega), \quad \omega = j_1x + j_2y + j_3t, \quad \theta = \mathcal{G}(x + y - \gamma t), \tag{12}$$

where  $j_1, j_2, j_3, \mathcal{G}$  and  $\gamma$  are constants. By using Eq. (12), Eq. (11) is reduced into NLODEs as follows,

$$(\mathcal{G}\gamma - 2\mathcal{G}^2)\phi + 2p(\phi\varphi + \phi^3) + (j_1^2 + j_2^2)\phi'' + i(j_3 + 2j_1\mathcal{G} + 2j_2\mathcal{G})\phi' = 0, \tag{13}$$

$$(j_1^2 + qj_2^2)\phi'' + 2j_1^2(\phi^2)'' = 0. \tag{14}$$

From Eq. (13)  $j_3 = -2\mathcal{G}(j_1 + j_2)$  is obtained using the complex numbers equality. Thus, Eq. (13) is rewritten as follows

$$(j_1^2 + j_2^2)\phi'' + 2p(\phi\varphi + \phi^3) + (\mathcal{G}\gamma - 2\mathcal{G}^2)\phi = 0. \tag{15}$$

The two sides of the Eq. (14) are integrated twice with respect to  $\omega$  and when the integral constant is chosen to be zero, we get following equation

$$\varphi = -\frac{2j_1^2\phi^2}{j_1^2 + qj_2^2}. \tag{16}$$

When the last equation is replaced by Eq. (15), the following NLODE

$$(j_1^2 + j_2^2)\phi'' + (\mathcal{G}\gamma - 2\mathcal{G}^2)\phi + \frac{(qj_2^2 - j_1^2)2p}{j_1^2 + qj_2^2}\phi^3 = 0, \tag{17}$$

is obtained. Balancing  $\phi''$  and  $\phi^3$  in Eq. (17), the solution of Eq. (17) is in the form of:

$$\phi(\omega) = k_0 + k_1F(\omega) + \frac{l_1}{F(\omega)} + m_1\left(\frac{F'(\omega)}{F(\omega)}\right) + n_1\left(\frac{F(\omega)}{F'(\omega)}\right). \tag{18}$$

Obtaining the terms  $\phi''$  and  $\phi^3$  are from Eq. (18) and substituting them into Eq. (17), gives a zero polynomial depending on the elliptic functions of  $F(\omega)$  and  $F'(\omega)$ . Solving the algebraic equation system, obtained by equating the coefficients of this polynomial to zero, with the help of the Mathematica package program the values  $k_0, k_1, l_1, m_1, n_1, \phi$  and  $e_3$  are found. These coefficients and inverse transformations are replaced by the solution function in Eq. (18) and the following solutions are obtained depending on the elliptic

functions of  $F(\omega)$  and  $F'(\omega)$ . If we postulate  $F(\omega) = sn(\omega)$  from Eq. (6) we have  $P = m^2$ ,  $Q = -(1+m^2)$ ,  $R = 1$  following situations:

**Case (1):**

$$k_1 = \sqrt{\frac{P(j_1^2 + qj_2^2)(j_1^2 + j_2^2)}{p(j_1^2 - qj_2^2)}}, k_0 = l_1 = n_1 = m_1 = 0,$$

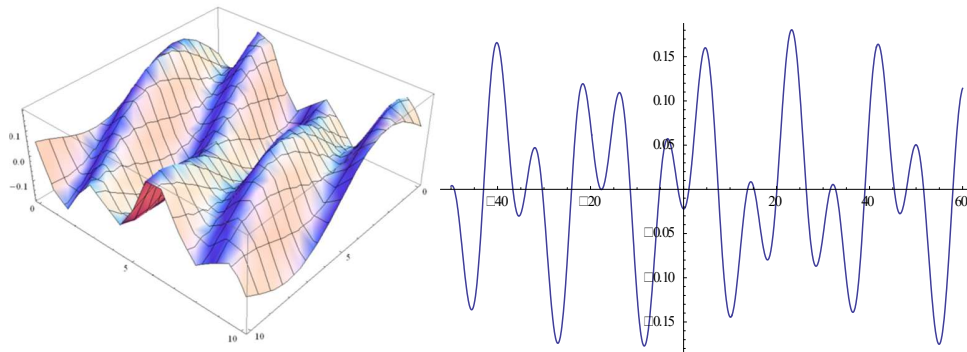
$$g = \frac{\gamma - \sqrt{\gamma^2 + 8Q(j_1^2 + j_2^2)}}{4}, j_3 = \frac{j_1 + j_2}{2} \left( \sqrt{\gamma^2 + 8Q(j_1^2 + j_2^2)} - \gamma \right). \quad (19)$$

When we use Eq. (19) in Eq. (18), new types of exact solutions of Eq. (11) are evaluated as follows:

$$\begin{aligned} \phi(\omega_1) &= B_1 m e^{i\theta_1} sn(\omega_1), \\ \varphi(\omega_1) &= B_2 m^2 sn^2(\omega_1), \end{aligned} \quad (20)$$

where  $\omega_1 = j_1x + j_2y + \frac{j_1 + j_2}{2} \left( \sqrt{\gamma^2 - 8(1+m^2)(j_1^2 + j_2^2)} - \gamma \right) t$ ,  $B_1 = \sqrt{\frac{(j_1^2 + j_2^2)(j_1^2 + qj_2^2)}{pj_1^2 - pqj_2^2}}$ ,

$$\theta_1 = -\frac{\sqrt{\gamma^2 - 8(1+m^2)(j_1^2 + j_2^2)} - \gamma}{4} (x + y - \gamma t), B_2 = -\frac{2j_1^2(j_1^2 + j_2^2)}{p(j_1^2 - qj_2^2)}.$$



**Figure 1:** Graph of the solution  $\phi(\omega_1)$  corresponding to the values  $j_1 = 1/2$ ,  $j_2 = q = 1$ ,  $\gamma = 7$ ,  $p = -1$ ,  $y = 0$ ,  $m = 1/8$

**Case (2):**

$$l_1 = -\sqrt{\frac{R(j_1^2 + j_2^2)(j_1^2 + qj_2^2)}{pj_1^2 - pqj_2^2}}, k_0 = k_1 = n_1 = m_1 = 0,$$

$$g = \frac{\gamma + \sqrt{\gamma^2 + 8Q(j_1^2 + j_2^2)}}{4}, j_3 = -\frac{j_1 + j_2}{2} \left( \gamma + \sqrt{\gamma^2 + 8Q(j_1^2 + j_2^2)} \right). \quad (21)$$

If we substitute Eq. (21) into Eq. (18), we get the JEFSSs of Eq. (11)

$$\begin{aligned}\phi(\omega_2) &= -B_1 e^{i\theta_2} ns(\omega_2), \\ \varphi(\omega_2) &= B_2 ns^2(\omega_2),\end{aligned}\tag{22}$$

where  $\omega_2 = j_1x + j_2y - \frac{j_1 + j_2}{2} \left( \gamma + \sqrt{\gamma^2 - 8(1+m^2)(j_1^2 + j_2^2)} \right) t$ ,  $\theta_2 = \frac{\gamma + \sqrt{\gamma^2 - 8(1+m^2)(j_1^2 + j_2^2)}}{4} (x + y - \gamma t)$ .

