

A Decomposition Formula for Bivariate Hypergeometric-Trigonometric Series

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ABSTRACT. A general identity is presented for bivariate hypergeometric-trigonometric series, which can be considered as a decomposition formula for the aforementioned series. Some special examples are also given in this sense.

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1. INTRODUCTION

Let

$$f^*(z) = \sum_{k=0}^{\infty} a_k^* z^k \quad (1.1)$$

be a convergent series in which are known real numbers. If

$$z = x + iy = r e^{i\theta} \quad (i = \sqrt{-1})$$

is a complex variable with

$$r = \sqrt{x^2 + y^2} \quad \text{and} \quad \theta = \arg(x + iy)$$

then it can be verified from (1.1) that

$$\operatorname{Im}(z^\lambda f^*(z) + \bar{z}^\lambda f^*(\bar{z})) = \operatorname{Im}\left(\frac{z^\lambda f^*(z) - \bar{z}^\lambda f^*(\bar{z})}{i}\right) = 0, \quad \forall \lambda \in \mathbb{R}. \quad (1.2)$$

This means that $z^\lambda f^*(z) + \bar{z}^\lambda f^*(\bar{z})$ and $(z^\lambda f^*(z) - \bar{z}^\lambda f^*(\bar{z}))/i$ are always two real functions if (1.1) holds. Based on the results (1.2), we have recently introduced two bivariate series in [5] as

$$C_\alpha(f^*; r, \theta, m, n) = \sum_{k=0}^{\infty} a_{nk+m}^* r^k \cos(\alpha + k)\theta \quad (1.3)$$

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and

$$S_\alpha(f^*; r, \theta, m, n) = \sum_{k=0}^\infty a_{nk+m}^* r^k \sin(\alpha + k)\theta \tag{1.4}$$

where r, θ are real variables, $\alpha \in \mathbb{R}$, $n \in \mathbb{N}$ and $m \in \{0, 1, \dots, n - 1\}$, and showed that they are convergent if the reduced series $\sum_{k=0}^\infty a_{nk+m}^* r^k$ is convergent. Now, assume in (1.3) and (1.4) that

$$a_k^* = \frac{(a_1)_k(a_2)_k \dots (a_p)_k}{(b_1)_k(b_2)_k \dots (b_q)_k}$$

are hypergeometric terms where $(r)_k = \prod_{j=0}^{k-1} (r + j)$ denotes the well-known Pochhammer symbol [1]. Then

$${}_pC_q \left(\begin{matrix} a_1, a_2, \dots, a_p \\ b_1, b_2, \dots, b_q \end{matrix} \middle| (r, \theta); \alpha \right) = \sum_{k=0}^\infty \frac{(a_1)_k(a_2)_k \dots (a_p)_k}{(b_1)_k(b_2)_k \dots (b_q)_k} \frac{r^k}{k!} \cos(\alpha + k)\theta, \tag{1.5}$$

and

$${}_pS_q \left(\begin{matrix} a_1, a_2, \dots, a_p \\ b_1, b_2, \dots, b_q \end{matrix} \middle| (r, \theta); \alpha \right) = \sum_{k=0}^\infty \frac{(a_1)_k(a_2)_k \dots (a_p)_k}{(b_1)_k(b_2)_k \dots (b_q)_k} \frac{r^k}{k!} \sin(\alpha + k)\theta, \tag{1.6}$$

are called bivariate hypergeometric-trigonometric series [6]. It is clear from (1.5) and (1.6) that

$${}_pC_q \left(\begin{matrix} a_1, a_2, \dots, a_p \\ b_1, b_2, \dots, b_q \end{matrix} \middle| (r, \theta); \alpha \right) = \cos \alpha \theta {}_pC_q \left(\begin{matrix} a_1, a_2, \dots, a_p \\ b_1, b_2, \dots, b_q \end{matrix} \middle| (r, \theta); 0 \right) - \sin \alpha \theta {}_pS_q \left(\begin{matrix} a_1, a_2, \dots, a_p \\ b_1, b_2, \dots, b_q \end{matrix} \middle| (r, \theta); 0 \right), \tag{1.7}$$

and

$${}_pS_q \left(\begin{matrix} a_1, a_2, \dots, a_p \\ b_1, b_2, \dots, b_q \end{matrix} \middle| (r, \theta); \alpha \right) = \sin \alpha \theta {}_pC_q \left(\begin{matrix} a_1, a_2, \dots, a_p \\ b_1, b_2, \dots, b_q \end{matrix} \middle| (r, \theta); 0 \right) + \cos \alpha \theta {}_pS_q \left(\begin{matrix} a_1, a_2, \dots, a_p \\ b_1, b_2, \dots, b_q \end{matrix} \middle| (r, \theta); 0 \right). \tag{1.8}$$

