# Estimation of population distribution function in the presence of non-response 

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#### Abstract

This article addresses the problem of estimating the population distribution function in the presence of non-response. We suggest a general class of estimators for estimating the cumulative distribution function using the auxiliary information. Expressions for bias and mean squared error of considered estimators are derived up to the first order of approximation. The performance of estimators are compared theoretically and numerically. A numerical study is carried out to evaluate the performances of estimators.


Keywords: Auxiliary variable; absolute relative bias; cumulative distribution function; mean squared error; relative efficiency.
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## 1. Introduction

It is a well established phenomenon in the theory of sample survey that the nonresponse is an unavoidable fact, which is devastating and almost in every surveys of human respondents, suffer from some degree of non-response. Non-response mainly classified as: ( $i$ ), unit non-response or total failure, in which entire unit is missing, for example, a person may totally refuse or unable to participate in the survey for some specified reasons and (ii), item non-response or partial failure, in which at least one item is missing from some measurements for the given observations. For example, a household may hesitate to give information about his income. The problem of non-response has already been tackled from different ways, is common and widespread in mail surveys than in personal interviewing. The usual approach to overcome non-response problem is to contact the non-respondent and obtain maximum information as much as possible.

[^0]Hansen and Hurwitz [11] were the first to suggest a non-response technique in mail surveys, combined the advantages of mailed questionnaires and personal interviews. They plan first use the economies involved in the use of questionnaires by mailing them to a sample of population under study. After this a follow-up is carried out by interviewing a subsample of the non-respondents.

Consider a finite population of size $N$ and a random sample of size $m$ is drawn from a population by using simple random sample without replacement (SRSWOR) sampling scheme. In survey of human populations, it is often the case that $m_{R}$ units respond, but the remaining $m_{M}=\left(m-m_{R}\right)$ units do not. The initial survey may be conducted through the mail or by telephone, perhaps computer aided. Hansen and Hurwitz [11] suggested a two phase sampling scheme for estimating the population mean by using the following steps.
(a) a simple random sample of size $m$ is selected and the questionnaire are mailed to the sampled units;
(b) a subsample of size $r=\frac{m_{M}}{k}$ for $(k>1)$ is taken from $m_{M}$ non-responding units. The graphical illustration of non-response scheme is given in Figure 1. A widely debated


Figure 1. Illustration of Hansen and Hurwitz [11] non-response scheme
topic in sample survey is the estimation of population mean for the study variable by using the auxiliary variables in the presence of non-response. Several authors including Chambers and Dunstan [3], Rao [28], Rao et al. [27], Khare and Srivastava [17, 18, 19], Olkin [25] suggested different types of estimators for estimation of population mean using the auxiliary information under non-response. Okafor and Lee [24] presented ratio and regression estimation with sub-sampling the non-respondents in estimating the population mean $\bar{Y}$. Further, Khare and Sinha $[14,15,16]$ proposed some classes of estimators for estimating population mean using multi-auxiliary characters in different way. For the estimating population mean under two-phase sampling scheme in presence of nonresponse, Singh and Kumar [34, 35, 36], Klein [20], Tabasum and Khan [40], and Shabbir
and Nasir [33] have made significant contributions. Diana and Perri [5] suggested a class of estimators in two-phase sampling with sub-sampling of non respondents in estimating the finite population mean. For controlling the non-response bias and eliminating the need for call backs in survey sampling, John and Robert [13], citeBS, and Dunkelberg and Goerge [7], El-Badry [8], Diana and Perri [4], Hansen et al. [12], and Politz and Simmons [26], discussed some good techniques and plans.

An extensive literature is available on estimation of population mean under nonresponse, but lesser effort has been devoted in the development of efficient methods for population cumulative distribution function by using the auxiliary information.

We are often concerned with the proportion of $y_{i}$ values in the population. Users of sample survey data commonly need to estimate the population distribution function, or, equivalently, the proportion of units in the population with values less than or equal to a specified value $t_{y}$. For example, we may be interested in the proportion of agricultural area for poisonous effect of pesticides less than zero, the proportion of filtration plants for the present of arsenic in portable water less than zero. Such a proportion is particular value of the cumulative distribution function (CDF) for the population.

$$
F_{Y}\left(t_{y}\right)=\frac{1}{N} \sum_{i=1}^{N} I\left(y_{i} \leq t_{y}\right)
$$

Above expression is just the average of the values of Bernoulli distribution $I\left(y_{i} \leq t_{y}\right)$ over all elements of the population, where $I\left(y_{i} \leq t_{y}\right)=1$ for $y \leq t_{y}$ and $I\left(y_{i} \leq t_{y}\right)$ $=0$, for $y>t_{y}$. Often in survey sampling, we can only measure the study variable for those items in some sample, thus, the usual estimators of the distribution function depends exclusively on the selection of the sampling design and the sampled portion of the population. It is often seen the case, that some values of study variable are not available for non-sampled portion of the population, so we may use auxiliary information for improving the efficiency of population distribution function.

Chambers and Dunstan [3] and Chambers et al. [2] suggested the procedure and properties for estimating the finite population distribution function and the quantiles based on use of the auxiliary information. Rao et al. [27] used a general sampling design and proposed ratio and difference type estimators for population distribution function. Kuk [21], presented a classical as well as a prediction approach in estimating the distribution function from survey data. Some more work is due to Woodruff [42], Kuk and Mak [22, 23], Rueda et al. [30, 31], Rueda and Arcos [29], Dorfman [6], Ahmed and Abu-Dayyeh [1], and Singh and Joarder [39].

In presence of the auxiliary information, there exist several general estimation procedures. For more details see Wang and Alan [41], Kuk and Mak [23], Rao et al. [27], Rueda et al. [31], Garcia and Cebrian [9] and Singh et al. [37] to obtain more efficient estimates for the population mean or totals.

An extensive literature is available on estimation of population mean under nonresponse, but lesser effort has been devoted in the development of efficient methods for population cumulative distribution function (CDF) by using the auxiliary information. The present article focuses on the estimation of population distribution function of the study variable using the auxiliary information when data are not collected from all sampled units due to the problem of non-response.

We organize the rest of the article as follows: Section 2 introduces the notations and symbols. Section 3 gives detailed proof for estimating the population distribution function under non-response case. Section 4 contains the expressions for the bias and mean squared error (MSE). Section 5 gives a general class of estimators to first order
of approximation. A numerical study is presented in Section 6 and cost of the survey is discussed in Section 7. Section 8 gives the conclusion.

## 2. Notations and symbols

Consider a finite population $\Omega=\{1,2, \ldots, N\}$ having $N$ distinct and identifiable units. Let $\left(y_{1}, y_{2}, \ldots, y_{N}\right)$ be the values of the study variable $Y$. For each index $t_{y}$, $\left(-\infty<t_{y}<+\infty\right)$, the cumulative distribution function (CDF) of $Y$ is given by

$$
\begin{equation*}
F_{Y}\left(t_{y}\right)=\frac{1}{N} \sum_{i=1}^{N} I\left(y_{i} \leq t_{y}\right) \tag{2.1}
\end{equation*}
$$

where $I($.$) is an indicator function.$
Then the corresponding population $\beta$ quantile $(0<\beta<1)$ is defined by

$$
\begin{equation*}
Q_{Y}(\beta)=\inf \left\{y \mid F_{Y}(y) \geq \beta\right\}=F_{Y}^{-1}(\beta), \tag{2.2}
\end{equation*}
$$

where inf stands for infinimum. The problem is to estimate $F_{Y}\left(t_{y}\right)$ for any given $t_{y}$. We draw a random sample of size $m$ from $N$ by simple random sampling without replacement sampling scheme (SRSWOR). Then given $t_{y}$, the $F_{Y}\left(t_{y}\right)$ can be estimated by

$$
\begin{equation*}
\hat{F}_{Y}\left(t_{y}\right)=\frac{1}{m} \sum_{i=1}^{m} I\left(y_{i} \leq t_{y}\right) \tag{2.3}
\end{equation*}
$$

Following Garcia and Cebrian [9], it is easy to show that

$$
\begin{equation*}
E\left(\hat{F}_{Y}\left(t_{y}\right)\right)=F_{Y}\left(t_{y}\right) \quad \text { and } \quad V\left(\hat{F}_{Y}\left(t_{y}\right)\right)=\frac{N-m}{m(N-1)} F_{Y}\left(t_{y}\right)\left(1-F_{Y}\left(t_{y}\right)\right) \tag{2.4}
\end{equation*}
$$

where $E($.$) \quad and \quad V($.$) are the mathematical expectation and variance of (.), respec-$ tively. The layout of response stratum is given in Table 1.

Table 1. Layout of respondent stratum

|  | $X \leq F_{X}\left(t_{x}\right)$ | $X>F_{X}\left(t_{x}\right)$ | Total |
| :---: | :---: | :---: | :---: |
| $Y \leq F_{Y}\left(t_{y}\right)$ | $m_{11} / N_{11}$ | $m_{12} / N_{12}$ | $N_{1 .}$ |
| $Y>F_{Y}\left(t_{y}\right)$ | $m_{21} / N_{21}$ | $m_{22} / N_{22}$ | $N_{2 .}$ |
| Total | $N_{.1}$ | $N_{.2}$ | N |

Here, $N_{11}, N_{12}, N_{21}$, and $N_{22}$ be the number of units in the population in their respective cells for respondents. Similarly, $m_{11}, m_{12}, m_{21}$, and $m_{22}$ be the number of units in the sample in their respective cells. Hence ( $m_{11}, m_{12}, m_{21}, m_{22}$ ) is a trivariate Hyper Geometrically $(T H G)$ distributed random variable,
i.e., $\left(m_{11}, m_{12}, m_{21}, m_{22}\right) \sim T H G\left(N, m, N_{11}, N_{12}, N_{21}\right)$.

Also $m \hat{F}_{Y}\left(t_{y}\right)=m_{11}+m_{12}$ and $m \hat{F}_{X}\left(t_{x}\right)=m_{11}+m_{21}$.
The non-response stratum layout is given in Table 2.
Table 2. Layout of non-response stratum

|  | $X_{2} \leq F_{X}^{(2)}\left(t_{x_{2}}\right)$ | $X_{2}>F_{X}^{(2)}\left(t_{x_{2}}\right)$ | Total |
| :---: | :---: | :---: | :---: |
| $Y_{2} \leq F_{Y}^{(2)}\left(t_{y_{2}}\right)$ | $m_{11}^{(2)} / N_{11}^{(2)}$ | $m_{12}^{(2)} / N_{12}^{(2)}$ | $N_{1}^{(2)}$ |
| $Y_{2}>F_{Y}^{(2)}\left(t_{y_{2}}\right)$ | $m_{21}^{(2)} / N_{21}^{(2)}$ | $m_{22}^{(2)} / N_{22}^{(2)}$ | $N_{2 .}^{(2)}$ |
| Total | $N_{.1}^{(2)}$ | $N_{.2}^{(2)}$ | N |

Here, $N_{11}^{(2)}, N_{12}^{(2)}, N_{21}^{(2)}$, and $N_{22}^{(2)}$ be the number of units in the population in their respective cells for non-respondents. Similarly, $m_{11}^{(2)}, m_{12}^{(2)} m_{21}^{(2)}$ and $m_{22}^{(2)}$ be the number of units in the sample in their respective cells.
Let $\left\{I\left(Y_{i} \leq t_{y}\right), I\left(X_{i} \leq t_{x}\right)\right\}=1$ if $i$ th unit possesses an attribute and
$\left\{I\left(Y_{i} \leq t_{y}\right), I\left(X_{i} \leq t_{x}\right)\right\}=0$ otherwise, which follows the uniform probability distribution. Let sample means $\left(\hat{F}_{Y i}^{*}\left(t_{y}\right), \hat{F}_{X i}^{*}\left(t_{x}\right)\right)$ be the unbiased estimators of population means $\left(F_{Y}\left(t_{y}\right), F_{X}\left(t_{x}\right)\right)$ based on $m$ observations. Let $S_{F_{Y}}^{2}\left(t_{y}\right)=F_{Y}\left(t_{y}\right)\left(1-F_{Y}\left(t_{y}\right)\right)$, $S_{F_{X}}^{2}\left(t_{x}\right)=F_{X}\left(t_{x}\right)\left(1-F_{X}\left(t_{x}\right)\right)$,
$S_{F_{X 2}}^{2}\left(t_{x_{2}}\right)=F_{X 2}\left(t_{x_{2}}\right)\left(1-F_{X 2}\left(t_{x_{2}}\right)\right)$ be the population variances and $S_{F_{Y X}}\left(t_{y}, t_{x}\right)=F_{Y, X}\left(t_{y}, t_{x}\right)-F_{Y}\left(t_{y}\right) F_{X}\left(t_{x}\right)$ be the population covariance for Stratum 1 and Stratum 2 respectively.
Also $C_{F_{Y}}\left(t_{y}\right)=\frac{1-F_{Y}\left(t_{y}\right)}{F_{Y}\left(t_{y}\right)}, C_{F_{X}}\left(t_{x}\right)=\frac{1-F_{Y}\left(t_{x}\right)}{F_{Y}\left(t_{x}\right)}, C_{F_{X 2}}\left(t_{x_{2}}\right)=\frac{1-F_{X_{2}}\left(t_{x_{2}}\right)}{F_{X_{2}}\left(t_{x_{2}}\right)}$ be the population coefficient of variations of $X$ for Stratum 1 and Stratum 2 respectively.
Let $\beta_{1}\left(F_{X}\left(t_{x}\right)\right)=\frac{1-2 F_{X}\left(t_{x}\right)}{\sqrt{F_{X}\left(t_{x}\right)\left(1-F_{X}\left(t_{x}\right)\right)}}$ and $\beta_{2}\left(F_{X}\left(t_{x}\right)\right)=\frac{1-3 F_{X}\left(t_{x}\right)+3 F_{X}^{2}\left(t_{x}\right)}{F_{X}\left(t_{x}\right)\left(1-F_{X}\left(t_{x}\right)\right)}$ be the population coefficients of skewness and kurtosis of $X$. Let $\left(\rho_{\left(F_{Y}\left(t_{y}\right), F_{X}\left(t_{x}\right)\right)}\right)=\frac{S_{F_{Y X}\left(t_{y}, t_{x}\right)}}{S_{F_{Y}}\left(t_{y}\right) S_{F_{X}}\left(t_{x}\right)}$ be the phi-population correlation coefficient. To obtain Bias and MSE of estimators up to first order of approximation, we define the following relative error terms.
Let $e_{0}^{*}=\frac{\hat{F}_{Y}^{*}\left(t_{y}\right)-F_{Y}\left(t_{y}\right)}{F_{Y}\left(t_{y}\right)}, e_{1}^{*}=\frac{\hat{F}_{X}^{*}\left(t_{x}\right)-F_{X}\left(t_{x}\right)}{F_{X}\left(t_{x}\right)}, e_{0}=\frac{\hat{F}_{Y}\left(t_{y}\right)-F_{Y}\left(t_{y}\right)}{F_{Y}\left(t_{y}\right)}$ and $e_{1}=\frac{\hat{F}_{X}\left(t_{x}\right)-F_{X}\left(t_{x}\right)}{F_{X}\left(t_{x}\right)}$ such that $E\left(e_{i}^{*}\right)=E\left(e_{i}\right)=0$, for $i=0,1$. To first order of approximation we have
$E\left(e_{0}^{* 2}\right)=\frac{1}{F_{Y}^{2}\left(t_{y}\right)}\left\{\lambda_{1} F_{Y}\left(t_{y}\right)\left(1-F_{Y}\left(t_{y}\right)\right)+\lambda_{2} F_{Y}^{(2)}\left(t_{y_{2}}\right)\left(1-F_{Y}^{(2)}\left(t_{y_{2}}\right)\right)\right\} \cong V_{20}^{*}$,
$E\left(e_{1}^{* 2}\right)=\frac{1}{F_{X}^{2}\left(t_{x}\right)}\left\{\lambda_{1} F_{X}\left(t_{x}\right)\left(1-F_{X}\left(t_{x}\right)\right)+\lambda_{2} F_{X}^{(2)}\left(t_{x_{2}}\right)\left(1-F_{X}^{(2)}\left(t_{x_{2}}\right)\right)\right\} \cong V_{02}^{*}$,
$E\left(e_{0}^{*} e_{1}^{*}\right)=\frac{1}{F_{Y}\left(t_{y}\right) F_{X}\left(t_{x}\right)}\left\{\lambda_{1}\left(\frac{N_{11} N_{22}-N_{12} N_{21}}{N^{2}}\right)+\lambda_{2}\left(\frac{N_{11}^{(2)} N_{22}^{(2)}-N_{12}^{(2)} N_{21}^{(2)}}{\left(N_{2}^{(2)}\right)^{2}}\right)\right\} \cong V_{11}^{*}$,
$E\left(e_{0}^{2}\right)=\frac{1}{F_{Y}^{2}\left(t_{y}\right)}\left\{\lambda_{1} F_{Y}\left(t_{y}\right)\left(1-F_{Y}\left(t_{y}\right)\right)\right\} \cong V_{20}$,
$E\left(e_{1}^{2}\right)=\frac{1}{F_{X}^{2}\left(t_{x}\right)}\left\{\lambda_{1} F_{X}\left(t_{x}\right)\left(1-F_{X}\left(t_{x}\right)\right)\right\} \cong V_{02}$,
$E\left(e_{0}^{*} e_{1}\right)=\frac{1}{F_{Y}\left(t_{y}\right) F_{X}\left(t_{x}\right)}\left\{\lambda_{1}\left(\frac{N_{11} N_{22}-N_{12} N_{21}}{N^{2}}\right)\right\} \cong V_{11}^{*^{\prime}}$,
where
$V_{r s}^{*}=\frac{E\left\{\left(\hat{F}_{Y}^{*}\left(t_{y}\right)-F_{Y}\left(t_{y}\right)\right)^{r}\left(\hat{F}_{X}^{*}\left(t_{x}\right)-F_{X}\left(t_{x}\right)\right)^{s}\right\}}{\left(F_{Y h}\left(t_{y}\right)\right)^{r}\left(F_{X h}\left(t_{x}\right)\right)^{s}}, V_{r s}^{*^{\prime}}=\frac{E\left\{\left(\hat{F}_{Y}^{*}\left(t_{y}\right)-F_{Y}\left(t_{y}\right)\right)^{r}\left(\hat{F}_{X}\left(t_{x}\right)-F_{X}\left(t_{x}\right)\right)^{s}\right\}}{\left(F_{Y h}\left(t_{y}\right)\right)^{r}\left(F_{X h}\left(t_{x}\right)\right)^{s}}$.
$\lambda_{1}=\left(\frac{1}{m}-\frac{1}{N}\right)$, and $\lambda_{2}=\frac{W_{M}(k-1)}{m}$, with $W_{M}=\frac{N_{M}}{N}, N_{M}$ be the number of units in the population corresponding to non-response group.

## 3. Estimation of population distribution function under non-response

In this section, we drive the expressions for mean, variance and covariance of the estimator, $\hat{F}_{Y}^{(*)}\left(t_{y}\right)=w_{R} \hat{F}_{Y}^{(1)}\left(t_{y}\right)+w_{M} \hat{F}_{Y}^{(2 r)}\left(t_{y_{2}}\right)$ under non-response for estimating the CDF.
Suppose that the underlying population is divided into two homogeneous strata: (i) response group and (ii) non-response group. Let $N_{R}$ and $N_{M}$ be the number of units in the population that correspond to the response group and the non-response group, respectively, where $N_{R}+N_{M}=N$. Given this information, following Gross [10], the finite population $\mathrm{CDF}, F_{Y}\left(t_{y}\right)$, can be written as

$$
\begin{equation*}
F_{Y}\left(t_{y}\right)=W_{R} F_{Y}^{(1)}\left(t_{y}\right)+W_{M} F_{Y}^{(2)}\left(t_{y_{2}}\right), \tag{3.1}
\end{equation*}
$$

where $W_{i}=N_{i} / N$ for $i=R, M$.
Out of $m$ selected units, $m_{R}$ units respond and $m_{M}$ units do not respond, where $m_{R}+$ $m_{M}=m$. In order to get response from $m_{M}$, the non-respondents are contacted once
again by personal interview. Then sub-sample of size $r=m_{M} / k$ for $(k>1)$, is obtained from $m_{M}$ non-responding units. It is assumed that all $r$ units respond. Let $\hat{F}_{Y}^{(1)}\left(t_{y}\right)$ and $\hat{F}_{Y}^{(2 r)}\left(t_{y_{2}}\right)$ be the CDF estimators based on $m_{R}$ and $r$ responding units. On the lines of Hansen and Hurwitz [11], the estimator of $F_{Y}\left(t_{y}\right)$ under non-response is given by

$$
\begin{equation*}
\hat{F}_{Y}^{(*)}\left(t_{y}\right)=w_{R} \hat{F}_{Y}^{(1)}\left(t_{y}\right)+w_{M} \hat{F}_{Y}^{(2 r)}\left(t_{y_{2}}\right) \tag{3.2}
\end{equation*}
$$

where $w_{i}=m_{i} / m$ for $i=R, M$.
Based on the estimator given in (3.2), we present the following theorem.