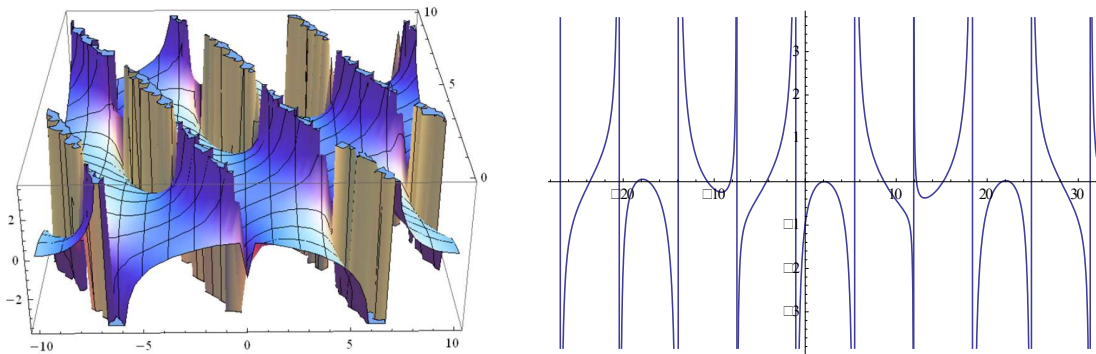
**Case (3):**

$$\begin{aligned}m_1 &= -\sqrt{\frac{(j_1^2 + j_2^2)(j_1^2 + qj_2^2)}{pj_1^2 - pqj_2^2}}, \quad k_0 = k_1 = l_1 = n_1 = 0, \\ g &= \frac{\gamma - \sqrt{\gamma^2 - 16Q(j_1^2 + j_2^2)}}{4}, \quad j_3 = \frac{j_1 + j_2}{2} \left( \sqrt{\gamma^2 - 16Q(j_1^2 + j_2^2)} - \gamma \right).\end{aligned}\tag{23}$$

When we put Eq. (23) into Eq. (18), we gain the following combined JEFSSs

$$\begin{aligned}\phi(\omega_3) &= -B_1 e^{i\theta_3} cs(\omega_3) dn(\omega_3), \\ \varphi(\omega_3) &= B_2 cs^2(\omega_3) dn^2(\omega_3),\end{aligned}\tag{24}$$

where  $\omega_3 = j_1x + j_2y - \frac{j_1 + j_2}{2} \left( \gamma - \sqrt{\gamma^2 + 16(1+m^2)(j_1^2 + j_2^2)} \right) t$ ,  $\theta_3 = \frac{\sqrt{\gamma^2 + 16(1+m^2)(j_1^2 + j_2^2)} - \gamma}{4} (x + y - \gamma t)$ .



**Figure 2:** Graph of the solution  $\phi(\omega_3)$  corresponding to the values  $j_1 = 1/2$ ,  $j_2 = m = 1/3$ ,  $\gamma = 2$ ,  $p = -1$ ,  $q = 1$ ,  $y = 0$ .

**Case (4):**

$$\begin{aligned}n_1 &= \sqrt{\frac{(Q^2 - 4PR)(j_1^2 + j_2^2)(j_1^2 + qj_2^2)}{pj_1^2 - pqj_2^2}}, \quad k_1 = l_1 = k_0 = m_1 = 0, \\ g &= \frac{\gamma + \sqrt{\gamma^2 - 16Q(j_1^2 + j_2^2)}}{4}, \quad j_3 = -\frac{j_1 + j_2}{2} \left( \gamma + \sqrt{\gamma^2 - 16Q(j_1^2 + j_2^2)} \right).\end{aligned}\tag{25}$$

When we put Eq. (25) into Eq. (18), we find new exact solution named as combined JEFSSs of Eq. (11)

$$\begin{aligned}\phi(\omega_4) &= (1 - m^2) B_1 e^{i\theta_4} sc(\omega_4) nd(\omega_4), \\ \varphi(\omega_4) &= (1 - m^2)^2 B_2 sc^2(\omega_4) nd^2(\omega_4),\end{aligned}\tag{26}$$

where  $\omega_4 = j_1x + j_2y - \frac{j_1 + j_2}{2} \left( \gamma + \sqrt{\gamma^2 + 16(1+m^2)(j_1^2 + j_2^2)} \right) t$ ,  $\theta_4 = \frac{\gamma + \sqrt{\gamma^2 + 16(1+m^2)(j_1^2 + j_2^2)}}{4} (x + y - \gamma t)$ .

**Case (5):**

$$k_1 = \sqrt{\frac{P(j_1^2 + j_2^2)(j_1^2 + qj_2^2)}{pj_1^2 - pqj_2^2}}, \quad m_1 = n_1 = k_0 = 0, \quad l_1 = \sqrt{\frac{R(j_1^2 + j_2^2)(j_1^2 + qj_2^2)}{pj_1^2 - pqj_2^2}},$$

$$g = \frac{\gamma - \sqrt{\gamma^2 + 8(Q - 6\sqrt{PR})(j_1^2 + j_2^2)}}{4},$$

$$j_3 = \frac{-(j_1 + j_2)}{2} \left( \gamma - \sqrt{\gamma^2 + 8(Q - 6\sqrt{PR})(j_1^2 + j_2^2)} \right), \quad (27)$$

Putting Eq. (27) into Eq. (18), we achieve the following new combined JEFs of Eq. (11)

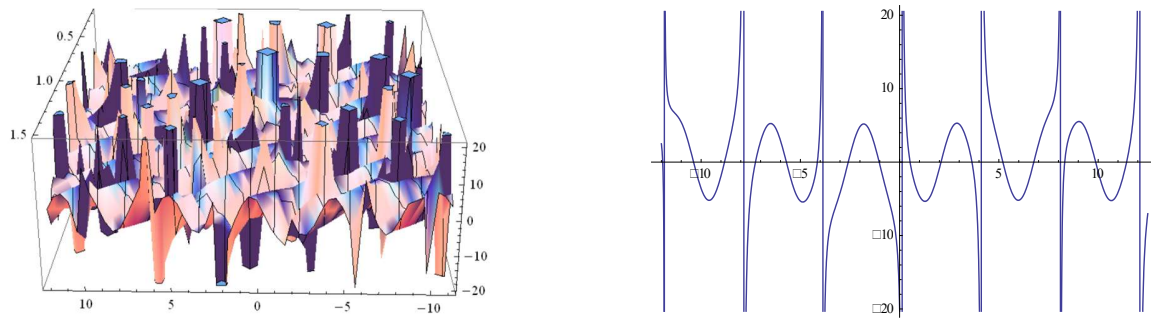
$$\phi(\omega_5) = B_1 \frac{e^{i\theta_5} (1 + msn^2(\omega_5))}{sn(\omega_5)},$$

$$\varphi(\omega_5) = B_2 \frac{(1 + msn^2(\omega_5))^2}{sn^2(\omega_5)}, \quad (28)$$

where

$$\omega_5 = j_1x + j_2y + \frac{j_1 + j_2}{2} \left( \sqrt{\gamma^2 - 8(1+m^2+6m)(j_1^2 + j_2^2)} - \gamma \right) t,$$

$$\theta_5 = \frac{\gamma - \sqrt{\gamma^2 - 8(1+m^2+6m)(j_1^2 + j_2^2)}}{4} (x + y - \gamma t).$$