Many ordinary hypergeometric series (when $\theta = 0$) and Fourier trigonometric series (when r is fixed and pre-assigned) can be represented in terms of the series (1.5) or (1.6). See also [2, 6].

2. A GENERAL IDENTITY FOR BIVARIATE HYPERGEOMETRIC-TRIGONOMETRIC SERIES

First, for any arbitrary series that we clearly have

$$\sum_{k=0}^\infty u_k = \sum_{j=0}^\infty u_{2j} + \sum_{j=0}^\infty u_{2j+1} = \sum_{j=0}^\infty u_{3j} + \sum_{j=0}^\infty u_{3j+1} + \sum_{j=0}^\infty u_{3j+2} = \dots = \sum_{j=0}^\infty u_{mj} + \sum_{j=0}^\infty u_{mj+1} + \dots + \sum_{j=0}^\infty u_{mj+m-1}, \tag{2.1}$$

where m is a natural number. By recalling the Pochhammer symbol and noting the series (1.5) and (1.6), if

$$u_k = \frac{(a_1)_k(a_2)_k \dots (a_p)_k}{(b_1)_k(b_2)_k \dots (b_q)_k(1)_k} r^k \left\{ \begin{matrix} \cos(\alpha + k)\theta \\ \sin(\alpha + k)\theta \end{matrix} \right\},$$

is substituted in the last equality of (2.1), then we have

$$\begin{aligned} {}_p \left\{ \begin{matrix} C \\ S \end{matrix} \right\}_q \left(\begin{matrix} a_1, a_2, \dots, a_p \\ b_1, b_2, \dots, b_q \end{matrix} \middle| (r, \theta); \alpha \right) &= \sum_{j=0}^\infty \frac{(a_1)_{mj}(a_2)_{mj} \dots (a_p)_{mj}}{(b_1)_{mj}(b_2)_{mj} \dots (b_q)_{mj}(1)_{mj}} r^{mj} \left\{ \begin{matrix} \cos(\alpha + mj)\theta \\ \sin(\alpha + mj)\theta \end{matrix} \right\} \\ &+ \sum_{j=0}^\infty \frac{(a_1)_{mj+1}(a_2)_{mj+1} \dots (a_p)_{mj+1}}{(b_1)_{mj+1}(b_2)_{mj+1} \dots (b_q)_{mj+1}(1)_{mj+1}} r^{mj+1} \left\{ \begin{matrix} \cos(\alpha + mj + 1)\theta \\ \sin(\alpha + mj + 1)\theta \end{matrix} \right\} + \dots \\ &+ \sum_{j=0}^\infty \frac{(a_1)_{mj+m-1} \dots (a_p)_{mj+m-1}}{(b_1)_{mj+m-1} \dots (b_q)_{mj+m-1}(1)_{mj+m-1}} r^{mj+m-1} \left\{ \begin{matrix} \cos(\alpha + mj + m - 1)\theta \\ \sin(\alpha + mj + m - 1)\theta \end{matrix} \right\}. \end{aligned} \tag{2.2}$$