## Theorem 1

(i) $\hat{F}_{Y}^{(*)}\left(t_{y}\right)$ is an unbiased estimator of $F_{Y}\left(t_{y}\right)$, i.e., $E\left(\hat{F}_{Y}^{(*)}\left(t_{y}\right)\right)=F_{Y}\left(t_{y}\right)$.
(ii) $\operatorname{Var}\left(\hat{F}_{Y}^{(*)}\left(t_{y}\right)\right)$

$$
=\left[\frac{N-m}{m(N-1)} F_{Y}\left(t_{y}\right)\left(1-F_{Y}\left(t_{y}\right)\right)+\frac{W_{M}(k-1)}{m} \frac{N_{M}}{N_{M}-1} F_{Y}^{(2)}\left(t_{y_{2}}\right)\left(1-F_{Y}^{(2)}\left(t_{y_{2}}\right)\right)\right] .
$$

(iii) $\operatorname{Cov}\left(\hat{F}_{Y}^{(*)}\left(t_{y}\right), \hat{F}_{X}^{(*)}\left(t_{x}\right)\right)$

$$
=\left[\frac{(1-f)}{m}\left(\frac{N_{11} N_{22}-N_{12} N_{21}}{(N)^{2}}\right)+\frac{W_{M}(k-1)}{m}\left(\frac{N_{11}^{(2)} N_{22}^{(2)}-N_{12}^{(2)} N_{21}^{(2)}}{\left(N_{M}^{(2)}\right)^{2}}\right)\right] \text {. }
$$

Proof (i). Taking mathematical expectation on both sides of (3.2), we have
$E\left(\hat{F}_{Y}^{(*)}\left(t_{y}\right)\right)=E\left\{w_{R} \hat{F}_{Y}^{(1)}\left(t_{y}\right)\right\}+E\left\{w_{M} \hat{F}_{Y}^{(2 r)}\left(t_{y_{2}}\right)\right\}$,
$E\left(\hat{F}_{Y}^{(*)}\left(t_{y}\right)\right)=E_{1}\left\{w_{R} E_{2}\left(\hat{F}_{Y}^{(1)}\left(t_{y}\right) \mid m_{R}\right)\right\}+E\left\{w_{M} E_{2}\left(\hat{F}_{Y}^{(2 r)}\left(t_{y_{2}}\right) \mid m_{R}\right)\right\}$,
$E\left(\hat{F}_{Y}^{(*)}\left(t_{y}\right)\right)=E_{1}\left\{w_{R}\left(F_{Y}^{(1)}\right)\left(t_{y}\right) \mid m_{R}\right\}+E\left\{w_{M} E_{2}\left(E_{3}\left(\hat{F}_{Y}^{(2 r)}\left(t_{y_{2}}\right) \mid r, m_{R}\right)\right)\right\}$,
$E\left(\hat{F}_{Y}^{(*)}\left(t_{y}\right)\right)=E_{1}\left\{w_{R}\left(F_{Y}^{(1)}\right)\left(t_{y}\right) \mid m_{R}\right\}+E\left\{w_{M} E_{2}\left(\hat{F}_{Y}^{(2)}\left(t_{y_{2}}\right) \mid m_{R}\right)\right\}$,
$E\left(\hat{F}_{Y}^{(*)}\left(t_{y}\right)\right)=E_{1}\left\{w_{R}\left(F_{Y}^{(1)}\right)\left(t_{y}\right) \mid m_{R}\right\}+E\left\{w_{M}\left(F_{Y}^{(2)}\left(t_{y_{2}}\right) \mid m_{R}\right)\right\}$,
$E\left(\hat{F}_{Y}^{(*)}\left(t_{y}\right)\right)=W_{R} F_{Y}^{(1)}\left(t_{y}\right)+W_{M} F_{Y}^{(2)}\left(t_{y_{2}}\right)=F_{Y}\left(t_{y}\right)$,
which completes the proof.
Proof (ii). From (3.2), we can write

$$
\begin{equation*}
\hat{F}_{Y}^{(*)}(t)=\hat{F_{Y}}\left(t_{y}\right)+w_{M}\left(\hat{F}_{Y}^{(2 r)}\left(t_{y_{2}}\right)-\hat{F}_{Y}^{(2)}\left(t_{y_{2}}\right)\right) \tag{3.3}
\end{equation*}
$$

where, $\hat{F}_{Y}\left(t_{y}\right)=w_{R} \hat{F}_{Y}^{(1)}\left(t_{y}\right)+w_{M} \hat{F}_{Y}^{(2)}\left(t_{y_{2}}\right)$.
It is easy to show that

$$
\begin{equation*}
E\left(\hat{F}_{Y}\left(t_{y}\right)\right)=F_{Y}\left(t_{y}\right) \tag{3.4}
\end{equation*}
$$

and

$$
\begin{equation*}
\operatorname{Var}\left(\hat{F}_{Y}\left(t_{y}\right)\right)=\left[\frac{N-m}{m(N-1)} F_{Y}\left(t_{y}\right)\left(1-F_{Y}\left(t_{y}\right)\right)\right] \tag{3.5}
\end{equation*}
$$

If we consider $N-1 \cong N$, then we can write (3.5) as

$$
\operatorname{Var}\left(\hat{F}_{Y}(t)\right)=\left[\frac{N-m}{m N} F_{Y}\left(t_{y}\right)\left(1-F_{Y}\left(t_{y}\right)\right)\right] .
$$

Applying variance on both sides of (3.3), we get

$$
\operatorname{Var}\left(\hat{F}_{Y}^{(*)}\left(t_{y}\right)\right)=\left[\begin{array}{r}
\frac{N-m}{m N} F_{Y}\left(t_{y}\right)\left(1-F_{Y}\left(t_{y}\right)\right)  \tag{3.6}\\
+\operatorname{Var}\left\{w_{M}\left(\hat{F}_{Y}^{(2 r)}\left(t_{y_{2}}\right)-\hat{F}_{Y}^{(2)}\left(t_{y_{2}}\right)\right)\right\} \\
+2 \operatorname{Cov}\left\{\hat{F}_{Y}\left(t_{y}\right), w_{M}\left(\hat{F}_{Y}^{(2 r)}\left(t_{y_{2}}\right)-\hat{F}_{Y}^{(2)}\left(t_{y_{2}}\right)\right)\right\}
\end{array}\right] .
$$

From (3.6), we can write

$$
\operatorname{Var}\left\{w_{M}\left(\hat{F}_{Y}^{(2 r)}\left(t_{y_{2}}\right)-\hat{F}_{Y}^{(2)}\left(t_{y_{2}}\right)\right)\right\}=\left[\begin{array}{c}
V_{1} E_{2}\left\{w_{M}\left(\hat{F}_{Y}^{(2 r)}\left(t_{y_{2}}\right)-\hat{F}_{Y}^{(2)}\left(t_{y_{2}}\right)\right)\right\}  \tag{3.7}\\
+E_{1} V_{2}\left\{w_{M}\left(\hat{F}_{Y}^{(2 r)}\left(t_{y_{2}}\right)-\hat{F}_{Y}^{(2)}\left(t_{y_{2}}\right)\right)\right\}
\end{array}\right] .
$$

Considering the terms on right hand side of (3.7), we have
$V_{1} E_{2}\left\{w_{M}\left(\hat{F}_{Y}^{(2 r)}\left(t_{y_{2}}\right)-\hat{F}_{Y}^{(2)}\left(t_{y_{2}}\right)\right)\right\}=V_{1} E_{2} E_{3}\left\{w_{M}\left(\hat{F}_{Y}^{(2 r)}\left(t_{y_{2}}\right)-\hat{F}_{Y}^{(2)}\left(t_{y_{2}}\right)\right)\right\}$

$$
\begin{equation*}
E_{1} V_{2}\left\{w_{M}\left(\hat{F}_{Y}^{(2 r)}\left(t_{y_{2}}\right)-\hat{F}_{Y}^{(2)}\left(t_{y_{2}}\right)\right)\right\}=E_{1}\left\{w_{M}^{2} V_{2}\left(\hat{F}_{Y}^{(2 r)}\left(t_{y_{2}}\right)-\hat{F}_{Y}^{(2)}\left(t_{y_{2}}\right)\right)\right\} . \tag{3.8}
\end{equation*}
$$

Considering the term on right hand side of (3.9), we have
$V_{2}\left\{\left(\hat{F}_{Y}^{(2 r)}\left(t_{y_{2}}\right)-\hat{F}_{Y}^{(2)}\left(t_{y_{2}}\right)\right)\right\}$
$=V_{2} E_{3}\left\{\left(\hat{F}_{Y}^{(2 r)}\left(t_{y_{2}}\right)-\hat{F}_{Y}^{(2)}\left(t_{y_{2}}\right)\right)\right\}+E_{2} V_{3}\left\{\left(\hat{F}_{Y}^{(2 r)}\left(t_{y_{2}}\right)-\hat{F}_{Y}^{(2)}\left(t_{y_{2}}\right)\right)\right\}$,
$\stackrel{\text { or }}{V_{2}}\left\{\left(\hat{F}_{Y}^{(2 r)}\left(t_{y_{2}}\right)-\hat{F}_{Y}^{(2)}\left(t_{y_{2}}\right)\right)\right\}=E_{2} V_{3}\left\{\left(\hat{F}_{Y}^{(2 r)}\left(t_{y_{2}}\right)-\hat{F}_{Y}^{(2)}\left(t_{y_{2}}\right)\right)\right\}$.
Finally, we get

$$
\begin{equation*}
V_{2}\left\{\left(\hat{F}_{Y}^{(2 r)}\left(t_{y_{2}}\right)-\hat{F}_{Y}^{(2)}\left(t_{y_{2}}\right)\right)\right\}=\frac{m_{M}-r}{r\left(m_{M}-1\right)} E_{2}\left\{\hat{F}_{Y}^{(2)}\left(t_{y_{2}}\right)\left(1-\hat{F}_{Y}^{(2)}\left(t_{y_{2}}\right)\right)\right\} \tag{3.10}
\end{equation*}
$$

Replace the values of $r=m_{M} / k, E_{2}\left(\hat{F}_{Y}^{(2)}\left(t_{y_{2}}\right)\right)=F_{Y}^{(2)}\left(t_{y_{2}}\right)$ and
$E_{2}\left(F_{Y}^{(2)}\left(t_{y_{2}}\right)\right)^{2}=V_{2}\left(\hat{F} Y^{(2)}\left(t_{y_{2}}\right)\right)+\left(F_{Y}^{(2)}\left(t_{y_{2}}\right)\right)^{2}$
$=\frac{N_{M}-m_{M}}{m_{M}\left(N_{M}-1\right)} F_{Y}^{(2)}\left(t_{y_{2}}\right)\left(-F_{Y}^{(2)}\left(t_{y_{2}}\right)\right)+\left(F_{Y}^{(2)}\left(t_{y_{2}}\right)\right)^{2}$ in (3.10), and after some simplifications, we get
(3.11) $\quad V_{2}\left\{\left(\hat{F}_{Y}^{(2 r)}\left(t_{y_{2}}\right)-\hat{F}_{Y}^{(2)}\left(t_{y_{2}}\right)\right)\right\}=\frac{N_{M}(k-1)}{m_{M}\left(N_{M}-1\right)} F_{Y}^{(2)}\left(t_{y_{2}}\right)\left(1-F_{Y}^{(2)}\left(t_{y_{2}}\right)\right)$.

Substituting (3.11) in (3.9), we have
$E_{1}\left\{w_{M}^{2} V_{2}\left(\hat{F}_{Y}^{(2 r)}\left(t_{y_{2}}\right)-\hat{F}_{Y}^{(2)}\left(t_{y_{2}}\right)\right)\right\}$
$=E_{1}\left\{\frac{m_{M}^{2}}{m^{2}} \frac{N_{M}(k-1)}{m_{M}\left(N_{M}-1\right)} F_{Y}^{(2)}\left(t_{y_{2}}\right)\left(1-F_{Y}^{(2)}\left(t_{y_{2}}\right)\right)\right\}$,
$\stackrel{\text { or }}{E_{1}}\left\{w_{M}^{2} V_{2}\left(\hat{F}_{Y}^{(2 r)}\left(t_{y_{2}}\right)-\hat{F}_{Y}^{(2)}\left(t_{y_{2}}\right)\right)\right\}=\frac{W_{M}(k-1)}{m} \frac{N_{M}}{N_{M}-1} F_{Y}^{(2)}\left(t_{y_{2}}\right)\left(1-F_{Y}^{(2)}\left(t_{y_{2}}\right)\right)$.
If we consider $N_{M}-1 \cong N_{M}$, then above expression can be written as

$$
\begin{equation*}
E_{1}\left\{w_{M}^{2} V_{2}\left(\hat{F}_{Y}^{(2 r)}\left(t_{y_{2}}\right)-\hat{F}_{Y}^{(2)}\left(t_{y_{2}}\right)\right)\right\}=\frac{W_{M}(k-1)}{m} F_{Y}^{(2)}\left(t_{y_{2}}\right)\left(1-F_{Y}^{(2)}\left(t_{y_{2}}\right)\right) \tag{3.12}
\end{equation*}
$$

Substituting (3.8) and (3.12) in (3.7), we get

$$
\begin{equation*}
\operatorname{Var}\left\{w_{M}\left(\hat{F}_{Y}^{(2 r)}\left(t_{y_{2}}\right)-\hat{F}_{Y}^{(2)}\left(t_{y_{2}}\right)\right)\right\}=\frac{W_{M}(k-1)}{m} F_{Y}^{(2)}\left(t_{y_{2}}\right)\left(1-F_{Y}^{(2)}\left(t_{y_{2}}\right)\right) \tag{3.13}
\end{equation*}
$$

From (3.6), the covariance term can be written as
$\operatorname{Cov}\left\{\hat{F}_{Y}\left(t_{y}\right), w_{M}\left(\hat{F}_{Y}^{(2 r)}\left(t_{y_{2}}\right)-\hat{F}_{Y}^{(2)}\left(t_{y_{2}}\right)\right)\right\}$
$(3.14)=\left[\begin{array}{c}E_{1} \operatorname{Cov}_{2}\left\{\hat{F_{Y}}\left(t_{y}\right), w_{M}\left(\hat{F}_{Y}^{(2 r)}\left(t_{y_{2}}\right)-\hat{F}_{Y}^{(2)}\left(t_{y_{2}}\right)\right)\right\} \\ +\operatorname{Cov}_{1} E_{2}\left\{\hat{F_{Y}}\left(t_{y}\right), w_{M}\left(\hat{F}_{Y}^{(2 r)}\left(t_{y_{2}}\right)-\hat{F}_{Y}^{(2)}\left(t_{y_{2}}\right)\right)\right\}\end{array}\right]$.

Now considering the term $\operatorname{Cov}_{2}\left\{\hat{F}_{Y}\left(t_{y}\right), w_{M}\left(\hat{F}_{Y}^{(2 r)}\left(t_{y_{2}}\right)-\hat{F}_{Y}^{(2)}\left(t_{y_{2}}\right)\right)\right\}$ on right hand side of (3.14), we get

$$
=\left[\begin{array}{l}
E_{2} \operatorname{Cov}_{3}\left\{\hat{F}_{Y}\left(t_{y}\right), w_{M}\left(\hat{F}_{Y}^{(2 r)}\left(t_{y_{2}}\right)-\hat{F}_{Y}^{(2)}\left(t_{y_{2}}\right)\right)\right\}  \tag{3.15}\\
+\operatorname{Cov}_{2} E_{3}\left\{\hat{F}_{Y}\left(t_{y}\right), w_{M}\left(\hat{F}_{Y}^{(2 r)}\left(t_{y} y_{2}\right)-\hat{F}_{Y}^{(2)}\left(t_{y_{2}}\right)\right)\right\}
\end{array}\right]=0
$$

On similar steps, it can be shown that

$$
\begin{equation*}
\operatorname{Cov}_{1} E_{2}\left\{\hat{F}_{Y}\left(t_{y}\right), w_{M}\left(\hat{F}_{Y}^{(2 r)}\left(t_{y_{2}}\right)-\hat{F}_{Y}^{(2)}\left(t_{y_{2}}\right)\right)\right\}=0 \tag{3.16}
\end{equation*}
$$

Substituting (3.15) and (3.16) in (3.14), we get

$$
\begin{equation*}
\operatorname{Cov}\left\{\hat{F_{Y}}\left(t_{y}\right), w_{M}\left(\hat{F}_{Y}^{(2 r)}\left(t_{y_{2}}\right)-\hat{F}_{Y}^{(2)}\left(t_{y_{2}}\right)\right)\right\}=0 \tag{3.17}
\end{equation*}
$$

Again by using (3.13) and (3.17) in (3.6), we get

$$
\operatorname{Var}\left(\hat{F}_{Y}^{(*)}\left(t_{y}\right)\right)=\left[\begin{array}{l}
\frac{N-m}{m N} F_{Y}\left(t_{y}\right)\left(1-F_{Y}\left(t_{y}\right)\right) \\
+\frac{W_{M}(k-1)}{m} F_{Y}^{(2)}\left(t_{y_{2}}\right)\left(1-F_{Y}^{(2)}\left(t_{y_{2}}\right)\right)
\end{array}\right]
$$

This completes the proof and on the same lines we have

$$
\operatorname{Var}\left(\hat{F}_{X}^{(*)}\left(t_{x}\right)\right)=\left[\begin{array}{l}
\frac{N-m}{m N} F_{X}\left(t_{x}\right)\left(1-F_{X}\left(t_{x}\right)\right) \\
+\frac{W_{M}(k-1)}{m} F_{X}^{(2)}\left(t_{x_{2}}\right)\left(1-F_{X}^{(2)}\left(t_{x_{2}}\right)\right)
\end{array}\right]
$$

Proof (iii). See Appendix A, Page 53.

## 4. Suggested estimators of population distribution function

We suggest the following family of estimators for estimating the population distribution function.
4.1. General family of estimators. A general family of estimators for estimating CDF, is given by

$$
\begin{equation*}
\hat{F}_{M J}\left(t_{y}\right)=\hat{F}_{Y}\left(t_{y}\right)\left[\frac{a F_{X}\left(t_{x}\right)+b}{\delta\left(a \hat{F}_{X}\left(t_{x}\right)+b\right)+(1-\delta)\left(a F_{X}\left(t_{x}\right)+b\right)}\right]^{g} \tag{4.1}
\end{equation*}
$$

where $\delta, g$ are suitably chosen constants and $a(\neq 0), b$ are either real numbers or function of known parameters of the auxiliary variable $X$, such as standard deviation $\left(S_{F_{X}}\left(t_{x}\right)\right)$, co-efficient of variation $\left(C_{F_{X}}\left(t_{x}\right)\right)$, co-efficient of skewness $\left(\beta_{1}\left(F_{X}\left(t_{x}\right)\right)\right.$ ), co-efficient of kurtosis $\left(\beta_{2}\left(F_{X}\left(t_{x}\right)\right)\right)$, and co-efficient of correlation $\left(\rho_{\left(F_{Y}\left(t_{y}\right), F_{X}\left(t_{x}\right)\right.}\right)$.
Expressing (4.1) in terms of $e^{\prime} s$, we have

$$
\hat{F}_{M J}\left(t_{y}\right)=F_{Y}\left(t_{y}\right)\left(1+e_{0}\right)\left(1+\delta \alpha e_{1}\right)^{-g}
$$

where $\alpha=\frac{a F_{X}\left(t_{x}\right)}{a F_{X}\left(t_{x}+b\right)}$.
Expanding the right hand side of the above expression and retaining the terms up to power 2 in $e^{\prime} s$, we have

$$
\begin{equation*}
\hat{F}_{M J}\left(t_{y}\right)=F_{Y}\left(t_{y}\right)\left[1+e_{0}-\delta \alpha g e_{1}+\frac{g(g+1)}{2} \delta^{2} \alpha^{2} e_{1}^{2}-\delta \alpha g e_{0} e_{1}\right] \tag{4.2}
\end{equation*}
$$

4.1.1. Situation $I$ - Non-response both on the study and the auxiliary variables: $\hat{F}_{Y}^{*}\left(t_{y}\right)$, $\hat{F}_{X}^{*}\left(t_{x}\right)$. When non-response occurs on both the study and the auxiliary variables, and population mean $F_{X}\left(t_{x}\right)$ of the auxiliary variable $X$ is known in advance. In agricultural survey, for instance, expenditures of fertilizer or pesticides on crop can be used as the auxiliary variable for the estimation, say, production of crop, there may be non-response on both the variables and for Situation I, Equation (4.1) can be written as,

$$
\begin{equation*}
\hat{F}_{M J}\left(t_{y}\right)=\hat{F}_{Y}^{*}\left(t_{y}\right)\left[\frac{a F_{X}\left(t_{x}\right)+b}{\delta\left(a \hat{F}_{X}^{*}\left(t_{x}\right)+b\right)+(1-\delta)\left(a F_{X}\left(t_{x}\right)+b\right)}\right]^{g} . \tag{4.3}
\end{equation*}
$$

For this, (4.2) can be written as,

$$
\begin{equation*}
\hat{F}_{M J_{i}}^{(1)}\left(t_{y}\right) \cong F_{Y}\left(t_{y}\right)\left[1+e_{0}^{*}-\delta \alpha g e_{1}^{*}+\frac{g(g+1)}{2} \delta^{2} \alpha^{2} e_{1}^{* 2}-\delta \alpha g e_{0}^{*} e_{1}^{*}\right], \tag{4.4}
\end{equation*}
$$

where $\hat{F}_{M J_{i}}^{(1)}\left(t_{y}\right)$ for case of Situation I.
Subtracting $F_{Y}\left(t_{y}\right)$ from both sides of (4.4) and then taking expectation, we get the bias of $\hat{F}_{M J_{i}}^{(1)}\left(t_{y}\right)$ up to first order of approximation, given as

$$
\begin{equation*}
\operatorname{Bias}\left(\hat{F}_{M J_{i}}^{(1)}\left(t_{y}\right)\right) \cong F_{Y}\left(t_{y}\right)\left[\delta^{2} g(g+1) \alpha_{i}^{2} \frac{1}{2} V_{02}^{*}-\delta g \alpha_{i} V_{11}^{*}\right] \tag{4.5}
\end{equation*}
$$

Squaring both sides of (4.4) and then taking expectations, we get the MSE of $\hat{F}_{M J_{i}}^{(1)}\left(t_{y}\right)$, up to first order of approximations, given by

$$
\begin{equation*}
\operatorname{MSE}\left(\hat{F}_{M J_{i}}^{(1)}\left(t_{y}\right)\right) \cong F_{Y}^{2}\left(t_{y}\right)\left[V_{20}^{*}+\delta^{2} g^{2} \alpha_{i}^{2} V_{02}^{*}-2 \delta g \alpha_{i} V_{11}^{*}\right] \tag{4.6}
\end{equation*}
$$

where $\alpha_{i}=\frac{a F_{X}\left(t_{x}\right)}{a F_{X}\left(t_{x}\right)+b}$ for $i=0,1, \ldots, 13$.
Different estimators can be generated from proposed class of estimators by substituting the suitable choices of $(\delta, a, b, g)$. The generated estimators are listed in Table 3. Many more estimators can also be generated from suggested family of estimators by substituting different values of $(\delta, a, b, g)$.
The biases of the suggested family of estimators $\hat{F}_{M J_{i}}^{(1)}\left(t_{y}\right)$ up to the first order of approximations are given below.

$$
\begin{align*}
& \operatorname{Bias}\left(\hat{F}_{M J_{1}}^{(1)}\left(t_{y}\right)\right) \cong F_{Y}\left(t_{y}\right)\left(V_{02}^{*}-V_{11}^{*}\right)  \tag{4.7}\\
& \operatorname{Bias}\left(\hat{F}_{M J_{2}}^{(1)}\left(t_{y}\right)\right) \cong F_{Y}\left(t_{y}\right)\left(V_{11}^{*}\right)  \tag{4.8}\\
& \operatorname{Bias}\left(\hat{F}_{M J_{i}}^{(1)}\left(t_{y}\right)\right) \cong F_{Y}\left(t_{y}\right)\left(\alpha_{i}^{2} V_{02}^{*}-\alpha_{i} V_{11}^{*}\right), \tag{4.9}
\end{align*}
$$

for $i=3,10,12$, and

$$
\begin{equation*}
\operatorname{Bias}\left(\hat{F}_{M J_{i}}^{(1)}\left(t_{y}\right)\right) \cong F_{Y}\left(t_{y}\right)\left(\alpha_{i}^{2} V_{02}^{*}+\alpha_{i} V_{11}^{*}\right) \tag{4.10}
\end{equation*}
$$

for $i=4-9,11,13$.
The MSE of the suggested family of estimators $\left(\hat{F}_{M J_{i}}^{(1)}\left(t_{y}\right)\right)$ up to first order of approximation are given below.

$$
\begin{align*}
& \operatorname{MSE}\left(\hat{F}_{M J_{0}}^{(1)}\left(t_{y}\right)\right) \cong F_{Y}^{2}\left(t_{y}\right) V_{20}^{*}  \tag{4.11}\\
& \operatorname{MSE}\left(\hat{F}_{M J_{1}}^{(1)}\left(t_{y}\right)\right) \cong F_{Y}^{2}\left(t_{y}\right)\left(V_{20}^{*}+V_{02}^{*}-2 V_{11}^{*}\right)  \tag{4.12}\\
& \operatorname{MSE}\left(\hat{F}_{M J_{2}}^{(1)}\left(t_{y}\right)\right) \cong F_{Y}^{2}\left(t_{y}\right)\left(V_{20}^{*}+V_{02}^{*}+2 V_{11}^{*}\right)  \tag{4.13}\\
& \operatorname{MSE}\left(\hat{F}_{M J_{i}}^{(1)}\left(t_{y}\right)\right) \cong F_{Y}^{2}\left(t_{y}\right)\left(V_{20}^{*}+\alpha_{i}^{2} V_{02}^{*}-2 \alpha_{i} V_{11}^{*}\right) \tag{4.14}
\end{align*}
$$