**Figure 3:** Graph of the solution  $\phi(\omega_5)$  corresponding to the values  $j_1 = q = 1$ ,  $j_2 = 2$ ,  $\gamma = 20$ ,  $p = -1$ ,  $y = 0$ ,  $m = 4/5$ .

**Case (6):**

$$m_1 = \sqrt{\frac{(j_1^2 + j_2^2)(j_1^2 + qj_2^2)}{pj_1^2 - pqj_2^2}}, \quad n_1 = \sqrt{\frac{(Q^2 - 4PR)(j_1^2 + j_2^2)(j_1^2 + qj_2^2)}{pj_1^2 - pqj_2^2}}, \quad k_0 = k_1 = l_1 = 0,$$

$$g = \frac{\gamma - \sqrt{\gamma^2 - 16(Q + 3\sqrt{Q^2 - 4PR})(j_1^2 + j_2^2)}}{4},$$

$$j_3 = -\frac{j_1 + j_2}{2} \left( \gamma - \sqrt{\gamma^2 - 16(Q + 3\sqrt{Q^2 - 4PR})(j_1^2 + j_2^2)} \right). \tag{29}$$

Writing Eq. (29) into Eq. (18), we attain the following new mixed JEFSSs of Eq. (11)

$$\begin{aligned} \phi(\omega_6) &= B_1 \frac{e^{i\theta_6} (1 - m^2 + m^2 cn^4(\omega_6))}{cn(\omega_6) dn(\omega_6) sn(\omega_6)}, \\ \varphi(\omega_6) &= B_2 \frac{\left( (1 - m^2 + m^2 cn^4(\omega_6)) \right)^2}{cn^2(\omega_6) dn^2(\omega_6) sn^2(\omega_6)}, \end{aligned} \tag{30}$$

where

$$\omega_6 = j_1 x + j_2 y + \frac{j_1 + j_2}{2} \left( \sqrt{\gamma^2 - 16(2 - 4m^2)(j_1^2 + j_2^2)} - \gamma \right) t,$$

$$\theta_6 = \frac{\gamma - \sqrt{\gamma^2 - 16(2 - 4m^2)(j_1^2 + j_2^2)}}{4} (x + y - \gamma t).$$

**Case (7):**

$$k_1 = \sqrt{\frac{P(j_1^2 + j_2^2)(j_1^2 + qj_2^2)}{4pj_1^2 - 4pqj_2^2}}, l_1 = \sqrt{\frac{R(j_1^2 + j_2^2)(j_1^2 + qj_2^2)}{4pj_1^2 - 4pqj_2^2}}, m_1 = \sqrt{\frac{(j_1^2 + j_2^2)(j_1^2 + qj_2^2)}{4pj_1^2 - 4pqj_2^2}}, k_0 = 0,$$

$$n_1 = 0, g = \frac{\gamma - \sqrt{\gamma^2 - 4(Q + 6\sqrt{PR})(j_1^2 + j_2^2)}}{4},$$

$$j_3 = \frac{j_1 + j_2}{2} \left( \sqrt{\gamma^2 - 4(Q + 6\sqrt{PR})(j_1^2 + j_2^2)} - \gamma \right). \tag{31}$$

When we put Eq. (31) into Eq. (18), we find the combined JEFSSs of Eq. (11)

$$\begin{aligned} \phi(\omega_7) &= B_1 e^{i\theta_7} \frac{(1 + cn(\omega_7) dn(\omega_7) + msn^2(\omega_7))}{2sn(\omega_7)}, \\ \varphi(\omega_7) &= B_2 \frac{(1 + cn(\omega_7) dn(\omega_7) + msn^2(\omega_7))^2}{4sn^2(\omega_7)}, \end{aligned} \tag{32}$$

where

$$\omega_7 = j_1 x + j_2 y + \frac{j_1 + j_2}{2} \left( \sqrt{\gamma^2 - 4(-1 - m^2 + 6m)(j_1^2 + j_2^2)} - \gamma \right) t,$$

$$\theta_7 = \frac{\gamma - \sqrt{\gamma^2 - 4(-1 - m^2 + 6m)(j_1^2 + j_2^2)}}{4} (x + y - \gamma t).$$

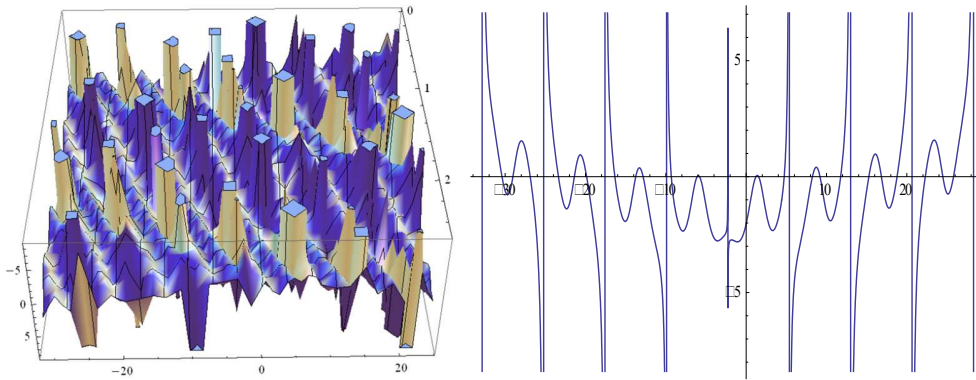


Figure 4: Graph of the solution  $\phi(\omega_7)$  corresponding to the values  $j_1 = q = 1, j_2 = 2, \gamma = 10, p = -1, y = 0, m = 3/4$

**Remark 1:** According to our findings, all the JEFs of Eq. (11) obtained with the new version of generalized F-expansion method are uncharted and are not proved before in researches. When the results obtained in reference [43] are examined, it is seen that trigonometric and hyperbolic function solutions are obtained. The results obtained here are completely different from these and are new Jacobian elliptic function solutions. In addition, 2D and 3D graphics of the obtained solution functions are shown in Figs. 1-4 which are established with suitable parametric selections.

