# Results for nonlinear fractional differential equations on pseudo-metric spaces with three boundary val 

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Abstract. In this paper, we investigate the existence of solutions in Gauge spaces for the nonlinear fractional
differential equation boundary value problem
\(D_{0}^{\alpha}+u(t)+f(t, u(t))=0, \quad t \in[0, \mathrm{~T}](1,1)\)
With different boundary value
\(u(O)=u(T)=0\)
and
\(u(0)=\beta_{1} u(\mu), u(T)=\beta_{2} u(\mu)\)
and different order \(1<\mathrm{a} \leq 2\) and \(0<\mathrm{a}<1\). where \(0</ 31</ 32<\mathrm{T}\) and \(\mu \in[\mathrm{O}, \mathrm{T}]\) and \(D_{0}^{\alpha}+\) is the standard Riemann-
Lowville differentiation with \(f(t, u(t)) \in C([O, T] \times[O, \infty), R)\). By using some fixed-point results on gauge spaces,
some existence results of positive solutions are obtained.
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Keywords: Boundary value problem, Fixed point, Fractional differential equation, Green function, Positive solution.

## 1. INTRODUCTION

Fractional differential equations have been of great interest recently. It is caused both by the intensive development of the theory of fractional calculus itself and by the applications of such constructions in various sciences such as physics, mechanics, chemistry, engine erg. For details, see [1]-[6]. It should be noted that most of papers and books on fractional calculus are devoted to the solvability of linear initial fractional differential equations in terms of special functions [6]-[8]. Recently, there are some papers that deal with the existence and uniquence of solution of nonlinear initial fractional differential equation by the use of techniques of nonlinear analysis (fixed point theorems, Leray-Shauder theory, etc.); see [9]-[18].

## 2. THE PRELIMINARY

For the convenience of the reader, we present the necessary definitions from fractional calulus theory. These definitions can be found in the recent literaturs and books (see [8]).

Definition 2.1. The Riemann-Liouville fractional integral of order $\alpha>0$ of a function $\mathrm{f}:(0, \infty)$ $\rightarrow \mathrm{R}$ is given by

[^0]$I^{\alpha} f(t)=\frac{1}{T(\alpha)} \int_{0}^{t}(t-s)^{\alpha-1} f(s) d s$
provided the right side is pointwise defind on $(0, o o)$.
Definition 2.2. The Riemann-Liouville fractional derivative of order $\alpha>0$ of a function $\mathrm{f}:(0$, $\infty) \rightarrow R$ is given by
$D^{\alpha} f(t)=\frac{1}{T(n-\alpha)}\left(\frac{d}{d t}\right)^{n} \int_{0}^{t}(t-s)^{n-\alpha-1} f(s) d s$.
where $\mathrm{ti}=[\alpha]+1$, provided the right side is pointwise de find on $(0, \infty)$. Definition 2.3. An altering distance function is a function: $[0, \infty) \rightarrow[0, \infty)$ which satisfies
(i) $\psi$ is continuous and nondecreasing; (ii) $\psi(\mathrm{t})=0$ if and only if $\mathrm{t}=0$.

Definition 2.4. Let X be a nonempty set. A map d: $\mathrm{X} \times \mathrm{X} \rightarrow[\mathrm{O}, \infty)$ is called a pseudo-metric in X whenever
(i) $d(x, x)=0$ for all $x \in X$;
(ii) $d(x, y)=d(y, x)$ for all $x, y \in X$;
(iii) $d(x, y) \leq d(x, z)+d(z, y)$ for all $x, y, z \in X$.

Definition 2.5. Let X be a nonempty set endowed with a pseudo-metric d . The d-ball of radius $\varepsilon$ $>0$ centered at $\mathrm{x} \in \mathrm{X}$ is the set
$B(x ; d, \varepsilon)=\{y \in X l d(x, y)<\varepsilon\}$.
Definition 2.6. A family $Y=\left\{d_{\lambda} J \lambda \in \mathrm{~A}\right\}$ of pseudo-metrics is called separating if for each pair $\mathrm{x} \neq \mathrm{y}$, there exists a $d_{\lambda} . \in \Upsilon$ such that $d_{\lambda} .(\mathrm{x}, \mathrm{y}) \neq \mathrm{o}$.

Definition 2.7. Let $X$ be a nonempty set and $Y=\left\{d_{\lambda} \cdot / \lambda \in A\right\}$ be a separating family of pseudometrics on $X$. The topology $T(Y)$ having for the subbasis the family
$B(Y)=\left\{B\left(x_{i}, d_{\lambda}, \varepsilon\right) l x \in x_{n}, d_{\lambda} \in Y, \varepsilon>0\right\}$
of balls is called the topology in $X$ induced by the family $Y$. The pair ( $X, T(Y)$ ) is called a gauge space. Note that $(\mathrm{X}, \mathrm{T}(\mathrm{Y})$ ) is hausdorff because we require $Y$ to be separating.