Table 3. Some members of the suggested classes of estimators $\hat{F}_{M J_{i}}^{(1)}\left(t_{y}\right)$

| $\delta$ | $a$ | $b$ | $g$ | Estimator |
| :---: | :---: | :---: | :---: | :---: |
| 0 | 0 | 0 | 0 | $\hat{F}_{M J_{0}}^{(1)}\left(t_{y}\right)=\hat{F}_{Y}^{*}\left(t_{y}\right)$ |
| 1 | 1 | 0 | 1 | $\hat{F}_{M J_{1}}^{(1)}\left(t_{y}\right)=\hat{F}_{Y}^{*}\left(t_{y}\right)\left(\frac{F_{X}\left(t_{x}\right)}{\hat{F}_{X}^{*}\left(t_{x}\right)}\right)$ |
| 1 | 1 | 0 | -1 | $\hat{F}_{M J_{2}}^{(1)}\left(t_{y}\right)=\hat{F}_{Y}^{*}\left(t_{y}\right)\left(\frac{\hat{F}_{X}^{*}\left(t_{x}\right)}{F_{X}\left(t_{x}\right)}\right)$ |
| 1 | 1 | $C_{F_{X}}\left(t_{x}\right)$ | 1 | $\hat{F}_{M J_{3}}^{(1)}\left(t_{y}\right)=\hat{F}_{Y}^{*}\left(t_{y}\right)\left(\frac{F_{X}\left(t_{x}\right)+C_{F_{X}}\left(t_{x}\right)}{\hat{F}_{X}^{*}\left(t_{x}\right)+C_{F_{X}}\left(t_{x}\right)}\right)$ |
| 1 | 1 | $C_{F_{X}}\left(t_{x}\right)$ | -1 | $\hat{F}_{M J_{4}}^{(1)}\left(t_{y}\right)=\hat{F}_{Y}^{*}\left(t_{y}\right)\left(\frac{\hat{F}_{X}^{*}\left(t_{x}\right)+C_{F_{X}}\left(t_{x}\right)}{F_{X}\left(t_{x}\right)+C_{F_{X}}\left(t_{x}\right)}\right)$ |
| 1 | $\beta_{2}\left(F_{X}\left(t_{x}\right)\right)$ | $C_{F_{X}}\left(t_{x}\right)$ | -1 | $\hat{F}_{M J_{5}}^{(1)}\left(t_{y}\right)=\hat{F}_{Y}^{*}\left(t_{y}\right)\left(\frac{\beta_{2}\left(F_{X}\left(t_{x}\right)\right) \hat{F}_{X}^{*}\left(t_{x}\right)+C_{F_{X}}\left(t_{x}\right)}{\beta_{2}\left(F_{X}\left(t_{x}\right)\right) F_{X}\left(t_{x}\right)+C_{F_{X}}\left(t_{x}\right)}\right)$ |
| 1 | $C_{F_{X}}\left(t_{x}\right)$ | $\beta_{2}\left(F_{X}\left(t_{x}\right)\right)$ | -1 | $\hat{F}_{M J_{6}}^{(1)}\left(t_{y}\right)=\hat{F}_{Y}^{*}\left(t_{y}\right)\left(\frac{C_{F_{X}}\left(t_{x}\right) \hat{F}_{X}^{*}\left(t_{x}\right)+\beta_{2}\left(F_{X}\left(t_{x}\right)\right)}{C_{F_{X}}\left(t_{x}\right) F_{X}\left(t_{x}\right)+\beta_{2}\left(F_{X}\left(t_{x}\right)\right)}\right)$ |
| 1 | 1 | $S_{F_{X}}\left(t_{x}\right)$ | -1 | $\hat{F}_{M J_{7}}^{(1)}\left(t_{y}\right)=\hat{F}_{Y}^{*}\left(t_{y}\right)\left(\frac{\hat{F}_{X}^{*}\left(t_{x}\right)+S_{F_{X}}\left(t_{x}\right)}{F_{X}\left(t_{x}\right)+S_{F_{X}}\left(t_{x}\right)}\right)$ |
| 1 | $S_{F_{X}}\left(t_{x}\right)$ | $\beta_{2}\left(F_{X}\left(t_{x}\right)\right)$ | -1 | $\hat{F}_{M J_{8}}^{(1)}\left(t_{y}\right)=\hat{F}_{Y}^{*}\left(t_{y}\right)\left(\frac{S_{F_{X}}\left(t_{x}\right) \hat{F}_{X}^{*}\left(t_{x}\right)+\beta_{2}\left(F_{X}\left(t_{x}\right)\right)}{S_{F_{X}}\left(t_{x}\right) F_{X}\left(t_{x}\right)+\beta_{2}\left(F_{X}\left(t_{x}\right)\right)}\right)$ |
| 1 | $\beta_{2}\left(F_{X}\left(t_{x}\right)\right)$ | $S_{F_{X}}\left(t_{x}\right)$ | -1 | $\hat{F}_{M J_{9}}^{(1)}\left(t_{y}\right)=\hat{F}_{Y}^{*}\left(t_{y}\right)\left(\frac{\beta_{2}\left(F_{X}\left(t_{x}\right)\right) \hat{F}_{X}^{*}\left(t_{x}\right)+S_{F_{X}}\left(t_{x}\right)}{\beta_{2}\left(F_{X}\left(t_{x}\right)\right) F_{X}\left(t_{x}\right)+S_{F_{X}}\left(t_{x}\right)}\right)$ |
| 1 | 1 | $\rho_{\left(F_{Y}\left(t_{y}\right), F_{X}\left(t_{x}\right)\right)}$ | 1 | $\hat{F}_{M J_{10}}^{(1)}\left(t_{y}\right)=\hat{F}_{Y}^{*}\left(t_{y}\right)\left(\frac{F_{X}\left(t_{x}\right)+\rho_{\left(F_{Y}\left(t_{y}\right), F_{X}\left(t_{x}\right)\right.}}{\hat{F}_{X}^{*}\left(t_{x}\right)+\rho_{\left(F_{Y}\left(t_{y}\right), F_{X}\left(t_{x}\right)\right)}}\right)$ |
| 1 | 1 | $\rho_{\left(F_{Y}\left(t_{y}\right), F_{X}\left(t_{x}\right)\right)}$ | -1 |  |
| 1 | 1 | $\beta_{2}\left(F_{X}\left(t_{x}\right)\right)$ | 1 | $\hat{F}_{M J_{12}}^{(1)}\left(t_{y}\right)=\hat{F}_{Y}^{*}\left(t_{y}\right)\left(\frac{F_{X}\left(t_{x}\right)+\beta_{2}\left(F_{X}\left(t_{x}\right)\right)}{\hat{F}_{X}^{*}\left(t_{x}\right)+\beta_{2}\left(F_{X}\left(t_{x}\right)\right)}\right)$ |
| 1 | 1 | $\beta_{2}\left(F_{X}\left(t_{x}\right)\right)$ | -1 | $\hat{F}_{M J_{13}}^{(1)}\left(t_{y}\right)=\hat{F}_{Y}^{*}\left(t_{y}\right)\left(\frac{\hat{F}_{X}^{*}\left(t_{x}\right)+\beta_{2}\left(F_{x}\left(t_{x}\right)\right)}{F_{X}\left(t_{x}\right)+\beta_{2}\left(F_{X}\left(t_{x}\right)\right)}\right)$ |

for $i=3,10,12 .$, and
(4.15) $\operatorname{MSE}\left(\hat{F}_{M J_{i}}^{(1)}\left(t_{y}\right)\right) \cong F_{Y}^{2}\left(t_{y}\right)\left(V_{20}^{*}+\alpha_{i}^{2} V_{02}^{*}+2 \alpha_{i} V_{11}^{*}\right)$,
for $i=4-9,11,13$.
Also here,
$\alpha_{1}=0, \alpha_{2}=\alpha_{3}=1, \alpha_{3}=\alpha_{4}=\frac{F_{X}\left(t_{x}\right)}{F_{X}\left(t_{x}\right)+C_{F_{X}}}, \alpha_{5}=\frac{\beta_{2}\left(F_{X}\left(t_{x}\right)\right) F_{X}\left(t_{x}\right)}{\beta_{2}\left(F_{X}\left(t_{x}\right)\right) F_{X}\left(t_{x}\right)+C_{F_{X}}}$,
$\alpha_{6}=\frac{C_{F_{X}} F_{X}\left(t_{x}\right)}{C_{F_{X}} F_{X}\left(t_{x}\right)+C_{F_{X}}}, \alpha_{7},=\frac{F_{X}\left(t_{x}\right)}{F_{X}\left(t_{x}\right)+S_{F_{X}}}, \alpha_{8}=\frac{S_{F_{X}} F_{X}\left(t_{x}\right)}{S_{F_{X}} F_{X}\left(t_{x}\right)+\beta_{2}\left(F_{X}\left(t_{x}\right)\right)}$,
$\alpha_{9}=\frac{\beta_{2}\left(F_{X}\left(t_{x}\right)\right) F_{X}\left(t_{x}\right)}{\beta_{2}\left(F_{X}\left(t_{x}\right)\right) F_{X}\left(t_{x}\right)+S_{F_{X}}}, \alpha_{(10,11)}=\frac{F_{X}\left(t_{x}\right)}{F_{X}\left(t_{x}\right)+\rho_{\left(F_{Y}\left(t_{y}\right), F_{X}\left(t_{x}\right)\right)}}$,
$\alpha_{(12,13)}=\frac{F_{X}\left(t_{x}\right)}{F_{X}\left(t_{x}\right)+\beta_{2}\left(F_{X}\left(t_{x}\right)\right)}$.
4.1.2. Situation II - Non-response only on the study variable: $\hat{F}_{Y}^{*}\left(t_{y}\right)$. When non-response occurs only on the study variable, information on the auxiliary variable $X$ is obtained from all sampled units and population mean $F_{X}\left(t_{x}\right)$ of the auxiliary variable $X$ is known. In household survey, for example, by using the household size as the auxiliary variable for the estimation of family expenditures. Information can be obtained completely on family size, while there may be non-response on household expenditure. For Situation II, (4.1) can be written as

$$
\begin{equation*}
\hat{F}_{M J_{i}}^{(2)}\left(t_{y}\right)=\hat{F}_{Y}^{*}\left(t_{y}\right)\left[\frac{a F_{X}\left(t_{x}\right)+b}{\delta\left(a \hat{F}_{X}\left(t_{x}\right)+b\right)+(1-\delta)\left(a F_{X}\left(t_{x}\right)+b\right)}\right]^{g} \tag{4.16}
\end{equation*}
$$

Expression (4.16) in terms of $e^{\prime} s$, we have

$$
\begin{equation*}
\hat{F}_{M J_{i}}^{(2)}\left(t_{y}\right) \cong F_{Y}\left(t_{y}\right)\left[1+e_{0}^{*}-\delta \alpha g e_{1}+\frac{g(g+1)}{2} \delta^{2} \alpha^{2} e_{1}^{2}-\delta \alpha g e_{0}^{*} e_{1}\right] \tag{4.17}
\end{equation*}
$$

where $\hat{F}_{M J_{i}}^{(2)}\left(t_{y}\right)$, for the case of Situation II.
Different estimators can be generated from suggested family of estimators by substituting the suitable choices of $(\delta, a, b, g)$ and are listed in Table 4.
The biases of the suggested family of estimators $\left(\hat{F}_{M J_{i}}^{(2)}\left(t_{y}\right)\right)$ up to the first order are
Table 4. Some members of the suggested class of estimators $\hat{F}_{M J_{i}}^{(2)}\left(t_{y}\right)$

| $\delta$ | $a$ | $b$ | $g$ | Estimator |
| :---: | :---: | :---: | :---: | :---: |
| 0 | 0 | 0 | 0 | $\hat{F}_{M J_{0}}^{(2)}\left(t_{y}\right)=\hat{F}_{Y}^{*}\left(t_{y}\right)$ |
| 1 | 1 | 0 | 1 | $\hat{F}_{M J_{1}}^{(2)}\left(t_{y}\right)=\hat{F}_{Y}^{*}\left(t_{y}\right)\left(\frac{F_{X}\left(t_{x}\right)}{\hat{F}_{X}\left(t_{x}\right)}\right)$ |
| 1 | 1 | 0 | -1 | $\hat{F}_{M J_{2}}^{(2)}\left(t_{y}\right)=\hat{F}_{Y}^{*}\left(t_{y}\right)\left(\frac{\hat{F}_{X}\left(t_{x}\right)}{F_{X}\left(t_{x}\right)}\right)$ |
| 1 | 1 | $C_{F_{X}}\left(t_{x}\right)$ | 1 | $\hat{F}_{M J_{3}}^{(2)}\left(t_{y}\right)=\hat{F}_{Y}^{*}\left(t_{y}\right)\left(\frac{F_{X}\left(t_{x}\right)+C_{F_{X}}\left(t_{x}\right)}{\hat{F}_{X}\left(t_{x}\right)+C_{F_{X}}\left(t_{x}\right)}\right)$ |
| 1 | 1 | $C_{F_{X}}\left(t_{x}\right)$ | -1 | $\hat{F}_{M J_{4}}^{(2)}\left(t_{y}\right)=\hat{F}_{Y}^{*}\left(t_{y}\right)\left(\frac{\hat{F}_{X}\left(t_{x}\right)+C_{F_{X}}\left(t_{x}\right)}{F_{X}\left(t_{x}\right)+C_{F_{X}}\left(t_{x}\right)}\right)$ |
| 1 | $\beta_{2}\left(F_{X}\left(t_{x}\right)\right)$ | $C_{F_{X}}\left(t_{x}\right)$ | -1 | $\hat{F}_{M J_{5}}^{(2)}\left(t_{y}\right)=\hat{F}_{Y}^{*}\left(t_{y}\right)\left(\frac{\beta_{2}\left(F_{X}\left(t_{x}\right)\right) \hat{F}_{X}\left(t_{x}\right)+C_{F_{X}}\left(t_{x}\right)}{\beta_{2}\left(F_{X}\left(t_{x}\right)\right) F_{X}\left(t_{x}\right)+C_{F_{X}}\left(t_{x}\right)}\right)$ |
| 1 | $C_{F_{X}}\left(t_{x}\right)$ | $\beta_{2}\left(F_{X}\left(t_{x}\right)\right)$ | -1 | $\hat{F}_{M J_{6}}^{(2)}\left(t_{y}\right)=\hat{F}_{Y}^{*}\left(t_{y}\right)\left(\frac{C_{F_{X}}\left(t_{x}\right) \hat{F}_{X}\left(t_{x}\right)+\beta_{2}\left(F_{X}\left(t_{x}\right)\right)}{C_{F_{X}}\left(t_{x}\right) F_{X}\left(t_{x}\right)+\beta_{2}\left(F_{X}\left(t_{x}\right)\right)}\right)$ |
| 1 | 1 | $S_{F_{X}}\left(t_{x}\right)$ | -1 | $\hat{F}_{M J_{7}}^{(2)}\left(t_{y}\right)=\hat{F}_{Y}^{*}\left(t_{y}\right)\left(\frac{\hat{F}_{X}\left(t_{x}\right)+S_{F_{X}}\left(t_{x}\right)}{F_{X}\left(t_{x}\right)+S_{F_{X}}\left(t_{x}\right)}\right)$ |
| 1 | $S_{F_{X}}\left(t_{x}\right)$ | $\beta_{2}\left(F_{X}\left(t_{x}\right)\right)$ | -1 | $\hat{F}_{M J_{8}}^{(2)}\left(t_{y}\right)=\hat{F}_{Y}^{*}\left(t_{y}\right)\left(\frac{S_{F_{X}}\left(t_{x}\right) \hat{F}_{X}\left(t_{x}\right)+\beta_{2}\left(F_{X}\left(t_{x}\right)\right)}{S_{F_{X}}\left(t_{x}\right) F_{X}\left(t_{x}\right)+\beta_{2}\left(F_{X}\left(t_{x}\right)\right)}\right)$ |
| 1 | $\beta_{2}\left(F_{X}\left(t_{x}\right)\right)$ | $S_{F_{X}}\left(t_{x}\right)$ | -1 | $\hat{F}_{M J_{9}}^{(2)}\left(t_{y}\right)=\hat{F}_{Y}^{*}\left(t_{y}\right)\left(\frac{\beta_{2}\left(F_{X}\left(t_{x}\right)\right) \hat{F}_{X}\left(t_{x}\right)+S_{F_{X}}\left(t_{x}\right)}{\beta_{2}\left(F_{X}\left(t_{x}\right)\right) F_{X}\left(t_{x}\right)+S_{F_{X}}\left(t_{x}\right)}\right)$ |
| 1 | 1 | $\rho_{\left(F_{Y}\left(t_{y}\right), F_{X}\left(t_{x}\right)\right)}$ | 1 | $\hat{F}_{M J_{10}}^{(2)}\left(t_{y}\right)=\hat{F}_{Y}^{*}\left(t_{y}\right)\left(\frac{F_{X}\left(t_{x}\right)+\rho_{\left(F_{Y}\left(t_{y}\right), F_{X}\left(t_{x}\right)\right.}}{\hat{F}_{X}\left(t_{x}\right)+\rho_{\left(F_{Y}\left(t_{y}\right), F_{X}\left(t_{x}\right)\right)}}\right)$ |
| 1 | 1 | $\rho_{\left(F_{Y}\left(t_{y}\right), F_{X}\left(t_{x}\right)\right)}$ | -1 |  |
| 1 | 1 | $\beta_{2}\left(F_{X}\left(t_{x}\right)\right)$ | 1 | $\hat{F}_{M J_{12}}^{(2)}\left(t_{y}\right)=\hat{F}_{Y}^{*}\left(t_{y}\right)\left(\frac{F_{X}\left(t_{x}\right)+\beta_{2}\left(F_{X}\left(t_{x}\right)\right)}{\hat{F}_{X}\left(t_{x}\right)+\beta_{2}\left(F_{X}\left(t_{x}\right)\right)}\right)$ |
| 1 | 1 | $\beta_{2}\left(F_{X}\left(t_{x}\right)\right)$ | -1 | $\hat{F}_{M J_{13}}^{(2)}\left(t_{y}\right)=\hat{F}_{Y}^{*}\left(t_{y}\right)\left(\frac{\hat{F}_{X}\left(t_{x}\right)+\beta_{2}\left(F_{x}\left(t_{x}\right)\right)}{F_{X}\left(t_{x}\right)+\beta_{2}\left(F_{X}\left(t_{x}\right)\right)}\right)$ |

given below.

$$
\begin{align*}
& \operatorname{Bias}\left(\hat{F}_{M J_{1}}^{(2)}\left(t_{y}\right)\right) \cong F_{Y}\left(t_{y}\right)\left(V_{02}-V_{11}^{*^{\prime}}\right)  \tag{4.18}\\
& \operatorname{Bias}\left(\hat{F}_{M J_{2}}^{(2)}\left(t_{y}\right)\right) \cong F_{Y}\left(t_{y}\right)\left(V_{11}^{*^{\prime}}\right)  \tag{4.19}\\
& \operatorname{Bias}\left(\hat{F}_{M J_{i}}^{(2)}\left(t_{y}\right)\right) \cong F_{Y}\left(t_{y}\right)\left[\alpha_{i}\left(\alpha_{i} V_{02}-V_{11}^{*^{\prime}}\right)\right], \tag{4.20}
\end{align*}
$$

for $i=3,10,12$, and

$$
\begin{equation*}
\operatorname{Bias}\left(\hat{F}_{M J_{i}}^{(2)}\left(t_{y}\right)\right) \cong F_{Y}\left(t_{y}\right)\left[\alpha_{i}\left(\alpha_{i} V_{02}+V_{11}^{*^{\prime}}\right)\right] \tag{4.21}
\end{equation*}
$$

for $i=4-9,11,13$.
The $M S E$ of the suggested family of estimators $\hat{F}_{M J_{i}}^{(2)}\left(t_{y}\right)$ up to the first order are given below,

$$
\begin{equation*}
\operatorname{MSE}\left(\hat{F}_{M J_{0}}^{(2)}\left(t_{y}\right)\right) \cong F_{Y}^{2}\left(t_{y}\right) V_{20}^{*} \tag{4.22}
\end{equation*}
$$

$$
\begin{align*}
& M S E\left(\hat{F}_{M J_{1}}^{(2)}\left(t_{y}\right)\right) \cong F_{Y}^{2}\left(t_{y}\right)\left(V_{20}^{*}+V_{02}-2 V_{11}^{*^{\prime}}\right)  \tag{4.23}\\
& \operatorname{MSE}\left(\hat{F}_{M J_{2}}^{(2)}\left(t_{y}\right)\right) \cong F_{Y}^{2}\left(t_{y}\right)\left(V_{20}^{*}+V_{02}+2 V_{11}^{*^{\prime}}\right)  \tag{4.24}\\
& \operatorname{MSE}\left(\hat{F}_{M J_{i}}^{(2)}\left(t_{y}\right)\right) \cong F_{Y}^{2}\left(t_{y}\right)\left[V_{20}^{*}+\alpha_{i}\left\{\alpha_{i} V_{02}-2 V_{11}^{*^{\prime}}\right\}\right] \tag{4.25}
\end{align*}
$$

for $i=3,10,12$, and
(4.26) $\quad \operatorname{MSE}\left(\hat{F}_{M J_{i}}^{(2)}\left(t_{y}\right)\right) \cong F_{Y}^{2}\left(t_{y}\right)\left[V_{20}^{*}+\alpha_{i}\left\{\alpha_{i} V_{02}+2 V_{11}^{*^{\prime}}\right\}\right]$,
for $i=4-9,11,13$.
4.2. Exponential family of estimators. A general family of exponential estimators for estimating population distribution function is given by

$$
\begin{equation*}
\hat{F}_{R e}\left(t_{y}\right)=\hat{F}_{Y}\left(t_{y}\right) \exp \left[\frac{\left(c F_{X}\left(t_{x}\right)+d\right)-\left(c \hat{F}_{X}\left(t_{x}\right)+d\right)}{\left(c F_{X}\left(t_{x}\right)+d\right)+\left(c \hat{F}_{X}\left(t_{x}\right)+d\right)}\right] \tag{4.27}
\end{equation*}
$$

or

$$
\begin{equation*}
\hat{F}_{R e}\left(t_{y}\right)=\hat{F}_{Y}\left(t_{y}\right) \exp \left[\frac{c\left(F_{X}\left(t_{x}\right)-\hat{F}_{X}\left(t_{x}\right)\right)}{c\left(F_{X}\left(t_{x}\right)+\hat{F}_{X}\left(t_{x}\right)\right)+2 d}\right] \tag{4.28}
\end{equation*}
$$

Expressing (4.28) in terms of $e^{\prime} s$, we have

$$
\begin{equation*}
\hat{F}_{R e}\left(t_{y}\right) \cong F_{Y}\left(t_{y}\right)\left(1+e_{0}\right)\left(1-\frac{1}{2} \psi e_{1}+\frac{3}{8} \psi^{2} e_{1}^{2}\right) \tag{4.29}
\end{equation*}
$$

with $\psi=\frac{c F_{X}\left(t_{x}\right)}{c F_{X}\left(t_{x}\right)+d}$.
Expanding the right hand side of (4.29) and retaining the terms up to the second order of $e^{\prime} s$, we have

$$
\begin{equation*}
\hat{F}_{R e}\left(t_{y}\right) \cong F_{Y}\left(t_{y}\right)\left(1+e_{0}-\frac{1}{2} \psi e_{1}+\frac{3}{8} \psi^{2} e_{1}^{2}-\frac{1}{2} \psi e_{0} e_{1}\right) . \tag{4.30}
\end{equation*}
$$

4.2.1. Situation $I$ - Non-response on both the study and the auxiliary variables: $\hat{F}_{Y}^{*}\left(t_{y}\right)$, $\hat{F}_{X}^{*}\left(t_{x}\right)$. For Situation I, (4.28) can be written as

$$
\begin{equation*}
\hat{F}_{R e}\left(t_{y}\right)=\hat{F}_{Y}^{*}\left(t_{y}\right) \exp \left[\frac{c\left(F_{X}\left(t_{x}\right)-\hat{F}_{X}^{*}\left(t_{x}\right)\right)}{c\left(F_{X}\left(t_{x}\right)+\hat{F}_{X}^{*}\left(t_{x}\right)\right)+2 d}\right] \tag{4.31}
\end{equation*}
$$

and from (4.30), we have

$$
\begin{equation*}
\hat{F}_{R e}^{(1)}\left(t_{y}\right) \cong F_{Y}\left(t_{y}\right)\left(1+e_{0}^{*}-\frac{1}{2} \psi e_{1}^{*}+\frac{3}{8} \psi^{2} e_{1}^{* 2}-\frac{1}{2} \psi e_{0}^{*} e_{1}^{*}\right) \tag{4.32}
\end{equation*}
$$

where $\hat{F}_{R e}^{(1)}\left(t_{y}\right)$ for case of Situation I.
The biases and MSE of the suggested family of estimators $\hat{F}_{R e_{j}}^{(1)}\left(t_{y}\right)$ up to the first order are given below.

$$
\begin{align*}
& \operatorname{Bias}\left(\hat{F}_{R e_{j}}^{(1)}\left(t_{y}\right)\right) \cong F_{Y}\left(t_{y}\right)\left(\frac{3}{8} \psi_{j}^{2} V_{02}^{*}-\frac{1}{2} \psi_{j} V_{11}^{*}\right)  \tag{4.33}\\
& \operatorname{MSE}\left(\hat{F}_{R e_{j}}^{(1)}\left(t_{y}\right)\right) \cong F_{Y}^{2}\left(t_{y}\right)\left(V_{20}^{*}+\frac{1}{4} \psi_{j}^{2} V_{02}^{*}-\psi_{j} V_{11}^{*}\right) \tag{4.34}
\end{align*}
$$

for $(j=1,2, \ldots, 10)$, with
$\psi_{1}=0, \psi_{2}=\frac{F_{X}\left(t_{x}\right)}{F_{X}\left(t_{x}\right)+C_{F_{X}}}, \psi_{3}=\frac{F_{X}\left(t_{x}\right)}{F_{X}\left(t_{x}\right)+\beta_{2}\left(F_{X}\left(t_{x}\right)\right)}, \psi_{4}=\frac{\beta_{2}\left(F_{X}\left(t_{x}\right)\right) F_{X}\left(t_{x}\right)}{\beta_{2}\left(F_{X}\left(t_{x}\right)\right)+C_{F_{x}}}$,

$$
\begin{aligned}
& \psi_{5}=\frac{F_{X}\left(t_{x}\right) C_{F_{X}}}{F_{X}\left(t_{x}\right) \beta_{2}\left(F_{X}\left(t_{x}\right)\right)+C_{F_{X}}}, \psi_{6}=\frac{F_{X}\left(t_{x}\right)}{F_{X}\left(t_{x}\right)+\rho_{\left(F_{Y}\left(t_{y}\right), F_{X}\left(t_{x}\right)\right)}}, \psi_{7}=\frac{F_{X}\left(t_{x}\right)}{F_{X}\left(t_{x}\right)+\rho_{\left(F_{Y}\left(t_{y}\right), F_{X}\left(t_{x}\right)\right)}}, \\
& \psi_{8}=\frac{F_{X}\left(t_{x}\right) \rho_{\left(F_{Y}\left(t_{y}\right), F_{X}\left(t_{x}\right)\right)}^{F_{X}\left(t_{x}\right) \rho_{\left(F_{Y}\left(t_{y}\right), F_{X}\left(t_{x}\right)\right)+C_{F_{X}}}}, \psi_{9}=\frac{\beta_{2}\left(F_{X}\left(t_{x}\right)\right) F_{X}\left(t_{x}\right)}{\beta_{2}\left(t_{x}\right)+C_{F_{x}}}}{F_{X}}, \\
& \psi_{10}=\frac{F_{X}\left(t_{x}\right) \rho_{\left(F_{Y}\left(t_{y}\right), F_{X}\left(t_{x}\right)\right)}^{F_{X}\left(t_{x}\right) \rho_{\left(F_{Y}\left(t_{y}\right), F_{X}\left(t_{x}\right)\right)+\beta_{2}\left(F_{X}\left(t_{x}\right)\right)}}}{} .
\end{aligned}
$$

Different estimators can be generated from suggested family by substituting the suitable choices of $(c, d)$. The generated estimators are in Table 5.