#### 4. Implementation of the new version of the generalized -expansion method to DSEs

In this section, the application of the new version of the generalized -expansion method to DSEs is given. The traveling wave transformation as in Section 3 has been used for DSEs,

$$\phi(x, y, t) = e^{i\sigma} \phi(\mu), \quad \varphi(x, y, t) = \varphi(\mu), \quad \mu = j_1x + j_2y + j_3t, \quad \sigma = \zeta(x + y - \gamma t), \quad (33)$$

where  $j_1, j_2, j_3, \zeta$  and  $\gamma$  are constants. When the transformation and necessary operations are performed, the NLODE below

$$(j_1^2 + j_2^2)\phi'' + (\zeta\gamma - 2\zeta^2)\phi + \frac{2p(qj_2^2 - j_1^2)}{j_1^2 + qj_2^2}\phi^3 = 0, \quad (34)$$

is obtained. Considering the new solution function Eq. (8), the balancing procedure is applied between the terms  $\phi''$  and  $\phi^3$  in Eq. (34). Since it can be written as  $F' = \pm\sqrt{PF^4 + QF^2 + R} \cong \pm\sqrt{PF^2} + \dots$  using Eq. (6), the solution function in Eq. (8) is briefly

taken as  $\phi = k_M^M \left(\frac{F'}{F}\right)^M + \dots \cong \pm k_M^M P^{M/2} F^M + \dots$ . Accordingly, the related terms that provide balancing are calculated as

$$\phi^3 = k_M^{3M} \left(\frac{F'}{F}\right)^{3M} + \dots \cong \pm k_M^{3M} P^{3M/2} F^{3M} + \dots$$

$$\phi'' \cong M(M+1)k_M^M P^{(M/2)+1} F^{M+2} + \dots$$

Then, the balancing term is obtained as  $M = 1$ . Thus, the general form of the new solution function is written as follows

$$\phi(\mu) = k_0 + k_1 \frac{F'(\mu)}{F(\mu)} + l_1 \frac{F(\mu)}{F'(\mu)} + m_1 \left(\frac{F'(\mu)}{F(\mu)}\right)' \frac{F(\mu)}{F'(\mu)} + n_1 \frac{F'(\mu)}{F(\mu)} \left(\left(\frac{F'(\mu)}{F(\mu)}\right)'\right)^{-1}. \quad (35)$$

When the terms  $\phi''$  and  $\phi^3$  obtained from Eq. (35) are substituted into Eq. (34), a zero polynomial is obtained depending on the elliptic

functions of the  $\left(\frac{F'(\mu)}{F(\mu)}\right)'$   $\left(\frac{F'(\mu)}{F(\mu)}\right)^p$  ( $r = 0, 1; p = 0, \pm 1, \pm 2, \dots$ ). When the algebraic equation system, which is obtained by

equalizing the coefficients of this polynomial with zero, is solved with the help of the Mathematica package program,  $k_0, k_1, l_1, m_1, n_1, \zeta$  and  $e_3$  are obtained. These coefficients and inverse transformations are replaced by Eq. (35) and the following

solutions are obtained depending on the JEFs of the  $\frac{F'(\mu)}{F(\mu)}$  and  $\left(\frac{F'(\mu)}{F(\mu)}\right)'$ . Then, unlike the solutions in Section 3,  $\phi(\mu)$  and

$\varphi(\mu)$  solutions for  $F(\mu) = sn(\mu)$  were obtained respectively.

**Case 1:**

$$k_1 = \sqrt{\frac{(j_1^2 + qj_2^2)(j_1^2 + j_2^2)}{pj_1^2 - pqj_2^2}}, \quad \zeta = \frac{\gamma + \sqrt{\gamma^2 - 16Q(j_1^2 + j_2^2)}}{4}, \quad k_0 = l_1 = n_1 = m_1 = 0,$$

$$j_3 = -\frac{j_1 + j_2}{2} \left( \gamma + \sqrt{\gamma^2 - 16Q(j_1^2 + j_2^2)} \right). \tag{36}$$

When we substitute Eq. (36) into Eq. (35), the following new mixed exact solutions of Eq. (11) are gained as follows:

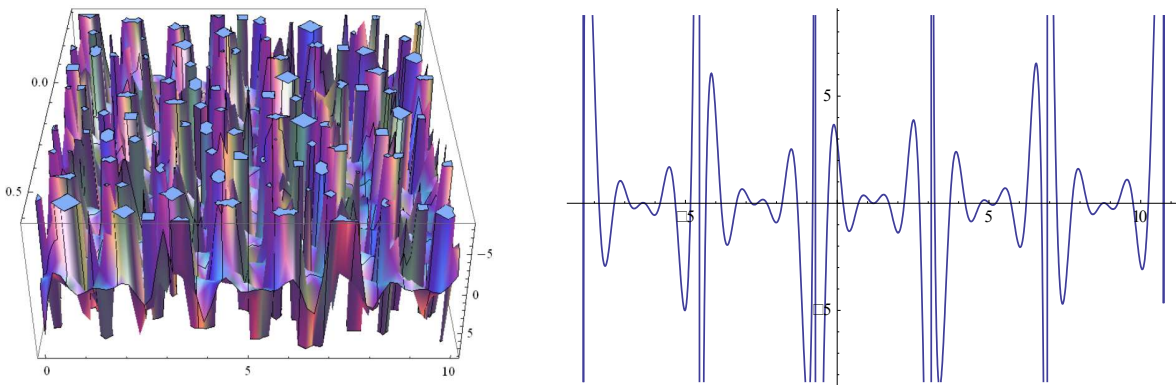
$$\phi(\mu_1) = D_1 \frac{e^{i\sigma_1} cn(\mu_1) dn(\mu_1)}{sn(\mu_1)},$$

$$\varphi(\mu_1) = D_2 \frac{cn^2(\mu_1) dn^2(\mu_1)}{sn^2(\mu_1)}, \tag{37}$$

where

$$\mu_1 = j_1x + j_2y - \frac{j_1 + j_2}{2} \left( \gamma + \sqrt{\gamma^2 + 16(1+m^2)(j_1^2 + j_2^2)} \right) t, \quad D_1 = \sqrt{\frac{(j_1^2 + j_2^2)(j_1^2 + qj_2^2)}{pj_1^2 - pqj_2^2}},$$

$$\sigma_1 = \frac{\gamma + \sqrt{\gamma^2 + 16(j_1^2 + j_2^2)(1+m^2)}}{4} (x + y - \gamma t), \quad D_2 = -\frac{2(j_1^2 + j_2^2)j_1^2}{p(j_1^2 - qj_2^2)}.$$



**Figure 5:** Graph of the solution  $\phi(\mu_1)$  corresponding to the values  $j_1 = q = 1, j_2 = 2, \gamma = 10, p = -1, y = 0, m = 3/4$

