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A Note on Ricci Solitons on Para-Sasakian Manifolds

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Abctract

In the present paper, in an almost para-contact metric manifold, especially on para-Sasakian manifolds, Ricci solitons were examined. Also, we consider the *generalized quasi-conformal curvature tensor* on a para-Sasakian manifold admitting Ricci soliton.

Keywords: Para-contact manifolds, Ricci soliton, Semi-symmetric manifolds

Para-Sasakian Manifoldlarda Ricci Solitonlar Üzerine Bir Not

Öz

Bu çalışmada, bir hemen hemen para-kontakt metrik manifoldda, özellikle para-Sasakian manifoldlar üzerinde, Ricci solitonlar incelenmiştir. Ayrıca bir para-Sasakian manifold üzerinde Ricci soliton şartı ile birlikte genelleştirilmiş quasi-conformal eğrilik tensörü ele alınmıştır.

Anahtar Kelimeler: Para-kontakt manifoldlar, Ricci soliton, Semi simetrik manifold

1. Introduction

R.S. Hamilton studied the notion of Ricci solitons as which were generalization of an Einstein metric (Hamilton, 1982). On a semi-Riemannian manifold M with semi-Riemannian metric g, a Ricci soliton is a triple (g, V, λ) such that

(1)
$$(\pounds_V g)(U,W) + 2S(U,W) + 2\lambda g(U,W) = 0,$$

where W,U vector fields on M, λ is a constant and \pounds denotes the Lie derivative.

The Ricci soliton is called expanding, steady or shrinking if

$$\lambda > 0, \ \lambda = 0 \text{ or } \lambda < 0.$$

In the recent years, this subject has been introduced in some papers; on Kaehler manifolds Hodes and Fong (2013), on contact manifolds Calin and Crasmereanu (2010); Turan et al., (2012); De et al., (2012) and paracontact manifolds Yüksel Perktaş and Keleş, (2015); Adara et al., (2018).

In 1985, the concept of almost para-contact structure in a semi-Riemannian manifold was

introduced in Kaneyuki and Konzai (1985) and then the almost para-complex structure on $M^{2n+1} \times \Box$ characterized.

Later, S. Zamkovoy Zamkovoy (2009) investigated almost para-contact structure and some considerable subclasses. Especially, in the recent years many authors have pointed out the importance of paracontact geometry Erdem (2002); Cortes et al. (2006), and in particular of para-Sasakian manifold by several papers (Acet et al. 2014; Acet et al. 2016).

K. Yano and S. Sawaki defined the concept of quasi-conformal curvature tensor (Yano and Sawaki, 1968). Later, generalized quasiconformal curvature tensor was investigated in (Baishya and Chawdhury, 2016). This tensor is given by

$$\overset{\Box}{W}(U,Y)T = \frac{2n-1}{2n+1} \binom{(2nr-s+1)}{-(2n(r+s)+1)t} C(U,Y)T + (2nr-s+1)E(U,Y)T + (2n(s-r))P(U,Y)T \frac{2n-1}{2n+1} \binom{2n(t-1)(r+s)}{+(t-1)} K(U,Y)T$$
(2)

for any $Y, U, T \in TM$, where $r, s, t \in \Box$ and curvature tensors are given by

$$C(U,Y)T = R(U,Y)T - \frac{1}{2n-1} \begin{pmatrix} S(Y,T)U - S(U,T)Y \\ +g(Y,T)QU - g(U,T)QY \end{pmatrix} + \frac{r}{(2n-1)2n} (g(Y,T)U - g(U,T)Y)$$

which is known conformal curvature tensor,

$$E(U,Y)T = R(U,Y)T - \frac{\tau}{2n(2n-1)} \left(g(Y,T)U - g(U,T)Y\right)$$

which is known concircular curvature tensor,

$$K(U,Y)T = R(U,Y)T - \frac{1}{2n-1} \begin{pmatrix} S(Y,T)U - S(U,T)Y & k_{T} \\ -g(U,T)QY + g(Y,T)QU(Z) & k_{T} \end{pmatrix}$$

which is known conharmonical curvature tensor

$$P(U,Y)T = R(U,Y)T - \frac{1}{2n} \left(S(Y,T)U - S(U,T)Y \right)$$

which is known projective curvature tensor. This generalized quasi-conformal curvature tensor is reduced to be

i) Riemannian curvature tensor if

$$r=s=0, \quad t=0,$$

ii) Conformal curvature tensor (Eisenhart, 1949) if

$$r = -\frac{1}{2n-1} = s, t = 1$$

iii) Concircular curvature tensor (Ishii, 1957) if

$$r = s = 0, t = 1,$$

iv) Conharmonic curvature tensor (Yano and Bochner, 1953) if

$$r = -\frac{1}{2n-1} = s, t = 0,$$

v) Projective curvature tensor (Ishii, 1957) if

$$r = -\frac{1}{2n}, s = 0 = t,$$

vi) *m*-Projective curvature tensor (Pokhariyal and Mishra, 1970) if

$$r = -\frac{1}{4n} = s, t = 0$$

Preliminaries

A para-contact manifold is a differentiable manifold equipped with a vector field ξ , a 1-form η and a tensor field ϕ of type (1,1) satisfying (Kaneyuki and Konzai, 1985):

$$\phi^2 = I - \eta \otimes \xi,$$

 $\eta(\xi) = 1, \ \phi \xi = 0.$

(4)