Table 5. Some members of the suggested class of estimators $\hat{F}_{R e_{j}}^{(1)}\left(t_{y}\right)$.

| c | $d$ | Estimator |
| :---: | :---: | :---: |
| 1 | 0 | $\hat{F}_{R e_{1}}^{(1)}\left(t_{y}\right)=\hat{F}_{Y}^{*}\left(t_{y}\right) \exp \left(\frac{\left(F_{X}\left(t_{x}\right)-\hat{F}_{X}^{*}\left(t_{x}\right)\right)}{\left(F_{X}\left(t_{x}\right)+\hat{F}_{X}^{*}\left(t_{x}\right)\right)}\right)$ |
| 1 | $C_{F_{X}}\left(t_{x}\right)$ | $\hat{F}_{R e_{2}}^{(1)}\left(t_{y}\right)=\hat{F}_{Y}^{*}\left(t_{y}\right) \exp \left(\frac{\left(F_{X}(t)-\hat{F}_{X}^{*}\left(t_{x}\right)\right)}{\left(F_{X}\left(t_{x}\right)+\hat{F}_{X}^{*}\left(t_{x}\right)\right)+2 C_{F_{X}}\left(t_{x}\right)}\right)$ |
| 1 | $\beta_{2}\left(F_{X}\left(t_{x}\right)\right)$ | $\hat{F}_{R e_{3}}^{(1)}\left(t_{y}\right)=\hat{F}_{Y}^{*}\left(t_{y}\right) \exp \left(\frac{\left(F_{X}(t)-\hat{F}_{X}^{*}\left(t_{x}\right)\right)}{\left(F_{X}\left(t_{x}\right)+\hat{F}_{X}^{*}\left(t_{x}\right)\right)+2 \beta_{2}\left(F_{X}\left(t_{x}\right)\right)}\right)$ |
| $\beta_{2}\left(F_{X}\left(t_{x}\right)\right)$ | $C_{F_{X}}\left(t_{x}\right)$ | $\hat{F}_{R e_{4}}^{(1)}\left(t_{y}\right)=\hat{F}_{Y}^{*}\left(t_{y}\right) \exp \left(\frac{\beta_{2}\left(F_{X}\left(t_{x}\right)\right)\left(F_{X}\left(t_{x}\right)-\hat{F}_{X}^{*}\left(t_{x}\right)\right)}{\beta_{2}\left(F_{X}\left(t_{x}\right)\right)\left(F_{X}\left(t_{x}\right)+\hat{F}_{X}^{*}\left(t_{x}\right)\right)+2 C_{F_{X}}\left(t_{x}\right)}\right)$ |
| $C_{F_{X}}\left(t_{x}\right)$ | $\beta_{2}\left(F_{X}\left(t_{x}\right)\right)$ | $\hat{F}_{R e_{5}}^{(1)}\left(t_{y}\right)=\hat{F}_{Y}^{*}\left(t_{y}\right) \exp \left(\frac{C_{F_{X}}\left(t_{x}\right)\left(F_{X}\left(t_{x}\right)-\hat{F}_{X}^{*}\left(t_{x}\right)\right)}{C_{F_{X}}\left(t_{x}\right)\left(F_{X}\left(t_{x}\right)+\hat{F}_{X}^{*}\left(t_{x}\right)\right)+2 \beta_{2}\left(F_{X}\left(t_{x}\right)\right)}\right)$ |
| 1 | $\rho_{\left(F_{Y}\left(t_{y}\right), F_{X}\left(t_{x}\right)\right)}$ | $\hat{F}_{R e_{6}}^{(1)}\left(t_{y}\right)=\hat{F}_{Y}^{*}\left(t_{y}\right) \exp \left(\frac{\left(F_{X}\left(t_{x}\right)-\hat{F}_{X}^{*}\left(t_{x}\right)\right)}{\left(F_{X}\left(t_{x}\right)+\hat{F}_{X}^{*}\left(t_{x}\right)\right)+2 \rho_{\left(F_{Y}\left(t_{y}\right), F_{X}\left(t_{x}\right)\right)}}\right)$ |
| $C_{F_{X}}\left(t_{x}\right)$ | $\rho_{\left(F_{Y}\left(t_{y}\right), F_{X}\left(t_{x}\right)\right)}$ | $\hat{F}_{R e_{Y}}^{(1)}\left(t_{y}\right)=\hat{F}_{Y}^{*}\left(t_{y}\right) \exp \left(\frac{C_{F_{X}}\left(t_{x}\right)\left(F_{X}\left(t_{x}\right)-\hat{F}_{X}^{*}\left(t_{x}\right)\right)}{C_{F_{x}}\left(F_{X}\left(t_{x}\right)+\hat{F}_{X}^{*}\left(t_{x}\right)\right)+2 \rho_{\left(F_{Y}\left(t_{y}\right), F_{X}\left(t_{x}\right)\right)}}\right)$ |
| $\rho_{\left(F_{Y}\left(t_{y}\right), F_{X}\left(t_{x}\right)\right)}$ | $C_{F_{X}}\left(t_{x}\right)$ | $\hat{F}_{R e_{8}}^{(1)}\left(t_{y}\right)=\hat{F}_{Y}^{*}\left(t_{y}\right) \exp \left(\frac{\rho_{\left(F_{Y}\left(t_{y}\right), F_{X}\left(t_{x}\right)\right)}\left(F_{X}\left(t_{x}\right)-\hat{F}_{X}^{*}\left(t_{x}\right)\right)}{\rho_{\left(F_{Y}\left(t_{y}\right), F_{X}\left(t_{x}\right)\right)}\left(F_{X}\left(t_{x}\right)+\hat{F}_{X}^{*}\left(t_{x}\right)\right)+2 C_{F_{X}}\left(t_{x}\right)}\right)$ |
| $\beta_{2}\left(F_{X}\left(t_{x}\right)\right)$ | $\rho_{\left(F_{Y}\left(t_{y}\right), F_{X}\left(t_{x}\right)\right)}$ | $\hat{F}_{R e_{9}}^{(1)}\left(t_{y}\right)=\hat{F}_{Y}^{*}\left(t_{y}\right) \exp \left(\frac{\beta_{2}\left(F_{X}\right)\left(F_{X}(t)-\hat{F}_{X}^{*}\left(t_{x}\right)\right)}{\beta_{2}\left(F_{X}\left(t_{x}\right)\right)\left(F_{X}\left(t_{x}\right)+\hat{F}_{X}^{*}\left(t_{x}\right)\right)+2 \rho_{\left(F_{Y}\left(t_{y}\right), F_{X}\left(t_{x}\right)\right)}}\right)$ |
| $\rho_{\left(F_{Y}\left(t_{y}\right), F_{X}\left(t_{x}\right)\right)}$ | $\beta_{2}\left(F_{X}(t)\right.$ | $\hat{F}_{R e_{10}}^{(1)}\left(t_{y}\right)=\hat{F}_{Y}^{*}\left(t_{y}\right) \exp \left(\frac{\rho_{\left(F_{Y}\left(t_{y}\right), F_{X}\left(t_{x}\right)\right.}\left(F_{X}^{*}\left(t_{x}\right)-\hat{F}_{X}\left(t_{x}\right)\right)}{\rho_{\left(F_{Y}\left(t_{y}\right), F_{X}\left(t_{x}\right)\right)}\left(F_{X}\left(t_{x}\right)+\hat{F}_{X}^{*}\left(t_{x}\right)\right)+2 \beta_{2}\left(F_{X}\left(t_{x}\right)\right)}\right)$ |

4.2.2. Situation II - Non-response only on the study variable: $\hat{F}_{Y}^{*}\left(t_{y}\right)$. For Situation II, (4.28) can be written as

$$
\begin{equation*}
\hat{F}_{R e}\left(t_{y}\right)=\hat{F}_{Y}^{*}\left(t_{y}\right) \exp \left[\frac{c\left(F_{X}\left(t_{x}\right)-\hat{F}_{X}\left(t_{x}\right)\right)}{c\left(F_{X}\left(t_{x}\right)+\hat{F}_{X}\left(t_{x}\right)\right)+2 d}\right] \tag{4.35}
\end{equation*}
$$

and from (4.30) we have,

$$
\begin{equation*}
\hat{F}_{R e}^{(2)}\left(t_{y}\right) \cong F_{Y}\left(t_{y}\right)\left\{\left(1+e_{0}^{*}-\frac{1}{2} \psi e_{1}+\frac{3}{8} \psi^{2} e_{1}^{2}-\frac{1}{2} \psi e_{0}^{*} e_{1}\right)\right\} \tag{4.36}
\end{equation*}
$$

where $\hat{F}_{R e}^{(2)}\left(t_{y}\right)$ for case of Situation II.
The biases of the suggested family of estimators $\left(\hat{F}_{R e_{j}}^{(2)}\left(t_{y}\right)\right)$ up to first order are given below.
(4.37) $\operatorname{Bias}\left(\hat{F}_{R e_{j}}^{(2)}(t)\right) \cong F_{Y}\left(t_{y}\right)\left[\psi_{j}\left(\frac{3}{8} \psi_{j} V_{02}-\frac{1}{2} V_{11}^{*^{\prime}}\right)\right]$.

The MSE of the suggested family of estimators $\left(\hat{F}_{R e_{j}}^{(2)}\left(t_{y}\right)\right)$ up to first order are given below.

$$
\begin{equation*}
\operatorname{MSE}\left(\hat{F}_{R e_{j}}^{(2)}(t)\right) \cong F_{Y}^{2}\left(t_{y}\right)\left[V_{20}^{*}+\left(\frac{1}{4} \psi_{j}^{2} V_{02}-\psi_{j} V_{11}^{*^{\prime}}\right)\right] . \tag{4.38}
\end{equation*}
$$

Different estimators can be generated from proposed class of estimators by substituting the suitable choices of $c$, and $d$ are listed in Table 6 .

Table 6. Some members of the suggested class of estimators $\hat{F}_{R e_{j}}^{(2)}\left(t_{y}\right)$.

| c | $d$ | Estimator |
| :---: | :---: | :---: |
| 1 | 0 | $\hat{F}_{R e_{1}}^{(2)}\left(t_{y}\right)=\hat{F}_{Y}^{*}\left(t_{y}\right) \exp \left(\frac{\left(F_{X}\left(t_{x}\right)-\hat{F}_{X}\left(t_{x}\right)\right)}{\left(F_{X}\left(t_{x}\right)+\hat{F}_{X}\left(t_{x}\right)\right)}\right)$ |
| 1 | $C_{F_{X}}\left(t_{x}\right)$ | $\hat{F}_{R e_{2}}^{(2)}\left(t_{y}\right)=\hat{F}_{Y}^{*}\left(t_{y}\right) \exp \left(\frac{\left(F_{X}(t)-\hat{F}_{X}\left(t_{x}\right)\right)}{\left(F_{X}\left(t_{x}\right)+\hat{F}_{X}\left(t_{x}\right)\right)+2 C_{F_{X}}\left(t_{x}\right)}\right)$ |
| 1 | $\beta_{2}\left(F_{X}\left(t_{x}\right)\right)$ | $\hat{F}_{R e_{3}}^{(2)}\left(t_{y}\right)=\hat{F}_{Y}^{*}\left(t_{y}\right) \exp \left(\frac{\left(F_{X}(t)-\hat{F}_{X}\left(t_{x}\right)\right)}{\left(F_{X}\left(t_{x}\right)+\hat{F}_{X}\left(t_{x}\right)\right)+2 \beta_{2}\left(F_{X}\left(t_{x}\right)\right)}\right)$ |
| $\beta_{2}\left(F_{X}\left(t_{x}\right)\right)$ | $C_{F_{X}}\left(t_{x}\right)$ | $\hat{F}_{R e_{4}}^{(2)}\left(t_{y}\right)=\hat{F}_{Y}^{*}\left(t_{y}\right) \exp \left(\frac{\beta_{2}\left(F_{X}(t)\right)\left(F_{X}\left(t_{x}\right)-\hat{F}_{X}\left(t_{x}\right)\right)}{\beta_{2}\left(F_{X}\left(t_{x}\right)\right)\left(F_{X}\left(t_{x}\right)+\hat{F}_{X}\left(t_{x}\right)\right)+2 C_{F_{X}}\left(t_{x}\right)}\right)$ |
| $C_{F_{X}}\left(t_{x}\right)$ | $\beta_{2}\left(F_{X}\left(t_{x}\right)\right)$ | $\hat{F}_{R e_{5}}^{(2)}\left(t_{y}\right)=\hat{F}_{Y}^{*}\left(t_{y}\right) \exp \left(\frac{C_{F_{X}}\left(t_{x}\right)\left(F_{X}\left(t_{x}\right)-\hat{F}_{X}\left(t_{x}\right)\right)}{C_{F_{X}}\left(t_{x}\right)\left(F_{X}\left(t_{x}\right)+\hat{F}_{X}\left(t_{x}\right)\right)+2 \beta_{2}\left(F_{X}\left(t_{x}\right)\right)}\right)$ |
| 1 | $\rho_{\left(F_{Y}\left(t_{y}\right), F_{X}\left(t_{x}\right)\right)}$ | $\hat{F}_{R e_{6}}^{(2)}\left(t_{y}\right)=\hat{F}_{Y}^{*}\left(t_{y}\right) \exp \left(\frac{\left(F_{X}\left(t_{x}\right)-\hat{F}_{X}\left(t_{x}\right)\right)}{\left(F_{X}\left(t_{x}\right)+\hat{F}_{X}\left(t_{x}\right)\right)+2 \rho_{\left(F_{Y}\left(t_{y}\right), F_{X}\left(t_{x}\right)\right)}}\right)$ |
| $C_{F_{X}}\left(t_{x}\right)$ | $\rho_{\left(F_{Y}\left(t_{y}\right), F_{X}\left(t_{x}\right)\right)}$ | $\hat{F}_{R e_{7}}^{(2)}\left(t_{y}\right)=\hat{F}_{Y}^{*}\left(t_{y}\right) \exp \left(\frac{C_{F_{X}}\left(t_{x}\right)\left(F_{X}\left(t_{x}\right)-\hat{F}_{X}\left(t_{x}\right)\right)}{\left.C_{F_{x}}\left(F_{X}\left(t_{x}\right)+\hat{F}_{X}\left(t_{x}\right)\right)+2 \rho_{\left(F_{Y}\left(t_{y}\right), F_{X}\left(t_{x}\right)\right)}\right)}\right.$ |
| $\rho_{\left(F_{Y}\left(t_{y}\right), F_{X}\left(t_{x}\right)\right)}$ | $C_{F_{X}}\left(t_{x}\right)$ | $\hat{F}_{R e_{S}}^{(2)}\left(t_{y}\right)=\hat{F}_{Y}^{*}\left(t_{y}\right) \exp \left(\frac{\rho_{\left(F_{Y}\left(t_{y}\right), F_{X}\left(t_{x}\right)\right)}\left(F_{X}\left(t_{x}\right)-\hat{F}_{X}\left(t_{x}\right)\right.}{\rho_{\left(F_{Y}\left(t_{y}\right), F_{X}\left(t_{x}\right)\right)}\left(F_{X}\left(t_{x}\right)+\hat{F}_{X}\left(t_{x}\right)\right)+2 C_{F_{X}}\left(t_{x}\right)}\right)$ |
| $\beta_{2}\left(F_{X}\left(t_{x}\right)\right)$ | $\rho_{\left(F_{Y}\left(t_{y}\right), F_{X}\left(t_{x}\right)\right)}$ | $\hat{F}_{R e_{9}}^{(2)}\left(t_{y}\right)=\hat{F}_{Y}^{*}\left(t_{y}\right) \exp \left(\frac{\beta_{2}\left(F_{X}\right)\left(F_{X}(t)-\hat{F}_{X}\left(t_{x}\right)\right)}{\beta_{2}\left(F_{X}\left(t_{x}\right)\right)\left(F_{X}\left(t_{x}\right)+\hat{F}_{X}\left(t_{x}\right)\right)+2 \rho_{\left(F_{Y}\left(t_{y}\right), F_{X}\left(t_{x}\right)\right)}}\right)$ |
| $\rho_{\left(F_{Y}\left(t_{y}\right), F_{X}\left(t_{x}\right)\right)}$ | $\beta_{2}\left(F_{X}\left(t_{x}\right)\right.$ | $\hat{F}_{R e_{10}}^{(2)}\left(t_{y}\right)=\hat{F}_{Y}^{*}\left(t_{y}\right) \exp \left(\frac{\rho_{\left(F_{Y}\left(t_{y}\right), F_{X}\left(t_{x}\right)\right)}\left(F_{X}\left(t_{x}\right)-\hat{F}_{X}\left(t_{x}\right)\right)}{\rho_{\left(F_{Y}\left(t_{y}\right), F_{X}\left(t_{x}\right)\right)}\left(F_{X}\left(t_{x}\right)+\hat{F}_{X}\left(t_{x}\right)\right)+2 \beta_{2}\left(F_{X}\left(t_{x}\right)\right)}\right)$ |

## 5. Proposed generalized class of exponential ratio type estimators

We propose a generalized class of exponential ratio type estimators, given by

$$
\begin{equation*}
\hat{F}_{M J P}\left(t_{y}\right)=K_{1}\left(\hat{F}_{M J_{i}}\left(t_{y}\right)\right)+\left(1-K_{1}\right)\left(\hat{F}_{R e_{j}}\left(t_{y}\right)\right), \tag{5.1}
\end{equation*}
$$

for $i=1,2,3, \ldots, 13, j=1,2,3, \ldots, 10$ and $K_{1}$ is suitably chosen constant.
5.1. Situation $I$ - Non-response on both the study and the auxiliary variables: $\hat{F}_{Y}^{*}\left(t_{y}\right), \hat{F}_{X}^{*}\left(t_{x}\right)$. For Situation I, (5.1) can be written as

$$
\begin{equation*}
\hat{F}_{M J P}^{(1)}\left(t_{y}\right)=K_{1}\left(\hat{F}_{M J_{i}}^{(1)}\left(t_{y}\right)\right)+\left(1-K_{1}\right)\left(\hat{F}_{R e_{j}}^{(1)}\left(t_{y}\right)\right), \tag{5.2}
\end{equation*}
$$

where $\hat{F}_{M J P}^{(1)}\left(t_{y}\right), \hat{F}_{M J_{i}}^{(1)}\left(t_{y}\right)$ and $\hat{F}_{M J_{j}}^{(1)}\left(t_{y}\right)$ for the case of Situation I respectively. Expressing (5.2) in terms of $e^{\prime} s$, we have

$$
\hat{F}_{M J P}^{(1)}\left(t_{y}\right) \cong F_{Y}\left(t_{y}\right)\left[\begin{array}{r}
e_{0}^{*}+\left(\frac{1}{2} K_{1}-\frac{1}{2}-\alpha g K_{1}\right) \psi e_{1}^{*}+\frac{1}{2}\left(g+\psi^{2}\right) K_{1} g \alpha^{2} e_{1}^{* 2}  \tag{5.3}\\
+\frac{3}{8}\left(1+K_{1}\right) \psi^{2} e_{1}^{* 2}+\left(\frac{1}{2}+\frac{1}{2} K_{1}-K_{1} \alpha g\right) \psi e_{0}^{*} e_{1}^{*}
\end{array}\right] .
$$

The bias and MSE of $\hat{F}_{M J P}^{(1)}\left(t_{y}\right)$, up to first order of approximation, is given by

$$
\left.\operatorname{Bias}\left(\hat{F}_{M J P}^{(1)}\left(t_{y}\right)\right) \cong F_{Y}\left(t_{y}\right)\left[\begin{array}{r}
\left(\frac{1}{2} \psi-\alpha g \psi\right) V_{11}^{*}  \tag{5.4}\\
+\left(\frac{1}{2} g \alpha^{2}+\frac{1}{2} g^{2} \alpha^{2}-\frac{3}{8}\right) V_{02}^{*}
\end{array}\right\} K_{1}\right] .
$$

and

$$
\operatorname{MSE}\left(\hat{F}_{M J P}^{(1)}\left(t_{y}\right)\right) \cong \frac{F_{Y}^{2}\left(t_{y}\right)}{4}\left[4 V_{20}^{*}+\left\{\begin{array}{r}
4\left(K_{1}-K_{1}^{2}+\alpha g K_{1}^{2}\right) \alpha g \psi^{2}  \tag{5.5}\\
+\left(1-\psi K_{1}\right)^{2}
\end{array}\right\} V_{02}^{*}\right] .
$$