**Case (2):**

$$k_0 = m_1 = k_1 = n_1 = 0, l_1 = -\sqrt{\frac{(j_1^2 + qj_2^2)(j_1^2 + j_2^2)(Q^2 - 4PR)}{pj_1^2 - pqj_2^2}},$$

$$\zeta = \frac{\gamma - \sqrt{\gamma^2 - 16Q(j_1^2 + j_2^2)}}{4}, j_3 = \frac{j_1 + j_2}{2} \left( \sqrt{\gamma^2 - 16Q(j_1^2 + j_2^2)} - \gamma \right). \quad (38)$$

If we put Eq. (38) into Eq. (35), we get the following new mixed JEFSSs of Eq. (11)

$$\phi(\mu_2) = D_3 \frac{e^{i\sigma_2} sn(\mu_2)}{cn(\mu_2) dn(\mu_2)},$$

$$\varphi(\mu_2) = D_4 \frac{sn^2(\mu_2)}{dn^2(\mu_2) cn^2(\mu_2)},$$
(39)

where

$$\mu_2 = j_1x + j_2y + \frac{j_1 + j_2}{2} \left( \sqrt{\gamma^2 + 16(1+m^2)(j_1^2 + j_2^2)} - \gamma \right) t, D_4 = -\frac{2j_1^2(j_1^2 + j_2^2)(1-m^2)^2}{p(j_1^2 - qj_2^2)},$$

$$D_3 = (1-m^2) \sqrt{\frac{(j_1^2 + qj_2^2)(j_1^2 + j_2^2)}{pj_1^2 - pqj_2^2}}, \sigma_2 = \frac{\sqrt{\gamma^2 - 8(1+m^2)(j_1^2 + j_2^2)} + \gamma}{4} (x + y - \gamma t).$$

**Case (3):**

$$m_1 = -\sqrt{\frac{(j_1^2 + qj_2^2)(j_1^2 + j_2^2)}{pj_1^2 - pqj_2^2}}, k_0 = n_1 = k_1 = l_1 = 0,$$

$$\zeta = \frac{\gamma + \sqrt{\gamma^2 + 32Q(j_1^2 + j_2^2)}}{4}, j_3 = -\frac{j_1 + j_2}{2} \left( \sqrt{\gamma^2 + 32Q(j_1^2 + j_2^2)} + \gamma \right). \quad (40)$$

When we substitute Eq. (40) into Eq. (35), we obtain the following combined JEFSSs,

$$\phi(\mu_3) = D_1 \frac{e^{i\sigma_3} (1-m^2 sn^4(\mu_3))}{cn(\mu_3) dn(\mu_3) sn(\mu_3)},$$

$$\varphi(\mu_3) = D_2 \frac{(1-m^2 sn^4(\mu_3))^2}{cn^2(\mu_3) dn^2(\mu_3) sn^2(\mu_3)},$$
(41)

where  $\mu_3 = j_1x + j_2y - \frac{j_1 + j_2}{2} \left( \sqrt{\gamma^2 - 32(1+m^2)(j_1^2 + j_2^2)} + \gamma \right) t, \sigma_3 = \frac{\gamma + \sqrt{\gamma^2 - 32(1+m^2)(j_1^2 + j_2^2)}}{4} (x + y - \gamma t).$

**Case (4):**

$$n_1 = 4 \sqrt{\frac{PR(j_1^2 + qj_2^2)(j_1^2 + j_2^2)}{pj_1^2 - pqj_2^2}}, k_0 = m_1 = k_1 = l_1 = 0,$$

$$\zeta = \frac{\gamma - \sqrt{\gamma^2 + 32Q(j_1^2 + j_2^2)}}{4}, j_3 = \frac{j_1 + j_2}{2} \left( \sqrt{\gamma^2 + 32Q(j_1^2 + j_2^2)} - \gamma \right). \quad (42)$$

When we put Eq. (42) into Eq. (35), we achieve new exact solution name as combined JEFSSs of Eq. (11)

$$\begin{aligned} \phi(\mu_4) &= D_5 \frac{e^{i\sigma_4} cn(\mu_4) dn(\mu_4) sn(\mu_4)}{(1 - m^2 sn^4(\mu_4))}, \\ \varphi(\mu_4) &= D_6 \frac{cn^2(\mu_4) dn^2(\mu_4) sn^2(\mu_4)}{(m^2 sn^4(\mu_4) - 1)^2}, \end{aligned} \quad (43)$$

where 
$$\mu_4 = j_1 x + j_2 y + \frac{j_1 + j_2}{2} \left( \sqrt{\gamma^2 - 32(1 + m^2)(j_1^2 + j_2^2)} - \gamma \right) t, D_6 = -\frac{32j_1^2(j_1^2 + j_2^2)m^2}{p(j_1^2 - qj_2^2)},$$

$$D_5 = -4m \sqrt{\frac{(j_1^2 + j_2^2)(j_1^2 + qj_2^2)}{p(j_1^2 - qj_2^2)}}, \sigma_4 = -\frac{\sqrt{\gamma^2 - 32(1 + m^2)(j_1^2 + j_2^2)} - \gamma}{4} (x + y - \gamma t).$$

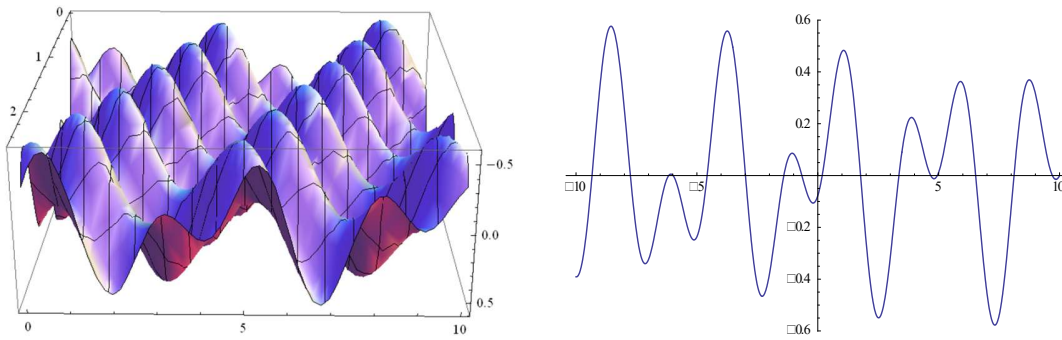


Figure 6: Graph of the solution  $\phi(\mu_4)$  corresponding to the values  $j_1 = q = 1, j_2 = 1/2, \gamma = 10, p = -1, y = 0, m = 1/5$ .