On the other hand, since the two following identities hold

$$(a)_{mk} = m^{mk} \prod_{j=0}^{m-1} \left(\frac{a+j}{m} \right)_k,$$

and

$$(a)_{mj+i} = (a+i)_m j(a)_i,$$

relation (2.2) can be re-written as

$$\begin{aligned} {}^p \left\{ \begin{matrix} C \\ S \end{matrix} \right\}_q \left(\begin{matrix} a_1, a_2, \dots, a_p \\ b_1, b_2, \dots, b_q \end{matrix} \middle| (r, \theta); \alpha \right) &= \sum_{j=0}^{\infty} \frac{\prod_{r=0}^{m-1} \left(\frac{a_1+r}{m} \right)_j \dots \prod_{r=0}^{m-1} \left(\frac{a_p+r}{m} \right)_j}{\prod_{r=0}^{m-1} \left(\frac{b_1+r}{m} \right)_j \dots \prod_{r=0}^{m-1} \left(\frac{b_q+r}{m} \right)_j \prod_{r=0}^{m-1} \left(\frac{1+r}{m} \right)_j} \left(m^{(p-q-1)m} r^m \right)^j \left\{ \begin{matrix} \cos\left(\frac{\alpha}{m} + j\right)(m\theta) \\ \sin\left(\frac{\alpha}{m} + j\right)(m\theta) \end{matrix} \right\} \\ &+ \frac{(a_1)_1 (a_2)_1 \dots (a_p)_1}{(b_1)_1 (b_2)_1 \dots (b_q)_1} \frac{r}{(1)_1} \sum_{j=0}^{\infty} \frac{\prod_{r=0}^{m-1} \left(\frac{a_1+1+r}{m} \right)_j \dots \prod_{r=0}^{m-1} \left(\frac{a_p+1+r}{m} \right)_j}{\prod_{r=0}^{m-1} \left(\frac{b_1+1+r}{m} \right)_j \dots \prod_{r=0}^{m-1} \left(\frac{b_q+1+r}{m} \right)_j \prod_{r=0}^{m-1} \left(\frac{2+r}{m} \right)_j} \left(m^{(p-q-1)m} r^m \right)^j \left\{ \begin{matrix} \cos\left(\frac{\alpha+1}{m} + j\right)(m\theta) \\ \sin\left(\frac{\alpha+1}{m} + j\right)(m\theta) \end{matrix} \right\} + \dots \\ &+ \frac{(a_1)_{m-1} (a_2)_{m-1} \dots (a_p)_{m-1}}{(b_1)_{m-1} (b_2)_{m-1} \dots (b_q)_{m-1}} \frac{r^{m-1}}{(1)_{m-1}} \sum_{j=0}^{\infty} \frac{\prod_{r=0}^{m-1} \left(\frac{a_1+m-1+r}{m} \right)_j \dots \prod_{r=0}^{m-1} \left(\frac{a_p+m-1+r}{m} \right)_j}{\prod_{r=0}^{m-1} \left(\frac{b_1+m-1+r}{m} \right)_j \dots \prod_{r=0}^{m-1} \left(\frac{b_q+m-1+r}{m} \right)_j \prod_{r=0}^{m-1} \left(\frac{m-1+r}{m} \right)_j} \left(m^{(p-q-1)m} r^m \right)^j \left\{ \begin{matrix} \cos\left(\frac{\alpha+m-1}{m} + j\right)(m\theta) \\ \sin\left(\frac{\alpha+m-1}{m} + j\right)(m\theta) \end{matrix} \right\}, \end{aligned}$$

which eventually leads to the main theorem.

Theorem 2.1. For any natural number m , the two series (1.5) and (1.6) satisfy the relation

$$\begin{aligned} {}^p \left\{ \begin{matrix} C \\ S \end{matrix} \right\}_q \left(\begin{matrix} a_1, a_2, \dots, a_p \\ b_1, b_2, \dots, b_q \end{matrix} \middle| (r, \theta); \alpha \right) \\ = \sum_{k=0}^{m-1} \frac{(a_1)_k \dots (a_p)_k}{(b_1)_k \dots (b_q)_k} \frac{r^k}{k!} (mp+1) \left\{ \begin{matrix} C \\ S \end{matrix} \right\}_{(mq+m)} \left(\begin{matrix} \vec{A}_{1,k}, \vec{A}_{2,k}, \dots, \vec{A}_{p,k}, 1 \\ \vec{B}_{1,k}, \vec{B}_{2,k}, \dots, \vec{B}_{q,k}, \vec{I}_{1,k} \end{matrix} \middle| (m^{(p-q-1)m} r^m, m\theta); \frac{\alpha+k}{m} \right), \end{aligned} \quad (2.3)$$

where

$$\vec{A}_{j,k} = \left(\frac{a_j+k}{m}, \frac{a_j+1+k}{m}, \dots, \frac{a_j+m-1+k}{m} \right) \quad (j = 1, 2, \dots, p),$$

$$\vec{B}_{j,k} = \left(\frac{b_j+k}{m}, \frac{b_j+1+k}{m}, \dots, \frac{b_j+m-1+k}{m} \right) \quad (j = 1, 2, \dots, q),$$

and

This theorem can be interpreted as a decomposition formula for many hypergeometric-trigonometric series of type (1.5) and (1.6).