By differentiating (5.5) with respect to $K_{1}$, we get the optimum value as $K_{1}^{(o p t)}=\frac{2 V_{11}^{* 2}-\psi V_{02}^{* 2}}{(2 \alpha g-1) \psi V_{02}^{* 2}}$.
The minimum $M S E$ of $\hat{F}_{M J P}^{(1)}\left(t_{y}\right)$ at optimum value of $K_{1}$, up to first order of approximation is given by

$$
\begin{equation*}
\operatorname{MSE}_{\min }\left(\hat{F}_{M J P}^{(1)}\left(t_{y}\right)\right) \cong F_{Y}^{2}\left(t_{y}\right) V_{20}^{*}\left(1-\rho_{\left(F_{Y}\left(t_{y}\right), F_{X}\left(t_{x}\right)\right)}^{2}\right), \tag{5.6}
\end{equation*}
$$

where $\rho_{\left(F_{Y}\left(t_{y}\right), F_{X}\left(t_{x}\right)\right)}^{2}=\frac{\left(V_{11}^{*}\right)^{2}}{V_{20}^{*} V_{02}^{*}}$.
5.2. Situation II - Non-response only on the study variable: $\hat{F}_{Y}^{*}\left(t_{y}\right)$. For Situation II, (5.1) can be written as,

$$
\begin{equation*}
\hat{F}_{M J P}^{(2)}\left(t_{y}\right)=K_{1}\left(\hat{F}_{M J_{i}}^{(2)}(t)\right)+\left(1-K_{1}\right)\left(\hat{F}_{R e_{j}}^{(2)}(t)\right), \tag{5.7}
\end{equation*}
$$

where $\hat{F}_{M J P}^{(2)}\left(t_{y}\right), \hat{F}_{M J_{i}}^{(2)}\left(t_{y}\right)$ and $\hat{F}_{M J_{j}}^{(2)}\left(t_{y}\right)$ for the case of Situation II.
The bias and minimum MSE up to first order of approximation at optimum value $K_{1}^{(o p t)}=$ $\frac{2\left(V_{11}^{*}\right)^{2}-V_{02}^{2}}{V_{02}^{2}}$ is given by

$$
\begin{align*}
& \text { (5.8) } \quad \operatorname{Bias}\left(\hat{F}_{M J P}^{(2)}\left(t_{y}\right)\right) \cong F_{Y}\left(t_{y}\right)\left[\left(\frac{5}{8} V_{02}-\frac{1}{2} V_{11}^{*^{\prime}}\right) K_{1}^{(o p t)}+\frac{3}{8} V_{02}-V_{11}^{*^{\prime}}\right],  \tag{5.8}\\
& \text { (5.9) } \quad \operatorname{MSE} E_{\min }\left(\hat{F}_{M J P}^{(2)}\left(t_{y}\right)\right) \cong F_{Y}^{2}\left(t_{y}\right) V_{20}^{*}\left(1-\rho_{(2)\left(F_{Y}\left(t_{y}\right), F_{X}\left(t_{x}\right)\right)}^{2}\right),  \tag{5.9}\\
& \text { where } \rho_{(2)\left(F_{Y}\left(t_{y}\right), F_{X}\left(t_{x}\right)\right)}^{2}=\frac{\left(V_{11}^{*_{1}^{\prime}}\right)^{2}}{V_{20} V_{02}} \text { for Situation II. }
\end{align*}
$$

5.2.1. Efficiency comparisons for general family of estimators. In this section, suggested estimators under Situation I are compared in terms of MSEs.
Condition i: By Equation (4.11) and Equation (5.6)

$$
\begin{aligned}
& \operatorname{MSE}\left(\hat{F}_{M J_{0}}^{(1)}\left(t_{y}\right)\right)-M S E_{\min }\left(\hat{F}_{M J P}^{(1)}\left(t_{y}\right)\right)>0, \quad \text { if } \\
& V_{20}^{*} \rho_{\left(F_{Y}\left(t_{y}\right), F_{X}\left(t_{x}\right)\right)}^{2}>0 .
\end{aligned}
$$

Condition ii: By Equations (4.12), (4.14) and Equation (5.6)

$$
\begin{aligned}
\operatorname{MSE}\left(\hat{F}_{M J_{i}}^{(1)}\left(t_{y}\right)\right)-M S E_{\min }\left(\hat{F}_{M J P}^{(1)}\left(t_{y}\right)\right) & >0, \quad \text { for } i=1,3,10,12, \text { if } \\
V_{20}^{*} \rho_{\left(F_{Y}\left(t_{y}\right), F_{X}\left(t_{x}\right)\right)}^{2}+\alpha_{i}\left(\alpha_{i} V_{02}^{*}-2 V_{11}^{*}\right) & >0 .
\end{aligned}
$$

Condition iii: By Equations (4.13), (4.15) and Equation (5.6)

$$
\begin{aligned}
\operatorname{MSE}\left(\hat{F}_{M J_{i}}^{(1)}\left(t_{y}\right)\right)-M S E_{\min }\left(\hat{F}_{M J P}^{(1)}\left(t_{y}\right)\right) & >0, \quad \text { for } i=2,4-9,11,13, \text { if } \\
V_{20}^{*} \rho_{\left(F_{Y}\left(t_{y}\right), F_{X}\left(t_{x}\right)\right)}^{2}+\alpha_{i}\left(\alpha_{i} V_{02}^{*}+2 V_{11}^{*}\right) & >0 .
\end{aligned}
$$

Note that the proposed estimator $\left(\hat{F}_{M J P}^{(1)}\left(t_{y}\right)\right)$ is more efficient than the other suggested estimators
$\left(\hat{F}_{M J_{1}}^{(1)}\left(t_{y}\right)\right), \ldots,\left(\hat{F}_{M J_{13}}^{(1)}\left(t_{y}\right)\right)$, when above conditions are satisfied.
The comparisons of estimators for Situation II are given below.
Condition i: By Equation (4.22) and Equation (5.9)

$$
\begin{aligned}
M S E\left(\hat{F}_{M J_{0}}^{(2)}\left(t_{y}\right)\right)-M S E_{\min }\left(\hat{F}_{M J P}^{(2)}\left(t_{y}\right)\right) & >0, \quad \text { if } \\
V_{20}^{*} \rho_{(2)\left(F_{Y}\left(t_{y}\right), F_{X}\left(t_{x}\right)\right)}^{2} & >0 .
\end{aligned}
$$

Condition ii: By Equations (4.23), (4.25) and Equation (5.9)

$$
\begin{aligned}
& \operatorname{MSE}\left(\hat{F}_{M J_{i}}^{(2)}\left(t_{y}\right)\right)-M S E_{\min }\left(\hat{F}_{M J P}^{(2)}\left(t_{y}\right)\right)>0, \quad \text { for } i=1,3,10,12, \text { if } \\
& V_{20}^{*} \rho_{(2)\left(F_{Y}\left(t_{y}\right), F_{X}\left(t_{x}\right)\right)}^{2}+\alpha_{i}\left(\alpha_{i} V_{02}^{*}-2 V_{11}^{*^{\prime}}\right)>0 .
\end{aligned}
$$

Condition iii: By Equations (4.24), (4.26) and Equation (5.9)

$$
\begin{aligned}
& M S E\left(\hat{F}_{M J_{i}}^{(2)}\left(t_{y}\right)\right)-M S E_{\min }\left(\hat{F}_{M J P}^{(2)}\left(t_{y}\right)\right)>0, \quad \text { for } i=2,4-9,11,13, \text { if } \\
& V_{20}^{*} \rho_{(2)\left(F_{Y}\left(t_{y}\right), F_{X}\left(t_{x}\right)\right)}^{2}+\alpha_{i}\left(\alpha_{i} V_{02}^{*}+2 V_{11}^{*^{\prime}}\right)>0 .
\end{aligned}
$$

Note that the proposed estimator $\left(\hat{F}_{M J P}^{(2)}\left(t_{y}\right)\right)$ is more efficient than the other suggested estimators $\left(\hat{F}_{M J_{1}}^{(2)}\left(t_{y}\right)\right), \ldots,\left(\hat{F}_{M J_{13}}^{(2)}\left(t_{y}\right)\right)$, when above conditions are satisfied.
5.2.2. Efficiency comparisons for exponential family of estimators. In this section, suggested estimators are compared under Situation I in terms of MSEs.
Condition (i- $\mathbf{x}$ ): By Equation (4.11) and Equation (4.34)

$$
\begin{aligned}
& M S E\left(\hat{F}_{M J_{0}}^{(1)}\left(t_{y}\right)\right)-M S E\left(\hat{F}_{R e_{j}}^{(1)}\left(t_{y}\right)\right)>0, \quad \text { for } j=1,2, . ., 10, \text { if } \\
& \left(\frac{1}{4} \psi_{j}^{2} V_{02}^{*}-\psi_{j} V_{11}^{*}\right)>0 .
\end{aligned}
$$

Condition xi: By Equations (4.34) and Equation (5.6)

$$
\begin{aligned}
& \operatorname{MSE}\left(\hat{F}_{R e_{j}}^{(1)}\left(t_{y}\right)\right)-M S E_{\min }\left(\hat{F}_{M J P}^{(1)}\left(t_{y}\right)\right)>0 . \\
& V_{20}^{*} \rho_{\left(F_{Y}\left(t_{y}\right), F_{X}\left(t_{x}\right)\right)}^{2}+\psi_{i}\left(\frac{1}{2} \psi_{i} V_{02}^{*}-V_{11}^{*}\right)>0 .
\end{aligned}
$$

Note that the proposed estimator $\left(\hat{F}_{M J P}^{(1)}\left(t_{y}\right)\right)$ is more efficient than the other suggested estimators
$\left(\hat{F}_{R e_{1}}^{(1)}\left(t_{y}\right)\right), \ldots,\left(\hat{F}_{R e_{10}}^{(1)}\left(t_{y}\right)\right)$, when above conditions are satisfied.

Proposed and existing estimators Under Situation II are compared in terms of MSEs.
Condition (i- $\mathbf{x}$ ): By Equation (4.11) and Equation (4.38)

$$
\begin{aligned}
\operatorname{MSE}\left(\hat{F}_{M J_{0}}^{(2)}\left(t_{y}\right)\right)-M S E\left(\hat{F}_{R e_{j}}^{(2)}\left(t_{y}\right)\right) & >0, \quad \text { for } j=1,2, . ., 10, \text { if } \\
\left(\frac{1}{4} \psi_{j}^{2} V_{02}^{*}-\psi_{j} V_{11}^{*}\right) & >0 .
\end{aligned}
$$

Condition xi: By Equations (4.38) and Equation (5.9)

$$
\begin{aligned}
\operatorname{MSE}\left(\hat{F}_{R e_{j}}^{(2)}\left(t_{y}\right)\right)-M S E_{\min }\left(\hat{F}_{M J P}^{(2)}\left(t_{y}\right)\right) & >0 . \\
V_{20}^{*} \rho_{(2)\left(F_{Y}\left(t_{y}\right), F_{X}\left(t_{x}\right)\right)}^{2}+\psi_{i}\left(\frac{1}{2} \psi_{i} V_{02}^{*}-V_{11}^{*}\right) & >0 .
\end{aligned}
$$

Note that the proposed estimator $\left(\hat{F}_{M J P}^{(2)}\left(t_{y}\right)\right)$ is more efficient than the other suggested estimators $\left(\hat{F}_{R e_{1}}^{(2)}\left(t_{y}\right)\right), \ldots,\left(\hat{F}_{R e_{10}}^{(2)}\left(t_{y}\right)\right)$, when above conditions are satisfied.

## 6. Numerical study

In this section, we consider the following data set for numerical comparisons of suggested estimators considered here.
Population I: Source: Sarndal et al. [32], (P-662)
The CO 120 data is based on 120 countries across five continents.
Let $Y=\mathrm{P}-83,1983$ population (in million) and $X=\mathrm{P}-80,1980$ population (in million). $N=120, m=50, W_{M}=0.25, k=2,3,4, f=0.41667, \lambda_{1}=0.0117, \lambda_{2}=0.0050$, $F_{Y}\left(t_{y}\right)=0.816667, F_{X}\left(t_{x}\right)=0.808333, N_{11}=97, N_{12}=01, N_{21}=00, N_{22}=22$, $\rho_{\left(F_{Y}\left(t_{y}\right), F_{X}\left(t_{x}\right)\right)}=0.9730, C_{F_{Y}\left(t_{y}\right)}=0.47578, C_{F_{X}\left(t_{x}\right)}=0.48889, \beta_{1}\left(F_{X}\left(t_{x}\right)\right)=-1.5667$, $\beta_{2}\left(F_{X}\left(t_{x}\right)\right)=3.454419$. Let $I\left(Y_{i} \leq t_{y}\right)=1$ for $Y \leq 0.816667, I\left(Y_{i} \leq t_{y}\right)=0$ for all $Y>0.816667$ and $I\left(X_{i} \leq t_{x}\right)=1$ for $X \leq 0.808333, I\left(X_{i} \leq t_{x}\right)=0$ for all $X>0.808333$ The non-response rate in the given population is considered to be 25 percent, taken as last 30 units of the population.
$N_{M}=30, F_{Y}^{(2)}\left(t_{y_{2}}\right)=0.66667, F_{X}^{(2)}\left(t_{x_{2}}\right)=0.66667, N_{11}^{(2)}=20, N_{12}^{(2)}=00, N_{21}^{(2)}=00$, $N_{22}^{(2)}=10$.
Let $I\left(Y_{i}^{(2)} \leq t_{y_{2}}\right)=1$ for $Y_{2} \leq 0.66667, I\left(Y_{i}^{(2)} \leq t_{y_{2}}\right)=0$ for all $Y_{2}>0.66667$ and $I\left(X_{i}^{(2)} \leq t_{x_{2}}\right)=1$ for $X_{2} \leq 0.66667, I\left(X_{i}^{(2)} \leq t_{x_{2}}\right)=0$ for all $X_{2}>0.66667$.
Population II: Source: Sarjinder Singh [38], P. 1113
Let $Y=$ Duration of sleep (in minutes) and $X=$ Age of old persons $(\geq 50)$ years.
$N=30, m=12, W_{M}=0.25, k=2, f=0.400, \lambda_{1}=0.020, \lambda_{2}=0.0833, F_{Y}(t)=0.5000$,
$F_{X}(t)=0.5333, N_{11}=02, N_{12}=13, N_{21}=14, N_{22}=01, \rho_{\left(F_{X}, F_{Y}\right)}=-0.80178$,
$C_{F_{Y}(t)}=1.00, C_{F_{X}(t)}=0.9355, \beta_{1}\left(F_{X}(t)\right)=-0.1335, \beta_{2}\left(F_{X}(t)\right)=1.0177$. Let
$I\left(Y_{i} \leq t_{y}\right)=1$ for $Y \leq 0.5000, I\left(Y_{i} \leq t_{y}\right)=0$ for all $Y>0.5000$ and $I\left(X_{i} \leq t_{x}\right)$ $=1$ for $X \leq 0.5333, I\left(X_{i} \leq t_{x}\right)=0$ for all $X>0.5333$
The non-response rate in the given population is considered to be 25 percent, taken as last 08 units of the population.
$N_{M}=08, F_{Y}^{(2)}(t)=0.25, F_{X}^{(2)}(t)=0.875, N_{11}^{(2)}=01, N_{12}^{(2)}=01, N_{21}^{(2)}=06, N_{22}^{(2)}=00$.
We use the following expressions for Percentage Relative Efficiency (PRE).

$$
\mathbf{i}: \operatorname{PRE}\left(\hat{F}_{M J_{0}}^{(\cdot)}\left(t_{y}\right), \hat{F}_{M J_{i}}^{(\cdot)}\left(t_{y}\right)\right)=\frac{\hat{F}_{M J_{0}}^{(\cdot)}\left(t_{y}\right)}{\hat{F}_{M J_{i}}^{(.)}\left(t_{y}\right)} \times 100
$$

$$
\mathbf{i i}: \operatorname{PRE}\left(\hat{F}_{M J_{0}}^{(\cdot)}\left(t_{y}\right), \hat{F}_{R e_{j}}^{(\cdot)}\left(t_{y}\right)\right)=\frac{\hat{F}_{M J_{0}}^{(\cdot)}\left(t_{y}\right)}{\hat{F}_{R e_{j}}^{(.)}\left(t_{y}\right)} \times 100,
$$

where (.) can be replaced by (1) and (2) under Situation I and Situation II respectively. We have computed the Absolute Relative Bias $(A R B)$ for different suggested estimators by using the following expression, given by

$$
A R B^{(\cdot)}=\frac{\left|\operatorname{Bias}\left(\hat{F}_{M J_{i}}^{(\cdot)}\left(t_{y}\right)\right)\right| \quad \text { or } \quad\left|\operatorname{Bias}\left(\hat{F}_{R e_{j}}^{(\cdot)}\left(t_{y}\right)\right)\right|}{\left|F_{Y}\left(t_{y}\right)\right|}
$$

for $i=1,2, \ldots, 13$ and for $j=1,2, . ., 10$.
MSE, PRE and ARB values based on given data set under both Situations I and II are given in Tables 7-14.
Table 7. MSE, PRE and ARB values of $\hat{F}_{M J_{i}}^{(1)}\left(t_{y}\right)$ for different values of $k$ of Population I

|  | $k=2$ |  |  | $k=3$ |  |  | $k=4$ |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | MSE | PRE | ARB | MSE | PRE | ARB | MSE | PRE | ARB |
| Estimator |  |  |  |  |  |  |  |  |  |
| $\hat{F}_{M J_{0}}^{(1)}\left(t_{y}\right)$ | 0.00286 | 100.00 | - | 0.00397 | 100.00 | - | 0.00508 | 100.00 | - |
| $\hat{F}_{M J_{1}}^{(1)}\left(t_{y}\right)$ | 0.00009 | 2906.35 | 0.00002 | 0.00009 | 4031.93 | 0.00003 | 0.00009 | 5155.06 | 0.00005 |
| $\hat{F}_{M J_{2}}^{(1)}\left(t_{y}\right)$ | 0.01157 | 24.68 | 0.00430 | 0.01607 | 24.70 | 0.00598 | 0.02056 | 24.71 | 0.00767 |
| $\hat{F}_{M J_{3}}^{(1)}\left(t_{y}\right)$ | 0.00044 | 651.29 | 0.00102 | 0.00059 | 671.22 | 0.00142 | 0.00074 | 682.97 | 0.00182 |
| $\hat{F}_{M J_{4}}^{(1)}\left(t_{y}\right)$ | 0.00434 | 37.65 | 0.00434 | 0.01054 | 37.65 | 0.00604 | 0.01349 | 37.65 | 0.00773 |
| $\hat{F}_{M J_{5}}^{(1)}\left(t_{y}\right)$ | 0.00990 | 28.87 | 0.00676 | 0.01374 | 28.88 | 0.00940 | 0.01758 | 28.89 | 0.01204 |
| $\hat{F}_{M J_{6}}^{(1)}\left(t_{y}\right)$ | 0.00348 | 82.16 | 0.00049 | 0.00483 | 82.14 | 0.00068 | 0.00618 | 82.13 | 0.00087 |
| $\hat{F}_{M J_{7}}^{(1)}\left(t_{y}\right)$ | 0.00806 | 35.48 | 0.00482 | 0.01112 | 35.48 | 0.00670 | 0.01432 | 35.48 | 0.00858 |
| $\hat{F}_{M J_{8}}^{(1)}\left(t_{y}\right)$ | 0.00336 | 84.93 | 0.00039 | 0.00467 | 84.91 | 0.00055 | 0.00598 | 84.90 | 0.00070 |
| $\hat{F}_{M J_{9}}^{(1)}\left(t_{y}\right)$ | 0.01017 | 28.10 | 0.00705 | 0.01412 | 28.11 | 0.00981 | 0.01807 | 28.12 | 0.01256 |
| $\hat{F}_{M M}^{(1)}{ }_{\text {J }}\left(t_{y}\right)$ | 0.00087 | 329.53 | 0.00107 | 0.00119 | 332.66 | 0.00149 | 0.00153 | 334.45 | 0.00191 |
| $\hat{F}_{M}^{(1)} J_{11}\left(t_{y}\right)$ | 0.00607 | 47.04 | 0.00284 | 0.00844 | 47.03 | 0.00394 | 0.01080 | 47.03 | 0.00505 |
| $\hat{F}_{M M}^{(1)}{ }_{\text {J }}\left(t_{y}\right)$ | 0.00188 | 152.27 | 0.00066 | 0.00260 | 152.48 | 0.00092 | 0.00333 | 152.60 | 0.00118 |
| $\hat{F}_{M}^{(1)} J_{13}\left(t_{y}\right)$ | 0.00405 | 70.51 | 0.00097 | 0.00563 | 70.49 | 0.00135 | 0.00721 | 70.47 | 0.00173 |
| $\hat{F}_{M J P}^{(1)}\left(t_{y}\right)$ | 0.00009 | 3031.09 | 0.00203 | 0.00009 | 4184.14 | 0.00286 | 0.00009 | 5337.46 | 0.00369 |

Table 8. MSE, PRE and ARB values of $\hat{F}_{M J_{i}}^{(2)}\left(t_{y}\right)$ for different values of $k$ Population I

|  | $k=2$ |  |  | $k=3$ |  |  | $k=4$ |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | MSE | PRE | ARB | MSE | PRE | ARB | MSE | PRE | ARB |
| Estimator |  |  |  |  |  |  |  |  |  |
| $\hat{F}_{M}^{(2)}{ }_{0}\left(t_{y}\right)$ | 0.00286 | 100.00 | - | 0.00397 | 100.00 | - | 0.00508 | 100.00 | - |
| $\hat{F}_{M J_{1}}^{(2)}\left(t_{y}\right)$ | 0.00121 | 236.31 | 0.00166 | 0.00232 | 171.04 | 0.00333 | 0.00343 | 148.04 | 0.00500 |
| $\hat{F}_{M J_{2}}^{(2)}\left(t_{y}\right)$ | 0.00820 | 34.87 | 0.00262 | 0.00931 | 42.64 | 0.00261 | 0.01042 | 48.76 | 0.00262 |
| $\hat{F}_{M J_{3}}^{(2)}\left(t_{y}\right)$ | 0.00140 | 206.51 | 0.00003 | 0.00251 | 158.22 | 0.00068 | 0.00362 | 140.35 | 0.00132 |
| $\hat{F}_{M J_{4}}^{(2)}\left(t_{y}\right)$ | 0.00575 | 49.69 | 0.00330 | 0.00686 | 57.84 | 0.00394 | 0.00797 | 63.72 | 0.00459 |
| $\hat{F}_{M J_{5}}^{(2)}\left(t_{y}\right)$ | 0.00717 | 39.79 | 0.00533 | 0.00828 | 47.95 | 0.00653 | 0.00939 | 54.11 | 0.00774 |
| $\hat{F}_{M J_{6}}^{(2)}\left(t_{y}\right)$ | 0.00324 | 88.31 | 0.00031 | 0.00435 | 91.30 | 0.00033 | 0.00546 | 93.07 | 0.00035 |
| $\hat{F}_{M J_{7}}^{(2)}\left(t_{y}\right)$ | 0.00604 | 47.34 | 0.00369 | 0.00715 | 55.53 | 0.00444 | 0.00826 | 61.51 | 0.00516 |
| $\hat{F}_{M J_{8}}^{(2)}\left(t_{y}\right)$ | 0.00317 | 90.24 | 0.00025 | 0.00428 | 92.78 | 0.00026 | 0.00539 | 94.27 | 0.00028 |
| $\hat{F}_{M J_{9}}^{(2)}\left(t_{y}\right)$ | 0.00733 | 38.97 | 0.00558 | 0.00844 | 47.00 | 0.00686 | 0.00956 | 53.11 | 0.00814 |
| $\hat{F}_{M J J_{10}}^{(2)}\left(t_{y}\right)$ | 0.00165 | 172.94 | 0.00031 | 0.00276 | 143.62 | 0.00004 | 0.00387 | 131.11 | 0.00038 |
| $\hat{F}_{M J J_{11}}^{(2)}\left(t_{y}\right)$ | 0.00482 | 59.25 | 0.00207 | 0.00593 | 66.88 | 0.00241 | 0.00704 | 72.11 | 0.00276 |
| $\hat{F}_{M J 12}^{(2)}\left(t_{y}\right)$ | 0.00226 | 126.36 | 0.00034 | 0.00337 | 117.67 | 0.00028 | 0.00448 | 113.29 | 0.00022 |
| $\hat{F}_{M J J 3}^{(2)}\left(t_{y}\right)$ | 0.00359 | 79.68 | 0.00065 | 0.00470 | 84.49 | 0.00071 | 0.00581 | 87.45 | 0.00077 |
| $\hat{F}_{M J P}^{(2)}\left(t_{y}\right)$ | 0.00120 | 237.34 | 0.00121 | 0.000231 | 171.43 | 0.00121 | 0.00343 | 148.26 | 0.00121 |