Case (5):

$$k_1 = \sqrt{\frac{(j_1^2 + e_2^2)(j_1^2 + qj_2^2)}{pj_1^2 - pqj_2^2}}, l_1 = \sqrt{\frac{(Q^2 - 4PR)(j_1^2 + j_2^2)(j_1^2 + qj_2^2)}{pj_1^2 - pqj_2^2}}, k_0 = 0,$$

$$m_1 = n_1 = 0, \zeta = \frac{\gamma - \sqrt{\gamma^2 - 16(Q + 3\sqrt{Q^2 - 4PR})(j_1^2 + j_2^2)}}{4},$$

$$j_3 = \frac{j_1 + j_2}{2} \left( \sqrt{\gamma^2 - 16(Q + 3\sqrt{Q^2 - 4PR})(j_1^2 + j_2^2)} - \gamma \right) \quad (44)$$

When we substitute Eq. (44) into Eq. (35), we find following new combined JEFSSs of Eq. (11),

$$\begin{aligned} \phi(\mu_5) &= D_1 \frac{e^{i\sigma_5} (cn^2(\mu_5) dn^2(\mu_5) + (1-m^2) sn^2(\mu_5))}{cn(\mu_5) dn(\mu_5) sn(\mu_5)}, \\ \varphi(\mu_5) &= D_2 \frac{(cn^2(\mu_5) dn^2(\mu_5) + (1-m^2) sn^2(\mu_5))^2}{cn^2(\mu_5) dn^2(\mu_5) sn^2(\mu_5)}, \end{aligned} \tag{45}$$

where 
$$\mu_5 = j_1x + j_2y + \frac{j_1 + j_2}{2} \left( \sqrt{\gamma^2 - 16(2-4m^2)(j_1^2 + j_2^2)} - \gamma \right) t,$$

$$\sigma_5 = \frac{\gamma - \sqrt{\gamma^2 - 16(2-4m^2)(j_1^2 + j_2^2)}}{4} (x + y - \gamma t).$$

**Case (6):**

$$m_1 = -\sqrt{\frac{(j_1^2 + j_2^2)(j_1^2 + qj_2^2)}{pj_1^2 - pqj_2^2}}, n_1 = 4\sqrt{\frac{PR(j_1^2 + j_2^2)(j_1^2 + qj_2^2)}{pj_1^2 - pqj_2^2}}, k_0 = l_1 = k_1 = 0,$$

$$\zeta = \frac{\gamma - \sqrt{\gamma^2 + 32(Q + 6\sqrt{PR})(j_1^2 + j_2^2)}}{4},$$

$$j_3 = \frac{j_1 + j_2}{2} \left( \sqrt{\gamma^2 + 32(Q + 6\sqrt{PR})(j_1^2 + j_2^2)} - \gamma \right). \tag{46}$$

When we replace Eq. (46) into Eq. (35), we attain following new combined and mixed type of JEFSSs of Eq. (11),

$$\begin{aligned} \phi(\mu_6) &= D_1 e^{i\sigma_6} \left( \frac{(1-m^2 sn^4(\mu_6))}{cn(\mu_6) dn(\mu_6) sn(\mu_6)} - \frac{4m cn(\mu_6) dn(\mu_6) sn(\mu_6)}{(1-m^2 sn^4(\mu_6))} \right), \\ \varphi(\mu_6) &= D_2 \left( \frac{(1-m^2 sn^4(\mu_6))}{cn(\mu_6) dn(\mu_6) sn(\mu_6)} - \frac{4m cn(\mu_6) dn(\mu_6) sn(\mu_6)}{(1-m^2 sn^4(\mu_6))} \right)^2, \end{aligned} \tag{47}$$

where 
$$\mu_6 = j_1x + j_2y + \frac{j_1 + j_2}{2} \left( \sqrt{\gamma^2 + 32(-1-m^2 + 6m)(j_1^2 + j_2^2)} - \gamma \right) t,$$

$$\sigma_6 = \frac{\gamma - \sqrt{\gamma^2 + 32(-1-m^2 + 6m)(j_1^2 + j_2^2)}}{4} (x + y - \gamma t).$$

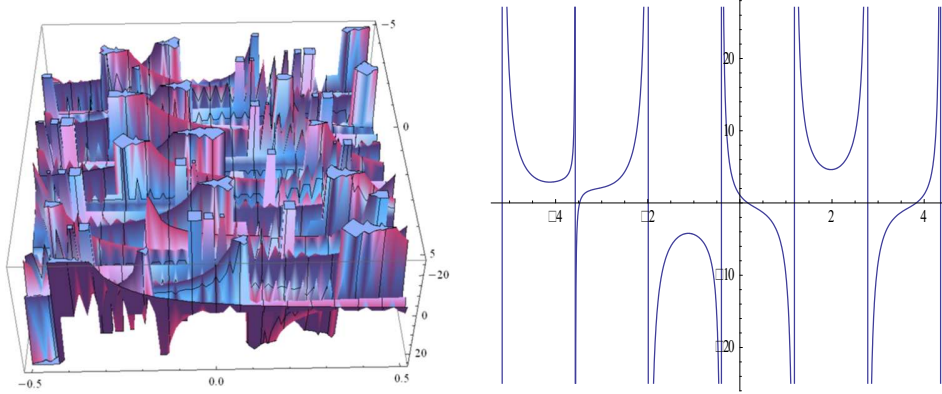


Figure 7: Graph of the solution  $\phi(\mu_6)$  corresponding to the values  $j_1 = q = 1, j_2 = \gamma = 2, p = -1, y = 0, m = 1/5$ .

Case (7):

$$l_1 = \frac{1}{2} \sqrt{\frac{(Q^2 - 4PR)(j_1^2 + j_2^2)(j_1^2 + qj_2^2)}{pj_1^2 - pqj_2^2}}, k_1 = \frac{1}{2} \sqrt{\frac{(j_1^2 + j_2^2)(j_1^2 + qj_2^2)}{pj_1^2 - pqj_2^2}}, k_0 = 0,$$

$$m_1 = \frac{1}{2} \sqrt{\frac{(j_1^2 + j_2^2)(j_1^2 + qj_2^2)}{pj_1^2 - pqj_2^2}}, n_1 = 0, \zeta = \frac{\gamma - \sqrt{\gamma^2 - 8(j_1^2 + j_2^2)(-Q + 3\sqrt{Q^2 - 4PR})}}{4},$$

$$j_3 = \frac{j_1 + j_2}{2} \left( \sqrt{\gamma^2 - 8(-Q + 3\sqrt{Q^2 - 4PR})(j_1^2 + j_2^2)} - \gamma \right). \quad (48)$$