Example 2.1. Since we have [4]

$${}_0C_0 \left(\begin{matrix} - \\ - \end{matrix} \middle| (r, \theta); 0 \right) = \sum_{k=0}^{\infty} \frac{r^k}{k!} \cos k\theta = e^{r \cos \theta} \cos(r \sin \theta),$$

and

$${}_0S_0 \left(\begin{matrix} - \\ - \end{matrix} \middle| (r, \theta); 0 \right) = \sum_{k=0}^{\infty} \frac{r^k}{k!} \sin k\theta = e^{r \cos \theta} \sin(r \sin \theta),$$

relations (1.7) and (1.8) respectively yield

$${}_0C_0 \left(\begin{matrix} - \\ - \end{matrix} \middle| (r, \theta); \alpha \right) = \sum_{k=0}^{\infty} \frac{r^k}{k!} \cos(k + \alpha)\theta = e^{r \cos \theta} \cos(\alpha\theta + r \sin \theta),$$

and

$${}_0S_0 \left(\begin{matrix} - \\ - \end{matrix} \middle| (r, \theta); 0 \right) = \sum_{k=0}^{\infty} \frac{r^k}{k!} \sin(k + \alpha)\theta = e^{r \cos \theta} \sin(\alpha\theta + r \sin \theta),$$

which are valid for any $r \in \mathbb{R}$, $\alpha \in \mathbb{R}$ and $\theta \in [-\pi, \pi]$. Hence, by taking $m = 2$ in (2.3) we respectively obtain

$$e^{r \cos \theta} \cos(\alpha \theta + r \sin \theta) = {}_0C_1 \left(\begin{matrix} - \\ 1/2 \end{matrix} \middle| \left(\frac{1}{4} r^2, 2\theta \right); \frac{\alpha}{2} \right) + r {}_0C_1 \left(\begin{matrix} - \\ 3/2 \end{matrix} \middle| \left(\frac{1}{4} r^2, 2\theta \right); \frac{\alpha + 1}{2} \right),$$

and

$$e^{r \cos \theta} \sin(\alpha \theta + r \sin \theta) = {}_0S_1 \left(\begin{matrix} - \\ 1/2 \end{matrix} \middle| \left(\frac{1}{4} r^2, 2\theta \right); \frac{\alpha}{2} \right) + r {}_0S_1 \left(\begin{matrix} - \\ 3/2 \end{matrix} \middle| \left(\frac{1}{4} r^2, 2\theta \right); \frac{\alpha + 1}{2} \right).$$

Similarly for $m = 3$ in (2.3) the decomposition formulae read as

$$e^{r \cos \theta} \cos(\alpha \theta + r \sin \theta) = {}_0C_2 \left(\begin{matrix} - \\ 1/3, 2/3 \end{matrix} \middle| \left(\frac{1}{27} r^3, 3\theta \right); \frac{\alpha}{3} \right) + r {}_0C_2 \left(\begin{matrix} - \\ 2/3, 4/3 \end{matrix} \middle| \left(\frac{1}{27} r^3, 3\theta \right); \frac{\alpha + 1}{3} \right) + \frac{1}{2} r^2 {}_0C_2 \left(\begin{matrix} - \\ 4/3, 5/3 \end{matrix} \middle| \left(\frac{1}{27} r^3, 3\theta \right); \frac{\alpha + 2}{3} \right),$$

and

$$e^{r \cos \theta} \sin(\alpha \theta + r \sin \theta) = {}_0S_2 \left(\begin{matrix} - \\ 1/3, 2/3 \end{matrix} \middle| \left(\frac{1}{27} r^3, 3\theta \right); \frac{\alpha}{3} \right) + r {}_0S_2 \left(\begin{matrix} - \\ 2/3, 4/3 \end{matrix} \middle| \left(\frac{1}{27} r^3, 3\theta \right); \frac{\alpha + 1}{3} \right) + \frac{1}{2} r^2 {}_0S_2 \left(\begin{matrix} - \\ 4/3, 5/3 \end{matrix} \middle| \left(\frac{1}{27} r^3, 3\theta \right); \frac{\alpha + 2}{3} \right).$$