Table 9. MSE, PRE and ARB values of $\hat{F}_{R e_{j}}^{(1)}\left(t_{y}\right)$ for different values of $k$ Population I

|  | $k=2$ |  |  | $k=3$ |  |  | $k=4$ |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | MSE | PRE | ARB | MSE | PRE | ARB | MSE | PRE | ARB |
| Estimator |  |  |  |  |  |  |  |  |  |
| $\hat{F}_{M}^{(1)}\left(J_{0}\left(t_{y}\right)\right.$ | 0.00286 | 100.00 | - | 0.00397 | 100.00 | - | 0.00508 | 100.00 | - |
| $\hat{F}_{R e_{1}}^{(1)}\left(t_{y}\right)$ | 0.00073 | 389.71 | 0.00048 | 0.00100 | 397.76 | 0.00068 | 0.00128 | 397.67 | 0.00088 |
| $\hat{F}_{R e_{2}}^{(1)}\left(t_{y}\right)$ | 0.00136 | 210.26 | 0.00203 | 0.00188 | 211.01 | 0.00283 | 0.00240 | 211.44 | 0.00363 |
| $\hat{F}_{R e_{3}}^{(1)}\left(t_{y}\right)$ | 0.00234 | 122.10 | 0.00076 | 0.00325 | 122.16 | 0.00105 | 0.00416 | 122.19 | 0.00135 |
| $\hat{F}_{R e_{4}}^{(1)}\left(t_{y}\right)$ | 0.00096 | 299.10 | 0.00245 | 0.00132 | 301.45 | 0.00342 | 0.00167 | 302.79 | 0.00439 |
| $\hat{F}_{R e_{5}}^{(1)}\left(t_{y}\right)$ | 0.00252 | 113.27 | 0.00049 | 0.00350 | 113.30 | 0.00069 | 0.00448 | 113.32 | 0.00088 |
| $\hat{F}_{R e e_{6}}^{(1)}\left(t_{y}\right)$ | 0.00171 | 167.20 | 0.00161 | 0.00237 | 167.52 | 0.00224 | 0.00303 | 167.69 | 0.00287 |
| $\hat{F}_{R e e_{7}}^{(1)}\left(t_{y}\right)$ | 0.00209 | 136.66 | 0.00110 | 0.00290 | 136.78 | 0.00154 | 0.00371 | 136.85 | 0.00197 |
| $\hat{F}_{R e e_{8}}^{(1)}\left(t_{y}\right)$ | 0.00137 | 208.34 | 0.00202 | 0.00190 | 209.06 | 0.00281 | 0.00242 | 209.48 | 0.00361 |
| $\hat{F}_{R e_{9}}^{(1)}\left(t_{y}\right)$ | 0.00114 | 250.78 | 0.00227 | 0.00157 | 252.13 | 0.00317 | 0.00201 | 252.90 | 0.00406 |
| $\hat{F}_{R e 10}^{(1)}\left(t_{y}\right)$ | 0.00235 | 121.54 | 0.00074 | 0.00326 | 121.60 | 0.00103 | 0.00418 | 121.63 | 0.00132 |
| $\hat{F}_{M J P}^{(1)}\left(t_{y}\right)$ | 0.00009 | 3031.09 | 0.00203 | 0.00009 | 4184.14 | 0.00286 | 0.00009 | 5337.46 | 0.00369 |

Table 10. MSE, PRE and ARB values of $\hat{F}_{R e_{j}}^{(2)}\left(t_{y}\right)$ for different values of $k$ Population I

|  | $k=2$ |  |  | $k=3$ |  |  | $k=4$ |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | MSE | PRE | ARB | MSE | PRE | ARB | MSE | PRE | ARB |
| Estimator |  |  |  |  |  |  |  |  |  |
| $\hat{F}_{M J_{0}}^{(2)}\left(t_{y}\right)$ | 0.00286 | 100.00 | - | 0.00397 | 100.00 | - | 0.00508 | 100.00 | - |
| $\hat{F}_{R e_{1}}^{(2)}\left(t_{y}\right)$ | 0.00157 | 181.76 | 0.00027 | 0.00268 | 147.90 | 0.00027 | 0.00379 | 133.88 | 0.00027 |
| $\hat{F}_{R e_{2}}^{(2)}\left(t_{y}\right)$ | 0.00195 | 146.66 | 0. 00283 | 0.00306 | 129.72 | 0. 00283 | 0.00417 | 121.80 | 0. 00283 |
| $\hat{F}_{R e_{3}}^{(2)}\left(t_{y}\right)$ | 0.00254 | 112.37 | 0.00046 | 0.00365 | 108.61 | 0.00046 | 0.00476 | 106.60 | 0.00046 |
| $\hat{F}_{R e_{4}}^{(2)}\left(t_{y}\right)$ | 0.00170 | 167.57 | 0.00148 | 0.00282 | 140.92 | 0.00148 | 0.00393 | 129.34 | 0.00148 |
| $\hat{F}_{R e_{5}}^{(2)}\left(t_{y}\right)$ | 0.00265 | 107.68 | 0.00030 | 0.00376 | 105.41 | 0.00030 | 0.00488 | 104.18 | 0.00030 |
| $\hat{F}_{R e_{6}}^{(2)}\left(t_{y}\right)$ | 0.00216 | 132.30 | 0.00097 | 0.00327 | 121.33 | 0.00097 | 0.00438 | 115.92 | 0.00097 |
| $\hat{F}_{R e_{7}}^{(2)}\left(t_{y}\right)$ | 0.00239 | 119.49 | 0.00067 | 0.00350 | 113.31 | 0.00067 | 0.0046 | 110.10 | 0.00067 |
| $\hat{F}_{R e 8}^{(2)}\left(t_{y}\right)$ | 0.00196 | 146.10 | 0.00122 | 0.00307 | 129.40 | 0.00122 | 0.00418 | 121.58 | 0.00122 |
| $\hat{F}_{R e_{9}}^{(2)}\left(t_{y}\right)$ | 0.00182 | 157.36 | 0.00137 | 0.00293 | 135.59 | 0.00137 | 0.00404 | 125.80 | 0.00137 |
| $\hat{F}_{R e_{10}}^{(2)}\left(t_{y}\right)$ | 0.00255 | 112.08 | 0.00045 | 0.00366 | 108.42 | 0.00045 | 0.00478 | 106.46 | 0.00045 |
| $\underline{\hat{F}_{M J P}^{(2)}\left(t_{y}\right)}$ | 0.00120 | 237.34 | 0.00121 | 0.00231 | 171.43 | 0.00121 | 0.00343 | 148.26 | 0.00121 |

Table 11. Values of MSE, PRE and ARB, of $\hat{F}_{M J_{i}}^{(1)}(t)$ for different values of $k$ of Population II

|  | $k=2$ |  |  | $k=3$ |  |  | $k=4$ |  |  | $k=5$ |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | MSE | PRE | ARB | MSE | PRE | ARB | MSE | PRE | ARB | MSE | PRE | ARB |
| Estimator |  |  |  |  |  |  |  |  |  |  |  |  |
| $\hat{F}_{M}^{(2)} J_{0}(t)$ | 0.01641 | 100.00 | - | 0.02031 | 100.00 | - | 0.02422 | 100.00 | - | 0.02812 | 100.00 | - |
| $\hat{F}_{M J_{1}}^{(2)}(t)$ | 0.05176 | 31.69 | 0.11045 | 0.06133 | 33.12 | 0.13340 | 0.07090 | 34.15 | 0.15635 | 0.08048 | 34.95 | 0.17930 |
| $\hat{F}_{M J_{2}}^{(2)}(t)$ | 0.00693 | 236.58 | 0.04483 | 0.00918 | 221.23 | 0.05215 | 0.01143 | 211.92 | 0.05948 | 0.01367 | 205.66 | 0.06680 |
| $\hat{F}_{M J J_{3}}^{(2)}(t)$ | 0.02625 | 62.50 | 0.02493 | 0.03175 | 63.97 | 0.02964 | 0.03725 | 65.01 | 0.03437 | 0.04275 | 65.79 | 0.03908 |
| $\hat{F}_{M J J_{4}}^{(2)}(t)$ | 0.00997 | 164.48 | 0.00762 | 0.01281 | 158.51 | 0.00822 | 0.01565 | 154.70 | 0.00882 | 0.01850 | 152.06 | 0.00942 |
| $\hat{F}_{M J_{5}}^{(2)}(t)$ | 0.00992 | 165.36 | 0.00761 | 0.01275 | 159.27 | 0.00820 | 0.01558 | 155.40 | 0.00878 | 0.01842 | 152.72 | 0.00936 |
| $\hat{F}_{M J J_{6}}^{(2)}(t)$ | 0.01043 | 157.24 | 0.00764 | 0.01335 | 152.13 | 0.00836 | 0.01627 | 148.85 | 0.00908 | 0.01919 | 146.57 | 0.00980 |
| $\hat{F}_{M J_{7}}^{(2)}(t)$ | 0.00828 | 198.12 | 0.00564 | 0.01083 | 187.57 | 0.00525 | 0.01338 | 181.03 | 0.00487 | 0.01593 | 176.59 | 0.00448 |
| $\hat{F}_{M J_{8}}^{(2)}(t)$ | 0.02049 | 80.05 | 0.00928 | 0.02507 | 81.03 | 0.01093 | 0.02964 | 81.71 | 0.01258 | 0.03421 | 82.21 | 0.01424 |
| $\hat{F}_{M}^{(2)}{ }_{\text {d }}{ }^{(2)}(t)$ | 0.00824 | 199.07 | 0.00554 | 0.01078 | 188.37 | 0.00511 | 0.01332 | 181.75 | 0.00469 | 0.01587 | 177.26 | 0.00426 |
| $\hat{F}_{M J J_{10}}^{(2)}(t)$ | 0.02295 | 71.49 | 0.00654 | 0.02748 | 73.91 | 0.006769 | 0.03202 | 75.64 | 0.00732 | 0.03655 | 76.94 | 0.00881 |
| $\hat{F}_{M J J_{11}}^{(2)}(t)$ | 0.02503 | 65.55 | 0.007208 | 0.03049 | 66.610 | 0.00749 | 0.0.599 | 67.29 | 0.00821 | 0.04080 | 68.92 | 0.00881 |
| $\hat{F}_{M J 12}^{(2)}(t)$ | 0.02564 | 63.98 | 0.02317 | 0.03104 | 65.43 | 0.02754 | 0.03645 | 66.45 | 0.03190 | 0.04185 | 67.20 | 0.03626 |
| $\hat{F}_{M J J_{13}}^{(2)}(t)$ | 0.01023 | 160.38 | 0.00765 | 0.01311 | 154.90 | 0.00832 | 0.01600 | 151.39 | 0.00900 | 0.01888 | 148.96 | 0.00967 |
| $\hat{F}_{M J P}^{(2)}(t)$ | 0.00670 | 244.80 | 0.08538 | 0.00893 | 227.25 | 0.09956 | 0.01117 | 216.75 | 0.11374 | 0.01341 | 209.76 | 0.12792 |

Table 12. Values of MSE, PRE and ARB, of $\hat{F}_{M J_{i}}^{(2)}(t)$ for different values of $k$ of Population II

|  | $k=2$ |  |  | $k=3$ |  |  | $k=4$ |  |  | $k=5$ |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | MSE | PRE | ARB | MSE | PRE | ARB | MSE | PRE | ARB | MSE | PRE | ARB |
| Estimator |  |  |  |  |  |  |  |  |  |  |  |  |
| $\hat{F}_{M J_{0}}^{(1)}(t)$ | 0.01641 | 100.00 | - | 0.02031 | 100.00 | - | 0.02422 | 100.00 | - | 0.02812 | 100.00 | - |
| $\hat{F}_{M J_{1}}^{(1)}(t)$ | 0.04610 | 35.59 | 0. 10313 | 0.05000 | 40.62 | 0.11875 | 0.05391 | 44.92 | 0.13438 | 0.05781 | 48.65 | 0.15000 |
| $\hat{F}_{M J_{2}}^{(1)}(t)$ | 0.00859 | 190.90 | 0.03750 | 0.01250 | 162.50 | 0.03750 | 0.01641 | 147.62 | 0.03750 | 0.02031 | 138.46 | 0.03750 |
| $\hat{F}_{M J_{3}}^{(1)}(t)$ | 0.02466 | 66.54 | 0.02227 | 0.02856 | 71.11 | 0.02433 | 0.03247 | 74.59 | 0.02639 | 0.03637 | 77.32 | 0.02845 |
| $\hat{F}_{M J_{4}}^{(1)}(t)$ | 0.01104 | 148.61 | 0.00496 | 0.01495 | 135.90 | 0.00290 | 0.01885 | 128.46 | 0.00084 | 0.02276 | 123.58 | 0.00121 |
| $\hat{F}_{M J_{5}}^{(1)}(t)$ | 0.01099 | 149.20 | 0.00492 | 0.01490 | 136.30 | 0.00282 | 0.01881 | 128.76 | 0.00071 | 0.02271 | 123.82 | 0.00140 |
| $\hat{F}_{M J_{6}}^{(1)}(t)$ | 0.01142 | 143.64 | 0.00523 | 0.01533 | 132.52 | 0.00354 | 0.01923 | 125.91 | 0.00185 | 0.02314 | 121.54 | 0.00016 |
| $\hat{F}_{M J^{(1)}}(t)$ | 0.00964 | 170.22 | 0.00186 | 0.01354 | 149.97 | 0.00231 | 0.01745 | 138.78 | 0.00448 | 0.02136 | 131.69 | 0.01065 |
| $\hat{F}_{M J_{8}}^{(1)}(t)$ | 0.01983 | 82.73 | 0.00806 | 0.02374 | 85.57 | 0.00849 | 0.02764 | 87.61 | 0.00893 | 0.03155 | 89.14 | 0.00936 |
| $\hat{F}_{M J_{9}}^{(1)}(t)$ | 0.00960 | 170.79 | 0.00172 | 0.01351 | 150.33 | 0.00252 | 0.01742 | 139.04 | 0.00676 | 0.02132 | 131.89 | 0.01100 |
| $\hat{F}_{M J_{10}(1)}^{(t)}$ | 0.02232 | 73.50 | 0.18444 | 0.02623 | 77.45 | 0.24609 | 0.03013 | 80.37 | 0.30774 | 0.03404 | 82.62 | 0.36939 |
| $\hat{F}_{M J_{11}(1)}^{(1)}$ | 0.02405 | 69.22 | 0.00540 | 0.02934 | 69.22 | 0.00589 | 0.03396 | 71.32 | 0.00601 | $0 . .03806$ | 73.89 | 0.00620 |
| $\hat{F}_{M J_{12}(t)}^{(1)}$ | 0.02415 | 67.94 | 0.02065 | 0.02850 | 72.41 | 0.02250 | 0.03196 | 75.78 | 0.02434 | 0.03586 | 78.42 | 0.02619 |
| $\hat{F}_{M J_{13}(1)}^{(t)}$ | 0.01125 | 145.81 | 0.00514 | 0.01516 | 134.00 | 0.00329 | 0.01906 | 127.03 | 0.00144 | 0.02297 | 122.44 | 0.00040 |
| $\hat{F}_{M J P}^{(1)}(t)$ | 0.00837 | 196.00 | 0.07121 | 0.01228 | 165.45 | 0.07121 | 0.01618 | 149.65 | 0.07121 | 0.02008 | 140.00 | 0.07121 |

Table 13. Values of MSE, PRE and ARB, of $\hat{F}_{R e_{j}}^{(2)}(t)$ for different values of $k$ of Population II

|  | $k=2$ |  |  | $k=3$ |  |  | $k=4$ |  |  | $k=5$ |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | MSE | PRE | ARB | MSE | PRE | ARB | MSE | PRE | ARB | MSE | PRE | ARB |
| Estimator |  |  |  |  |  |  |  |  |  |  |  |  |
| $\hat{F}_{M J 0}^{(2)}(t)$ | 0.01641 | 100.00 | - | 0.02031 | 100.00 | - | 0.02422 | 100.00 | - | 0.02812 | 100 | - |
| $\hat{F}_{R e_{1}}^{(2)}(t)$ | 0.03085 | 53.18 | 0.04182 | 0.03709 | 54.77 | 0.04849 | 0.04332 | 55.90 | 0.05516 | 0.04956 | 56.74 | 0.06183 |
| $\hat{F}_{R e 2}(2)$ | 0.02090 | 78.49 | 0.01000 | 0.02554 | 79.53 | 0.01162 | 0.03018 | 80.26 | 0.01323 | 0.03481 | 80.89 | 0.01484 |
| $\hat{F}_{R e_{3}}^{(2)}(t)$ | 0.02064 | 79.48 | 0.01000 | 0.02524 | 80.49 | 0.01162 | 0.02983 | 81.18 | 0.01323 | 0.03443 | 81.69 | 0.01484 |
| $\hat{F}_{R e_{4}}^{(2)}(t)$ | 0.02096 | 78.28 | 0.01085 | 0.02560 | 79.34 | 0.01260 | 0.03025 | 80.06 | 0.01434 | 0.03489 | 80.60 | 0.01609 |
| $\hat{F}_{R e 5}^{(2)}(t)$ | 0.02056 | 79.81 | 0.00978 | 0.02514 | 80.80 | 0.01135 | 0.02972 | 81.49 | 0.01293 | 0.03430 | 81.89 | 0.01451 |
| $\hat{F}_{R e_{6}}^{(2)}(t)$ | 0.00691 | 237.95 | 0.03207 | 0.00916 | 221.84 | 0.03665 | 0.01140 | 212.43 | 0.04123 | 0.01364 | 206.11 | 0.04581 |
| $\hat{F}_{R e 7}^{(2)}(t)$ | 0.00672 | 243.95 | 0.01575 | 0.00897 | 226.35 | 0.01787 | 0.01122 | 215.81 | 0.01999 | 0.01347 | 208.78 | 0.02211 |
| $\hat{F}_{R e 8}^{(2)}(t)$ | 0.00926 | 177.08 | 0.00511 | 0.01198 | 169.49 | 0.00606 | 0.01470 | 164.71 | 0.00702 | 0.01742 | 161.42 | 0.00797 |
| $\hat{F}_{R, 9}^{(2)}(t)$ | 0.00713 | 230.13 | 0.03826 | 0.00940 | 216.16 | 0.04377 | 0.01166 | 207.62 | 0.04929 | 0.01393 | 201.87 | 0.05480 |
| $\hat{F}_{R e_{10}}^{(2)}(t)$ | 0.00998 | 164.31 | 0.00605 | 0.01283 | 158.36 | 0.00712 | 0.01567 | 154.56 | 0.00820 | 0.01851 | 151.93 | 0.00928 |
| $\hat{F}_{M J P}^{(2)}(t)$ | 0.00670 | 244.80 | 0.08538 | 0.00894 | 227.25 | 0.09056 | 0.01117 | 216.75 | 0.11374 | 0.01341 | 209.76 | 0.12792 |

Table 14. Values of MSE, PRE and ARB, of $\hat{F}_{R e_{j}}^{(1)}(t)$ for different values of $k$ of Population II

|  | $k=2$ |  |  | $k=3$ |  |  | $k=4$ |  |  | $k=5$ |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | MSE | PRE | ARB | MSE | PRE | ARB | MSE | PRE | ARB | MSE | PRE | ARB |
| Estimator |  |  |  |  |  |  |  |  |  |  |  |  |
| $\hat{F}_{M J_{0}}^{(2)}(t)$ | 0.01641 | 100.00 | - | 0.02031 | 100.00 | - | 0.02422 | 100.00 | - | 0.02812 | 100 | - |
| $\hat{F}_{R e_{1}}^{(1)}(t)$ | 0.02852 | 57.53 | 0.03516 | 0.03242 | 62.65 | 0.03516 | 0.03632 | 66.66 | 0.03516 | 0.04023 | 69.90 | 0.03516 |
| $\hat{F}_{R e_{2}}^{(1)}(t)$ | 0.02017 | 81.34 | 0. 00897 | 0.02408 | 84.36 | 0. 00897 | 0.02798 | 86.55 | 0. 00897 | 0.03188 | 88.19 | 0. 00897 |
| $\hat{F}_{R e_{3}}^{(1)}(t)$ | 0.01995 | 82.22 | 0.00839 | 0.02386 | 85.13 | 0.00839 | 0.02776 | 87.22 | 0.00839 | 0.03167 | 88.80 | 0.00839 |
| $\hat{F}_{R e_{4}}^{(1)}(t)$ | 0.02022 | 81.15 | 0.00910 | 0.02412 | 84.20 | 0.00910 | 0.02803 | 86.40 | 0.00910 | 0.03193 | 88.07 | 0.00910 |
| $\hat{F}_{R e_{5}}^{(1)}(t)$ | 0.01988 | 82.52 | 0.00820 | 0.02379 | 85.39 | 0.00820 | 0.02769 | 87.45 | 0.00820 | 0.03160 | 89.00 | 0.00820 |
| $\hat{F}_{R e_{6}}^{(1)}(t)$ | 0.00857 | 191.36 | 0.02750 | 0.01248 | 162.77 | 0.00038 | 0.01638 | 147.80 | 0.00038 | 0.02029 | 138.60 | 0.00038 |
| $\hat{F}_{R e_{7}}^{(1)}(t)$ | 0.00838 | 195.71 | 0.01363 | 0.01229 | 165.28 | 0.02750 | 0.01619 | 149.54 | 0.02750 | 0.02010 | 139.91 | 0.02750 |
| $\hat{F}_{R}^{(1)}(t)$ | 0.01045 | 156.97 | 0.00416 | 0.01436 | 141.47 | 0.00416 | 0.01826 | 132.60 | 0.00416 | 0.004752217 | 126.86 | 0.00416 |
| $\hat{F}_{R e 9}^{(1)}(t)$ | 0.00877 | 187.12 | 0.03274 | 0.01267 | 160.27 | 0.03274 | 0.01658 | 146.07 | 0.03274 | 0.02049 | 137.29 | 0.03274 |
| $\hat{F}_{R e_{10}}^{(1)}(t)$ | 0.01105 | 148.49 | 0.00497 | 0.01495 | 135.82 | 0.00497 | 0.01886 | 128.04 | 0.00497 | 0.02277 | 123.53 | 0.00497 |
| $\hat{F}_{\text {MJP }}^{(1)}(t)$ | 0.00837 | 196.00 | 0.07121 | 0.01228 | 165.45 | 0.07121 | 0.01618 | 149.65 | 0.07121 | 0.02008 | 140.00 | 0.07121 |

Table 15. MSE, PRE and ARB values of $\hat{F}_{R e_{j}}^{(1)}\left(t_{y}\right)$ for different values of $m$ of Population I

|  | $m=50$ |  |  | $m=60$ |  |  | $m=70$ |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | MSE | PRE | ARB | MSE | PRE | ARB | MSE | PRE | ARB |
| Estimator |  |  |  |  |  |  |  |  |  |
| $\hat{F}_{M J_{0}}^{(1)}\left(t_{y}\right)$ | 0.00286 | 100.00 | - | 0.00217 | 100.00 | - | 0.00168 | 100.00 | - |
| $\hat{F}_{R e_{1}}^{(1)}\left(t_{y}\right)$ | 0.00073 | 389.71 | 0.00048 | 0.00055 | 390.80 | 0.00036 | 0.00043 | 392.13 | 0.00028 |
| $\hat{F}_{R e_{2}}^{(1)}\left(t_{y}\right)$ | 0.00136 | 210.26 | 0.00203 | 0.00103 | 210.42 | 0.00154 | 0.00080 | 210.62 | 0.00120 |
| $\hat{F}_{R e_{3}}^{(1)}\left(t_{y}\right)$ | 0.00234 | 122.10 | 0.00076 | 0.00178 | 122.11 | 0.00057 | 0.00138 | 122.13 | 0.00044 |
| $\hat{F}_{R e_{4}}^{(1)}\left(t_{y}\right)$ | 0.00096 | 299.10 | 0.00245 | 0.00072 | 299.61 | 0.00186 | 0.00056 | 300.23 | 0.00145 |
| $\hat{F}_{R e_{5}}^{(1)}\left(t_{y}\right)$ | 0.00252 | 113.27 | 0.00049 | 0.00192 | 113.28 | 0.00038 | 0.00149 | 113.29 | 0.00029 |
| $\hat{F}_{R e_{6}}^{(1)}\left(t_{y}\right)$ | 0.00171 | 167.20 | 0.00161 | 0.00130 | 167.27 | 0.00122 | 0.00101 | 167.35 | 0.00095 |
| $\hat{F}_{R e_{7}}^{(1)}\left(t_{y}\right)$ | 0.00209 | 136.66 | 0.00110 | 0.00159 | 136.69 | 0.00084 | 0.00123 | 136.72 | 0.00065 |
| $\left.\hat{F}_{\text {Res }}(1) t_{y}\right)$ | 0.00137 | 208.34 | 0.00202 | 0.00104 | 208.50 | 0.00173 | 0.00081 | 208.69 | 0.00119 |
| $\hat{F}_{R e_{9}}^{(1)}\left(t_{y}\right)$ | 0.00114 | 250.78 | 0.00227 | 0.00086 | 251.07 | 0.00133 | 0.00067 | 251.43 | 0.00132 |
| $\hat{F}_{R}^{(1)}{ }_{\text {R }}{ }^{(1)}\left(t_{y}\right)$ | 0.00235 | 121.54 | 0.00074 | 0.00179 | 121.55 | 0.00056 | 0.00138 | 121.57 | 0.00044 |
| $\hat{F}_{M J P}^{(1)}\left(t_{y}\right)$ | 0.00009 | 3031.09 | 0.00203 | 0.00007 | 3223.24 | 0.00155 | 0.00005 | 3492.27 | 0.00121 |