(3)

As a consequence of (4), we get

$$\eta \circ \phi = 0$$
, $rank\phi = 2n$.

Moreover if the manifold M is equipped with a semi Riemannian metric g which is known compatible metric satisfying /(Zamkovoy, 2009)

$$g(\phi W, \phi X) = -g(W, X) + \eta(W)\eta(X), \quad (5)$$

then one can say that M is an almost paracontact metric manifold.

From the definition, we get (Zamkovoy, 2009),

$$\eta(W) = g(\xi, W)$$

(6) and

$$g(\phi W, X) = -g(W, \phi X),$$
(7)

The fundamental 2-form Φ of an almost para-contact structure (ϕ, ξ, η, g) is defined by

$$\Phi(W, X) = g(W, \phi X),$$
(8)

$$g(W,\phi X) = d\eta(W,X)$$

where

If

 $d\eta(W, X) = (1/2)(W\eta(X) - X\eta(W) - \eta([W, X])),$ an almost para-contact metric structure is called a para-contact metric structure. For (M, ϕ, ξ, η, g) an almost para-contact metric manifold one can find a local orthonormal basis which is known ϕ -basis $(X_i, \phi X_i, \xi)$ (i = 1, 2, ..., n) (Zamkovoy, 2009).

An almost para-contact metric manifold M is a para-Sasakian manifold iff (Zamkovoy, 2009)

$$(\nabla_X \phi)W = -g(X, W)\xi + \eta(W)X.$$
(9)

In view of (9), one arrive at

$$\nabla_W \xi = -\phi W.$$
(10)

Moreover, in para-Sasakian manifolds, we get

$$R(\xi, W)U = -g(U, W)\xi + \eta(U)W,$$
(11)
$$g(R(W, Y)X, \xi) = g(W, X)\eta(Y) - g(Y, X)\eta(W),$$
(12)

(13)

$$R(W, X)\xi = \eta(W)X - \eta(X)W,$$
(14)
$$S(W,\xi) = -2n\eta(W).$$
(15)

 $R(\xi, W)\xi = W - \eta(W)\xi,$

Assume that M^{2n+1} is a para-Sasakian manifold and (g,V,λ) is a Ricci soliton on M. From (1), we get

$$2S(W, X) = -(\pounds_V g)(W, X) - 2\lambda g(W, X).$$

Using (6) with (10), we arrive at

$$S(W, X) = -\lambda g(W, X).$$
(16)

So, we can give:

Theorem 2.1 A para-Sasakian manifold admitting a Ricci soliton is an Einstein manifold.

Moreover, putting $X = \xi$ in (16) and using (15), we get

(

$$\lambda = 2n.$$

So, we get the following.

Theorem 2.2 A Ricci soliton in para-Sasakian manifold M^{2n+1} is expanding.

Main Theorems

Definition 3.1 A para-contact manifold is called semi-symmetric type if the curvature tensor $\stackrel{\Box}{W}$ fulfills the equation

$$R(U,V)\cdot \overset{\sqcup}{W}=0$$

(18)

for all $U, V \in TM$.

We suppose that the equation (18) fulfills on M . So we get

$$R(\xi,U)\overset{\square}{W}(Z,Y)X - \overset{\square}{W}(R(\xi,U)Z,Y)X$$
$$-\overset{\square}{W}(Z,R(\xi,U)Y)X - \overset{\square}{W}(Z,Y)R(\xi,U)X$$
(19)

= 0.

Using the equation (13) in (19), we have

$$\eta(W(Z,Y)X)U - g(U,W(Z,Y)X)\xi$$
$$+g(U,Z)W(\xi,Y)X - \eta(Z)W(U,Y)X$$
$$+g(U,Y)W(Z,\xi)X - \eta(Y)W(Z,U)X$$

(20)

$$+g(U,X)\overset{\cup}{W}(Z,Y)\xi -\eta(X)\overset{\cup}{W}(Z,Y)U$$
$$=0.$$

Taking an inner product with ξ , we obtain

$$\eta(\widetilde{W}(Z,Y)X)\eta(U) - g(U,\widetilde{W}(Z,Y)X)$$
$$+g(U,Z)\eta(\widetilde{W}(\xi,Y)X)$$
$$-\eta(Z)\eta(\widetilde{W}(U,Y)X)$$
$$+g(U,Y)\eta(\widetilde{W}(Z,\xi)X) - \eta(Y)\eta(\widetilde{W}(Z,U)X)$$

(21)

= 0.