Finally for $m = 4$ in (2.3) we have

$$e^{r \cos \theta} \cos(\alpha \theta + r \sin \theta) = {}_0C_3 \left(\begin{matrix} - \\ 1/4, 2/4, 3/4 \end{matrix} \middle| \left(\frac{1}{256} r^4, 4\theta \right); \frac{\alpha}{4} \right) + r {}_0C_3 \left(\begin{matrix} - \\ 2/4, 3/4, 5/4 \end{matrix} \middle| \left(\frac{1}{256} r^4, 4\theta \right); \frac{\alpha + 1}{4} \right) + \frac{1}{2} r^2 {}_0C_3 \left(\begin{matrix} - \\ 3/4, 5/4, 6/4 \end{matrix} \middle| \left(\frac{1}{256} r^4, 4\theta \right); \frac{\alpha + 2}{4} \right) + \frac{1}{6} r^3 {}_0C_3 \left(\begin{matrix} - \\ 5/4, 6/4, 7/4 \end{matrix} \middle| \left(\frac{1}{256} r^4, 4\theta \right); \frac{\alpha + 3}{4} \right),$$

and

$$e^{r \cos \theta} \sin(\alpha \theta + r \sin \theta) = {}_0S_3 \left(\begin{matrix} - \\ 1/4, 2/4, 3/4 \end{matrix} \middle| \left(\frac{1}{256} r^4, 4\theta \right); \frac{\alpha}{4} \right) + r {}_0S_3 \left(\begin{matrix} - \\ 2/4, 3/4, 5/4 \end{matrix} \middle| \left(\frac{1}{256} r^4, 4\theta \right); \frac{\alpha + 1}{4} \right) + \frac{1}{2} r^2 {}_0S_3 \left(\begin{matrix} - \\ 3/4, 5/4, 6/4 \end{matrix} \middle| \left(\frac{1}{256} r^4, 4\theta \right); \frac{\alpha + 2}{4} \right) + \frac{1}{6} r^3 {}_0S_3 \left(\begin{matrix} - \\ 5/4, 6/4, 7/4 \end{matrix} \middle| \left(\frac{1}{256} r^4, 4\theta \right); \frac{\alpha + 3}{4} \right).$$

Example 2.2. Since

$${}_1C_0 \left(\begin{matrix} b \\ - \end{matrix} \middle| (r, \theta); 0 \right) = \sum_{k=0}^{\infty} (b)_k \frac{r^k}{k!} \cos k\theta = (1 + r^2 - 2r \cos \theta)^{-\frac{b}{2}} \cos \left(b \arctan \frac{r \sin \theta}{r \cos \theta - 1} \right),$$

and

$${}_1S_0 \left(\begin{matrix} b \\ - \end{matrix} \middle| (r, \theta); 0 \right) = \sum_{k=0}^{\infty} (b)_k \frac{r^k}{k!} \sin k\theta = (1 + r^2 - 2r \cos \theta)^{-\frac{b}{2}} \sin \left(b \arctan \frac{r \sin \theta}{r \cos \theta - 1} \right),$$

relations (1.7) and (1.8) respectively yield

$${}_1C_0 \left(\begin{matrix} b \\ - \end{matrix} \middle| (r, \theta); \alpha \right) = \sum_{k=0}^{\infty} (b)_k \frac{r^k}{k!} \cos(k + \alpha)\theta = (1 + r^2 - 2r \cos \theta)^{-\frac{b}{2}} \cos \left(\alpha \theta + b \arctan \frac{r \sin \theta}{r \cos \theta - 1} \right),$$

and

$${}_1S_0 \left(\begin{matrix} b \\ - \end{matrix} \middle| (r, \theta); \alpha \right) = \sum_{k=0}^{\infty} (b)_k \frac{r^k}{k!} \sin(k + \alpha)\theta = (1 + r^2 - 2r \cos \theta)^{-\frac{b}{2}} \sin \left(\alpha \theta + b \arctan \frac{r \sin \theta}{r \cos \theta - 1} \right),$$