Table 16. MSE, PRE and ARB values of $\hat{F}_{R e_{j}}^{(2)}\left(t_{y}\right)$ for different values of $m$ of Population I

|  | $m=50$ |  |  | $m=60$ |  |  | $m=70$ |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | MSE | PRE | ARB | MSE | PRE | ARB | MSE | PRE | ARB |
| Estimator |  |  |  |  |  |  |  |  |  |
| $\hat{F}_{M J_{0}}^{(2)}\left(t_{y}\right)$ | 0.00286 | 100.00 | - | 0.00217 | 100.00 | - | 0.00168 | 100.00 | - |
| $\hat{F}_{R e_{1}}^{(2)}\left(t_{y}\right)$ | 0.00157 | 181.76 | 0.00027 | 0.00125 | 173.14 | 0.00019 | 0.00103 | 163.74 | 0.00014 |
| $\hat{F}_{R e 2}(2)\left(t_{y}\right)$ | 0.00195 | 146.66 | 0. 00203 | 0.00152 | 142.61 | 0. 00154 | 0.00122 | 138.00 | 0. 00120 |
| $\hat{F}_{R e_{3}}^{(2)}\left(t_{y}\right)$ | 0.00254 | 112.37 | 0.00046 | 0.00195 | 111.53 | 0.00033 | 0.00152 | 110.53 | 0.00023 |
| $\left.\hat{F}_{R e 4}(2) t_{y}\right)$ | 0.00170 | 167.57 | 0.00148 | 0.00135 | 160.96 | 0.00105 | 0.00110 | 153.60 | 0.00075 |
| $\hat{F}_{R e_{5}}^{(2)}\left(t_{y}\right)$ | 0.00265 | 107.67 | 0.00030 | 0.00203 | 107.17 | 0.00021 | 0.00158 | 106.57 | 0.00015 |
| $\hat{F}_{R e_{6}}^{(2)}\left(t_{y}\right)$ | 0.00216 | 132.30 | 0.00097 | 0.00167 | 129.75 | 0.00070 | 0.00133 | 126.78 | 0.00050 |
| $\hat{F}_{R e_{7}}^{(2)}\left(t_{y}\right)$ | 0.00239 | 119.49 | 0.00067 | 0.00184 | 118.09 | 0.00048 | 0.00145 | 116.43 | 0.00034 |
| $\hat{F}_{R e s}^{(2)}\left(t_{y}\right)$ | 0.00196 | 146.10 | 0.00122 | 0.00153 | 142.11 | 0.00087 | 0.00122 | 137.56 | 0.00062 |
| $\hat{F}_{R e_{9}}^{(2)}\left(t_{y}\right)$ | 0.00182 | 157.36 | 0.00137 | 0.00143 | 152.05 | 0.00098 | 0.00115 | 146.08 | 0.00070 |
| $\hat{F}_{R e_{10}}^{(2)}\left(t_{y}\right)$ | 0.00255 | 112.08 | 0.00045 | 0.00195 | 111.26 | 0.00032 | 0.00153 | 110.29 | 0.00023 |
| $\hat{F}_{M J P}^{(2)}\left(t_{y}\right)$ | 0.00120 | 237.34 | 0.00121 | 0.00100 | 219.04 | 0.00086 | 0.00084 | 200.32 | 0.00062 |

Table 17. MSE, PRE and ARB values of $\hat{F}_{R e_{j}}^{(1)}\left(t_{y}\right)$ for different values of $W_{M}$ of Population I

|  | $W_{M}=0.25$ |  |  | $W_{M}=0.30$ |  |  | $W_{M}=0.35$ |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | MSE | PRE | ARB | MSE | PRE | ARB | MSE | PRE | ARB |
| Estimator |  |  |  |  |  |  |  |  |  |
| $\hat{F}_{M J_{0}}^{(1)}\left(t_{y}\right)$ | 0.00286 | 100.00 | - | 0.00313 | 100.00 | - | 0.00324 | 100.00 | - |
| $\hat{F}_{R e_{1}}^{(1)}\left(t_{y}\right)$ | 0.00073 | 389.71 | 0.00048 | 0.00080 | 391.27 | 0.00053 | 0.00083 | 391.83 | 0.00055 |
| $\hat{F}_{R e_{2}}^{(1)}\left(t_{y}\right)$ | 0.00136 | 210.26 | 0.00203 | 0.00149 | 210.49 | 0.00223 | 0.00154 | 210.58 | 0.00231 |
| $\hat{F}_{R e_{3}}^{(1)}\left(t_{y}\right)$ | 0.00234 | 122.10 | 0.00076 | 0.00256 | 122.12 | 0.00083 | 0.00265 | 122.13 | 0.00086 |
| $\hat{F}_{R e_{4}}^{(1)}\left(t_{y}\right)$ | 0.00096 | 299.10 | 0.00245 | 0.00104 | 299.83 | 0.00269 | 0.00108 | 300.09 | 0.00278 |
| $\hat{F}_{R e_{5}}^{(1)}\left(t_{y}\right)$ | 0.00252 | 113.27 | 0.00049 | 0.00276 | 113.28 | 0.00054 | 0.00286 | 113.28 | 0.00056 |
| $\hat{F}_{R e_{6}}^{(1)}\left(t_{y}\right)$ | 0.00171 | 167.20 | 0.00161 | 0.00187 | 167.30 | 0.00176 | 0.00194 | 167.34 | 0.00183 |
| $\hat{F}_{R e_{7}}^{(1)}\left(t_{y}\right)$ | 0.00209 | 136.66 | 0.00110 | 0.00229 | 136.70 | 0.00121 | 0.00237 | 136.72 | 0.00125 |
| $\left.\hat{F}_{\text {Res }}(1) t_{y}\right)$ | 0.00137 | 208.34 | 0.00202 | 0.00150 | 208.56 | 0.00221 | 0.00155 | 208.65 | 0.00229 |
| $\hat{F}_{R e_{9}}^{(1)}\left(t_{y}\right)$ | 0.00114 | 250.78 | 0.00227 | 0.00125 | 251.20 | 0.00249 | 0.00129 | 251.35 | 0.00258 |
| $\hat{F}_{R}^{(1)}{ }_{\text {R }}{ }^{(1)}\left(t_{y}\right)$ | 0.00235 | 121.54 | 0.00074 | 0.00258 | 121.56 | 0.00081 | 0.00267 | 121.56 | 0.00084 |
| $\hat{F}_{M J P}^{(1)}\left(t_{y}\right)$ | 0.00009 | 3031.09 | 0.00203 | 0.00009 | 3314.18 | 0.00224 | 0.00009 | 3427.33 | 0.00232 |

Table 18. MSE, PRE and ARB values of $\hat{F}_{R e_{j}}^{(2)}\left(t_{y}\right)$ for different values of $W_{M}$ of Population I

|  | $W_{M}=0.25$ |  |  | $W_{M}=0.30$ |  |  | $W_{M}=0.35$ |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | MSE | PRE | ARB | MSE | PRE | ARB | MSE | PRE | ARB |
| Estimator |  |  |  |  |  |  |  |  |  |
| $\hat{F}_{M J_{0}}^{(2)}\left(t_{y}\right)$ | 0.00286 | 100.00 | - | 0.00313 | 100.00 | - | 0.00324 | 100.00 | - |
| $\hat{F}_{R e_{1}}^{(2)}\left(t_{y}\right)$ | 0.00157 | 181.76 | 0.00027 | 0.00184 | 169.66 | 0.00027 | 0.00196 | 165.68 | 0.00027 |
| $\hat{F}_{R e 2}^{(2)}\left(t_{y}\right)$ | 0.00195 | 146.66 | 0. 00123 | 0.00222 | 140.93 | 0. 00123 | 0.00233 | 138.97 | 0. 00123 |
| $\hat{F}_{R e_{3}}^{(2)}\left(t_{y}\right)$ | 0.00254 | 112.37 | 0.00046 | 0.00282 | 111.17 | 0.00046 | 0.00293 | 110.74 | 0.00046 |
| $\hat{F}_{R e_{4}}^{(2)}\left(t_{y}\right)$ | 0.00170 | 167.57 | 0.00148 | 0.00198 | 158.24 | 0.00148 | 0.00209 | 155.13 | 0.00148 |
| $\hat{F}_{\text {Res }}^{(2)}\left(t_{y}\right)$ | 0.00265 | 107.68 | 0.00030 | 0.00293 | 106.96 | 0.00030 | 0.00304 | 106.70 | 0.00030 |
| $\hat{F}_{R e g}^{(2)}\left(t_{y}\right)$ | 0.00216 | 132.30 | 0.00097 | 0.00243 | 128.67 | 0.00097 | 0.00254 | 127.41 | 0.00097 |
| $\hat{F}_{\text {Re7 }}^{(2)}\left(t_{y}\right)$ | 0.00239 | 119.49 | 0.00067 | 0.00266 | 117.49 | 0.00067 | 0.00278 | 116.79 | 0.00067 |
| $\hat{F}_{\text {Res }}^{(2)}\left(t_{y}\right)$ | 0.00196 | 146.10 | 0.00122 | 0.00223 | 140.45 | 0.00122 | 0.00234 | 138.52 | 0.00122 |
| $\hat{F}_{R e 9}^{(2)}\left(t_{y}\right)$ | 0.00182 | 157.36 | 0.00137 | 0.00209 | 149.86 | 0.00137 | 0.00220 | 147.33 | 0.00137 |
| $\hat{F}_{R e_{10}}^{(2)}(t y)$ | 0.00255 | 112.08 | 0.00045 | 0.00282 | 110.91 | 0.00045 | 0.00293 | 110.50 | 0.00045 |
| $\hat{F}_{M J P}^{(2)}\left(t_{y}\right)$ | 0.00120 | 237.34 | 0.00121 | 0.00148 | 211.94 | 0.00121 | 0.00159 | 204.07 | 0.00121 |

From Tables $7-8$, it is observed that $\operatorname{MSE}\left(\hat{F}_{M J_{i}}^{(2)}\left(t_{y}\right)\right)$ and $\operatorname{MSE}\left(\hat{F}_{M J_{i}}^{(1)}\left(t_{y}\right)\right)$ increases at increasing rate of $(k)$ for the given data set. Percentage Relative Efficiencies of $\left(\hat{F}_{M J_{(i=1-3,5,9,10,12, P)}^{(2)}}\left(t_{y}\right)\right)$ and $\left(\hat{F}_{M J_{(i=2,4-9,11,13)}^{(1)}}\left(t_{y}\right)\right)$ increases by increasing values of $(k)$ and decreases for $\left(\hat{F}_{M J_{(i=6,8,11,13)}(2)}\left(t_{y}\right)\right),\left(\hat{F}_{M J_{(i=1,3,10,12, P)}^{(1)}}^{\left(t_{y}\right)}\right)$, but having same values for $\left(\hat{F}_{M J_{(i=4,7)}}^{(2)}\left(t_{y}\right)\right)$. The PREs of ratio type of estimators having more values in comparison with product type of estimators as there is positive correlation between study and auxiliary variables here, but our proposed estimator $\hat{F}_{M J P}^{(.)}\left(t_{y}\right)$ is more efficient from all other suggested estimators considered here. As for as ARBs of $\hat{F}_{M J_{(i=1-P)}}^{(2)}\left(t_{y}\right)$ and for $\hat{F}_{M J_{(i=1,3-13)}}^{(1)}\left(t_{y}\right)$ increases at increasing rates of inverse sampling rate $(k)$ but having same values for $\hat{F}_{M J_{(i=2, P)}}^{(1)}\left(t_{y}\right)$.

From Tables 9-10, we examined that $\operatorname{MSE}\left(\hat{F}_{M J_{i}}^{(2)}\left(t_{y}\right)\right)$ and $\operatorname{MSE}\left(\hat{F}_{M J_{i}}^{(1)}\left(t_{y}\right)\right)$ increases at increasing rate of $(k)$ for the given data set. By increasing values of $k$ the PREs of $\left(\hat{F}_{R e_{(j=1-P)}^{(2)}}^{\left(t_{y}\right)}\right)$ increases, and decreases for $\left(\hat{F}_{R e_{(j=1-P)}}^{(1)}\left(t_{y}\right)\right)$. The ARBs of
 inverse sampling rates.

From Tables 11-12, we observed that $\operatorname{MSE}\left(\hat{F}_{M J_{i}}^{(1)}\left(t_{y}\right)\right)$ decreases, as compared to $\operatorname{MSE}\left(\hat{F}_{M J_{i}}^{(2)}\left(t_{y}\right)\right)$, at fixed values of $(k)$, and increases, at increasing rate of $(k)$ for Popu-
 increases $(k)$ and decreases for $\left(\hat{F}_{M J_{(i=2,4,7,9,13, P)}^{(1)}}\left(t_{y}\right)\right),\left(\hat{F}_{M J_{(i=2,4-7,9,13, P)}^{(2)}}\left(t_{y}\right)\right)$. Here, efficiencies of product type of estimators having more values as compared to ratio type of estimators because of negative correlation between study and auxiliary variables here, but our proposed estimator $\hat{F}_{M J P}^{(\cdot)}\left(t_{y}\right)$ is more efficient from all suggested estimators.



From Tables $15-16$, we studied that $\operatorname{MSE}\left(\hat{F}_{M J_{i}}^{(2)}\left(t_{y}\right)\right)$ and $\operatorname{MSE}\left(\hat{F}_{M J_{i}}^{(1)}\left(t_{y}\right)\right)$ decreases by increasing values of $(m)$ for the given data set. For increasing the sample size $(m)$, the Percentage Relative Efficiencies of $\left(\hat{F}_{R e_{(j=0-P)}^{(2)}}\left(t_{y}\right)\right)$ increases, and decreases for $\left(\hat{F}_{R e_{(j=0-P)}^{(1)}}\left(t_{y}\right)\right)$. The ARBs decreases under both the situations of $\left(\hat{F}_{R e_{j}}^{(2)}\left(t_{y}\right)\right)$ and $\left(\hat{F}_{R e_{j}}^{(1)}\left(t_{y}\right)\right)$ by increasing the sample size $(m)$ respectively.

From Tables $17-18$, we see that $\operatorname{MSE}\left(\hat{F}_{R e_{j}}^{(1)}\left(t_{y}\right)\right)$ increases, as compared to the $\operatorname{MSE}\left(\hat{F}_{R e_{j}}^{(2)}\left(t_{y}\right)\right)$, at fixed values of $\left(W_{M}\right)$ for given Population, but increases under both the situations at increasing rates of $\left(W_{M}\right)$. PREs of $\left(\hat{F}_{R e_{(j=0-P)}^{(2)}}^{(2)}\left(t_{y}\right)\right)$ increases and decreases for $\left(\hat{F}_{\operatorname{Re}_{(j=0-P)}^{(1)}}\left(t_{y}\right)\right)$ at increasing rates of $\left(W_{M}\right)$. The ARBs of $\left(\hat{F}_{R e_{(j=1-P)}^{(2)}}\left(t_{y}\right)\right)$ increases and having same values for $\left(\hat{F}_{R e_{j}}^{(1)}\left(t_{y}\right)\right)$ at increasing values of $\left(W_{M}\right)$. Overall our proposed class of estimators $\hat{F}_{M J P}^{(.)}\left(t_{y}\right)$ is more efficient than all other suggested estimators considered here.
6.1. Comparison through percentage loss in efficiency. To judge the effect of non-response in simple random sampling, we obtain the percent relative loss in efficiency of proposed estimator $\hat{F}_{R e_{j}}^{(2)}\left(t_{y}\right)$ with respect to the same situation as discussed earlier but without of non-response. For this we modify $\hat{F}_{R e_{j}}^{(1)}\left(t_{y}\right)$ as $\left.\hat{F}_{R e_{j}}{ }^{\prime}{ }^{\prime}\right)\left(t_{y}\right)$ for estimating population distribution function. The $M S E$ of $\hat{F}_{R e_{j}}^{\left({ }^{\prime}\right)}\left(t_{y}\right)$ is given by

$$
\begin{equation*}
\operatorname{MSE}\left(\hat{F}_{R e_{j}}^{\left({ }^{\prime}\right)}\left(t_{y}\right)\right)=F_{Y}^{2}\left(t_{y}\right)\left[V_{20}+\left(\frac{1}{4} \psi_{j}^{2} V_{02}-\psi_{j} V_{11}^{*^{\prime}}\right)\right] . \tag{6.1}
\end{equation*}
$$

The Percentage Relative Loss in Precision (PRLP) of $\hat{F}_{R e_{j}}^{\left({ }^{\prime}\right)}\left(t_{y}\right)$ with respect to $\hat{F}_{M J_{0}}^{(1)}\left(t_{y}\right)$ is given by

$$
\begin{equation*}
\operatorname{PRLP}\left(\hat{F}_{R e_{j}}^{(\prime)}\left(t_{y}\right)\right)=\frac{M S E\left(\hat{F}_{M J_{0}}^{(1)}\left(t_{y}\right)\right)-M S E\left(\hat{F}_{R e_{j}}^{(\prime)}\left(t_{y}\right)\right)}{M S E\left(\hat{F}_{M J_{0}}^{(1)}\left(t_{y}\right)\right)} \times 100 \tag{6.2}
\end{equation*}
$$

Table 19. PRE, PRLP, of $\hat{F}_{R e_{j}}^{(.)}\left(t_{y}\right)$ at different values of $W_{M}, m$ and $k$

| Estimator $\rightarrow$ |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $W_{M}$ | $m$ | $k$ Case |  |  |  |  |  |  |  |  |  |  |  |  |
| 0.25 | 50 | PRE | 100.00 | 389.71 | 210.86 | 122.10 | 299.10 | 113.27 | 167.20 | 136.66 | 208.34 | 250.78 | 121.54 | 3031.09 |
|  |  | PRLP | 38.88 | 83.86 | 70.70 | 49.89 | 79.20 | 46.01 | 63.29 | 55.19 | 70.43 | 75.33 | 49.66 | 96.74 |
|  |  | PRE | 100.00 | 397.76 | 211.01 | 122.16 | 301.45 | 113.30 | 167.52 | 136.78 | 209.06 | 252.13 | 121.60 | 4184.14 |
|  |  | PRLP | 55.99 | 88.38 | 78.90 | 63.92 | 85.02 | 61.12 | 73.57 | 67.73 | 78.71 | 82.24 | 63.75 | 97.66 |
| 0.30 | 60 | PRE | 100.00 | 392.40 | 210.66 | 122.13 | 300.36 | 113.29 | 167.37 | 136.73 | 208.73 | 251.50 | 121.57 | 3553.50 |
|  |  | PRLP | 48.04 | 86.28 | 75.09 | 57.40 | 82.32 | 54.10 | 68.80 | 61.90 | 74.86 | 79.03 | 57.20 | 97.23 |
|  |  | PRE | 100.00 | 397.44 | 211.40 | 122.19 | 302.69 | 113.32 | 167.68 | 136.85 | 209.44 | 252.84 | 121.63 | 5228.86 |
|  |  | PRLP | 64.90 | 90.73 | 83.17 | 71.22 | 88.06 | 68.99 | 78.92 | 74.27 | 83.02 | 85.83 | 71.09 | 98.13 |
| 0.35 | 70 | PRE | 100.00 | 394.33 | 210.95 | 122.16 | 301.25 | 113.30 | 167.49 | 136.77 | 209.00 | 252.01 | 121.59 | 4050.60 |
|  |  | PRLP | 54.52 | 87.99 | 78.20 | 62.72 | 84.53 | 59.83 | 72.69 | 66.66 | 78.00 | 81.64 | 62.55 | 97.58 |
|  |  |  | 100.00 | 399.17 | 211.65 | 122.21 | 303.48 | 113.33 | 167.78 | 136.88 | 209.69 | 253.30 | 121.64 | 6222.85 |
|  |  | PRLP | 70.57 | 92.23 | 85.89 | 75.87 | 89.99 | 74.00 | 82.32 | 78.42 | 85.76 | 88.12 | 75.76 | 98.43 |

From Table 15, it is observed that, if non-response is considered, there is loss in precision. The percent relative loss in precision increases by increasing the values of $k$ and $m$ respectively. It is also observed that for fixed values of $k$ and $m$ with the increasing values of $W_{M}$, PRLP also increase, so more values of $k$ and $m$, taken more loss in precision is to be observed due to presence of non-response.

## 7. Cost of the survey

Following Hansen and Hurwitz [11], for attaining the better precision at minimum cost, we consider here the case, for determining the number of questionnaires to be sent out and the personal interviews to take in follow ups for non-responses to the mail questionnaires. For this, we assume that questionnaires are sent to 30 people, randomly drawn from 120 countries of a given data set. Further assume that 50 percent or 15 respond, and from other 15 which are non-respondents, 10 percent or 3 visited for insuring some representation of the class of non-respondents. An unbiased estimate is given by:

$$
\begin{equation*}
\hat{F}_{X}^{(*)}\left(t_{x}\right)=w_{R} \hat{F}_{X}^{(1)}\left(t_{x}\right)+w_{M} \hat{F}_{X}^{(2 r)}\left(t_{x}\right), \tag{7.1}
\end{equation*}
$$

where $w_{i}=m_{i} / m$ for $i=R, M$.
$N=120=$ Total number of people in population;
$m=30=$ Total mailed out questionnaires;
$\hat{F}_{X}^{(1)}\left(t_{x}\right)=$ The average of people to the mailed out questionnaires;
$m_{R}=15=$ The number of respondents;
$\hat{F}_{X}^{(2 r)}\left(t_{x}\right)=$ The average number of peoples for personal interviewing;
$m_{M}=3=$ Not reply through mailed questionnaires which are personally interviewed.
It is noted that the actual processed sample size would be $15+3=18$. The sample variance of $\hat{F}_{X}^{(*)}(t)$, is given by

$$
V\left(\hat{F}_{X}^{(*)}\left(t_{x}\right)\right)=\left[\begin{array}{l}
\frac{N-\hat{m}}{\hat{m}(N-1)} F_{X}\left(t_{x}\right)\left(1-F_{X}\left(t_{x}\right)\right)  \tag{7.2}\\
+\frac{W_{M}(k-1)}{m} \frac{N_{M}}{N_{M}-1} F_{X}^{(2)}\left(t_{x}\right)\left(1-F_{X}^{(2)}\left(t_{x}\right)\right)
\end{array}\right]
$$

where $F_{X}\left(t_{x}\right)\left(1-F_{X}\left(t_{x}\right)\right)$ is the variance of whole population and $F_{X}^{(2)}\left(t_{x}\right)\left(1-F_{X}^{(2)}\left(t_{x}\right)\right)$ is the variance from not respondents. $N_{M}$ is the number of people in the population having no response; $r$ is personally visited numbers; and $k=\frac{m_{M}}{r}$, $m_{M}$ is the number of non-respondents in the sample. By using Equation (7.2), we can see that there are wide range of different sample sizes which will give us the same reliability and finally we reached at that point the sample size $m$ alone give us the poor indicator for sampling reliability. For example, assume that $F_{X}\left(t_{x}\right)\left(1-F_{X}\left(t_{x}\right)\right)=$ $F_{X}^{(2)}\left(t_{x}\right)\left(1-F_{X}^{(2)}\left(t_{x}\right)\right)$ and that $N$ and $N_{M}$ are so large that is $\frac{N}{N-1}$ and $\frac{N_{M}}{N_{M}-1}$ tends to one. Further assume that the accuracy we required is such that, the average value of ( $\epsilon=$ standard error) would be given by $m=30$ people when $W_{R}=100 \%$. If questionnaires were mailed to a random sample of $m$ people with $W_{R}=100 \%$, the variance of the auxiliary variable $F_{X}\left(t_{x}\right)$ estimated from sample would be

$$
\begin{equation*}
V\left(\hat{F}_{X}^{(*)}\left(t_{x}\right)\right)=\frac{N-m}{m(N-1)} F_{X}\left(t_{x}\right)\left(1-F_{X}\left(t_{x}\right)\right) \tag{7.3}
\end{equation*}
$$

Thus,

$$
\begin{equation*}
\epsilon^{2}=\frac{N-30}{30(N-1)} F_{X}\left(t_{x}\right)\left(1-F_{X}\left(t_{x}\right)\right) . \tag{7.4}
\end{equation*}
$$

By substituting different numerical values at different response rate of mailed returns along with personal interviews in (7.2), we see that, although $m$ which differs in size but
each one will give us same reliability.