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Definition 2.8. Let $Y=\left\{d_{\lambda} \cdot / \lambda \in \mathrm{A}\right\}$ be a family of pseudo-metrics on $\mathrm{X},(\mathrm{X}, \mathrm{Y}, \leq)$ is called an ordered gauge space and ( $\mathrm{X}, \leq$ ) is a partially ordered set.

For more details on gauge spaces, we refer the reader to [?].
Definition 2.9. Let $(X, \leq)$ be a partially ordered set. We say that $(X, \leq)$ is directed if every pair of elements has an upper bound, that is, for every $\mathrm{a}, \mathrm{b} \in \mathrm{X}$, there exists $\mathrm{c} \in \mathrm{X}$ such that $\mathrm{a} \leq \mathrm{c}$ and $\mathrm{b} \leq \mathrm{c}$.

We consider the class of functions $\left\{\psi_{\lambda}\right\} \lambda \in A$ and $\left\{\varphi_{\lambda}\right\} \lambda \in A$ such that for all $\lambda \in \mathrm{A}, \psi_{\lambda}, \varphi_{\lambda}$ : $[0, \infty) \rightarrow[0, \infty)$ satisfy the following conditions
(c1) $\psi_{\lambda}$. is an altering distance function.,
(c2) $\varphi_{\lambda}$ is a lower semi-continuous function with $\varphi_{\lambda}(\mathrm{t})=0$ if and only if $\mathrm{t}=0$.

Theorem 2.1. (see[19\}) Let ( $\mathrm{X}, \mathrm{Y}, \leq$ )be an ordered complete gauge space and $\mathrm{f}: \mathrm{X} \rightarrow \mathrm{X}$ be a no decreasing. Suppose that , $\psi_{\lambda}, \psi_{\lambda}$. satisfy conditions ( $\mathrm{c} 1, \mathrm{c} 2$ ) and
$\left.\psi_{\lambda^{\prime}} \cdot\left(d_{\lambda^{\prime}} \cdot(f x, f y)\right)<\psi_{\lambda^{\prime}} d_{\lambda^{\cdot}}(x, y)\right)-\varphi_{\lambda^{\prime}}>\left(d_{\lambda^{\prime}}(x, y)\right)$
for all ( $\mathrm{X}, \mathrm{Y}, \leq$ all $\mathrm{x}, \mathrm{y} \in \mathrm{X}$ with $\mathrm{x} \leq \mathrm{y}$. Also suppose either
(i) f is continuous or
(ii) If $\{X n\} C X$ is a nondecreasing sequence with $X n \rightarrow z \in X$, then $X n \leq z$ for all $n$,

If there exists x 0 such that $\mathrm{x} 0 \leq \mathrm{fx} 0$, then f has a fixed point, that is, there exists $\mathrm{z} \in \mathrm{X}$, such that $\mathrm{z}=\mathrm{f} \mathrm{z}$. Moreover, if $(X, \leq)$ is directed, we obtain the uniqueness of the fixed point off.

## 3. MAIN RESULTS

We study the existence and uniqueness of solution for boundary value problems of nonlinear fractional differential equations in two type problems.

### 3.1. Existence Results for Nonlinear Fractional Differential Equations with periodic Boundary Conditions

We consider following fractional differential equation with boundary value problem
$D_{0}^{\alpha}+u(t)+f(t, u(t))=0, \quad t \in[0, \mathrm{~T}]$
$u(O)=u(T)=0$
where $1<\alpha \leq: 2$, is a real number, $D_{0}^{\alpha}+$ is the standard RiemannLiouville differentiation and $f(t, u(t)) \in C([O, T] x[O, \infty), R)$.

Now we prove the existence of solution for the problem (1.1). We consider the space $\mathrm{X}=\mathrm{C}([\mathrm{O}$, $\mathrm{T}], \mathrm{R}$ ) of real continuous functions defind on $[\mathrm{O}, \mathrm{T}]$. For each positive integer $\mathrm{ti} \geq 1$, we define the mapll. $l_{n}: \mathrm{X} \rightarrow[\mathrm{O}, \infty)$ by
$\|x\|_{n}=\underset{\substack{\max \mid x(t) \| \\ 0 \leq t \leq n^{\prime}}}{ } \quad$ for all $\quad x \in X$.

This map is a semi- norm on X. Define now,
$d_{n}(x, y)=\|x-y\|_{n}$
for all $x, y \in X$.

Then $Y=\left\{d_{n}\right\} n \geq 1$ is a separating family of pseudo-metrics on $X$. The gauge space $(X, T(Y))$ with respect to the family $Y$ is complete. Consider on $X$ the partial order: $S$ defind by

$$
x, y \in X, x \leq y<=>x(t) \leq y(t)
$$

for all $t \geq 0$.