which are valid for any $|r| < 1$, $\alpha \in \mathbb{R}$ and $\theta \in [-\pi, \pi]$. Hence, by taking $m = 2$ in (2.3) we respectively obtain

$$(1 + r^2 - 2r \cos \theta)^{-\frac{b}{2}} \cos(\alpha\theta + b \arctan \frac{r \sin \theta}{r \cos \theta - 1}) = {}_2C_1 \left(\begin{matrix} b/2, (b+1)/2 \\ 1/2 \end{matrix} \middle| (r^2, 2\theta); \frac{\alpha}{2} \right) \\ + br {}_2C_1 \left(\begin{matrix} (b+1)/2, (b+2)/2 \\ 3/2 \end{matrix} \middle| (r^2, 2\theta); \frac{\alpha+1}{2} \right),$$

and

$$(1 + r^2 - 2r \cos \theta)^{-\frac{b}{2}} \sin(\alpha\theta + b \arctan \frac{r \sin \theta}{r \cos \theta - 1}) = {}_2S_1 \left(\begin{matrix} b/2, (b+1)/2 \\ 1/2 \end{matrix} \middle| (r^2, 2\theta); \frac{\alpha}{2} \right) \\ + br {}_2S_1 \left(\begin{matrix} (b+1)/2, (b+2)/2 \\ 3/2 \end{matrix} \middle| (r^2, 2\theta); \frac{\alpha+1}{2} \right).$$

Similarly for $m = 3$ in (2.3) the decomposition formulae read as

$$(1 + r^2 - 2r \cos \theta)^{-\frac{b}{2}} \cos(\alpha\theta + b \arctan \frac{r \sin \theta}{r \cos \theta - 1}) = {}_3C_2 \left(\begin{matrix} b/3, (b+1)/3, (b+2)/3 \\ 1/3, 2/3 \end{matrix} \middle| (r^3, 3\theta); \frac{\alpha}{3} \right) \\ + br {}_3C_2 \left(\begin{matrix} (b+1)/3, (b+2)/3, (b+3)/3 \\ 2/3, 4/3 \end{matrix} \middle| (r^3, 3\theta); \frac{\alpha+1}{3} \right) \\ + b(b+1) \frac{1}{2} r^2 {}_3C_2 \left(\begin{matrix} (b+2)/3, (b+3)/3, (b+4)/3 \\ 4/3, 5/3 \end{matrix} \middle| (r^3, 3\theta); \frac{\alpha+2}{3} \right),$$

and

$$(1 + r^2 - 2r \cos \theta)^{-\frac{b}{2}} \sin(\alpha\theta + b \arctan \frac{r \sin \theta}{r \cos \theta - 1}) = {}_3S_2 \left(\begin{matrix} b/3, (b+1)/3, (b+2)/3 \\ 1/3, 2/3 \end{matrix} \middle| (r^3, 3\theta); \frac{\alpha}{3} \right) \\ + br {}_3S_2 \left(\begin{matrix} (b+1)/3, (b+2)/3, (b+3)/3 \\ 2/3, 4/3 \end{matrix} \middle| (r^3, 3\theta); \frac{\alpha+1}{3} \right) \\ + b(b+1) \frac{1}{2} r^2 {}_3S_2 \left(\begin{matrix} (b+2)/3, (b+3)/3, (b+4)/3 \\ 4/3, 5/3 \end{matrix} \middle| (r^3, 3\theta); \frac{\alpha+2}{3} \right).$$

Example 2.3. Since we have [4]

$${}_2C_1 \left(\begin{matrix} 1, 1 \\ 2 \end{matrix} \middle| (r, \theta); 0 \right) = \sum_{k=0}^{\infty} \frac{r^k}{k+1} \cos k\theta = \frac{1}{r} \left(-\frac{\cos \theta}{2} \ln(1 + r^2 - 2r \cos \theta) + \sin \theta \arctan \left(\frac{r \sin \theta}{1 - r \cos \theta} \right) \right),$$

and

$${}_2S_1 \left(\begin{matrix} 1, 1 \\ 2 \end{matrix} \middle| (r, \theta); 0 \right) = \sum_{k=0}^{\infty} \frac{r^k}{k+1} \sin k\theta = \frac{1}{r} \left(\cos \theta \arctan \left(\frac{r \sin \theta}{1 - r \cos \theta} \right) + \frac{\sin \theta}{2} \ln(1 + r^2 - 2r \cos \theta) \right),$$