Using (2) in (21) and after some calculations, we get

$$\begin{bmatrix} 1+\lambda(r+s) \\ +\frac{t\tau}{2n+1}\left(\frac{1}{2n}+r+s\right) \end{bmatrix} \begin{pmatrix} g(U,Y)g(Z,X) \\ -g(U,Z)g(Y,X) \end{pmatrix}$$
$$-g(U,W(Z,Y)X)$$
(22)

= 0.

In view of (2) with (16) in (22), we find

$$-g(\overset{\cup}{W}(Z,Y)X,U) + g(Z,X)g(U,Y)$$
$$-g(U,Z)g(Y,X) = 0.$$
(23)

Since $\{e_i, \phi e_i, \xi\}$ is a basis of *M*. from (23), we have

$$S(Y, X) + 2ng(Y, X) = 0.$$
(24)

Now, one can state:

Theorem 3.1 A para-Sasakian manifold satisfying $R(\xi, X) \cdot \stackrel{\square}{W} = 0$ admitting a Ricci soliton (g, V, λ) is an Einstein manifold.

Taking $X = \xi = Y$ in (24) and in view of (16), we arrive at

$$\lambda = 2n$$

which yields λ is positive. Thus, we have :

Theorem 3.2 Let (g, V, λ) be a Ricci soliton on para-Sasakian manifold. If the semisymmetric condition $R(\xi, X) \cdot \overset{\Box}{W} = 0$ satisfies on *M*, then the Ricci soliton is expanding.

Now, assume that (g, V, λ) is a Ricci soliton on a para-Sasakian manifold M and the equation $S(\xi, X) \cdot \overset{\cup}{W} = 0$ satisfies on M. By use of the following equations

$$(S(\xi, X) \cdot \overset{\Box}{W})(U, Y)Z = ((X \wedge_{s} \xi) \overset{\Box}{W})(U, Y)Z$$
$$= (X \wedge_{s} \xi) \overset{\Box}{W}(U, Y)Z + \overset{\Box}{W}((X \wedge_{s} \xi)U, Y)Z$$

$$+ \overset{\square}{W(U, (X \wedge_{S} \xi)Y)Z} + \overset{\square}{W(U, Y)(X \wedge_{S} \xi)Z},$$

where the endomorphisim

$$(U \wedge_S Y)Z = S(Y,Z)U - S(U,Z)Y,$$

we obtain

$$(S(X,\xi) \cdot W)(U,Y)Z = S(\xi,W(U,Y)Z)X$$
$$-S(X,W(U,Y)Z)\xi + S(\xi,U)W(X,Y)Z$$
$$(25) -S(X,Y)W(U,X)Z$$
$$(25) -S(X,Y)W(U,\xi)Z$$
$$+S(\xi,Z)W(U,Y)X$$
$$-S(X,Z)W(U,Y)\xi.$$

Now, if we consider the equation (16) in (25), then we find

$$\lambda \begin{bmatrix} -\eta(W(U,Y)Z)X + g(X,W(U,Y)Z)\xi \\ +g(X,U)W(\xi,Y)Z - \eta(U)W(X,Y)Z \\ +g(X,Y)W(U,\xi)Z - \eta(Y)W(U,X)Z \\ +g(X,Z)W(U,Y)\xi - \eta(Z)W(U,Y)X \end{bmatrix} = 0.$$

(26)

Taking inner product with ξ and in view of (11) - (14) with (2), one can find

$$\lambda \begin{bmatrix} -\eta(W(U,Y)Z)\eta(X) + g(X,W(U,Y)Z) \\ +g(X,U)\eta(W(\xi,Y)Z) - \eta(U)\eta(W(X,Y)Z) \\ +g(X,Y)\eta(W(U,\xi)Z) - \eta(Y)\eta(W(U,X)Z) \\ +g(X,Z)\eta(W(U,Y)\xi) - \eta(Z)\eta(W(U,Y)X) \end{bmatrix} = 0,$$

which yields

$$\lambda \begin{bmatrix} g(X, R(U, Y)Z) - g(Y, Z)g(U, X) + g(X, Y)g(U, Z) \\ -2 \begin{pmatrix} 1 + \lambda(r+s) \\ + \frac{t\tau}{2n+1} (\frac{1}{2n} + r+s) \end{pmatrix} \begin{pmatrix} g(U, Z)\eta(X)\eta(Y) \\ -g(Y, Z)\eta(X)\eta(U) \end{pmatrix} = 0.$$
(27)

Let $\{e_i, \phi e_i, \xi\}_{(i=1,\dots,n)}$ is a basis of *M*. Thus by a contraction of (27), we get

$$\lambda(S(Y,Z)-2ng(Y,Z))=0.$$

(28)

Theorem 3.3 A para-Sasakian manifold M satisfying $S(\xi, X) \cdot \overset{\Box}{W} = 0$ admitting a nonsteady Ricci soliton (g, V, λ) is an Einstein manifold.