For any increasing sequence $\left\{x_{n}\right\}$ in X converging to some $\mathrm{z} \in \mathrm{X}$ we have $x_{n}(\mathrm{t}) \leq \mathrm{z}(\mathrm{t})$ for any $t \geq 0$. Also, for every $x, y \in X$, there exists $c(x, y) \in X$ which is comparable to $x, y$.

We shall prove the following result

Theorem 3.1. Suppose that
(i) $f:[0, T] x[0, o o) \rightarrow R$ is continuous, $T \geq 1$,
(ii) f is increasing, for each $t \geq 0, u \leq v$, we have $f(t, u(t)) \leq f(t, v(t))$

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(iii) for each $t \geq 0, u \leq v$, we have
$|f(t, u)-f(t, v)| \leq \gamma(t) \sqrt{\ln \left[(v-u)^{2}+1\right]}$
$\sup _{t \geq 0} \int_{0}^{T} \gamma(s) d s \leq \frac{\Gamma(\alpha)}{T^{\alpha-1}}$
(iv) there exists $x_{0} \in C([0, T], R)$ such that
$x_{0}(t) \leq \int_{0}^{T} G(t, s) f(s, u(s))$
$d s$, for anyt $\geq 0$.
Then the fractional differential equation (1.1) has a unique solution $x^{*} \in C([0, T], R)$.

### 3.2 Existence Results for Nonlinear Fractional Differential Equations with nonlocal Boundary Conditions

We consider following fractional differential equation with boundary value problem

$$
\begin{aligned}
& D_{0}^{\alpha}+u(t)+f(t, u(t)), \quad t \in[0, T], T \geq 1 \\
& u(0)=\beta_{1} u(\mu), u(T)=\beta_{2} u(\mu) \\
& b<\text { where } 0<\alpha<1, \text { is a real number, } 0<\beta_{1}<\beta_{2}<T \text { and } \mu \\
& \\
& \quad \in[0, T], D_{0}^{\alpha}+\text { is the standard Riemann } \\
& \\
& \quad-\text { Liouville differentiation and } f(t, u(t)) \in C([0, T] \times[0, \infty), R) .
\end{aligned}
$$

Now we prove the existence of solution for the problem (1.1). we consider the space $X=C([0, T], R)$ for real continuous functions defined on $[0, T]$. for each positive integer $n \geq 1$ , we define the map $\|\cdot\| \|_{n}: X \rightarrow[0, \infty)$ by $\|x\|_{n}=\begin{aligned} \max \\ 0 \leq t \leq n\end{aligned}|x(t)|$
for all $x \in X$.

This map is a semi-norm on X. Define now,
$d_{n}(x, y)=\|x-y\|_{n}$
for all $x, y \in X$.

Then $Y=\left\{d_{n}\right\}_{n \geq 1}$ Is a separating family of pseudo-metrics on $X$. the gauge space $(X, T(Y)$ with respect to the family Y is complete. Consider on X the partial order $\leqslant$ defined by
$x, y \in X, x \leqslant y \Leftrightarrow x(t) \leq y(t)$
for all $t \geq 0$.

For any increasing sequence $\left\{x_{n}\right\}$ in $X$ converging to some $z \in X$ we have $x_{n}(t) \leq z(t), t \geq 0$ for any $t \geq 0$. Also, for every $x, y \in X$, there exists $c(x, y) \in X$ which is comparable to $\mathrm{x}, \mathrm{y}$.

Theorem 3.2. Suppose that
(i) $f:[0, T] x[0, \infty) \rightarrow R$ is continuous, $\mathrm{T} \geq 1$,
(ii) f is increasing, for each $t \geq 0, u \leqslant v$, we have $\mathrm{f}(\mathrm{t}, \mathrm{u}(\mathrm{t})) \leq \mathrm{f}(\mathrm{t}, \mathrm{v}(\mathrm{t}))$
(iii) for each $t \geq 0, u \leqslant v$, we have

$$
|f(t, u)-f(t, v)| \leq \gamma(t) \sqrt{\ln \left[(v-u)^{2}+1\right]}
$$

Where $\gamma:[0, \infty) \rightarrow[0, \infty)$ is continuous, the function $\int_{0}^{T} \gamma(s) d s$ is bounded on $[0, \infty)$ and $\sup _{t \geq 0} \int_{0}^{T} \gamma(s) d s \leq \frac{\Gamma(\alpha)}{T^{\alpha-1}}$
(iv) there exists $x_{0} \in C([0, T], R)$ such that
$x_{0}(t) \leq \int_{0}^{T} G(t, s) f(s, u(s))$
$d s$, for any $t \geq 0$.

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