relations (1.7) and (1.8) respectively yield

$${}_2C_1 \left(\begin{matrix} 1, 1 \\ 2 \end{matrix} \middle| (r, \theta); \alpha \right) = \sum_{k=0}^{\infty} \frac{r^k}{k+1} \cos(\alpha + k)\theta = -\frac{\sin(\alpha-1)\theta}{r} \arctan \left(\frac{r \sin \theta}{1 - r \cos \theta} \right) - \frac{\cos(\alpha-1)\theta}{2r} \ln(1 + r^2 - 2r \cos \theta), \quad (2.4)$$

and

$${}_2S_1 \left(\begin{matrix} 1, 1 \\ 2 \end{matrix} \middle| (r, \theta); \alpha \right) = \sum_{k=0}^{\infty} \frac{r^k}{k+1} \sin(\alpha + k)\theta = \frac{\cos(\alpha-1)\theta}{r} \arctan \left(\frac{r \sin \theta}{1 - r \cos \theta} \right) - \frac{\sin(\alpha-1)\theta}{2r} \ln(1 + r^2 - 2r \cos \theta), \quad (2.5)$$

which are valid for any $|r| < 1$, $\alpha \in \mathbb{R}$ and $\theta \in [-\pi, \pi]$. Hence, by taking $m = 2$ in (2.3) we respectively obtain

$$-\frac{\sin(\alpha-1)\theta}{r} \arctan\left(\frac{r \sin \theta}{1-r \cos \theta}\right) - \frac{\cos(\alpha-1)\theta}{2r} \ln(1+r^2-2r \cos \theta) = {}_2C_1\left(\begin{matrix} 1/2, 1 \\ 3/2 \end{matrix} \middle| (r^2, 2\theta); \frac{\alpha}{2}\right) + \frac{1}{2}r {}_2C_1\left(\begin{matrix} 1, 1 \\ 2 \end{matrix} \middle| (r^2, 2\theta); \frac{\alpha+1}{2}\right),$$

and

$$\frac{\cos(\alpha-1)\theta}{r} \arctan\left(\frac{r \sin \theta}{1-r \cos \theta}\right) - \frac{\sin(\alpha-1)\theta}{2r} \ln(1+r^2-2r \cos \theta) = {}_2S_1\left(\begin{matrix} 1/2, 1 \\ 3/2 \end{matrix} \middle| (r^2, 2\theta); \frac{\alpha}{2}\right) + \frac{1}{2}r {}_2S_1\left(\begin{matrix} 1, 1 \\ 2 \end{matrix} \middle| (r^2, 2\theta); \frac{\alpha+1}{2}\right).$$

Finally, it may be valuable to point out that it was first Euler [3] who obtained the following well known sum

$$\frac{\pi - \theta}{2} = \sum_{k=1}^{\infty} \frac{\sin k\theta}{k}, \quad 0 < \theta < 2\pi a.$$

Now, Euler's sum can be represented as

$$\sum_{k=1}^{\infty} \frac{\sin k\theta}{k} = \sum_{j=0}^{\infty} \frac{\sin(j+1)\theta}{j+1} = \sum_{j=0}^{\infty} \frac{(1)_j (1)_j}{(2)_j} \frac{\sin(j+1)\theta}{j!} = {}_2S_1\left(\begin{matrix} 1, 1 \\ 2 \end{matrix} \middle| (1, \theta); 1\right),$$

which according to (2.5) is simplified as

$${}_2S_1\left(\begin{matrix} 1, 1 \\ 2 \end{matrix} \middle| (1, \theta); 1\right) = \arctan\left(\frac{\sin \theta}{1 - \cos \theta}\right) = \arctan(\cot(\theta/2)) = \frac{\pi - \theta}{2}.$$

Similarly, relation (2.4) yields

$${}_2C_1\left(\begin{matrix} 1, 1 \\ 2 \end{matrix} \middle| (1, \theta); 1\right) = \sum_{k=1}^{\infty} \frac{\cos k\theta}{k} = -\frac{1}{2} \ln(2 - 2 \cos \theta).$$

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