When we put Eq. (48) into Eq. (35), we obtain the combined JEFSSs of Eq. (11),

$$\phi(\mu_7) = D_1 e^{i\sigma_7} \frac{(1 - m^2 - dn^2(\mu_7)) sn(\mu_7)}{cn(\mu_7) dn(\mu_7)},$$

$$\varphi(\mu_7) = D_2 \frac{(1 - m^2 - dn^2(\mu_7))^2 sn^2(\mu_7)}{cn^2(\mu_7) dn^2(\mu_7)}, \quad (49)$$

where  $\mu_7 = j_1 x + j_2 y + \frac{j_1 + j_2}{2} \left( \sqrt{\gamma^2 - 8(4 - 2m^2)(j_1^2 + j_2^2)} - \gamma \right) t, \sigma_7 = \frac{\gamma - \sqrt{\gamma^2 - 8(4 - 3m^2)(j_1^2 + j_2^2)}}{4} (x + y - \gamma t).$

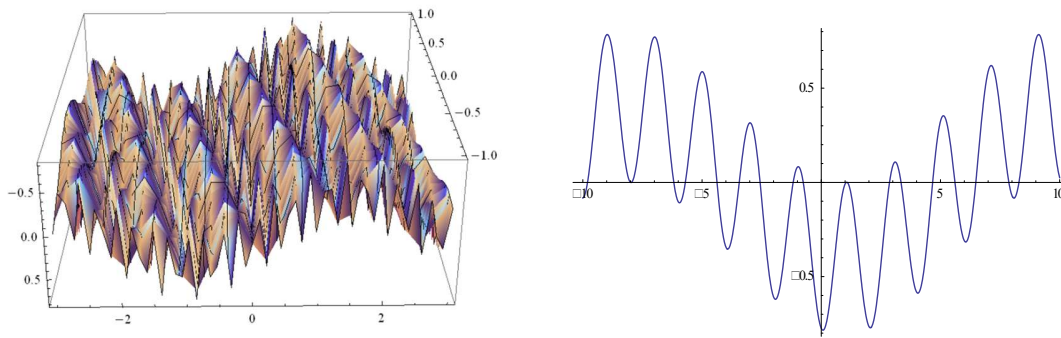


Figure 8: Graph of the solution  $\phi(\mu_7)$  corresponding to the values  $j_1 = q = 1, j_2 = 2, \gamma = 10, p = -1, y = 0, m = 3/4$

**Remark 2:** According to the results obtained, single, combined and mixed JEFs of Eq. (11) that we acquired with the new version of the generalized  $F'/F$ -expansion method is new and are not observed in the literature. Also, 2D and 3D graphics of the obtained solutions are shown in Figs. 5-8 which represent with appropriate parametric choices.

## 5. CONCLUSION

In this paper, the new versions of the generalized F-expansion method and the generalized  $F'/F$ -expansion method have been successfully implemented to achieve new exact solutions of the DSEs. These methods make it possible to obtain new function solutions. The new obtained results for DSEs seem to be very different and interesting. When the results obtained in reference [43] are examined, it is seen that trigonometric and hyperbolic function solutions are obtained. The results obtained here are completely different from these and include different types of Jacobi elliptic function solutions. These solutions include single, combined and multiple combined JEFs. Consequently, the current study is assumed an enterprise to fill the gap in the related literature. If we set the parameters in the attained JEFs as special values, a variety of special solutions like different solitary wave solutions are obtained. We propose that new solutions of other nonlinear complex models and nonlinear complex systems can be obtained with these fertile algorithms.

## CONFLICTS OF INTEREST

The authors declare that they have no conflict of interest.

## REFERENCES

- Ablowitz, M. J., & Clarkson, P. A. (1991). *Solitons, nonlinear evolution equations and inverse scattering*. Cambridge University Press.
- Baojian, H., Dianchen, L., & Fushu, S. (2009). The extended Jacobi elliptic functions expansion method and new exact solutions for the Zakharov equations. *World Journal of Modelling Simulation*, 3, 216–224.
- Cai, G., Wang, Q., & Huang, J. A. (2006). Modified F-expansion method for solving breaking soliton equation. *International Journal of Nonlinear Science*, 2, 122–128.
- Chen, H. T., & Hong-Qing, Z. (2006). New double periodic and multiple soliton solutions of the generalized (2 + 1)-dimensional Boussinesq equation. *Chaos, Solitons & Fractals*, 20, 765–769. <https://doi.org/10.1016/j.chaos.2003.08.006>
- Chen, Y., & Yan, Z. (2006). The Weierstrass elliptic function expansion method and its applications in nonlinear wave equations. *Chaos, Solitons & Fractals*, 29, 948–964. <https://doi.org/10.1016/j.chaos.2005.08.071>
- Chuntao, Y. A. (1996). Simple transformation for nonlinear waves. *Physics Letters A*, 224, 77–84. [https://doi.org/10.1016/S0375-9601\(96\)00770-0](https://doi.org/10.1016/S0375-9601(96)00770-0)

- Enam, I. (2010). Generalized Jacobi elliptic function method for traveling wave solutions of (2+1)-dimensional breaking soliton equation. *Cankaya University Journal of Science and Engineering*, 1, 39–50.
- Fan, E. G. (2000). Extended tanh-function method and its applications to nonlinear equations. *Physics Letters A*, 277, 212–218. [https://doi.org/10.1016/S0375-9601\(00\)00725-8](https://doi.org/10.1016/S0375-9601(00)00725-8)
- Feng, Z. S. (2002). On explicit exact solutions to the compound Burgers-KdV equation. *Physics Letters A*, 293, 57–66. [https://doi.org/10.1016/S0375-9601\(01\)00825-8](https://doi.org/10.1016/S0375-9601(01)00825-8)
- Fu, Z., Liu, S., Liu, S., & Zhao, Q. (2001). New Jacobi elliptic function expansion and new periodic solutions of nonlinear wave equations. *Physics Letters A*, 290, 72–76. [https://doi.org/10.1016/S0375-9601\(01\)00644-2](https://doi.org/10.1016/S0375-9601(01)00644-2)
- Gurefe, Y., Misirli, E., Ekici, M., & Sonmezoglu, A. (2013). Extended trial equation method to generalized nonlinear partial differential equations. *Applied Mathematics and Computation*, 219(10), 5253–5260. <https://doi.org/10.1016/j.amc.2012.11.046>
- Gurefe, Y., Misirli, E., & Sonmezoglu, A. (2011). Application of trial equation method to the nonlinear partial differential equations arising in mathematical physics. *Pramana – Journal of Physics*, 77(6), 1023–1029. <https://doi.org/10.1007/s12043-011-0201-5>
- Gurefe, Y., Sonmezoglu, A., & Misirli, E. (2012). Application of an irrational trial equation method to high dimensional nonlinear evolution equations. *Journal of Advanced Mathematical Studies*, 5(1), 41–47.
- Guo, S., & Zhou, Y. (2010). The extended -expansion method and its applications to the Whitham-Broer-Kaup-like equations and coupled Hirota-Satsuma KdV equations. *Applied Mathematics and Computation*, 215, 3214–3221. <https://doi.org/10.1016/j.amc.2009.10.008>
- He, J. H., & Wu, X. H. (2006). Exp-function method for nonlinear wave equations. *Chaos, Solitons & Fractals*, 30, 700–708. <https://doi.org/10.1016/j.chaos.2006.03.020>
- Inc, M., & Ergut, M. (2005). Periodic wave solutions for the generalized shallow water wave equation by the improved Jacobi elliptic function. *Applied Mathematics E-Notes*, 5, 89–96.
- Liu, C. S. (2005). Trial equation method and its applications to nonlinear evolution equations. *Acta Physica Sinica*, 54(6), 2505–2509. <https://doi.org/10.7498/aps.54.2505>
- Liu, C. S. (2006). Trial equation method for nonlinear evolution equations with rank inhomogeneous: Mathematical discussions and applications. *Communications in Theoretical Physics*, 45(2), 219–223. <https://doi.org/10.1088/0253-6102/45/2/005>
- Liu, C. S. (2010). Applications of complete discrimination system for polynomial for classifications of traveling wave solutions to nonlinear differential equations. *Computer Physics Communications*, 181(2), 317–324. <https://doi.org/10.1016/j.cpc.2009.10.006>
- Liu, S., Fu, S., Liu, S., & Zhao, Q. (2001). Jacobi elliptic function expansion method and periodic wave solutions of nonlinear wave equations. *Physics Letters A*, 289, 69–74. [https://doi.org/10.1016/S0375-9601\(01\)00580-1](https://doi.org/10.1016/S0375-9601(01)00580-1)
- Lu, H. L., Liu, X. Q., & Niu, L. A. (2010). Generalized -expansion method and its applications to nonlinear evolution equations. *Applied Mathematics and Computation*, 215(11), 3811–3816. <https://doi.org/10.1016/j.amc.2009.11.021>
- Malanyuk, T. M. (1991). Finite-gap solutions of the Davey-Stewartson II equations. *Communications of the Moscow Mathematical Society*, 46(5), 193–194.