Table 20. Some Cost under different sample sizes at $W_{R}=50 \%$ for Situation I.

| $m$ | $m_{R}$ | $m_{M}$ | $r=\frac{m_{M}}{k}$ | Scheduled Tabulated <br> $\left(m_{R}+r\right)$ | Cost $=c_{0} m+c_{1} m_{R}+c_{2} m_{M}$ |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 16 | 8 | 8 | 8 | 16 | $\mathbf{1 0 4 0}$ |
| 20 | 10 | 10 | 5 | 15 | $\mathbf{8 0 0}$ |
| 26 | 13 | 13 | 5 | 18 | $\mathbf{8 9 0}$ |
| 30 | 15 | 15 | 4 | 19 | $\mathbf{8 5 0}$ |
| 40 | 20 | 20 | 4 | 24 | $\mathbf{1 0 0 0}$ |
| 60 | 30 | 30 | 3 | 33 | $\mathbf{1 2 0 0}$ |

Let $c_{0}=$ Rs $5=$ Overhead cost,
$c_{1}=$ Rs $20=$ Cost per unit for responding stratum, and $c_{2}=R_{s} 100,=$ Cost per unit for non-responding stratum. Generally $c_{2}$ having more values than $c_{1}$, as extra effort is required for making contact with non-respondents and obtained responses from them.
From Table 20, Column 5 shows that for different sample sizes $m$ each one give us the same required precision. For instance, sending 20 questionnaires, obtaining ( 10 by mail and 05 by personal interviewing) give us the same ( $\epsilon$ ) as for sending out 60 questionnaires and obtaining a total of 33 questionnaire ( 30 by mail and 03 by visited personally). Therefore at some point it would be at a loss to put extra money for having additional mail returns. Sensibly, it will be better to spend extra effort for those which are nonrespondents. Column 6 gives us the total cost for each of the sample sizes under the unit cost. Since in Table 20, for different schedules tabulated all give us same precision, so logically it will be better for us to choose that particular value of $m$ which would give us minimum cost. Consequently, by sending 20 schedules, 10 of them are returned by mail (at 50 per cent response rate) and 5 are personally interviewed which were nonrespondents.
Now instead of suggested procedure for Table 20, we obtain an optimum number of schedules mailed out and choose personal interviews accordingly, the optimum values of $m$ and $r$ are given by:

$$
\begin{equation*}
m^{(o p t)}=\hat{m}\left\{1+(k-1) W_{M}\right\}, \tag{7.5}
\end{equation*}
$$

and

$$
\begin{equation*}
r=\frac{m_{M}}{k} \tag{7.6}
\end{equation*}
$$

where, $k=\sqrt{\frac{c_{2} W_{R}}{c_{0}+c_{1} W_{R}}}$
and

$$
\begin{equation*}
\hat{m}=\frac{N T_{1}}{(N-1) \epsilon^{2}+T_{1}}, \tag{7.7}
\end{equation*}
$$

where
$T_{1}=F_{Y}\left(t_{y}\right)\left(1-F_{Y}\left(t_{y}\right)\right)+F_{X}\left(t_{x}\right)\left(1-F_{X}\left(t_{x}\right)\right)-2\left(\frac{N_{11} N_{22}-N_{12} N_{21}}{N^{2}}\right)$,
$W_{R}$ is the response rate obtained through mailed questionnaire, $W_{R}=1-W_{M}$. Expressions in (7.5) and (7.6) are obtained under the assumptions that $F_{X}(t)\left(1-F_{X}(t)\right)=$
$F_{X}^{(2)}(t)\left(1-F_{X}^{(2)}(t)\right)$ and $\frac{N}{N-1}=\frac{N_{M}}{N_{M}-1} \cong 1$. But when the above assumption is eliminated the optimum values of $m$ and $r$ are given by

$$
\begin{equation*}
m^{(o p t)}=\hat{m}\left\{1+(k-1) W_{M} \frac{T_{2}}{T_{1}}\right\}, \tag{7.8}
\end{equation*}
$$

where
$T_{2}=F_{Y}^{(2)}\left(t_{y}\right)\left(1-F_{Y}^{(2)}\left(t_{y}\right)\right)+F_{X}^{(2)}\left(t_{x}\right)\left(1-F_{X}^{(2)}\left(t_{x}\right)\right)-2\left(\frac{N_{11}^{(2)} N_{22}^{(2)}-N_{12}^{(2)} N_{21}^{(2)}}{\left(N_{2}^{(2)}\right)^{2}}\right)$.
and

$$
\begin{equation*}
r=\frac{m_{M}}{k} \tag{7.9}
\end{equation*}
$$

where $k=\sqrt{\frac{c_{2} W_{R}}{c_{0}+c_{1} W_{R}}\left\{\frac{(N-m) T_{1}}{N W_{M} T_{2}}-1\right\}}$.
Of course, at different response rate $m_{R}$ and $r$ varies for achieving the specified precision. In practice we do not know what will be the approximate response rate but for estimating optimum values and by using (7.8) and (7.9), there must be an approximate known value of $W_{R}$ in advance.
For the case, when $W_{R}$ is not known in advance, suggesting to design the survey for achieving at least definite specified precision at minimal cost, and parallel to these must know about total cost of the survey. Under such circumstances, it is possible for obtaining optimum values of $m_{R}$ and $k$. For example, instead of using $50 \%$ response rate in Table 20, we compute optimum values of $m_{R}$ and $r$ at different values of $W_{R}(10 \%$ to $90 \%)$ respectively for achieving same precision. The optimum values of Equations (7.5) and (7.6) along with their cost are given in Table 21.

Table 21. Comparison of minimum cost for various response rates of $W_{R}$

| $W_{R}$ | $m$ | $m_{R}$ | $m_{M}$ | $r=\frac{m_{M}}{k}$ | Optimum <br> Cost | Cost of <br> Strategy 1 | Increase <br> in Cost |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 0.10 | 35 | 4 | 31 | 26 | 2855 | 2910 | $\mathbf{0 5 5}$ |
| 0.20 | 42 | 8 | 34 | 23 | 2670 | 2710 | $\mathbf{0 4 0}$ |
| 0.30 | 44 | 13 | 31 | 19 | 2380 | 2430 | $\mathbf{0 5 0}$ |
| 0.40 | 44 | 18 | 26 | 15 | 2080 | 2190 | $\mathbf{1 1 0}$ |
| 0.50 | 42 | 21 | 21 | 12 | 1830 | 1950 | $\mathbf{1 2 0}$ |
| 0.60 | 40 | 24 | 16 | 9 | 1600 | 1710 | $\mathbf{1 1 0}$ |
| 0.70 | 38 | 27 | 11 | 6 | 1330 | 1470 | $\mathbf{1 4 0}$ |
| 0.80 | 35 | 28 | 7 | 4 | 1135 | 1230 | $\mathbf{0 9 5}$ |
| 0.90 | 33 | 30 | 3 | 2 | 965 | 990 | $\mathbf{0 2 5}$ |

Table 21, Column 6 gives us the optimum cost at specified response rate, but for unknown response rate, we give Strategy 1 by sending 30 questionnaires and follow up on all non-respondents whatever the value of $W_{R}$ is. Therefore for specified response rate $W_{R}$, the cost for Strategy 1 will always be more than the optimum cost as shown in Table 21.
It is interesting to note that how costly this strategy is, as compared to the optimum cost method by using different response rates $W_{R}$. The comparison between Column 6 and Column 7 is presented in Column 8 which shows that at smaller response rates give low cost since less questionnaires have been received. For at least $30 \%$ response rate, increase in cost from $09 \%$ to $22 \%$ is to be expected for this strategy.
When an approximate value of $W_{R}$ is not known in advance, the Strategy 2 is preferable as compared to Strategy 1. There are two steps involved in Strategy 2 as:
(i) Determine the maximum number of $m$, whatever the size for $W_{R}$,
(ii) Determine $r$ for achieving the required precision and value of $W_{R}$ is actually determined from the sample results. Hence $r$ will change its value with the actual $W_{R}$;
In Table 21 as there are maximum number (44) questionnaires to be sent out for $W_{R}=$ $40 \%$ then by using formula, $r=\frac{m_{M}}{k}$, we get $r=15$.

Table 22. Comparison between optimum cost for known values of $W_{R}$ and Strategies 1 and 2.

| $W_{R}$ | $m$ | $m_{R}$ | $m_{M}$ | $r=\frac{m M}{k}$ | Cost of <br> Strategy 2 | Cost of <br> Strategy 1 | Optimum <br> cost |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 0.10 | 44 | 4 | 40 | 33 | 3600 | 2910 | $\mathbf{2 8 5 5}$ |
| 0.20 | 44 | 9 | 35 | 23 | 2700 | 2710 | $\mathbf{2 6 7 0}$ |
| 0.30 | 44 | 13 | 31 | 19 | 2380 | 2430 | $\mathbf{2 3 8 0}$ |
| 0.40 | 44 | 18 | 26 | 15 | 2080 | 2190 | $\mathbf{2 0 8 0}$ |
| 0.50 | 44 | 22 | 22 | 12 | 1860 | 1950 | $\mathbf{1 8 3 0}$ |
| 0.60 | 44 | 26 | 18 | 10 | 1740 | 1710 | $\mathbf{1 6 0 0}$ |
| 0.70 | 44 | 31 | 13 | 7 | 1540 | 1470 | $\mathbf{1 3 3 0}$ |
| 0.80 | 44 | 35 | 9 | 5 | 1420 | 1230 | $\mathbf{1 1 3 5}$ |
| 0.90 | 44 | 40 | 4 | 2 | 1220 | 990 | $\mathbf{9 6 5}$ |

Table 22, show the number of mailed questionnaires and number of personal interviewed $r$ at varying values of $W_{R}$ for achieving the required precision, along with their total cost of the survey. The optimum costs are also given at known values of $W_{R}$. Of course at high value of $W_{R}$, the optimum cost of any survey will give us the small values accordingly.
Thus from the above discussions, we conclude that it is not necessarily found that an optimum value of $m$ and $r$ but an optimum procedure (Strategy) is also vital even when we have nothing in hand about values of $W_{R}$ in advance and consequently it will give us in any case at least a precise procedure at slightly low cost.

## 8. Conclusion

In this article, we proposed an improved generalized class of ratio type exponential estimators $\hat{F}_{M J P}^{(\cdot)}\left(t_{y}\right)$. Expressions for bias and MSE of the proposed class of estimators $\hat{F}_{M J P}^{(\cdot)}\left(t_{y}\right)$ are compared with two suggested families of estimators theoretically and numerically under Situations I and II. From Tables $7-15$, it is observed that proposed class of estimators $\hat{F}_{M J P}^{(.)}\left(t_{y}\right)$ is preferable in both the Situations and is recommended for precise estimation for population distribution function in the presence of non-response.

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## Appendix A

For finding the $\operatorname{Cov}\left(\hat{F}_{Y}^{(*)}\left(t_{y}\right), \hat{F}_{X}^{(*)}\left(t_{x}\right)\right)$, we have

$$
\begin{equation*}
=\operatorname{Cov}\left(w_{R} \hat{F}_{Y}^{(1)}\left(t_{y}\right)+w_{M} \hat{F}_{Y}^{(2 r)}\left(t_{y_{2}}\right), w_{R} \hat{F}_{X}^{(1)}\left(t_{x}\right)+w_{M} \hat{F}_{X}^{(2 r)}\left(t_{x_{2}}\right)\right) \tag{8.1}
\end{equation*}
$$

(8.1) can also be written as

$$
\begin{array}{r}
=\operatorname{Cov}\left\{\hat{F}_{Y}\left(t_{y}\right)+w_{M}\left(\hat{F}_{Y}^{(2 r)}\left(t_{y_{2}}\right)-\hat{F}_{Y}^{(2)}\left(t_{y_{2}}\right)\right),\right.  \tag{8.2}\\
\\
\left.\hat{F}_{X}\left(t_{x}\right)+w_{M}\left(\hat{F}_{X}^{(2 r)}\left(t_{x_{2}}\right)-\hat{F}_{X}^{(2)}\left(t_{x_{2}}\right)\right)\right\} .
\end{array}
$$

By applying covariance on (8.2), we have
(8.3) $=\left[\begin{array}{l}\operatorname{Cov}\left(\hat{F}_{Y}\left(t_{y}\right), \hat{F}_{X}\left(t_{x}\right)\right)+\operatorname{Cov}\left(w_{M}\left(\hat{F}_{Y}^{(2 r)}\left(t_{y_{2}}\right)-\hat{F}_{Y}^{(2)}\left(t_{y_{2}}\right)\right), \hat{F}_{X}\left(t_{x}\right)\right) \\ +\operatorname{Cov}\left(\hat{F}_{Y}\left(t_{y}\right), w_{M}\left(\hat{F}_{X}^{(2 r)}\left(t_{x_{2}}\right)-\hat{F}_{X}^{(2)}\left(t_{x_{2}}\right)\right)\right) \\ +\operatorname{Cov}\left(w_{M}\left(\hat{F}_{Y}^{(2 r)}\left(t_{y_{2}}\right)-\hat{F}_{Y}^{(2)}\left(t_{y_{2}}\right)\right), w_{M}\left(\hat{F}_{X}^{(2 r)}\left(t_{x_{2}}\right)-\hat{F}_{X}^{(2)}\left(t_{x_{2}}\right)\right)\right.\end{array}\right]$.

Since
$\operatorname{Cov}\left(\hat{F}_{Y}\left(t_{y}\right), w_{M}\left(\hat{F}_{X}^{(2 r)}\left(t_{x_{2}}\right)-\hat{F}_{X}^{(2)}\left(t_{x_{2}}\right)\right)\right)$
$=\operatorname{Cov}\left(w_{M}\left(\hat{F}_{Y}^{(2 r)}\left(t_{y_{2}}\right)-\hat{F}_{Y}^{(2)}\left(t_{y_{2}}\right)\right), \hat{F}_{X}\left(t_{x}\right)\right)=0$.
Hence (8.3) becomes

$$
=\left[\begin{array}{l}
\operatorname{Cov}\left(\hat{F}_{Y}\left(t_{y}\right), \hat{F}_{X}\left(t_{x}\right)\right)  \tag{8.4}\\
+\operatorname{Cov}\left(w_{M} \hat{F}_{Y}^{(2 r)}\left(t_{y_{2}}\right)-\hat{F}_{Y}^{(2)}\left(t_{y_{2}}\right), w_{M} \hat{F}_{X}^{(2 r)}\left(t_{x_{2}}\right)-\hat{F}_{X}^{(2)}\left(t_{x_{2}}\right)\right)
\end{array}\right] .
$$

Following Garcia and Cebrian [9], it is easy to obtain

$$
\operatorname{Cov}\left(\hat{F}_{Y}\left(t_{y}\right), \hat{F}_{X}\left(t_{x}\right)\right)=\frac{N-m}{N-1} \frac{m}{N^{2}}\left(\frac{N_{11} N_{22}-N_{12} N_{21}}{m^{2}}\right) .
$$

If we consider $N-1 \cong N$, then we can write above as

$$
\begin{equation*}
\operatorname{Cov}\left(\hat{F}_{Y}\left(t_{y}\right), \hat{F}_{X}\left(t_{x}\right)\right)=\frac{1-f}{m}\left(\frac{N_{11} N_{22}-N_{12} N_{21}}{N^{2}}\right) \tag{8.5}
\end{equation*}
$$

where $f=\frac{m}{N}$ and now consider last term of (8.3),
$\operatorname{Cov}\left(w_{M}\left(\hat{F}_{Y}^{(2 r)}\left(t_{y_{2}}\right)-\hat{F}_{Y}^{(2)}\left(t_{y_{2}}\right)\right), w_{M}\left(\hat{F}_{X}^{(2 r)}\left(t_{x_{2}}\right)-\hat{F}_{X}^{(2)}\left(t_{x_{2}}\right)\right)\right)$
(8.6) $=\left[\begin{array}{l}E_{1} \operatorname{Cov}_{2}\left(w_{M}\left(\hat{F}_{Y}^{(2 r)}\left(t_{y_{2}}\right)-\hat{F}_{Y}^{(2)}\left(t_{y_{2}}\right)\right), w_{M}\left(\hat{F}_{X}^{(2 r)}\left(t_{x_{2}}\right)-\hat{F}_{X}^{(2)}\left(t_{x_{2}}\right)\right)\right) \\ +\operatorname{Cov}_{1} E_{2}\left(w_{M}\left(\hat{F}_{Y}^{(2 r)}\left(t_{y_{2}}\right)-\hat{F}_{Y}^{(2)}\left(t_{y_{2}}\right)\right), w_{M}\left(\hat{F}_{X}^{(2 r)}\left(t_{x_{2}}\right)-\hat{F}_{X}^{(2)}\left(t_{x_{2}}\right)\right)\right)\end{array}\right]$.

Since,
$E_{2}\left(w_{2}\left(\hat{F}_{Y}^{(2 r)}\left(t_{y_{2}}\right)-\hat{F}_{Y}^{(2)}\left(t_{y_{2}}\right)\right), w_{2}\left(\hat{F}_{X}^{(2 r)}\left(t_{x_{2}}\right)-\hat{F}_{X}^{(2)}\left(t_{x_{2}}\right)\right)\right)=0$.
Hence (8.6), becomes

$$
\begin{equation*}
=\left[E_{1} \operatorname{Cov}_{2}\left(w_{M}\left(\hat{F}_{Y}^{(2 r)}\left(t_{y_{2}}\right)-\hat{F}_{Y}^{(2)}\left(t_{y_{2}}\right)\right), w_{M}\left(\hat{F}_{X}^{(2 r)}\left(t_{x_{2}}\right)-\hat{F}_{X}^{(2)}\left(t_{x_{2}}\right)\right)\right)\right] . \tag{8.7}
\end{equation*}
$$

Now consider
$\operatorname{Cov}_{2}\left(w_{M}\left(\hat{F}_{Y}^{(2 r)}\left(t_{y_{2}}\right)-\hat{F}_{Y}^{(2)}\left(t_{y_{2}}\right)\right), w_{M}\left(\hat{F}_{X}^{(2 r)}\left(t_{x_{2}}\right)-\hat{F}_{X}^{(2)}\left(t_{x_{2}}\right)\right)\right)$,
$(8.8)=\left[\begin{array}{l}E_{2} \operatorname{Cov}_{3}\left(w_{M}\left(\hat{F}_{Y}^{(2 r)}\left(t_{y_{2}}\right)-\hat{F}_{Y}^{(2)}\left(t_{y_{2}}\right)\right), w_{M}\left(\hat{F}_{X}^{(2 r)}\left(t_{x_{2}}\right)-\hat{F}_{X}^{(2)}\left(t_{x_{2}}\right)\right)\right) \\ +\operatorname{Cov}_{2} E_{3}\left(w_{M}\left(\hat{F}_{Y}^{(2 r)}\left(t_{y_{2}}\right)-\hat{F}_{Y}^{(2)}\left(t_{y_{2}}\right)\right), w_{M}\left(\hat{F}_{X}^{(2 r)}\left(t_{x_{2}}\right)-\hat{F}_{X}^{(2)}\left(t_{x_{2}}\right)\right)\right)\end{array}\right]$.
(8.9) $=\left[E_{2} \operatorname{Cov}_{3}\left(w_{M}\left(\hat{F}_{Y}^{(2 r)}\left(t_{y_{2}}\right)-\hat{F}_{Y}^{(2)}\left(t_{y_{2}}\right)\right), w_{M}\left(\hat{F}_{X}^{(2 r)}\left(t_{x_{2}}\right)-\hat{F}_{X}^{(2)}\left(t_{x_{2}}\right)\right)\right)\right]$.

Consider $\operatorname{Cov}_{3}\left(w_{M}\left(\hat{F}_{Y}^{(2 r)}\left(t_{y_{2}}\right)-\hat{F}_{Y}^{(2)}\left(t_{y_{2}}\right)\right), w_{M}\left(\hat{F}_{X}^{(2 r)}\left(t_{x_{2}}\right)-\hat{F}_{X}^{(2)}\left(t_{x_{2}}\right)\right)\right)$,
(8.10) $=\operatorname{Cov}_{3}\left(\hat{F}_{Y}^{(2 r)}\left(t_{y_{2}}\right), \hat{F}_{X}^{(2 r)}\left(t_{x_{2}}\right)\right)$.

By taking $r$ sample points out of $m_{M}$ and after some simplifications, (??) becomes
(8.11) $\operatorname{Cov}_{3}\left(\hat{F}_{Y}^{(2 r)}\left(t_{y_{2}}\right), \hat{F}_{X}^{(2 r)}\left(t_{x_{2}}\right)\right)=\frac{(k-1)}{m_{M}-1}\left(\frac{N_{11}^{(2)} N_{22}^{(2)}-N_{12}^{(2)} N_{21}^{(2)}}{\left(m_{M}^{(2)}\right)^{2}}\right)$.
$E_{2} \operatorname{Cov}_{3}\left(w_{M} \hat{F}_{Y}^{(2 r)}\left(t_{y_{2}}\right)-\hat{F}_{Y}^{(2)}\left(t_{y_{2}}\right), w_{M} \hat{F}_{X}^{(2 r)}\left(t_{x_{2}}\right)-\hat{F}_{X}^{(2)}\left(t_{x_{2}}\right)\right)$,
(8.12) $=\frac{m_{M}^{2}(k-1)}{m^{2}\left(m_{M}-1\right)} E_{2}\left[\left(\frac{\hat{N}_{11}^{(2)} \hat{N}_{22}^{(2)}-\hat{N}_{12}^{(2)} \hat{N}_{21}^{(2)}}{\left(m_{M}^{(2)}\right)^{2}}\right)\right]$.

Applying expectations on (8.12), we have
(8.13) $=\frac{(k-1) W_{M}}{m}\left(\frac{N_{11}^{(2)} N_{22}^{(2)}-N_{12}^{(2)} N_{21}^{(2)}}{N_{M}\left(N_{M}-1\right)}\right)$.

For considering, $N_{M}-1 \cong N_{M}$, Equation (8.13) becomes,
(8.14) $=\frac{W_{M}(k-1)}{m}\left(\frac{N_{11}^{(2)} N_{22}^{(2)}-N_{12}^{(2)} N_{21}^{(2)}}{\left(N_{M}^{(2)}\right)^{2}}\right)$.

Using (8.5) and (8.14) in (8.2) we have following result given as

$$
\operatorname{Cov}\left(\hat{F}_{Y}^{(*)}\left(t_{y}\right), \hat{F}_{X}^{(*)}\left(t_{x}\right)\right)=\left[\begin{array}{l}
\frac{(1-f)}{m}\left(\frac{N_{11} N_{22}-N_{12} N_{21}}{(N)^{2}}\right)  \tag{8.15}\\
+\frac{W_{M}(k-1)}{m}\left(\frac{N_{11}^{(2)} N_{22}^{(2)}-N_{12}^{(2)} N_{21}^{(2)}}{\left(N_{M}^{(2)}\right)^{2}}\right)
\end{array}\right]
$$


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