Now, taking $Y = \xi = Z$ in (28) and using (16), we obtain

$$\lambda(\lambda+2n)=0,$$

which implies $\lambda = 0$ or $\lambda = -2n$. Thus, we get:

Theorem 3.4 Let (g,V,λ) be a Ricci soliton on a para-Sasakian manifold. If the equation $S(\xi,X) \cdot \overset{\Box}{W} = 0$ satisfies on M, the Ricci soliton is either steady or shrinking.

Take a para-Sasakian manifold satisfying the condition $S(\xi, X) \cdot R = 0$. By definition we have

$$(S(\xi, X) \cdot R)(U, Y)Z = ((X \wedge_S \xi)R)(U, Y)Z$$

$$= (X \wedge_S \xi) R(U, Y) Z + R((X \wedge_S \xi) U, Y) Z$$

 $+R(U,(X\wedge_{S}\xi)Y)Z+R(U,Y)(X\wedge_{S}\xi)Z,$

where the endomorphisim

$$(U \wedge_{S} Y)Z = S(Y,Z)U - S(U,Z)Y,$$

we obtain

$$(S(X,\xi) \cdot R)(U,Y)Z = S(\xi, R(U,Y)Z)X$$
$$-S(X, R(U,Y)Z)\xi + S(\xi,U)R(X,Y)Z$$

$$-S(X,U)R(\xi,Y)Z + S(\xi,Y)R(U,X)Z$$

$$(29) -S(X,Y)R(U,\xi)Z$$

$$+S(\xi,Z)R(U,Y)X$$

$$-S(X,Z)R(U,Y)\xi$$
.

Now, if we consider the equation (16) in (29), then we get

$$\lambda \begin{bmatrix} -\eta(R(U,Y)Z)X + g(X,R(U,Y)Z)\xi \\ +g(X,U)R(\xi,Y)Z - \eta(U)R(X,Y)Z \\ +g(X,Y)R(U,\xi)Z - \eta(Y)R(U,X)Z \\ +g(X,Z)R(U,Y)\xi - \eta(Z)R(U,Y)X \end{bmatrix} = 0.$$
(30)

By taking inner product with ξ and by use of

(11)-(14) with (2), we find

$$\lambda \begin{bmatrix} -\eta(R(U,Y)Z)\eta(X) + g(X,R(U,Y)Z) \\ +g(X,U)\eta(R(\xi,Y)Z) - \eta(U)\eta(R(X,Y)Z) \\ +g(X,Y)\eta(R(U,\xi)Z) - \eta(Y)\eta(R(U,X)Z) \\ +g(X,Z)\eta(R(U,Y)\xi) - \eta(Z)\eta(R(U,Y)X) \end{bmatrix} = 0,$$
(31)

from which

$$\lambda \begin{bmatrix} g(X, R(U, Y)Z) - g(Y, Z)g(U, X) \\ +g(X, Y)g(U, Z) \\ -2 \begin{pmatrix} g(U, Z)\eta(X)\eta(Y) \\ -g(Y, Z)\eta(X)\eta(U) \end{pmatrix} \end{bmatrix} = 0.$$

Let $\{e_i, \phi e_i, \xi\}_{(i=1,...,n)}$ is an orthonormal basis of *M*. Thus by a contraction of (32), we have

$$\lambda \begin{bmatrix} S(Y,Z) - (2n-2)g(Y,Z) \\ -2\eta(Y)\eta(Z) \end{bmatrix} = 0.$$

(33)

Theorem 3.5 A para-Sasakian manifold satisfying $S(\xi, X) \cdot R = 0$ admitting a nonsteady Ricci soliton (g, V, λ) is a η -Einstein manifold.

Also, putting $Y = \xi = Z$ in (33) and in view of (16), we obtain $\lambda(-\lambda - 2n) = 0$,

which implies $\lambda = 0$ or $\lambda = -2n$. Thus, we get:

Theorem 3.6 Let (g, V, λ) be a Ricci soliton

on a para-Sasakian manifold M. If the equation $S(\xi, X) \cdot R = 0$ satisfies on M, then the Ricci soliton is either steady or shrinking.

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