- Malanyuk, T. M. (1994). Finite-gap solutions of the Davey-Stewartson I equations. *Journal of Nonlinear Science*, 4, 1–21.
- Matveev, V. B., & Salle, M. A. (1991). *Darboux transformations and solitons*. Springer-Verlag.
- Pandir, Y. (2014). New exact solutions of the generalized Zakharov-Kuznetsov modified equal-width equation. *Pramana – Journal of Physics*, 82(6), 949–964. <https://doi.org/10.1007/s12043-014-0748-z>
- Pandir, Y., Gurefe, Y., & Misirli, E. (2013). Classification of exact solutions to the generalized Kadomtsev-Petviashvili equation. *Physica Scripta*, 87(2), 1–12. <https://doi.org/10.1088/0031-8949/87/02/025003>
- Pandir, Y., Gurefe, Y., & Misirli, E. (2013). The extended trial equation method for some time fractional differential equations. *Discrete Dynamics in Nature and Society*, 2013, Article ID 491359, 1–8. <https://doi.org/10.1155/2013/491359>
- Pandir, Y., Gurefe, Y., Kadak, U., & Misirli, E. (2012). Classifications of exact solutions for some nonlinear partial differential equations with generalized evolution. *Abstract and Applied Analysis*, 2012, Article ID 478531, 1–16. <https://doi.org/10.1155/2012/478531>
- Qi, W., Yong, C., & Zhang, H. (2005). A new Jacobi elliptic function rational expansion method and its application to (1+1)-dimensional dispersive long wave equation. *Chaos, Solitons & Fractals*, 23, 477–483. <https://doi.org/10.1016/j.chaos.2004.04.029>
- Shen, S., & Pan, Z. (2003). A note on the Jacobi elliptic function expansion method. *Physics Letters A*, 308, 143–148. [https://doi.org/10.1016/S0375-9601\(02\)01802-9](https://doi.org/10.1016/S0375-9601(02)01802-9)
- Tajiri, M., & Arai, T. (2010). Periodic soliton solutions to the Davey-Stewartson equation. *Proceedings of the Institute of Applied Mathematics and Mechanics of the National Academy of Sciences of Ukraine*, 30(1), 210–217.
- Wang, M., Li, X., & Zhang, J. (2008). The F-expansion method and travelling wave solutions of nonlinear evolution equations in mathematical physics. *Physics Letters A*, 372, 417–424. <https://doi.org/10.1016/j.physleta.2007.07.051>
- Wang, M., & Li, X. (2005). Applications of F-expansion to periodic wave solutions for a new Hamiltonian amplitude equation. *Chaos, Solitons & Fractals*, 24, 1257–1268. <https://doi.org/10.1016/j.chaos.2004.09.044>
- Xia, T., & Zhang, S. (2008). An improved generalized F-expansion method and its application to the (2+1)-dimensional KdV equations. *Communications in Nonlinear Science and Numerical Simulation*, 13, 1294–1301. <https://doi.org/10.1016/j.cnsns.2006.12.008>
- Xia, T. A., & Zhang, S. (2007). Generalized F-expansion method with symbolic computation exactly solving Broer–Kaup equations. *Applied Mathematics and Computation*, 189, 949–955. <https://doi.org/10.1016/j.amc.2006.11.143>
- Xia, X. Y., Haili, X., & Hongqing, Z. (2012). An extended elliptic equation expansion method and its application in the ZK-MEW equation. *International Journal of Nonlinear Science*, 3, 316–322.
- Xia, X. Y., Haili, X., & Hongqing, Z. (2012). A new extended Jacobi elliptic function expansion method and its application to the generalized shallow water wave equation. *Journal of Applied Mathematics*, 2012, Article ID 896748, 1–21. <https://doi.org/10.1155/2012/896748>
- Xun, C. (2011). Jacobi elliptic function solutions for (2 + 1) dimensional Boussinesq and Kadomtsev-Petviashvili equation. *Applied Mathematics*, 2, 1313–1316. <https://doi.org/10.4236/am.2011.211183>
- Yang, K., & Liu, J. (2004). The extended F-expansion method and exact solutions of nonlinear PDEs. *Chaos, Solitons & Fractals*, 22, 111–121. <https://doi.org/10.1016/j.chaos.2003.12.069>

Yong, C., Qi, W., & Biao, L. (2004). Jacobi elliptic function rational expansion method with symbolic computation to construct new doubly-periodic solutions of nonlinear evolution equations. *Zeitschrift für Naturforschung A*, 59a, 529–536. <https://doi.org/10.1515/zna-2004-0901>

Zhang, J. L., Wang, M. L., Wang, Y. M., & Fang, Z. D. (2006). The improved F-expansion method and its applications. *Physics Letters A*, 350, 103–109. <https://doi.org/10.1016/j.physleta.2005.10.099>

Zhang, S., Li, W., Zheng, F., Yu, J., Ji, M., Lu, Z., & Ma, C. A. (2008). Generalized F-expansion method and its application to (2+1)-dimensional breaking soliton equations. *International Journal of Nonlinear Science*, 5, 25–32.